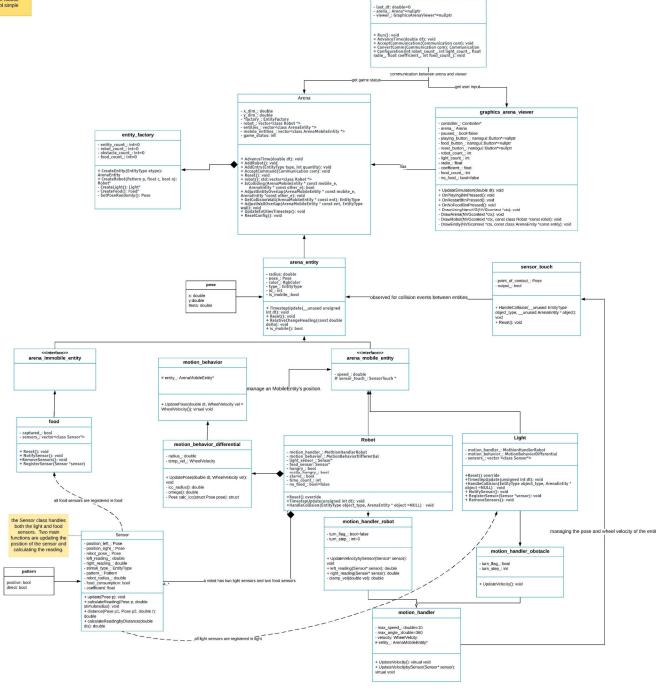
Author: Ruoyun Chen

This is a UML Class Diagram of a Braitenberg Vehicles simulator. The robots simulate Braitenberg vehicles which sense light and food in arena. These Complex robotic behaviours can be achieved by simple control simple sensor-motor connections.



controller