# JIHYO PARK

West Lafayette, IN 47906 | 201-989-4209 | park1384@purdue.edu https://www.linkedin.com/in/jihyoparkk/|github.com/jihyopark02

#### **EDUCATION**

Purdue University - West Lafayette, IN

August 2021 - May 2025

• Bachelor of Science in Computer Engineering | Concentration in AI/ML (GPA: 3.53/4.0)

## **TECHNICAL SKILLS**

Languages: Python (PyTorch, TensorFlow, NumPy, Pandas, Keras, Scikit-learn, Seaborn), SQL, C, C++, Java

Tools: Git, GDB, Visual Studio Code, PyCharm, Jupyter Notebook, SAS

Skills: Deep Learning, Reinforcement Learning, Computer Vision, Natural Language Processing, Data Structures and Algorithms

# WORK EXPERIENCE

## AI/ML Team Leader | Purdue University

Aug 2024 - Present

Vertically Integrated Projects - Team ORSOL X SAS Institute

- Acting as the point of contact for the Forecasting AI/ML Team, overseeing the planning, development, and implementation of projects and strategies.
- Enhanced the previous forecasting model by 15% for EV charging demand, incorporating CNN1D, RNN, and Temporal Fusion Transformer, utilizing I210 Corridor traffic flow data.
- Leading a team of three ML students, fostering strong decision-making and strategic planning skills, and providing extensive leadership in the
  implementation of complex ML strategies.

# AI Research Intern | Purdue University

May 2024 - July 2024

Summer Undergraduate Research Fellowship - Collaborative Robotics Lab X Kaur Lab

- Conducted research in agricultural engineering within robotics, focusing on anomaly detection and leveraging robotics data science lifecycle
  methodologies with a team of 10.
- Designed and improved 8 detection devices and data collection tools, enhancing the robotic mechanisms' efficiency.
- Implemented Spiking Neural Networks and Central Pattern Generators to boost sensory processing, energy efficiency, and motor control.

#### **Undergraduate AI Researcher | Purdue University**

Feb 2024 - Present

Collaborative Robotics Lab X Kaur Lab - PI: Richard Voyles, Upinder Kaur

- Contributing as co-author to the "Subterranean Robot" project by taking the responsibility of data analysis and building the 3D reconstruction model using **ORB\_SLAM3**.
- · Enhanced the accuracy of circle detection model for feature extraction by 20% utilizing Adaptive Gaussian Threshold and CLAHE.
- Improved detection performance by applying custom preprocessing techniques and leveraging the YOLOv5 framework for real-time object detection.

# **PROJECTS**

# **OneFormer Reimplementation**

Oct 2024 - Present

- Reimplemented OneFormer to unify image segmentation tasks (semantic, instance, panoptic) into a single transformer-based model using PvTorch.
- Improving accuracy across ADE20k and Cityscapes datasets, focusing on optimizing task-conditioned joint training and query-text contrastive loss
- Gained experiences with image segmentation and computer vision techniques by implementing and optimizing transformer-based models for real-world datasets.

# **Sokoban with Reinforcement Learning**

Sep 2024 - Present

- Implementing reinforcement learning algorithms (Monte Carlo, Temporal Difference, DQN) in Sokoban, optimizing for puzzle completion
  rates and minimizing actions taken.
- Comparing RL-based performance against traditional algorithms (DFS/BFS), assessing efficiency and computational complexity.

#### **Sentiment Analysis Model**

Mar 2024 - Apr 2024

- Developed and implemented a sentiment analysis model using **TensorFlow** to classify text data into positive, negative, and neutral sentiments, leveraging **CNN**.
- Achieved 94% accuracy on a dataset containing thousands of text samples, improving sentiment classification through advanced preprocessing, tokenization, and feature engineering.
- · Gained in-depth knowledge of natural language processing techniques, and understanding of text analysis, tokenization, and model optimization.

#### AWARDS

SAS Institute: 1x Hackathon Winner