## SI231 Matrix Analysis and Computations Singular Value Decomposition

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## **Singular Value Decomposition**

- singular values, singular vectors, and singular value decomposition
- matrix norms
- linear systems
- least squares, pseudo-inverse, orthogonal projections
- low-rank matrix approximation
- variational characterizations for singular values
- singular value inequalities
- computations of the SVD

## **Main Results**

ullet any matrix  $\mathbf{A} \in \mathbb{R}^{m imes n}$  admits a singular value decomposition

$$\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T$$

where  $\mathbf{U} \in \mathbb{R}^{m \times m}$  and  $\mathbf{V} \in \mathbb{R}^{n \times n}$  are orthogonal, and  $\mathbf{\Sigma} \in \mathbb{R}^{m \times n}$  has  $[\mathbf{\Sigma}]_{ij} = 0$  for all  $i \neq j$  and  $[\mathbf{\Sigma}]_{ii} = \sigma_i$  for all i, with  $\sigma_1 \geq \sigma_2 \geq \ldots \geq \sigma_{\min\{m,n\}} \geq 0$ .

- matrix 2-norm:  $\|\mathbf{A}\|_2 = \sigma_1$
- let r be the number of nonzero  $\sigma_i$ 's, partition  $\mathbf{U} = [\mathbf{U}_1 \ \mathbf{U}_2]$ ,  $\mathbf{V} = [\mathbf{V}_1 \ \mathbf{V}_2]$ , and let  $\tilde{\Sigma} = \mathrm{Diag}(\sigma_1, \ldots, \sigma_r)$ 
  - thin SVD:  $\mathbf{A} = \mathbf{U}_1 \tilde{\mathbf{\Sigma}} \mathbf{V}_1^T$
  - pseudo-inverse:  $\mathbf{A}^\dagger = \mathbf{V}_1 ilde{\mathbf{\Sigma}}^{-1} \mathbf{U}_1^T$
  - linear system solution:  $\mathbf{x} = \mathbf{A}^\dagger \mathbf{y} + \boldsymbol{\eta}$  for any  $\boldsymbol{\eta} \in \mathcal{R}(\mathbf{V}_2)$  and  $\mathbf{U}_2^T \mathbf{y} = \mathbf{0}$
  - least squares solution:  $\mathbf{x} = \mathbf{A}^\dagger \mathbf{y} + \boldsymbol{\eta}$  for any  $\boldsymbol{\eta} \in \mathcal{R}(\mathbf{V}_2)$
  - orthogonal projection:  $\mathbf{P}_{\mathbf{A}} = \mathbf{U}_1 \mathbf{U}_1^T$

## **Main Results**

• low-rank matrix approximation: given  $\mathbf{A} \in \mathbb{R}^{m \times n}$  and  $k \in \{1, \dots, \min\{m, n\}\}$ , the problem

$$\min_{\mathbf{B} \in \mathbb{R}^{m \times n}, \text{ rank}(\mathbf{B}) \le k} \|\mathbf{A} - \mathbf{B}\|_F^2$$

has a solution given by  $\mathbf{B}^\star = \sum_{i=1}^k \sigma_i \mathbf{u}_i \mathbf{v}_i^T$ 

• in this lecture, we will deal with the real matrices—the complex case follows along the same lines

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# Singular Values, Singular Vectors, and Singular Value Decomposition

**Theorem 1.** Given any  $\mathbf{A} \in \mathbb{R}^{m \times n}$ , there exists a 3-tuple  $(\mathbf{U}, \mathbf{\Sigma}, \mathbf{V}) \in \mathbb{R}^{m \times m} \times \mathbb{R}^{m \times n} \times \mathbb{R}^{n \times n}$  such that

$$\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T$$
,

 ${f U}$  and  ${f V}$  are orthogonal, and  ${f \Sigma}$  takes the form

$$[\mathbf{\Sigma}]_{ij} = \begin{cases} \sigma_i, & i = j \\ 0, & i \neq j \end{cases}, \qquad \sigma_1 \geq \sigma_2 \geq \ldots \geq \sigma_p \geq 0, \ p = \min\{m, n\}.$$

(requires a proof)

- the above decomposition is called the singular value decomposition (SVD)
- $\sigma_i$  is called the ith singular value (always nonnegative even for complex matrices)
- $\mathbf{u}_i$  and  $\mathbf{v}_i$  are called the *i*th left and right singular vectors, resp.  $\mathbf{u}_i^T \mathbf{A} = \sigma_i \mathbf{v}_i^T \iff \mathbf{U}^T \mathbf{A} = \mathbf{\Sigma} \mathbf{V}^T \iff \mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T$

$$\iff$$
 **AV** = **U** $\Sigma \implies$  **Av**<sub>i</sub> =  $\sigma_i$ **u**<sub>i</sub> for  $i = 1, ..., p$ 

 ${f U}$  and  ${f V}$  are called the left and right singular vector matrices, resp.

• the following notations may be used to denote singular values of a given A

$$\sigma_{\max}(\mathbf{A}) = \sigma_1(\mathbf{A}) \ge \sigma_2(\mathbf{A}) \ge \ldots \ge \sigma_p(\mathbf{A}) = \sigma_{\min}(\mathbf{A})$$

## Singular Spectrum and Singular Subspace

- The set  $\{\sigma_1, \ldots, \sigma_p\}$  is called the singular spectrum of  ${\bf A}$
- A pair of k-dimensional subspaces  $\mathcal{U}$  and  $\mathcal{V}$  are called left and right singular subspaces of  $\mathbf{A}$ , resp., if

$$\mathbf{A}\mathbf{v} \in \mathcal{U}$$
 for all  $\mathbf{v} \in \mathcal{V}$ 

and

$$\mathbf{A}^T \mathbf{u} \in \mathcal{V}$$
 for all  $\mathbf{u} \in \mathcal{U}$ .

We also write this as  $\mathbf{A}\mathcal{V} \subset \mathcal{U}$  and  $\mathbf{A}^T\mathcal{U} \subset \mathcal{V}$ .

- The simplest example is when  $\mathcal{U}$  and  $\mathcal{V}$  are spanned by a single pair of singular vectors  $\mathbf{u}_i$  and  $\mathbf{v}_i$  of  $\mathbf{A}$ , respectively.
- More generally, any pair of singular subspaces can be spanned by a subset of the singular vectors of  $\mathbf{A}$ , although the spanning vectors do not have to be singular vectors themselves.

## Different Ways of Writing out SVD

- thin SVD: only compute the first  $p = \min\{m, n\}$  columns of **U** and **V** 
  - for  $m \leq n$ :  $(\mathbf{U}, \mathbf{\Sigma}, \mathbf{V}) \in \mathbb{R}^{m \times m} \times \mathbb{R}^{m \times m} \times \mathbb{R}^{m \times n}$
  - for  $n \leq m$ :  $(\mathbf{U}, \mathbf{\Sigma}, \mathbf{V}) \in \mathbb{R}^{m \times n} \times \mathbb{R}^{n \times n} \times \mathbb{R}^{n \times n}$
- partitioned form of the full SVD: let r be the number of nonzero singular values, and note  $\sigma_1 \ge ... \ge \sigma_r > 0$ ,  $\sigma_{r+1} = ... = \sigma_p = 0$ . Then,

$$\mathbf{A} = egin{bmatrix} \mathbf{U}_1 & \mathbf{U}_2 \end{bmatrix} egin{bmatrix} \mathbf{ ilde{\Sigma}} & \mathbf{0} \ \mathbf{0} & \mathbf{0} \end{bmatrix} egin{bmatrix} \mathbf{V}_1^T \ \mathbf{V}_2^T \end{bmatrix},$$

where

- $-\tilde{\Sigma} = \mathrm{Diag}(\sigma_1, \ldots, \sigma_r),$
- $-\mathbf{U}_1=[\mathbf{u}_1,\ldots,\mathbf{u}_r^-]\in\mathbb{R}^{m imes r}$ ,  $\mathbf{U}_2=[\mathbf{u}_{r+1},\ldots,\mathbf{u}_m^-]\in\mathbb{R}^{m imes (m-r)}$ ,
- $\mathbf{V}_1=[\ \mathbf{v}_1,\ldots,\mathbf{v}_r\ ]\in\mathbb{R}^{n imes r}$ ,  $\mathbf{V}_2=[\ \mathbf{v}_{r+1},\ldots,\mathbf{v}_n\ ]\in\mathbb{R}^{n imes (n-r)}$ .
- compact SVD:  $\mathbf{A} = \mathbf{U}_1 \tilde{\mathbf{\Sigma}} \mathbf{V}_1^T$ 
  - both thin SVD and compact SVD are reduced SVD forms; in contrast, the one in Theorem 1 is also called full SVD
- outer-product form (i.e., dyadic decomposition):  $\mathbf{A} = \sum_{i=1}^{r} \sigma_i \mathbf{u}_i \mathbf{v}_i^T = \sum_{i=1}^{r} \sigma_i \mathbf{u}_i \mathbf{v}_i^T$

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## **SVD** and **Eigendecomposition**

From the SVD  $\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T$ , we see that

$$\mathbf{A}\mathbf{A}^T = \mathbf{U}\mathbf{D}_1\mathbf{U}^T, \qquad \mathbf{D}_1 = \mathbf{\Sigma}\mathbf{\Sigma}^T = \mathrm{Diag}(\sigma_1^2, \dots, \sigma_p^2, \underbrace{0, \dots, 0}_{m-p \text{ zeros}})$$
 (\*)

$$\mathbf{A}^T \mathbf{A} = \mathbf{V} \mathbf{D}_2 \mathbf{V}^T, \qquad \mathbf{D}_2 = \mathbf{\Sigma}^T \mathbf{\Sigma} = \operatorname{Diag}(\sigma_1^2, \dots, \sigma_p^2, \underbrace{0, \dots, 0}_{n-p \text{ zeros}})$$
 (\*\*)

#### **Observations:**

- (\*) and (\*\*) are the SVD's of  $AA^T$  and  $A^TA$ , resp.
- (\*) and (\*\*) are the eigendecompositions of  $AA^T$  and  $A^TA$ , resp.
- ullet the left singular matrix  ${f U}$  of  ${f A}$  is the eigenvector matrix of  ${f A}{f A}^T$
- ullet the right singular matrix  ${f V}$  of  ${f A}$  is the eigenvector matrix of  ${f A}^T{f A}$
- the squares of nonzero singular values of A,  $\sigma_1^2, \ldots, \sigma_r^2$ , are the nonzero eigenvalues of both  $AA^T$  and  $A^TA$ .
- the relation between SVD and eigendec. can be used for analysis and computations

## Insights of the Proof of SVD

- the proof of SVD is constructive
- to see the insights, consider the special case of square nonsingular A
- $\bullet$   $\mathbf{A}\mathbf{A}^T$  is PD, and denote its eigendecomposition by

$$\mathbf{A}\mathbf{A}^T = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^T$$
, with  $\lambda_1 \geq \ldots \geq \lambda_n > 0$ .

- let  $\Sigma = \text{Diag}(\sqrt{\lambda_1}, \dots, \sqrt{\lambda_m})$ ,  $\mathbf{V} = \mathbf{A}^T \mathbf{U} \Sigma^{-1}$
- ullet it can be verified that  $\mathbf{U} oldsymbol{\Sigma} \mathbf{V}^T = \mathbf{A}$ ,  $\mathbf{V}^T \mathbf{V} = \mathbf{I}$
- how to prove the SVD in the general case? (requires a proof)

## **Uniqueness of SVD**

- the singular values  $\sigma_i$ 's are uniquely determined and the nonzero singular values are the positive square roots of the eigenvalues of  $\mathbf{A}\mathbf{A}^T$  or, equivalently, of  $\mathbf{A}^T\mathbf{A}$
- the multiplicity of a singular value  $\sigma$  of  $\bf A$  is the multiplicity of  $\sigma^2$  as an eigenvalue of  $\bf A \bf A^T$  or, equivalently, of  $\bf A^T \bf A$
- a singular value  $\sigma$  of  $\mathbf{A}$  is simple (algebraic multiplicity is 1) if  $\sigma^2$  is a simple eigenvalue of  $\mathbf{A}\mathbf{A}^T$  or, equivalently, of  $\mathbf{A}^T\mathbf{A}$

uniqueness of SVD is highly related to the multiplicity of singular values and zero singular values of **A** and there are different kinds of characterizations; see Theorem 2.6.5 in [Horn-Johnson'12].

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## **Matrix Equivalences**

Given  $\mathbf{A},\ \mathbf{B} \in \mathbb{R}^{m \times n}$ , they are called equivalent if

$$\mathbf{B} = \mathbf{Q}^{-1} \mathbf{A} \mathbf{P}$$

for some invertible P and Q, which are called the equivalence transformations.

- Two matrices are equivalent if and only if they have the same rank.
- not be confused with matrix similarity, which is only defined for square matrices

Suppose  $\mathbf{Q}$  and  $\mathbf{P}$  are unitary matrices, i.e.,  $\mathbf{Q}^{-1} = \mathbf{Q}^H$  and  $\mathbf{P}^{-1} = \mathbf{P}^H$ . We say that  $\mathbf{B}$  is unitarily (orthogonally) equivalent to  $\mathbf{A}$ , where  $\mathbf{Q}$  and  $\mathbf{P}$  are unitary (orthogonal) equivalence transformations.

- B has the same singular values as A.
- If  $\mathbf{u}$  and  $\mathbf{v}$  are left and right singular vectors of  $\mathbf{A}$ , resp., so that  $\mathbf{A}\mathbf{v} = \sigma\mathbf{u}$  and  $\mathbf{A}^H\mathbf{u} = \sigma\mathbf{v}$ , then  $\mathbf{Q}^H\mathbf{u}$  and  $\mathbf{P}^H\mathbf{v}$  are left and right singular vectors of  $\mathbf{B}$ , resp.

## **Properties of SVD**

**Property 1.** The following properties hold:

- (a)  $\mathbf{A}^T = \mathbf{V} \mathbf{\Sigma}^T \mathbf{U}^T$
- (b)  $\mathbf{A}$ ,  $\mathbf{A}^*$ ,  $\mathbf{A}^T$ , and  $\mathbf{A}^H$  have the same singular values
- (c)  $\mathbf{u}_i^T \mathbf{A} \mathbf{v}_i = \sigma_i$  for  $i = 1, \dots, p$ , or, equivalently, in matrix form  $\mathbf{U}^T \mathbf{A} \mathbf{V} = \mathbf{\Sigma}$
- (d)  $\operatorname{tr}(\mathbf{A}^T \mathbf{A}) = \operatorname{tr}(\mathbf{A} \mathbf{A}^T) = \sum_{i=1}^p \sigma_i^2$
- (e) let  $\mathbf{A} \in \mathbb{R}^{n \times n}$ ,  $|\det(\mathbf{A})| = |\det(\mathbf{\Sigma})| = \prod_{i=1}^n \sigma_i$
- (f)  $rank(\mathbf{A}) < q$  (singular for square  $\mathbf{A}$ ) if and only if 0 is one singular value of  $\mathbf{A}$
- (g)  $rank(\mathbf{A}) = number of nonzero singular values$
- (h) let  $\mathbf{A} \in \mathbb{S}^n$ , the singular values are the absolute values of eigenvalues of  $\mathbf{A}$
- (i) if **A** is invertible,  $\mathbf{A}^{-1} = \mathbf{V} \mathbf{\Sigma}^{-1} \mathbf{U}^T$  (can be used to compute matrix inversion)
- (j) for othogonal  $\mathbf{P}$  and  $\mathbf{Q}$ , SVD of  $\mathbf{P}\mathbf{A}\mathbf{Q}^T$  is given by  $\tilde{\mathbf{U}}\mathbf{\Sigma}\tilde{\mathbf{V}}^T$  where  $\tilde{\mathbf{U}}=\mathbf{P}\mathbf{U}$  and  $\tilde{\mathbf{V}}=\mathbf{Q}\mathbf{V}$ , i.e., singular values are orthogonally invariant (i.e.,  $\sigma_i(\mathbf{A})=\sigma_i(\mathbf{P}\mathbf{A}\mathbf{Q}^T)$ ) but singular vectors not

## **Properties of SVD**

## **Property 2.** The following properties hold:

(a) 
$$\mathcal{R}(\mathbf{A}) = \mathcal{N}(\mathbf{A}^T)^{\perp} = \mathcal{R}(\mathbf{U}_1)$$
,  $\mathcal{R}(\mathbf{A})^{\perp} = \mathcal{N}(\mathbf{A}^T) = \mathcal{R}(\mathbf{U}_2)$ ;

(b) 
$$\mathcal{R}(\mathbf{A}^T) = \mathcal{N}(\mathbf{A})^{\perp} = \mathcal{R}(\mathbf{V}_1)$$
,  $\mathcal{R}(\mathbf{A}^T)^{\perp} = \mathcal{N}(\mathbf{A}) = \mathcal{R}(\mathbf{V}_2)$ ;

(c)  $rank(\mathbf{A}) = r$  (the number of nonzero singular values).

(Proof as a Quiz)

#### Note:

- in practice, SVD can be used a numerical tool for computing bases of  $\mathcal{R}(\mathbf{A})$ ,  $\mathcal{N}(\mathbf{A}^T)$ ,  $\mathcal{R}(\mathbf{A}^T)$ ,  $\mathcal{N}(\mathbf{A})$
- we have previously learnt the following properties
  - $-\operatorname{rank}(\mathbf{A}^T) = \operatorname{rank}(\mathbf{A}) = \operatorname{rank}(\mathbf{A}\mathbf{A}^T) = \operatorname{rank}(\mathbf{A}^T\mathbf{A})$
  - $\operatorname{rank}(\mathbf{A}) + \operatorname{nullity}(\mathbf{A}) = n$

By SVD, the above properties are easily seen to be true

SVD can also be used as a numerical tool to compute the rank of a matrix