

## Objectives:

- \* Linear transformations.

$$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

A function from  $\mathbb{R}^n$  to  $\mathbb{R}^m$  for which the output depends linearly on the input.

Eg. Cost of an object

$$P: \mathbb{R} \rightarrow \mathbb{R}$$

$$q \mapsto P(q)$$

$$1\text{ kg} \mapsto 100\text{ ₹}$$

$$2\text{ kg} \mapsto 200\text{ ₹}$$

$$\underline{3.47\text{ kg}} \mapsto \underline{(3.47)100}$$

347.

$$P(q_0) = 100q_0$$

$$P: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$1\text{ kg of sugar} \mapsto 50$$

$$1\text{ kg of rice} \mapsto 60$$

$$P(x, y) = 50x + 60y$$

$$\begin{aligned} i) \quad & P((x_1, y_1) + (x_2, y_2)) = \\ & P(x_1, y_1) + P(x_2, y_2) \\ ii) \quad & P(c(x, y)) = cP(x, y) \end{aligned}$$

What does (2 kg of sugar and 3 kg of rice) cost? (280)

$$2(50) + 3(60)$$

In general,  $x$  of sugar and  $y$  of rice, the cost is

$$x(50) + y(60)$$

Transaction 1: Cost of 2 kg sugar, 1 kg rice is  $P_1$

Transaction 2: Cost of 1 kg sugar, 2 kg rice is  $P_2$ .

Cost of 3 kg sugar, 3 kg rice:  $P_1 + P_2$ .

- \* Using  $P_1$  and  $P_2$ , the cost of  $x$  kg sugar and  $y$  kg rice can be calculated (for any  $x, y$ ).

Eg. 3 kg sugar, 2 kg rice.

Sugar	Rice
50	60

Eg. Same setup as above but delivery fee - 20.

$$\tilde{P}(x, y) = 50x + 60y + 20.$$

$$\tilde{P}(1, 1) = 130$$

$$\tilde{P}(1, 2) = 190$$

$$\tilde{P}(2, 2) = 240$$

$$\tilde{P}(1, 1) + \tilde{P}(0, 1) = 210.$$

$\tilde{P}$  is not a linear map. (This is an affine map)

(If  $P(c(x, y)) \neq c P(x, y)$  for some  $x, y \in \mathbb{R}^2$ ,  $c \in \mathbb{R}$ , then  $P$  is not a linear)

Eg.  $A: \mathbb{R} \rightarrow \mathbb{R}$ .

$A(x)$  is the area of the square with side  $|x|$ .

$$A(1) = 1 \quad A(2) = 4.$$

$$A(2) \neq 2A(1). \therefore A \text{ is not a linear map.}$$

$$A(x) = x^2.$$

Eg./Ex. Compound interest

\* A map  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  is said to be a linear map if the following two conditions hold:

a)  $T((x_1, \dots, x_n) + (y_1, \dots, y_n)) = T(x_1, \dots, x_n) + T(y_1, \dots, y_n)$ .

b)  $T(c(x_1, \dots, x_n)) = cT(x_1, \dots, x_n)$ .

$\forall (x_1, \dots, x_n), (y_1, \dots, y_n) \in \mathbb{R}^n$   
 $\& c \in \mathbb{R}$ .

Eg.  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$(x, y) \mapsto (x+y, x-y)$ .

a)  $T((x_1, y_1) + (x_2, y_2)) = T(x_1+x_2, y_1+y_2)$   
 $= (x_1+x_2+y_1+y_2, x_1+x_2-y_1-y_2)$

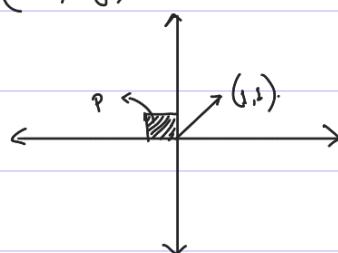
$T$  is a linear transformation.

$T(x_1, y_1) + T(x_2, y_2) = \underbrace{(x_1+y_1, x_1-y_1)} + (x_2+y_2, x_2-y_2)$   
 $= (x_1+y_1+x_2+y_2, x_1+x_2-y_1-y_2)$ .

b)  $T(c(x_1, y_1)) = T(cx_1, cy_1) = (cx_1+cy_1, cx_1-cy_1)$   
 $cT(x_1, y_1) = c(x_1+y_1, x_1-y_1) = (cx_1+cy_1, cx_1-cy_1)$ .

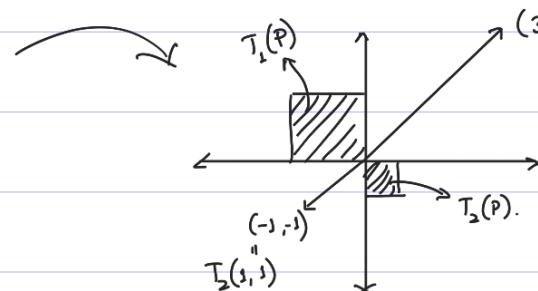
Eg.  $T_1: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$(x, y) \mapsto (3x, 3y)$ .



Domain

Ex.  $T_1$  is a linear transformation



Co-domain

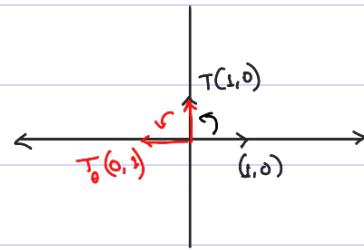
$T_2(x, y) = (-x, -y)$ .

Ex.  $T_\theta: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$(x, y) \mapsto (x \cos \theta - y \sin \theta, x \sin \theta + y \cos \theta)$$

$$(1, 0) \mapsto (\cos \theta, \sin \theta)$$

$$(0, 1) \mapsto (-\sin \theta, \cos \theta)$$



$$\theta = \frac{\pi}{2} \quad (1, 0) \mapsto (0, 1)$$

$T_\theta$  is a linear map which rotates every vector in the plane counterclockwise by  $\theta$ .

Ex.  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \quad (x, y) \mapsto (y, x)$ . Show that  $T$  is a l.m and describe it geometrically.

- \* Given vector spaces  $V$  and  $W$ , a linear transformation from  $V$  to  $W$  is a map  $T: V \rightarrow W$  such that
  - $T(v_1 + v_2) = T(v_1) + T(v_2)$   $\forall v_1, v_2, v \in V, c \in \mathbb{R}$ .
  - $T(cv) = cT(v)$

Remark: If  $T: V \rightarrow W$  is a l.t., then  $T(0_v) = 0_w$ .

$$a) T(0_v + 0_v) = T(0_v) + T(0_v)$$

$$0_w + T(0_v) = T(0_v) + T(0_v)$$

$$T(0_v) = 0_w$$

\* Injective (one-to-one) l.t.: A l.t. which is injective, i.e.,

$$T(v) = T(v') \Rightarrow v = v'$$

(No vector in  $W$  has more than one pre-image)

Result: A l.t.  $T: V \rightarrow W$  is injective if and only if

$$T(v) = 0 \Rightarrow v = 0. \quad (*)$$

$$T(v_1) = T(v_2) \Rightarrow T(v_1) - T(v_2) = 0$$

$$\Rightarrow T(v_1) + T(-v_2) = 0$$

$$\Rightarrow T(v_1 + (-v_2)) = 0.$$

$$\stackrel{(*)}{\Rightarrow} v_1 + (-v_2) = 0 \Rightarrow v_1 = v_2$$

Eg.  $T_1: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$T_1(x, y) = (x+y, x-y)$$

Solve:  $T_1(x, y) = (0, 0)$

$$(x+y, x-y) = (0, 0)$$

$$\begin{cases} x+y=0 \\ x-y=0 \end{cases} \quad (x, y) = (0, 0)$$

is the  
unique solution

$$\Rightarrow (x, y) = (0, 0)$$

$\Rightarrow T_1$  is injective

$$T_2: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$(x, y) \mapsto (x+y, 2x+2y).$$

Find  $(x, y)$  ( $\in$  Domain) s.t

$$T_2(x, y) = (0, 0).$$

$$(x+y, 2x+2y) = (0, 0)$$

$$\begin{cases} x+y=0 \\ 2x+2y=0 \end{cases}$$

Ininitely many solutions.

$$\text{In particular, } T_2(\underline{1}, \underline{-1}) = (0, 0)$$

$\Rightarrow T_2$  is not injective.

- \* Surjective l.t.: A l.t.  $T: V \rightarrow W$  s.t.  $\forall \omega \in W \exists v \in V$  s.t.  $T(v) = \omega$ .
- \* A bijective l.t. is called a linear isomorphism.
- \* A linear transformation  $T: V \rightarrow W$  is completely determined by the images of a basis of  $V$ .

Suppose  $\{v_1, \dots, v_n\}$  is a basis of  $V$  and we know  $T(v_1), \dots, T(v_n)$ .

Then,  $T(v)$  can be calculated for any  $v \in V$ .

Let  $v \in V$ .

$$v = a_1 v_1 + a_2 v_2 + \dots + a_n v_n \quad \text{for some } a_i \in \mathbb{R}.$$

$$\begin{aligned} T(v) &= T(a_1 v_1 + \dots + a_n v_n) \\ &\stackrel{(a)}{=} T(a_1 v_1) + \dots + T(a_n v_n) \\ &\stackrel{(b)}{=} a_1 T(v_1) + \dots + a_n T(v_n). \end{aligned}$$

$$\text{Eg. } P(2,1) = P_1, \quad P(1,2) = P_2.$$

$$P(3,3) = P_1 + P_2$$

Calculate the cost of 2 kg of sugar and 3 kg of rice.

Note that  $\{(2,1), (1,2)\}$  is a basis of  $\mathbb{R}^2$

$$\underline{\underline{(2,3)}} = a(2,1) + b(1,2)$$

$$2a+b=2 \quad (4a+2b=4).$$

$$a+2b=3$$

$$a = \frac{1}{3}, \quad b = \frac{4}{3}$$

$$(2, 3) = \frac{1}{3} (2, 1) + \frac{4}{3} (1, 2)$$

$$\begin{aligned} P(2, 3) &= \frac{1}{3} P(2, 1) + \frac{4}{3} P(1, 2) \\ &= \frac{P_1 + 4P_2}{3}. \end{aligned}$$

Eg.  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$T(1, 1) = (3, 1), T(1, 0) = (4, 2), T(1, -1) = (x, y).$$

Find  $x$  &  $y$ .

Basis:  $\{(1, 1), (1, 0)\}$ .

$$(x = 3, y = 3)$$

$$(x = 5, y = 2)$$

$$\begin{aligned} (1, -1) &= a(1, 1) + b(1, 0) \\ a+b &= 1 \\ a &= -1. \\ a &= -1, b = 2. \end{aligned}$$

$$\begin{aligned} T(1, -1) &= (-1)(3, 1) + 2(4, 2) \leftarrow \\ &= (5, 3). \end{aligned}$$

$$\begin{aligned} T(1, -1) &= T(\underline{\underline{a(1, 1)}} + \underline{\underline{b(1, 0)}}) \\ &= T(a(1, 1)) + T(b(1, 0)) \\ &= \underline{\underline{a T(1, 1) + b T(1, 0)}}. \end{aligned}$$

E.C.

$$\text{Prove that } T(x, y) = (4x-y, 2x-y).$$



Nullity of a matrix:

$\{ \underline{x} \in \mathbb{R}^n \mid A\underline{x} = \underline{0} \}$  is a vector subspace, called nullspace of  $A$ , denoted  $N(A)$ .

$\dim(N(A))$  is called the nullity of  $A$ .

$$\begin{array}{c} \left( \begin{array}{cccc} 1 & 3 & 4 & 1 \\ 1 & 2 & 3 & 2 \\ 1 & 1 & 0 & 1 \end{array} \right) \longrightarrow \left( \begin{array}{cccc} 1 & 3 & 4 & 1 \\ 0 & -1 & -1 & 1 \\ 0 & -2 & -4 & 0 \end{array} \right) \\ \longrightarrow \left( \begin{array}{cccc} 1 & 3 & 4 & 1 \\ 0 & 1 & 1 & -1 \\ 0 & 1 & 2 & 0 \end{array} \right) \\ \longrightarrow \left( \begin{array}{cccc} 1 & 3 & 4 & 1 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 1 & 1 \end{array} \right) \end{array}$$

4 variables

3 dep. 1 ind

$$\left( \begin{array}{cccc|c} 1 & 3 & 4 & 1 & 0 \\ 0 & 1 & 1 & -1 & 0 \\ 0 & 0 & 1 & 1 & 0 \end{array} \right)$$

$$x_4 = t$$

$$x_3 + x_4 = 0 \Rightarrow x_3 = -t$$

$$x_2 + x_3 - x_4 = 0 \Rightarrow x_2 = 2t$$

$$x_1 + 3x_2 + 4x_3 + x_4 = 0 \Rightarrow x_1 = -3t$$

$$N(A) = \{ (-3t, 2t, -t, t) \mid t \in \mathbb{R} \}$$

$$= \text{Span} \{ (-3, 2, -1, 1) \}$$

Nullity = 1.

$$\text{Ex: } \left( \begin{array}{ccccc} 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

What is the nullity and nullspace of this matrix?

Quy 1: (5x7)  $\max(\text{rank}) - \min(\text{rank})$ .

$$\begin{pmatrix} 2 \times 3 \\ (0 & 0 & 0) \\ (0 & 0 & 0) \end{pmatrix}$$