

EE160 Introduction to Control: Homework 8

Prof. Boris Houska

Deadline: June 16, 2022

1. (6 points) *Infinite Horizon Optimal Control.* Solve the following optimal control problems explicitly. What are the optimal solution for x and u ?

(a)

$$\min_{x,u} \int_0^\infty (2x(t)^2 + 3u(t)^2) dt \quad \text{s.t.} \quad \begin{cases} \dot{x}(t) = 2x(t) + u(t) \\ x(0) = 1 \end{cases}$$

(b)

$$\min_{x,u} \int_0^\infty ((x(t) - 1)^2 + u(t)^2) dt \quad \text{s.t.} \quad \begin{cases} \dot{x}(t) = x(t) + u(t) + 1 \\ x(0) = 1 \end{cases}$$

(c)

$$\min_{x,u} \int_0^\infty (x_1(t)^2 + u(t)^2) dt \quad \text{s.t.} \quad \begin{cases} \dot{x}_1(t) = x_2(t) & \text{with } x_1(0) = 1 \\ \dot{x}_2(t) = x_3(t) & \text{with } x_2(0) = -1 \\ \dot{x}_3(t) = u(t) & \text{with } x_3(0) = 1 \end{cases}$$

Hint: Always think first about whether the infinite horizon optimal control problem has a solution at all.

2. (4 points) *Finite Horizon Optimal Control.* Solve the following scalar finite horizon optimal control problem explicitly,

$$\min_{x,u} \int_0^{10} (x(t)^2 + u(t)^2) dt + 5x(10)^2 \quad \text{s.t.} \quad \begin{cases} \dot{x}(t) = -x(t) + u(t) \\ x(0) = 1 \end{cases}$$

What are the optimal solution for x and u ?

Hint: Use the "separation of variables" to solve the associated Riccati differential equation.