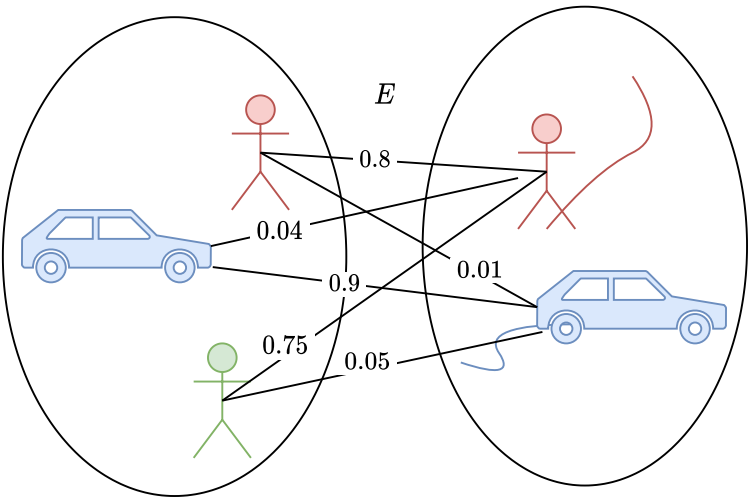


$U_{detections}$ V_{tracks} E 

$$G = (U_{detections}, V_{tracks}, E)$$