# MOTION LEARNING AND MONITORING

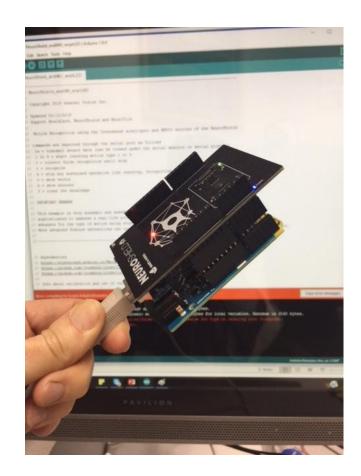
Powered by a NeuroMem network

On Arduino platform

General Vision Technical Brief

### Assembly

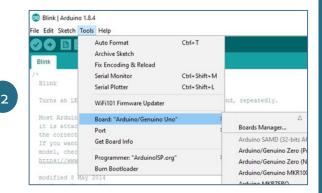
- Arduino microcontroller board with at least 3 KB of dynamic memory
- NeuroShield featuring
  - InvenSense Accel/Gyro
  - 576 NeuroMem neurons
- Optional set of spacers

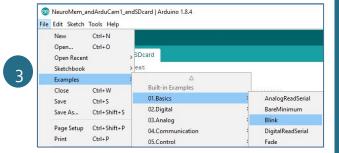




#### Installation

- Download the latest Arduino IDE (<u>https://www.arduino.cc/en/Main/Software</u>)
- 2. Under the Tools\Board menu, select your board model.
  - If not in the list, select Board Manager and install its driver
- 3. Load the File\Examples\Basic\Blink script
- 4. Upload the script to your board
- 5. Verify that the LED is blinking







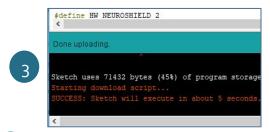


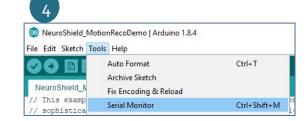


# Running the demo

- 1. Load the NeuroShield\_MotionRecoDemo
- 2. Upload the script to the Arduino
- 3. Verify that the upload is successful.
  - If not, go to troubleshooting slide
- 4. Open the serial Monitor
- 5. Follow the instructions on the screen.
  - If the window is blank and frozen, go to the Troubleshooting slide









# Academic training case

- Move the board up and down
- Type 1+Enter to teach vertical motion
- Move the board left and right
- Type 2+Enter to teach horizontal motion
- Stop moving
- Type o + Enter to teach "No motion"

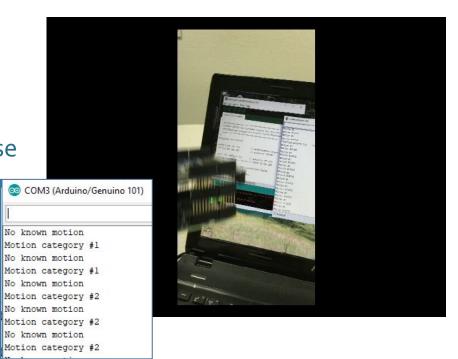
```
com3 (Arduino/Genuino 101)
NeuroMem Smart device is initialized!
Neuron capacity = 576
NN Maxif = 32768
IMU connection successful!
Calibration... Make sure your board is stable. Type enter when ready
Calibration terminated
Type a command + Enter
         1 to 9 = start learning motion type 1 to 9
         0 = incorrect recognition
             transmit sensor data
         c = show configuration
         f = clear the knowledge

✓ Autoscroll
```



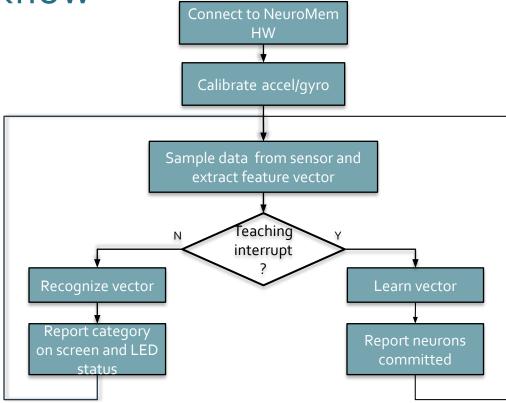
# Continuous recognition

- Report 1 for up-down motion
- Report 2 for left-right motion
- Report Unknown for anything else





# Script workflow





**Technical Brief** 

#### About the feature extraction

- // This example is very academic and assemble a simple sequence pattern which should be more
- // sophisticated to address a real-life problem such as real-time sampling rate and calibration
- // adequate for the type of motion being studied.
- // More advanced feature extractions can include waveform profiles, distribution of peaks and zero crossing, etc.

```
NeuroShield_MotionRecoDemo

for (int j=0; j<sampleNbr; j++)
{
   getSensorData();
   vector[(j*channelNbr)]= (int) (ax);
   vector[(j*channelNbr)+1]= (int) (ay);
   vector[(j*channelNbr)+2]= (int) (az);
   vector[(j*channelNbr)+3]= (int) (gx);
   vector[(j*channelNbr)+4]= (int) (gy);
   vector[(j*channelNbr)+5]= (int) (gz);</pre>
```

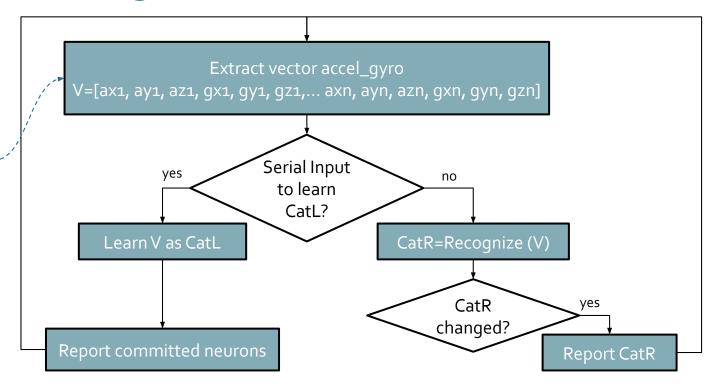
Collect N consecutive measurements of ax, ay, az, gx, gy, gz and append to a feature vector



# Example using 1 feature

Quick & simple sampling

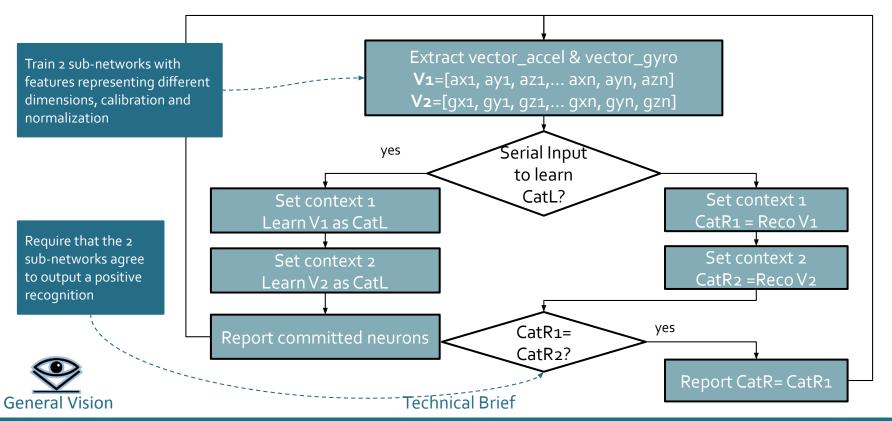
WARNING: combines data with different dimensions, different calibration and normalization





**Technical Brief** 

# Examples using 2 features

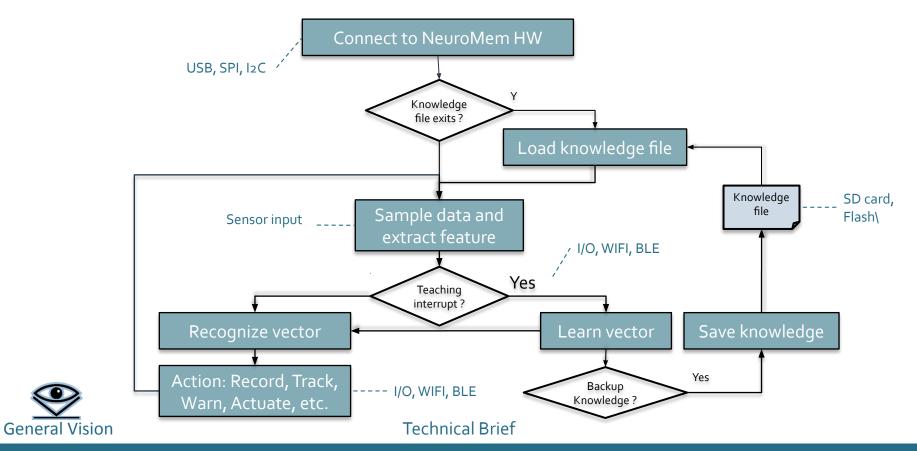


#### What is next?

- Improve the calibration routine
- Extract more advanced feature(s) depending on the application
- Improve UI to better synchronize the teaching instruction to the real-time motion
- And more....



# Typical signal monitoring workflow



# Troubleshooting

- Script does not load properly
  - Verify the selected platform and COM port under Tools menu
  - Use the board's external power supply instead of the USB power
  - Unplug all shields for the duration of the upload
- Serial monitor is blank and frozen
  - Verify the selected baud rate
  - Close the window
  - Unplug / Replug the Arduino board
  - Wait a few seconds and re-open the serial monitor

