每周汇报

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论文列表

No.	title	Publication Source	Year
1	Boosting Coverage-Based Fault Localization via Graph-Based Representation Learning	FSE/ESEC	2021
2	A First Look at Developers' Live Chat on Gitter	FSE/ESEC	2021
3	Empirical Study of Transformers for Source Code	FSE/ESEC	2021

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Boosting Coverage-Based Fault Localization via Graph-Based Representation Learning (2021.FSE/ESEC)

Boosting Coverage-Based Fault Localization via Graph-Based Representation Learning (2021.FSE/ESEC)

SBFL (Spectrum Fault Localization)

Program entities covered by more failed tests and less passed tests are more likely to be faulty.

ID	Method signature		Coverage					SBFL	Rank		
			$\int ft_2$	pt_1	pt_2	pt_3	pt_4	pt_5	pt_6	SDIL	Nank
m_1	<pre>public String getNullText()</pre>	1	/	/	1	1				0.63	1
m_2	<pre>public StrBuilder appendFixedWidthPadLeft(Object, int, char)</pre>	/		/			1			0.41	2
m_3	<pre>public StrBuilder appendFixedWidthPadRight(Object, int, char)</pre>		/		1			/	1	0.35	3
m_4	<pre>public StrBuilder()</pre>	/	/	/	1	1	1	/		0.12	5
m_5	<pre>public StrBuilder(int)</pre>	1	/	1	1	1	1	/	1	0.12	5
m_6	<pre>public StrBuilder ensureCapacity(int)</pre>	1	1	/	1		/	/	1	0.10	6

```
public String getNullText() {
   return nullText;}

public StrBuilder appendFixedWidthPadLeft(Object, int, char) {
   if (width > 0) {
      ensureCapacity(size + width);
      String str = (obj == null ? getNullText() : obj.toString());
      int strLen = str.length(); // bug
      ...
```

Figure 1: Code snippets of m_1 and m_2

Boosting Coverage-Based Fault Localization via Graph-Based Representation Learning (2021.FSE/ESEC)

Nodes:

- Program entities
- Tests

Edges:

- Coverage relationships
- Code structures

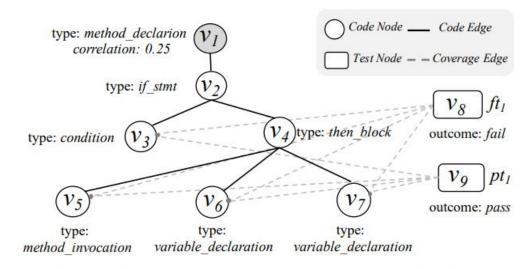


Figure 2: Representations for the method m_2

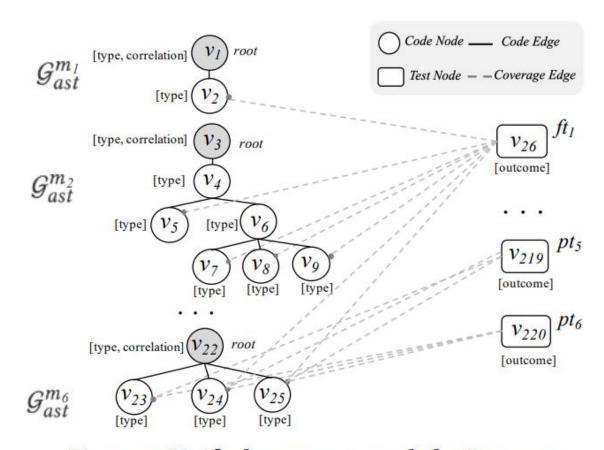


Figure 3: Unified coverage graph for Lang-47

$$cor(w_m, w_t) = len(w_m \cap w_t)/len(w_t)$$

Boosting Coverage-Based Fault Localization via Graph-Based Representation Learning (2021.FSE/ESEC)

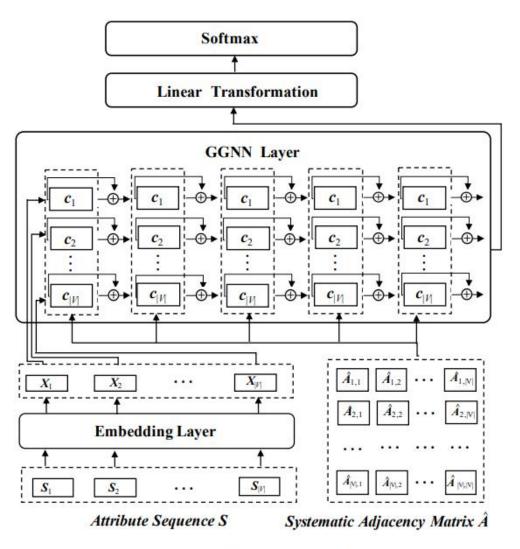


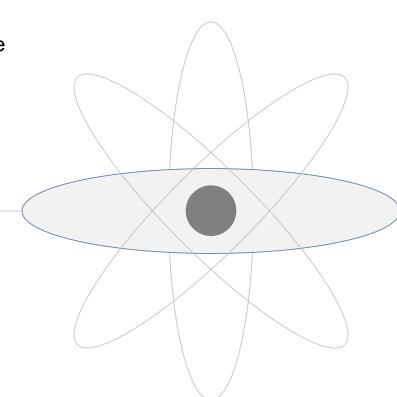
Figure 4: Architecture of GRACE

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A First Look at Developers' Live Chat on Gitter (2021. FSE/ESEC)

RQ1(Communication Profile)

 Do Gitter communities demonstrate consistent community communication profiles?



RQ2(Community Structure)

 What are the structural characteristics of social networks built from developer live chat data?

RQ3(Dialog Topic)

 What are the primary topic types frequently discussed by developers in live chat?

RQ4(Interaction Pattern)

 How do developers typically interact with each other in live chat?

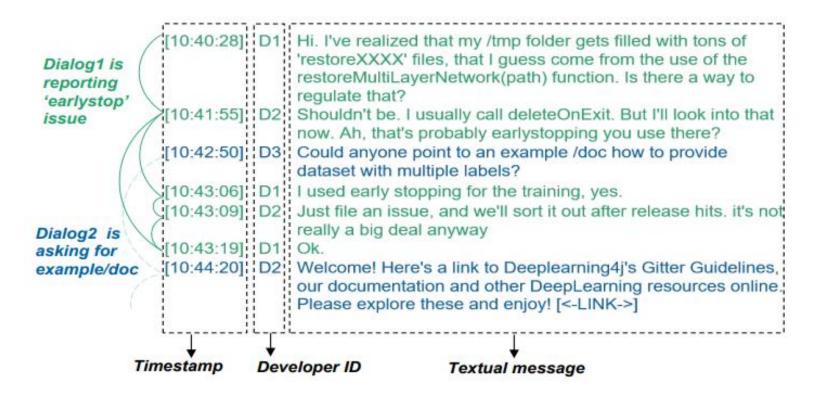


Figure 1: A slice of live chat log from the DL4J community.

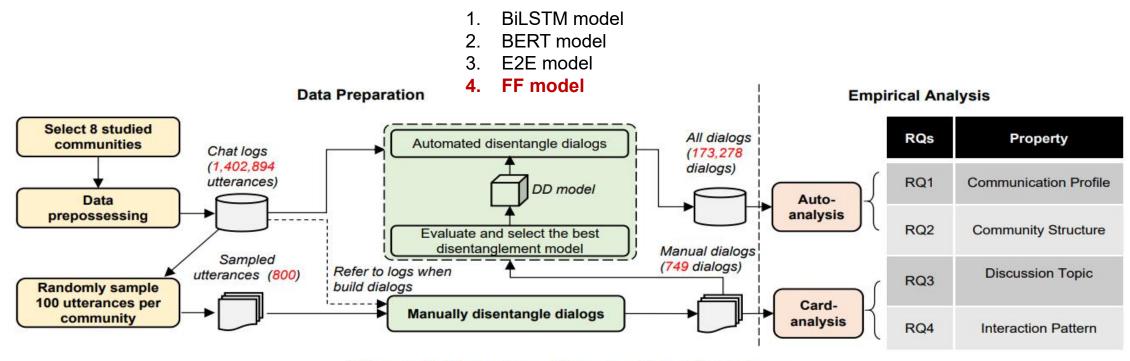


Figure 2: Overview of research methodology

When the developers are active?

How long the respondent replies to the dialog initiator?

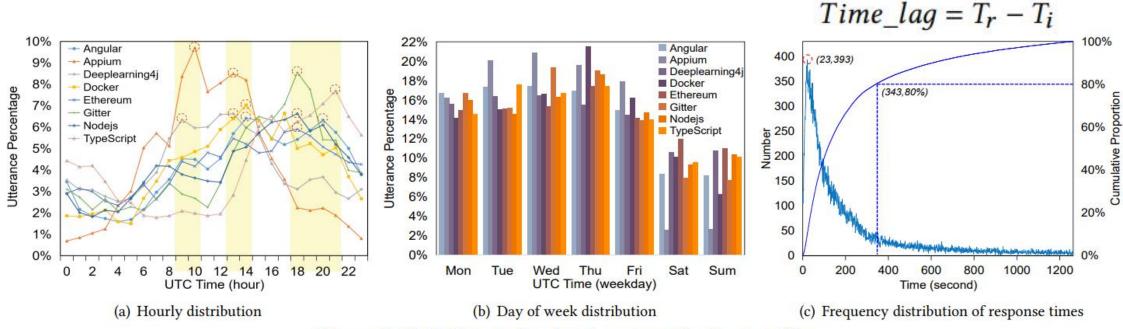
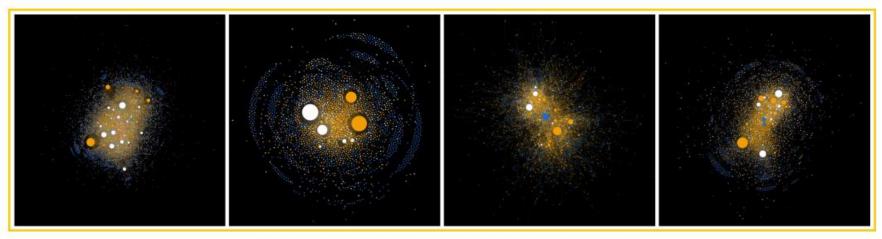
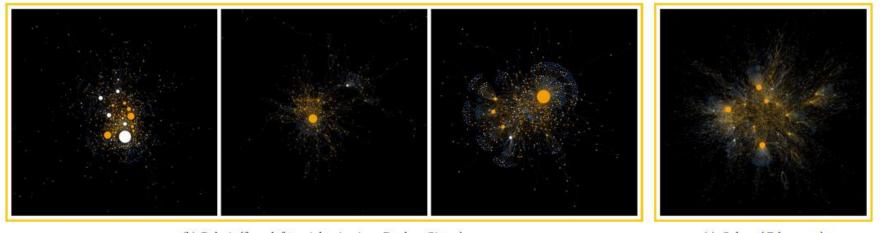


Figure 3: Statistic results about communication profiles

RQ2 Initiator: Blue, Respondent: White, Both: Orange



(a) Constellation (from left to right: Angular, DL4J, Nodejs, Typescript)



(c) Galaxy { Ethereum }

RQ3

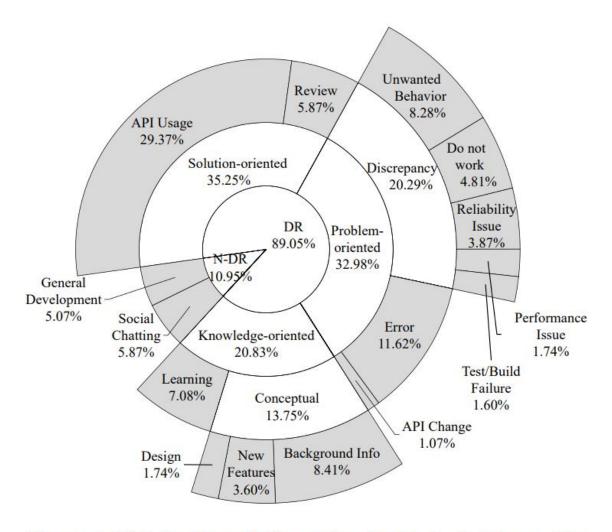


Figure 5: Distribution of discussion topics in developer live chat by reading from center to outside

Table 2: Developer intent category in live chat

RQ4

Code	Label	Description			
OQ	Original Question	The first question from the developer to initiate the dialog			
CQ	Clarifying Question	Developers ask for clarifications			
FD	Further Details	Developers provide more details			
FQ	Follow Up Question	Developers ask for follow up questions about relevant issues			
PA	Potential Answer	A potential answer or solution provided by developers			
PF	Positive Feedback	Developer provides positive feedback for working solutions			
NF	Negative Feedback	Developer provides negative feedback for useless solutions			
GG	Greetings/Gratitude	Greetings or expressing gratitude			

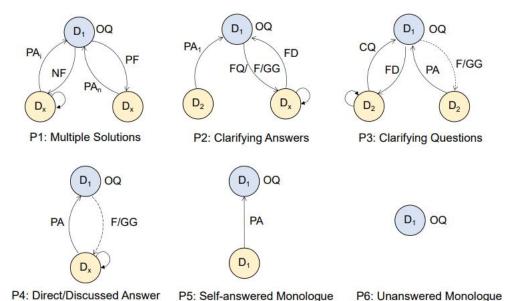


Figure 6: Interactive patterns, F denotes feedback including negative feedback and positive feedback, dashed lines denote optional interaction.

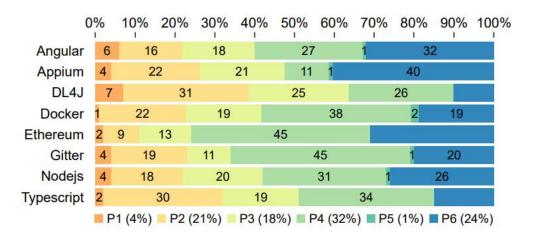


Figure 7: Distribution of interaction patterns among different communities

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Sequential positional encodings and embeddings

$$p_i \in R^{d_{model}} : \hat{x}_i = x_i + p_i$$

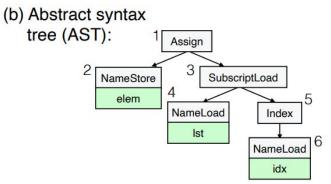
Sequential relative attention

$$z_{i} = \sum_{j} \tilde{\alpha}_{ij} (x_{j}^{v} + e_{i-j}^{v}), \ \tilde{\alpha}_{ij} = \frac{\exp(a_{ij})}{\sum_{j} \exp(a_{ij})}, \ a_{ij} = \frac{x_{i}^{q} (x_{j}^{k} + e_{i-j}^{k})^{T}}{\sqrt{d_{z}}}$$

 $e_{i-j}^v, e_{i-j}^k \in \mathbb{R}^{d_z}$ are learned embeddings for each relative position i-j

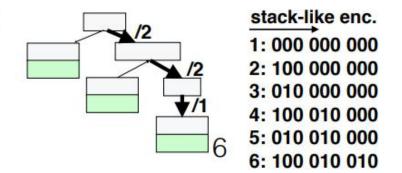
Tree positional encodings

(a) Code: elem = lst[idx]



(d) Tree positional encodings:

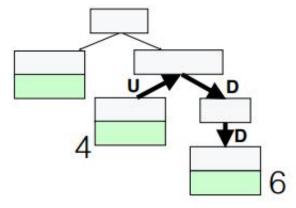
1	2	3	4	5	6
/	/1	/2	/2/1	/2/2	/2/2/1



n_w——the maximum number of children node n_d——the maximum depth of the tree

Tree relative attention

(e) Tree relative attention:



	1	2	3	4	5	6
1	I	D	D	DD	DD	DDD
2	U	I	UD	UDD	UDD	UDDD
3	U	UD	I	D	D	DD
4	UU	UUD	U	I	UD	UDD
5	UU	UUD	U	UD	I	D
6	UUU	UUUD	UU	UUD	U	I

$$\tilde{\alpha}_{ij} = \frac{\exp(a_{ij} \cdot r_{ij})}{\sum_{j} \exp(a_{ij} \cdot r_{ij})}$$

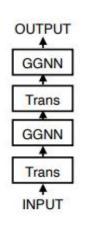
GGNN Sandwich

(f) GGNN Sandwich:

Types of edges:

- · Parent (P) · Left (L)
- · Child (C) · Right (R) · Self (S)

	1	2	3	4	5	6
1	S	P, L	P			
2	C, R	S	L			
3	С	R	S	P, L	P	
4			C, R	S	L	
5			С	R	S	P, L
6					C, R	S



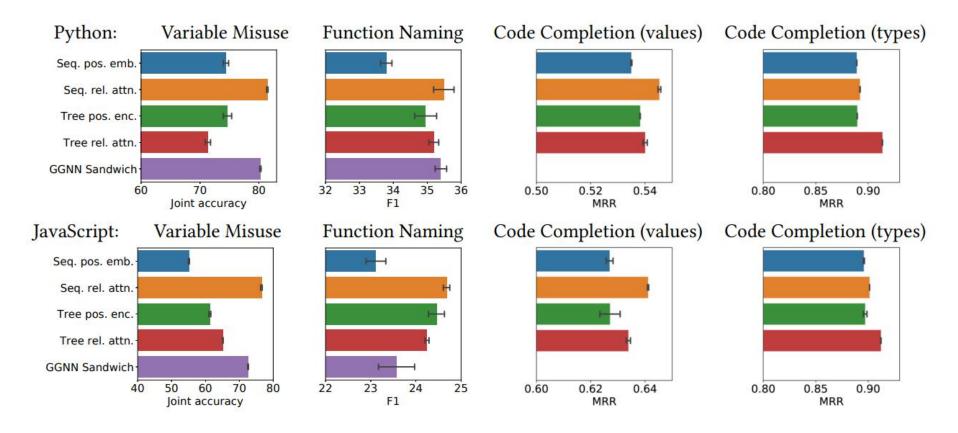


Figure 2: A comparison of different mechanisms for processing AST structure in Transformer, in the full-data setting. The numeric data for barplots is given in Supplementary materials.

Table 2: Time- and storage-consumption of different structure-capturing mechanisms for the variable misuse task on the Python dataset.

Model	Train time (h/epoch)	Preprocess time (ms/func.)	Add. train data (GB)
Seq. pos. emb.	2.3	0	0
Seq. rel. att.	2.7	0	0
Tree pos. enc.	2.5	0.4	0.3
Tree rel. attn.	3.9	16.7	18
GGNN Sandwich	7.2	0.3	0.35

Table 3: Comparison of combinations of sequential relative attention (SRA) with other structure-capturing approaches. All numbers in percent, standard deviations: VM: 0.5%, FN: 0.4%, CC: 0.1%. Bold emphasizes combinations that significantly outperform SRA. *In the VM task, SRA+GGNN Sandwich significantly outperforms SRA during the first half of epochs, but loses superiority at the last epochs, for both datasets. On the Python dataset, SRA+GGNN Sandwich outperforms SRA by one standard deviation at the last epoch.

	Model	VM	FN	CC (val.)
PY	SRA	81.42	35.73	54.53
	SRA + Seq. pos. emb.	80.77	33.99	54.37
PY	SRA + Tree pos. enc.	81.73	34.71	54.63
	SRA + Tree rel. attn.	81.58	35.41	54.91
	SRA + GGNN sand.	82.00*	33.39	N/A
JS	SRA	76.52	24.62	64.11
	SRA + Seq. pos. emb.	73.17	23.09	63.97
	SRA + Tree pos. enc.	74.73	23.70	64.49
JS	SRA + Tree rel. attn.	76.34	24.71	64.79
	SRA + GGNN sand.	75.33*	21.44	N/A

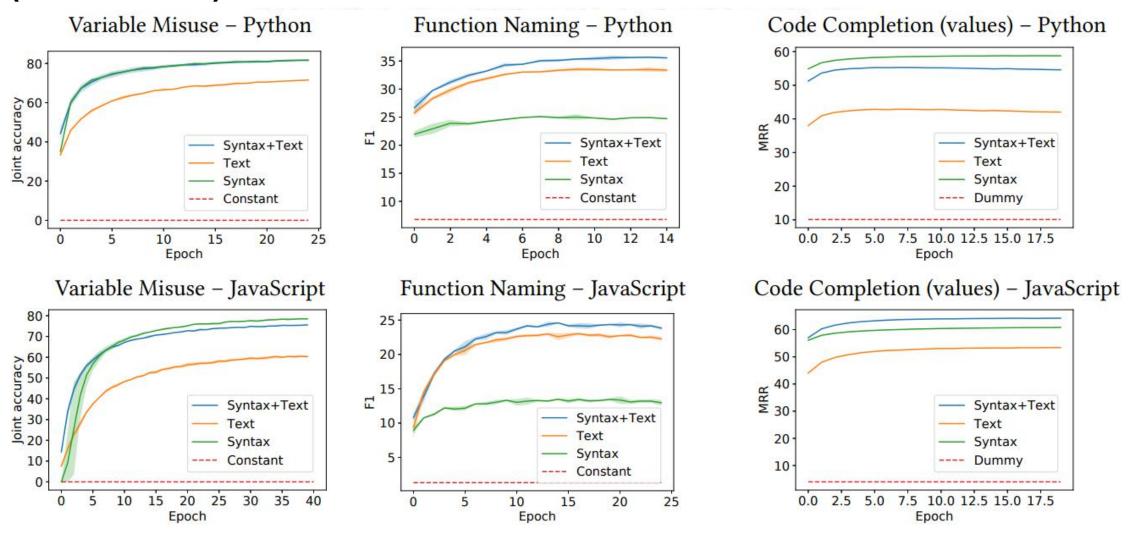


Figure 3: Comparison of syntax-based Transformer models with text-only and constant baselines.

Thanks!