

Friot: A Functional Reactive Language for IoT Programs with Dependent Type-and-Effect System (Report)

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I. TYPE CHECKING TREES FOR FUNCTION DELAY

```
delay t =
  if t == 0 then ev (LightUp)
  else ev (Tick);
  delay (t - 1);
```

```
 $\tau_{\text{delay}} = t : \text{Int} \rightarrow (\text{Unit} \ \& \ \Phi_{\text{delay}})$ 
 $\Phi_{\text{delay}} = (t \geq 0 \wedge \underline{\text{Tick}}^t \cdot \underline{\text{LightUp}}) \vee (t < 0 \wedge \underline{\text{Tick}}^\omega)$ 
```

delay	
$\frac{\frac{\Phi = \underline{\text{LightUp}}}{\Gamma' \vdash \text{ev}(\text{LightUp}) : \text{Unit} \ \& \ \underline{\text{LightUp}}} \text{ (T-Event)} \quad \frac{\frac{\Phi = \underline{\text{Tick}}}{\Gamma' \vdash \text{ev}(\text{Tick}) : \text{Unit} \ \& \ \underline{\text{Tick}}} \text{ (T-Event)} \quad \mathbf{A}}{\Gamma' \vdash (\text{ev}(\text{Tick}); \text{delay}(t-1)) : \text{Unit} \ \& \ (\underline{\text{Tick}} \cdot \Phi_{\text{delay}}^{(t-1)})} \text{ (T-Let)}$ $\frac{\Gamma' \vdash (\text{if } t == 0 \text{ then ev}(\text{LightUp}) \text{ else ev}(\text{Tick}); \text{delay}(t-1)) : \text{Unit} \ \& \ (t == 0 \wedge \underline{\text{LightUp}}) \vee (t \neq 0 \wedge \underline{\text{Tick}} \cdot \Phi_{\text{delay}}^{(t-1)})}{\Gamma' \vdash (\text{if } t == 0 \text{ then ev}(\text{LightUp}) \text{ else ev}(\text{Tick}); \text{delay}(t-1)) : \text{Unit} \ \& \ (t == 0 \wedge \underline{\text{LightUp}}) \vee (t \neq 0 \wedge \underline{\text{Tick}} \cdot \Phi_{\text{delay}}^{(t-1)})} \text{ (T-If)}$ $\frac{\dots \text{ (Effects Computation I) } \dots}{\Gamma \vdash (\text{delay } t = \text{if } \dots \text{ then } \dots \text{ else } \dots) : (t : \text{Int}) \rightarrow (\text{Unit} \ \& \ (t \geq 0 \wedge \underline{\text{Tick}}^t \cdot \underline{\text{LightUp}}) \vee (t < 0 \wedge \underline{\text{Tick}}^\omega))} \text{ (T-Fun)}$	
$\Gamma' = \Gamma, \text{delay} : \tau_{\text{delay}}$	
$\Phi_{\text{delay}}^{(t-1)} = (t \geq 1 \wedge \underline{\text{Tick}}^{t-1} \cdot \underline{\text{LightUp}}) \vee (t < 1 \wedge \underline{\text{Tick}}^\omega)$	
$\mathbf{A}:$	$\frac{\frac{\text{sty}(\Gamma'(\text{delay})) \in \rightarrow}{\Gamma' \vdash \text{delay} : (t : \text{Int}) \rightarrow (\text{Unit} \ \& \ (t \geq 0 \wedge \underline{\text{Tick}}^t \cdot \underline{\text{LightUp}}) \vee (t < 0 \wedge \underline{\text{Tick}}^\omega))} \text{ (T-VaF)} \quad \frac{\text{sty}(\Gamma'(t)) = \text{Int}}{\Gamma' \vdash (t-1) : \text{int}} \text{ (T-Var, T-Op)}}{\Gamma' \vdash \text{delay}(t-1) : (t-1 : \text{int}) \rightarrow (\text{Unit} \ \& \ (t \geq 1 \wedge \underline{\text{Tick}}^{t-1} \cdot \underline{\text{LightUp}}) \vee (t < 1 \wedge \underline{\text{Tick}}^\omega))} \text{ (T-App, S-Base)}$
$\mathbf{I}:$	$\begin{aligned} & (t == 0 \wedge \underline{\text{LightUp}}) \vee (t \neq 0 \wedge \underline{\text{Tick}} \cdot \Phi_{\text{delay}}^{(t-1)}) \\ \equiv & (t == 0 \wedge \underline{\text{LightUp}}) \vee (t \neq 0 \wedge \underline{\text{Tick}} \cdot ((t \geq 1 \wedge \underline{\text{Tick}}^{t-1} \cdot \underline{\text{LightUp}}) \vee (t < 1 \wedge \underline{\text{Tick}}^\omega))) \\ \equiv & (t == 0 \wedge \underline{\text{LightUp}}) \vee ((t \neq 0 \wedge t \geq 1) \wedge \underline{\text{Tick}} \cdot \underline{\text{Tick}}^{t-1} \cdot \underline{\text{LightUp}}) \vee ((t \neq 0 \wedge t < 1) \wedge (\underline{\text{Tick}} \cdot \underline{\text{Tick}}^\omega)) \\ \equiv & (t == 0 \wedge \underline{\text{LightUp}}) \vee (t \geq 1 \wedge \underline{\text{Tick}} \cdot \underline{\text{Tick}}^{t-1} \cdot \underline{\text{LightUp}}) \vee (t < 0 \wedge (\underline{\text{Tick}} \cdot \underline{\text{Tick}}^\omega)) \\ \equiv & (t == 0 \wedge \underline{\text{LightUp}}) \vee (t \geq 1 \wedge \underline{\text{Tick}}^t \cdot \underline{\text{LightUp}}) \vee (t < 0 \wedge \underline{\text{Tick}}^\omega) \\ \equiv & (t \geq 0 \wedge \underline{\text{Tick}}^t \cdot \underline{\text{LightUp}}) \vee (t < 0 \wedge \underline{\text{Tick}}^\omega) \\ \equiv & \Phi_{\text{delay}} \end{aligned}$

II. TYPE CHECKING TREES FOR FUNCTION DOOR_CONTROL

```
motion_sensor =
  if * then
    ev (Active)
  else
    ev (Passive);
    motion_sensor;

door_control =
  ev (Close);
  motion_sensor;
  ev (Open);
  ev (Delay);
  door_control;
```

```
 $\tau_{\text{motion\_sensor}} = \text{Unit} \rightarrow (\text{Unit} \ \& \ \Phi_{\text{motion\_sensor}})$ 
 $\Phi_{\text{motion\_sensor}} = \underline{\text{Passive}}^* \cdot \underline{\text{Active}} \vee \underline{\text{Passive}}^\omega$ 
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$$\tau_{\text{door_control}} = \text{Unit} \rightarrow (\text{Unit} \ \& \ \Phi_{\text{door_control}})$$

$$\Phi_{\text{door_control}} = (\underline{\text{Close}} \cdot (\underline{\text{Passive}}^* \cdot \underline{\text{Active}} \vee \underline{\text{Passive}}^\omega) \cdot \underline{\text{Open}} \cdot \underline{\text{Delay}})^\omega$$

door_control	
$\frac{\Phi = \underline{\text{Close}}}{\Gamma' \vdash \text{ev}(\text{Close}) : \text{Unit} \ \& \ \underline{\text{Close}}} \text{ (T-Event)} \quad \mathbf{A} \quad \frac{\Phi = \underline{\text{Open}}}{\Gamma' \vdash \text{ev}(\text{Open}) : \text{Unit} \ \& \ \underline{\text{Open}}} \text{ (T-Event)} \quad \frac{\Phi = \underline{\text{Delay}}}{\Gamma' \vdash \text{ev}(\text{Delay}) : \text{Unit} \ \& \ \underline{\text{Delay}}} \text{ (T-Event)} \quad \mathbf{B}$	(T-If)
$\frac{\Gamma' \vdash (\text{ev}(\text{Close}); \text{motion_sensor}; \text{ev}(\text{Open}); \text{ev}(\text{Delay}); \text{door_control}); : \text{Unit} \ \& \ (\underline{\text{Close}} \cdot \Phi_{\text{motion_sensor}} \cdot \underline{\text{Open}} \cdot \underline{\text{Delay}} \cdot \Phi_{\text{door_control}})}{\dots \text{ (Effects Computation I) } \dots}$	
$\frac{}{\Gamma \vdash (\text{door_control} = \dots) : \text{Unit} \rightarrow (\text{Unit} \ \& \ (\underline{\text{Close}} \cdot (\underline{\text{Passive}}^* \cdot \underline{\text{Active}} \vee \underline{\text{Passive}}^\omega) \cdot \underline{\text{Open}} \cdot \underline{\text{Delay}})^\omega)} \text{ (T-Fun)}$	
$\Gamma' = \Gamma, \text{door_control} : \tau_{\text{door_control}}$	
$\mathbf{A}: \frac{\text{sty}(\Gamma'(\text{motion_sensor})) \in \rightarrow}{\Gamma' \vdash \text{motion_sensor} : \text{Unit} \rightarrow (\text{Unit} \ \& \ \Phi_{\text{motion_sensor}})} \text{ (T-VaF)}$	
$\mathbf{B}: \frac{\text{sty}(\Gamma'(\text{door_control})) \in \rightarrow}{\Gamma' \vdash \text{door_control} : \text{Unit} \rightarrow (\text{Unit} \ \& \ \Phi_{\text{door_control}})} \text{ (T-VaF)}$	
$\begin{aligned} & \underline{\text{Close}} \cdot \Phi_{\text{motion_sensor}} \cdot \underline{\text{Open}} \cdot \underline{\text{Delay}} \cdot \Phi_{\text{door_control}} \\ \mathbf{I}: & \equiv \underline{\text{Close}} \cdot (\underline{\text{Passive}}^* \cdot \underline{\text{Active}} \vee \underline{\text{Passive}}^\omega) \cdot \underline{\text{Open}} \cdot \underline{\text{Delay}} \cdot ((\underline{\text{Close}} \cdot (\underline{\text{Passive}}^* \cdot \underline{\text{Active}} \vee \underline{\text{Passive}}^\omega) \cdot \underline{\text{Open}} \cdot \underline{\text{Delay}})^\omega) \\ & \equiv (\underline{\text{Close}} \cdot (\underline{\text{Passive}}^* \cdot \underline{\text{Active}} \vee \underline{\text{Passive}}^\omega) \cdot \underline{\text{Open}} \cdot \underline{\text{Delay}})^{\omega+1} \\ & \equiv (\underline{\text{Close}} \cdot (\underline{\text{Passive}}^* \cdot \underline{\text{Active}} \vee \underline{\text{Passive}}^\omega) \cdot \underline{\text{Open}} \cdot \underline{\text{Delay}})^\omega \\ & \equiv \Phi_{\text{door_control}} \end{aligned}$	

III. TYPE CHECKING TREES FOR FUNCTION TEMPERATURE_CONTROL

<pre>device_control t = if t < 20 then ev (CloseBoth) else if 20 <= t < 30 then ev (Fan) else if 30 <= t < 40 then ev (Alternate) else if 40 <= t < 50 then ev (AC) else ev (OpenBoth);</pre>	<pre>temperature_control = device_control (get_temp ()); temperature_control;</pre>
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$$\tau_{\text{device_control}} = t : \text{Int} \rightarrow (\text{Unit} \ \& \ \Phi_{\text{device_control}})$$

$$\Phi_{\text{device_control}} = (t < 20 \wedge \underline{\text{CloseBoth}}) \vee (20 \leq t < 30 \wedge \underline{\text{Fan}}) \vee (30 \leq t < 40 \wedge \underline{\text{Alternate}}) \vee (40 \leq t < 50 \wedge \underline{\text{AC}}) \vee (50 \leq t \wedge \underline{\text{OpenBoth}})$$

$$\tau_{\text{get_temp}} = \text{Unit} \rightarrow \text{Int}$$

$$\tau_{\text{temperature_control}} = \text{Unit} \rightarrow (\text{Unit} \ \& \ \Phi_{\text{temperature_control}})$$

$$\Phi_{\text{temperature_control}} = ((t < 20 \wedge \underline{\text{CloseBoth}}) \vee (20 \leq t < 30 \wedge \underline{\text{Fan}}) \vee (30 \leq t < 40 \wedge \underline{\text{Alternate}}) \vee (40 \leq t < 50 \wedge \underline{\text{AC}}) \vee (50 \leq t \wedge \underline{\text{OpenBoth}}))^\omega$$

device_control	
$\frac{\Phi = \underline{\text{CloseBoth}}}{\Gamma' \vdash \text{ev}(\text{CloseBoth}) : \text{Unit} \ \& \ \underline{\text{CloseBoth}}} \text{ (T-Event)}$ $\frac{\Gamma' \vdash \text{ev}(\text{CloseBoth}) : \text{Unit} \ \& \ \underline{\text{CloseBoth}} \quad (\underline{\text{Fan}}) \quad (\underline{\text{Alternate}}) \quad (\underline{\text{AC}}) \quad \Gamma' \vdash \text{ev}(\text{OpenBoth}) : \text{Unit} \ \& \ \underline{\text{OpenBoth}}}{\Gamma' \vdash (\text{if } t < 20 \text{ then ev}(\text{CloseBoth}) \text{ else if ... else ev}(\text{OpenBoth});) : \text{Unit} \ \& \ (\Phi_1 \vee \Phi_2 \vee \Phi_3 \vee \Phi_4 \vee \Phi_5)} \text{ (T-If)}$ $\frac{\dots \text{ (Effects Computation I) } \dots}{\Gamma \vdash (\text{device_control } t = \text{if } \dots) : (t : \text{Int}) \rightarrow (\text{Unit} \ \& \ \Phi_{\text{device_control}})} \text{ (T-Fun)}$ <p> $\Gamma' = \Gamma, \text{ device_control} : \tau_{\text{device_control}}$ $\Phi_1 = (t < 20 \wedge \underline{\text{CloseBoth}})$ $\Phi_2 = (20 \leq t < 30 \wedge \underline{\text{Fan}})$ $\Phi_3 = (30 \leq t < 40 \wedge \underline{\text{Alternate}})$ $\Phi_4 = (40 \leq t < 50 \wedge \underline{\text{AC}})$ $\Phi_5 = (50 \leq t \wedge \underline{\text{OpenBoth}})$ </p>	$\frac{\Phi = \underline{\text{OpenBoth}}}{\Gamma' \vdash \text{ev}(\text{OpenBoth}) : \text{Unit} \ \& \ \underline{\text{OpenBoth}}} \text{ (T-Event)}$
$\begin{aligned} & \underline{\text{Close}} \cdot \Phi_{\text{motion_sensor}} \cdot \underline{\text{Open}} \cdot \underline{\text{Delay}} \cdot \Phi_{\text{door_control}} \\ \equiv & \underline{\text{Close}} \cdot (\underline{\text{Passive}}^* \cdot \underline{\text{Active}} \vee \underline{\text{Passive}}^\omega) \cdot \underline{\text{Open}} \cdot \underline{\text{Delay}} \cdot ((\underline{\text{Close}} \cdot (\underline{\text{Passive}}^* \cdot \underline{\text{Active}} \vee \underline{\text{Passive}}^\omega) \cdot \underline{\text{Open}} \cdot \underline{\text{Delay}})^\omega) \\ \text{I: } \equiv & (\underline{\text{Close}} \cdot (\underline{\text{Passive}}^* \cdot \underline{\text{Active}} \vee \underline{\text{Passive}}^\omega) \cdot \underline{\text{Open}} \cdot \underline{\text{Delay}})^{\omega+1} \\ \equiv & (\underline{\text{Close}} \cdot (\underline{\text{Passive}}^* \cdot \underline{\text{Active}} \vee \underline{\text{Passive}}^\omega) \cdot \underline{\text{Open}} \cdot \underline{\text{Delay}})^\omega \\ \equiv & \Phi_{\text{door_control}} \end{aligned}$	
temperature_control	
$\frac{\text{sty}(\Gamma'(\text{temperature_control})) \in \rightarrow}{\text{A} \quad \Gamma' \vdash \text{temperature_control} : \text{Unit} \rightarrow (\text{Unit} \ \& \ \Phi_{\text{temperature_control}})} \text{ (T-VaF)}$ $\frac{\Gamma' \vdash \text{temperature_control} : \text{Unit} \rightarrow (\text{Unit} \ \& \ \Phi_{\text{temperature_control}})}{\Gamma' \vdash (\text{device_control } \text{get_temp}; \text{temperature_control};) : \text{Unit} \ \& \ (\Phi_{\text{device_control}} \cdot \Phi_{\text{temperature_control}})} \text{ (T-Let)}$ $\frac{\dots \text{ (Effects Computation II) } \dots}{\Gamma \vdash (\text{temperature_control} = \dots) : \text{Unit} \rightarrow (\text{Unit} \ \& \ \Phi_{\text{temperature_control}})} \text{ (T-Fun)}$ <p> $\Gamma' = \Gamma, \text{ temperature_control} : \tau_{\text{temperature_control}}$ </p>	
$\text{A: } \frac{\text{sty}(\Gamma'(\text{device_control})) \in \rightarrow}{\Gamma' \vdash \text{device_control} : (t : \text{Int}) \rightarrow (\text{Unit} \ \& \ \Phi_{\text{device_control}})} \text{ (T-VaF)} \quad \frac{\text{sty}(\Gamma'(\text{get_temp})) \in \rightarrow}{\Gamma' \vdash \text{get_temp} : \text{Unit} \rightarrow \text{Int}} \text{ (T-VaF)} \quad \frac{\Gamma' \vdash () : \text{Unit}}{\Gamma' \vdash \text{get_temp} () : \text{Int}} \text{ (T-App)}$ $\frac{\Gamma' \vdash \text{device_control} : (t : \text{Int}) \rightarrow (\text{Unit} \ \& \ \Phi_{\text{device_control}}) \quad \Gamma' \vdash \text{get_temp} () : \text{Int}}{\Gamma' \vdash \text{device_control } (\text{get_temp} ()) : \text{Unit} \ \& \ (\Phi_{\text{device_control}})} \text{ (T-App)}$	
$\begin{aligned} & (\Phi_{\text{device_control}} \cdot \Phi_{\text{temperature_control}}) \\ \equiv & ((t < 20 \wedge \underline{\text{CloseBoth}}) \vee (20 \leq t < 30 \wedge \underline{\text{Fan}}) \vee (30 \leq t < 40 \wedge \underline{\text{Alternate}}) \vee (40 \leq t < 50 \wedge \underline{\text{AC}}) \vee (50 \leq t \wedge \underline{\text{OpenBoth}})) \\ & \cdot ((t < 20 \wedge \underline{\text{CloseBoth}}) \vee (20 \leq t < 30 \wedge \underline{\text{Fan}}) \vee (30 \leq t < 40 \wedge \underline{\text{Alternate}}) \vee (40 \leq t < 50 \wedge \underline{\text{AC}}) \vee (50 \leq t \wedge \underline{\text{OpenBoth}}))^\omega \\ \text{II: } \equiv & ((t < 20 \wedge \underline{\text{CloseBoth}}) \vee (20 \leq t < 30 \wedge \underline{\text{Fan}}) \vee (30 \leq t < 40 \wedge \underline{\text{Alternate}}) \vee (40 \leq t < 50 \wedge \underline{\text{AC}}) \vee (50 \leq t \wedge \underline{\text{OpenBoth}}))^{\omega+1} \\ \equiv & ((t < 20 \wedge \underline{\text{CloseBoth}}) \vee (20 \leq t < 30 \wedge \underline{\text{Fan}}) \vee (30 \leq t < 40 \wedge \underline{\text{Alternate}}) \vee (40 \leq t < 50 \wedge \underline{\text{AC}}) \vee (50 \leq t \wedge \underline{\text{OpenBoth}}))^\omega \\ \equiv & \Phi_{\text{temperature_control}} \end{aligned}$	

IV. TYPE CHECKING TREES FOR FUNCTION SURVEILLANCE

```

camera_on = ev (10Mins)
permission t f =
  if * then return ev (Legal)
  else if t == 0 then camera_on ()
  else
    ev (Tick);
    permission (f t) f

```

```

surveillance t =
  motion_sensor;
  permission t (\x -> x - 1);
  ev (CameraOff);
  surveillance t;

```

$\tau_{\text{camera_on}} = \text{Unit} \rightarrow (\text{Unit} \ \& \ \underline{\text{10Mins}})$
 $\tau_{\text{permission}} = t : \text{Int} \rightarrow f : (x : \text{Int} \rightarrow \{u : \text{Int} \mid u = x - 1\}) \rightarrow (\text{Unit} \ \& \ \Phi_{\text{permission}})$
 $\Phi_{\text{permission}} = (\underline{\text{Legal}} \vee ((t < 0 \wedge \underline{\text{Tick}}^\omega) \vee (t \geq 0 \wedge \underline{\text{Tick}}^t \cdot \underline{\text{10Mins}})))$
 $\tau_{\text{surveillance}} = t : \text{Int} \rightarrow (\text{Unit} \ \& \ \Phi_{\text{surveillance}})$
 $\Phi_{\text{surveillance}} = ((\underline{\text{Passive}}^* \cdot \underline{\text{Active}} \vee \underline{\text{Passive}}^\omega) \cdot (\underline{\text{Legal}} \vee ((t < 0 \wedge \underline{\text{Tick}}^\omega) \vee (t \geq 0 \wedge \underline{\text{Tick}}^t \cdot \underline{\text{10Mins}})))) \cdot \underline{\text{CameraOff}})^\omega$

permission	
$\frac{\frac{\Phi = \underline{\text{Legal}}}{\Gamma' \vdash \text{ev}(\text{Legal}) : \text{Unit} \ \& \ \underline{\text{Legal}}} \text{ (T-Event)} \quad \frac{\frac{\text{sty}(\Gamma'(\text{camera_on})) \in \rightarrow}{\Gamma' \vdash \text{camera_on} : \text{Unit} \rightarrow (\text{Unit} \ \& \ \underline{\text{10Mins}})} \text{ (T-VaF)} \quad \frac{\Gamma' \vdash () : \text{Unit}}{\Gamma' \vdash \text{camera_on} () : (\text{Unit} \ \& \ \underline{\text{10Mins}})} \text{ (T-App)} \quad \mathbf{A}}{\Gamma' \vdash (\text{if } * \text{ then return ev}(\text{Legal}) \text{ else if } t == 0 \text{ then camera_on} () \text{ else ev}(\text{Tick}); \text{permission}(\text{f } t) \text{ f};) : \text{Unit} \ \& \ (\Phi_1 \vee (\Phi_2 \vee \Phi_3))} \text{ (T-If)}$ $\frac{\dots \text{ (Effects Computation I) } \dots}{\Gamma \vdash (\text{permission } t \text{ f} = \text{if } \dots) : t : \text{Int} \rightarrow f : (x : \text{Int} \rightarrow \{u : \text{Int} \mid u = x - 1\}) \rightarrow (\text{Unit} \ \& \ \Phi_{\text{permission}})} \text{ (T-Fun)}$ <p> $\Gamma' = \Gamma, \text{ permission} : \tau_{\text{permission}}, t : \text{Int}, f : (x : \text{Int} \rightarrow \{u : \text{Int} \mid u = x - 1\})$ $\Phi_1 = \underline{\text{Legal}}$ $\Phi_2 = t == 0 \wedge \underline{\text{10Mins}}$ $\Phi_3 = t \neq 0 \wedge (\underline{\text{Legal}} \vee \underline{\text{Tick}} \cdot ((t \geq 1 \wedge \underline{\text{Tick}}^{t-1} \cdot \underline{\text{10Mins}}) \vee (t < 1 \wedge \underline{\text{Tick}}^\omega)))$ </p>	
A:	$\frac{\frac{\Phi = \underline{\text{Tick}}}{\Gamma' \vdash \text{ev}(\text{Tick}) : \text{Unit} \ \& \ \underline{\text{Tick}}} \text{ (T-Event)} \quad \frac{\frac{\text{sty}(\Gamma'(\text{permission})) \in \rightarrow}{\Gamma' \vdash \text{permission} : \tau_{\text{permission}}} \text{ (T-VaF)} \quad \frac{\mathbf{B} \quad \mathbf{C}}{\Gamma' \vdash \text{permission}(\text{f } t) \text{ f} : \text{Unit} \ \& \ \Phi_{\text{permission}}^{t-1}} \text{ (T-App)}}{\Gamma' \vdash (\text{ev}(\text{Tick}); \text{permission}(\text{f } t) \text{ f};) : \text{Unit} \ \& \ (\underline{\text{Tick}} \cdot \Phi_{\text{permission}}^{t-1})} \text{ (T-Let)}$ <p> $\Phi_{\text{permission}}^{t-1} = \underline{\text{Legal}} \vee (t \geq 1 \wedge \underline{\text{Tick}}^{t-1} \cdot \underline{\text{10Mins}}) \vee (t < 1 \wedge \underline{\text{Tick}}^\omega)$ </p>
B:	$\frac{\frac{\text{sty}(\Gamma'(f)) \in \rightarrow}{\Gamma' \vdash f : (x : \text{Int} \rightarrow \{u : \text{Int} \mid u = x - 1\}) \rightarrow \text{Int}} \text{ (T-VaF)} \quad \Gamma' \vdash t : \text{Int}}{\Gamma' \vdash f \ t : \{u : \text{Int} \mid u = t - 1\}} \text{ (T-App)}$
C:	$\frac{\text{sty}(\Gamma'(f)) \in \rightarrow}{\Gamma' \vdash f : (x : \text{Int} \rightarrow \{u : \text{Int} \mid u = x - 1\}) \rightarrow \text{Int}} \text{ (T-VaF)}$
I:	$\begin{aligned} & (\Phi_1 \vee (\Phi_2 \vee \Phi_3)) \\ \equiv & \underline{\text{Legal}} \vee (t == 0 \wedge \underline{\text{10Mins}}) \vee (t \neq 0 \wedge (\underline{\text{Legal}} \vee \underline{\text{Tick}} \cdot ((t \geq 1 \wedge \underline{\text{Tick}}^{t-1} \cdot \underline{\text{10Mins}}) \vee (t < 1 \wedge \underline{\text{Tick}}^\omega)))) \\ \equiv & (\underline{\text{Legal}} \vee ((t < 0 \wedge \underline{\text{Tick}}^\omega) \vee (t \geq 0 \wedge \underline{\text{Tick}}^t \cdot \underline{\text{10Mins}}))) \\ \equiv & \Phi_{\text{permission}} \end{aligned}$