Adaptive Integration

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Sunday, October 11, 2020 5:39 PM
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This is ch 4.6 in Burden + Faires, but we'll follow ch 5.7 in Driscoll and Braun Alg. 4.3 is hard to follow

Idea:

Software puekages (Mathematica's NIntegrate

Mathables integral (vs "tropz")

Rython's scripy integrate good)

are not going to ask the user for # nodes, instead they're going to ask for an accuracy (w/ a sensible default)

How can we do this?

Key Mathematical idea: a posteriori error estimate

"a primi" vs "a posteriori" come up a lot in other subjects too, so let's review them: a priori = estimate before you've done work

- + always rated
- may require knowledge you don't have
- can't exploit it when you get lucky, it's always pessionstre

Ex: Simpsun's Rule $\int_{c}^{b} f(x)dx = \frac{h}{3} \left(f(x_0) + \frac{h}{4} f(x_1) + f(x_2) \right) - \frac{h^5}{90} f^{(4)}(5)$ for some $\frac{h}{3} e^{(a,b)}$, $\frac{h}{4} = \frac{b-a}{3}$

a posteriori = estimate after you've done work

- + sometimes easiler, sometimes mere useful (no unknown things involver)
- + can adapt to your specific situation, and it takes
 it into account if you got lucky
- not useful for prediction or planning, only useful for verifying/certifying
- in some cases (like for our usage in integration)
 it is a heuristic or based on unverifiable assumptions.

so, let's make an a posteriori error estimate for integration,

ie, a practical way to evaluate the error, so we know when we have enough nodes

Start w/ composite Simpson's rule (though you could do a similar derivation for other rules)

Write S(n) to be Simpson's rule w/ n nodes, or S(h)

Recall non-composite Simpson has error $-\frac{h^5}{90}f^{(4)}(\xi)$ (h= $\frac{b-a}{2}$) $\xi \in (a,b)$

and composite simpson has error $-\frac{b-a}{180}h^{4}f^{(4)}(\eta)$ $\eta \in (a,b)$

So composite Simpson's Rule 13 O(N4) = O(n-4)

Apply Richardson extrapolation $R(h/z) = S(h/z) + \frac{S(h/z) - S(h)}{15 = 4^{4} - 1}$ $R(2n) = S(2n) + \frac{S(2n) - S(n)}{15}$

Assumption: R(2n) is so much more accurate than S(2n) that the error in R(2n) is negligible, and so

$$E = \int_{a}^{b} f(x)dx - S(2n) \approx R(2n) - S(2n)$$
our a posteriori en estimate
$$= \left| S(2n) - S(n) \right| = \hat{E}$$

So, basic strategy: double # of n until | Ê | is small.

Details:

- How small should |ê| be? ie-, pick a tolerance "tol" and require |ê| < tol?

 well, it often makes sense to ask for a relative error.

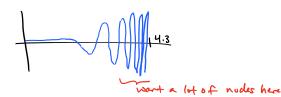
 In practice, we usually do both!

 Stop when |ê| < tol_absolute + tol_clative S(n)
- Doubling is going to lead to a lot of nodes very quickly.

 Observation: we often don't need dense nodes everywhere.

Ex: $\int_{0}^{100} e^{-x} dx$ don't need many nodes here since integrand is so small

 $E \times : \int (x) = (x+1)^2 \cos\left(-\frac{2x+1}{x-4}, \frac{2x+1}{x}\right)$



ie, we want to be ADAPTIVE

A rice, popular way to do this is Divide and Conquer (this is a general class of techniques beyond Idea: just integration)

- 1) estimate ê and Stop it lêl is small enough
- 2) Split [a,b] in tues, (a,c] and [c,b] where c= a+5

note that $\int_{a}^{b} f(x) dx = \int_{a}^{c} f(x) dx + \int_{a}^{b} f(x) dx$

Recurse, integrating on [a,c] and estimating its error = left and on [c,b] and estimately its error Emil

That's the basic idea.

Usually, we use composite Simpson's rule by N=4, and are coreful to reuse any f(node) computations. See pseudocode

FUNCTION Adaptive Integration (f, a, b, tolass, tolas)

return I, nodes = Recursive Integral (a, fla), b, flb), c, flc)) // and, implicitly, tolabs, toland

Recursive Integral (a, fla), b, flb), c, fl() FUNCTION

$$X_{left} = \frac{a+c}{2}$$
 $X_{right} = \frac{c+b}{2}$
 $X_{left} = \frac{x_{night}}{2}$
 $X_{left} = \frac{x_{night}}{2}$

$$X_{right} = \frac{c+b}{2}$$

nodes = { a, x, eft, c, x, my, b}

$$S_2 = \frac{h}{3} \left(f(a) + 4f(c) + f(b) \right) // regular (non-composite) Simpson's rule$$

11 often use 110 instead of 115 to be more conservative

return Sy, nodes

else

11 error is too love. So hiseet

$$\hat{T}_{left}$$
, nodes left = Recursine Integral (a, f(a), c, f(c), x_{left} , $f(x_{left})$)

 \hat{T}_{right} , nodes right = Recursine Integral (c, f(c), b, f(b), x_{right} , $f(x_{right})$)

return $\hat{T}_{left} + \hat{T}_{right}$, nodes left U nodes right // as lists, the first entry in nodes right is a duplicate of last entry in nodes left

Summan

All professional integration puckages are adaptive so

- (1) they don't waste time where extra nodes aren't needed
- @ they automortically generate nodes until a tolerance is reached, and give a (heuristre) "guarantee" on the final error.