

# Complete Mathematical Formulas in Machine Learning

## Table of Contents

1. Foundational Mathematics
  2. Statistical Measures
  3. Linear Algebra in ML
  4. Calculus in ML
  5. Probability Theory
  6. Information Theory
  7. Loss Functions
  8. Optimization Algorithms
  9. Linear Models Mathematics
  10. Tree-Based Models Mathematics
  11. Support Vector Machines Mathematics
  12. Neural Network Mathematics
  13. Clustering Mathematics
  14. Dimensionality Reduction Mathematics
  15. Evaluation Metrics Mathematics
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## Foundational Mathematics

### Basic Notation

- **Scalar**: Single value, denoted as  $x, y, a, b$
- **Vector**: Column of values, denoted as  $\mathbf{x}, \mathbf{y}$  (bold)
- **Matrix**: 2D array, denoted as  $\mathbf{X}, \mathbf{W}$  (bold capital)
- **Tensor**: n-dimensional array

### Summation and Product Notation

#### Summation:

$$\sum_{i=1}^n x_i = x_1 + x_2 + \dots + x_n$$

#### Product:

$$\prod_{i=1}^n x_i = x_1 \times x_2 \times \dots \times x_n$$

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## Statistical Measures

### Mean (Average)

#### Arithmetic Mean:

$$\mu = \bar{x} = (1/n) \times \sum_{i=1}^n x_i$$

- $\mu$  (mu) or  $\bar{x}$  represents the mean
- $n$  is the number of observations
- $x_i$  is the  $i$ -th observation

### Variance

#### Population Variance:

$$\sigma^2 = (1/n) \times \sum_{i=1}^n (x_i - \mu)^2$$

#### Sample Variance (Bessel's correction):

$$s^2 = (1/(n-1)) \times \sum_{i=1}^n (x_i - \bar{x})^2$$

### Standard Deviation

$$\sigma = \sqrt{\sigma^2} \quad (\text{population})$$

$$s = \sqrt{s^2} \quad (\text{sample})$$

### Covariance

#### Between two variables X and Y:

$$\text{Cov}(X, Y) = (1/n) \times \sum_{i=1}^n (x_i - \mu_x)(y_i - \mu_y)$$

### Correlation Coefficient

#### Pearson Correlation:

$$\rho(X, Y) = \text{Cov}(X, Y) / (\sigma_x \times \sigma_y)$$

- Range:  $[-1, 1]$

- -1: perfect negative correlation
- 0: no linear correlation
- 1: perfect positive correlation

## Standardization (Z-score)

$$z = (x - \mu) / \sigma$$

- Transforms data to have  $\mu = 0$  and  $\sigma = 1$
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## Linear Algebra in ML

### Vector Operations

**Dot Product** (Inner Product):

$$a \cdot b = \sum_{i=1}^n a_i b_i = a_1 b_1 + a_2 b_2 + \dots + a_n b_n$$

**Vector Norm** (Length):

- L1 Norm (Manhattan):  $\|x\|_1 = \sum_i |x_i|$
- L2 Norm (Euclidean):  $\|x\|_2 = \sqrt{\sum_i x_i^2}$
- L $\infty$  Norm (Max):  $\|x\|_\infty = \max_i |x_i|$

### Matrix Operations

**Matrix Multiplication:**

$$C = AB \text{ where } C_{ij} = \sum_k A_{ik} B_{kj}$$

**Matrix Transpose:**

$$(A^T)_{ij} = A_{ji}$$

**Matrix Inverse:**

$$AA^{-1} = A^{-1}A = I$$

where  $I$  is the identity matrix

## Eigenvalues and Eigenvectors

For matrix  $A$  and vector  $v$ :

$$Av = \lambda v$$

- $\lambda$  is the eigenvalue
- $v$  is the eigenvector

### Characteristic Equation:

$$\det(A - \lambda I) = 0$$


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## Calculus in ML

### Derivatives

#### Basic Rules:

- Power Rule:  $d/dx(x^n) = nx^{n-1}$
- Chain Rule:  $d/dx[f(g(x))] = f'(g(x)) \times g'(x)$
- Product Rule:  $d/dx[f(x)g(x)] = f'(x)g(x) + f(x)g'(x)$

### Partial Derivatives

For function  $f(x,y)$ :

$\partial f / \partial x$  = partial derivative with respect to  $x$   
 $\partial f / \partial y$  = partial derivative with respect to  $y$

### Gradient

For function  $f(x_1, x_2, \dots, x_n)$ :

$$\nabla f = [\partial f / \partial x_1, \partial f / \partial x_2, \dots, \partial f / \partial x_n]^T$$

### Gradient Descent Update Rule

$$\theta_{t+1} = \theta_t - \alpha \nabla f(\theta_t)$$

- $\theta$ : parameters
- $\alpha$ : learning rate
- $\nabla f$ : gradient of loss function

### Hessian Matrix

Second-order partial derivatives:

$$H(f)_{ij} = \partial^2 f / (\partial x_i \partial x_j)$$

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## Probability Theory

### Basic Probability

$$P(A) \in [0, 1]$$

$$P(\Omega) = 1 \quad (\text{probability of sample space})$$

$$P(\emptyset) = 0 \quad (\text{probability of empty set})$$

### Conditional Probability

$$P(A|B) = P(A \cap B) / P(B)$$

- $P(A|B)$ : probability of A given B

### Bayes' Theorem

$$P(A|B) = [P(B|A) \times P(A)] / P(B)$$

**Extended form:**

$$P(A|B) = [P(B|A) \times P(A)] / [\sum_i P(B|A_i) \times P(A_i)]$$

## Probability Distributions

### Bernoulli Distribution:

$$P(X = x) = p^x (1-p)^{1-x} \quad \text{for } x \in \{0, 1\}$$

### Binomial Distribution:

$$P(X = k) = C(n, k) \times p^k \times (1-p)^{n-k}$$

where  $C(n, k) = n! / (k!(n-k)!)$

### Normal (Gaussian) Distribution:

$$f(x) = (1/\sqrt{2\pi\sigma^2}) \times \exp(-(x-\mu)^2/(2\sigma^2))$$

## Multivariate Normal:

$$f(x) = (1 / ((2\pi)^{(k/2)} |\Sigma|^{(1/2)})) \times \exp(-\frac{1}{2}(x-\mu)^T \Sigma^{-1} (x-\mu))$$

- $\Sigma$ : covariance matrix
- $|\Sigma|$ : determinant of  $\Sigma$

## Expectation and Variance

**Expectation** (Expected Value):

- Discrete:  $E[X] = \sum_x x \times P(X = x)$
- Continuous:  $E[X] = \int x \times f(x) dx$

**Variance:**

$$\text{Var}(X) = E[(X - E[X])^2] = E[X^2] - (E[X])^2$$

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## Information Theory

### Entropy

**For discrete variable X:**

$$H(X) = -\sum_i P(x_i) \times \log_2(P(x_i))$$

- Measures uncertainty/information content
- Units: bits ( $\log_2$ ) or nats ( $\ln$ )

### Cross-Entropy

**Between distributions P and Q:**

$$H(P, Q) = -\sum_i P(x_i) \times \log(Q(x_i))$$

### Kullback-Leibler (KL) Divergence

$$KL(P || Q) = \sum_i P(x_i) \times \log(P(x_i)/Q(x_i))$$

- Measures difference between distributions
- $KL(P||Q) \neq KL(Q||P)$  (not symmetric)

### Mutual Information

$$I(X;Y) = \sum_x \sum_y P(x,y) \times \log(P(x,y)/(P(x)P(y)))$$


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## Loss Functions

### Regression Loss Functions

#### Mean Squared Error (MSE):

$$MSE = (1/n) \times \sum_{i=1}^n (y_i - \hat{y}_i)^2$$

#### Mean Absolute Error (MAE):

$$MAE = (1/n) \times \sum_{i=1}^n |y_i - \hat{y}_i|$$

#### Huber Loss (Robust to outliers):

$$L_{\delta}(y, \hat{y}) = \begin{cases} \frac{1}{2}(y - \hat{y})^2 & \text{if } |y - \hat{y}| \leq \delta \\ \delta|y - \hat{y}| - \frac{1}{2}\delta^2 & \text{if } |y - \hat{y}| > \delta \end{cases}$$

### Classification Loss Functions

#### Binary Cross-Entropy (Log Loss):

$$BCE = -(1/n) \times \sum_{i=1}^n [y_i \log(\hat{y}_i) + (1 - y_i) \log(1 - \hat{y}_i)]$$

#### Categorical Cross-Entropy (Multi-class):

$$CCE = -(1/n) \times \sum_{i=1}^n \sum_{j=1}^m y_{ij} \log(\hat{y}_{ij})$$

- m: number of classes
- $y_{ij}$ : 1 if sample i belongs to class j, 0 otherwise

#### Hinge Loss (SVM):

$$L = \max(0, 1 - y \times \hat{y})$$


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## Optimization Algorithms

### Gradient Descent Variants

## Batch Gradient Descent:

$$\theta = \theta - \alpha \times (1/n) \times \sum_{i=1}^n \nabla \theta L(x_i, y_i, \theta)$$

## Stochastic Gradient Descent (SGD):

$$\theta = \theta - \alpha \times \nabla \theta L(x_i, y_i, \theta)$$

## Mini-batch Gradient Descent:

$$\theta = \theta - \alpha \times (1/m) \times \sum_{i=1}^m \nabla \theta L(x_i, y_i, \theta)$$

## Advanced Optimizers

### Momentum:

$$v_t = \beta v_{t-1} + \alpha \nabla \theta L$$

$$\theta_t = \theta_{t-1} - v_t$$

### RMSprop:

$$s_t = \beta s_{t-1} + (1-\beta)(\nabla \theta L)^2$$

$$\theta_t = \theta_{t-1} - \alpha \times \nabla \theta L / \sqrt{s_t + \epsilon}$$

### Adam (Adaptive Moment Estimation):

$$m_t = \beta_1 m_{t-1} + (1-\beta_1) \nabla \theta L \quad (1st \text{ moment})$$

$$v_t = \beta_2 v_{t-1} + (1-\beta_2) (\nabla \theta L)^2 \quad (2nd \text{ moment})$$

$$\hat{m}_t = m_t / (1-\beta_1^t) \quad (\text{bias correction})$$

$$\hat{v}_t = v_t / (1-\beta_2^t) \quad (\text{bias correction})$$

$$\theta_t = \theta_{t-1} - \alpha \times \hat{m}_t / (\sqrt{\hat{v}_t} + \epsilon)$$

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## Linear Models Mathematics

### Linear Regression

#### Model:

$$\hat{y} = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_n x_n = x^T \beta$$

#### Normal Equation (Closed-form solution):



$$\beta = (X^T X)^{-1} X^T y$$

**Cost Function (MSE):**

$$J(\beta) = (1/2n) \times \sum_{i=1}^n (y_i - x_i^T \beta)^2$$

**Gradient:**

$$\nabla J = -(1/n) \times X^T (y - X\beta)$$

## Ridge Regression (L2 Regularization)

**Cost Function:**

$$J(\beta) = (1/2n) \times \sum_{i=1}^n (y_i - x_i^T \beta)^2 + \lambda ||\beta||_2^2$$

**Solution:**

$$\beta = (X^T X + \lambda I)^{-1} X^T y$$

## Lasso Regression (L1 Regularization)

**Cost Function:**

$$J(\beta) = (1/2n) \times \sum_{i=1}^n (y_i - x_i^T \beta)^2 + \lambda ||\beta||_1$$

- No closed-form solution
- Solved using coordinate descent or proximal gradient

## Logistic Regression

**Sigmoid Function:**

$$\sigma(z) = 1/(1 + e^{-z})$$

**Model:**

$$P(y=1|x) = \sigma(x^T \beta) = 1/(1 + e^{-x^T \beta})$$

**Log-Likelihood:**

$$LL = \sum_{i=1}^n [y_i \log(\sigma(x_i^T \beta)) + (1-y_i) \log(1-\sigma(x_i^T \beta))]$$

**Gradient:**

$$\nabla_{\beta} LL = X^T (y - \sigma(X\beta))$$


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## Tree-Based Models Mathematics

### Decision Trees

**Gini Impurity:**

$$\text{Gini} = 1 - \sum_{j=1}^c p_j^2$$

- c: number of classes
- $p_j$ : proportion of samples in class j

**Entropy:**

$$\text{Entropy} = -\sum_{j=1}^c p_j \log_2(p_j)$$

**Information Gain:**

$$IG = \text{Entropy}(\text{parent}) - \sum_i (n_i/n) \times \text{Entropy}(\text{child}_i)$$

- $n_i$ : number of samples in child i
- n: total samples in parent

**Variance Reduction** (for regression):

$$VR = \text{Var}(\text{parent}) - \sum_i (n_i/n) \times \text{Var}(\text{child}_i)$$

### Random Forest

**Prediction** (Regression):

$$\hat{y} = (1/B) \times \sum_{\beta=1}^B T_{\beta}(x)$$

- B: number of trees
- $T_{\beta}$ : prediction from tree b

## Prediction (Classification):

$$\hat{y} = \text{mode}\{T_1(x), T_2(x), \dots, T^B(x)\}$$

## Feature Importance:

$$\text{Importance}_j = (1/B) \times \sum_{\beta=1}^B \sum_{t \in \beta} 1(v(t)=j) \times p(t) \Delta_{it}$$

- $v(t)$ : variable used at node  $t$
- $p(t)$ : proportion of samples reaching node  $t$
- $\Delta_{it}$ : impurity decrease at node  $t$

## Gradient Boosting

### Additive Model:

$$F(x) = \sum_{m=1}^M \gamma_m h_m(x)$$

### Update Rule:

$$F_m(x) = F_{m-1}(x) + \gamma_m h_m(x)$$

### Gradient Calculation:

$$r_{im} = -[\partial L(y_i, F(x_i)) / \partial F(x_i)]_{F=F_{m-1}}$$

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## Support Vector Machines Mathematics

### Hard Margin SVM

#### Objective:

$$\begin{aligned} \text{minimize: } & \frac{1}{2} \|w\|^2 \\ \text{subject to: } & y_i(w^T x_i + b) \geq 1 \text{ for all } i \end{aligned}$$

### Soft Margin SVM

#### Objective:

$$\begin{aligned} \text{minimize: } & \frac{1}{2} \|w\|^2 + C \times \sum_i \xi_i \\ \text{subject to: } & y_i(w^T x_i + b) \geq 1 - \xi_i \\ & \xi_i \geq 0 \end{aligned}$$

- $\xi_i$ : slack variables
- C: regularization parameter

## Kernel Trick

### Kernel Function:

$$K(x, x') = \phi(x)^T \phi(x')$$

### Common Kernels:

- Linear:  $K(x, x') = x^T x'$
- Polynomial:  $K(x, x') = (\gamma x^T x' + r)^d$
- RBF (Gaussian):  $K(x, x') = \exp(-\gamma \|x - x'\|^2)$
- Sigmoid:  $K(x, x') = \tanh(\gamma x^T x' + r)$

### Dual Form Prediction:

$$f(x) = \sum_{i=1}^n \alpha_i y_i K(x_i, x) + b$$


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## Neural Network Mathematics

### Forward Propagation

#### Linear Transformation:

$$z^{(1)} = W^{(1)} a^{(1-1)} + b^{(1)}$$

#### Activation:

$$a^{(1)} = g^{(1)}(z^{(1)})$$

### Activation Functions

#### ReLU (Rectified Linear Unit):

$$\text{ReLU}(z) = \max(0, z)$$

## Leaky ReLU:

$$\text{LeakyReLU}(z) = \max(\alpha z, z) \quad \text{where } \alpha \approx 0.01$$

## Sigmoid:

$$\sigma(z) = 1/(1 + e^{-z})$$

## Tanh:

$$\tanh(z) = (e^z - e^{-z})/(e^z + e^{-z})$$

## Softmax (Multi-class output):

$$\text{softmax}(z_i) = e^{z_i} / \sum_j e^{z_j}$$

## Backpropagation

### Chain Rule Application:

$$\partial L / \partial w^{(1)} = \partial L / \partial z^{(1)} \times \partial z^{(1)} / \partial w^{(1)}$$

### Error Propagation:

$$\delta^{(1)} = (w^{(1+1)})^T \delta^{(1+1)} \odot g'(z^{(1)})$$

- $\odot$ : element-wise multiplication

### Weight Update:

$$w^{(1)} = w^{(1)} - \alpha \times \delta^{(1)} (a^{(1-1)})^T$$

## Batch Normalization

### Normalization:

$$\hat{x}_i = (x_i - \mu_B) / \sqrt{(\sigma_B^2 + \epsilon)}$$

### Scale and Shift:

$$y_i = \gamma \hat{x}_i + \beta$$

- $\gamma, \beta$ : learnable parameters

## Dropout

### Training:

$$a^{(1)} = a^{(1)} \odot m^{(1)} / p$$

- $m^{(i)}$ : binary mask (Bernoulli(p))
  - p: keep probability
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## Clustering Mathematics

### K-Means

#### Objective Function:

$$J = \sum_{i=1}^n \sum_{k=1}^K r_{ik} \|x_i - \mu_k\|^2$$

- $r_{ik}$ : 1 if  $x_i$  belongs to cluster k, 0 otherwise

#### Update Rules:

$$\begin{aligned} \mu_k &= (\sum_i r_{ik} x_i) / (\sum_i r_{ik}) \quad (\text{centroid update}) \\ r_{ik} &= 1 \text{ if } k = \underset{j}{\operatorname{argmin}} \|x_i - \mu_j\|^2 \quad (\text{assignment}) \end{aligned}$$

### DBSCAN

#### Core Point:

$$|N_\epsilon(p)| \geq \text{minPts}$$

- $N_\epsilon(p) = \{q \in D \mid \text{dist}(p, q) \leq \epsilon\}$

#### Density-Reachable:

- p is reachable from q if there's a chain of core points

### Gaussian Mixture Models

#### Probability Model:

$$p(x) = \sum_{k=1}^K \pi_k \times N(x \mid \mu_k, \Sigma_k)$$

#### E-step (Expectation):

$$\gamma_{ik} = (\pi_k \times N(x_i | \mu_k, \Sigma_k)) / (\sum_j \pi_j \times N(x_i | \mu_j, \Sigma_j))$$

**M-step** (Maximization):

$$\pi_k = (1/n) \times \sum_i \gamma_{ik}$$

$$\mu_k = (\sum_i \gamma_{ik} x_i) / (\sum_i \gamma_{ik})$$

$$\Sigma_k = (\sum_i \gamma_{ik} (x_i - \mu_k)(x_i - \mu_k)^T) / (\sum_i \gamma_{ik})$$

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## Dimensionality Reduction Mathematics

### Principal Component Analysis (PCA)

**Objective:** Find projection that maximizes variance

**Covariance Matrix:**

$$C = (1/n) \times X^T X$$

**Eigendecomposition:**

$$C = V \Lambda V^T$$

- $V$ : eigenvectors (principal components)
- $\Lambda$ : eigenvalues (diagonal matrix)

**Projection:**

$$Z = X V_k$$

- $V_k$ : first  $k$  eigenvectors

**Reconstruction:**

$$\hat{X} = Z V_k^T$$

**Explained Variance Ratio:**

$$EVR = \lambda_i / \sum_j \lambda_j$$

### Linear Discriminant Analysis (LDA)

**Between-class Scatter:**

$$S_B = \sum_k n_k (\mu_k - \mu)(\mu_k - \mu)^T$$

### Within-class Scatter:

$$S_W = \sum_k \sum_{i \in C_k} (x_i - \mu_k)(x_i - \mu_k)^T$$

### Objective:

$$\text{maximize: } (w^T S_B w) / (w^T S_W w)$$

**Solution:** Eigenvectors of  $S_W^{-1} S_B$

## t-SNE

### Joint Probability (High-dimensional):

$$p_{i,j} = (p_{j|i} + p_{i|j}) / (2n)$$

where:

$$p_{j|i} = \exp(-||x_i - x_j||^2 / (2\sigma_i^2)) / \sum_{k \neq i} \exp(-||x_i - x_k||^2 / (2\sigma_i^2))$$

### Joint Probability (Low-dimensional):

$$q_{i,j} = (1 + ||y_i - y_j||^2)^{-1} / \sum_{k \neq i} (1 + ||y_i - y_k||^2)^{-1}$$

### Cost Function (KL divergence):

$$C = KL(P||Q) = \sum_i \sum_j p_{i,j} \log(p_{i,j}/q_{i,j})$$

## Evaluation Metrics Mathematics

### Classification Metrics

#### Confusion Matrix Elements:

- TP: True Positives
- TN: True Negatives
- FP: False Positives
- FN: False Negatives



## Accuracy:

$$\text{Accuracy} = (TP + TN) / (TP + TN + FP + FN)$$

## Precision:

$$\text{Precision} = TP / (TP + FP)$$

## Recall (Sensitivity, True Positive Rate):

$$\text{Recall} = TP / (TP + FN)$$

## Specificity (True Negative Rate):

$$\text{Specificity} = TN / (TN + FP)$$

## F1 Score:

$$F1 = 2 \times (\text{Precision} \times \text{Recall}) / (\text{Precision} + \text{Recall})$$

## F-beta Score:

$$F\beta = (1 + \beta^2) \times (\text{Precision} \times \text{Recall}) / ((\beta^2 \times \text{Precision}) + \text{Recall})$$

## Matthews Correlation Coefficient:

$$MCC = (TP \times TN - FP \times FN) / \sqrt{(TP + FP)(TP + FN)(TN + FP)(TN + FN)}$$

## ROC and AUC

**ROC Curve:** Plot of TPR vs FPR at various thresholds

**AUC** (Area Under ROC Curve):

$$AUC = \int_0^1 TPR(FPR) \, dFPR$$

**Approximation** (Trapezoidal Rule):

$$AUC \approx \sum_i \frac{1}{2} (TPR_i + TPR_{i+1}) (FPR_{i+1} - FPR_i)$$

## Regression Metrics

## **R<sup>2</sup> Score** (Coefficient of Determination):

$$R^2 = 1 - (SS_{\text{res}}/SS_{\text{tot}})$$

where:

$$SS_{\text{res}} = \sum_i (y_i - \hat{y}_i)^2 \quad (\text{residual sum of squares})$$

$$SS_{\text{tot}} = \sum_i (y_i - \bar{y})^2 \quad (\text{total sum of squares})$$

## **Adjusted R<sup>2</sup>:**

$$R^2_{\text{adj}} = 1 - [(1-R^2)(n-1)/(n-p-1)]$$

- p: number of predictors

## **Mean Absolute Percentage Error (MAPE):**

$$\text{MAPE} = (100/n) \times \sum_i |y_i - \hat{y}_i| / |y_i|$$

## **Clustering Metrics**

### **Silhouette Score:**

$$s(i) = (b(i) - a(i)) / \max(a(i), b(i))$$

where:

- a(i): average distance to points in same cluster
- b(i): minimum average distance to points in other clusters

### **Davies-Bouldin Index:**

$$DB = (1/k) \times \sum_{i=1}^k \max_{j \neq i} [(\sigma_i + \sigma_j) / d(c_i, c_j)]$$

- $\sigma_i$ : average distance of points in cluster i to centroid
- $d(c_i, c_j)$ : distance between centroids

### **Calinski-Harabasz Index:**

$$CH = [\text{tr}(B_k) / (k-1)] / [\text{tr}(W_k) / (n-k)]$$

- $B_k$ : between-group dispersion matrix

- $W_k$ : within-group dispersion matrix
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## Additional Important Formulas

### Regularization

**Elastic Net** ( $L1 + L2$ ):

$$J(\theta) = L(\theta) + \lambda_1 ||\theta||_1 + \lambda_2 ||\theta||_2^2$$

### Distance Metrics

**Euclidean Distance:**

$$d(x, y) = \sqrt{\sum_i (x_i - y_i)^2}$$

**Manhattan Distance:**

$$d(x, y) = \sum_i |x_i - y_i|$$

**Cosine Similarity:**

$$\cos(x, y) = (x \cdot y) / (||x||_2 \times ||y||_2)$$

**Minkowski Distance:**

$$d(x, y) = (\sum_i |x_i - y_i|^p)^{1/p}$$

### Bias-Variance Decomposition

**Total Error:**

$$E[(y - \hat{y})^2] = \text{Bias}^2 + \text{Variance} + \text{Irreducible Error}$$

where:

$$\text{Bias} = E[\hat{y}] - y$$

$$\text{Variance} = E[(\hat{y} - E[\hat{y}])^2]$$

### Cross-Validation Error

**k-Fold CV Error:**

$$CV(k) = (1/k) \times \sum_{i=1}^k L(h_i, D_i)$$

- $h_i$ : model trained on all folds except  $i$
- $D_i$ : validation data from fold  $i$