

1) cam file generation

Camera:

Ox:

Oy:

Oz:

Bx:

By:

Bz:

f:

Generate cam file

2) image segmentation

threshold:

x min size:

x max size:

y min size:

y max size:

mass min:

mass max:

blur sigma:

median filter:

local filter:

ROI

x0, y0:

x1, y1:

Segment image

Save blobs

3) mark image points

x image:

y image:

x lab:

y lab:

z lab:

(1253, 129)

Mark point

Forget last point

Save points

4) sortgrid

Initial calibration

Show calibration

Error:

Match target file

Save cal points

Quit