

FACE RECOGNITION + Liveness detection

* Face verification v/s face recognition

Input: image, id
output: input image
is of claimed
person?

database of k
persons

Input: image
output: ID (person
belonging to k)

* one shot learning

(Just one training example)

→ SIMILARITY FUNCTION

$d(\text{img1}, \text{img2})$ = degree of difference b/w image

If $d(\text{img1}, \text{img2}) \leq \tau$ same person

$> \tau$... different people

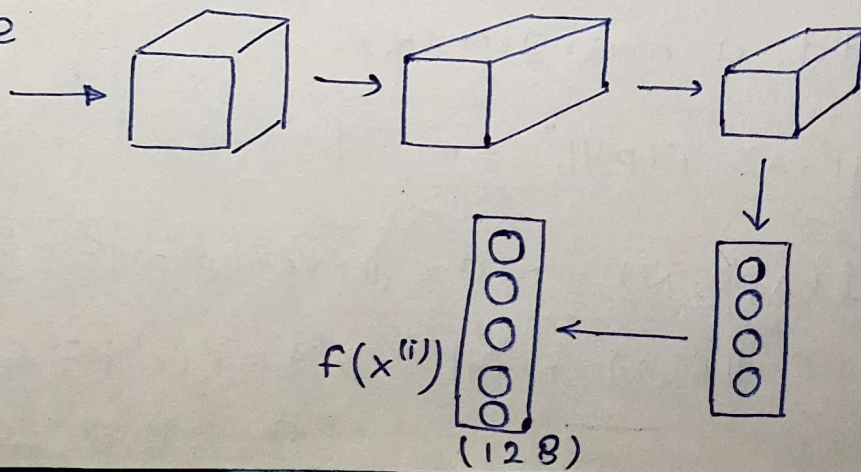
[τ = small threshold]

* siamese network

$$d(x^{(1)}, x^{(2)}) = \|f(x^{(1)}) - f(x^{(2)})\|^2$$

Run each input image on an independent
neural network

eg: Input image



→ parameters of ~~encoding~~ NN define an encoding $f(x^{(i)})$

Learn parameters so that:

↓ If $x^{(i)}, x^{(j)}$ are same person, $\|f(x^{(i)}) - f(x^{(j)})\|^2$ is small

↓ If $(x^{(i)}, x^{(j)})$ are different people then $\|f(x^{(i)}) - f(x^{(j)})\|^2$ is large

* Triplet Loss

$\alpha = \text{margin}$ (to push Anchor-positive & Anchor-negative pair further away from each other)

Anchor \Rightarrow Reference image (person 1)

positive \Rightarrow Another image of person 1, closer to Anchor

negative \Rightarrow Image of person 2, different from anchor

3 images: A, P, N

$$\underbrace{\|f(A) - f(P)\|^2}_{d(A,P)} \leq \underbrace{\|f(A) - f(N)\|^2}_{d(A,N)}$$

$$\|f(A) - f(P)\|^2 - \|f(A) - f(N)\|^2 \leq 0 \dots f(\text{img}) = \vec{0}$$

Add a margin (α)

$$\boxed{\|f(A) - f(P)\|^2 + \alpha \leq \|f(A) - f(N)\|^2}$$

$$\therefore \mathcal{L}(A, P, N) = \max(\|f(A) - f(P)\|^2 - \|f(A) - f(N)\|^2 + \alpha, 0)$$

\Rightarrow If $\|f(A) - f(P)\|^2 - \|f(A) - f(N)\|^2 + \alpha < 0$ then loss = 0

If $\|f(A) - f(P)\|^2 - \|f(A) - f(N)\|^2 + \alpha > 0$ then loss = $\|f(A) - f(P)\|^2 - \|f(A) - f(N)\|^2 + \alpha$

cost function

$$J = \sum_{i=1}^m \mathcal{L}(A^{(i)}, P^{(i)}, N^{(i)})$$

* training set²
must have multiple
pictures of same
person.

* choosing A, P, N

1) A, P, N if chosen randomly, $d(A, P) + \alpha \leq d(A, N)$
is easily satisfied.

2) choose triplets that are harder to
train on. $d(A, P) \approx d(A, N) \dots \alpha \ll \ll$

Goal → use gradient descent to minimize
cost function "J"

* Binary classification

$$\hat{y} = \sigma \left(\sum_{k=1}^{128} w_k |f(x^{(1)})_k - f(x^{(j)})_k| + b \right)$$

for χ^2 formula:

$$\frac{(f(x^{(1)})_k - f(x^{(j)})_k)^2}{f(x^{(1)})_k + f(x^{(j)})_k}$$

* use pairs of images:

Target label = 1 → same

= 0 → different

• NEURAL STYLE TRANSFER

content (c)
+
style (s) } Generated image (G)

→ Initial layers (Lines, colours, simple shapes) NEURONS DETECT ↘
→ deeper layers (complex pattern, texture) NEURONS DETECT ↘

* cost function

$$J(G) = \alpha J_{\text{content}}(C, G) + \beta J_{\text{style}}(S, G)$$

DIFFERENT "HYPERPARAMETERS" TO DENOTE WEIGHTS

* Find generated image 'G'

(1) Initialize G randomly $\Rightarrow G : 100 \times 100 \times 3$

(2) use gradient descent to minimize $J(G)$

$$G := G - \frac{\partial}{\partial G} J(G)$$

* content cost function

(1) choose hidden layer l (middle layer) to compute cost

(2) use pre-trained convnet (VGG-19)

(3) $a^{[l]}(c)$ & $a^{[l]}(G)$ be activation of layer l
if $a^{[l]}(c)$ & $a^{[l]}(G)$ are similar, both images have similar content

$$J_{\text{content}}(C, G) = \frac{1}{4 \times n_H \times n_W \times n_c} \sum_{\text{all entries}} (a^{[l]}(c) - a^{[l]}(G))^2$$

• style cost function

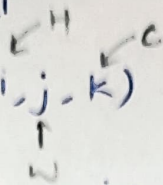
3

→ using layer 'l' activation to measure style

→ define style as correlation between activations across channels

→ Style / Gram Matrix

$a_{i,j,k}^{[l]}$ = activation at (i,j,k)



$G^{[l]} = n_c^{[l]} \times n_c^{[l]}$ dimensional

$$G_{kk'}^{[l](S)} = \sum_{i=1}^{n_H^{[l]}} \sum_{j=1}^{n_W^{[l]}} a_{ijk}^{[l](S)} a_{ijk'}^{[l](S)} \quad k, k' = 1, \dots, n_c^{[l]}$$

$$G_{kk'}^{[l](G)} = \sum_{i=1}^{n_H^{[l]}} \sum_{j=1}^{n_W^{[l]}} a_{ijk}^{[l](G)} a_{ijk'}^{[l](G)}$$

$$J_{style}^{[l]}(S, G) = \| G^{[l](S)} - G^{[l](G)} \|^2$$

$$= \sum_k \sum_{k'} \left(G_{kk'}^{[l](S)} - G_{kk'}^{[l](G)} \right)^2 \times \frac{1}{\left(2 \times n_H^{[l]} \times n_W^{[l]} \times n_c^{[l]} \right)^2}$$

$$J_{style}(S, G) = \sum_l \lambda^{[l]} J_{style}^{[l]}(S, G)$$

$\lambda^{[l]}$
hyperparameter