

# How to Do xtabond2

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# **xtabond2 in a nutshell**

- First ado version in 11/03, Mata version in 11/05.
- Extends built-in xtabond, to do system GMM, Windmeijer correction, revamped syntax
- Estimators designed for
  - Small- $T$ , large- $N$  panels
  - One dependent variable
  - Dynamic
  - Linear
  - Regressors endogenous and predetermined
  - Fixed individual effects
  - Arbitrary autocorrelation and het. within panels
  - General application

# Outline of paper

- Introduction to linear GMM
- Motivation and design of difference and system GMM
- **xtabond2** syntax

# Black box problem

- Canned & sophisticated procedure
- Dangers in hidden sophistication
  - finite sample  $\neq$  asymptotic
- Users should understand motivation and limits of estimator

# Linear GMM in one slide

- Instrument vector  $\mathbf{z}$  such that  $E[\mathbf{z}\varepsilon] = \mathbf{0}$
- # instruments > # parameters so can't have  $E_N[\mathbf{z}\varepsilon] = \frac{1}{N} \mathbf{Z}'\hat{\mathbf{E}} = \mathbf{0}$
- Want to “minimize”  $\frac{1}{N} \mathbf{Z}'\hat{\mathbf{E}}$  in some sense
- In what sense? By a pos-semi-def. quad. form given by  $\mathbf{A}$ :

$$\|E_N[\mathbf{z}\varepsilon]\|_{\mathbf{A}} = \left\| \frac{1}{N} \mathbf{Z}'\hat{\mathbf{E}} \right\|_{\mathbf{A}} \equiv N \left( \frac{1}{N} \mathbf{Z}'\hat{\mathbf{E}} \right)' \mathbf{A} \left( \frac{1}{N} \mathbf{Z}'\hat{\mathbf{E}} \right) = \frac{1}{N} \hat{\mathbf{E}}' \mathbf{Z} \mathbf{A} \mathbf{Z}' \hat{\mathbf{E}}$$

- Given  $\mathbf{A}$ , minimizing leads to  $\hat{\boldsymbol{\beta}}_{\mathbf{A}} = (\mathbf{X}' \mathbf{Z} \mathbf{A} \mathbf{Z}' \mathbf{X})^{-1} \mathbf{X}' \mathbf{Z} \mathbf{A} \mathbf{Z}' \mathbf{Y}$
- Always unbiased, but which  $\mathbf{A}$  is efficient? Answer:  $\mathbf{A}$  should weight moments  $\mathbf{z}_i'\mathbf{E}$  inversely with their variances and covariances:

$$\mathbf{A}_{EGMM} = \text{Var}[\mathbf{Z}'\mathbf{E}|\mathbf{X}, \mathbf{Z}]^{-1} = (\mathbf{Z}' \text{Var}[\mathbf{E}|\mathbf{X}, \mathbf{Z}] \mathbf{Z})^{-1} = (\mathbf{Z}' \boldsymbol{\Omega} \mathbf{Z})^{-1}$$

- To make feasible, choose arbitrary proxy for  $\boldsymbol{\Omega}$ , call it  $\mathbf{H}$ . Do GMM (*one-step*). Use residuals to make robust sandwich estimator of  $(\mathbf{Z}' \boldsymbol{\Omega} \mathbf{Z})^{-1}$ . Rerun. *Two-step* is feasible, theoretically efficient.

# Linear GMM and 2SLS

$$\hat{\beta}_{EGMM} = \left( \mathbf{X}' \mathbf{Z} (\mathbf{Z}' \Omega \mathbf{Z})^{-1} \mathbf{Z}' \mathbf{X} \right)^{-1} \mathbf{X}' \mathbf{Z} (\mathbf{Z}' \Omega \mathbf{Z})^{-1} \mathbf{Z}' \mathbf{Y}$$

- If  $\Omega = \sigma^2 \mathbf{I}$ , reduces to

$$\hat{\beta}_{2SLS} = \left( \mathbf{X}' \mathbf{Z} (\mathbf{Z}' \mathbf{Z})^{-1} \mathbf{Z}' \mathbf{X} \right)^{-1} \mathbf{X}' \mathbf{Z} (\mathbf{Z}' \mathbf{Z})^{-1} \mathbf{Z}' \mathbf{Y}$$

- If errors i.i.d., efficient GMM *is* 2SLS
- If not, 2SLS inefficient

# Linear GMM in another slide

(Holtz-Eakin, Newey, and Rosen 1988)

(1)  $\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{E}$

OLS inconsistent:  $E[\mathbf{X}'\mathbf{E}] \neq 0$

(2) Take  $\mathbf{Z}$ -moments:  $\mathbf{Z}'\mathbf{Y} = \mathbf{Z}'\mathbf{X}\boldsymbol{\beta} + \mathbf{Z}'\mathbf{E}$

OLS consistent ( $E[\mathbf{X}'\mathbf{Z}\mathbf{Z}'\mathbf{E}] = 0$ )

but inefficient ( $\text{Var}[\mathbf{Z}'\mathbf{E}] = \mathbf{Z}'\boldsymbol{\Omega}\mathbf{Z}$  not scalar)

Left-multiply by  $(\mathbf{Z}'\boldsymbol{\Omega}\mathbf{Z})^{-\frac{1}{2}}$ :

$$(\mathbf{Z}'\boldsymbol{\Omega}\mathbf{Z})^{-\frac{1}{2}}\mathbf{Z}'\mathbf{Y} = (\mathbf{Z}'\boldsymbol{\Omega}\mathbf{Z})^{-\frac{1}{2}}\mathbf{Z}'\mathbf{X}\boldsymbol{\beta} + (\mathbf{Z}'\boldsymbol{\Omega}\mathbf{Z})^{-\frac{1}{2}}\mathbf{Z}'\mathbf{E}$$

$$\text{Let } \mathbf{X}^* = (\mathbf{Z}'\boldsymbol{\Omega}\mathbf{Z})^{-\frac{1}{2}}\mathbf{Z}'\mathbf{X}, \mathbf{Y}^* = (\mathbf{Z}'\boldsymbol{\Omega}\mathbf{Z})^{-\frac{1}{2}}\mathbf{Z}'\mathbf{Y}, \mathbf{E}^* = (\mathbf{Z}'\boldsymbol{\Omega}\mathbf{Z})^{-\frac{1}{2}}\mathbf{Z}'\mathbf{E}$$

(3)  $\mathbf{Y}^* = \mathbf{X}^*\boldsymbol{\beta} + \mathbf{E}^*$

OLS efficient ( $\text{Var}[\mathbf{E}^*] = \mathbf{I}$ )

OLS on (3) = GLS on (2) = GMM on (1)

GMM = GLS on  $\mathbf{Z}$ -moments

# Difference and system GMM

Basic model:

$$y_{it} = \alpha y_{i,t-1} + \mathbf{x}'_{it} \boldsymbol{\beta} + \nu_{it}$$

$$\nu_{it} = \mu_i + \varepsilon_{it}$$

$$E[\mu_i] = E[\varepsilon_{it}] = E[\mu_i \varepsilon_{it}] = 0$$

Conceptual starting point: OLS

# Problem: Dynamic Panel Bias (Nickell 1981)

- Fixed effects in disturbance term make  $y_{i,t-1}$  endogenous
  - Example: Indonesia
- A problem of short panels
- Individual dummies (=Within Groups) don't help
  - Transformed  $y_{i,t-1}$  endogenous, as are deeper lags

# Partial solution: OLS in differences

$$\Delta y_{it} = \alpha \Delta y_{i,t-1} + \Delta \mathbf{x}_{it}' \boldsymbol{\beta} + \Delta \varepsilon_{it}$$

- Purges fixed effects, doesn't spread endogeneity much
- Transformed  $y_{i,t-1}$  still becomes endogenous since the  $y_{i,t-1}$  in  $\Delta y_{i,t-1} = y_{i,t-1} - y_{i,t-2}$  correlates with the  $\varepsilon_{i,t-1}$  in  $\Delta \varepsilon_{it} = \varepsilon_{it} - \varepsilon_{i,t-1}$
- But deeper lags exogenous if no AR(), offering instruments

# Problem: Other endogeneity

- Differencing eliminates endogeneity to fixed effects error component. But
  - $\Delta y_{i,t-1}$  now endogenous to  $\Delta \varepsilon_{it}$
  - Other predetermined variables become endogenous in same way
  - Still other variables may be endogenous from the start
- For general application, assume no perfect instruments waiting in the wings

# Solution: Instrument with lags (2SLS) (Anderson and Hsiao 1981)

- Assuming no AR() in  $\varepsilon_{it}$ , natural instruments for  $\Delta y_{i,t-1}$  are  $\Delta y_{i,t-2}$  and  $y_{i,t-2}$
- Both mathematically related to  $\Delta y_{i,t-1}$
- $y_{i,t-2}$  seems preferable: available at  $t = 3$
- Again, small  $T$  influences
- Do same for other endogenous variables

# Problem: Inefficiency

- Deeper lags available as instruments
  - But reduce sample in 2SLS
  - Problem for short panels
- In differences, errors not i.i.d.
  - $\Delta \varepsilon_{it}$  and  $\Delta \varepsilon_{i,t-1}$  mathematically correlated
  - 2SLS not efficient

# Solution: GMM & GMM-style instruments (Holtz-Eakin, Newey, and Rosen 1988)

- Use many lags, replacing missing with zero
- Generate separate instrument for each lag and time period instrumented

$$\text{IV-style: } \begin{bmatrix} \vdots \\ \vdots \\ y_{i1} \\ \vdots \\ y_{iT-2} \end{bmatrix} \quad \text{GMM-style: } \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & \dots \\ 0 & 0 & 0 & 0 & 0 & 0 & \dots \\ y_{i1} & 0 & 0 & 0 & 0 & 0 & \dots \\ 0 & y_{i2} & y_{i1} & 0 & 0 & 0 & \dots \\ 0 & 0 & 0 & y_{i3} & y_{i2} & y_{i1} & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

- Result: Arellano-Bond (1991) difference GMM

# Problem: Autocorrelation

- E.g., if  $\varepsilon_{it}$  are AR(1), then  $y_{i,t-2} \sim \varepsilon_{i,t-2} \sim \varepsilon_{i,t-1} \sim \Delta\varepsilon_{it}$
- Must assume  $y_{i,t-2}$  is invalid instrument in  $i,t$

# Solution: Restrict to deeper lags

- If we find AR( $l$ ) in  $\varepsilon_{it}$ , use lags  $l + 1$  and deeper

# Arellano-Bond AR() test

- Expect AR(0) in  $\nu_{it} = \mu_i + \varepsilon_{it}$
- To check for AR(1) in  $\varepsilon_{it}$ , test for AR(2) in  $\Delta e_{it}$
- E.g., compare  $e_{it} - e_{i,t-1}$  and  $e_{i,t-2} - e_{i,t-3}$  to detect  $e_{i,t-1} \sim e_{i,t-2}$
- Test statistic for AR( $l$ ) in differences:  $\sum_{i,t} \Delta e_{it} \Delta e_{i,t-l}$
- Normal under null of no AR( $l$ )
- Arellano and Bond calculate its standard deviation
- z test for AR()
- More general than other AR() tests in Stata.
- abar: post-estimation command for regress, ivreg, ivreg2

# Problem: Weak instruments

If  $y$  is nearly a random walk,  $y_{i,t-1}$  is a poor instrument for  $\Delta y_{it}$ , mathematical relationship notwithstanding

# Solution: Instead of purging fixed effects, find instruments orthogonal to them (Arellano and Bover 1995)

- If  $E[y_{it}\mu_i]$  stationary, then  $E[\Delta y_{it}\mu_i] = 0$
- $\Delta y_{i,t-1}$  uncorrelated with fixed effects, thus with  $\nu_{it} = \mu_i$  good instrument in *levels* (if no AR)
- Make system of difference and levels equations
- Concretely, make a stacked data set, with differences up top, levels below. Treat as single estimation problem
- Instrument differences with levels and v.v.
- “System GMM” (Blundell and Bond 1998)

# Relationship among moments (Tue Gorgens)

$$\begin{array}{cccccc} \mathbb{E}[w_{i1}\nu_{i1}] & \stackrel{D}{=} & \mathbb{E}[w_{i1}\nu_{i2}] & \stackrel{D}{=} & \mathbb{E}[w_{i1}\nu_{i3}] & \stackrel{D}{=} & \mathbb{E}[w_{i1}\nu_{i4}] \\ & & \|_L & & \|_L & & \|_L \\ \mathbb{E}[w_{i2}\nu_{i1}] & & \mathbb{E}[w_{i2}\nu_{i2}] & \stackrel{D}{=} & \mathbb{E}[w_{i2}\nu_{i3}] & \stackrel{D}{=} & \mathbb{E}[w_{i2}\nu_{i4}] \\ & & & & \|_L & & \|_L \\ \mathbb{E}[w_{i3}\nu_{i1}] & & \mathbb{E}[w_{i3}\nu_{i2}] & & \mathbb{E}[w_{i3}\nu_{i3}] & \stackrel{D}{=} & \mathbb{E}[w_{i3}\nu_{i4}] \\ & & & & & & \|_L \\ \mathbb{E}[w_{i4}\nu_{i1}] & & \mathbb{E}[w_{i4}\nu_{i2}] & & \mathbb{E}[w_{i4}\nu_{i3}] & & \mathbb{E}[w_{i4}\nu_{i4}] \end{array}$$

# Problem: Two-step errors too small

## Regression for Arellano-Bond (1991) column (a1), Table 4

Arellano-Bond dynamic panel-data estimation, **one-step** difference GMM results

	Robust					
	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
<hr/>						
n						
L1.	.6862261	.1445943	4.75	0.000	.4003376	.9721147
L2.	-.0853582	.0560155	-1.52	0.130	-.1961109	.0253944
w						
--.	-.6078208	.1782055	-3.41	0.001	-.9601647	-.2554769
L1.	.3926237	.1679931	2.34	0.021	.0604714	.7247759
k						
--.	.3568456	.0590203	6.05	0.000	.240152	.4735392

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L2.	-.0651882	.0265009	-2.46	0.015	-.1175852	-.0127912
w						
--.	-.5257597	.0537692	-9.78	0.000	-.6320709	-.4194485
L1.	.3112899	.0940116	3.31	0.001	.1254122	.4971675
k						
--.	.2783619	.0449083	6.20	0.000	.1895702	.3671537

# Problem, cont'd

- Problem appears to be one of overfitting
  - Efficient GMM deemphasizes moments with high variance (high second moments)
  - Feasible efficient GMM in small samples may deemphasize outliers (high first moments)
  - Spurious precision

# Solution: finite-sample correction (Windmeijer 2005)

- One-step estimate:  $\hat{\beta}_1 = f(\mathbf{Y})$  (conditioning on  $\mathbf{X}, \mathbf{Z}$ )
- One-step residuals used to construct  $\hat{\Omega}$ :  
$$\hat{\beta}_2 = \left( \mathbf{X}' \mathbf{Z} (\mathbf{Z}' \hat{\Omega} \mathbf{Z})^{-1} \mathbf{Z}' \mathbf{X} \right)^{-1} \mathbf{X}' \mathbf{Z} (\mathbf{Z}' \hat{\Omega} \mathbf{Z})^{-1} \mathbf{Z}' \mathbf{Y} \equiv g(\mathbf{Y}, \hat{\Omega}) \equiv g(\mathbf{Y}, f(\mathbf{Y}))$$
- Standard estimate of  $\text{Var}[\hat{\beta}_2]$  treats  $\hat{\Omega}$  as constant, observed, precise—despite dependence on random  $\mathbf{Y}$
- Taylor expansion of  $g$  around true  $\beta$ :  
$$\hat{\beta}_2 = g\left(\mathbf{Y}, \hat{\Omega}_{\hat{\beta}_1}\right) \approx g\left(\mathbf{Y}, \hat{\Omega}_\beta\right) + \frac{\partial}{\partial \hat{\beta}} g\left(\mathbf{Y}, \hat{\Omega}_{\hat{\beta}}\right) \Big|_{\hat{\beta}=\beta} \left( \hat{\beta}_1 - \beta \right)$$
- “Correction” comes from second term
  - $E[\hat{\beta}_1 - \beta] = 0$  so no effect on  $E[\hat{\beta}_2]$ —no coefficient bias
  - Affects variance

Arellano-Bond dynamic panel-data estimation, **one-step** difference GMM results

	Robust					
	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
n						
L1.	.6862261	.1445943	4.75	0.000	.4003376	.9721147
L2.	-.0853582	.0560155	-1.52	0.130	-.1961109	.0253944
w						
--.	-.6078208	.1782055	-3.41	0.001	-.9601647	-.2554769
L1.	.3926237	.1679931	2.34	0.021	.0604714	.7247759
k						
--.	.3568456	.0590203	6.05	0.000	.240152	.4735392

Arellano-Bond dynamic panel-data estimation, **two-step** difference GMM results

	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
n						
L1.	.6287089	.0904543	6.95	0.000	.4498646	.8075531
L2.	-.0651882	.0265009	-2.46	0.015	-.1175852	-.0127912
w						
--.	-.5257597	.0537692	-9.78	0.000	-.6320709	-.4194485
L1.	.3112899	.0940116	3.31	0.001	.1254122	.4971675
k						
--.	.2783619	.0449083	6.20	0.000	.1895702	.3671537

Arellano-Bond dynamic panel-data estimation, **two-step** difference GMM results

	Corrected					
	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
n						
L1.	.6287089	.1934138	3.25	0.001	.2462954	1.011122
L2.	-.0651882	.0450501	-1.45	0.150	-.1542602	.0238838
w						
--.	-.5257597	.1546107	-3.40	0.001	-.8314524	-.2200669
L1.	.3112899	.2030006	1.53	0.127	-.0900784	.7126582
k						
--.	.2783619	.0728019	3.82	0.000	.1344196	.4223043

# Problem: too many instruments

- In difference and system GMM, # instruments ( $j$ ) quadratic in  $T$
- Analogy:
  - In 2SLS, if  $j = \#$  of regressors, first-stage  $R^2$ 's=1.0 and 2SLS=OLS (biased)
  - Too many instruments overfit endogenous variables
- And # of cross-moments in  $\text{Var}[\mathbf{Z}'\mathbf{E}|\mathbf{X}, \mathbf{Z}]^{-1}$  to be estimated for efficient GMM quadratic in  $j$ —quartic in  $T$ !
- Estimate of  $\text{Var}[\mathbf{Z}'\mathbf{E}|\mathbf{X}, \mathbf{Z}]^{-1}$  degrades
- Hansen test very weak— $p$  values of 1.000 not uncommon
- Little guidance on how many is too many
- xtabond2 warns if  $j > N$

# Solution: consider limiting instruments

- Limit number of lags of variables used as instruments
- Or “collapse” instruments:

$$\begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & \dots \\ 0 & 0 & 0 & 0 & 0 & 0 & \dots \\ y_{i1} & 0 & 0 & 0 & 0 & 0 & \dots \\ 0 & y_{i2} & y_{i1} & 0 & 0 & 0 & \dots \\ 0 & 0 & 0 & y_{i3} & y_{i2} & y_{i1} & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix} \xrightarrow{\hspace{1cm}} , \begin{bmatrix} 0 & 0 & 0 & \dots \\ 0 & 0 & 0 & \dots \\ y_{i1} & 0 & 0 & \dots \\ y_{i2} & y_{i1} & 0 & \dots \\ y_{i3} & y_{i2} & y_{i1} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix}.$$

$$\sum_i y_{i,t-2} \Delta \hat{e}_{it} = 0 \text{ for each } t \geq 3$$

$$\xrightarrow{\hspace{1cm}} \sum_{i,t} y_{i,t-2} \Delta e_{it} = 0.$$

# xtabond2 syntax

Y

X

Z

```
xtabond2 depvar varlist [if exp] [in range]
[, level(#) twostep robust noconstant small noleveleq
artests(#) arlevels h(#) nomata]
ivopt [ivopt ...] gmmopt [gmmopt ..]]
```

where **gmmopt** is

```
gmmstyle(varlist [, laglimits(# #) collapse
equation({diff | level | both}) passthru])
```

“GMM-style”

and **ivopt** is

```
ivstyle(varlist [, equation({diff | level | both})
passthru mz])
```

Classic

# Examples

- Classic one-step difference GMM with no controls except time dummies

```
xi: xtabond2 y L.y i.t, gmm(y, laglim(2 .))  
    iv(i.t) robust noleveleq
```

- Equivalents:

```
xi: xtabond2 y L.y i.t, gmm(L.y, laglim(1 .))  
    iv(i.t) robust noleveleq  
xi: xtabond2 y L.y i.t, gmm(L.y)  
    iv(i.t) robust noleveleq
```

- System GMM, two-step, Windmeijer correction, w1 exogenous, w2 predetermined, w3 exogenous:

```
xi: xtabond2 y L.y w1 w2 w3 i.t,  
    gmm(L.y w2 L.w3) iv(i.t w1) two robust
```

# Examples, cont'd

If conditions imposed only on levels,  
difference equation effectively discarded.

Equivalent pairs:

```
regress n w k
```

```
xtabond2 n w k, iv(w k, eq(level)) small
```

```
ivreg2 n cap (w = k ys)
```

```
xtabond2 n w cap, iv(cap k ys, eq(level))
```

```
ivreg2 n cap (w = k ys), cluster(id) gmm
```

```
xtabond2 n w cap, iv(cap k ys, eq(level)) two
```

Or even:

```
regress n w k
```

```
abar, lags(2)
```

```
xtabond2 n w k, iv(w k, eq(level)) small arlevel
```

# Run times for bbest (seconds)

## 700 MHz PC

<b>xtabond2 ado</b>	57
<b>xtabond2 Mata, favoring space</b>	14
<b>xtabond2 Mata, favoring speed</b>	11
<b>DPD for Ox</b>	3