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Course Name – Neural Networks and Deep Learning

Course Number – CSC 578

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Rank – 10 [246.29115] (Public Score)

Final Class Project (A) Time Series Kaggle

Introduction:

- I created a Baseline Model and also five other models in order to see which one does better in performance. I was able to achieve a better result with the Model 4 (Kaggle Best Model) which will be explained below as we go. So, the other Models were executed and produced results were good and bad at the same time.
- Before conducting the experiments in these models, firstly, I loaded the data and the
 preprocessing steps were done that includes the Data Cleaning, Data Transformation, and
 Feature Extraction.
- Second step, was to use the method **Data Windowing** as from the **Tensor Flow Tutorial**, this was an important task for the **time-series forecasting**. This **Window Generator class** helps to convert the data into a usable format from which the model might be able to learn from the last 12 hours in order to predict the future data.
- Splitting the Data was done as the next process, it was split into three parts, namely **training**, **validation**, and **testing**. Next, I created **dictionaries** in order to store the performance of the model on the **validation** and **testing** datasets.
- According to the instructions, I created a Window Generator class with the respective parameters as the input width 12, offset 3, and label width 1. Using the Tensor Flow Tutorial, I was able to create a function that compiles and fits the model and uses the MSE as the loss function and the Adam Optimizer in it.
- An important note is that I did not shuffle the data before or after the train/test splitting.
 So, the next process would be to construct the Baseline Model and the other models in order to see the performance in them.

Models and Development:

BASELINE MODEL

Model – 1:

Architecture: -

Here, in this baseline model I trained a LSTM-based model that has 2 LSTM layers,
 2 dropout layers, and 3 dense layers. In order to avoid the overfitting in the model I also included the dropout layers on regularizing the model.

Model: "sequential"		
Layer (type)	Output Shape	Param #
lstm (LSTM)	(None, 12, 128)	78336
dropout (Dropout)	(None, 12, 128)	0
lstm_1 (LSTM)	(None, 12, 128)	131584
dropout_1 (Dropout)	(None, 12, 128)	0
dense (Dense)	(None, 12, 64)	8256
dense_1 (Dense)	(None, 12, 32)	2080
dense_2 (Dense)	(None, 12, 1)	
reshape (Reshape)	(None, 1, 12)	0
		========
Total params: 220,289		
Trainable params: 220,289		
Non-trainable params: 0		

Expectation: -

- From the **epoch**, we can see that the model is learning pretty well with each of the epoch, where the **loss** and **mean absolute error** is getting **reduced** on the **training** and **validation**. This will lead to a **better accuracy** of the model.
- Furthermore, from the epoch, the performance on the validation seems to be
 irregular, like we can see there is a small improvement in the mean absolute error
 and loss that tells about the overfitting present in it.

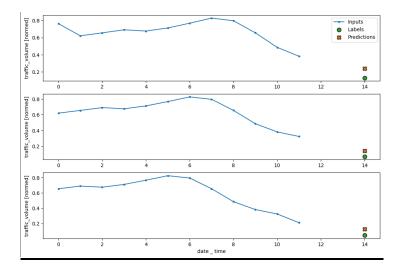
Result: -

- In order to further improve the performance of the model and reduce the loss, we are moving onto the other models that helps in improving the performance.
- Among the other models, this model's performance was good with the performance and the value on both the **loss** and **mean** absolute error.

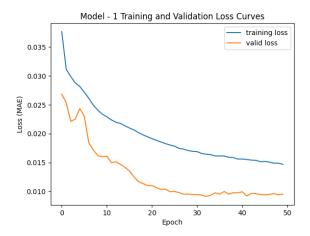
Epoch (50/50):

```
Epoch 50/50
955/955 [=============] - 12s 13ms/step - loss: 0.0147 - mean_absolute_error: 0.0781 - val_loss: 0.0095 - val_mean_absolute_error: 0.0681
156/156 [=============] - 1s 4ms/step - loss: 0.0095 - mean_absolute_error: 0.0681
```

Window Plot:



Loss Plot:



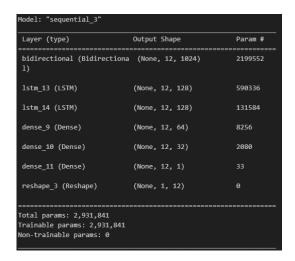
BEST MODEL

<u>Model – 4: Bidirectional RNNs:</u> [Kaggle-Best Model]

• Among all the models that I have experimented, the **loss value** in this **Model -4** seems to be **decreasing** very good consistently which indicates that the model is trained well.

Architecture:-

o This Model – 4 uses **one Bidirectional LSTM model** with **512 units and 2 LSTM layers** of **128 units**, **2 additional LSTM layers** with **128 units** on each of the layer and then **2 dense layers** that consists of **64** and **32** units respectively. The **output layer** consists of a **1** unit **dense layer**.



Expectation:-

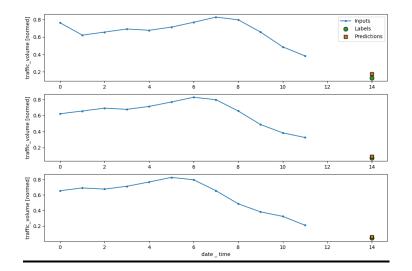
- From the below epochs of 50, we can conclude that the loss on the training seems to be reduced increasingly well and the validation loss is also reduced by the number of epochs that indicates that the model is not overfitting.
- The MAE (Mean Absolute Error) is also getting reduced overtime by the number of epochs, since MAE tells how the model's prediction are on average. I trained the LSTM on the sequence data, and the bidirectional RNNs here is capable of allowing the past and future data in the sequence to be added.

Result:-

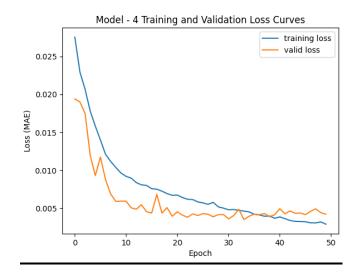
With this model, I was able to achieve a significant result among the Kaggle
 [246.29115] and this was the Best Model in comparison with the other models
 because of the LSTM Bidirectional LSTM layer.

Epoch (50/50):

Window Plot:



Loss Plot:

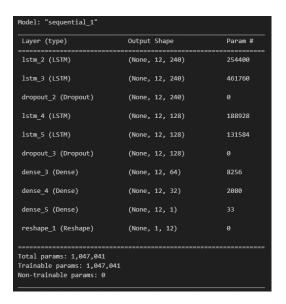


WORST MODEL

Model - 2: Adding Layers

Architecture:-

• Due to the addition of 2 LSTM layers with 128 units each may have been not good as it's contributing to the model's worst performance. This model consists of 2 dense layers with 64 and 32 neurons and the last dense having one unit respectively with 2 dropout layers in the model.



Expectation:-

- The training and validation loss was way worse in comparison to the other models that I
 experimented, within each of the epochs I could see the model performing worst.
- This could be due to the **overfitting** of the model, since there are **additional layers** present in the model that could make the model to fit too closely to the training data, which in term causes the performance to be worse.
- Also, the use of **dropouts** which prevents the overfitting by setting a **fraction rate** of units randomly for each training time. These may lead to overfitting of the model if not performing better.

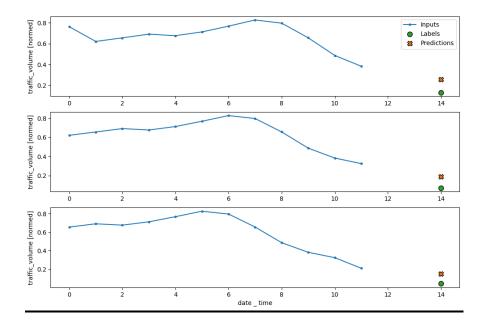
Result:-

 With the additional layers the model performed the worst among the others, and also the performance was not that good.

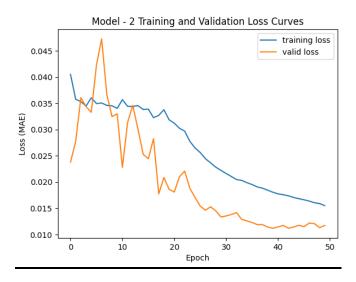
Epochs (50/50):

```
Epoch 50/50
955/955 [=============] - 51s 53ms/step - loss: 0.0155 - mean_absolute_error: 0.0809 - val_loss: 0.0117 - val_mean_absolute_error: 0.0779
156/156 [============] - 2s 11ms/step - loss: 0.0117 - mean_absolute_error: 0.0779
```

Window Plot:



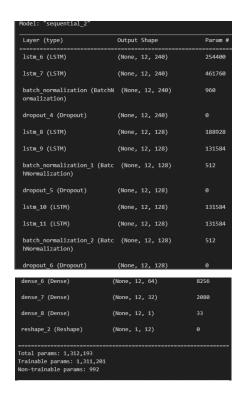
Loss Plot:



<u>Model – 3: Batch Normalization</u>

Architecture:-

• This model consists of one **LSTM layer** with 240 units and 2 additional **LSTM layers** with, 128 units of respectively. Also, 3 **BatchNormalization layers**, and 3 dropout layers. This model also uses an additional of 3 dense layers with the neurons of 64 and 32 respectively with the last dense layer with one unit.



Expectation:-

- With the end of the epochs 50/50 we can see that the loss and mean absolute error was 0.0157 and 0.0748 on the validation data which explains that the model is learning well and is performing well after the end of epoch.
- I thought the model would **accurately** run the **training** and predicts the **target variable**, and as we know the model's accuracy improves when the there is a **decrease** in the **loss**.

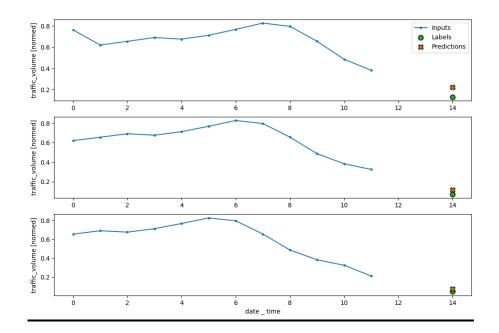
Results:-

This model performed well in comparison to the other models but not as good as the Model –
 4 that was the best model. Because of the additional LSTM layers, and the batch normalization, the model was able to perform better.

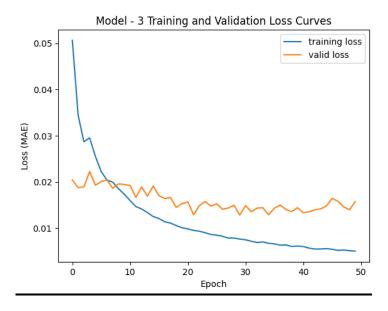
Epochs (50/50):

```
Epoch 50/50
955/955 [==============] - 60s 63ms/step - loss: 0.0050 - mean_absolute_error: 0.0450 - val_loss: 0.0157 - val_mean_absolute_error: 0.0748
156/156 [==============] - 2s 13ms/step - loss: 0.0157 - mean_absolute_error: 0.0748
```

Window Plot:



Loss Plot:



Reaction and Reflection on the results and competition:

• This is the second time I'm joining a kaggle competition. It was challenging and enjoyable at the same time, watching many of my classmates competing each other for a better score. I was able to bring up a good score with my model, but the hardest part was to experiment with different hyperparameters and try to achieve a better score with everyone among the leaderboard was the hardest. My previous scores and the ranking motivated me to bring up with different models and get a better score every time I submit my predictions.

Reaction and Reflection on the project and course:

• With this advanced course, I was able to learn more in-depth about the neural networks, deep learning and with various assignments and quiz I was able to learn more methods in python and also the tensorflow. This is my second advanced course, and with every assignment the difficulty was increasing, overall the course was very challenging since it involved new techniques that I have not implemented and tried to learn it from the beginning and getting the results were challenging.