

# Friot: A Functional Reactive Language for IoT Programs with Dependent Type-and-Effect System (Report)

(anonymous authors)

## I. TYPE CHECKING TREES FOR FUNCTION DELAY

Table I

delay	
$\frac{\Phi = \text{LightUp}}{\Gamma' \vdash \text{ev}(\text{LightUp}) : \text{Unit} \ \& \ \text{LightUp}} \text{ (T-Event)} \quad \frac{\frac{\Phi = \text{Tick}}{\Gamma' \vdash \text{ev}(\text{Tick}) : \text{Unit} \ \& \ \text{Tick}} \text{ (T-Event)} \quad \mathbf{A}}{\Gamma' \vdash (\text{ev}(\text{Tick}); \text{delay}(t-1)) : \text{Unit} \ \& \ (\text{Tick} \cdot \Phi_{\text{delay}}^{(t-1)})} \text{ (T-Let)}$	
$\Gamma' \vdash (\text{if } t == 0 \text{ then ev}(\text{LightUp}) \text{ else ev}(\text{Tick}); \text{delay}(t-1)) : \text{Unit} \ \& \ (t == 0 \wedge \text{LightUp}) \vee (t \neq 0 \wedge \text{Tick} \cdot \Phi_{\text{delay}}^{(t-1)}) \text{ (T-If)}$	
$\dots \text{ (Effects Computation I) } \dots$	
$\Gamma \vdash (\text{delay } t = \text{if } \dots \text{ then } \dots \text{ else } \dots) : (t : \text{Int}) \rightarrow (\text{Unit} \ \& \ (t \geq 0 \wedge \text{Tick}^t \cdot \text{LightUp}) \vee (t < 0 \wedge \text{Tick}^\omega)) \text{ (T-Fun)}$	
$\Gamma' = \Gamma, \text{ delay} : \tau_{\text{delay}}$	
$\Phi_{\text{delay}}^{(t-1)} = (t \geq 1 \wedge \text{Tick}^{t-1} \cdot \text{LightUp}) \vee (t < 1 \wedge \text{Tick}^\omega)$	
$\mathbf{A:} \quad \frac{\text{sty}(\Gamma'(\text{delay})) \in \rightarrow}{\Gamma' \vdash \text{delay} : (t : \text{Int}) \rightarrow (\text{Unit} \ \& \ (t \geq 0 \wedge \text{Tick}^t \cdot \text{LightUp}) \vee (t < 0 \wedge \text{Tick}^\omega))} \text{ (T-VaF)} \quad \frac{\text{sty}(\Gamma'(t)) = \text{Int}}{\Gamma' \vdash (t-1) : \text{int}} \text{ (T-Var, T-Op)}$	
$\Gamma' \vdash \text{delay}(t-1) : (t-1 : \text{int}) \rightarrow (\text{Unit} \ \& \ (t \geq 1 \wedge \text{Tick}^{t-1} \cdot \text{LightUp}) \vee (t < 1 \wedge \text{Tick}^\omega)) \text{ (T-App, S-Base)}$	
$\begin{aligned} & (t == 0 \wedge \text{LightUp}) \vee (t \neq 0 \wedge \text{Tick} \cdot \Phi_{\text{delay}}^{(t-1)}) \\ \equiv & (t == 0 \wedge \text{LightUp}) \vee (t \neq 0 \wedge \text{Tick} \cdot ((t \geq 1 \wedge \text{Tick}^{t-1} \cdot \text{LightUp}) \vee (t < 1 \wedge \text{Tick}^\omega))) \\ \equiv & (t == 0 \wedge \text{LightUp}) \vee ((t \neq 0 \wedge t \geq 1) \wedge \text{Tick} \cdot \text{Tick}^{t-1} \cdot \text{LightUp}) \vee ((t \neq 0 \wedge t < 1) \wedge (\text{Tick} \cdot \text{Tick}^\omega)) \\ \mathbf{I:} \quad \equiv & (t == 0 \wedge \text{LightUp}) \vee (t \geq 1 \wedge \text{Tick} \cdot \text{Tick}^{t-1} \cdot \text{LightUp}) \vee (t < 0 \wedge (\text{Tick} \cdot \text{Tick}^\omega)) \\ \equiv & (t == 0 \wedge \text{LightUp}) \vee (t \geq 1 \wedge \text{Tick}^t \cdot \text{LightUp}) \vee (t < 0 \wedge \text{Tick}^\omega) \\ \equiv & (t \geq 0 \wedge \text{Tick}^t \cdot \text{LightUp}) \vee (t < 0 \wedge \text{Tick}^\omega) \\ \equiv & \Phi_{\text{delay}} \end{aligned}$	

$\frac{c \in B}{\Gamma \vdash c : (\{u : B \mid u = c\})} \text{ (T-Const)}$	$\frac{\text{sty}(\Gamma(x)) = B}{\Gamma \vdash x : (\{u : B \mid u = x\})} \text{ (T-Var)}$	$\frac{\text{sty}(\Gamma(x)) \in \rightarrow}{\Gamma \vdash x : (\Gamma(x))} \text{ (T-VaF)}$	$\frac{\Phi = \mathbf{a}}{\Gamma \vdash \text{ev}(\mathbf{a}) : (\text{Unit} \ \& \ \Phi)} \text{ (T-Event)}$
$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2 \quad \Gamma(\oplus) \vdash x_1 : \tau_1 \rightarrow x_2 : \tau_2 \rightarrow \tau_3}{\Gamma \vdash e_1 \oplus e_2 : \tau_3[e_1/x_1][e_2/x_2]} \text{ (T-Op)}$	$\frac{\Gamma \vdash e : x_1 : \tau_1 \rightarrow \tau \ \& \ \Phi \quad \Gamma \vdash e_1 : \tau_1 \ \& \ \Phi_1}{\Gamma \vdash e \ e_1 : \tau[e_1/x_1] \ \& \ \Phi_1 \cdot \Phi} \text{ (T-App)}$	$\frac{\Gamma \vdash (F \ \bar{x} = e) : \tau_F \ \& \ \Phi_F}{\Gamma \vdash (F \ \bar{x} = e) : \tau_F \ \& \ \Phi_F} \text{ (T-Fun)}$	$\frac{\Gamma \vdash e_1 : \tau_1 \ \& \ \Phi_1 \quad \Gamma, x : \tau_1 \vdash e_2 : \tau_2 \ \& \ \Phi_2}{\Gamma \vdash \text{let } (e_1; x.e_2) : \tau_2 \ \& \ \Phi_1 \cdot \Phi_2} \text{ (T-Let)}$
$\frac{\Gamma, p : \tau_p \vdash e : (\tau \ \& \ \Phi)}{\Gamma \vdash \lambda p.e : (p : \tau_p) \rightarrow \tau} \text{ (T-Lam)}$	$\frac{\Gamma \vdash e : \tau_e \quad \Gamma, \text{ty}(D_i) = \bar{p}_j : \bar{\tau}_j \rightarrow \tau_e, x : \tau_e \vdash e_i : \tau \ \& \ \Phi_i}{\Gamma \vdash \text{case } x = e \text{ of } \{D_i \bar{p}_j \rightarrow e_i\} : \tau \ \& \ (\bigvee_{i \in I} \Phi_i)} \text{ (T-Case)}$	$\frac{\Gamma \vdash \text{if } (e; e_1; e_2) : \tau \ \& \ \Phi_1 \vee \Phi_2}{\Gamma \vdash \text{if } (e; e_1; e_2) : \tau \ \& \ \Phi_1 \vee \Phi_2} \text{ (T-If)}$	$\frac{\Gamma \vdash \tau_2 <: \tau_1 \quad \Gamma, x : \tau_2 \vdash \sigma_1 <: \sigma_2}{\Gamma \vdash (x : \tau_1) \rightarrow \sigma_1 <: (x : \tau_2) \rightarrow \sigma_2} \text{ (S-Fun)}$
$\frac{T \in B \quad \models \Gamma \vdash \pi_1 \Rightarrow \pi_2}{\Gamma \vdash \{u : T \mid \pi_1\} <: \{u : T \mid \pi_2\}} \text{ (S-Base)}$	$\frac{\Gamma \vdash \tau_1 <: \tau_2 \quad \Phi_1 \preceq \Phi_2}{\Gamma \vdash (\tau_1 \ \& \ \Phi_1) <: (\tau_2 \ \& \ \Phi_2)} \text{ (S-Qual)}$		

Figure 1. Type Judgements.

$$\begin{array}{c}
\frac{S = \{ \}}{\vdash \{ \Delta \} \text{ c } \{ S \}} (\text{FV-Const}) \quad \frac{\text{sty}(\Gamma(x)) = B}{\Gamma \vdash x : (\{ u : B \mid u = x \})} (\text{T-Var}) \quad \frac{\text{sty}(\Gamma(x)) \in \rightarrow}{\Gamma \vdash x : (\Gamma(x))} (\text{T-VaF}) \quad \frac{\Phi = \mathbf{a}}{\Gamma \vdash \text{ev}(\mathbf{a}) : (\text{Unit} \ \& \ \Phi)} (\text{T-Event}) \\
\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2 \quad \Gamma(\oplus) \vdash x_1 : \tau_1 \rightarrow x_2 : \tau_2 \rightarrow \tau_3}{\Gamma \vdash e_1 \oplus e_2 : \tau_3[e_1/x_1][e_2/x_2]} (\text{T-Op}) \quad \frac{\tau_F = (\bar{x} : \bar{\tau}) \rightarrow (\tau \ \& \ \Phi_F) \quad \Gamma, F : \tau_F, \bar{x} : \bar{\tau} \vdash e : \tau \ \& \ \Phi_F}{\Gamma \vdash (F \ \bar{x} = e) : \tau_F \ \& \ \Phi_F} (\text{T-Fun}) \\
\frac{\Gamma, p : \tau_p \vdash e : (\tau \ \& \ \Phi)}{\Gamma \vdash \lambda p. e : (p : \tau_p) \rightarrow \tau} (\text{T-Lam}) \quad \frac{\Gamma \vdash e : x_1 : \tau_1 \rightarrow \tau \ \& \ \Phi \quad \Gamma \vdash e_1 : \tau_1 \ \& \ \Phi_1}{\Gamma \vdash e \ e_1 : \tau[e_1/x_1] \ \& \ \Phi_1 \cdot \Phi} (\text{T-App}) \quad \frac{\Gamma \vdash e_1 : \tau_1 \ \& \ \Phi_1 \quad \Gamma, x : \tau_1 \vdash e_2 : \tau_2 \ \& \ \Phi_2}{\Gamma \vdash \mathbf{let} (e_1; x. e_2) : \tau_2 \ \& \ \Phi_1 \cdot \Phi_2} (\text{T-Let}) \\
\frac{\Gamma, e \Downarrow \mathbf{true} \vdash e_1 : \tau \ \& \ \Phi_1 \quad \Gamma, e \Downarrow \mathbf{false} \vdash e_2 : \tau \ \& \ \Phi_2}{\Gamma \vdash \mathbf{if} (e; e_1; e_2) : \tau \ \& \ \Phi_1 \vee \Phi_2} (\text{T-If}) \quad \frac{\Gamma \vdash e : \tau_e \quad \Gamma, \text{ty}(D_i) = \overline{p_j} : \overline{\tau_j} \rightarrow \tau_e, x : \tau_e \vdash e_i : \tau \ \& \ \Phi_i}{\Gamma \vdash \mathbf{case} x = e \text{ of } \{ D_i \ \overline{p_j} \rightarrow e_i \} : \tau \ \& \ (\bigvee_{i \in I} \Phi_i)} (\text{T-Case}) \\
\frac{T \in B \quad \models \Gamma \vdash \pi_1 \Rightarrow \pi_2}{\Gamma \vdash \{ u : T \mid \pi_1 \} <: \{ u : T \mid \pi_2 \}} (\text{S-Base}) \quad \frac{\Gamma \vdash \tau_2 <: \tau_1 \quad \Gamma, x : \tau_2 \vdash \sigma_1 <: \sigma_2}{\Gamma \vdash (x : \tau_1) \rightarrow \sigma_1 <: (x : \tau_2) \rightarrow \sigma_2} (\text{S-Fun}) \quad \frac{\Gamma \vdash \tau_1 <: \tau_2 \quad \Phi_1 \preceq \Phi_2}{\Gamma \vdash (\tau_1 \ \& \ \Phi_1) <: (\tau_2 \ \& \ \Phi_2)} (\text{S-Qual})
\end{array}$$

Figure 2. Forward Verification Rules with Non-Determinism