



《An Empirical Study of Model- Agnostic Techniques for Defect Prediction Models》	2020	TSE
《CC2Vec: Distributed Representations of Code Changes》	2020	ICSE
《Are fix-inducing changes a moving target? a longitudinal case study of just-in-time defect prediction》	2017	TSE

ADUATION DEFE



Explanation

- (1) the event to be explained, also called the explanandum(e.g., file A is defective);
- (2) a set of similar events that are similar to the explanandum but did not occur (e.g., file A is clean);
- (3) a request for information that can distinguish the occurrence of the explanandum from the non-occurrence of the other similar events (e.g., a large number of changes made to file A).



2020 TSE

Model-Agnostic Techniques

LIME, LIME-HPO, Breakdown

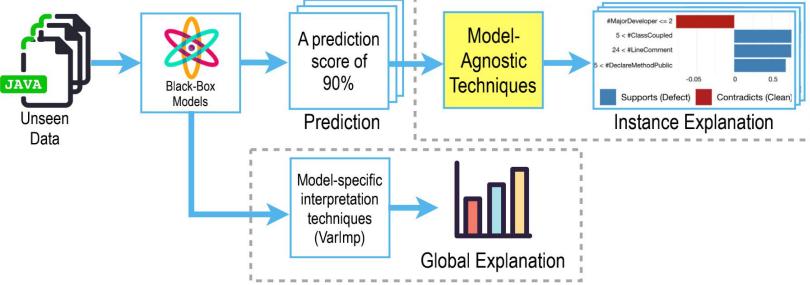
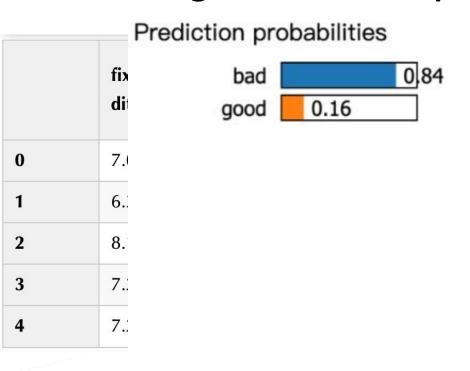


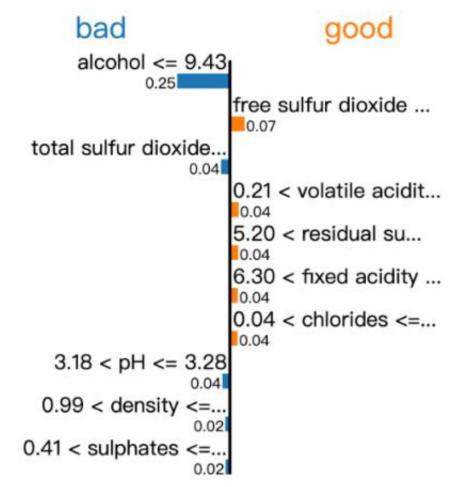
Figure 1: An illustration of model-agnostic techniques. Model-agnostic techniques are used to explain the predictions of unseen data, while the global explanation is derived from the trained models from training data. In other words, one model can have only one global explanation, but should have multiple instance explanations.



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Model-Agnostic Techniques





Feature	value
alcohol	9.20
free sulfur dioxide	52.00
total sulfur dioxide	209.00
volatile acidity	0.25
residual sugar	7.80
fixed acidity	6.40
chlorides	0.04
pН	3.21
density	1.00



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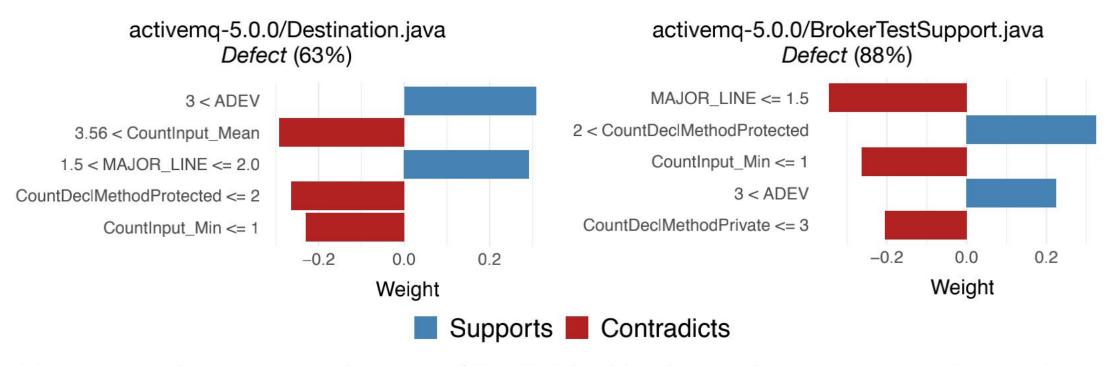
RF、LR... Repeat 100 times Apply model-specific Analyse Remove Construct explanation Global global correlated defect techniques Training Defect Non-correlated Explanation explanation metrics models Samples Metrics Models land instance Generate Apply explanations training model-agnostic and testing techniques Instance Defect samples Testing **Explanations** Dataset Samples Generate Analyse predicted model probability performance Predicted **Probabilities**

Figure 3: An overview diagram of the design of our case study.

LIME, LIME-HPO, Breakdown

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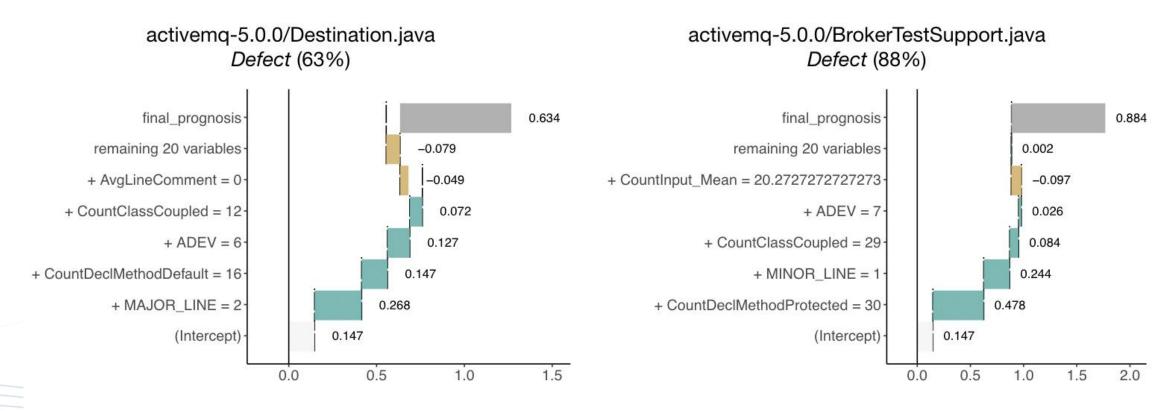
Can model-agnostic techniques explain the predictions of defect models?



(a) An example instance explanation of LIME. The blue bars indicate supporting (positive) scores towards a file being predicted as defective, while the red bars indicate contradict (negative) scores towards its prediction.

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Can model-agnostic techniques explain the predictions of defect models?



(b) An example instance explanation of BreakDown. The x-axis presents the contribution (probability score) of each metric in the y-axis.

CC2Vec: Distributed Representations of Code Changes

2020 ICSE

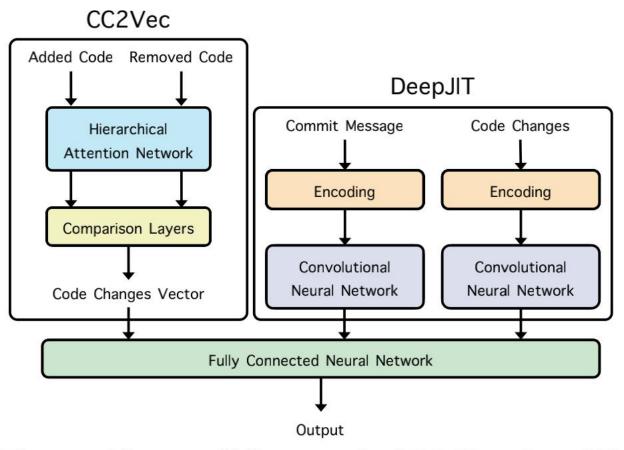
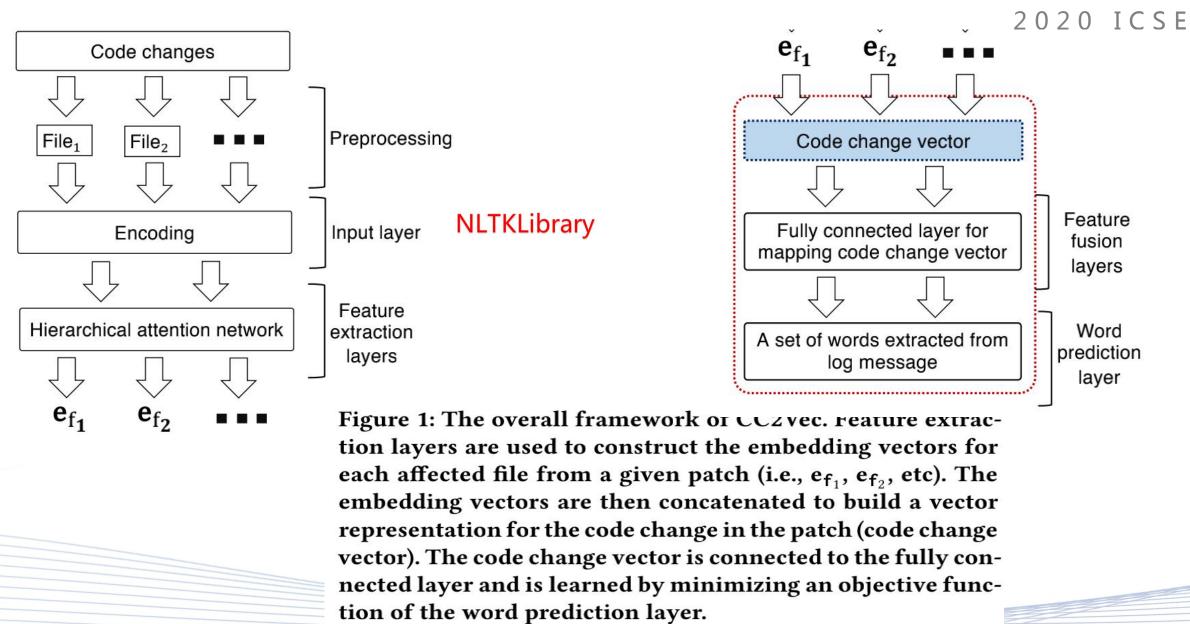


Figure 2: The overall framework of CC2Vec + DeepJIT



CC2Vec: Distributed Representations of Code Changes





CC2Vec: Distributed Representations of Code Changes

2020 ICSE

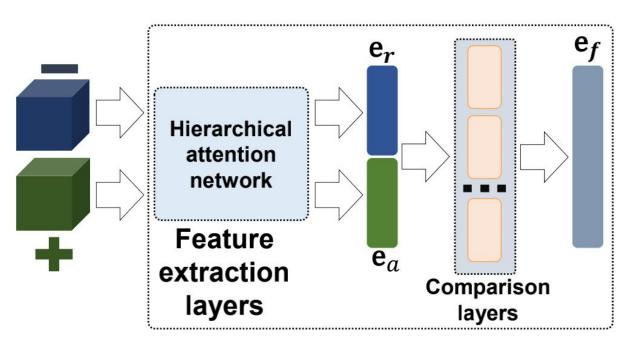


Figure 2: Architecture of the feature extraction layers for mapping the code change of the affected file in a given patch to an embedding vector. The input of the module is the removed code and added code of the affected file, denoted by "-" and "+", respectively.

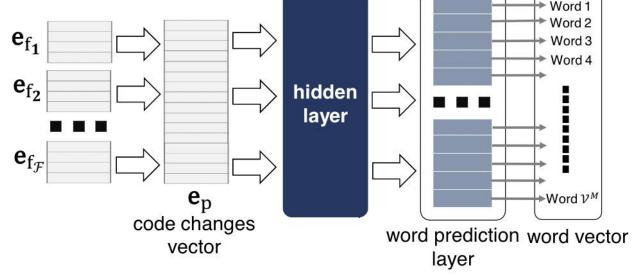


Figure 5: The details of the red dashed box in Figure 1. It takes as input a list of embedding vectors of the affected files of a given patch (i.e., e_{f_1} , e_{f_2} , ..., $e_{f_{\mathcal{F}}}$). e_p is the vector representation of the code change and is fed to a hidden layer to produce the word vector (i.e., the probability distribution over words). \mathcal{V}^M is a set of words extracted from the first line of the log messages.



Central Question: <u>Do the important properties of fix-inducing</u> <u>changes remain consistent as systems evolve?</u>

Fix-inducing Changes

Despite the advantages of JIT defect prediction, like all prediction models, they assume that the properties of past events (i.e., fix-inducing changes) are similar to the properties of future ones.



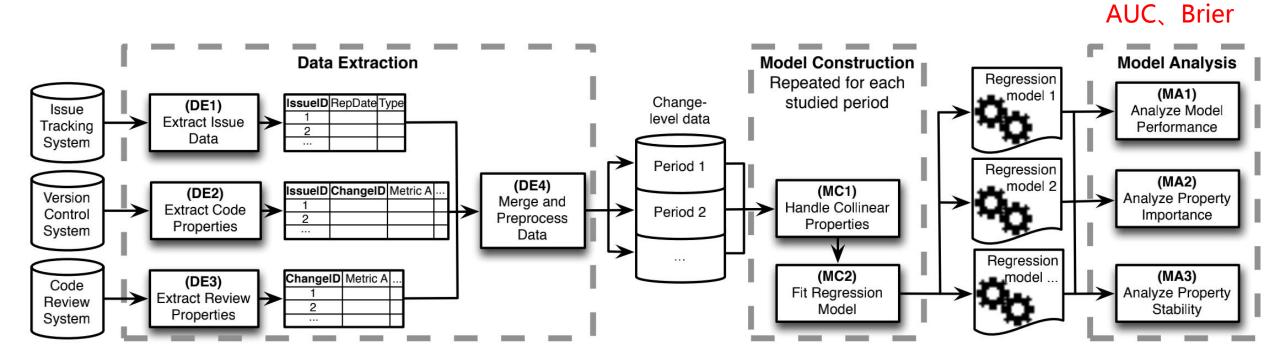


Fig. 2. An overview of the design of our case study. SZZ Algorithm



	Property	Description	Rationale	
Size	Lines added	The number of lines added by a change.	The more code that is changed, the more likely that defects	
	Lines deleted	The number of lines deleted by a change.	will be introduced [31].	
no	Subsystems	The number of modified subsystems.	Scattered changes are riskier than focused ones because they	
Diffusion	Directories	The number of modified directories.	require a broader spectrum of expertise 6 14.	
#	Files	The number of modified files.		
Ä	Entropy	The spread of modified lines across file.		
	Unique changes	The number of prior changes to the modified	More changes are likely more risky because developers will have to	
\sim		files.	recall and track many previous changes [18].	
tor	Developers	The number of developers who have changed	Files previously touched by more developers are likely more	
History		the modified files in the past.	risky [24].	
14	Age	The time interval between the last and current	More recently changed code is riskier than older code [10].	
	1709F006	changes.		
- a	Prior changes	The number of prior changes that an actor ¹	Changes that are produced by novices are likely to be more risky	
nc		has participated in. ²	than changes produced by experienced developers [28].	
rie	Recent changes	The number of prior changes that an actor		
- be	WH0 1004	has participated in weighted by the age of the		
Š		changes (older changes are given less weight		TABLE 6
eV.		than recent ones).		TABLE 2
	Subsystem	The number of prior changes to the modified	A taxonomy of the studied fa	amiliae of code and review properties
\simeq				armics of code and review properties.
or/R	changes	subsystem(s) that an actor has participated in.	·	armines of code and review properties.
thor/R		subsystem(s) that an actor has participated in. The proportion of the prior changes to the	Changes that involve developers who are aware of the prior	armines of code and review properties.
Author/R	changes	subsystem(s) that an actor has participated in. The proportion of the prior changes to the modified subsystem(s) that an actor has par-	Changes that involve developers who are aware of the prior changes in the impacted subsystems are likely to be less risky than	armines of code and review properties.
Author/Rev. Experience	changes Awareness ³	subsystem(s) that an actor has participated in. The proportion of the prior changes to the modified subsystem(s) that an actor has participated in.	Changes that involve developers who are aware of the prior changes in the impacted subsystems are likely to be less risky than those that do not.	armines of code and review properties.
Author/R	changes	subsystem(s) that an actor has participated in. The proportion of the prior changes to the modified subsystem(s) that an actor has participated in. Number of times that a change was revised	Changes that involve developers who are aware of the prior changes in the impacted subsystems are likely to be less risky than those that do not. The quality of a change likely improves with each iteration. Hence,	armines of code and review properties.
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Author/R	changes Awareness ³	subsystem(s) that an actor has participated in. The proportion of the prior changes to the modified subsystem(s) that an actor has participated in. Number of times that a change was revised prior to integration. Number of reviewers who have voted on	Changes that involve developers who are aware of the prior changes in the impacted subsystems are likely to be less risky than those that do not. The quality of a change likely improves with each iteration. Hence, changes that undergo plenty of iterations prior to integration may be less risky than those that undergo few 34 42. Since more reviewers will likely raise more issues so that they may	armines of code and review properties.
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	changes Awareness³ Iterations Reviewers	subsystem(s) that an actor has participated in. The proportion of the prior changes to the modified subsystem(s) that an actor has participated in. Number of times that a change was revised prior to integration. Number of reviewers who have voted on whether a change should be integrated or abandoned.	Changes that involve developers who are aware of the prior changes in the impacted subsystems are likely to be less risky than those that do not. The quality of a change likely improves with each iteration. Hence, changes that undergo plenty of iterations prior to integration may be less risky than those that undergo few 34 42. Since more reviewers will likely raise more issues so that they may be addressed prior to integration, changes with many reviewers are likely to be less risky than those with fewer reviewers 36.	armines of code and review properties.
	changes Awareness ³ Iterations	subsystem(s) that an actor has participated in. The proportion of the prior changes to the modified subsystem(s) that an actor has participated in. Number of times that a change was revised prior to integration. Number of reviewers who have voted on whether a change should be integrated or abandoned. The number of non-automated, non-owner	Changes that involve developers who are aware of the prior changes in the impacted subsystems are likely to be less risky than those that do not. The quality of a change likely improves with each iteration. Hence, changes that undergo plenty of iterations prior to integration may be less risky than those that undergo few [34][42]. Since more reviewers will likely raise more issues so that they may be addressed prior to integration, changes with many reviewers are likely to be less risky than those with fewer reviewers [36]. Changes with short discussions may not be deriving value from the	armines of code and review properties.
Review Author/R	changes Awareness³ Iterations Reviewers	subsystem(s) that an actor has participated in. The proportion of the prior changes to the modified subsystem(s) that an actor has participated in. Number of times that a change was revised prior to integration. Number of reviewers who have voted on whether a change should be integrated or abandoned. The number of non-automated, non-owner comments posted during the review of a	Changes that involve developers who are aware of the prior changes in the impacted subsystems are likely to be less risky than those that do not. The quality of a change likely improves with each iteration. Hence, changes that undergo plenty of iterations prior to integration may be less risky than those that undergo few 34 42. Since more reviewers will likely raise more issues so that they may be addressed prior to integration, changes with many reviewers are likely to be less risky than those with fewer reviewers 36.	animes of code and review properties.
	changes Awareness³ Iterations Reviewers Comments	subsystem(s) that an actor has participated in. The proportion of the prior changes to the modified subsystem(s) that an actor has participated in. Number of times that a change was revised prior to integration. Number of reviewers who have voted on whether a change should be integrated or abandoned. The number of non-automated, non-owner comments posted during the review of a change.	Changes that involve developers who are aware of the prior changes in the impacted subsystems are likely to be less risky than those that do not. The quality of a change likely improves with each iteration. Hence, changes that undergo plenty of iterations prior to integration may be less risky than those that undergo few [34] [42]. Since more reviewers will likely raise more issues so that they may be addressed prior to integration, changes with many reviewers are likely to be less risky than those with fewer reviewers [36]. Changes with short discussions may not be deriving value from the review process, and hence may be more risky [25] [26].	animes of code and review properties.
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Review	changes Awareness³ Iterations Reviewers Comments Review window	subsystem(s) that an actor has participated in. The proportion of the prior changes to the modified subsystem(s) that an actor has participated in. Number of times that a change was revised prior to integration. Number of reviewers who have voted on whether a change should be integrated or abandoned. The number of non-automated, non-owner comments posted during the review of a change. The length of time between the creation of	Changes that involve developers who are aware of the prior changes in the impacted subsystems are likely to be less risky than those that do not. The quality of a change likely improves with each iteration. Hence, changes that undergo plenty of iterations prior to integration may be less risky than those that undergo few [34] [42]. Since more reviewers will likely raise more issues so that they may be addressed prior to integration, changes with many reviewers are likely to be less risky than those with fewer reviewers [36]. Changes with short discussions may not be deriving value from the review process, and hence may be more risky [25] [26]. Changes with shorter review windows may not have spent enough time carefully analyzing the implications of a change prior to integration, and hence may be more risky [34] [42].	annies of code and review properties.



(RQ1) Do JIT models lose predictive power over time?

(RQ2) Does the

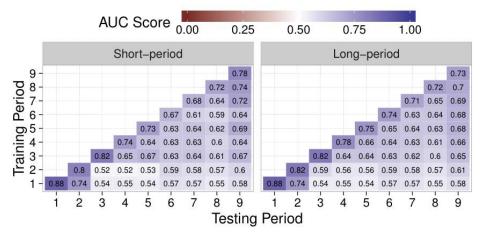
code change

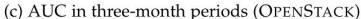
a fix evolve?

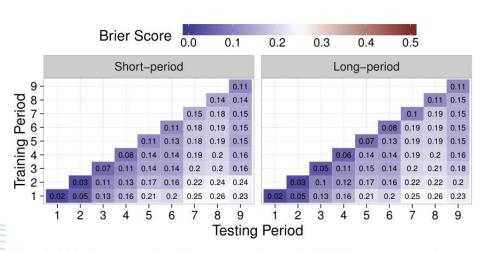
relationship between

likelihood of inducing

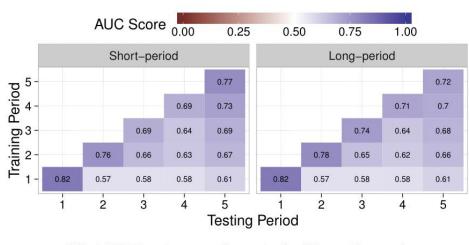
properties and the



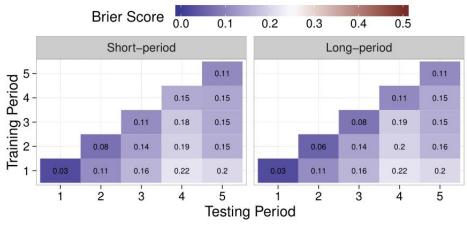




(g) Brier score in three-month periods (OPENSTACK)



(d) AUC in six-month periods (OPENSTACK)



(h) Brier score in six-month periods (OPENSTACK)