

Intro to 1D rootfinding

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Chapter 2 covers 1D root-finding and fixed-point equations,
aka zeros

i.e., solving a single scalar equation $f(x)=0$ ← why 0? just a convention to solve $f(x)=13$,
define $g(x)=f(x)-13$
and solve $g(x)=0$

Ex

Our country produces $(\cos(\pi \cdot \frac{t}{12}) + 1) \cdot e^{-0.1 \cdot t}$
amount of CO_2 per year (t is in years)

How long before we produce 500 amount of CO_2 ?

Solve $(\cos(\dots) + 1) e^{-0.1t} - 500 = 0$

Ex

Find the minimum of $g(x) = 2x^4 - 3x^3 + x^2 - x + 5$

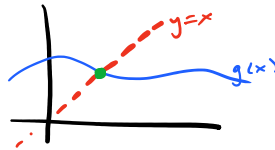
set $g'(x) = 0$
call this $f(x)$

* solving polynomial root-finding has special methods that are better than the generic methods in this chapter



Fixed-pt. equations

$g(x) = x$



A root-finding problem in disguise!

$g(x) - x = 0$
 $f(x)$

(...and vice versa: $f(x) = 0$

iff $-c \cdot f(x) = 0$ ($c \neq 0$)

iff $x - c \cdot f(x) = x$

$g(x)$... a fixed-pt. problem)

choose c wisely!

Big Picture

1D rootfinding is easy, not many new developments in past 100 years.

TL;DR ... in Matlab, use **fzero** (combination of bisection, secant, inverse quad. interpolation)

in Python, use **Scipy.optimize.root_scalar** (you can choose

Brent's, bisection, Newton, secant, etc.)

(fsolve is deprecated)

Solving Equations

	linear	non-linear
scalar	Trivial $3x=2$	Easy. Ch. 2 $(\tan^{-1}(x))^2 = x^{1/3}$
multi-dimensional	OK! Ch. 6 $3x+4y=2$ $2x-5y=5$	Challenging, active research (many special cases)

* laptop can solve
 10^4 equations in a
 few seconds,
 but 10^5 is tricky

Solving linear equations (multi-dimensional) is one of
 the most common scientific computing operations
 We're good at doing it, so we try to exploit it
 when possible, i.e., linearizing nonlinear systems

Justification that 1D root finding is a "static" (old-school) topic

First edition of Burden & Faires is about 40 yrs ago.

ie. Newton
 Raphson } all 1600's
 Gregory

Let's say computers are now 1,000 times faster
 (not exactly, but 1000 is a nice number)

Method

- Find a root on an interval
 $[a, b]$, w/ accuracy ϵ ,
 using **bisection**

1980

$[0, 2]$
 accuracy ϵ

2020

either accuracy ϵ on interval $[0, 2^{\overbrace{1000}^{\approx 10^{300}}}]$
 or interval $[0, 2]$ and accuracy $\epsilon/2^{1000}$
Nice!

- Find a root via **Newton's method**
 e.g., error
 $e_n = (0.99999)^{2^n}$

$n = 10$
 error is
 $e_{10} \approx 3 \cdot 10^{-5}$

$n = 10,000$
 error is $< 10^{-300}$
 (cannot compute error expression due to
 underflow! Even for $n = 100$) Nice!

- Find a root by making a
grid and checking each pt.

$[0, 1]$ interval
 accuracy ϵ

either accuracy ϵ on interval $[0, 1000]$
 or interval $[0, 1]$ w/ accuracy $\epsilon/1000$.
Not bad

= In comparison, linear or nonlinear problems
 in high dimensions are still active topics
 of research. Why? We need algorithms, not just computer power =

- Solve n linear equations
 with n variables

n

$10 \cdot n$

Not good
 (recall we have 1,000x speed)

- Find a max or min or root
 by making a **grid** in
 dimension d

$d = 3$, $[0, 1]^3$

$[0, 10]^3$

Not good

$d = 100$, $[0, 1]^{100}$

$[0, 1.07]^{100}$

Terrible --- barely
 noticeable difference

1D rootfinding research/innovation essentially stopped
 after Brent's 1973 book

Bottomline:

1D root-finding is easy

Why teach it? (you'll never need to implement it yourself)

- Basis for more complicated algorithms
- Classical
- Illustrates concepts like rate of convergence