Time-rEversed diffusioN tEnsor Transformer: A new TENET of Few-Shot Object Detection

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Abstract. In this paper, we tackle the challenging problem of Few-shot Object Detection. Existing FSOD pipelines (i) use average-pooled representations that result in information loss; and/or (ii) discard position information that can help detect object instances. Consequently, such pipelines are sensitive to large intra-class appearance and geometric variations between support and query images. To address these drawbacks, we propose a Time-rEversed diffusion tensor Transformer (TENET), which i) forms high-order tensor representations that capture multi-way feature occurrences that are highly discriminative, and ii) uses a transformer that dynamically extracts correlations between the query image and the entire support set, instead of a single average-pooled support embedding. We also propose a Transformer Relation Head (TRH), equipped with higher-order representations, which encodes correlations between query regions and the entire support set, while being sensitive to the positional variability of object instances. Our model achieves state-ofthe-art results on PASCAL VOC, FSOD, and COCO.

Keywords: few-shot object detection; transformer; multiple order pooling; high order pooling; heat diffusion process;

1 Introduction

Object detectors based on deep learning, usually addressed by supervised models, achieve impressive performance [31,32,33,8,27,13] but they rely on a large number of images with human-annotated class labels/object bounding boxes. Moreover, object detectors cannot be easily extended to new class concepts not seen during training. Such a restriction limits supervised object detectors to predefined scenarios. In contrast, humans excel at rapidly adapting to new scenarios by "storing knowledge gained while solving one problem and applying it to a different but related problem" [40], also called as "transfer of practice" [41].

Few-shot Object Detection (FSOD) [4,11,12,45,7,50,51] methods mimic this ability, and enable detection of test classes that are disjoint from training classes.

^{*} SZ was mainly in charge of the pipeline/developing the transformer. PK (corresponding author) was mainly in charge of mathematical design of TENET & TSO.

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Code: https://github.com/ZS123-lang/TENET.

They perform this adaptation using a few "support" images from test classes. Successful FSOD models must (i) find promising candidate regions-of-Interest (RoIs) in query images; and (ii) accurately regress bounding box locations and predict RoI classes, under large intra-class geometric and photometric variations.

To address the first requirement, approaches [45,7,50,51] use the region proposal network [33]. For example, FSOD-ARPN [7], PNSD [50] and KFSOD [51] cross-correlate query feature maps with a class prototype formed from average-pooled (ie., first-order) features, second-order pooled representations and kernel-pooled representations, respectively. These methods use a single class prototype which limits their ability to leverage diverse information from different class samples. Inspired by Transformers [38], approach [23] uses average pooling over support feature maps to generate a vector descriptor per map. Attention mechanism is then used to modulate query image features using such descriptors.

The above methods rely on first- and second-order pooling, while so-called higher-order pooling is more discriminative [17,18,15]. Thus, we propose a non-trivial Time-rEversed diffusion tEnsor Transformer (TENET). With TENET, higher-order tensors undergo a time-reversed heat diffusion to condense signal on super-diagonals of tensors, after which coefficients of these super-diagonals are passed to a Multi-Head Attention transformer block. TENET performs second, third- and fourth-order pooling. However, higher-order pooling suffers from several issues, ie., (i) high computational complexity of computing tensors with three/more modes, (ii) non-robust tensor estimates due to the limited number of vectors being aggregated, and (iii) tensor burstiness[17].

To this end, we propose a Tensor Shrinkage Operator (TSO) which generalizes spectral power normalization (SPN) operators [18], such as the Fast Spectral MaxExp operator (MaxExp(F)) [18], to higher-order tensors. As such, it can be used to reduce tensor burstiness. Moreover, by building on the linear algebra of the heat diffusion process (HDP) [34] and recent generalisation of HDP to SPN operators [18], we also argue that such operators can reverse the diffusion of signal in autocorrelation or covariance matrices, and high-order tensors, instead of just reducing the burstiness. Using a parametrization which lets us control the reversal of diffusion, TSO condenses signal captured by a tensor toward its super-diagonal, preserving information along it. This super-diagonal serves as our final representation, reducing the feature size from d^r to d, making our representation computationally tractable. Finally, shrinkage operators are known for their ability to estimate covariances well when only a small number of samples are available [22]. To the best of our knowledge, we are the first to show that MaxExp(F) is a shrinkage operator, and to propose TSO for orders $r \ge 2$.

To address the second requirement, FSOD-ARPN introduces a multi-relation head that captures global, local and patch relations between support and query objects, while PNSD passes second-order autocorrelation matrices to a similarity network. However, FSOD-ARPN and PNSD do not model spatial relations [9]. The QSAM [23] uses attention to highlight the query RoI vectors that are similar to the set of support vectors (obtained using only first-order spatial average pooling). Thus, we introduce a Transformer Relation Head (TRH) to

improve modeling of spatial relations. TRH computes self-attention between spatially-aware features and global spatially invariant first-, second- and higher-order TENET representations of support and/or query RoI features. The second attention mechanism of TRH performs cross-attention between Z support embeddings (for Z-shot if $Z \ge 2$), and a set of global representations of query RoIs. This attention encodes similarities between query RoIs and support samples.

Our FSOD pipeline contains TENET Region Proposal Network (TENET RPN) and the TRH, both equipped with discriminative TENET representations, improving generation of RoI proposals and modeling of query-support relations.

Below are our contributions:

- i. We propose a Time-rEversed diffusiON tEnsor Transformer, called TENET, which captures high-order patterns (multi-way feature cooccurrences) and decorrelates them/reduces tensor burstiness. To this end, we generalize the MaxExp(F) operator [18] for autocorrelation/covariance matrices to higher-order tensors by introducing the so-called Tensor Shrinkage Operator (TSO).
- ii. We propose a Transformer Relation Head (TRH) that is sensitive both to the variability between the Z support samples provided in a Z-shot scenario, and to positional variability between support and query objects.
- iii. In §4.1, we demonstrate that TSO emerges from the MLE-style minimization over the Kullback-Leibler (KL) divergence between the input and output spectrum, with the latter being regularized by the Tsallis entropy [2]. Thus, we show that TSO meets the definition of shrinkage estimator whose target is the identity matrix (tensor).

Our proposed method outperforms the state of the art on novel classes by 4.0%, 4.7% and 6.1% mAP on PASCAL VOC 2007, FSOD, and COCO respectively.

2 Related Works

Below, we review FSOD models and vision transformers, followed by a discussion on feature grouping, tensor descriptors and spectral power normalization.

Few-shot Object Detection. A Low-Shot Transfer Detector (LSTD) [4] leverages rich source domain to construct a target domain detector with few training samples but needs to be fine-tuned to novel categories. Meta-learning-based approach [45] reweights RoI features in the detection head without fine-tuning. Similarly, MPSR [43] deals with scale invariance by ensuring the detector is trained over multiple scales of positive samples. NP-RepMet [46] introduces a negative- and positive-representative learning framework via triplet losses that bootstrap the classifier. FSOD-ARPN [7] is a general FSOD network equipped with a channel-wise attention mechanism and multi-relation detector that scores pair-wise object similarity in both the RPN and the detection head, inspired by Faster R-CNN. PNSD [50], inspired by FSOD-ARPN [7], uses contraction of second-order autocorrelation matrix against query feature maps to produce attention maps. Single-prototype (per class) methods suffer information loss.

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Per-sample Prototype FSOD [23] uses the entire support set to form prototypes of a class but it ignores spatial information within regions. Thus, we employ TENET RPN and TRH to capture spatial and high-order patterns, and extract correlations between the query image and the Z-shot support samples for a class.

Transformers in Vision. Transformers, popular in natural language processing [38], have also become popular in computer vision. Pioneering works such as ViT [9] show that transformers can achieve the state of the art in image recognition. DETR [3] is an end-to-end object detection framework with a transformer encoder-decoder used on top of backbone. Its deformable variant [52] improves the performance/training efficiency. SOFT [29], the SoftMax-free transformer approximates the self-attention kernel by replacing the SoftMax function with Radial Basis Function (RBF), achieving linear complexity. In contrast, our TENET is concerned with reversing the diffusion of signal in high-order tensors via the shrinkage operation, with the goal of modeling spatially invariant high-order statistics of regions. Our attention unit, so-called Spatial-HOP in TRH, also uses RBF to capture correlations of between spatial and high-order descriptors.

Multi-path and Groups of Feature Maps. GoogleNet [36] has shown that multi-path representations (several network branches) lead to classification improvements. ResNeXt [44] adopts group convolution [20] in the ResNet bottleneck block. SK-Net [25], based on SE-Net [10], uses feature map attention across two network branches. However, these approaches do not model feature statistics. ReDRO [30] samples groups of features to apply the matrix square root over submatrices to improve the computational speed. In contrast, TENET forms fixed groups of features to form second-, third- and fourth-order tensors (simply using groups of features to form second-order matrices is not effective).

Second-order Pooling (SOP). Region Covariance Descriptors for texture [37] and object recognition [17] use SOP. Approach [19] uses spectral pooling for fine-grained image classification, whereas SoSN [48] and its variants [47,49] leverage SOP and element-wise Power Normalization (PN) [17] for end-to-end few-shot learning. In contrast, we develop a multi-object few-shot detector. Similarly to SoSN, PNSD [50] uses SOP with PN as representations which are passed to the detection head. So-HoT [14] that uses high-order tensors for domain adaptation is also somewhat related to TENET but So-HoT uses multiple polynomial kernel matrices, whereas we apply TSO to achieve decorrelation and shrinkage. TENET without TSO reduces to polynomial feature maps and performs poorly.

Power Normalization (PN). Burstiness is "the property that a given visual element appears more times in an image than a statistically independent model would predict". PN [16] limits the burstiness of first- and second-order statistics due to the binomial PMF-based feature detection factoring out feature counts [16,17,19]. Element-wise MaxExp pooling [16] gives likelihood of "at least one particular visual word being present in an image", whereas SigmE pooling [19] is its practical approximation. Noteworthy are recent Fast Spectral MaxExp operator, MaxExp(F) [18], which reverses the heat diffusion on the underlying loopy graph of second-order matrix to some desired past state [34], and Tensor Power-Euclidean (TPE) metric [15]. TPE alas uses the Higher Order Singular Value

Decomposition [21], which makes TPE intractable for millions of region proposals per dataset. Thus, we develop TENET and TSO, which reverses diffusion on high-order tensors by shrinking them towards the super-diagonal of tensor.

3 Background

Below, we detail notations and show how to calculate multiple higher-order statistics and Power Normalization, followed by revisiting the transformer block.

Notations. Let $\mathbf{x} \in \mathbb{R}^d$ be a d-dimensional feature vector. \mathcal{I}_N stands for the index set $\{1, 2, ..., N\}$. We define a vector of all-ones as $\mathbf{1} = [1, ..., 1]^T$. Let $\mathcal{X}^{(r)} = \uparrow \otimes_r \mathbf{x}$ denote a tensor of order r generated by the r-th order outer-product of \mathbf{x} , and $\mathcal{X}^{(r)} \in \mathbb{R}^{d \times d ... \times d}$. Typically, capitalised boldface symbols such as $\boldsymbol{\Phi}$ denote matrices, lowercase boldface symbols such as $\boldsymbol{\phi}$ denote vectors and regular case such as $\boldsymbol{\Phi}_{i,j}$, ϕ_i , n or Z denote scalars, e.g., $\boldsymbol{\Phi}_{i,j}$ is the (i,j)-th coefficient of $\boldsymbol{\phi}$.

High-order Tensor Descriptors (HoTD). Below we formalize HoTD [14].

Proposition 1. Let $\Phi \equiv [\phi_1, ..., \phi_N] \in \mathbb{R}^{d \times N}$ and $\Phi' \equiv [\phi'_1, ..., \phi'_M] \in \mathbb{R}^{d \times M}$ be feature vectors extracted from some two image regions. Let $\mathbf{w} \in \mathbb{R}^N_+$, $\mathbf{w}' \in \mathbb{R}^M_+$ be some non-negative weights and $\boldsymbol{\mu}, \boldsymbol{\mu}' \in \mathbb{R}^d$ be the mean vectors of $\boldsymbol{\Phi}$ and $\boldsymbol{\Phi}'$, respectively. A linearization of the sum of polynomial kernels of degree r,

$$\left\langle \mathcal{M}^{(r)}(\boldsymbol{\Phi};\boldsymbol{w},\boldsymbol{\mu}),\,\mathcal{M}^{(r)}(\boldsymbol{\Phi}';\boldsymbol{w}',\boldsymbol{\mu}')\right\rangle = \frac{1}{NM}\sum_{n=1}^{N}\sum_{m=1}^{M}w_{n}^{r}w_{m}'^{r}\left\langle \boldsymbol{\phi}_{n} - \boldsymbol{\mu}, \boldsymbol{\phi}'_{m} - \boldsymbol{\mu}'\right\rangle^{r},\,\,(1)$$

yields the tensor feature map

$$\mathcal{M}^{(r)}(\boldsymbol{\Phi};\boldsymbol{w},\boldsymbol{\mu}) = \frac{1}{N} \sum_{n=1}^{N} w_n^r \uparrow \otimes_r (\boldsymbol{\phi}_n - \boldsymbol{\mu}) \in \mathbb{R}^{d \times d \dots \times d}.$$
 (2)

In our paper, we set w = w' = 1 and $\mu = \mu' = 0$, whereas orders r = 2, 3, 4.

(Eigenvalue) Power Normalization ((E)PN). For second-order matrices, MaxExp(F), a state-of-the-art EPN [18], is defined as

$$g(\lambda;\eta) = 1 - (1-\lambda)^{\eta} \tag{3}$$

on the ℓ_1 -norm normalized spectrum from SVD $(\lambda_i := \lambda_i/(\varepsilon + \sum_{i'} \lambda_{i'}))$, and on symmetric positive semi-definite matrices as

$$\widehat{\boldsymbol{\mathcal{G}}}_{\text{MaxExp}}(\boldsymbol{M}; \eta) = \mathbb{I} - (\mathbb{I} - \boldsymbol{M})^{\eta},$$
 (4)

where M is a trace-normalized matrix, ie., $M := M/(\varepsilon + \text{Tr}(M))$ with $\varepsilon \approx 1e-6$, and $\text{Tr}(\cdot)$ denotes the trace. The time-reversed heat diffusion process is adjusted by integer $\eta \geq 1$. The larger the value of η is, the more prominent the time reversal is. $\widehat{\mathcal{G}}_{\text{MaxExp}}$ is followed by the element-wise PN, called SigmE [18]:

$$G_{\text{SigmE}}(p; \eta') = 2/(1 + e^{-\eta' p}) - 1,$$
 (5)

where p takes each output coefficient of Eq. (4), $\eta' \ge 1$ controls detecting feature occurrence vs. feature counting trade-off.

Transformers. An architecture based on blocks of attention and MLP layers forms a transformer network [38]. Each attention layer takes as input a set of query, key and value matrices, denoted Q, K and V, respectively. Let $Q \equiv [\mathbf{q}_1,...,\mathbf{q}_N] \in \mathbb{R}^{d\times N}$, $K \equiv [\mathbf{k}_1,...,\mathbf{k}_N] \in \mathbb{R}^{d\times N}$, and $V \equiv [\mathbf{v}_1,...,\mathbf{v}_N] \in \mathbb{R}^{d\times N}$, where N is the number of input feature vectors, also called tokens, and d is the channel dimension. A generic attention layer can then be formulated as:

Attention
$$(Q, K, V) = \alpha(\gamma(Q, K))V^{T}$$
. (6)

Self-attention is composed of $\alpha(\gamma(\cdot, \cdot))$, $\alpha(\cdot)$ is a non-linearity and $\gamma(\cdot, \cdot)$ computes similarity. A popular choice is SoftMax with the scaled dot product [38]:

$$\alpha(\cdot) = \text{SoftMax}(\cdot) \text{ and } \gamma(\boldsymbol{Q}, \boldsymbol{K}) = \frac{\boldsymbol{Q}^T \boldsymbol{K}}{\sqrt{d}}.$$
 (7)

Note the LayerNorm and residual connections are added at the end of each block.

To facilitate the design of linear self-attention, approach [29] introduces a SoftMax-free transformer with the dot product replaced by the RBF kernel:

$$\alpha(\cdot) = \text{Exp}(\cdot) \text{ and } \gamma(\boldsymbol{Q}, \boldsymbol{K}) = -\frac{1}{2\sigma^2} \left[\|\mathbf{q}_i - \mathbf{k}_j\|_2^2 \right]_{i,j \in \mathcal{I}_N},$$
 (8)

where $[\cdot]$ stacks distances into a matrix, σ^2 is the kernel variance set by cross-validation, and \mathbf{q}_i and \mathbf{k}_i are ℓ_2 -norm normalized.

The Multi-Head Attention (MHA) layer uses T attention units whose outputs are concatenated. Such an attention splits input matrices Q, K, and V along their channel dimension d into T groups and computes attention on each group:

$$MHA(\mathbf{Q}, \mathbf{K}, \mathbf{V}) = [\mathbf{A}_1, \dots, \mathbf{A}_T], \tag{9}$$

where $[\cdot]$ performs concatenation along the channel mode, the m^{th} head is $\mathbf{A}_m = \operatorname{Attention}(\mathbf{Q}_m, \mathbf{K}_m, \mathbf{V}_m)$, and $\mathbf{Q}_m \in \mathbb{R}^{\frac{d}{T} \times N}$, $\mathbf{K}_m \in \mathbb{R}^{\frac{d}{T} \times N}$, and $\mathbf{V}_m \in \mathbb{R}^{\frac{d}{T} \times N}$.

4 Proposed Approach

Given a set of Z support crops $\{X_z\}_{z\in\mathcal{I}_Z}$ and a query image X^* per episode, our approach learns a matching function between representations of query RoIs and and support crops. Fig. 1 shows our pipeline comprised of three main modules:

- i. **Encoding Network** (EN) extracts feature map $\Phi \in \mathbb{R}^{d \times N}$ per image (of $N = W \times H$ spatial size) from query and support images via ResNet-50.
- ii. **TENET RPN** extracts RoIs from the query image and computes embeddings for the query RoIs and the support crops. Improved attention maps are obtained by T-Heads Attention (THA) that operates on TENET descriptors.
- iii. Transformer Relation Head captures relations between query and support features using self- and cross-attention mechanisms. This head produces representations for the classifier and bounding-box refinement regression loss.

Next, we describe TENET RPN, followed by the Transformer Relation Head.

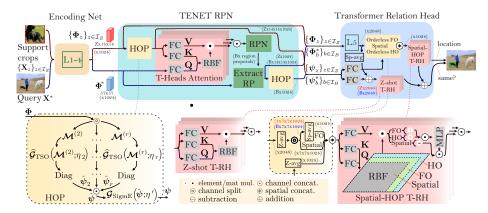


Fig. 1: Our pipeline. (top) We pass ground truth support crops $\{\mathcal{X}_z\}_{z\in\mathcal{I}_Z}$ for Z-shot problem and a query image \mathcal{X}^* to the Encoding Network (EN). The resulting convolutional feature maps, $\{\boldsymbol{\Phi}_z\}_{z\in\mathcal{I}_Z}$ for support and $\boldsymbol{\Phi}^*$ for query, are passed to the TENET-RPN module to produce a set of B descriptors $\{\boldsymbol{\Phi}_b^*\}_{b\in\mathcal{I}_B}$ for B Region Proposals (RP a.k.a. RoIs) of query image, and high-order pooled (HOP) representations for both support crops $\{\psi_z\}_{z\in\mathcal{I}_Z}$ and query image RoIs $\{\psi_b^*\}_{b\in\mathcal{I}_B}$. TENET contains HOP units which compute high-order tensor descriptors and then apply a novel tensor shrinkage operator to them, yielding spatially orderless HOP representations. Sets of features $\{\psi_z\}_{z\in\mathcal{I}_Z}$ and $\{\psi_b^*\}_{b\in\mathcal{I}_B}$ are then passed to the Transformer Relation Head (TRH), along with the convolutional features $\{\boldsymbol{\Phi}_z\}_{z\in\mathcal{I}_Z}$ and $\{\boldsymbol{\Phi}_b^*\}_{b\in\mathcal{I}_B}$. The TRH consists of Z-shot and Spatial-HOP transformer heads for measuring similarities across support regions and query proposals, and refining the localization of target objects, respectively. (bottom) Details of HOP, "Orderless FO, Spatial, Orderless HO", Z-shot T-RH and Spatial-HOP T-RH blocks. See §4.3 for details.

4.1 Extracting representations for support and query RoIs

Fig. 1 (top) shows our TENET RPN that produces embeddings and query RoIs. Central to this module is our HOP unit that produces Higher-order Tensor Descriptors (HoTDs). HOP splits features along the channel mode into multiple groups of feature maps, from which second-, third- and fourth- order tensors are aggregated over desired regions. HoTDs use a generalization of the MaxExp(F) to higher-order tensors, called the Tensor Shrinkage Operator (TSO).

Tensor Shrinkage Operator. Ledoit and Wolf [22] define autocorrelation/covariance matrix estimation as a trade-off between the sample matrix M and a highly structured operator F, using the linear combination $(1-\delta)M+\delta F$. For symmetric positive semi-definite matrices and tensors, one can devise a convex shrinkage operator by minimizing some divergence $d(\lambda, \lambda')$ between the source and target spectra, where λ' is regularized by $\Omega(\lambda')$ with weight $\delta \geq 0$:

$$\lambda^* = \underset{\lambda'>0}{\arg\min} d(\lambda, \lambda') + \delta \Omega(\lambda'). \tag{10}$$

Below we derive the TSO as a generalization of $MaxExp(F)^{1}$.

With $\widehat{\mathcal{G}}_{TSO}(\cdot)$ we extract representations $\hat{\psi}_r$ from HoTDs $\mathcal{M}^{(r)}$:

$$\widehat{\mathcal{G}}_{TSO}\left(\mathcal{M}^{(r)};\eta\right) = \mathcal{I}_r - \left(\mathcal{I}_r - \mathcal{M}^{(r)}\right)^{\eta},\tag{11}$$

$$\hat{\psi}_r = \text{Diag}\left(\widehat{\mathcal{G}}_{\text{TSO}}\left(\mathcal{M}^{(r)}; \eta_r\right)\right),$$
 (12)

$$\psi_r = \mathcal{G}_{\text{SigmE}}(\hat{\psi}_r; \eta_r'),$$
 (13)

where $\operatorname{Diag}(\cdot)$ extracts the super-diagonal of tensor. The identity tensor \mathcal{I}_r of order r is defined such that $\mathcal{I}_{1,\dots,1} = \mathcal{I}_{2,\dots,2} \dots = \mathcal{I}_{d,\dots,d} = 1$ and $\mathcal{I}_{i_1,\dots,i_r} = 0$ if $i_j \neq i_k$ and $j \neq k$, $j,k \in \mathcal{I}_r$.

Theorem 1. Let λ be the ℓ_1 -norm normalized spectrum, as in Eq. (3). Then $g(\lambda;\eta)=1-(1-\lambda)^{\eta}$ is a shrinkage operator as it is a solution to Eq. (10) if $\delta=\frac{\eta t^{1/\eta}}{s}(1-\frac{1}{\eta})$, and the Kullback-Leibler divergence and the Tsallis entropy are substituted for the divergence term d and the regularization term Ω , respectively. In the above theorem, $\lambda \in \mathbb{R}^d_+$, s=d-1, t=d-t' and t'>0 is the trace of $g(\lambda;\eta)$.

Proof. Let $d(\boldsymbol{\lambda}, \boldsymbol{\lambda}') = D_{\mathrm{KL}}(\boldsymbol{\lambda}^{\circ} || \boldsymbol{\lambda}^{\circ}') = -\left(\sum_{i \in \mathcal{I}_d} \lambda_i^{\circ} \log \lambda_i^{\circ}'\right) + \left(\sum_{i \in \mathcal{I}_d} \lambda_i^{\circ} \log \lambda_i^{\circ}\right)$, where

 $\lambda^{\circ} = \frac{1-\lambda}{s}$ and $\lambda^{\circ'} = \frac{1-\lambda'}{t}$ are complements of λ and λ' normalized by s = d-1 and t = d-t' to obtain normalized distributions to ensure valid use of the Kullback-Leibler divergence and the Tsallis entropy. Let $\Omega(\lambda'; \alpha) = \frac{1}{\alpha-1} (1 - \sum_{i \in \mathcal{I}_d} \lambda_i^{\circ'\alpha})$.

Define $f(\lambda, \lambda') = -\left(\sum_{i \in \mathcal{I}_d} \lambda_i^{\circ} \log \lambda_i^{\circ'}\right) + \left(\sum_{i \in \mathcal{I}_d} \lambda_i^{\circ} \log \lambda_i^{\circ}\right) + \frac{1}{\alpha - 1} \left(1 - \sum_{i \in \mathcal{I}_d} \lambda_i^{\circ' \alpha}\right)$ (following

Eq. (10)) which we minimize w.r.t. λ' by computing $\frac{\partial f}{\partial \lambda'_i} = 0$, that is,

$$\frac{\partial f}{\partial \lambda_i'} = 0 \Rightarrow \lambda_i' = 1 - t \left(\frac{\eta}{\delta s}\right)^{\eta} (1 - 1/\eta)^{\eta} (1 - \lambda_i)^{\eta}, \tag{14}$$

where $\frac{1}{\alpha} = \eta$. Solving $t \left(\frac{\eta}{\delta s} \right)^{\eta} (1 - \frac{1}{\eta})^{\eta} = 1$ for δ completes the proof.

Theorem 2. The highly structured operator F (target of shrinkage) equals \mathbb{I} .

Proof. Notice $\lim_{\eta \to \infty} 1 - (1 - \lambda_i)^{\eta} = 1$ if $\lambda \neq 0$ is the ℓ_1 -norm normalized spectrum from SVD, ie., $U\lambda U^T = M \succcurlyeq 0$ with $\lambda_i := \lambda_i/(\sum_{i'} \lambda_{i'} + \varepsilon)$, $\varepsilon > 0$. Thus, $UU^T = \mathbb{I}$.

Note $\mathcal{I}_r - (\mathcal{I}_r - \mathcal{M})^{\eta} \to \mathcal{I}_r$ if $\eta \to \infty$. Thus, for sufficiently large $1 \ll \eta \ll \infty$, the diffused heat reverses towards the super-diagonal, where the majority of the signal should concentrate. Thus, we limit the number of coefficients of feature representations by extracting the super-diagonals from the TSO-processed $\mathcal{M}^{(r)}$ as in Eq. 12, where r is the order of HoTD \mathcal{M} . In our experiments, r = 2, 3, 4.

For r=2, Eq. (12) yields $\operatorname{Diag}(\mathbb{I}-(\mathbb{I}-M)^{\eta_2})$. $\operatorname{Diag}(\operatorname{Sqrtm}(M))$ is its approximation.

Algorithm 1 Tensor Shrinkage Operator with Exponentiation by Squaring, left part for even orders and right part for odd orders r.

```
Input: \mathcal{M}, \eta \ge 1, r = 2, 4, ...
   1: \mathcal{M}_1^* = \mathcal{I}_r - \mathcal{M}, \ n = \text{int}(\eta), \ t = 1, \ q = 1
                                                                                                                           Input: \mathcal{M}, \eta = 3^0, 3^1, 3^2, ..., r = 3, 5, ...
   2: while n \neq 0:
                                                                                                                              1: \mathcal{M}_1^* = \mathcal{I}_r - \mathcal{M}, n = \operatorname{int}(\eta), q = 1
  3:
                   if n&1:
                                                                                                                              2: while n \neq 0:
   4:
                            if t > 1: G_{t+1} = G_t \times_{1,...,r/2} M_q^*,
                                                                                                                              3:
                                                                                                                                               n \leftarrow \operatorname{int}(n/3)
   5:
                            else: \mathcal{G}_{t+1} = \mathcal{M}_q^*
                                                                                                                              4:
                            n \leftarrow n-1, t \leftarrow t+1
   6:
                                                                                                                                                       \mathcal{M}_{q+1}^* = \mathcal{M}_q^* \times_{1,\dots,\lfloor r/2 \rfloor} \mathcal{M}_q^* \times_{1,\dots,\lceil r/2 \rceil} \mathcal{M}_q^* \times_{1,\dots,\lceil r/2 \rceil} \mathcal{M}_q^*
                                                                                                                              5:
   7:
                   n \leftarrow \operatorname{int}(n/2)
                                                                                                                              6:
  8:
                   if n > 0:
                            oldsymbol{\mathcal{M}}_{q+1}^* = oldsymbol{\mathcal{M}}_q^* 	imes_{1,...,r/2} oldsymbol{\mathcal{M}}_q^* q \leftarrow q + 1
                                                                                                                              7:
  9:
                                                                                                                           Output: \widehat{\mathcal{G}}_{TSO}(\mathcal{M}) = \mathcal{I}_r - \mathcal{M}_a^*
10:
Output: \widehat{\boldsymbol{\mathcal{G}}}_{TSO}(\mathcal{M}) = \boldsymbol{\mathcal{I}}_r - \boldsymbol{\mathcal{G}}_t
```

As super-diagonals contain information obtained by multiplying η times the complement $1-\lambda_i$ (spectral domain), TSO can be seen as $\eta-1$ aggregation steps along the tensor product mode(s). THus, we pass $\hat{\psi}_r$ via the element-wise SigmE from Eq. (5) (as in Eq. (13)) to detect the presence of at least one feature being detected in $\hat{\psi}_r$ after such an aggregation. For brevity, we drop subscript r of ψ_r . Complexity. For integers $\eta \geq 2$ and even orders $r \geq 2$, computing $\eta-1$ tensor-

tensor multiplications $(\mathcal{I}_r - \mathcal{M}^{(r)})^{\eta}$ has the complexity $\mathcal{O}(d^{\frac{3}{2}r}\eta)$. For odd orders $r \geq 3$, due to alternations between multiplications in $\lfloor \frac{r}{2} \rfloor$ and $\lceil \frac{r}{2} \rceil$ modes, the complexity is $\mathcal{O}(d^{\lfloor \frac{r}{2} \rfloor} d^{2 \lceil \frac{r}{2} \rceil} \eta) \approx \mathcal{O}(d^{\frac{3}{2}r}\eta)$. Thus, the complexity of Eq. (11) w.r.t. integer $\eta \geq 2$ scales linearly. However, for even orders r, one can readily replace $(\mathcal{I}_r - \mathcal{M}^{(r)})^{\eta}$ with exponentiation by squaring [1], whose cost is $\log(\eta)$. This readily yields the sublinear complexity $\mathcal{O}(d^{\frac{3}{2}r}\log(\eta))$ w.r.t. η .

Implementation of TSO. Algorithm 1 shows fast TSO for even/odd orders r. We restrict the odd variant to $r=3^0,3^1,3^2,...$ for brevity. Finally, we note that matrix-matrix and tensor multiplications with cuBLAS are highly parallelizable so the $d^{\frac{3}{2}r}$ part of complexity can be reduced in theory even to $\log(d)$.

TENET-RPN. To extract query RoIs, we firstly generate a set \mathcal{Z} of TSO representations $\boldsymbol{\Psi} \equiv \{\boldsymbol{\psi}_z\}_{z \in \mathcal{I}_Z}$ from the support images, with $Z = |\mathcal{Z}|$. We then perform cross-attention between $\boldsymbol{\Psi} \in \mathbb{R}^{d \times Z}$ and the N feature vectors $\boldsymbol{\Phi}^* \in \mathbb{R}^{d \times N}$ extracted from the query image. The attention input \boldsymbol{Q} is then generated from $\boldsymbol{\Phi}^*$, while \boldsymbol{K} and \boldsymbol{V} are both generated from $\boldsymbol{\Psi}$. The output of the transformer block in Eq. 6 is fed into an RPN layer to output a set $\boldsymbol{\mathcal{B}}$ of $B = |\boldsymbol{\mathcal{B}}|$ query RoIs.

Query RoIs are represented by spatially ordered features $\{\boldsymbol{\Phi}_b^*\}_{b\in\mathcal{I}_B}$ and TSO orderless features $\{\boldsymbol{\psi}_b^*\}_{b\in\mathcal{I}_B}$, passed to the Transformer Relation Head.

4.2 Transformer Relation Head

TRH, in Fig. 1, models relations between support crops and query RoIs. TSO representations are derived from features of layer 4 of ResNet-50, leading to a

channel dimension d=1024. Spatially ordered representations of support features $\{\boldsymbol{\Phi}_z \in \mathbb{R}^{2d \times N}\}_{z \in \mathcal{I}_Z}$ and query RoIs $\{\boldsymbol{\Phi}_b^* \in \mathbb{R}^{2d \times N}\}_{b \in \mathcal{I}_B}$ are both extracted from layer 5 of ResNet-50, leading to a channel dimension 2d=2048.

They are then fed into 2 different transformers: (i) a Z-shot transformer head, which performs cross-attention between globally-pooled representations of the query images and support images; and (ii) a Spatial-HOP transformer head, which performs self-attention between spatially ordered representations and spatially orderless high-order representations for a given image.

Z-shot transformer head consists of a cross-attention layer formed with:

$$\begin{pmatrix}
\mathbf{Q} \\
\mathbf{K} \\
\mathbf{V}
\end{pmatrix} = \begin{pmatrix}
[\mathbf{q}_{1}, ..., \mathbf{q}_{B}] \\
[\mathbf{k}_{1}, ..., \mathbf{k}_{Z}] \\
[\mathbf{v}_{1}, ..., \mathbf{v}_{Z}]
\end{pmatrix} \quad \text{where} \quad \begin{pmatrix}
\mathbf{q}_{b} \\
\mathbf{k}_{z} \\
\mathbf{v}_{z}
\end{pmatrix} = \begin{pmatrix}
\mathbf{W}^{(q)} (\bar{\phi}_{b}^{*} + \mathbf{W}^{(p)} \psi_{b}^{*}) \\
\mathbf{W}^{(k)} (\bar{\phi}_{z} + \mathbf{W}^{(p)} \psi_{z}) \\
\mathbf{W}^{(v)} (\bar{\phi}_{z} + \mathbf{W}^{(p)} \psi_{z})
\end{pmatrix}. (15)$$

Moreover, $\bar{\phi}_b^*$ and $\bar{\phi}_z$ are average-pooled features $\frac{1}{N} \boldsymbol{\Phi}_b^* \mathbf{1}$ and $\frac{1}{N} \boldsymbol{\Phi}_z \mathbf{1}$, respectively. The matrices $\boldsymbol{W}^{(q)} \in \mathbb{R}^{2d \times 2d}$, $\boldsymbol{W}^{(k)} \in \mathbb{R}^{2d \times 2d}$, $\boldsymbol{W}^{(v)} \in \mathbb{R}^{2d \times 2d}$, and $\boldsymbol{W}^{(p)} \in \mathbb{R}^{2d \times d}$ is a linear projection mixing spatially orderless TSO representations with spatially ordered representations. Thus, each attention query vector \mathbf{q}_b combines the extracted spatially orderless TSO representations with spatially ordered representations for a given query RoI. Similarly, each key vector \mathbf{k}_z and value vector \mathbf{v}_z combine such two types of representations for a support crop.

Spatial-HOP transformer head consists of a layer that performs self-attention on spatially orderless TSO representations and spatially ordered representations, extracted either from Z support crops, or B query RoIs. Below we take one support crop as an example. For the set \mathcal{Z} , we compute "Spatial", a spatially ordered Z-averaged representation $\Phi^{\dagger} = \frac{1}{Z} \sum_{z \in \mathcal{I}_Z} \Phi_z \in \mathbb{R}^{2d \times N}$. We also compute HO, a spatially orderless High-Order Z-pooled representation $\psi^{\dagger} = \frac{1}{Z} \sum_{z \in \mathcal{I}_Z} \psi_z \in \mathbb{R}^d$. We split Φ^{\dagger} along the channel mode of dimension 2d to create two new matrices $\Phi^{\dagger u} \in \mathbb{R}^{d \times N}$ and $\Phi^{\dagger l} \in \mathbb{R}^{d \times N}$. We set $\Phi^{\dagger l} = [\phi_1^{\dagger l}, ..., \phi_N^{\dagger l}] \in \mathbb{R}^d$. Also, we form FO (from $\Phi^{\dagger u}$), a spatially orderless First-Order Z-pooled representation. Self-attention is then performed over the matrix of token vectors:

$$\mathcal{T} = [\boldsymbol{\phi}_1^{\dagger l}, ..., \boldsymbol{\phi}_N^{\dagger l}, \bar{\boldsymbol{\phi}}^{\dagger u}, \boldsymbol{W}^{(g)} \boldsymbol{\psi}^{\dagger}], \tag{16}$$

where $\mathbf{W}^{(g)} \in \mathbb{R}^{d \times d}$ a linear projection for HO. \mathcal{T} is projected onto the query, key and value linear projections. Spatial-HOP attention captures relations among spatially-aware first-order and spatially orderless high-order representations. The outputs of Z-shot and Spatial-HOP transformer heads are combined and fed into the classifier/bounding-box regressor. See §B of Suppl. Material for details.

4.3 Pipeline Details (Figure 1 (bottom))

HOP unit uses \odot to split the channel mode into groups (e.g., 2:1:1) split means two parts of the channel dimension are used to form $\mathcal{M}^{(2)}$, one part to form $\mathcal{M}^{(3)}$, and one part to form $\mathcal{M}^{(4)}$). TSOs with parameters $\eta_2 = ... = \eta_r = \eta$ are applied for orders r = 2, ..., r, and diagonal entries are extracted from each tensor and concatenated by \odot . Element-wise SigmE with $\eta'_2 = ... = \eta'_r = \eta'$ is applied.

"Orderless FO, Spatial, Orderless HO" block combines the First-Order (FO), spatial and High-Order (HO) representations. Operator "Z-avg" performs average pooling along Z-way mode, operator "Sp-avg" performs average pooling along the spatial modes of feature maps, operator \odot simply splits the channel mode into two equally sized groups (each is half of the channel dimension), and operator \odot performs concatenation of FO, spatial and HO representations along the spatial mode of feature maps, e.q., we obtain N+2 fibers times 1024 channels.

Z-shot T-RH is a transformer which performs attention on individual Z-shots. The spatial representation Φ is average pooled along spatial dimensions by "Spave" and combined with high-order Ψ (passed by a FC layer) via addition \oplus . Another FC layer follows and subsequently the value, key and query matrices are computed, an RBF attention formed. Operator \bullet multiplies the value matrix with the RBF matrix. Head is repeated T times, outputs concatenated by \odot .

Spatial-HOP T-RH takes inputs from the "Orderless FO, Spatial, Orderless HO" block, and computes the value, key and query matrices. The attention matrix (RBF kernel) has $(N+2)\times(N+2)$ size, being composed of spatial, FO-spatial and HO-spatial attention. After multiplying the attention matrix with the value matrix, we extract the spatial, FO and HO representations. Support and query first-order representations (FO) (and high-order representations (HO)) are element-wisely multiplied by \bullet (multiplicative relationship). Finally, support and query spatial representations use the subtraction operator \ominus . After the concatenation of FO and HO relational representations by \odot , passing via an MLP (FC+ReLU+FC), and concatenation with the spatial relational representations, we get one attention block, repeated T times.

5 Experiments

Datasets and Settings . For PASCAL VOC 2007/12 [6], we adopt the 15/5 base/novel category split setting and use training/validation sets from PASCAL VOC 2007 and 2012 for training, and the testing set from PASCAL VOC 2007 for testing, following [11,7,50,23]. For MS COCO [28], we follow [45], and adopt the 20 categories that overlap with PASCAL VOC as the novel categories for testing, whereas the remaining 60 categories are used for training. For the FSOD dataset [7], we split its 1000 categories into 800/200 for training/testing.

Implementation Details. TENET uses ResNet-50 pre-trained on ImageNet [5] and MS COCO [28]. We fine-tune the network with a learning rate of 0.002 for the first 56000 iterations and 0.0002 for another 4000 iterations. Images are resized to 600 pixels (shorter edge) and the longer edge is capped at 1000 pixels. Each support image is cropped based on ground-truth boxes, bilinearly interpolated and padded to 320×320 pixels. We set, via cross-validation) SigmE parameter $\eta' = 200$ and TSO parameters $\eta_2 = \eta_3 = \eta_4 = 7$. We report standard metrics for FSOD, namely mAP, AP, AP, AP₅₀ and AP₇₅.

Method	/Shot		Spl	it 1			Split 2				Split 3				Me	ean	
	,	1	3	5	10	1	3	5	10	1	3	5	10	1	3	5	10
FRCN	ICCV12	11.9	29.0	36.9	36.9	5.9	23.4	29.1	28.8	5.0	18.1	30.8	43.4	7.6	23.5	32.3	36.4
FR	ICCV19	14.8	26.7	33.9	47.2	15.7	22.7	30.1	39.2	19.2	25.7	40.6	41.3	16.6	25.0	34.9	42.6
Meta	ICCV19	19.9	35.0	45.7	51.5	10.4	29.6	34.8	45.4	14.3	27.5	41.2	48.1	14.9	30.7	40.6	48.3
FSOD	CVPR20	29.8	36.3	48.4	53.6	22.2	25.2	31.2	39.7	24.3	34.4	47.1	50.4	25.4	32.0	42.2	47.9
NP-RepMet	NeurIPS20	37.8	41.7	47.3	49.4	41.6	43.4	47.4	49.1	33.3	39.8	41.5	44.8	37.6	41.6	45.4	47.8
PNSD Î	ACCV20	32.4	39.6	50.2	55.1	30.2	30.3	36.4	42.3	30.8	38.6	46.9	52.4	31.3	36.2	44.5	49.9
MPSR	ECCV20												49.7				
TFA	ICML20	39.8	44.7	55.7	56.0	23.5	34.1	35.1	39.1	30.8	42.8	49.5	49.8	31.4	40.5	46.8	48.3
FSCE	CVPR21	44.2	51.4	61.9	63.4	27.3	43.5	44.2	50.2	22.6	39.5	47.3	54.0	31.4	44.8	51.1	55.9
CGDP+FRCN		40.7	46.5	57.4	62.4	27.3	40.8	42.7	46.3	31.2	43.7	50.1	55.6	33.1	43.7	50.0	54.8
TIP	CVPR21	27.7	43.3	50.2	56.6	22.7	33.8	40.9	46.9	21.7	38.1	44.5	50.9	24.0	38.4	45.2	52.5
$FSOD^{up}$	ICCV21	43.8	50.3	55.4	61.7	31.2	41.2	44.2	48.3	35.5	43.9	50.6	53.5	36.8	45.1	50.1	54.5
QSAM	WACV22	31.1	39.2	50.7	59.4	22.9	32.1	35.4	42.7	24.3	35.0	50.0	53.6	26.1	35.4	45.4	51.9
TENET	(Ours)	46.7	55.4	62.3	66.9	40.3	44.7	49.3	52.1	35.5	46.0	54.4	54.6	40.8	48.7	55.3	57.9

Table 1: Evaluations (mAP %) on three splits of the VOC 2007 testing set.

Table 2: Evaluations on the MS COCO minival set (2a) and FSOD testset (2b).

Shot	Metho	d	AP	AP_{50}	AP_{75}	Shot	Me	thod	AP_{50}	AP_{75}
10	LSTD FR Meta MPSR FSOD PNSD TFA FSCE CGDP+FRCN FSOD ^{up} OSAM	AAAI18 ICCV12 ICCV19 ECCV20 CVPR20 ACCV20 ICML20 CVPR21 CVPR21 ICCV21 WACV22	3.2 5.6 8.7 9.8 11.1 12.3 9.6 10.7 11.3 11.6	23.9	2.1 4.6 6.6 9.7 10.6 11.7 9.3 10.5 11.5 9.8	5	LSTD (FRN) LSTD FSOD PNSD QSAM	AAAI18 AAAI18 CVPR20 ACCV20 WACV22	23.0 24.2 27.5 29.8 30.7	12.9 13.5 19.4 22.6 25.9
	TENET	(Ours)		27.4			TENET	(Ours)	35.4	31.6
		(a)						(b)		

5.1 Comparisons with the State of the Art

PASCAL VOC 2007/12. We compare our method to QSAM[23], FSOD^{up} [42], CGDP+FRCN [26], TIP [24], FSCE [35], TFA [39], Feature Reweighting (FR) [11], LSTD [4], FRCN [33], NP-RepMet [46], MPSR[43], PSND [50] and FSOD [7]. Table 1 shows that our TENET outperforms FSOD by a 7.1−15.4% margin. For the 1- and 10-shot regime, we outperform QSAM [23] by ∼14.7%.

MS COCO. Table 2a compares TENET with QSAM[23], FSOD^{up} [42], CGDP+FRCN [26], TIP [24], FSCE [35], TFA [39], FR [11], Meta R-CNN [45], FSOD [7] and PNSD[50] on the MS COCO minival set (20 novel categories, 10-shot protocol). Although MS COCO is more challenging in terms of complexity and the dataset size, TENET boosts results to 19.1%, 27.4% and 19.6%, surpassing the SOTA method QSAM by 6.1%, 2.7% and 7.5% on AP, AP_{50} and AP_{75} .

FSOD. Table 2b compares TENET (5-shot) with PNSD [50], FSOD [7], LSTD [4] and LSTD (FRN [33]). We re-implement BD&TK, modules of LSTD, based on Faster-RCNN for fairness. TENET yields SOTA 35.4% AP_{50} and 31.6% AP_{75} .

RPN TRHShot(Novel) Shot(Base) Shot(Novel) Shot(Base) Speed dim 2 3 4 10 10 (img/ms) 10 56.5 64.271.775.532 1 72.1 1 53.461.8 64.955.7 63.267.0 69 2,3,4 57.2 63.7 68.8 76.6 51.458.9 68.774.878 2,3,4 61.0 65.4 77.3С 2,3,4 71.33:1 58.342 63.2 69.3 75.1 3:1 56.1 70.8 d 2,3,4 1,2,3,4 62.3 78.2 62.475.468 66.9 73.8 2:2 51.8 61.7 68.1 73.6 71 TRHShot(Novel) Shot(Base) 6:1:1 | 53.6 62.7 69.4 72.8 5:2:1 62.3 66.9 73.8 77.9 Z-shot Spatial-HOP 59 5 10 5 10 5:1:2 53.9 63.169.7 63.269.3 75.158.5 4:2:2 61.4 65.070.474.961.0 65.8 71.7 4:3:1 59.1 63.6 71.875.24:1:3 61.0 62.3 66.9 73.8 78.2 64.168.9 72.5(a) (b)

Table 3: Results on VOC2007 testset for applying TENET in RPN or TRH (3a, top panel of 3b). TRH ablation shown in bottom panel of 3b.

5.2 Hyper-parameter and ablation analysis

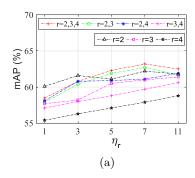
TENET. Table 3a shows that among orders r=2, r=3 and r=4, variant r=2 is the best. We next consider pairs of orders, and the triplet r=2,3,4. As the number of tensor coefficients grows quickly w.r.t. r, we split the 1024 channels into groups, e.g., r=2,3. A 3:1 split means that second- and third-order tensors are built from 768 and 256 channels (768+256=1024). We report only the best splits. For pairs of orders, variant r=2,3 was the best. Triplet r=2,3,4, the best performer, outperforms r=2 by 5.8% and 2.7% in novel classes (5- and 10-shot), and 2.1% and 2.4% in base classes. As all representations are 1024-dimensional, we conclude that multi-order variants are the most informative.

TSO. Based on the best channel-wise splits in Table 3a, we study the impact of η_r (shrinkage/decorrelation) of TSO to verify its effectiveness. Figure 2a shows mAP w.r.t. the individual η_2, η_3 and η_4 for r=2, r=3 and r=4. We then investigate the impact of η_r on pairwise representations, where we set the same η_r for pairwise variants, e.g., $\eta_2 = \eta_3$. Again, the same value of η_r is used for triplet r=2,3,4. Note that for $\eta_r=1$, TSO is switched off and all representations reduce to the polynomial feature maps in So-HoT [14]. As shown in Figure 2a, TSO is very beneficial ($\sim 5\%$ gain for triplet r=2,3,4 over not using TSO).

TRH. Below we investigate the impact of Z-shot and Spatial-HOP T-RHs on results. Table 3b (bottom) shows that both heads are highly complementary.

Other hyperparameters. We start by varying σ of the RBF kernel from 0.3 to 3. Fig 2b shows that $\sigma=0.5$ gives the best result. We now fix σ and investigate the impact of varying the number of heads used in T-Heads Attention (TA). Table 4a shows best performance with TA=4. Lastly, we vary the number of TENET blocks (TB). Table 4b shows that results are stable especially if $TB\geq 2$. Unless otherwise noted, TA=2 and TB=4, respectively, on VOC dataset. See §C of Suppl. Material for more results on FSOD and MS COCO.

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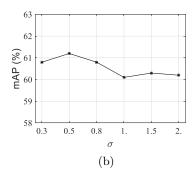


Fig. 2: mAP (VOC2007 dataset, novel classes, 10-shot) w.r.t. varying η_r in TSO (Fig. 2a) and the σ of RBF kernel in self-attention (Fig. 2b).

Table 4: Effect of varying (a) group within MHA in Tab. 4a and (b) TENET block in Tab. 4b on PASCAL VOC 2007 (5/10-shot, novel classes). When varying TENET block, group number is fixed to 4 (best value).

TA	.	1	2	4	8	16	32	64		TB		1	2	3	4	5
Shot (Novel)				61.8					-	Shot (Novel)		1	62.3			
(Novel)	10	61.2	62.8	65.8	64.2	61.2	61.7	60.4		(Nover)	10	65.8	66.9	66.4	66.1	66.4
				(a)									(b)			

Impact of TENET on RPN and TRH. Table 3b shows ablations w.r.t. TENET variants in: 1) either RPN or TRH, or 2) both RPN and TRH. Comparing results for settings a,b, and c confirms that using second-, third- and fourth-orders simultaneously benefits both RPN and TRH, achieving 3.8%/1.9% as well as 3.8%/1.8% improvement on novel classes over the first-order-only variant. Results for settings c and d show that TRH encodes better the information carried within regions if leveraging both first- and higher-order representations.

6 Conclusions

We have proposed TENET, which uses higher-order tensor descriptors, in combination with a novel Tensor Shrinkage Operator, to generate highly-discriminative representations with tractable dimensionality. We use these representations in our proposed Transformer Relation Head to dynamically extract correlations between query image regions and support crops. TENET has heightened robustness to large intra-class variations, leading to SOTA performance on all benchmarks.

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Time-rEversed diffusioN tEnsor Transformer: A new TENET of Few-Shot Object Detection (Supplementary Material)

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Below are additional derivations, evaluations and illustrations of our method.

A Ablation Study on Encoding Network

Below we perform ablations of the backbone (Encoding Network, termed as EN in main paper). We use ConvNet (ResNet-50) and Transformer network [54] (Swin-B⁷/ Swin-B¹² pre-trained on ImageNet-22K [5] with window size of 7/12), as shown in Table 5c. The comparisons are conducted by changing the backbone, whereas other settings remain unchanged. When ResNet-50 is replaced by Swin-B⁷, we gain an improvement of 0.3% and 0.5% in the 5/10-shot setting (novel classes).

B Details of Transformer Relation Head (TRH) with Z-shot and Spatial-HOP blocks.

As Z-shot T-RH is described in Eq. (15) of the main paper, below we focus on describing Spatial-HOP T-RH.

This head first forms a so-called self-attention on a set \mathcal{Z} of support regions and \mathcal{B} query RoIs, respectively. We formulate its operation for B query RoIs (refer §4.2 of main paper for support regions). Spatial-HOP T-RH takes as input RoI features $\{\boldsymbol{\Phi}_b^* \in \mathbb{R}^{2d \times N}\}_{b \in \mathcal{I}_B}$ (2d because layer 5 of ResNet-50 maps d-dimensional features to 2d-dimensional features) and $\{\boldsymbol{\psi}_b^* \in \mathbb{R}^d\}_{b \in \mathcal{I}_B}$. We split $\boldsymbol{\Phi}_b^*$ along the channel mode of dimension 2d to create two new matrices $\boldsymbol{\Phi}_b^{*u} \in \mathbb{R}^{d \times N}$ and $\boldsymbol{\Phi}_b^{*l} \in \mathbb{R}^{d \times N}$ for $b \in \mathcal{I}_B$. We let $\boldsymbol{\Phi}_b^{*l} = [\boldsymbol{\phi}_{b,1}^{*l}, ..., \boldsymbol{\phi}_{b,N}^{*l}] \in \mathbb{R}^{d \times N}$. Self-attention is then performed over $\boldsymbol{\mathcal{T}}_b$ containing vectors, in parallel across B RoIs, $ie., \{\boldsymbol{\mathcal{T}}_b\}_{b \in \mathcal{I}_B}$:

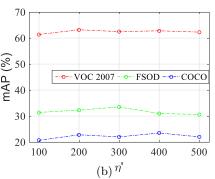
$$\mathcal{T}_b = [\phi_{b,1}^{*l}, ..., \phi_{b,N}^{*l}, \bar{\phi}_b^{*u}, W_g \psi_b^*], \tag{17}$$

where $\bar{\phi}$ denotes average-pooled features (FO) and $W_g \in \mathbb{R}^{d \times d}$ denotes a linear projection (shared between query and support representations).

Based on these representations passed through the transformer head (variables indicated by widehat $\hat{\cdot}$) between support regions and query RoIs, we then

Table 5: Experimental results of different variants of Transformer Relation Head (TRH), by varying Z-shot and Spatial-HOP blocks, are in Tab. 5a. Digits 1, ..., 4 indicate different orders included or excluded from each experiment. "Spatial" is the size of spatial map (downsampled by the bilinear interpolation). Next, Tab. 5c is an ablation of different variants of Encoding Network (5/10-shot setting on VOC2007 testing set was used in Tab. 5a and 5c). Finally, Fig. 5b shows mAP w.r.t. η' in SigmE (10-shot protocol on VOC2007 and COCO testing dataset, 5-shot setting on FSOD testing dataset).

$^{-\rm shot}_{,2,3,4)}$	Spatial	1	2,3,4	5-shot	10-shot
	7×7	√	V	57.9 61.3 62.3	64.2 65.8 66.9
✓	5×5	√ √	1	58.7 60.3 61.1	63.7 64.3 65.2
	3×3	\ \ \	\'	54.8 56.0 56.6	57.9 59.2 60.1
	1×1	√ √	1	$\begin{array}{ c c c } 45.1 \\ 46.8 \\ 47.4 \end{array}$	$49.3 \\ 51.9 \\ 52.4$
	7×7	√ √	1	55.2 59.4 61.0	60.7 64.6 65.8
	5×5	√ √	1	57.6 58.6 60.3	61.5 63.0 63.4
	3×3	√ √	1	52.4 54.1 54.5	54.8 57.8 58.3
	1×1	√	1	44.0 45.2 46.3	47.1 48.4 50.1
			(a)		



62.3	66.9
62.6	67.4
62.0	66.7
	62.6

compute relations as follows:

$$\mathcal{R}_{\text{Spatial}}^{b} = \left[\widehat{\boldsymbol{\Phi}}^{\dagger l} - \widehat{\boldsymbol{\Phi}}_{b}^{*l}\right] \in \mathbb{R}^{d \times N}, \ b \in \mathcal{I}_{B}, \tag{18}$$

$$\mathcal{R}_{\text{FO+HO}}^{b} = \begin{bmatrix} \widehat{\bar{\phi}}^{\dagger u} \cdot \widehat{\bar{\phi}}_{b}^{*u} \\ \widehat{\psi}^{\dagger} \cdot \widehat{\psi}_{b}^{*} \end{bmatrix} \in \mathbb{R}^{2d},$$
(19)

$$\mathcal{R}^{b} = \begin{bmatrix} \operatorname{Repeat}(\mathcal{R}_{\text{Spatial}}^{b}; N) \\ \mathbf{W}^{u} \mathcal{R}_{\text{FO+HO}}^{b} \end{bmatrix} \in \mathbb{R}^{2d \times B}, \tag{20}$$

where the learnable weight $\mathbf{W}^{(u)} \in \mathbb{R}^{d \times 2d}$ projects the channel-wise concatenated matrix to d dimensions, letters l and u indicate first and second half of channel coefficients, respectively, operator \cdot indicates element-wise multiplication, and Repeat $(\cdot; N)$ replicates spatial mode N times. The above process is shown in Fig. 4.3.

C Ablation Study on Transformer Relation Head (TRH) with Z-shot and Spatial-HOP blocks.

As the supplementary setting for the top panel of Tab. 3b (in the main paper), we utilize r=1 in RPN and r=2,3,4 in TRH, achieving 2.7%/2.4% improvement on novel/base classes, 5-shot protocol, over the variant applied r=1 in both RPN and TRH.

We then conduct more ablation studies on Spatial-HOP transformer head to analyze the impact brought by each component (5/10-shot setting on novel classes, VOC 2007). The results are shown on Table 5a. Specifically, we mainly ablate three variants: spatial maps of assorted size (as in the table) with either orderless HOP representation of order r=1 or r=2,3,4, or both r=1,2,3,4.

Furthermore, to investigate the impact of spatial attention, we use bilinearly subsampled maps, ranging from 1×1 to 7×7 in spatial size. Not surprisingly, the Spatial-HOP head performs best when utilizing larger spatial maps, together with the orderless high-order and first-order tensor descriptors.

D Visualization of Attention Maps of the Spatial-HOP block.

To explain why our model benefits from the combination of spatial attention, and orderless first-order and high-order representations, we provide qualitative results based on displaying attention maps.

Firstly, we performed training where Spatial-HOP T-RH used only spatial and first-order information (FO) during training. To obtain the picture, we picked $\bar{\phi}^{\dagger u}$ from Eq. (16) and we looked how it correlates with the N spatial representations $\phi_1^{\dagger l},...,\phi_N^{\dagger l}$. To that end, we passed these "spatial fibers" and FO representation via the RBF kernel of Eq. (8), and we then reshaped N into the spatial map $(7 \times 7 \text{ size})$.

Figure 3 (top left) shows how the first-order representation (FO) correlates with each spatial fiber in the attention of transformer. As Spatial-HOP T-RH block uses information averaged over K images of the same class in an episode (K-way images), each column shows one of these support images. Each row shows a different class image from Z-shot support images in the episode.

Subsequently, we performed training where Spatial-HOP T-RH used only spatial and high-order information (HO) during training. Thus, we picked the high-order representation $\mathbf{W}^{(g)}\boldsymbol{\psi}^{\dagger}$ from Eq. (16) and we looked how it correlates with the N spatial representations $\boldsymbol{\phi}_1^{\dagger l},...,\boldsymbol{\phi}_N^{\dagger l}$. To that end, we passed these "spatial fibers" and HO representation via the RBF kernel of Eq. (8), and we then reshaped N into the spatial map $(7 \times 7 \text{ size})$.

Figure 3 (top right) shows how the high-order representation (HO) correlates with each spatial fiber in the attention of transformer. As before, we visualise $K \times Z$ images from an episode given the K-way Z-shot problem.

Comparing FO an HO representations, HO is by far more focused on the foreground objects that correlate in the semantic sense with the object class. This

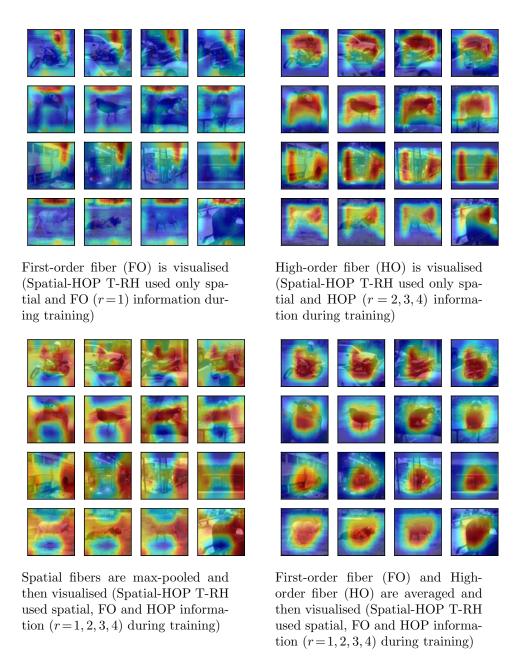


Fig. 3: Visualization of attention maps of self-attention w.r.t. support regions. The results are produced on VOC2007 test set, novel classes (motorbike, bird, bus and cow). See text for detailed descriptions.

explains why HO representations help our model obtain better results compared to traditional attention mechanisms that focus only on capturing spatial correlations of a region.

Figure 3 (bottom left) shows how the spatial fibers from the attention matrix that is max-pooled along columns (we of course removed FO and HO before pooling along columns). We follow the same procedure as above, however, this time the Spatial-HOP T-RH block was utilizing the spatial, FO and HO information during training. Clearly, spatial attention can focus on complex spatial patterns in contrast to the focus of FO and HO.

Figure 3 (bottom right) shows how the first-order representation (FO), averaged with the high-order representation (HO), correlate with each spatial fiber in the attention of transformer. We follow the same procedure as above, and still use the spatial, FO and HO information in the Spatial-HOP T-RH block during training. Clearly, utilizing r=1,2,3,4 compares favourably with utilizing either r=1 or r=2,3,4 during training.

E Impact of η' of SigmE.

According to Section 4, TSO benefits from element-wise PN, realized by the SigmE operator in Eq. (5), which depends on the parameter η' . Figure 5b shows that $\eta' = 200$ is a good choice on VOC dataset but $\eta' = 300/400$ helps obtain the best results on FSOD/COCO dataset. Overall, our approach is not overly sensitive to this parameter, and setting $\eta' = 200$ on all datasets if a good choice.

F Hyperparameters on the FSOD and COCO datasets.

Table 6: Ablation studies on the FSOD and COCO datasets (5/10-shot, novel classes), w.r.t. the effect of varying (a) the number of heads used in T-Heads Attention, as shown in Tab. 6a, and (b) the number of TENET blocks as shown in Tab. 6b. mAP of variants of High-order Tensor Descriptors (HoTD) with TSO $(\eta_r > 1)$ and without TSO $(\eta_r = 1)$ is in Tab. 6c.

TA	FSOD	COCO	TB	FSOD	COCO		r	dim.	η_r	5-s	hot	η_r	10-5	shot
	5-shot	10-shot	1 1	5-shot	10-shot		2 3 4	split			4 D	(COCO)	'	
1	30.5	20.1	-				2 3 4			AP_{50}	AP_{75}		AP_{50}	AP_{75}
2	31.7	22.3	1	31.7	23.5		√		7	33.1	29.6	10	25.7	17.5
4	31.2	22.6	2	33.5	24.2		•							
8	30.8	23.5	3	32.6	25.1		\checkmark \checkmark	3:1	7,7	33.7	30.4	10,10	26.0	18.2
16	30.0	23.0					111	5:2:1	7,7,7	35.4	31.6	10,10,10	27.4	19.6
32	29.4	21.8	4	31.0	24.8									
64	29.5	21.5	5	31.2	23.1		< < <	5:2:1	1,1,1	30.8	28.4	1,1,1	22.1	14.3
	(a	a)		(1	o)	•				(0	c)			

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Tables 6a and 6b present the impact of the number of head used in T-Heads Attention (TA) and TENET block (TB) on results. We fix the $\sigma = 0.5$ (the best value of standard deviation of the RBF kernel of transformers, selected by cross-validation on FSOD and COCO dataset) and then we investigate TA and TB (the number of attention units per block, and the number of blocks, respectively). Two heads together with two blocks are the best on the FSOD dataset, while eight heads aligned with three blocks yield the best results on the COCO dataset. Table 6c shows results on FSOD and COCO w.r.t. the dimension split along the feature channel (e.g., if r=2,3, ratio 3:1 means that three parts of channel dimension are taken to form the second-order representation, and one part of channel dimension is taken to form the third-order representation). The table also shows the impact of η_r of TSO on results, where η_r are individual parameters for each order r. Overall, using all three orders, as denoted by r=2,3,4, outperforms a second-order representation, indicated by r=2. Importantly, TSO is used when $\eta_r > 1$. Without TSO $(\eta_r = 1)$, results drop by a large margin, which highlights the practical importance of TSO on results.

G Comparison with QA-FewDet/DeFRCN fine-tuning/meta-testing setting (Table 7).

Below we compare our method with with QA-FewDet [53]/DeFRCN [55].

Table 7: Comparison with QA-FewDet/DeFRCN (mAP%).

Method	Encoding Network		Nov 2	el Se		10	1	Nov 2	vel Se		10	1		vel Se	et 3 5	10
Meta-training the model on base classes, and meta-testing on novel classes																
QA-FewDet TENET (Ou	rs) ResNet-101 ResNet-50															
	Fine-tuning	the:	mode	lon	nove	el cla	sses.	and	test	ing c	n nc	vel c	·lace	26		
						or ora	,	and	0000		,11 110		iass			

H Comparison with SOTA on MS COCO minival set (10/30 -shot) as shown in Table 8.

Table 8: Evaluations on the MS COCO minival set (10/30- shot). Methods that do not disclose all shot results are ignored and are replaced with '-'.

Method	Venue		P 30	$\begin{vmatrix} AI\\10 \end{vmatrix}$	$^{2}_{50}_{30}$	$\begin{vmatrix} AI \\ 10 \end{vmatrix}$	$\frac{5}{30}$
FSCE+SVD FADI SRR-FSD Zhang et al.	NeurIPS 2021 NeurIPS 2021 CVPR 2021 CVPR 2021	12.2		$\begin{bmatrix} - \\ - \\ 23.0 \\ 27.0 \end{bmatrix}$	- 29.2 -	$\begin{vmatrix} 10.4 \\ 11.9 \\ 9.8 \\ 10.9 \end{vmatrix}$	15.3 15.8 13.5
QA-FewDet DeFRCN	ICCV 2021 ICCV 2021		$\begin{array}{c} 16.5 \\ 22.6 \end{array}$	23.9	31.9	9.8	15.5
QSAM FCT	WACV 2022 CVPR 2022		$15.3 \\ 20.2$	$ ^{24.7}_{-}$	29.3	12.1	14.5
TENET	Ours	19.1	23.7	27.4	32.2	19.6	23.1

I Mean \pm std of mAP on PASCAL VOC 2007 (Table 9).

Table 9: Evaluations on three test splits of VOC 2007 (mean mAP \pm std).

Method	/Shot		Mear	n±std	
		1	3	5	10
FRCN FR Meta FSOD NP-RepMet PNSD MPSR TFA	ICCV12 ICCV19 ICCV19 CVPR20 NeurIPS20 ACCV20 ECCV20 ICML20	7.6 ± 3.1 16.6 ± 1.9 14.9 ± 3.9 25.4 ± 3.2 37.6 ± 3.4 31.3 ± 4.4 33.9 ± 7.2 31.4 ± 6.7	23.5 ± 4.5 25.0 ± 1.7 30.7 ± 3.2 32.0 ± 4.8 41.6 ± 1.5 36.2 ± 4.2 44.3 ± 5.2	32.3±3.3 34.9±4.3 40.6±4.5 42.2±4.2 45.4±2.8 44.5±3.8 47.7±6.2	36.4±6.0 42.6±3.4 48.3±2.5 47.9±3.9 47.8±2.1 49.9±5.4 53.1±6.2
FSCE CGDP+FRCN TIP FSOD ^{up} QSAM	CWPR21 CVPR21 CVPR21 ICCV21 WACV22	31.4±6.7 31.4±9.3 33.1±5.6 24.0±2.6 36.8±5.2 26.1±3.5	40.5 ± 4.6 44.8 ± 4.9 43.7 ± 2.3 38.4 ± 4.0 45.1 ± 3.8 35.4 ± 2.9	46.8 ± 8.6 51.1 ± 7.7 50.0 ± 6.0 45.2 ± 4.3 50.1 ± 4.6 45.4 ± 3.6	48.3 ± 7.0 55.9 ± 5.6 54.8 ± 6.6 52.5 ± 5.3 54.5 ± 5.5 51.9 ± 3.8
TENET	(Ours)	$40.8 {\pm} 3.6$	$\textbf{48.7} \!\pm\! \textbf{4.7}$	$55.3{\pm}3.1$	$57.9 {\pm} 5.8$

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