

# DLinCV Lecture 2.1

Image Segmentation  
07.06.2023

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# Schedule for part 3: Segmentation

## Part 2: Segmentation

Thursday 8.6	09:00-10:00 Lecture <ul style="list-style-type: none"><li>- Introduction to Segmentation</li></ul> 10:00-12:00 Exercises <ul style="list-style-type: none"><li>- Exercise 3 on Segmentation</li></ul> 13:00-17:00 Exercise 3 on Segmentation	Aasa  13 - 15 Thanos 14 - 16 Paraskevas 15 - 17 Manxi
Friday 9.6	09:00-10:00 Lecture: <ul style="list-style-type: none"><li>- Foundation models for segmentation</li></ul> 10:00-11:00 Project 1 poster session <ul style="list-style-type: none"><li>- Give peer feedback to designated groups</li></ul> 11:00-17:00 Work on project	Aasa  10 - 12 Aasa  13 - 15 Manxi 14 - 16 Paraskevas 15 - 17 Thanos
Monday 12.6	09:00-9:30 Q&A, quick tips 09:30-17:00 Work on project  <b>Project 2 deadline at midnight</b>	9 - 12 Aasa  13 - 15 Manxi 14 - 16 Paraskevas 15 - 17 Thanos

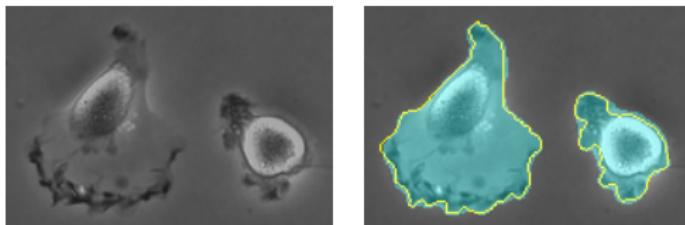
## This lecture's learning goals

After this lecture you should

- ▶ Know what image segmentation is, along with some of its applications
- ▶ Be familiar with challenges associated with image segmentation
- ▶ Be able to implement and validate a CNN for image segmentation
- ▶ Be able to implement your own U-net architecture
- ▶ Be able to reason about the U-net's construction and the roles played by its different parts

What is image segmentation?

# What is image segmentation?



Rönnberger et al, 2015

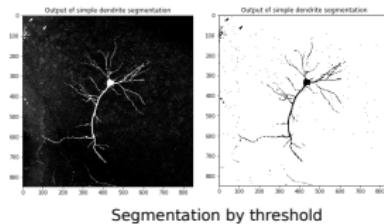
- ▶ Overall task: Partitioning an image into its objects and background – segmenting volumes and boundaries
- ▶ Difference from detection: Not just a bounding box

# What is image segmentation?



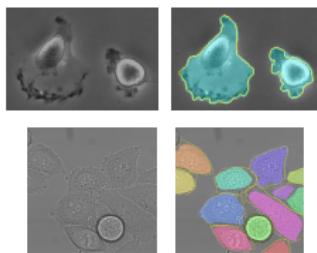
Active shape model

## "Old school" algorithms



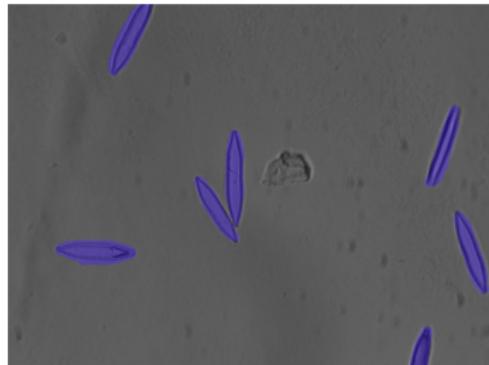
Segmentation by threshold

## Voxel classification (today: deep learning)

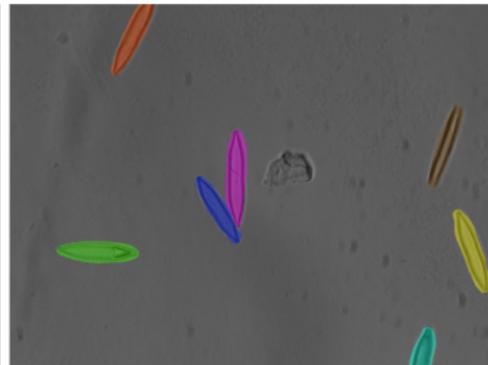


# What is image segmentation?

Semantic segmentation versus instance segmentation



(a) Semantic segmentation mask.



(b) Instance segmentation mask.

We will focus on semantic segmentation.

What is image segmentation  
useful for?

## Application: Preprocessing

Brain tissue segmentation: Constraining analysis to relevant regions

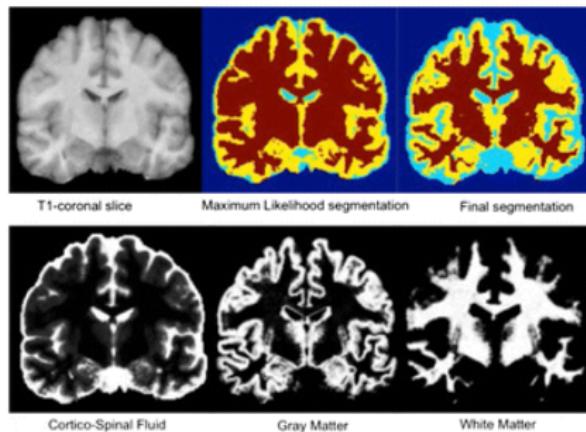


Figure: Figure from Villalon-Reina et al, 2016

## Application: Preprocessing

Brain region segmentation: Building a connectivity network

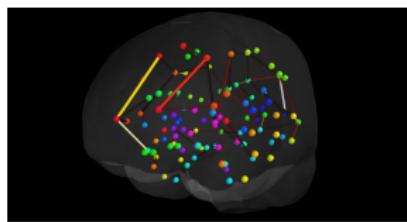
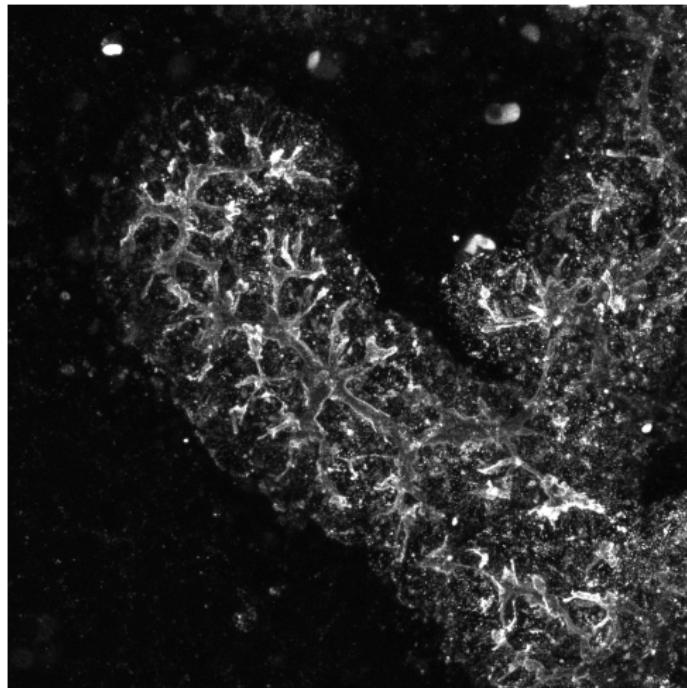


Figure: Left figure from Fan et al, 2016

# Application: Extracting objects for scientific discovery



## Predicting disease or focusing treatment

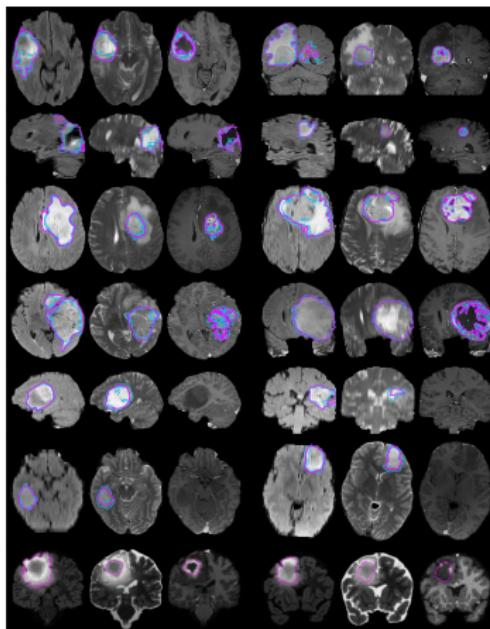
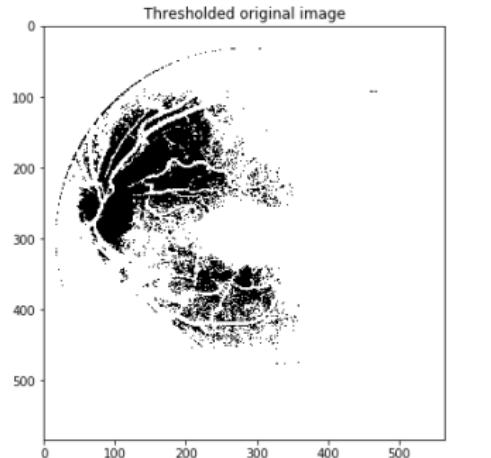
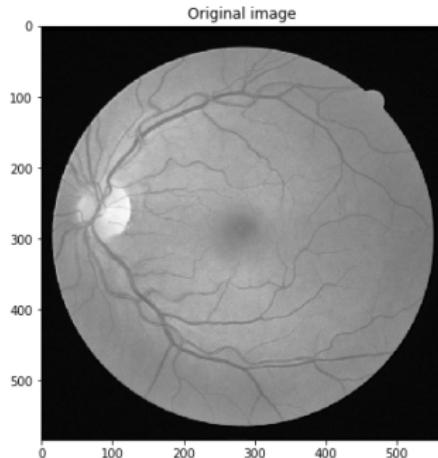


Figure: From the BRATS challenge dataset.

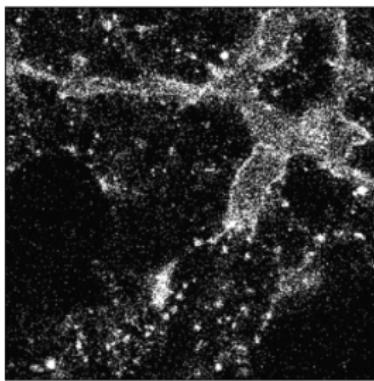
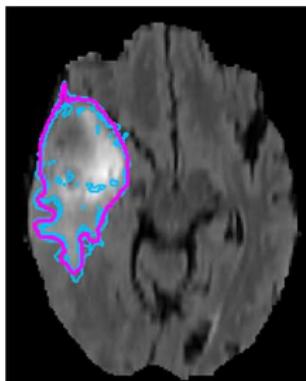
# Challenges in image segmentation

## Background inhomogeneity



# Challenges in image segmentation

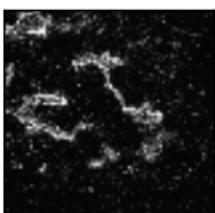
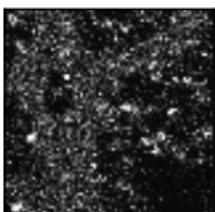
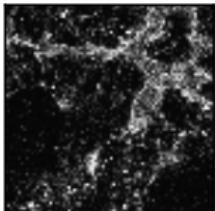
## Fuzzy boundaries



# Challenges in image segmentation

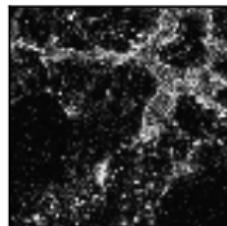
Noisy labels, few labels

Original image    Expert annotation



# Challenges in image segmentation

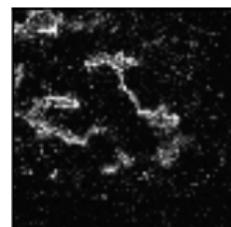
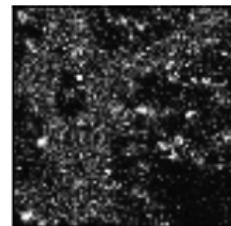
Original image



U-net segmentation



Expert annotation



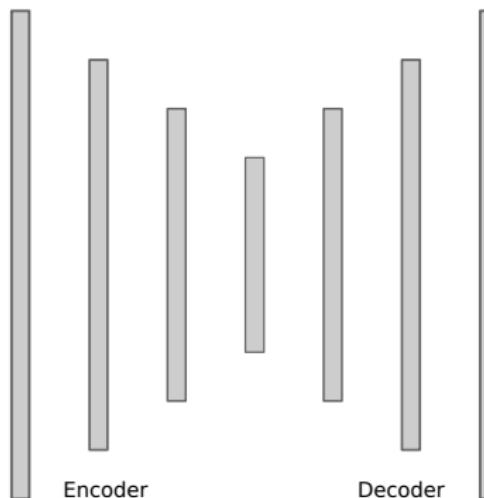
Small pixel error can be large object error

Questions?

# CNNs for segmentation

## It's "all" in the final layer

- ▶ You want a pixel-wise classification
- ▶ In principle: A CNN with output same size as your image, with a softmax at the end, will give you a segmentation network
- ▶ Good networks require a little more modelling



## Example: SegNet

- ▶ An encoder-decoder network
- ▶ Transports pooling indices to the decoder to obtain better upsampling

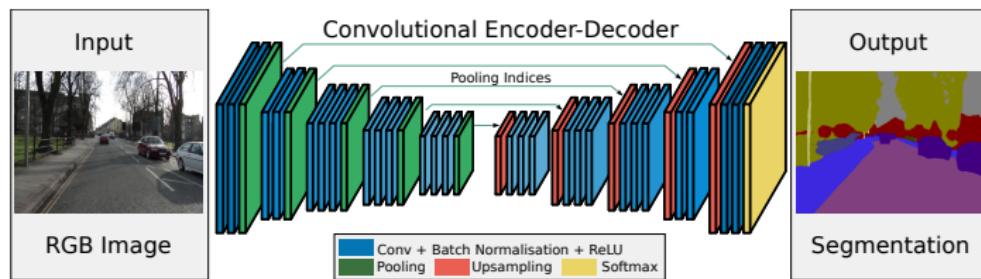


Figure: SegNet, Badrinarayanan et al, 2016

# The U-net (Rönnéberger et al, 2015)

- ▶ The U-net (<https://arxiv.org/abs/1505.04597>) and variants thereof still remain state-of-the-art for biomedical image segmentation

## U-Net: Convolutional Networks for Biomedical Image Segmentation

Olaf Ronneberger, Philipp Fischer, and Thomas Brox

Computer Science Department and BROSS Centre for Biological Signalling Studies,

### A Probabilistic U-Net for Segmentation of Ambiguous Images

Simon A. A. Kukl<sup>1,2</sup>, Bernhardino Romera-Paredes<sup>1</sup>, Clemens Moyer<sup>1</sup>, Jeffrey De Fauw<sup>1</sup>, Joseph R. Ichbiah<sup>1</sup>, Klaus H. Maier-Hein<sup>1</sup>, S. M. Ali Eslami<sup>1</sup>, Danilo Jimenez Rezende<sup>1</sup>, and Olaf Ronneberger<sup>2</sup>

<sup>1</sup>DeepMind, London, UK

<sup>2</sup>Division of Medical Image Computing, German Cancer Research Center, Heidelberg, Germany

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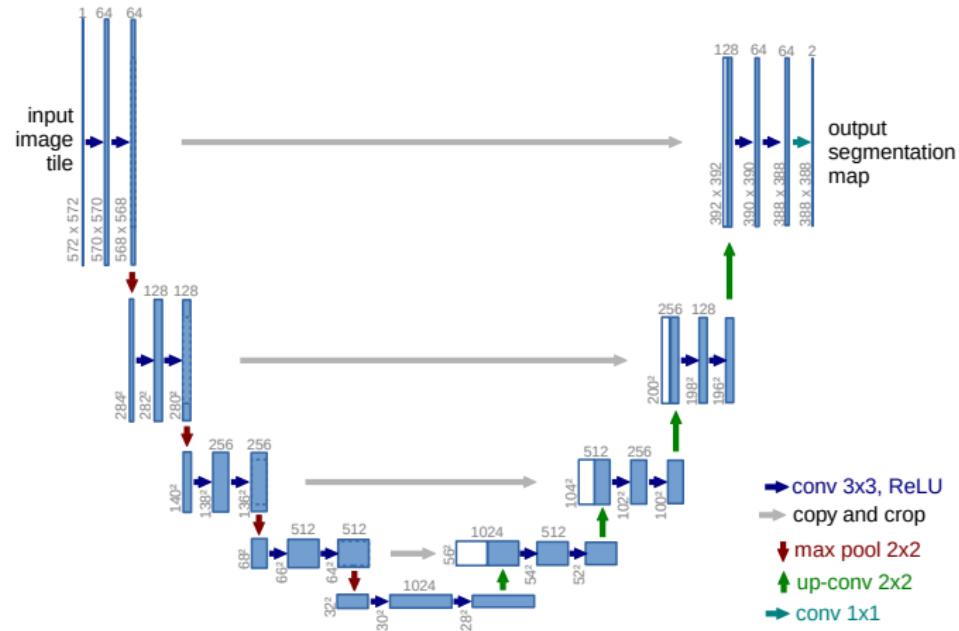
#### Abstract

Many real-world vision problems suffer from inherent ambiguity. In clinical applications for example, it might not be clear from a CT scan alone which particular region is cancer tissue. Therefore a group of graders typically produces a set of diverse but plausible segmentations. We consider the task of learning a

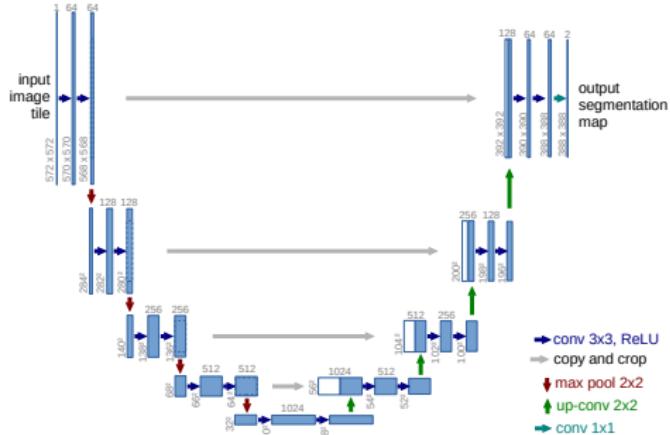
18 May 2015

.CV] 29 Jan 2019

# The U-net



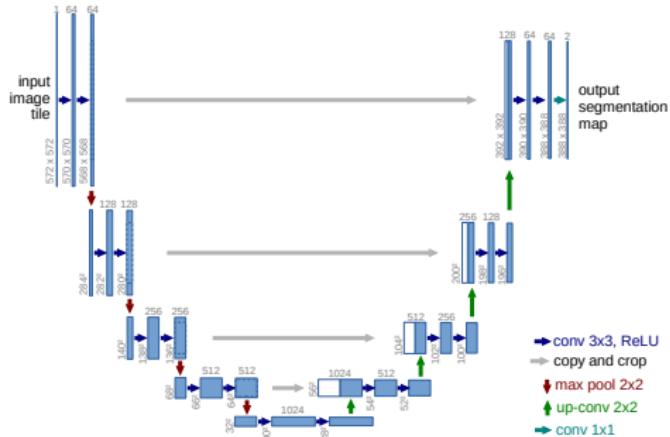
# The U-net



Discuss with your neighbor:

- ▶ Input and output have different sizes. Why?
- ▶ How do you map an output segmentation pixel to its corresponding input pixel?

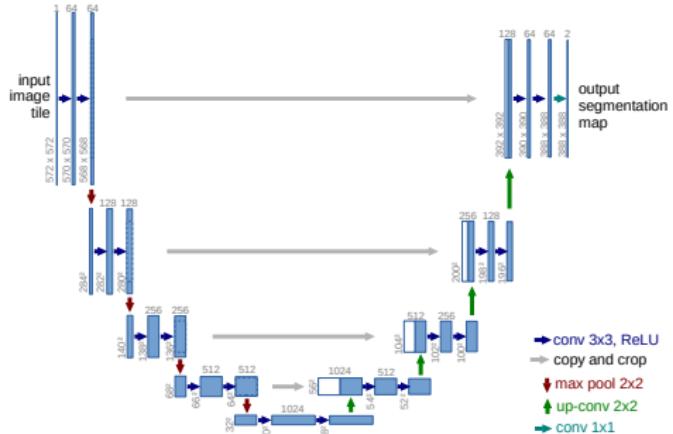
# The U-net



Discuss with your neighbor:

- ▶ The architecture – why does it look the way that it looks?
- ▶ What is the role of the max pooling and up-convolutions?
- ▶ What is the role of the skip connections?

# Questions?



## A few hints and observations

- ▶ The implementation in Exercise 2 of the U-net does not follow the figures precisely: Differences in depth, nr of convolutions, and padding. For your own simplicity, you may want to use a padding that matches your convolutional kernels to ensure that the output image has the same size as the input.
- ▶ Loss functions: Implementing your own is great for learning, but you may run into numerical issues. Try to figure out what causes them – but otherwise, a safe rescue is usually to use a built-in

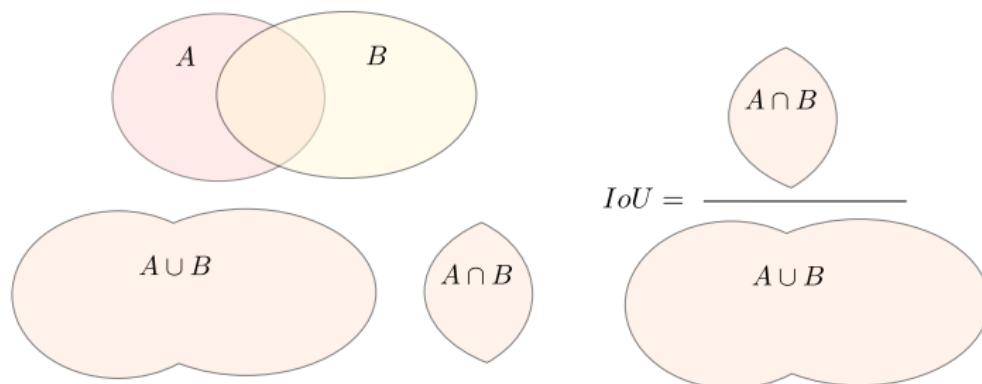
## How well did your segmentation do? Validation metrics

Accuracy:

$$\frac{\# \text{ correctly classified pixels}}{\# \text{ pixels in total}}$$

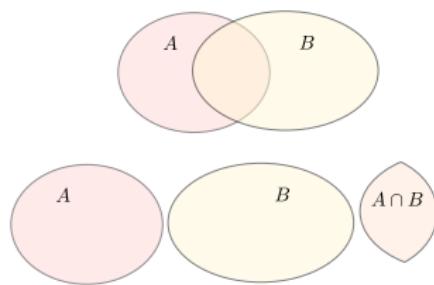
## How well did your segmentation do? Validation metrics

Intersection over Union (IoU)/Jaccard



# How well did your segmentation do? Validation metrics

## Dice



$$Dice = \frac{2|A \cap B|}{|A| + |B|} = \frac{\text{Area of } A \cap B}{\text{Area of } A + \text{Area of } B}$$

Two diamond-shaped regions, each labeled 'A ∩ B', representing the intersection area of sets A and B.

Two separate diamond-shaped regions, each labeled 'A ∩ B', representing the individual areas of sets A and B.

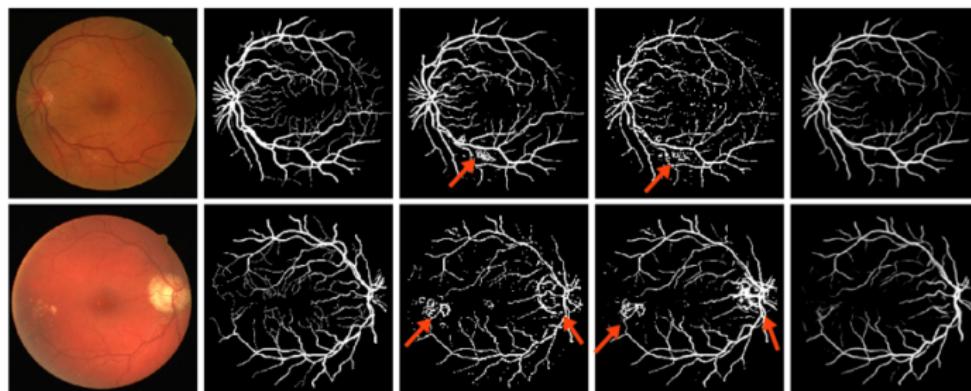
In today's exercise, you will use a version of Dice as a loss function.

## How well did your segmentation do? Validation metrics

Can you imagine a situation where these are poor measures?

# How well did your segmentation do? Validation metrics

Can you imagine a situation where these are poor measures?



(A) Fundus image

(B) Ground truth

(C) Nguyen et al. 2013

(D) Orlando et al. 2014

(E) Our DeepVessel

# How well did your segmentation do? Validation metrics

## Sensitivity/Specificity

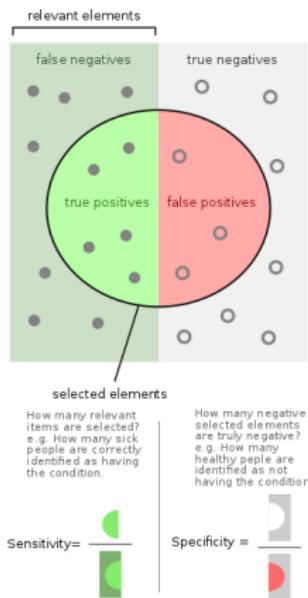


Figure from [https://commons.wikimedia.org/wiki/File:Sensitivity\\_and\\_specificity.svg](https://commons.wikimedia.org/wiki/File:Sensitivity_and_specificity.svg)

A couple of useful  
techniques

# Dilated convolutions<sup>1</sup>

Alternative to the alternating convolutional / pooling layers:

Exponentially dilate the convolutional kernel:



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<sup>1</sup><https://arxiv.org/pdf/1511.07122.pdf>

# Dilated convolutions

Exponentially enlarged receptive field as you move through the layers:

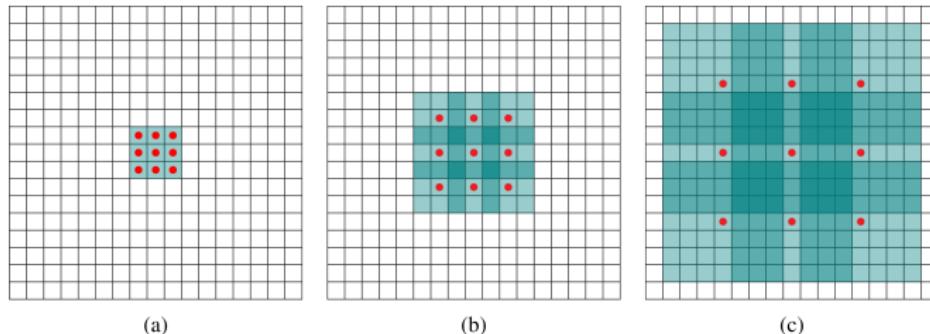
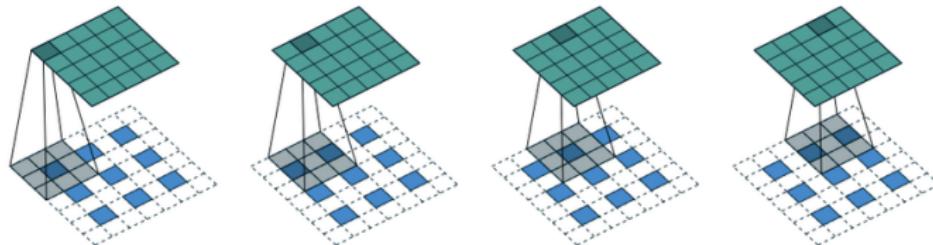


Figure 1: Systematic dilation supports exponential expansion of the receptive field without loss of resolution or coverage. (a)  $F_1$  is produced from  $F_0$  by a 1-dilated convolution; each element in  $F_1$  has a receptive field of  $3 \times 3$ . (b)  $F_2$  is produced from  $F_1$  by a 2-dilated convolution; each element in  $F_2$  has a receptive field of  $7 \times 7$ . (c)  $F_3$  is produced from  $F_2$  by a 4-dilated convolution; each element in  $F_3$  has a receptive field of  $15 \times 15$ . The number of parameters associated with each layer is identical. The receptive field grows exponentially while the number of parameters grows linearly.

## Transpose-convolutions

Another alternative upsampling strategy: Dilate the image prior to convolution.



Can lead to line-like artefacts due to uneven coverage of the image content.

## Now what?

Today, you will work with Exercise 2, which you find on Learn.

# Summary

By now you should

- ▶ Know what image segmentation is, along with some of its applications
- ▶ Be familiar with challenges associated with image segmentation
- ▶ Be able to implement and validate a CNN for image segmentation
- ▶ Be able to implement your own U-net architecture
- ▶ Be able to reason about the U-net's construction and the roles played by its different parts