Jacobian Matrix Part 1

$$H_{j} = \begin{bmatrix} \frac{\partial h_{1}}{\partial x_{1}} & \frac{\partial h_{1}}{\partial x_{2}} & \cdots & \frac{\partial h_{1}}{\partial x_{n}} \\ \frac{\partial h_{2}}{\partial x_{1}} & \frac{\partial h_{2}}{\partial x_{2}} & \cdots & \frac{\partial h_{2}}{\partial x_{n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial h_{m}}{\partial x_{1}} & \frac{\partial h_{m}}{\partial x_{2}} & \cdots & \frac{\partial h_{m}}{\partial x_{n}} \end{bmatrix}$$

$$h(x) \approx h(\mu) + \frac{\partial h(\mu)}{\partial x}(x - \mu)$$
Jacobian

$$H_{j} = \begin{bmatrix} \frac{\partial h_{1}}{\partial x_{1}} & \frac{\partial h_{1}}{\partial x_{2}} & \cdots & \frac{\partial h_{1}}{\partial x_{n}} \\ \frac{\partial h_{2}}{\partial x_{1}} & \frac{\partial h_{2}}{\partial x_{2}} & \cdots & \frac{\partial h_{2}}{\partial x_{n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial h_{m}}{\partial x_{1}} & \frac{\partial h_{m}}{\partial x_{2}} & \cdots & \frac{\partial h_{m}}{\partial x_{n}} \end{bmatrix} \qquad z = \begin{pmatrix} \rho \\ \varphi \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial h_{m}}{\partial x_{1}} & \frac{\partial h_{m}}{\partial x_{2}} & \cdots & \frac{\partial h_{m}}{\partial x_{n}} \end{bmatrix}$$

$$H_{j} = \begin{bmatrix} \frac{\partial \rho}{\partial p_{x}} & \frac{\partial \rho}{\partial p_{y}} & \frac{\partial \rho}{\partial v_{x}} & \frac{\partial \rho}{\partial v_{y}} \\ \frac{\partial \rho}{\partial p_{x}} & \frac{\partial \rho}{\partial p_{y}} & \frac{\partial \rho}{\partial v_{x}} & \frac{\partial \rho}{\partial v_{y}} \\ \frac{\partial \rho}{\partial p_{x}} & \frac{\partial \rho}{\partial p_{y}} & \frac{\partial \rho}{\partial v_{x}} & \frac{\partial \rho}{\partial v_{y}} \\ \frac{\partial \rho}{\partial p_{x}} & \frac{\partial \rho}{\partial p_{y}} & \frac{\partial \rho}{\partial v_{x}} & \frac{\partial \rho}{\partial v_{y}} \end{bmatrix} \qquad x = \begin{pmatrix} \rho \\ \varphi \\ \vdots & \vdots & \ddots & \vdots \\ P_{y} \\ \psi_{x} \\ \psi_{y} \end{pmatrix} \Rightarrow \text{ Position}$$

$$\Rightarrow \text{ Velocity}$$

$$H_{j} = \begin{bmatrix} \frac{\partial h_{1}}{\partial x_{1}} & \frac{\partial h_{1}}{\partial x_{2}} & \cdots & \frac{\partial h_{1}}{\partial x_{n}} \\ \frac{\partial h_{2}}{\partial x_{1}} & \frac{\partial h_{2}}{\partial x_{2}} & \cdots & \frac{\partial h_{2}}{\partial x_{n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial h_{m}}{\partial x_{1}} & \frac{\partial h_{m}}{\partial x_{2}} & \cdots & \frac{\partial h_{m}}{\partial x_{n}} \end{bmatrix} H_{j} = \begin{bmatrix} \frac{\partial \rho}{\partial p_{x}} & \frac{\partial \rho}{\partial p_{y}} & \frac{\partial \rho}{\partial v_{x}} & \frac{\partial \rho}{\partial v_{y}} \\ \frac{\partial \rho}{\partial p_{x}} & \frac{\partial \rho}{\partial p_{y}} & \frac{\partial \rho}{\partial v_{x}} & \frac{\partial \rho}{\partial v_{y}} \\ \frac{\partial \rho}{\partial p_{x}} & \frac{\partial \rho}{\partial p_{y}} & \frac{\partial \rho}{\partial v_{x}} & \frac{\partial \rho}{\partial v_{y}} \end{bmatrix}$$

$$H_{j} = \begin{bmatrix} \frac{p_{x}}{\sqrt{p_{x}^{2} + p_{y}^{2}}} & \frac{p_{y}}{\sqrt{p_{x}^{2} + p_{y}^{2}}} & 0 & 0 \\ \frac{p_{y}}{\sqrt{p_{x}^{2} + p_{y}^{2}}} & \frac{p_{x}}{\sqrt{p_{x}^{2} + p_{y}^{2}}} & 0 & 0 \\ \frac{p_{y}(v_{x}p_{y} - v_{y}p_{x})}{(p_{x}^{2} + p_{y}^{2})^{3/2}} & \frac{p_{x}(v_{y}p_{x} - v_{x}p_{y})}{(p_{x}^{2} + p_{y}^{2})^{3/2}} & \frac{p_{y}}{\sqrt{p_{x}^{2} + p_{y}^{2}}} \end{bmatrix}$$

We're going to calculate, step by step, all the partial derivatives in H_j :

$$H_{j} = \begin{bmatrix} \frac{\partial \rho}{\partial p_{x}} & \frac{\partial \rho}{\partial p_{y}} & \frac{\partial \rho}{\partial v_{x}} & \frac{\partial \rho}{\partial v_{y}} \\ \frac{\partial \varphi}{\partial p_{z}} & \frac{\partial \varphi}{\partial p_{y}} & \frac{\partial \varphi}{\partial v_{z}} & \frac{\partial \varphi}{\partial v_{y}} \\ \frac{\partial \rho}{\partial p_{z}} & \frac{\partial \rho}{\partial p_{z}} & \frac{\partial \rho}{\partial p_{z}} & \frac{\partial \rho}{\partial p_{z}} & \frac{\partial \rho}{\partial v_{y}} \end{bmatrix}$$

So all of H_i 's elements are calculated as follows:

$$\frac{\partial \rho}{\partial p_x} = \frac{\partial}{\partial p_x} (\sqrt{p_x^2 + p_y^2}) = \frac{2p_x}{2\sqrt{p_x^2 + p_y^2}} = \frac{p_x}{\sqrt{p_x^2 + p_y^2}}$$

$$rac{\partial
ho}{\partial p_y} = rac{\partial}{\partial p_y} (\!\sqrt{p_x^2 + p_y^2}) = rac{2p_y}{2\sqrt{p_x^2 + p_y^2}} = rac{p_y}{\sqrt{p_x^2 + p_y^2}}$$

$$rac{\partial
ho}{\partial v_x} = rac{\partial}{\partial v_x} (\sqrt{p_x^2 + p_y^2}) = 0$$

$$rac{\partial
ho}{\partial v_y} = rac{\partial}{\partial v_y} (\!\sqrt{p_x^2 + p_y^2}) = 0$$

$$rac{\partial arphi}{\partial p_x} = rac{\partial}{\partial p_x} arctan(p_y/p_x) = rac{1}{(rac{p_y}{p_x})^2 + 1}(-rac{p_y}{p_x^2}) = -rac{p_y}{p_x^2 + p_y^2}$$

$$\frac{\partial arphi}{\partial p_y} = \frac{\partial}{\partial p_y} arctan(p_y/p_x) = \frac{1}{(rac{p_y}{p_x})^2 + 1}(rac{1}{p_x}) = rac{p_x^2}{p_x^2 + p_y^2} rac{1}{p_x} = rac{p_x}{p_x^2 + p_y^2}$$

$$rac{\partial arphi}{\partial v_x} = rac{\partial}{\partial v_x} arctan(p_y/p_x) = 0$$

$$rac{\partial arphi}{\partial v_y} = rac{\partial}{\partial v_y} arctan(p_y/p_x) = 0$$

$$\frac{\partial \dot{
ho}}{\partial p_x} = \frac{\partial}{\partial p_x} \left(\frac{p_x v_x + p_y v_y}{\sqrt{p_x^2 + p_y^2}} \right)$$

In order to calculate the derivative of this function we use the quotient rule.

Given a function z that is quotient of two other functions, f and g:

$$z = \frac{f}{a}$$

its derivative with respect to \$x\$ is defined as: $\frac{\partial z}{\partial x} = \frac{\frac{\partial f}{\partial x}g - \frac{\partial g}{\partial x}f}{\sigma^2}$

In our case: $f=p_xv_x+p_yv_y$

$$g=\sqrt{p_x^2+p_y^2}$$

Their derivatives are: $rac{\partial f}{\partial p_x}=rac{\partial}{\partial p_x}(p_xv_x+p_yv_y)=v_x$

$$rac{\partial g}{\partial p_x} = rac{\partial}{\partial p_x} \left(\sqrt{p_x^2 + p_y^2}
ight) = rac{p_x}{\sqrt{p_x^2 + p_y^2}}$$

Putting everything together into the derivative quotient rule we have:

$$\frac{\partial \dot{\rho}}{\partial p_{x}} = \frac{v_{z}\sqrt{p_{x}^{2} + p_{y}^{2}} - \frac{p_{z}}{\sqrt{p_{x}^{2} + p_{y}^{2}}}(p_{x}v_{x} + p_{y}v_{y})}{p_{x}^{2} + p_{y}^{2}} = \frac{p_{y}(v_{x}p_{y} - v_{y}p_{x})}{(p_{x}^{2} + p_{y}^{2})^{3/2}}$$

Similarly
$$\frac{\partial \dot{\rho}}{\partial p_y} = \frac{\partial}{\partial p_y} \left(\frac{p_x v_x + p_y v_y}{\sqrt{p_x^2 + p_y^2}} \right) = \frac{p_x (v_y p_x - v_x p_y)}{(p_x^2 + p_y^2)^{3/2}}$$

$$\frac{\partial \dot{\rho}}{\partial v_x} = \frac{\partial}{\partial v_x} \left(\frac{p_x v_x + p_y v_y}{\sqrt{p_x^2 + p_y^2}} \right) = \frac{p_x}{\sqrt{p_x^2 + p_y^2}}$$

$$\frac{\partial \dot{\rho}}{\partial v_y} = \frac{\partial}{\partial v_y} \left(\frac{p_x v_x + p_y v_y}{\sqrt{p_x^2 + p_y^2}} \right) = \frac{p_y}{\sqrt{p_x^2 + p_y^2}}$$

So now, after calculating all the partial derivatives, our resulted Jacobian, H_j is:

$$H_j = egin{bmatrix} rac{p_x}{\sqrt{p_x^2 + p_y^2}} & rac{p_y}{\sqrt{p_x^2 + p_y^2}} & 0 & 0 \ -rac{p_y}{p_x^2 + p_y^2} & rac{p_x}{p_x^2 + p_y^2} & 0 & 0 \ rac{p_y}{p_x^2 + p_y^2} & rac{p_x}{p_x^2 + p_y^2} & rac{p_x}{p_x^2 + p_y^2} & rac{p_x}{\sqrt{p_x^2 + p_y^2}} \ rac{p_x}{(p_x^2 + p_y^2)^{3/2}} & rac{p_x}{\sqrt{p_x^2 + p_y^2}} & rac{p_y}{\sqrt{p_x^2 + p_y^2}} \ \end{pmatrix}$$