

# TBTK - Tight Binding ToolKit

A c++ library for solving tight-binding models

Designed to solve any bilinear Hamiltonian

$$H = \sum_{ij} a_{ij} c_i^\dagger c_j.$$

# Model: Indices and HoppingAmplitudes

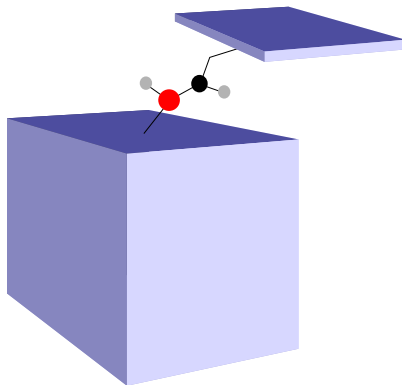
Flexible indices allows for general geometries to be defined that are not necessarily indexable by a single type of index. These are generally referred to as 'to' and 'from' indices, and are used to specify 'HoppingAmplitudes'  $a_{ij}$ .

$$H = \sum_{ij} a_{ij} c_i^\dagger c_j.$$

Index	Also known as	Example
i	to	{subsystem, x, y, spin}
j	from	{subsystem, x, y, z, orbital, spin}

# Model: Example

Consider for example a system consisting of three subsystems of different dimension.



# Model: Example

A possible indexing scheme might look like this.

3D bulk:  $\{0, x, y, z, \text{orbital}, \text{spin}\}$ ,  
1D molecule:  $\{1, x, \text{orbital}, \text{spin}\}$ ,  
2D sheet:  $\{2, x, y, \text{spin}\}$ .

# Model: Important functions

Setup model

```
Model model;
```

Add hopping amplitude

```
model.addHA(HoppingAmplitude(-mu, {x, y, s}, {x, y, s}));
```

Add hopping amplitude and Hermitian conjugate

```
model.addHAAndHC(HoppingAmplitude(-t,  
                                     {x+1, y, s},  
                                     {x, y, s}));
```

Construct model. Hilbert space is created.

```
model.construct();
```

## Model: Example

```
Model model;
for(int x = 0; x < SIZE_X; x++){
    for(int y = 0; y < SIZE_Y; y++){
        for(int s = 0; s < 2; s++){
            model.addHA(-mu, {x, y, s}, {x, y, s});
            if(x+1 < SIZE_X)
                model.addHAAndHC(-t, {x+1, y, s}, {x, y, s});
        }
    }
}
model.construct();
```

# Solvers

- DiagonalizationSolver (Eigenvalues and eigenvectors)
- ChebyshevSolver (Green's function)



# DiagonalizationSolver

The DiagonalizationSolver can be used to

- Calculate eigenvalues and eigenvectors.
- Self-consistently or non self-consistently.
- Calculate custom physical quantities by accessing the wave function directly using physical indices...
- ...or use a "property extractor" to extract common properties such as eigenvalues, DOS, spin-polarized LDOS, magnetization, etc.
- Have been tested for Hamiltonians with a basis size of up to 14000

# Diagonalization solver: Important functions

Create diagonalization solver

```
DiagonalizationSolver dSolver;
```

Set model

```
dSolver.setModel(&model);
```

Diagonalize Hamiltonian. Is done self-consistently if a self-consistent callback has been set

```
dSolver.run();
```

Set self-consistency callback, where `scCallback` is a user defined callback function

```
dSolver.setSCCallback(scCallback);
```

# Diagonalization solver: Important functions

Set maximum number of self-consistency iterations

```
dSolver.setMaxIterations(MAX_ITERATIONS);
```

Get eigenvalues

```
dSolver.getEigenValues();
```

Get amplitude of eigenstate  $n$  at index  $(x, y, s)$

```
dSolver.getAmplitude(n, {x, y, s});
```

Create property extractor

```
PropertyExtractor pe(&dSolver);
```

Get eigenvalues

```
double *ev = pe.getEV();
```

# Diagonalization solver: Important functions

Calculate DOS with a upper and lower energy cutoff of U\_LIM and L\_LIM, respectively, and a resolution of RESOLUTION number of points between L\_LIM and U\_LIM.

```
double *dos = pe.calculateDOS(U_LIM, L_LIM, RESOLUTION);
```

Calculate electron density. Will be calculated for all x and y, and spin-indices will be summed to create a total density.

```
double *density = pe.calculateDensity(  
    {IDX_X, IDX_Y, IDX_SUM_ALL},  
    {SIZE_X, SIZE_Y, 2});
```

## Diagonalization solver: Important functions

Calculate magnetization. Will be calculated for all x along the line  $y = \text{SIZE\_Y}/2$ .

```
double *mag = pe.calculateMAG(  
    {IDX_X, SIZE_Y/2, IDX_SPIN},  
    {SIZE_X, 1, 2});
```

# Diagonalization solver: Important functions

Calculate spin-polarized LDOS. Will be calculated for all  $y$  along the line  $x = \text{SIZE\_X}/2$ . Note that  $\text{IDX\_X}$  is used for the  $y$ -index here.  $\text{IDX\_X}$ ,  $\text{IDX\_Y}$ ,  $\text{IDX\_Z}$ , does for the property extractor refer to the first, second, and third loop index, and the  $y$  index is the first loop index when  $x$  is fixed. The upper and lower energy cutoff is set by  $\text{U\_LIM}$  and  $\text{L\_LIM}$ , respectively, and  $\text{RESOLUTION}$  number of points are used between the two limits.

```
double *sp_ldos = pe.calculateSP_LDOS(  
    {SIZE_X/2, IDX_X, IDX_SPIN},  
    {1, SIZE_Y, 2}  
    U_LIM, L_LIM, RESOLUTION);
```

## DiagonalizationSolver: Example

```
//Non self-consistently  
DiagonalizationSolver dSolver;  
dSolver.setModel(&model);  
dSolver.run()
```

```
//Self-consistently (requires scCallback to be defined).  
DiagonalizationSolver dSolver;  
dSolver.setModel(&model);  
dSolver.setSCCallback(scCallback);  
dSolver.setMaxIterations(MAX_ITERATIONS);  
dSolver.run();
```

# Chebyshev solver

$$G_{ij}(E) = \frac{-2i}{\sqrt{1-E^2}} \sum_n^{\infty} b_{ij}^{(n)} e^{-in \arccos(E)}.$$



- Calculates the Green's function
- Can be done either on CPU or GPU
- Works for Hamiltonians with a basis size of at least 4 million

## Chebyshev solver: Important functions

Create Chebyshev solver

```
ChebyshevSolver cSolver;
```

Set model

```
cSolver.setModel(&model);
```

Calculate Chebyshev coefficients for  $G_{\{ij\}}$ , where

$i = (x, y, 0)$ ,  $j = (x+1, y, 1)$

```
complex<double> coefficients[NUM_COEFFICIENTS];
```

```
cSolver.calculateCoefficients({x, y, 0}, {x+1, y, 1},  
                             coefficients,  
                             NUM_COEFFICIENTS);
```

```
cSolver.calculateCoefficientsGPU({x, y, 0}, {x+1, y, 1},  
                                coefficients,  
                                NUM_COEFFICIENTS);
```

## Chebyshev solver: Important functions

```
Calculate Chebyshev coefficients for  $G_{ij}$ , where  $i$  is a  
range of NUM_I indices and  $= (x, y, 1)$   
    complex<double> coefficients[NUM_COEFFICIENTS*NUM_I];  
    vector<Index> toIndices;  
    for(int x = 0; x < NUM_I; x++)  
        toIndices.push_back({x, y, 0});  
    cSolver.calculateCoefficientsGPU(toIndices, {x, y, 1},  
                                    coefficients,  
                                    NUM_COEFFICIENTS);
```

## Chebyshev solver: Important functions

Evaluate Green's function without using lookup table

```
complex<double> greensFunction[ENERGY_RESOLUTION];  
cSolver.generateGreensFunction(greensFunction,  
                                coefficients,  
                                NUM_COEFFICIENTS,  
                                ENERGY_RESOLUTION);
```

Setup lookup table

```
cSolver.generateLookupTable(NUM_COEFFICIENTS,  
                             ENERGY_RESOLUTION);
```

Load lookup table to GPU

```
cSolver.loadLookupTableGPU();
```

## Chebyshev solver: Important functions

Generate Green's function using lookup table

```
complex<double> greensFunction[ENERGY_RESOLUTION];  
cSolver.generateGreensFunction(greensFunction,  
                                coefficeints);  
cSolver.generateGreensFunctionGPU(greensFunction,  
                                   coefficeints);
```

Free GPU memory from lookup table

```
cSolver.destroyLookupTableGPU();
```