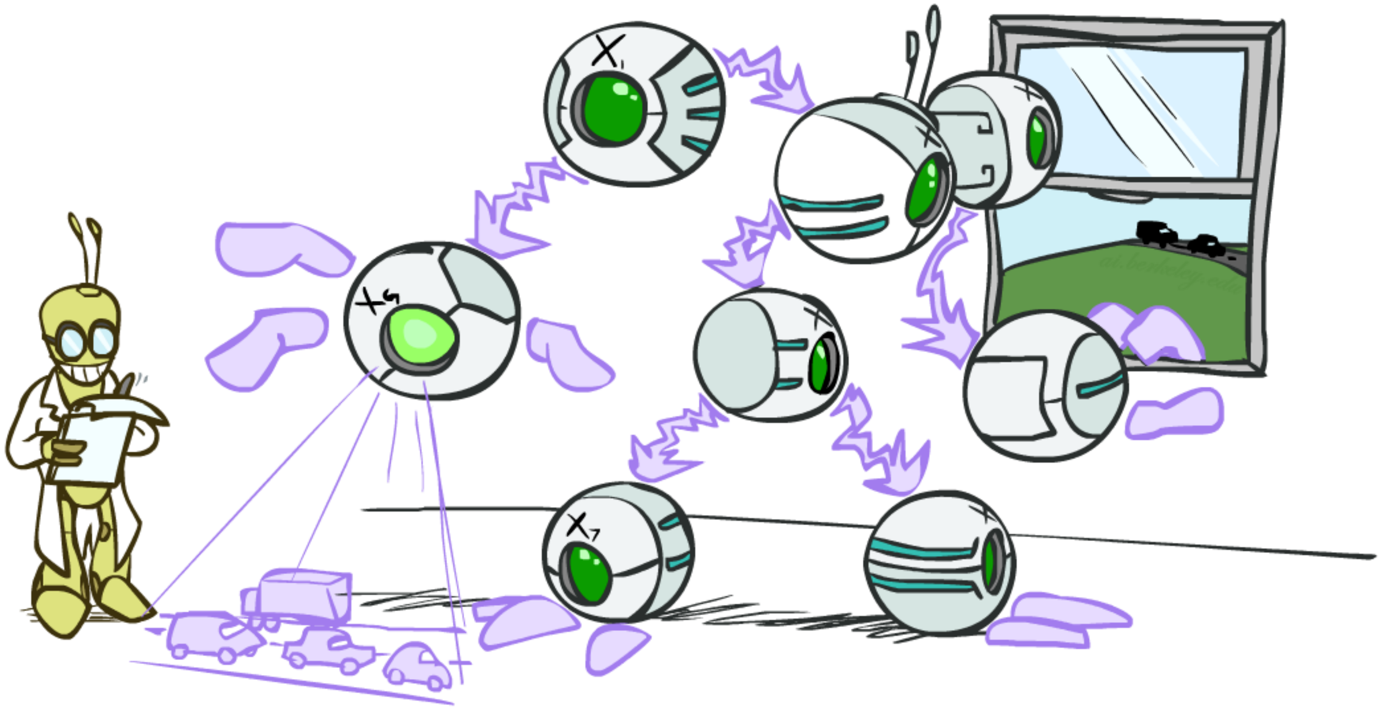
Announcement

- Programming 2 due 11:59pm today!

- Programming 3
  - Due: April 12, 11:59pm
- Homework 3
  - Due: April 7, 11:59pm

Bayes Nets: Exact Inference



AIMA Chapter 14.4, PRML Chapter 8.4

[Adapted from slides by Dan Klein and Pieter Abbeel at UC Berkeley]

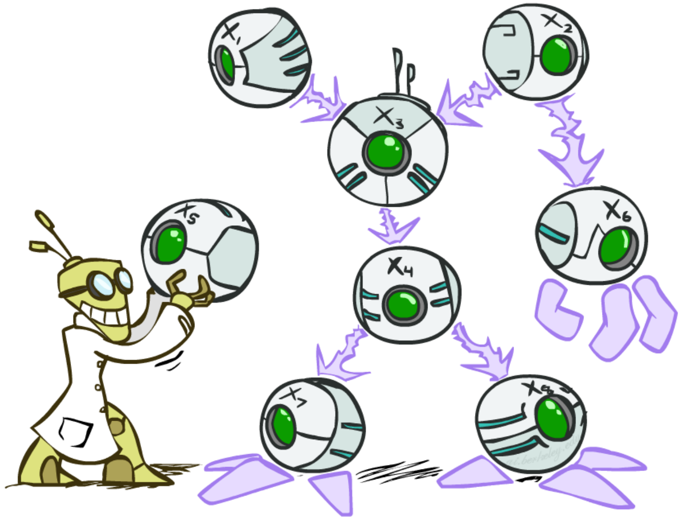
Bayes' Net Representation

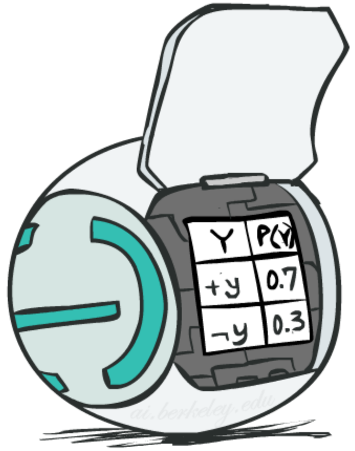
- A directed, acyclic graph, one node per random variable
- A conditional probability table (CPT) for each node
  - A collection of distributions over X, one for each combination of parents' values

$$P(X|a_1 \dots a_n)$$

- Bayes' nets implicitly encode joint distributions
  - As a product of local conditional distributions
  - To see what probability a BN gives to a full assignment, multiply all the relevant conditionals together:

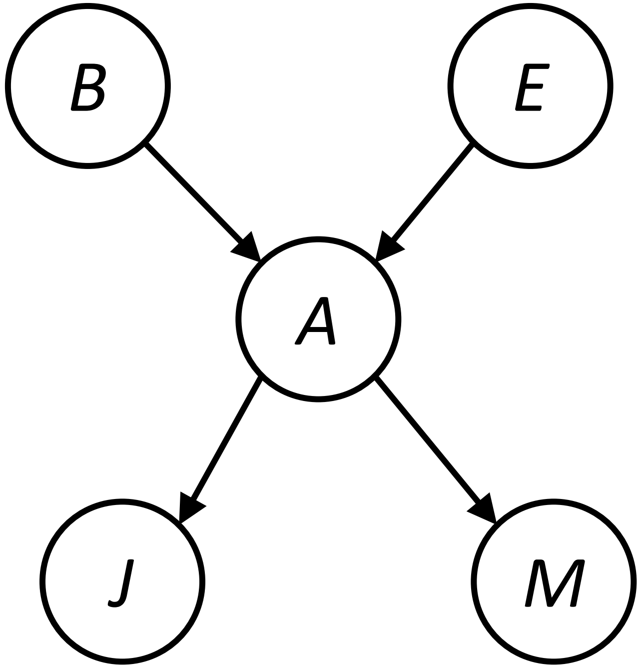
$$P(x_1, x_2, \dots x_n) = \prod_{i=1}^{n} P(x_i|parents(X_i))$$



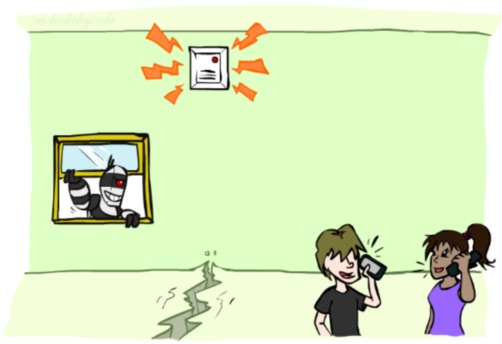


Example: Alarm Network

B	P(B)
+b	0.001
-b	0.999



E	P(E)
+e	0.002
-e	0.998



A	J	P(J|A)
+a	+j	0.9
+a	-j	0.1
-a	+j	0.05
-a	-j	0.95

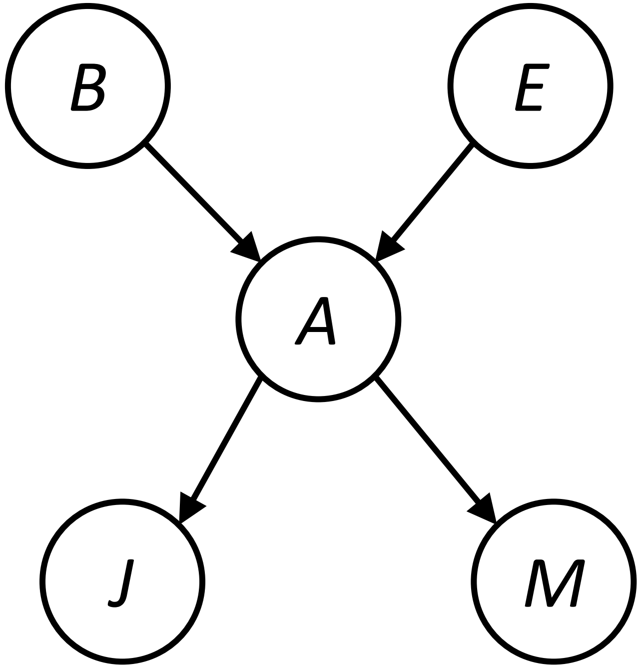
A	M	P(M|A)
+a	+m	0.7
+a	-m	0.3
-a	+m	0.01
-a	-m	0.99

B	E	A	P(A|B,E)
+b	+e	+a	0.95
+b	+e	-a	0.05
+b	-e	+a	0.94
+b	-e	-a	0.06
-b	+e	+a	0.29
-b	+e	-a	0.71
-b	-e	+a	0.001
-b	-e	-a	0.999

$$P(+b, -e, +a, -j, +m) =$$
$$P(+b)P(-e)P(+a| + b, -e)P(-j| + a)P(+m| + a) =$$

Example: Alarm Network

B	P(B)
+b	0.001
-b	0.999



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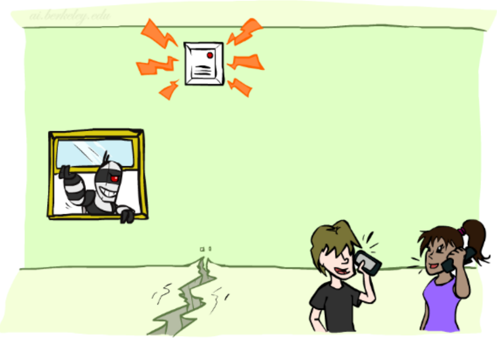

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-a	-j	0.95

A	M	P(M|A)
+a	+m	0.7
+a	-m	0.3
-a	+m	0.01
-a	-m	0.99

B	E	A	P(A|B,E)
+b	+e	+a	0.95
+b	+e	-a	0.05
+b	-e	+a	0.94
+b	-e	-a	0.06
-b	+e	+a	0.29
-b	+e	-a	0.71
-b	-e	+a	0.001
-b	-e	-a	0.999

$$P(+b,-e,+a,-j,+m) =$$
$$P(+b)P(-e)P(+a|+b,-e)P(-j|+a)P(+m|+a) =$$
$$0.001 \times 0.998 \times 0.94 \times 0.1 \times 0.7$$

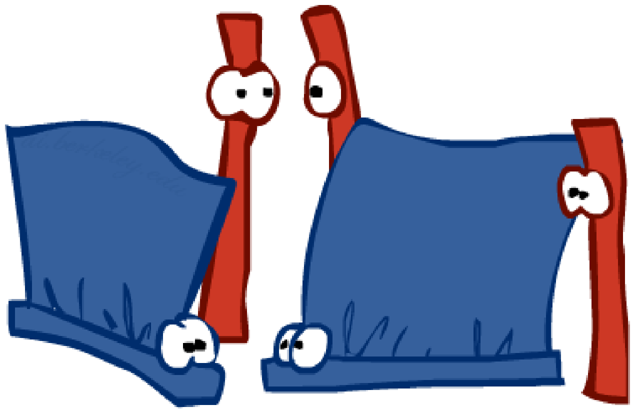
Probabilistic Inference

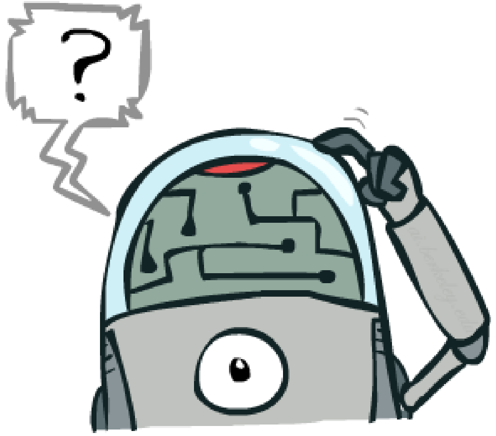
- Enumeration (exact, exponential complexity)
- Variable elimination (exact, worst-case exponential complexity, often better)
- Inference is NP-complete
- Sampling (approximate)

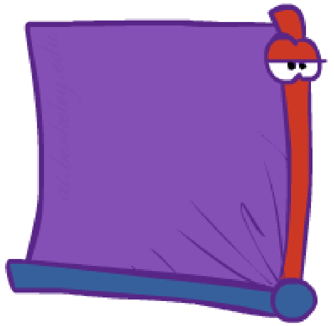
Inference

- Inference: calculating some useful quantity from a probability model (joint probability distribution)

- Examples:
  - Posterior marginal probability
    - $P(Q|e_1,..,e_k)$
    - E.g., what disease might I have?
  - Most likely explanation:
    - $\text{argmax}_q\ P(Q=q|e_1,..,e_k)$
    - E.g., what did he say?







Inference by Enumeration

- General case:
  - Evidence variables: $E_1 \dots E_k = e_1 \dots e_k$
  - Query variable: Q
  - Hidden variables: $H_1 \dots H_r$

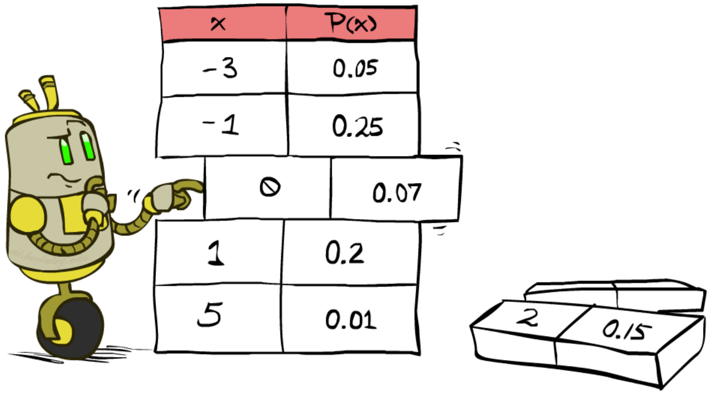
  $\left.\begin{array}{l} \\ \\ \\ \end{array}\right\} X_1, X_2, \dots X_n$

  All variables

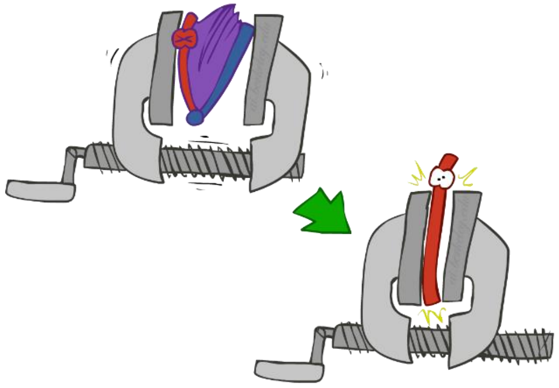
- We want:

$$P(Q|e_1 \dots e_k)$$

- Step 1: Select the entries consistent with the evidence



- Step 2: Sum out H to get joint of Query and evidence



$$P(Q, e_1 \dots e_k) = \sum_{h_1 \dots h_r} \underbrace{P(Q, h_1 \dots h_r, e_1 \dots e_k)}_{X_1, X_2, \dots X_n}$$

- Step 3: Normalize

$$\times \frac{1}{Z}$$

$$Z = \sum_q P(Q, e_1 \cdots e_k)$$

$$P(Q|e_1 \cdots e_k) = \frac{1}{Z} P(Q, e_1 \cdots e_k)$$

Inference by Enumeration in Bayes Net

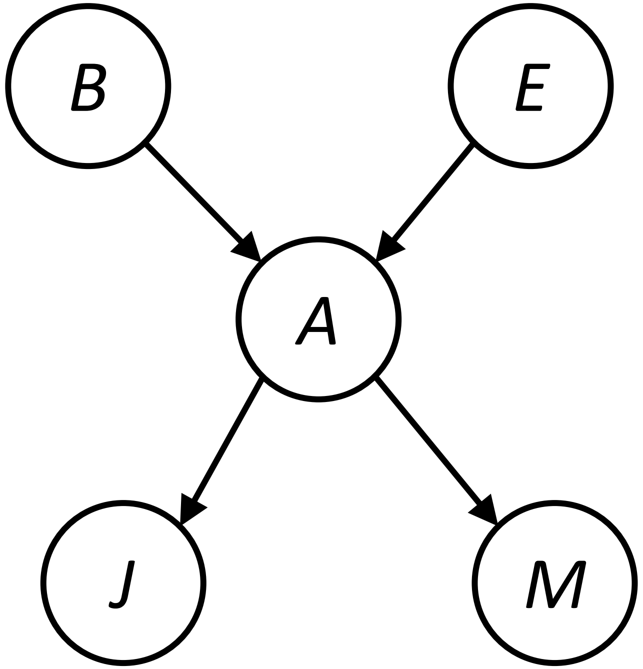
- The joint distribution can be computed from a BN by multiplying the conditional distributions
- Then we can do inference by enumeration

$$P(B \mid +j, +m) \ \propto_B P(B, +j, +m)$$

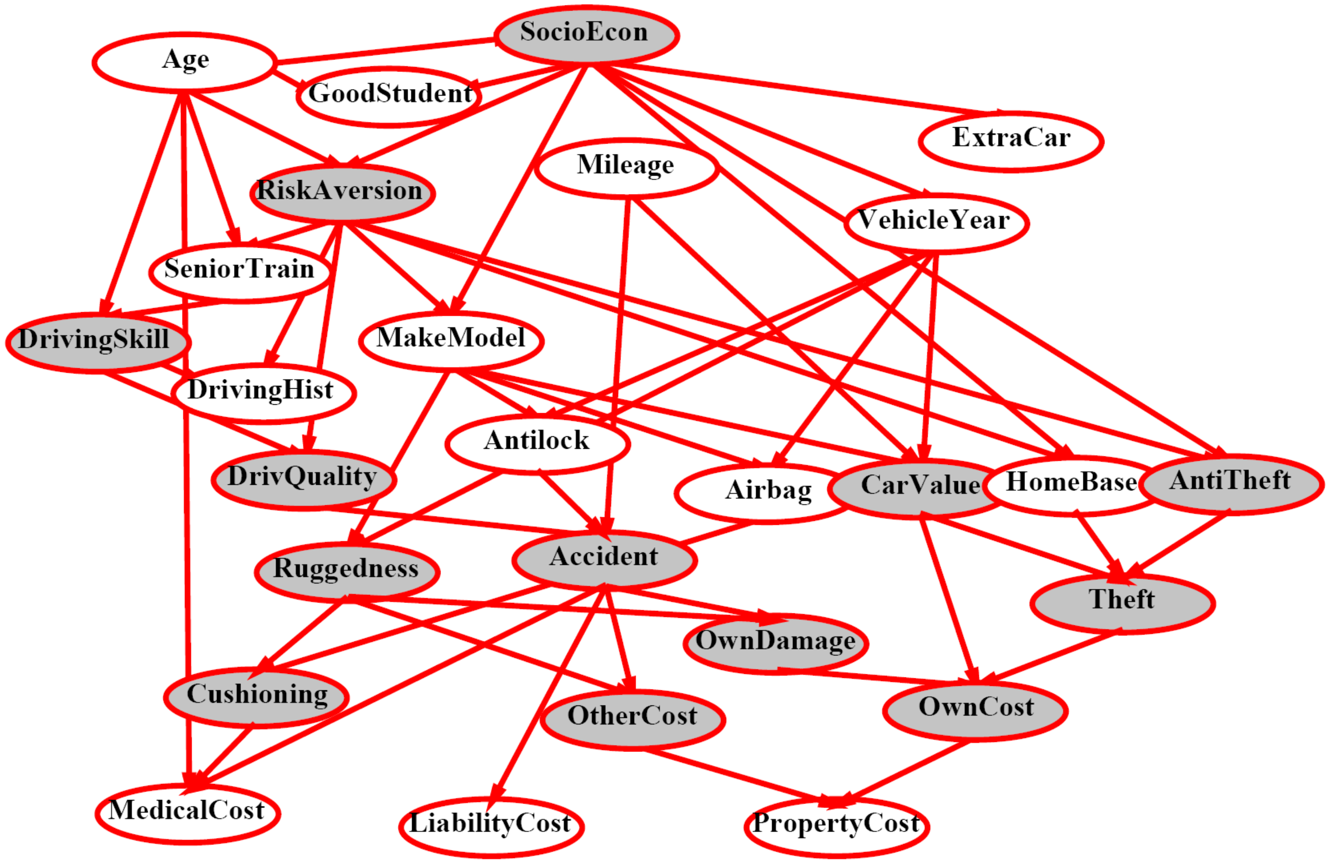
$$= \sum_{e,a} P(B, e, a, +j, +m)$$

$$= \sum_{e,a} P(B)P(e)P(a|B, e)P(+j|a)P(+m|a)$$

- Problem: sums of ***exponentially many*** products!



Inference by Enumeration?



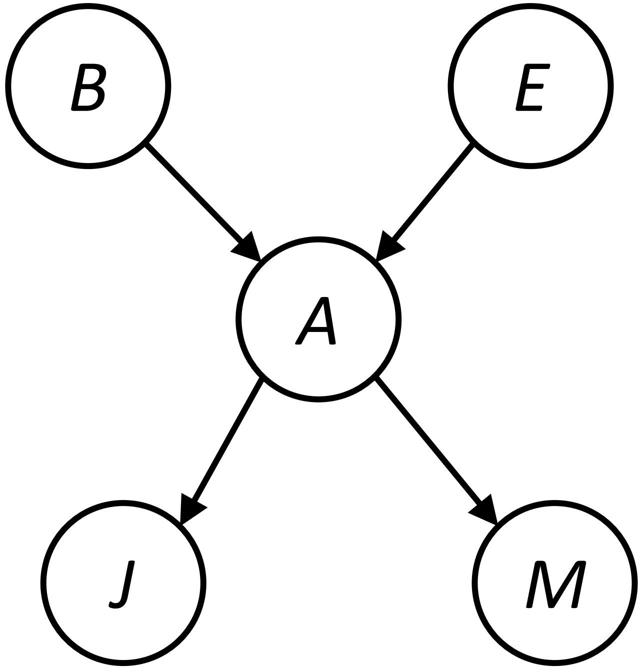
$$P(Antilock|observed\ variables) = ?$$

Inference by Enumeration in Bayes Net

$$P(B \mid +j, +m) \;\propto_B P(B, +j, +m)$$

$$= \sum_{e,a} P(B, e, a, +j, +m)$$

$$= \sum_{e,a} P(B)P(e)P(a|B,e)P(+j|a)P(+m|a)$$



$$= P(B)P(+e)P(+a|B,+e)P(+j|+a)P(+m|+a) + P(B)P(+e)P(-a|B,+e)P(+j|-a)P(+m|-a)$$
$$P(B)P(-e)P(+a|B,-e)P(+j|+a)P(+m|+a) + P(B)P(-e)P(-a|B,-e)P(+j|-a)P(+m|-a)$$

Lots of repeated subexpressions!

Can we do better?

- Consider **uwy + uwz + uxy + uxz + vwy + vwz + vxy +vxz**
  - 16 multiplies, 7 adds
  - Lots of repeated subexpressions!
- Rewrite as **(u+v)(w+x)(y+z)**
  - 2 multiplies, 3 adds

Can we do better?

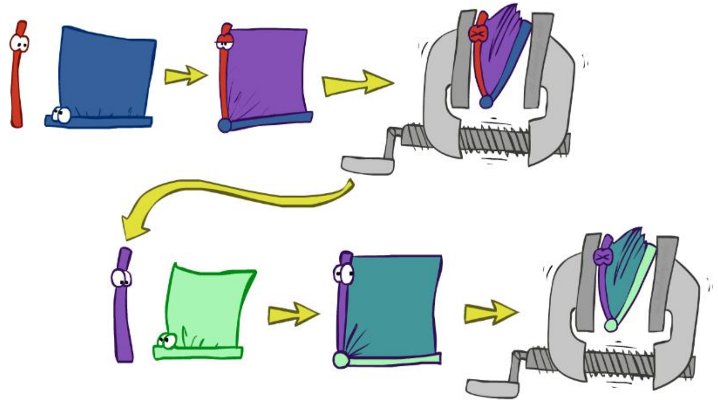
- $\sum_{e,a} P(B)\ \mathrm{P(e)}\ \mathrm{P(a}|B,e)\ P(j|a)\ P(m|a)$
- $= P(B)P(e)P(\mathrm{a}|B,e)P(j|a)P(m|a) + P(B)P(\neg e)P(\mathrm{a}|B,\neg e)P(j|a)P(m|a)$

  $+ P(B)P(e)P(\neg\mathrm{a}|B,e)P(j|\neg a)P(m|\neg a) + P(B)P(\neg e)P(\neg\mathrm{a}|B,\neg e)P(j|\neg a)P(m|\neg a)$

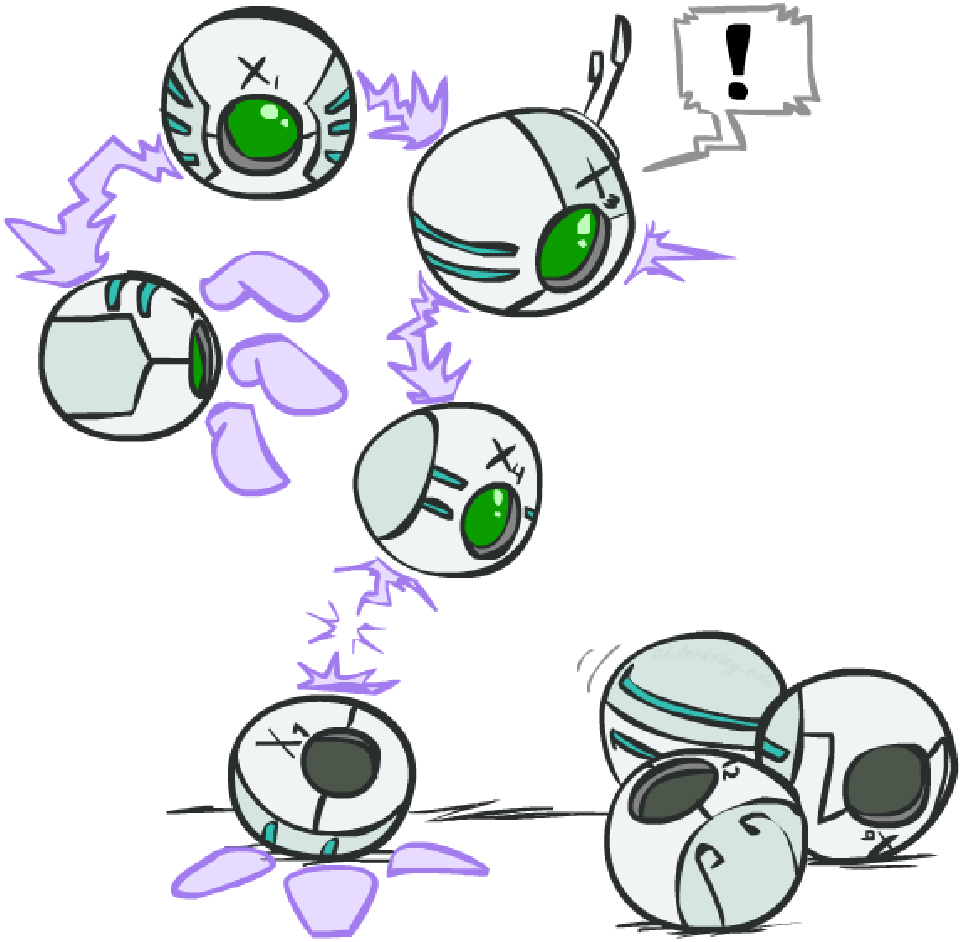
  Lots of repeated subexpressions!

Variable elimination: The basic ideas

- Move summations inwards as far as possible
  - $P(B \mid j, m) = \alpha \sum_{e,a} P(B)\, P(e)\, P(a|B,e)\, P(j|a)\, P(m|a)$
  - $= \alpha\, P(B) \sum_e P(e) \sum_a P(a|B,e)\, P(j|a)\, P(m|a)$
- Do the calculation from the inside out
  - I.e., sum over *a* first, the sum over *e*
  - Problem: $P(a|B,e)$ isn't a single number, it's a bunch of different numbers depending on the values of *B* and *e*
  - Solution: use arrays of numbers (of various dimensions) with appropriate operations on them; these are called ***factors***



Operations on Factors



Factors

- A factor is a multi-dimensional array to represent $P(Y_1 \ldots Y_N \mid X_1 \ldots X_M)$
  - If a variable is assigned (represented with lower-case), its dimension is missing (selected) from the array

- Joint distribution: P(X,Y)
  - Entries P(x,y) for all x, y
  - Sums to 1

$$P(T, W)$$

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

- Selected joint: P(x,Y)
  - A slice of the joint distribution
  - Entries P(x,y) for fixed x, all y
  - Sums to P(x)

$$P(cold, W)$$

T	W	P
cold	sun	0.2
cold	rain	0.3

Factors

- A factor is a multi-dimensional array to represent $P(Y_1 \ldots Y_N \mid X_1 \ldots X_M)$
  - If a variable is assigned (represented with lower-case), its dimension is missing (selected) from the array

- Single conditional: P(Y | x)
  - Entries P(y | x) for fixed x, all y
  - Sums to 1

$$P(W|cold)$$

T	W	P
cold	sun	0.4
cold	rain	0.6

- Family of conditionals: P(X |Y)
  - Multiple conditionals
  - Entries P(x | y) for all x, y
  - Sums to |Y|

$$P(W|T)$$

T	W	P
hot	sun	0.8
hot	rain	0.2
cold	sun	0.4
cold	rain	0.6

$P(W|hot)$

$P(W|cold)$

Factors

- A factor is a multi-dimensional array to represent $P(Y_1 \ldots Y_N \mid X_1 \ldots X_M)$
  - If a variable is assigned (represented with lower-case), its dimension is missing (selected) from the array

- Specified family: P(y | X)
  - Entries P(y | x) for fixed y, but for all x
  - Sums to … who knows!

$P(rain|T)$

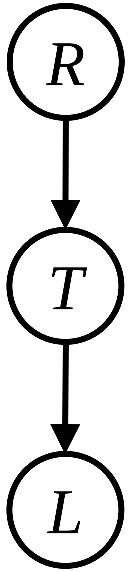
T	W	P
hot	rain	0.2
cold	rain	0.6

$\} P(rain|hot)$

$\} P(rain|cold)$

Example: Traffic Domain

- Random Variables
  - R: Raining
  - T: Traffic
  - L: Late for class!



$P(R)$

+r	0.1
-r	0.9

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

Running Example: Traffic Domain

- Initial factors are local CPTs (one per node)

$P(R)$

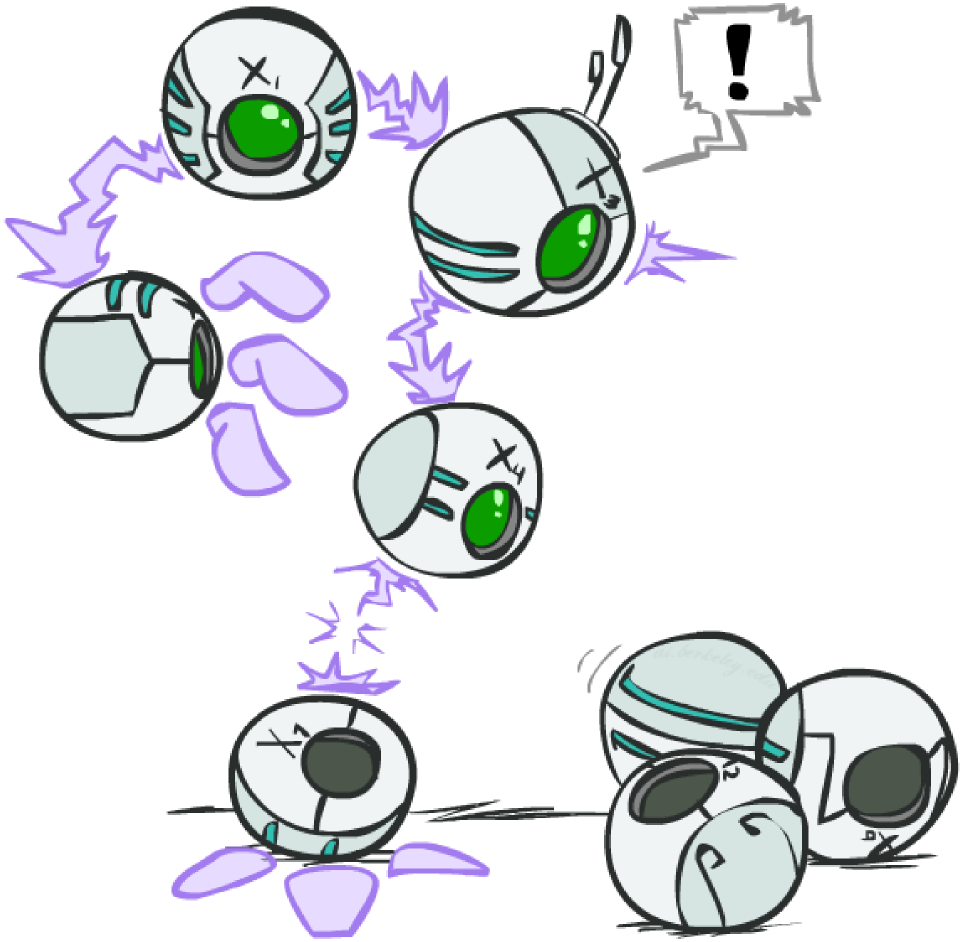
+r	0.1
-r	0.9

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9



- Any known values are selected
  - E.g. if we know $L = +\ell$, the initial factors are

$P(R)$

+r	0.1
-r	0.9

$P(T|R)$

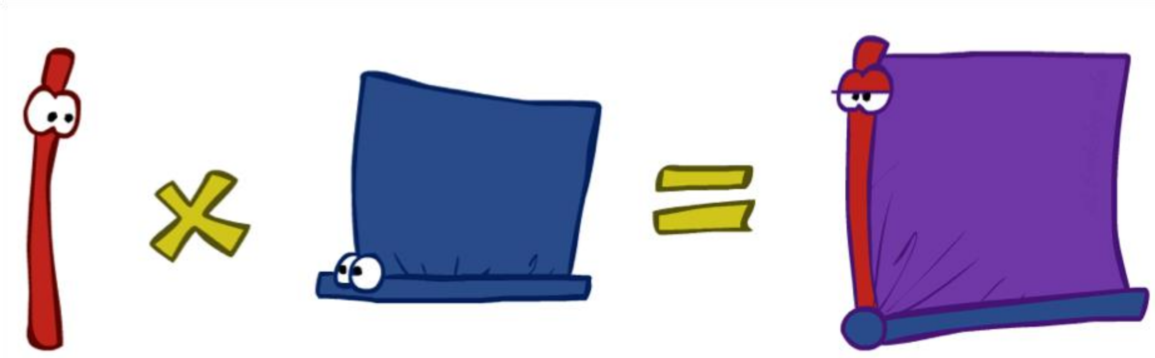
+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$P(+\ell|T)$

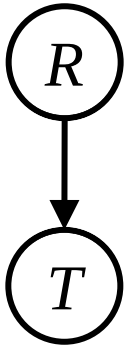
+t	+l	0.3
-t	+l	0.1

Operation 1: Join Factors

- First basic operation: joining factors
  - Just like a database join
  - Given multiple factors, build a new factor over the union of the variables involved
  - Each entry is computed by pointwise products



- Example:



$$P(R) \times P(T|R) \qquad P(R,T)$$

$P(R)$:

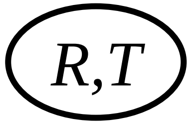
+r	0.1
-r	0.9

$P(T|R)$:

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$P(R,T)$:

+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81



$$\forall r, t : \quad P(r,t) = P(r) \cdot P(t|r)$$

Operation 2: Eliminate

- Second basic operation: eliminating a variable
  - Take a factor and sum out (marginalize) a variable

- Example:

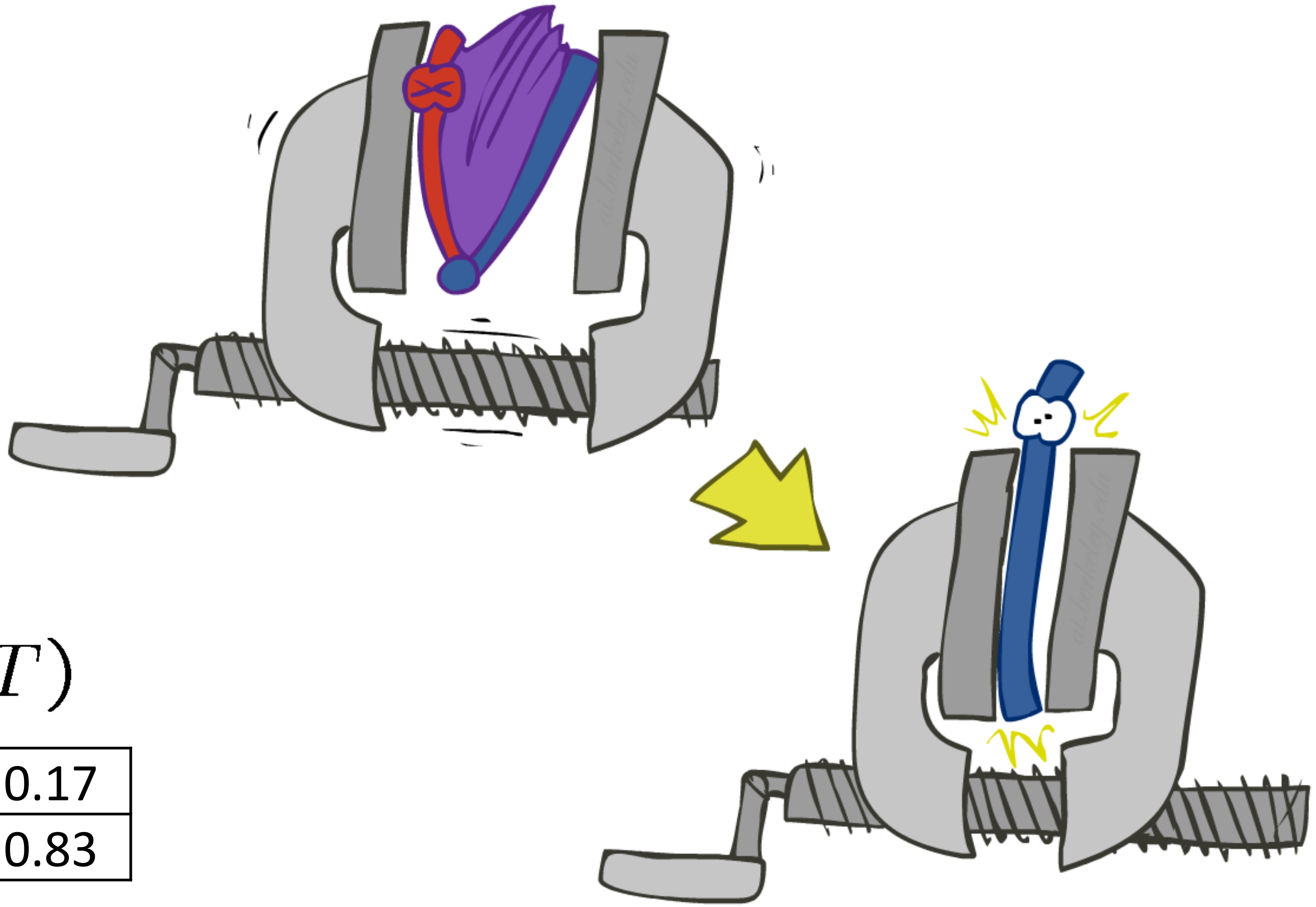
$P(R,T)$

+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81

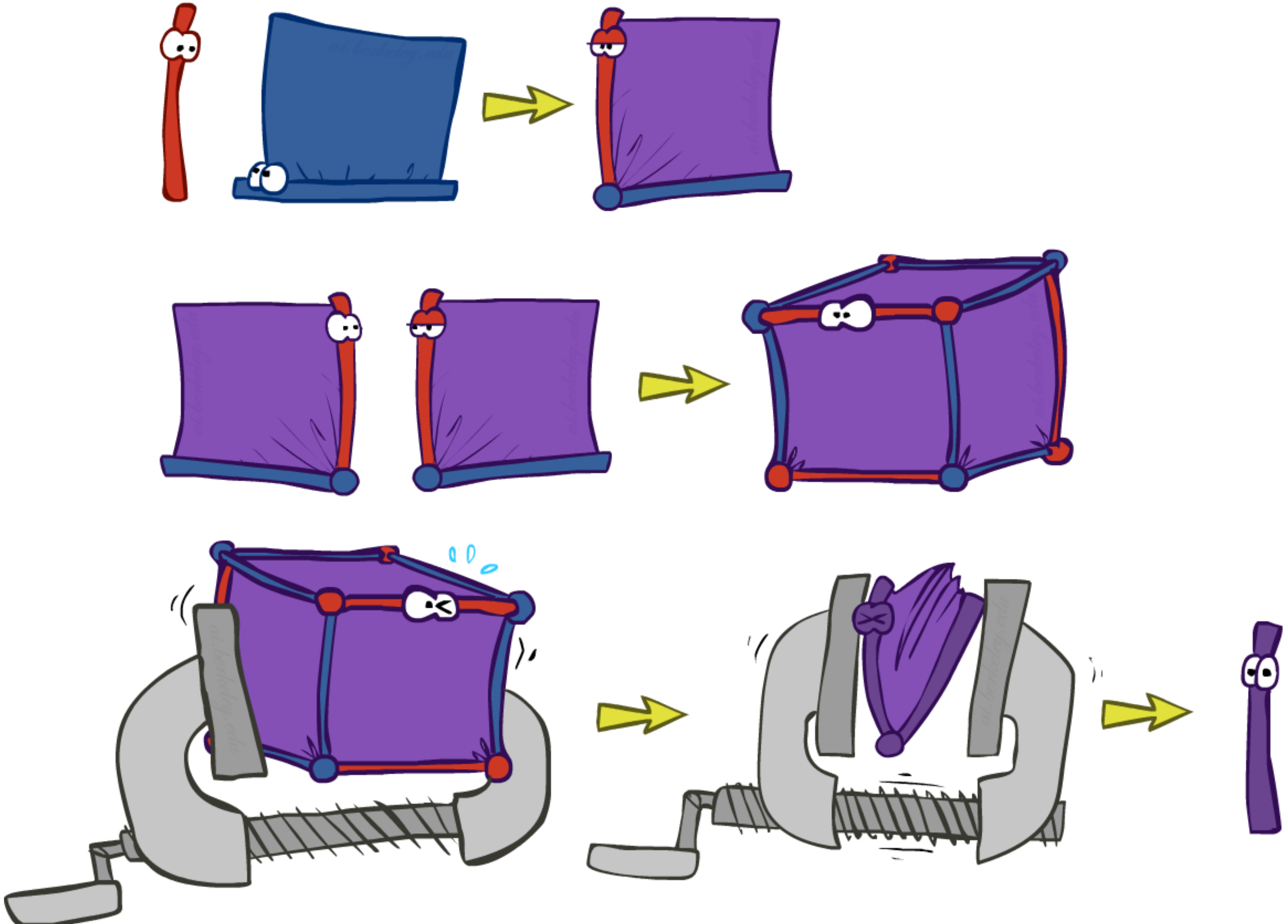
sum R →

$P(T)$

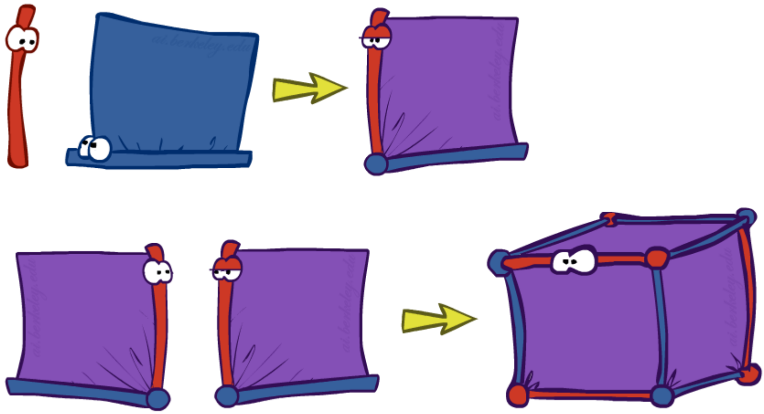
+t	0.17
-t	0.83

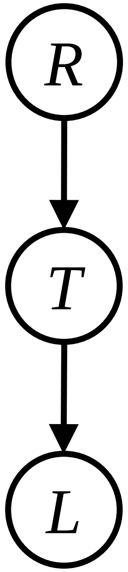


Inference by Enumeration in BN = Multiple Join + Multiple Eliminate



Computing $P(L)$: Multiple Joins





$P(R)$

+r	0.1
-r	0.9

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

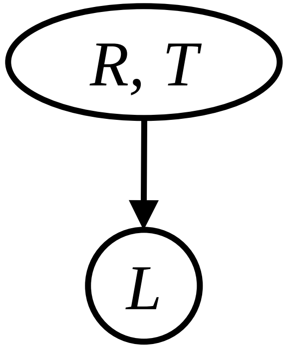
Join

$P(R,T)$

+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9



Join

$P(R,T,L)$

+r	+t	+l	0.024
+r	+t	-l	0.056
+r	-t	+l	0.002
+r	-t	-l	0.018
-r	+t	+l	0.027
-r	+t	-l	0.063
-r	-t	+l	0.081
-r	-t	-l	0.729

Computing $P(L)$: Multiple Elimination

R, T, L

$P(R,T,L)$

+r	+t	+l	0.024
+r	+t	-l	0.056
+r	-t	+l	0.002
+r	-t	-l	0.018
-r	+t	+l	0.027
-r	+t	-l	0.063
-r	-t	+l	0.081
-r	-t	-l	0.729

A factor of exponential size!

Sum out R

T, L

$P(T,L)$

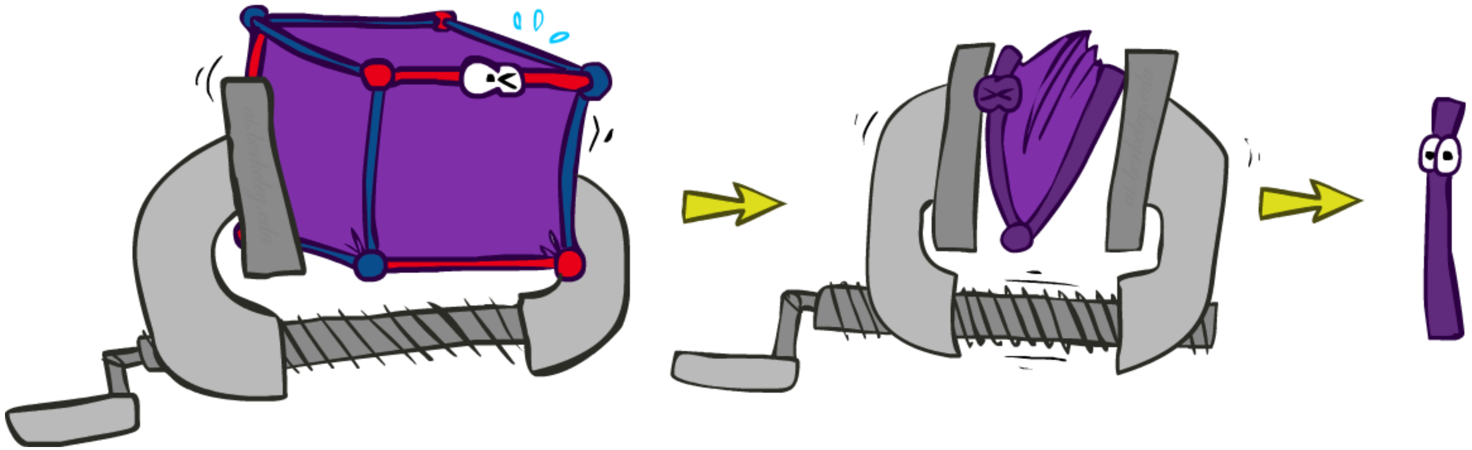
+t	+l	0.051
+t	-l	0.119
-t	+l	0.083
-t	-l	0.747

Sum out T

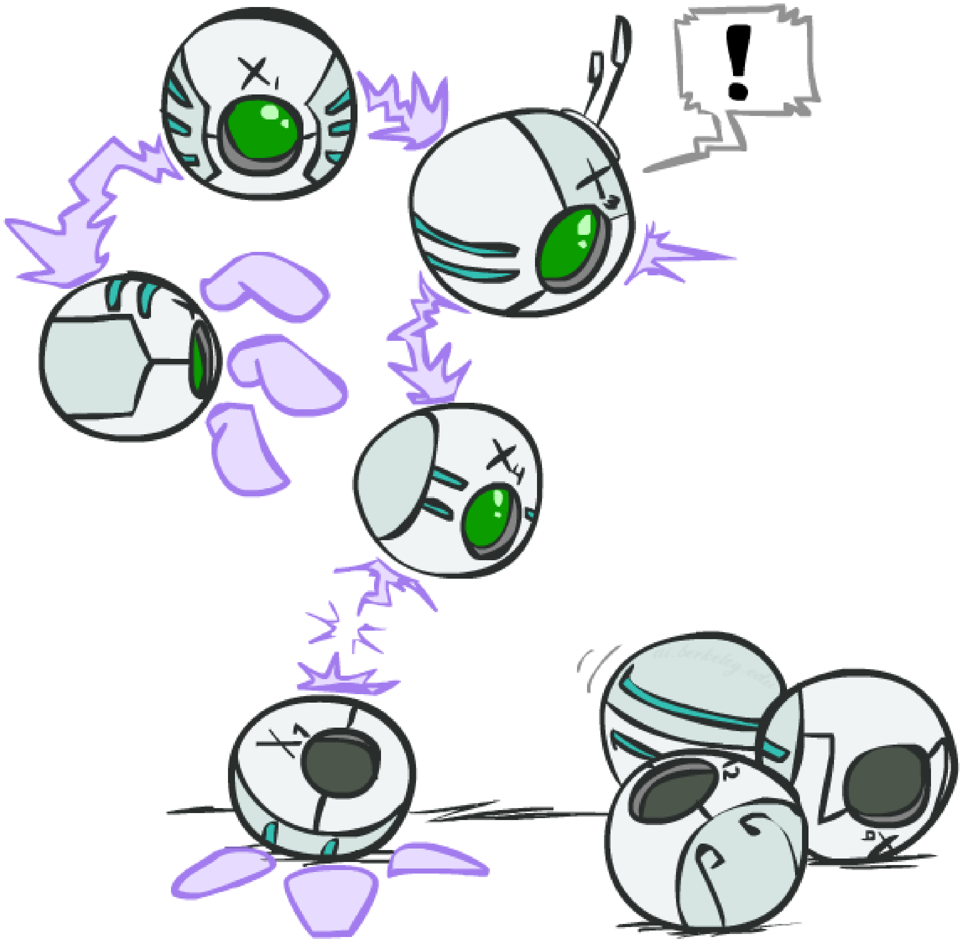
L

$P(L)$

+l	0.134
-l	0.866

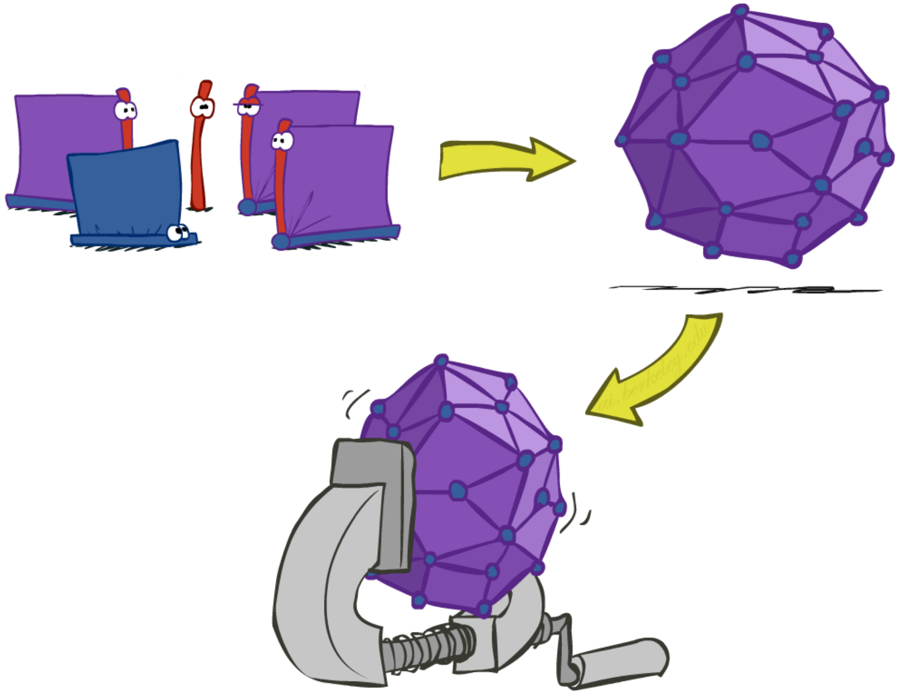


Variable Elimination

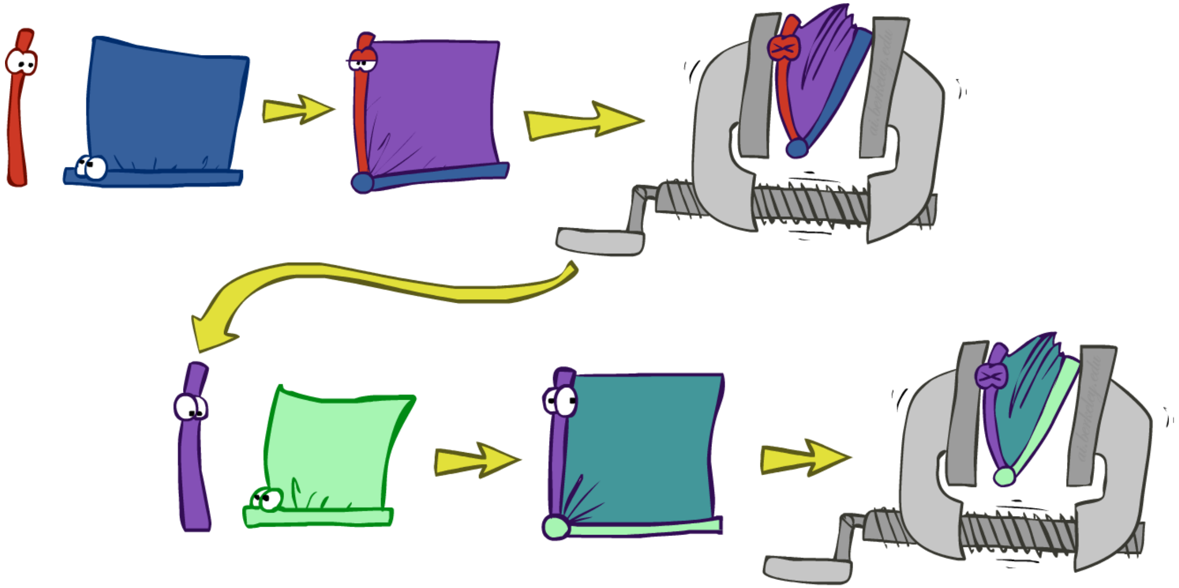


Inference by Enumeration vs. Variable Elimination

- Why is inference by enumeration so slow?
  - You join up the whole joint distribution before you sum out the hidden variables

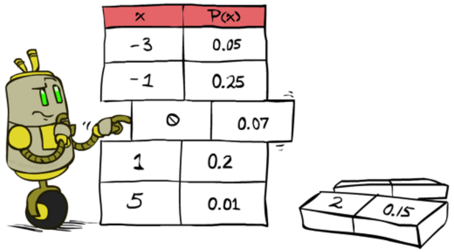


- Idea: interleave joining and elimination!
  - Called "Variable Elimination"
  - Still NP-hard, but usually much faster than inference by enumeration

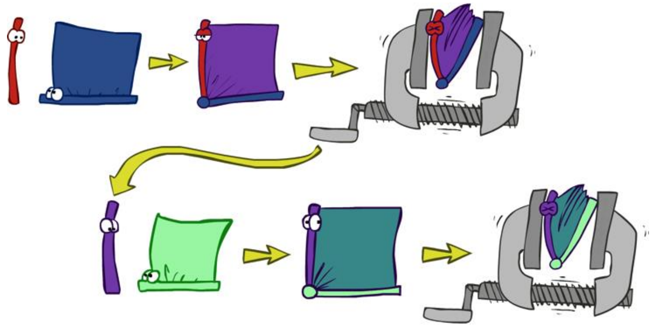


Variable Elimination

- Query: $P(Q|E_1 = e_1, \ldots E_k = e_k)$



- Start with initial factors:
  - Local CPTs (but instantiated by evidence)

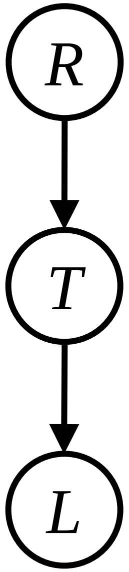


- While there are still hidden variables (not Q or evidence):
  - Pick a hidden variable H
  - Join all factors mentioning H
  - Eliminate (sum out) H

- Join all remaining factors and normalize

$\times \frac{1}{Z}$

Traffic Domain



$$P(L) = ?$$

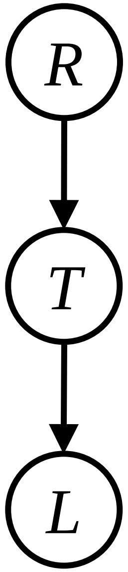
- Inference by Enumeration

$$= \underbrace{\sum_t \underbrace{\sum_r \underbrace{P(L|t)\underbrace{P(r)P(t|r)}_{\text{Join on r}}}_{\text{Join on t}}}_{\text{Eliminate r}}}_{\text{Eliminate t}}$$

- Variable Elimination

$$= \underbrace{\sum_t \underbrace{P(L|t) \underbrace{\sum_r \underbrace{P(r)P(t|r)}_{\text{Join on r}}}_{\text{Eliminate r}}}_{\text{Join on t}}}_{\text{Eliminate t}}$$

Variable Elimination



$P(R)$

+r	0.1
-r	0.9

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

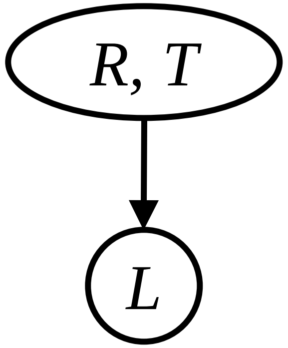
$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

Join R

$P(R,T)$

+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81



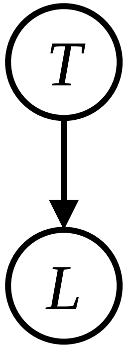
$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

Sum out R

$P(T)$

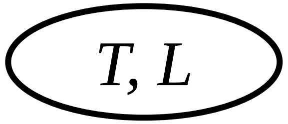
+t	0.17
-t	0.83



$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

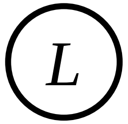
Join T



$P(T,L)$

+t	+l	0.051
+t	-l	0.119
-t	+l	0.083
-t	-l	0.747

Sum out T



$P(L)$

+l	0.134
-l	0.866

Evidence

- If evidence, start with factors that select that evidence
  - No evidence uses these initial factors:

$P(R)$

+r	0.1
-r	0.9

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

  - Computing $P(L|+r)$ the initial factors become:

$P(+r)$

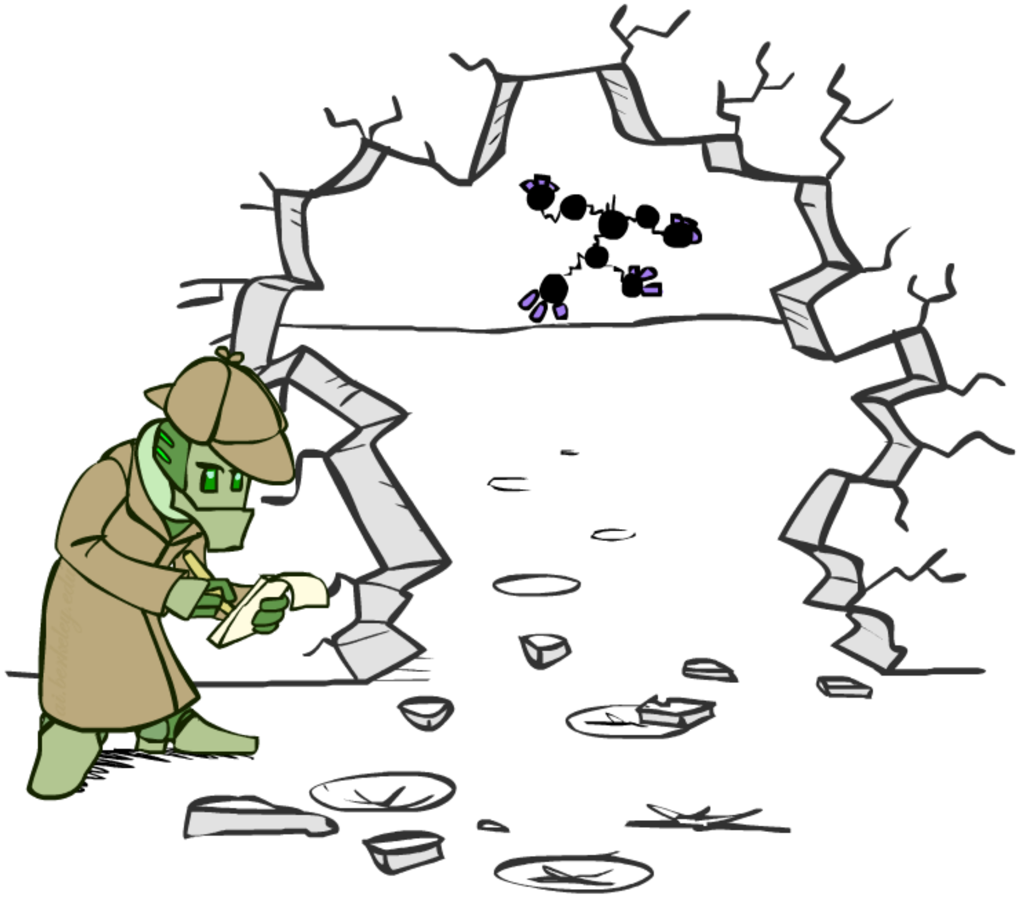
+r	0.1

$P(T|+r)$

+r	+t	0.8
+r	-t	0.2

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9



- We eliminate all vars other than query + evidence

Evidence II

- Result will be a selected joint of query and evidence
  - E.g. for P(L | +r), we would end up with:

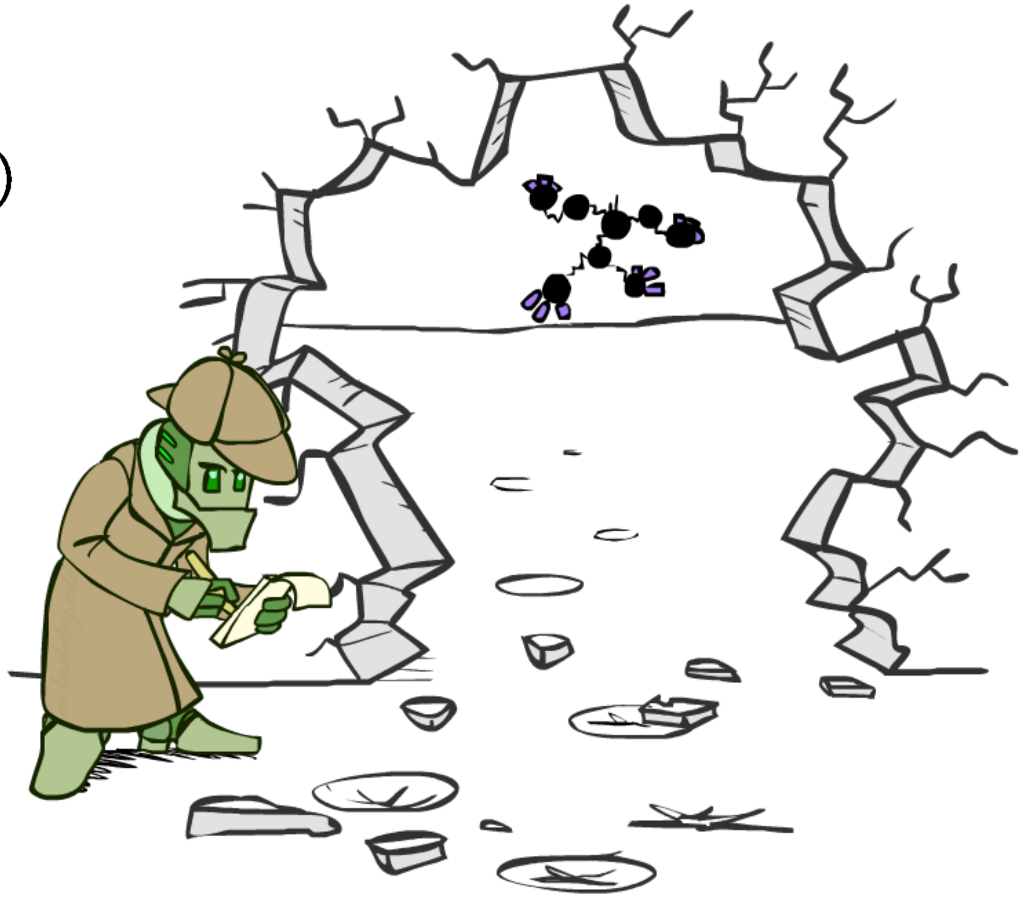
$$P(+r, L)$$

+r	+l	0.026
+r	-l	0.074

Normalize

$$P(L|+r)$$

+l	0.26
-l	0.74

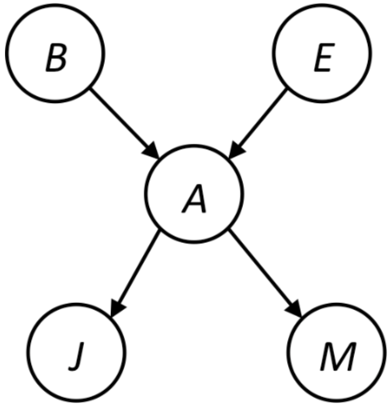


- To get our answer, just normalize this!

- That 's it!

Example

$$P(B|j,m) \propto P(B,j,m)$$



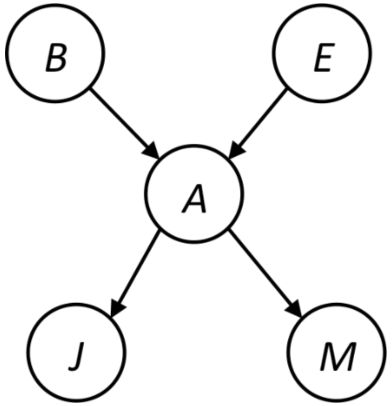
$$\boxed{P(B) \qquad P(E) \qquad P(A|B,E) \qquad P(j|A) \qquad P(m|A)}$$

Choose A

$$\begin{array}{l} P(A|B,E) \\ P(j|A) \\ P(m|A) \end{array} \xrightarrow{\times} \xrightarrow{\Sigma} P(j,m|B,E)$$

$$\boxed{P(B) \qquad P(E) \qquad P(j,m|B,E)}$$

Example



$$P(B) \qquad P(E) \qquad P(j,m|B,E)$$

Choose E

$$P(E)$$
$$P(j,m|B,E)$$

$\times$ Σ $P(j,m|B)$

$$P(B) \qquad P(j,m|B)$$

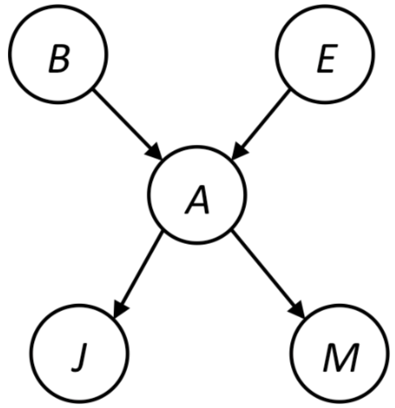
Finish with B

$$P(B)$$
$$P(j,m|B)$$

$\times$ $P(j,m,B)$ Normalize $P(B|j,m)$

Same Example in Equations

$$P(B|j,m) \propto P(B,j,m)$$



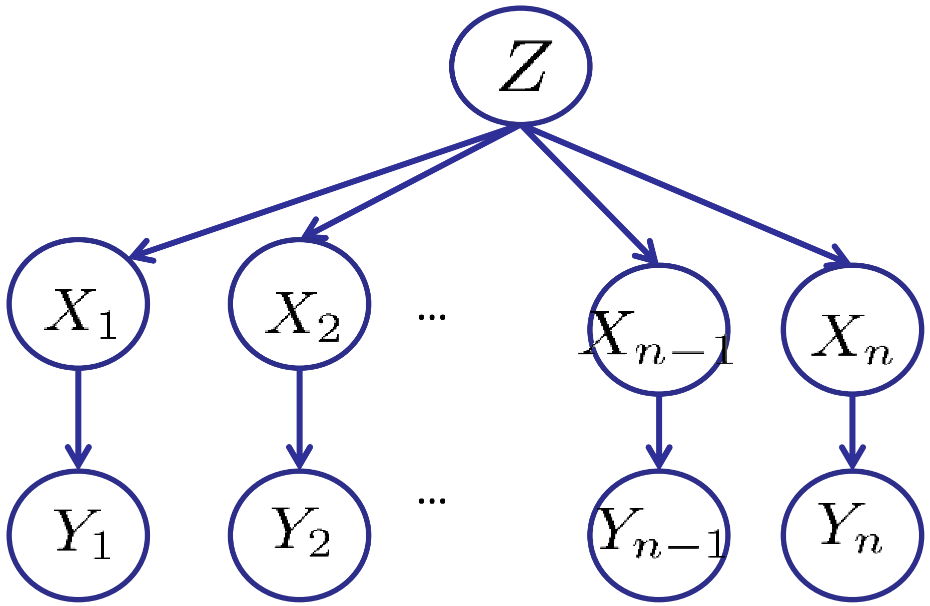
$$\boxed{P(B) \qquad P(E) \qquad P(A|B,E) \qquad P(j|A) \qquad P(m|A)}$$

$$\begin{aligned}
P(B|j,m) &\propto P(B,j,m) \\
&= \sum_{e,a} P(B,j,m,e,a) && \text{marginal can be obtained from joint by summing out} \\
&= \sum_{e,a} P(B)P(e)P(a|B,e)P(j|a)P(m|a) && \text{use Bayes' net joint distribution expression} \\
&= \sum_{e} P(B)P(e)\sum_{a} P(a|B,e)P(j|a)P(m|a) && \text{use x*(y+z) = xy + xz} \\
&= \sum_{e} P(B)P(e)f_1(B,e,j,m) && \text{joining on a, and then summing out gives } f_1 \\
&= P(B)\sum_{e} P(e)f_1(B,e,j,m) && \text{use x*(y+z) = xy + xz} \\
&= P(B)f_2(B,j,m) && \text{joining on e, and then summing out gives } f_2
\end{aligned}$$

All we are doing is exploiting uwy + uwz + uxy + uxz + vwy + vwz + vxy +vxz = (u+v)(w+x)(y+z) to improve computational efficiency!

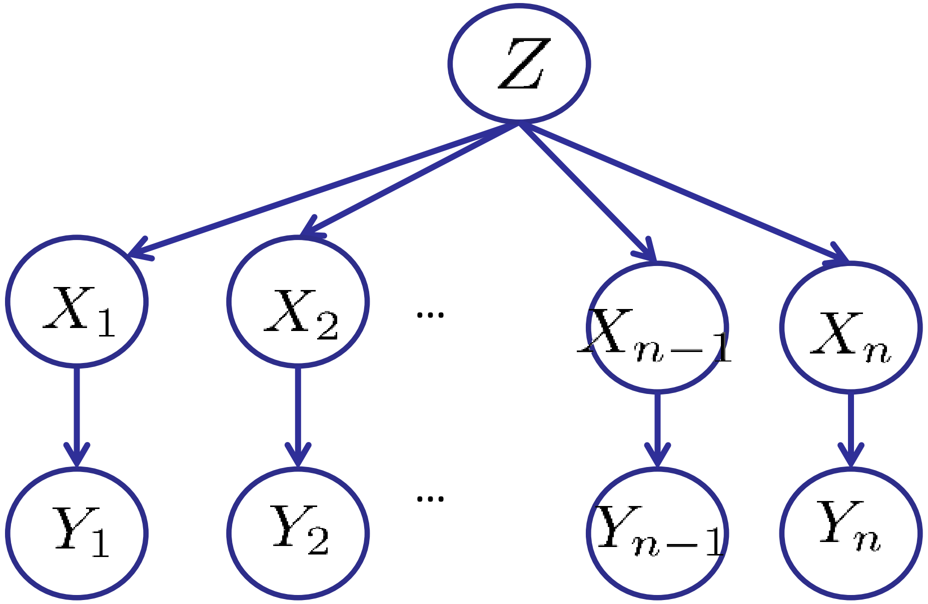
Variable Elimination Ordering

- Query: $P(X_n | y_1,\ldots,y_n)$
- Two different orderings: $Z, X_1, \ldots, X_{n-1}$ and $X_1, \ldots, X_{n-1}, Z$.
- What is the size of the maximum factor generated for each of the orderings?



Variable Elimination Ordering

- Z, X_1, …, X_{n-1}



$$P(Z)P(X_1|Z)P(X_2|Z),\ldots,P(X_n|Z)$$

$$f_1(X_1, X_2, \ldots, X_n)$$

$$f_2(y_1, X_2, \ldots, X_n)$$

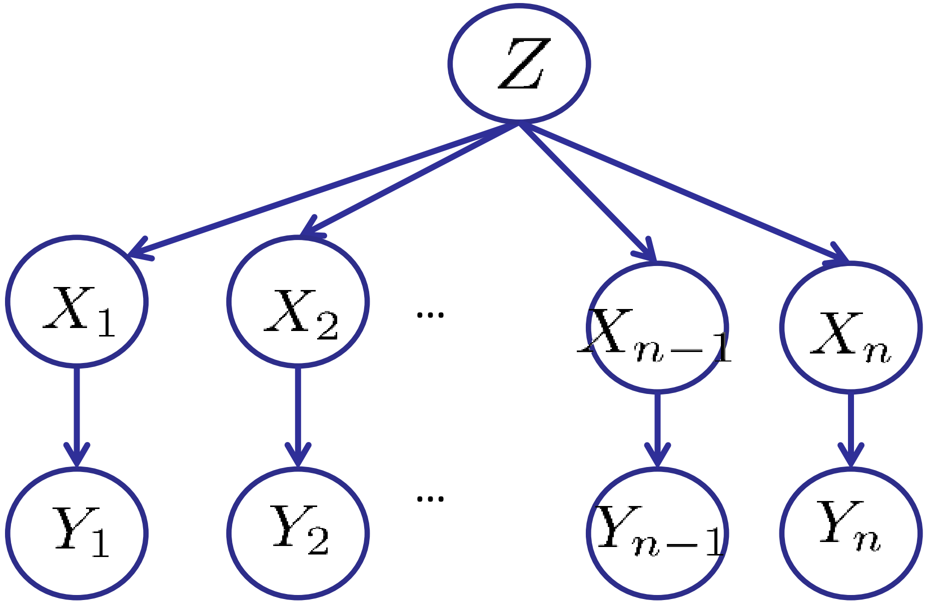
$$f_3(y_1, y_2, \ldots, X_n)$$

$$\vdots$$

$$2^{n+1}$$

Variable Elimination Ordering

- $X_1, \ldots, X_{n-1}, Z$



$$P(X_1|Z)P(y_1|X_1)$$

$$\Downarrow$$

$$f_1(Z, y_1)$$

$$\vdots$$

$$f_1(Z, y_1), f_2(Z, y_2), \ldots, f_{n-1}(Z, y_{n-1}), P(Z), P(X_n|Z)$$

$$\Downarrow$$

$$f_n(X_n, y_1, \ldots, y_{n-1})$$

$$\vdots$$

$$2^2$$

VE: Computational Complexity

- The size of the largest factor determines the time and space complexity of VE
- The elimination ordering can greatly affect the size of the largest factor.
  - E.g., previous slide's example 2^{n+1} vs. 2^2

- Does there always exist an ordering that only results in small factors?
  - No!

Reduction from 3SAT

$(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_1 \vee x_3 \vee \neg x_4) \wedge (x_2 \vee \neg x_2 \vee x_4) \wedge (\neg x_3 \vee \neg x_4 \vee \neg x_5) \wedge (x_2 \vee x_5 \vee x_7) \wedge (x_4 \vee x_5 \vee x_6) \wedge (\neg x_5 \vee x_6 \vee \neg x_7) \wedge (\neg x_5 \vee \neg x_6 \vee x_7)$

$P(X_i = 0) = P(X_i = 1) = 0.5$

$Y_1 = X_1 \vee X_2 \vee \neg X_3$

...

$Y_8 = \neg X_5 \vee X_6 \vee X_7$

$Y_{1,2} = Y_1 \wedge Y_2$

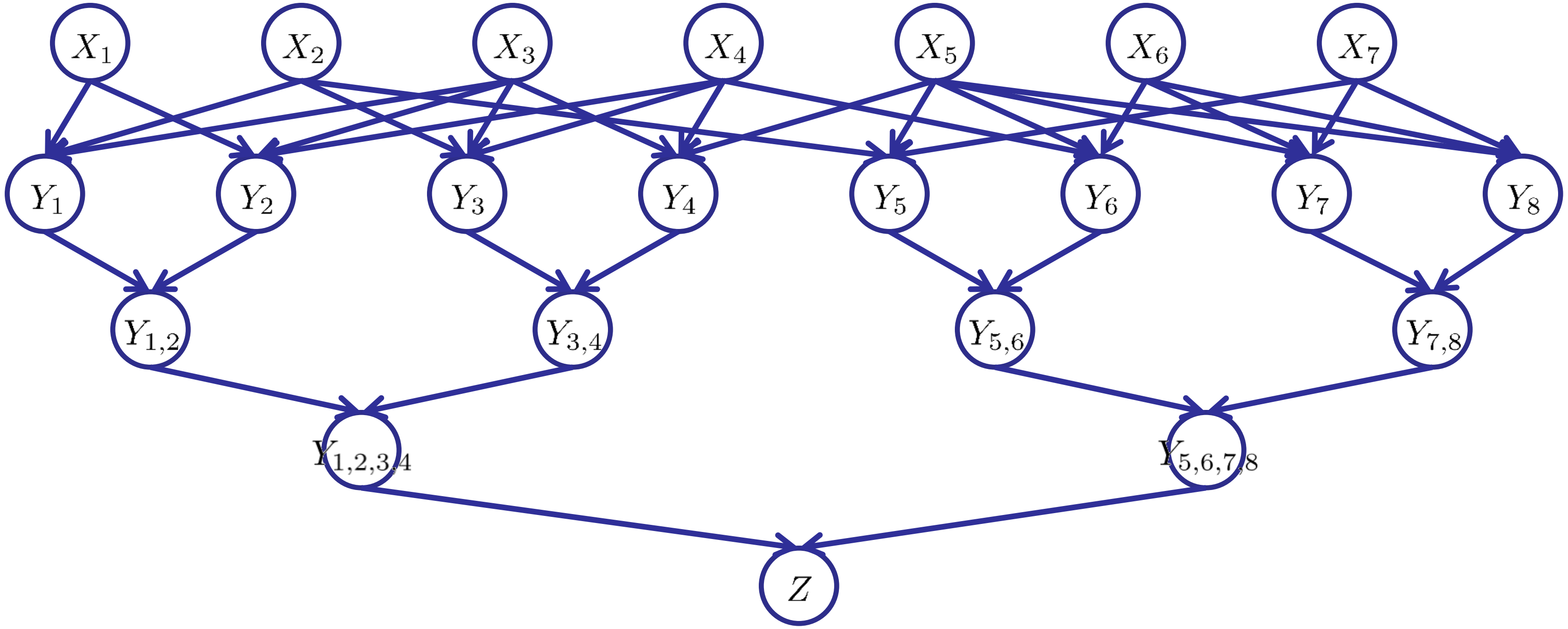
...

$Y_{7,8} = Y_7 \wedge Y_8$

$Y_{1,2,3,4} = Y_{1,2} \wedge Y_{3,4}$

$Y_{5,6,7,8} = Y_{5,6} \wedge Y_{7,8}$

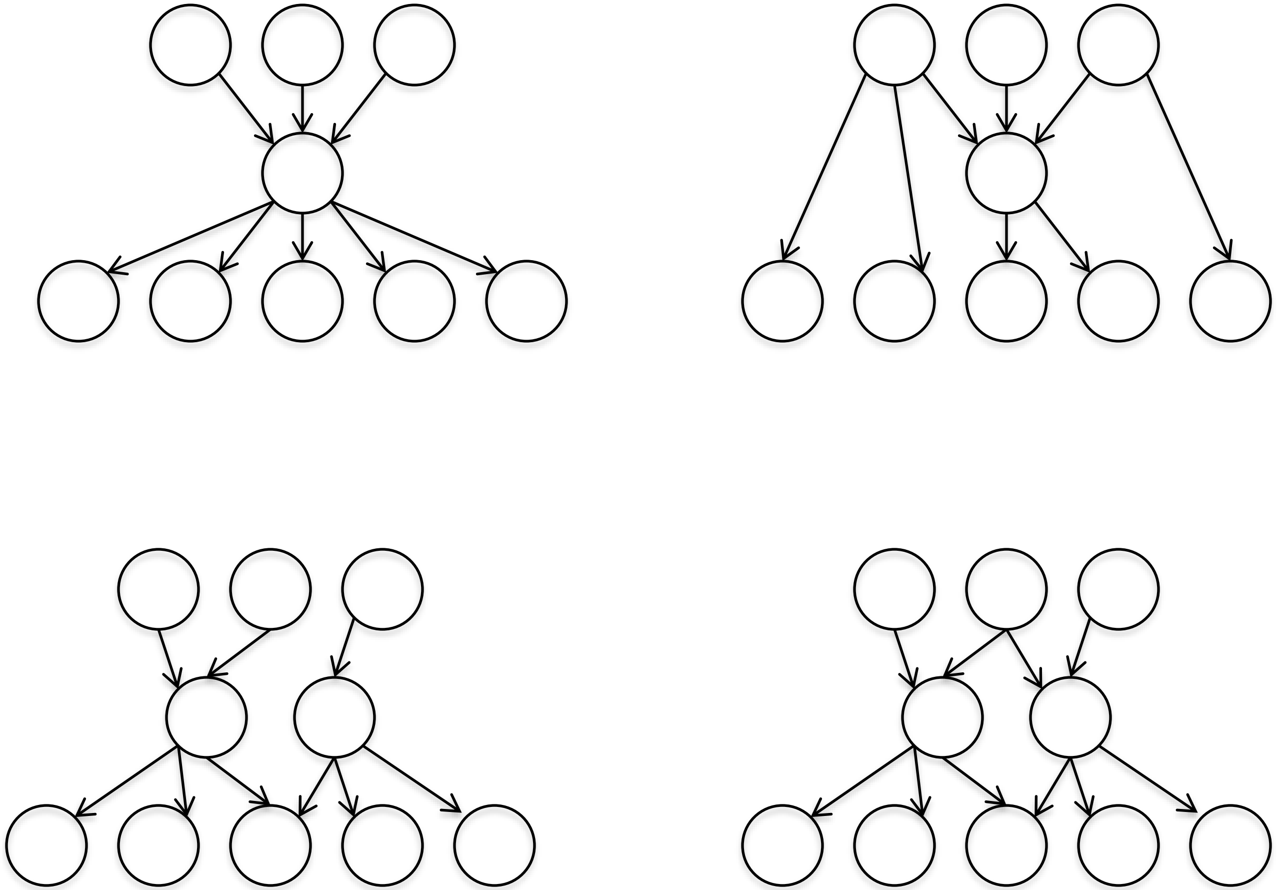
$Z = Y_{1,2,3,4} \wedge Y_{5,6,7,8}$



- If we can answer P(z) equal to zero or not, we answered whether the 3-SAT problem has a solution.
- Hence inference in Bayes' nets is NP-hard. No known efficient probabilistic inference in general.

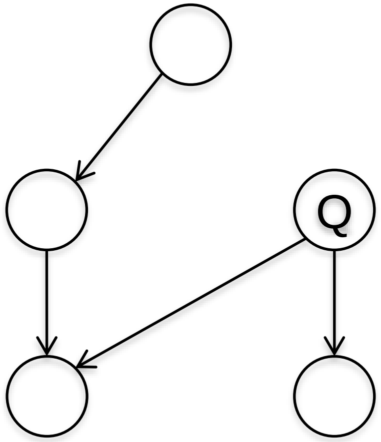
Polytrees

- A polytree is a directed graph with no undirected cycles

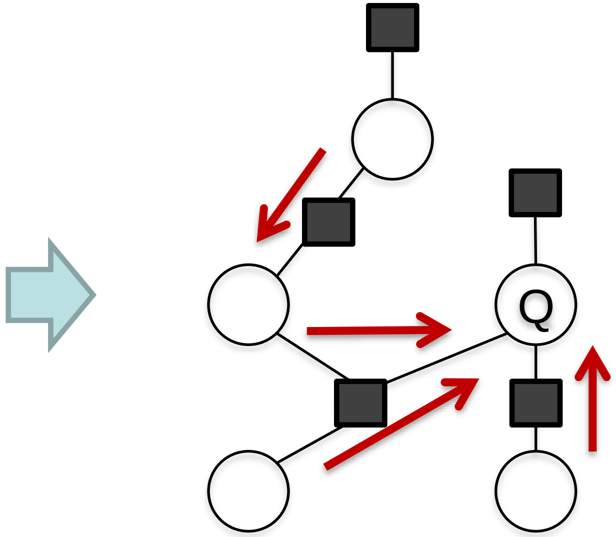


Variable Elimination on Polytrees

- For poly-tree BNs, the complexity of VE is ***linear in the BN size*** (number of CPT entries) with the following elimination ordering:
  - Convert to a factor graph
  - Take Q as the root
  - Eliminate from the leaves towards the root



Bayesian Network



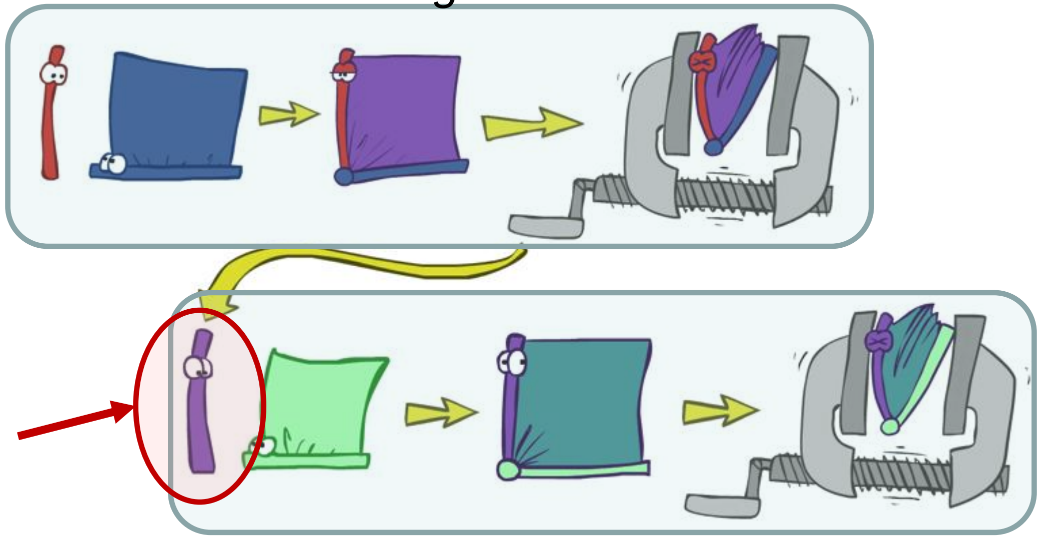
Factor Graph

Variable Elimination on Polytrees

- VE for poly-tree BNs is equivalent to
  - Sum-product message passing algorithm or belief propagation algorithm

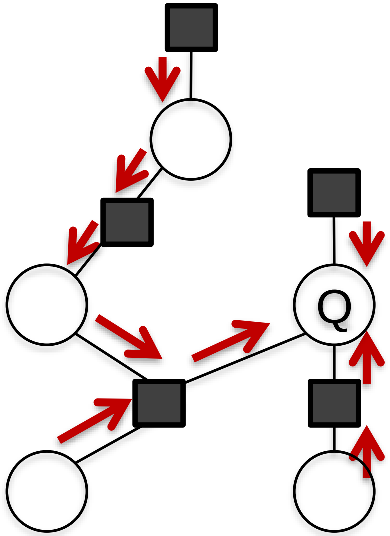
(i.e., passing messages/beliefs from leaf nodes to the root node)

Eliminating variable A



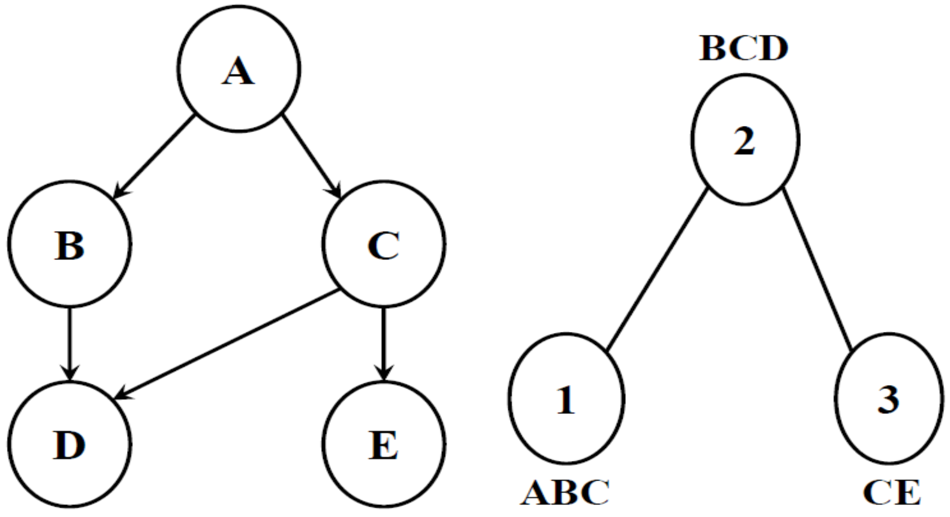
Message from A, which is used in eliminating B

Eliminating variable B



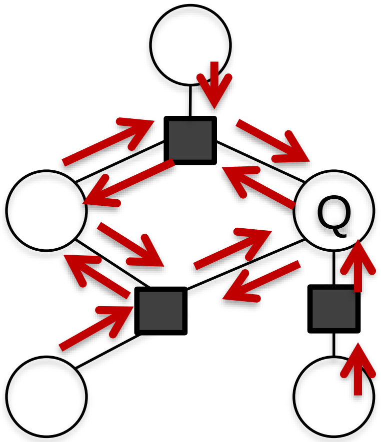
Message Passing on General Graphs

- Exact inference: Junction Tree Algorithm
  - Group individual nodes to form cluster nodes in such a way that the resulting network is a polytree (called a junction tree or join tree)
  - Run a sum-product-like algorithm on the junction tree.
  - *Intractable* on graphs with large cliques (i.e., large tree-width).



Message Passing on General Graphs

- Approximate inference: Loopy Belief Propagation
  - Simply pass the messages on the general graph
    - Will not terminate with loops
    - Run until convergence (not guaranteed!)
  - *Approximate* but *tractable* for large graphs.
  - Sometime works well, sometimes not at all.



Summary

- Exact inference of Bayesian networks
  - Enumeration
    - exponential complexity
  - Variable Eliminating
    - worst-case exponential complexity, often better
  - VE on polytrees
    - linear complexity
    - = message passing
  - Message passing on general graphs
    - Junction Tree Algorithm
    - Loopy Belief Propagation: no longer exact