# Randomized algorithms 2 Bloom filters, string matching

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Rui Fan

## Approximate sets

- A Bloom filter is a data structure that can implement a set.
  - It only keeps track of which keys are present, not any values associated to keys.
  - It supports insert and find operations.
  - It doesn't support delete operations.
- Bloom filters use less memory than hash tables or other ways of implementing sets.
- However, Bloom filters are approximate.
  - It can produce false positives: it says an element is present even though it's not.
    - We can bound the probability of false positives.
  - But it doesn't produce false negatives: if it says an element isn't present, then it's not.





#### Bloom filter applications

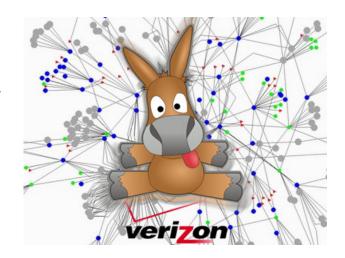
- Suppose we have a big database, and querying it to check if an item is present is expensive.
- We store the set of items in the database using a Bloom filter.
  - This tells us whether an item is in database or not.
- If filter says an item's not present, it's definitely not in the database.
  - □ So no need to do an expensive query.
- If filter says an item is present, then either item is present, or there's false positive.
  - When we query the database, there's a small probability we waste time querying for a nonexistent item.
- Overall we save time by checking Bloom filter first before querying database.





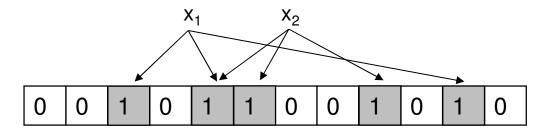
#### Bloom filter applications

- Consider a P2P network, where each node stores some files.
- If you want to get a file, you need to know which nodes have it.
- Keeping a list of all items stored at each node is too expensive.
- Instead, for every other node, keep a Bloom filter of its files.
- If filter says no for a node, it definitely doesn't have the file.
- If filter says yes, then either node has the file, or there's false positive and we make a useless request.
- Overall we save space, and also won't waste much communication because we rarely make useless requests.



#### Bloom filters

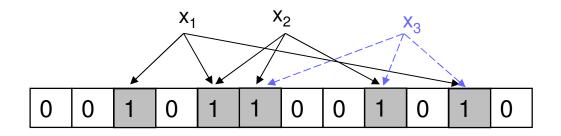
- A Bloom filter consists of
  - □ An array A of size m, initially all 0's.
  - □ k independent hash functions  $h_1,...,h_k$ , each mapping from keys to  $\{1,...,m\}$ .
- To store key x
  - $\square$  Set A[h<sub>1</sub>(x)], A[h<sub>2</sub>(x)], ..., A[h<sub>k</sub>(x)] all to 1.
  - □ Some locations can get set to 1 multiple times; that's fine.
- To check if key x is in the set
  - □ Read array locations  $A[h_1(x)]$ ,  $A[h_2(x)]$ , ...,  $A[h_k(x)]$ .
  - ☐ If all the values are 1, output "x is in set".
  - □ Otherwise output "x is not in set".



A Bloom filter with k=3 hash functions storing 2 items.

# M-

- Let's look at the correctness of the search function.
- If search for x returns no, then at least one of  $A[h_1(x)],...,$   $A[h_k(x)]$  equals 0.
  - □ So x cannot be in the set, because if x had been inserted into the set, then we would have  $A[h_1(x)]=...=A[h_k(x)]=1$ .
  - □ So there are no false negatives.
- If search for x returns yes, then  $A[h_1(x)]=...=A[h_k(x)]=1$ .
  - □ So either x was inserted into the set.
  - □ Or we inserted some keys that hashed to the same k locations as x.
    - So it looks as if x was inserted, even though it wasn't.
    - This is a false positive. We'll bound the probability this happens.



## False positive probability 1

- False positive probability depends on k (number of hash functions), m (size of table) and n (number of keys inserted).
- Assume hash functions hash keys to random locations.
- When inserting one key, we set k random locations to 1.
- Fix any position i. Probability i is set to 1 by a hash function is 1/m, so probability i stays 0 is 1-1/m.
  - $\square$  After k hashes, probability i still 0 is  $(1-1/m)^k$ .
  - □ To insert n items, we used nk hashes. So probability i still 0 after all these is  $p = (1 1/m)^{nk}$ .
- We now use an approximation  $\left(1 \frac{1}{m}\right)^{nk} \approx e^{-\frac{nk}{m}}$ .

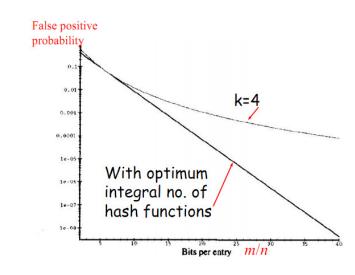
# False positive probability 2

- So probability any position i is 1 after n keys inserted is  $1-p\approx 1-e^{-\frac{nk}{m}}$ .
- Since there are m positions in the array, assume there are (1-p)m positions that are 1.
  - □ This isn't quite correct. The actual number of 1's in the array is a random variable, whose expectation is (1-p)m.
  - □ However, we can make the argument rigorous by showing that the actual number of 1's is  $(1-p)m + \sqrt{m \log m}$  with high probability.
- We only get a false positive if when we check k random locations, they're all 1.
  - □ Probability is  $f = (1 p)^k \approx \left(1 e^{-\frac{nk}{m}}\right)^k$ .



## False positive probability 3

- Notice the false prob.  $(1 e^{-\frac{nk}{m}})^k$  is a function of k, the number of hash functions we use.
- We find k to minimize the false positive prob. by differentiating f wrt k and solving.
- The optimum k is  $\frac{m \ln(2)}{n}$ , which leads to  $f = \left(\frac{1}{2}\right)^k \approx 0.6185^{\frac{m}{n}}$ .
  - □ Notice that m/n is the average number of bits per item. So error rate decreases exponentially in space usage.

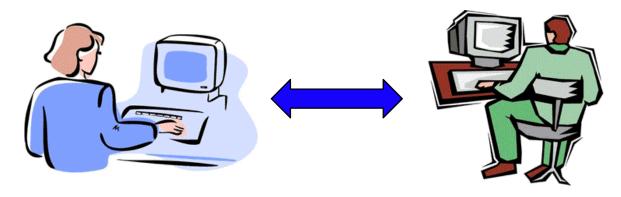


#### Improvements

- Right now Bloom filters can't handle deletes.
  - Say keys k₁, k₂ hash to two overlapping sets of locations. If you delete k₁ by setting some of its locations to 0, you could also delete k₂.
- Deletes can be done by storing a count of how many keys hashed to that location, and inc / dec the counts when inserting or deleting.
  - ☐ But this uses more memory.
  - ☐ Also, what if the counts overflow?
- Neat trick Given Bloom filters for sets  $S_1$ ,  $S_2$ , we can create Bloom filter for  $S_1 \cap S_2$  and  $S_1 \cup S_2$  just by bitwise ANDing or ORing  $S_1$  and  $S_2$ 's filters.
  - $\square$  ORing gives the exact Bloom filter for  $S_1 \cup S_2$ , while ANDing gives approximately the Bloom filter for  $S_1 \cap S_2$ .

# String equality and fingerprinting

- Alice and Bob both have copies of a database.
- They want to keep the database consistent, so they want to check if their copies are the same.
  - If you think of the databases as strings, they want to check if their strings are equal.
- But transferring the entire database is expensive.
- Instead, they calculate a small value called a fingerprint of their databases.
  - If the fingerprints are the different, then their databases are definitely different.
  - ☐ If the fingerprints are the same, then the databases are probably the same; but there's a small probability they're actually different.
- Transferring the fingerprint is much cheaper than the database.



## Fingerprinting

- Let Alice and Bob's databases be the bit sequences  $(a_1,...,a_n)$  and  $(b_1,...,b_n)$ .
- View these as n-bit integers  $a = \sum_{i=1}^{n} a_i^* 2^{i-1}$  and  $b = \sum_{i=1}^{n} b_i^* 2^{i-1}$ .
- The fingerprint  $F(a) = a \mod p$ , for a specially chosen prime number p.
  - □ Alice transfers F(a) to Bob, and Bob compares it to his fingerprint F(b)=b mod p.
  - □ Since F(a) < p, transferring the fingerprint only takes O(log p) bits, instead of n.

# MA.

- No false negatives.
  - $\square$  If  $F(a) \neq F(b)$ , then  $a \neq b$ .
- False positives are possible.
  - $\square$  If F(a)=F(b), then a mod p=b mod p.
  - $\square$  So either a=b, or a $\neq$ b but p divides (a-b).
- We can't avoid false positives. But we can minimize the probability it occurs.
- Pick a random p.
  - If a≠b, then probably p doesn't divide (a-b), so probably F(a)≠F(b) and we'll detect a and b are different.
  - □ Bigger p decreases false positives probability.
  - But we don't want to make p too big, since we have to transfer O(log p) bits.

- To analyze the false positives probability, we use two facts from number theory.
- Lemma Any number t has at most log<sub>2</sub>(t) distinct prime divisors.
- Proof Each divisor is  $\geq 2$ , and their product is  $\leq t$ . If there were more than  $\log_2(t)$  divisors, their product would be  $> 2^{\log_2(t)} = t$ , contradiction.
- Recall  $a = \sum_{i=1}^{n} a_i^* 2^{i-1}$  and  $b = \sum_{i=1}^{n} b_i^* 2^{i-1}$ .
- So a-b<2<sup>n</sup>, and so a-b has at most n distinct prime divisors.



- Prime Number Theorem Given any number t, the number of primes smaller than t is ~ t / ln(t).
- The PNT allows us to efficiently generate a random prime.
  - □ Picking a number less than t at random, it has a 1/ln(t) probability of being prime.
  - We can check if a number is prime using the Rabin-Miller primality test.
    - If number is prime, it always passes the test.
    - If number is composite, there's small probability it's declared a prime.
    - Run the test few more times to exponentially decrease false positive probability.
  - So with high probability, we can tell if a number is prime.

- Let  $t = n^2 \ln(n)$ . The number of primes less than t is  $\approx \frac{t}{\ln(t)} = \frac{n^2 \ln(n)}{2 \ln(n) + \ln \ln(n)} = O(n^2)$ .
- Pick a random prime p less than t.
- We get a false positives if  $a\neq b$  but p divides (a-b).
  - □ We saw earlier that a-b has < n prime divisors, and p must be one of these.</p>
  - □ But p is randomly chosen from O(n²) primes less than t.
  - □ So false positive probability  $\leq n/O(n^2) = O(1/n)$ .
- We transfer  $log(p) \le log(t) = O(log n)$  bits.
- Transferring O(log n) bits gets O(1/n) probability of error. If we want perfect accuracy, we need to transfer the entire database, O(n) bits.



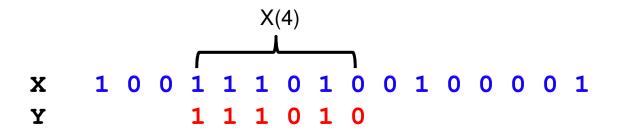
## String matching

- In the previous problem, we checked whether two strings are equal.
- We now want to see if one string X contains the other Y. I.e. we want to match Y to a part of X.
- Let X and Y be binary strings with length n and m, resp., where n≥m.
- We'll look at a simple randomized O(n+m) time string matching algorithm Rabin-Karp.

```
X 1 0 0 1 1 1 0 1 0 0 1 0 0 0 0 1
Y 1 1 1 0 1 0
```

## String matching

- Let  $X=x_1x_2...x_n$ , and define  $X(j)=x_jx_{j+1}...x_{j+m-1}$ .
  - $\square$  X(j) has the same length as Y.
  - □ It represents a potential match for Y starting at the j'th bit of X.
- Y matches X if there exists  $1 \le j \le n-m+1$  s.t. X(j)=Y.
- We just saw a way to test string equality using fingerprints.
- We first give a O(n+m) time Monte Carlo string matching algorithm.
  - □ There's small probability it says Y matches X even when it doesn't.
- Then we convert it to an expected O(n+m) time Las Vegas algorithm, which always gives correct answer.



## b/A

## Monte Carlo string matching

- Choose a random prime p.
  - We'll determine how big p should be later.
- For every 1≤j≤n-m+1.
  - View X(j) and Y as m-bit numbers.
  - Compute F(X(j))=X(j) mod p and F(Y)=Y mod p.
  - \*If  $F(X(j))\neq F(Y)$ , go to next j.
  - \*If F(X(j))=F(Y), output "Y matches X at bit j".
- Output "Y doesn't match X".

- Consider X(j) and Y, for some j.
- If F(X(j))≠F(Y), then X(j)≠Y and there's no match at X's j'th bit.
  - □ So no false negatives.
- If F(X(j))=F(Y), then either X(j)=Y, or X(j)≠Y but p divides X(j)-Y.
  - □ So there could be false positives.
  - □ Let's bound this probability.
- X(j)-Y is an m-bit number, so by the lemma, it has ≤ m distinct prime factors.
- Let t=n²m log(n²m), and let p be a random prime ≤ t.
  - $\square$  There are  $\sim$  n<sup>2</sup>m primes  $\leq$  t, by the PNT.

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- We only get a false positive if p is one of the ≤ m factors of X(j)-Y.
- So we get a false match between X(j) and Y with probability ≤ m/n²m = 1/n².
- Now, we falsely match X to Y if there is any 1≤j≤n-m+1 s.t. X(j)≠Y but F(X(j))=F(Y).
  - $\square$  For each j, this event has probability  $\leq 1/n^2$ .
  - □ So the probability this happens at any of the n-m+1 j's is  $\leq$   $(n-m+1)/n^2 = O(1/n)$ .
  - ☐ This is called the union bound.
    - If  $Pr[E_i]=p_i$  for  $1 \le i \le k$ , then  $Pr[E_1 \cup ... \cup E_k] \le p_1 + ... + p_n$ .
- Putting it together, if Y matches X somewhere, then this algorithm finds the match. If Y doesn't match X, this algorithm says Y matches X with probability O(1/n).

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#### Running time

- We said this algorithm runs in O(n+m) time. But computing  $F(X(j)) = \left(\sum_{i=j}^{j+m-1} x_i 2^{i-1}\right) \mod p$  takes O(m) time, and we have to do this for n-m+1 j's, which makes the running time O(mn)!
- However, there's a trick to computing F(X(j+1)) fast once you've computed F(X(j)).
  - $\square$  X(j+1) and X(j) differ only in bits  $x_i$  and  $x_{i+m}$ .
  - □ So  $F(X(j+1))=(2^*(F(X(j)) 2^{m-1}x_j) + x_{j+m}) \text{ mod } p.$
  - □ So computing F(X(j+1)) given F(X(j)) takes O(1) time.
- So computing F(X(1)),...,F(X(n-m+1)) takes O(n) time.
- Computing F(Y) takes O(m) time.
- So altogether the algorithm takes O(n+m) time.

$$X_{j}$$
 $X_{j+1}$ 
 $X_{j+m-1}$ 
 $X_{j+m}$ 
 $X_{j+m}$ 

## NA.

#### A Las Vegas algorithm

- We now modify the previous algorithm so it always produces the right answer.
- Run the Monte Carlo algorithm.
- If it never produces a match, output "Y doesn't match X".
- If it ever outputs a match, say between X(j) and Y, then check X(j)=Y in O(m) time.
- ❖ If X(j)=Y, output "Y matches X at bit j".
- ❖ If X(j)≠Y, start over and run the brute force O(mn) time to match Y to X.



- Since the Monte Carlo algorithm only produced false positives and this algorithm checks them using brute force, it always produces the right answer.
- The expected running time is Pr[no false positives]\*(running time if no false positives)+Pr[there is false positive]\*(running time when there's false positive).
  - $\square$  The first term is O(n+m).
  - □ The second term is  $\leq 1/n*O(mn)=O(m)$ .
  - $\square$  So the total expected running time is O(n+m).