trajectory number x y z vx vy vz ax ay az frame number

	x	y	z	vx	vy	vz	ax	ay	az	frame
0	53.527	31.692	-1.313	0.213	-0.504	0.050	0.001	0.001	-0.002	0.000
0	53.741	31.189	-1.264	0.214	-0.503	0.048	0.001	0.001	-0.002	1.000
0	53.956	30.686	-1.218	0.216	-0.502	0.045	0.001	0.001	-0.002	2.000
0	54.179	30.182	-1.187	0.216	-0.504	0.039	-0.010	0.003	0.015	3.000
0	54.388	29.685	-1.137	0.205	-0.504	0.048	-0.008	-0.008	0.005	4.000
0	54.588	29.175	-1.078	0.200	-0.509	0.052	-0.004	-0.003	-0.011	5.000
0	54.786	28.664	-1.032	0.194	-0.510	0.025	-0.006	0.001	-0.022	6.000
0	54.975	28.155	-1.022	0.192	-0.513	0.038	0.001	-0.004	0.012	7.000
0	55.171	27.641	-0.993	0.187	-0.512	0.052	-0.009	-0.001	0.035	8.000
0	55.353	27.127	-0.918	0.179	-0.514	0.052	-0.008	0.000	0.001	9.000
0	55.528	26.613	-0.839	0.176	-0.517	0.056	-0.005	-0.002	-0.038	10.000
0	55.699	26.098	-0.817	0.166	-0.515	0.032	-0.004	-0.003	-0.004	11.000
0	55.865	25.578	-0.797	0.165	-0.519	0.028	-0.005	0.001	0.011	12.000
0	56.026	25.060	-0.768	0.163	-0.517	0.063	-0.000	0.002	0.036	13.000
0	56.187	24.548	-0.678	0.160	-0.519	0.050	0.001	-0.006	-0.015	14.000
0	56.355	24.023	-0.634	0.152	-0.519	0.071	-0.017	0.003	0.010	15.000
0	56.495	23.505	-0.552	0.147	-0.516	0.061	-0.003	0.004	-0.015	16.000
0	56.638	22.989	-0.516	0.141	-0.514	0.047	-0.001	0.005	0.013	17.000
0	56.777	22.484	-0.439	0.138	-0.513	0.072	-0.000	-0.007	-0.014	18.000
0	56.921	21.966	-0.400	0.138	-0.518	0.052	-0.009	-0.003	0.021	19.000

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	x	y	z	vx	vy	vz	ax	ay	az	frame
101	11.187	54.710	-19.521	0.000	0.000	0.000	0.000	0.000	0.000	29.000
101	11.459	55.239	-19.118	0.000	0.000	0.000	0.000	0.000	0.000	30.000
102	7.828	46.884	-15.127	0.000	0.000	0.000	0.000	0.000	0.000	29.000
102	8.066	47.124	-15.184	0.000	0.000	0.000	0.000	0.000	0.000	30.000
103	52.867	51.209	16.306	0.000	0.000	0.000	0.000	0.000	0.000	29.000
103	53.109	51.084	16.461	0.000	0.000	0.000	0.000	0.000	0.000	30.000
-1	30.108	6.373	-15.330	0.000	0.000	0.000	0.000	0.000	0.000	0.000
-1	16.940	60.808	12.587	0.000	0.000	0.000	0.000	0.000	0.000	0.000
-1	45.245	57.933	-2.268	0.000	0.000	0.000	0.000	0.000	0.000	0.000
-1	4.736	45.102	-23.748	0.000	0.000	0.000	0.000	0.000	0.000	0.000

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The zero velocity and acceleration columns are due to too short trajectories and unlinked samples.