

# RNN Types

① One-to-One / Vanilla Mode: Vanilla mode of processing w/o RNN

fixed size i/p to fixed sized o/p.

eg: Image Classification



# RNN Types

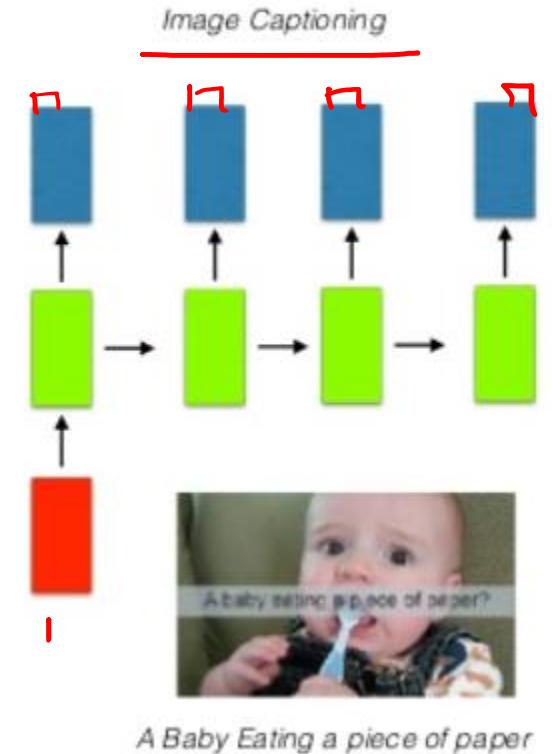
## ② One-to-Many:

Sequence O/p

Image Captioning:

Input: An image

o/p: Sentence of words

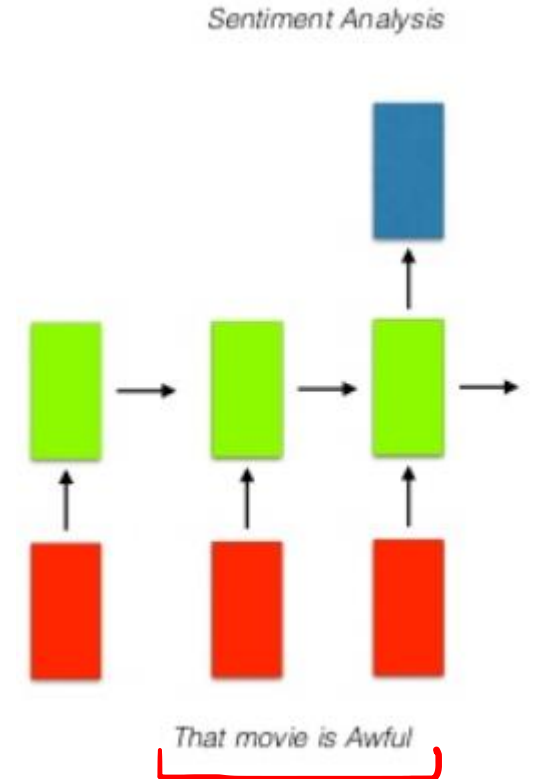


# RNN Types

③ Many-to-one:

Sequence input

eg: Sentiment analysis where a given sentence is classified as expressing +ve or -ve Sentiment-



# RNN Types

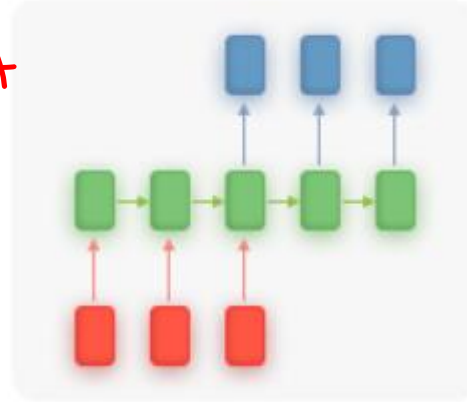
① Many to Many

Sequence input & Sequence Input

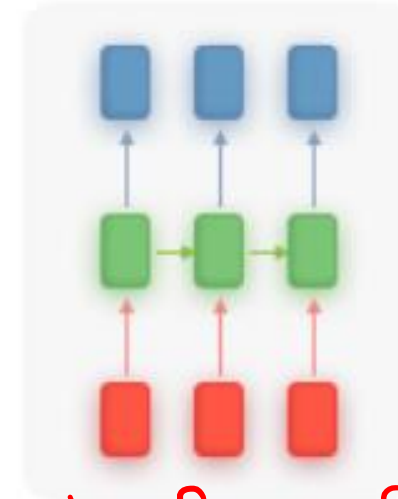
eg: Google Translate  
Machine Translation

Video Classification where we wish to label each frame of the video.

Many to many



Many to many

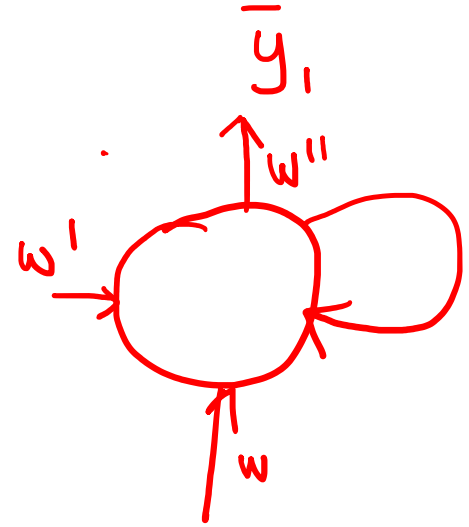


# Why RNN? Used popularly in NLP problems.

NLP: Input Data


$X$  = text format  
 $X$  = Number format  
 Naive Bayes Algo.

Preprocessing  
 + Bag of Words  
 (Count Vectorizer)



	love	play	cricket	fun
0	0	1	1	0
1	1	1	1	0
2	0	1	0	1
Count:	2	3	1	1

Sequence info is LOST.

	play	love	cricket	fun
0	1	1	0	0
1	1	1	1	0
2	1	0	0	1

- ① Bag of Words } Sequence info is lost.
- ② TF-IDF
- ③ WORD2VEC

$$0 = \begin{bmatrix} x_0 & x_1 & x_2 & x_3 \\ 1 & 1 & 0 & 0 \end{bmatrix}$$

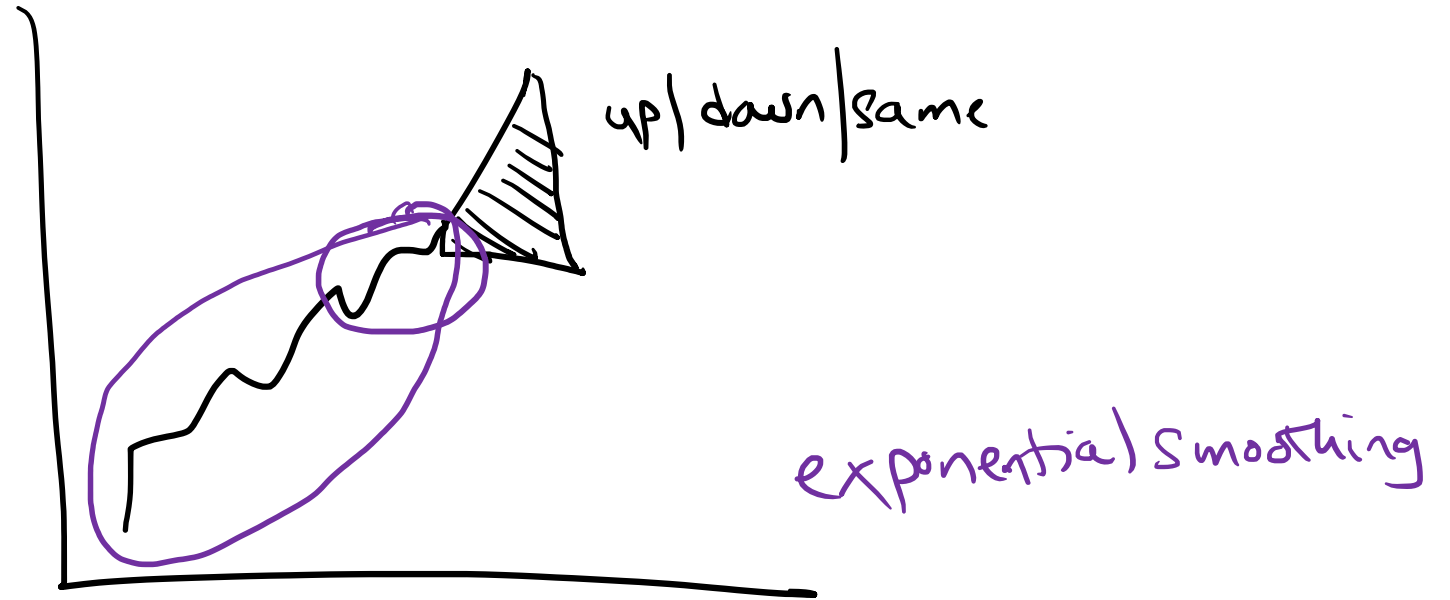
$$1 = \begin{bmatrix} 1 & 1 & 1 & 0 \\ x_0 & x_1 & x_2 & x_3 \end{bmatrix}$$

$$2 = \begin{bmatrix} 1 & 0 & 0 & 1 \\ x_0 & x_1 & x_2 & x_3 \end{bmatrix}$$

Trainer: Dr. Darshan Ingole

# Why RNN?

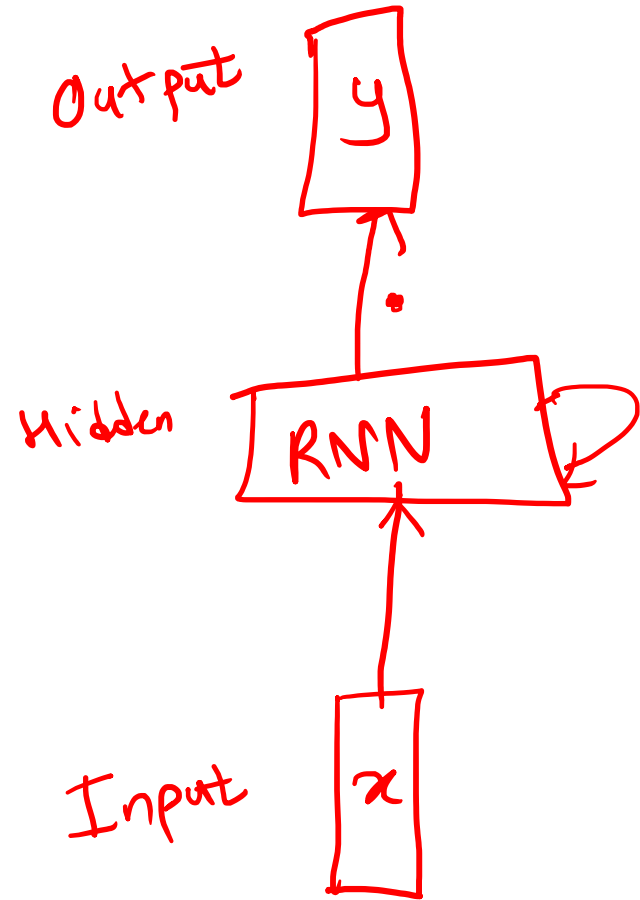
TimeSeries Prob



eg: Image Captioning,  
Google Translate  
Sentiment analysis for restaurant reviews  
Amazon alexa  
Google Assistant, Siri / Microsoft Cortana

Imp ~~Info~~: Sequence info.

# Summary Simple form of Vanilla RNN

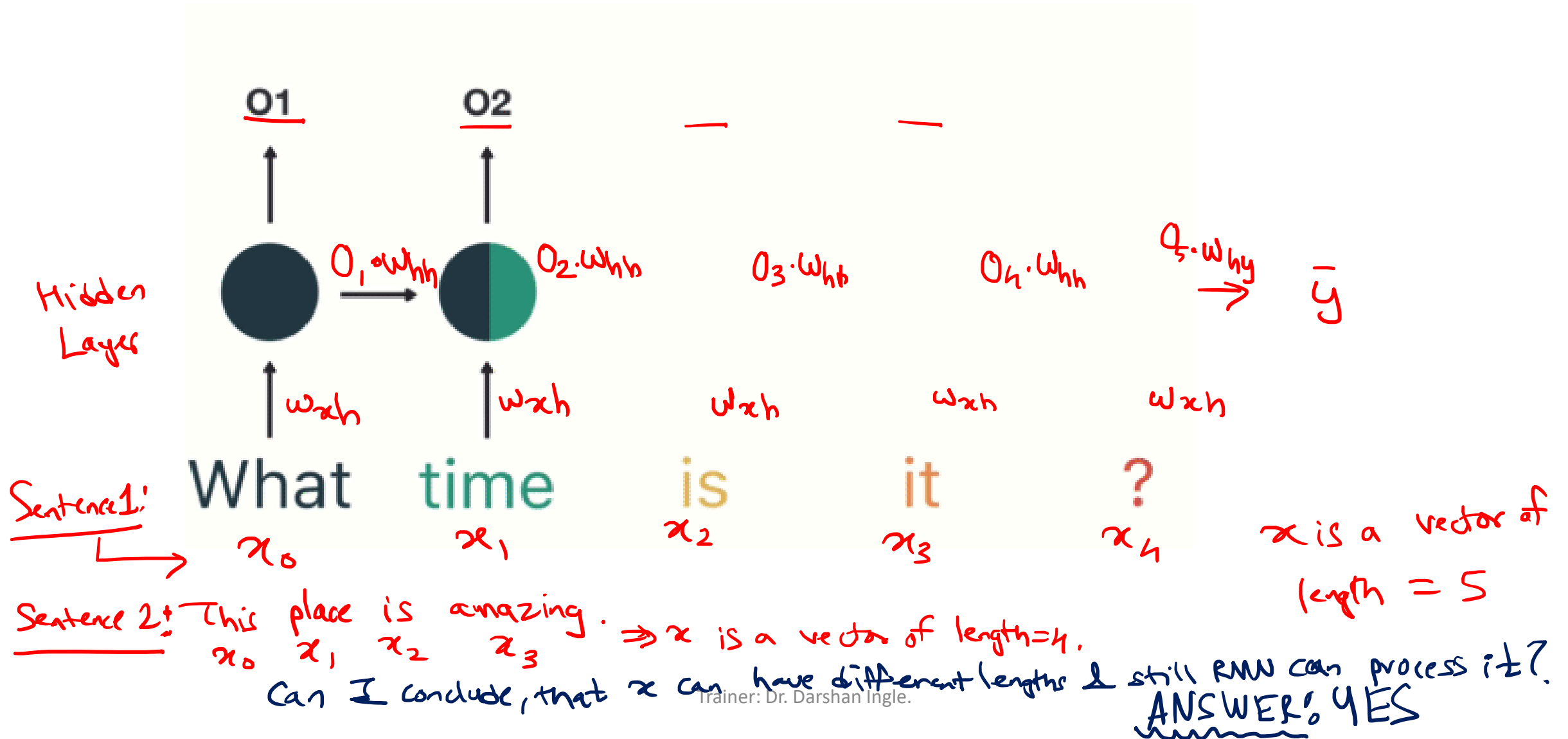


$$h_t = f_w(h_{t-1}, x_t)$$

$$\therefore h_t = \tanh(W_{hh} \cdot h_{t-1} + W_{xh} \cdot x_t)$$

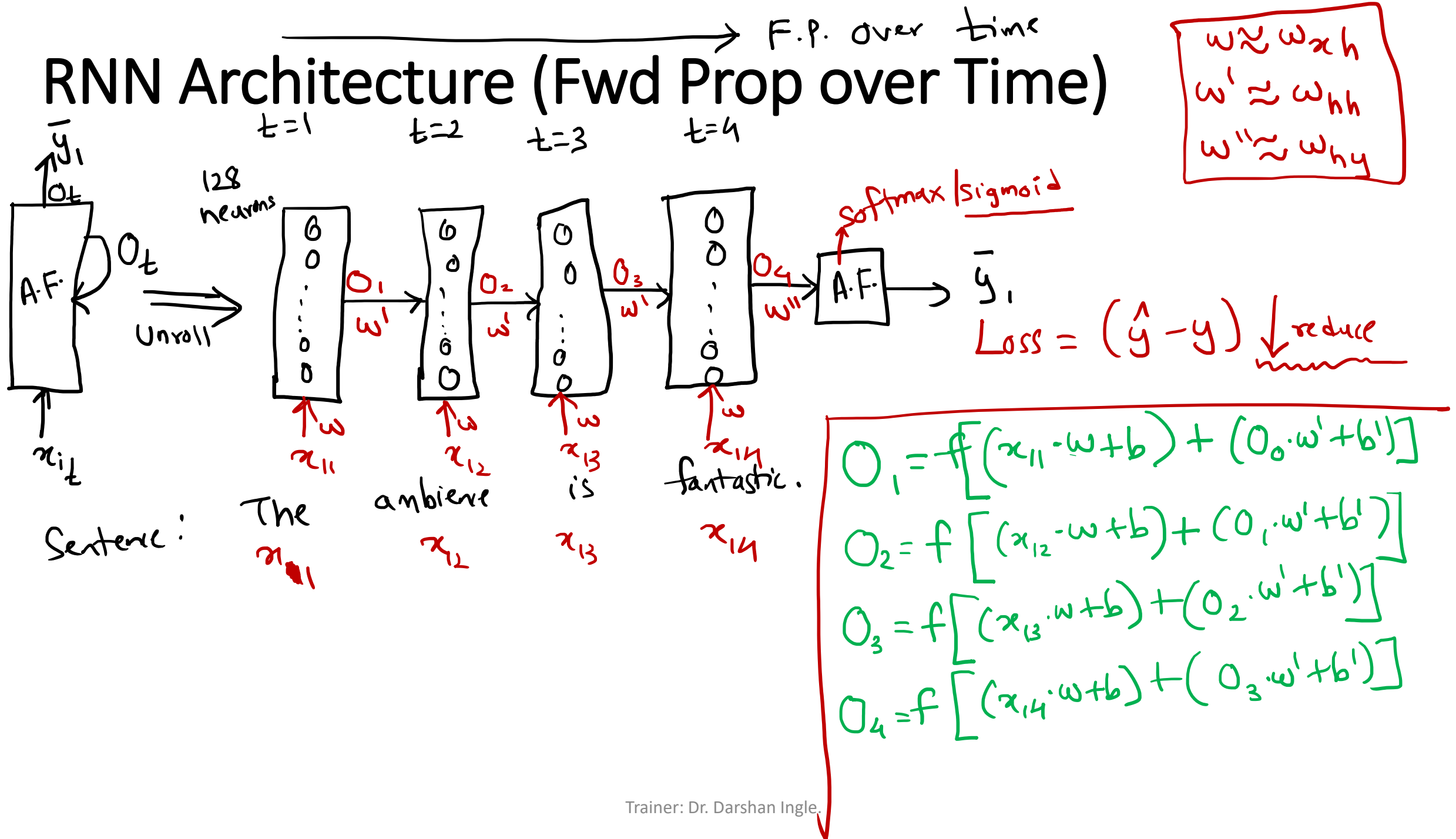
$$y_t = W_{hy} \cdot h_t$$

# Summary



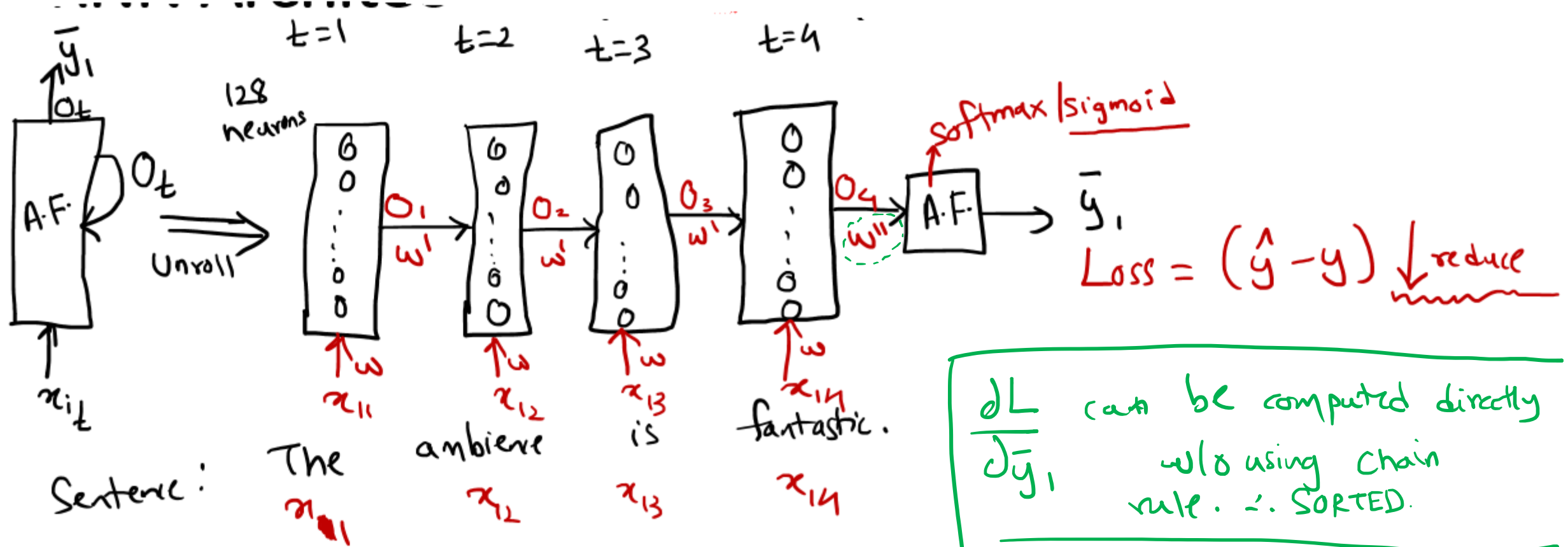


# RNN Architecture (Fwd Prop over Time)



# RNN Architecture (Fwd Prop over Time)

# RNN Architecture (Back Prop over Time)

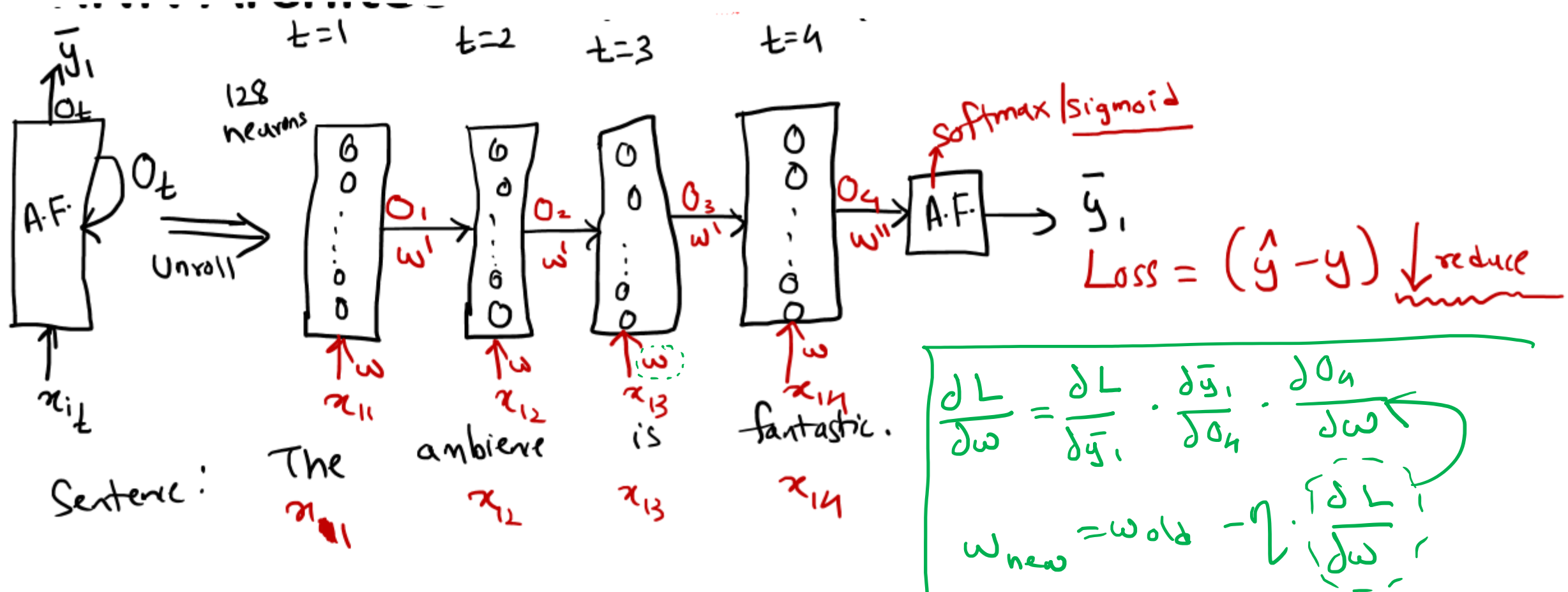


$\frac{\partial L}{\partial \bar{y}_1}$  can be computed directly w/o using chain rule.  $\therefore$  SORTED.

$$\frac{\partial L}{\partial w''} = \frac{\partial L}{\partial \bar{y}_1} \cdot \frac{\partial \bar{y}_1}{\partial w''}$$

$$\therefore w''_{new} = w''_{old} - \eta \cdot \frac{\partial L}{\partial w''}$$

# RNN Architecture (Back Prop over Time)



# Problems with RNN

① Vanishing Gradient Problem:

$\tanh()$  most common

Der. of  $\tanh \rightarrow [0, 1]$

A.F. in RNN  $\rightarrow [-1, +1]$

② Exploding Gradient problem: It is due to the higher assigned weights

# Problems with RNN

Due to these problems, we cannot do a lot of B.P. ,  
∴ we cannot consider older states i.e. we cannot process a lot of sequence data.

∴ We need a better or modified RNN Model.

\* Solution: 1997 : Long Short Term Memory (LSTM). \*

eg1: I live in Gujrat & I know Gujarati ⇒ RNN can process it.

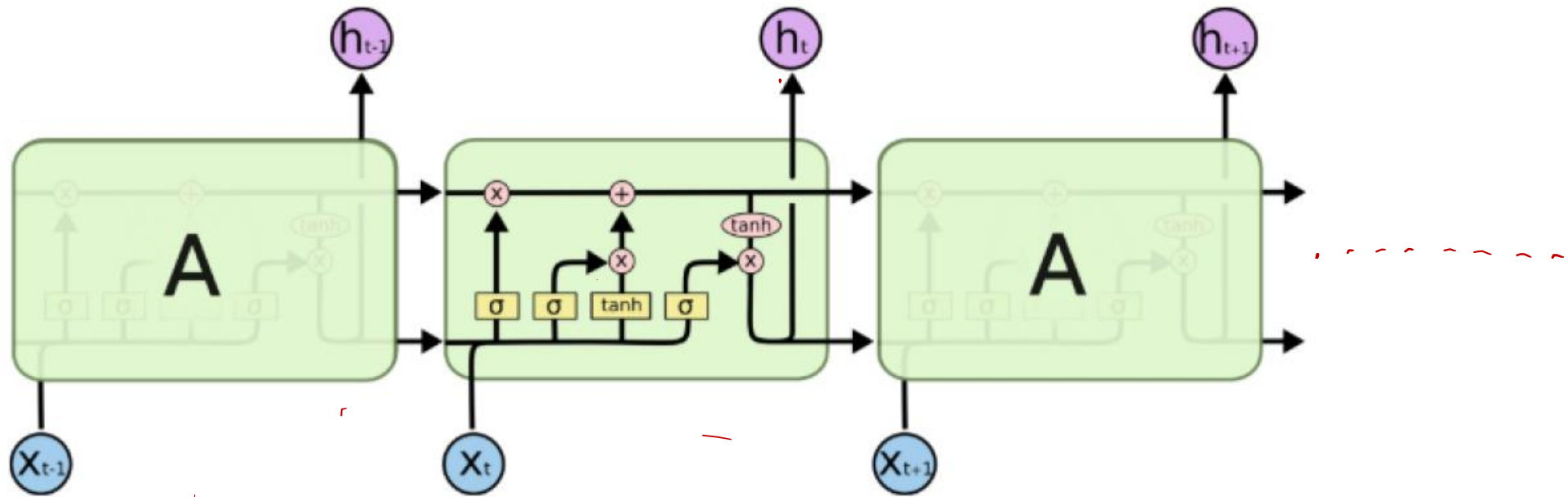
eg2: I live in Gujrat & I am a businessman and I know \_\_\_\_\_ ?

⇒ RNN fails

be2 the context is far away.

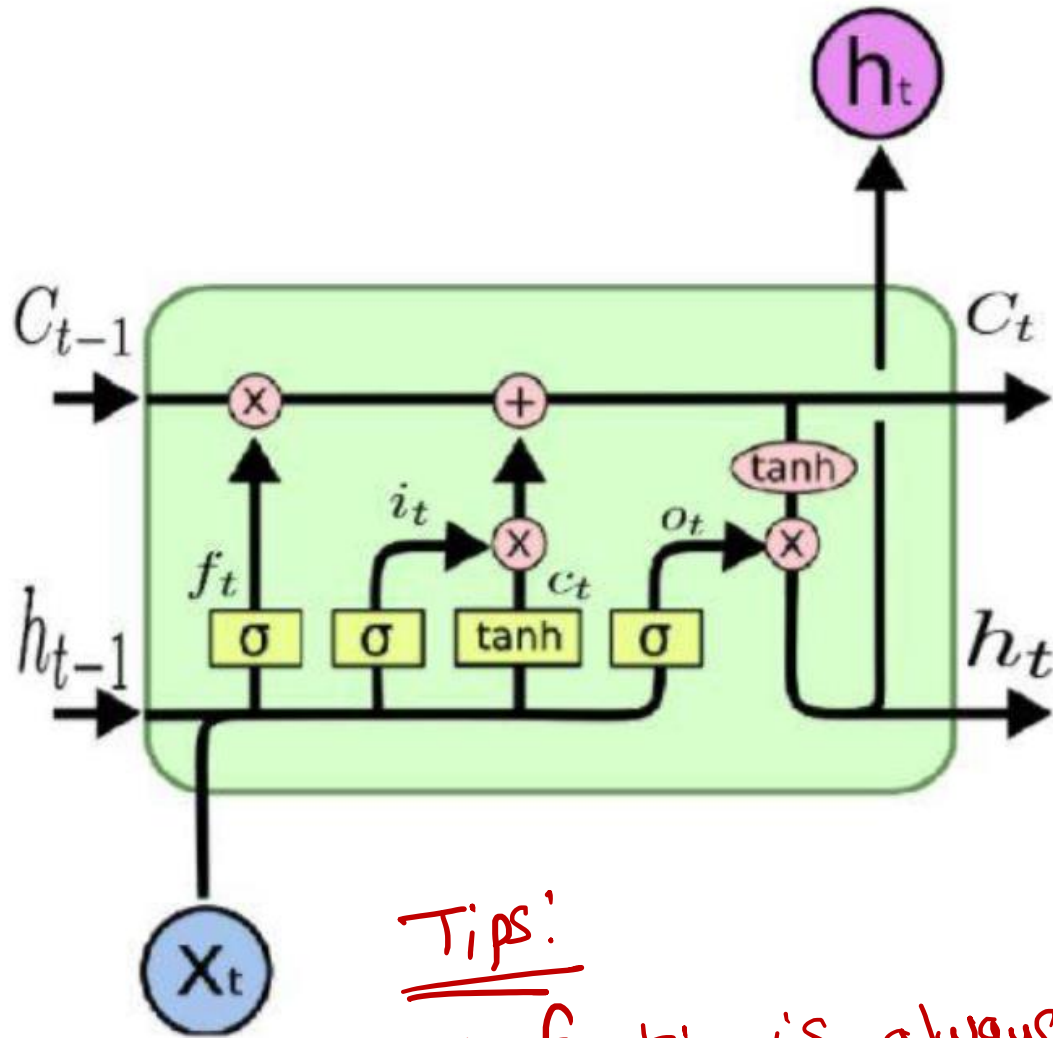
↑ far

① We have not studied entire NLP course. ② LSTM requires a good background of NLP.  
**LSTM Architecture** ③ LSTM is easy if you compare this to learn car driving.



The repeating module in an LSTM contains four interacting layers.

- ① f: Forget gate: whether to erase the cell data
- ② i: Input gate: whether to write to the cell
- ③ g: Gate gate: How much to write to the cell?
- ④ o: Output gate: How much to reveal cell.



$C$ : Cell State  
 $h$ : hidden State

$f$ : forget gate

$i$ : input gate

$o$ : output gate

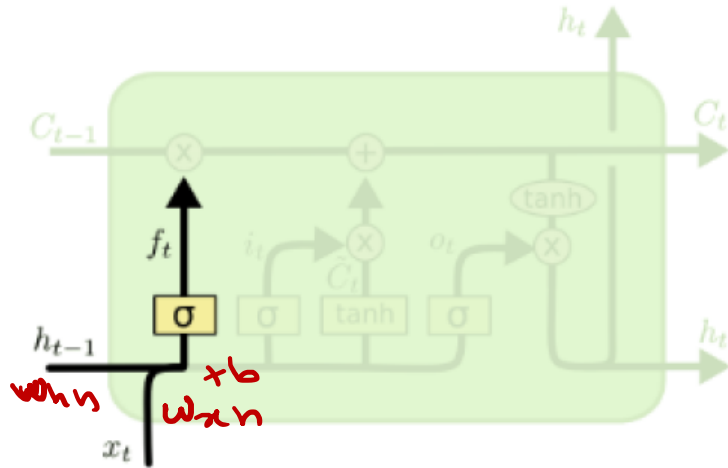
Tips:

- ① Sigmoid function is always used to filter out information.
- ② tanh function is used for adding new or modifying existing information.



# Forget Gate

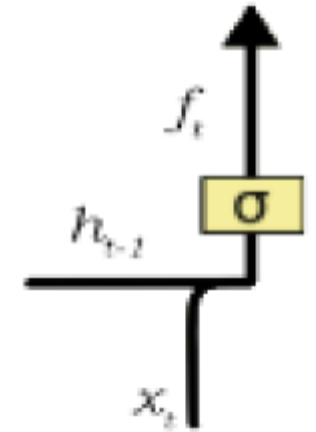
After getting o/p from  $h_{t-1}$  i.e. prev. state, Forget gate helps me to take decisions about what must be removed from  $h_{t-1}$  & thus keep only relevant info.



$$f_t = \sigma(W_f \cdot [h_{t-1}, x_t] + b_f)$$

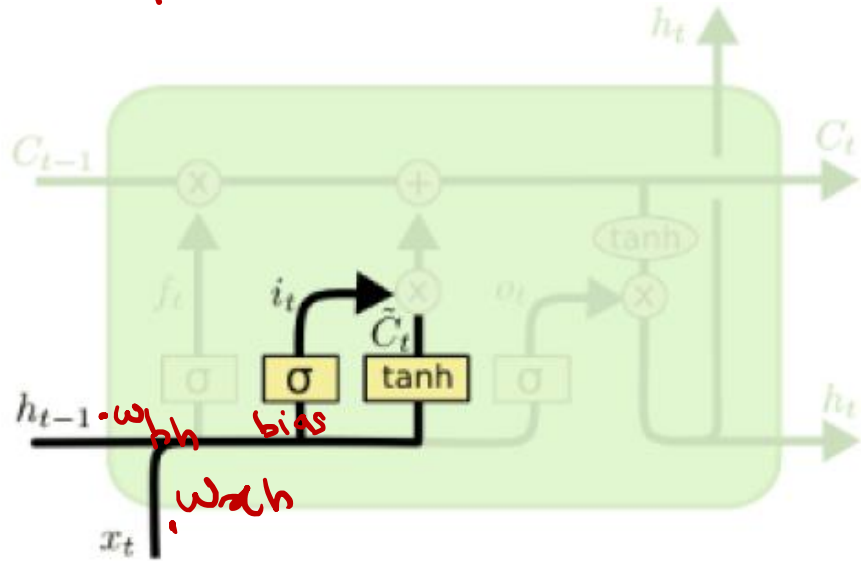
# Forget Gate Example

Bob is a nice person. Dan on the other hand is evil.



# Input Gate

In input gate, we decide to add new info from present input to our present cell state scaled by how much we want to add them.



$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i)$$

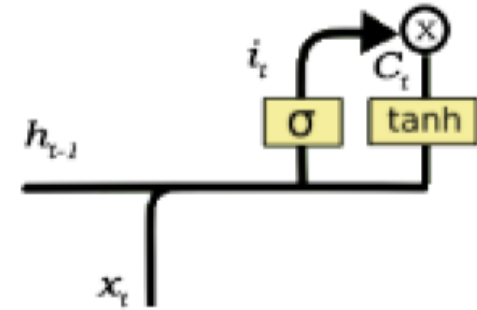
$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

Sigmoid layer decides which value should be updated & tanh create a vector for new info to be added to present cell state.

# Input Gate Example

Bob knows swimming. He told me over the phone that he had served the navy for 4 long years.

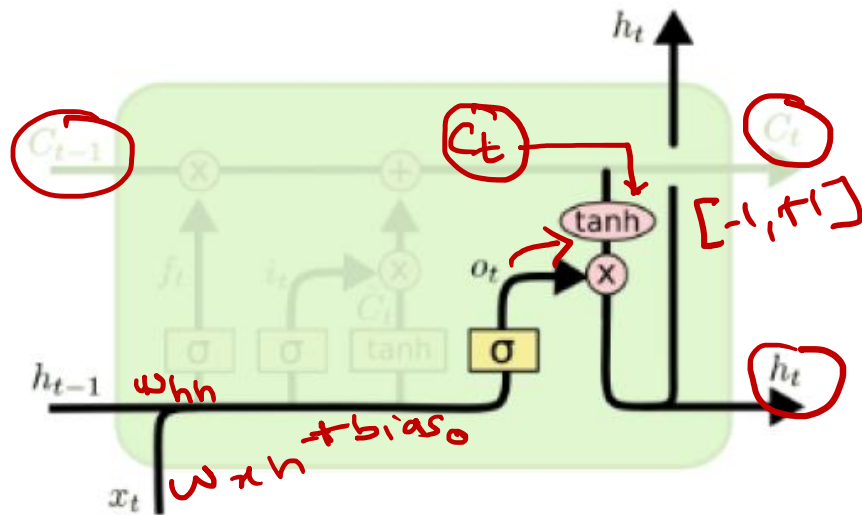
added to cell state



$$\begin{bmatrix} 0.1 \\ 0.002 \\ 0.1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 0.1 \\ 0.004 \\ 0.3 \end{bmatrix}$$

# Output Gate

we decide finally what to output from our cell state (which will be done by sigmoid).

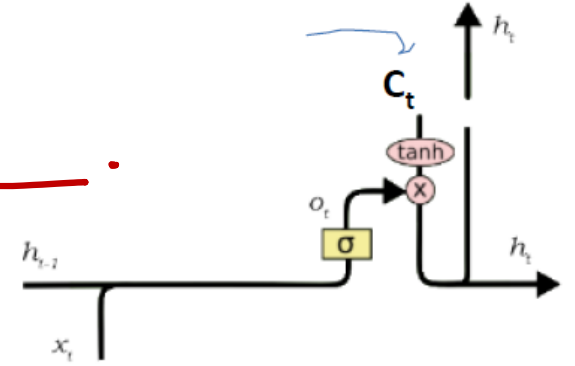


$$o_t = \sigma(W_o [h_{t-1}, x_t] + b_o)$$

$$h_t = o_t * \tanh(C_t)$$

# Output Gate Example

Bob fought single handedly with the enemy and  
died for his country. For his contributions brave man <sup>noun</sup>  
i.e. to describe a noun



# Additional Resource

- <https://colah.github.io/posts/2015-08-Understanding-LSTMs/>
- <https://www.analyticsvidhya.com/blog/2017/12/fundamentals-of-deep-learning-introduction-to-lstm/>
- <https://towardsdatascience.com/illustrated-guide-to-lstms-and-gru-s-a-step-by-step-explanation-44e9eb85bf21>
- <https://medium.com/@aidangomez/let-s-do-this-f9b699de31d9>