



Article

Transform and Deep Learning Algorithms for the Early Detection and Recognition of Tomato Leaf Disease

Mohammed Saeed Alzahrani and **Fawaz Waselallah Alsaade** *

College of Computer Science and Information Technology, King Faisal University, Al-Ahsa P.O. Box 4000, Saudi Arabia

* Correspondence: falsaade@kfu.edu.sa

Abstract: Plant diseases pose the greatest threat to food supply integrity, and it is a significant challenge to identify plant diseases in their earliest stages to reduce the potential for associated economic damage. Through the use of computer vision, a cutting-edge artificial intelligence is offered as a solution to this problem so that tomato leaf diseases may be classified. The proposed network is expected to provide excellent results. Transfer learning is also used to make the model efficient and cost effective. Since tomato diseases may significantly influence crop output and quality, early identification and diagnosis of these diseases are essential for successful treatment. Deep learning has shown a great deal of promise in plant disease identification, providing excellent accuracy and efficiency. In this investigation, we compared the performance of three different deep learning models—DenseNet169, ResNet50V2, and a transform model, namely ViT, with regard to diagnosing diseases affecting tomatoes. Both diseased and healthy tomato samples were included in the dataset of photos of tomato diseases used for training and testing the models. The DenseNet121 model had the best results, with a training accuracy of (99.88%) and a testing accuracy of (99.00%). This gave it the greatest overall accuracy. Both the ResNet50V2 and ViT models attained high levels of accuracy, with testing accuracies of (95.60% and 98.00%), respectively. Our results demonstrate deep learning's potential for accurate and efficient tomato disease detection, which could aid in early disease management and ultimately improve crop yield and quality. The experimental findings show that the suggested ensemble models stand out due to the short amount of time required for training and testing as well as their exceptional classification performances. Because of this study, professionals will be able to facilitate the early diagnosis of plant diseases in a straightforward and expedient way, thereby preventing the emergence of new infections.



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1. Introduction

Plants are crucial to our survival because they give us sustenance and shield us from radiation. Without plants, it is difficult to imagine there ever being life on Earth; they not only supply food for all terrestrial creatures but also shield the ozone layer, which blocks harmful ultraviolet light. Tomatoes are globally grown vegetables because they are nutrient rich and safe for human consumption [1]. Around 160,000,000 metric tons of tomatoes are consumed annually across the globe [2]. Many people believe that tomato sales could help rural communities earn much-needed income, which would significantly impact poverty levels [3]. Tomatoes have a high concentration of nutrients and are grown all over the world; as a result, they have a major impact on the agricultural economy when cultivated and harvested. Tomatoes are beneficial in preventing diseases, such as gingival bleeding, hypertension, and hepatitis, due to their pharmacological properties [1], and their anti-cancer properties are well documented. Tomatoes are increasingly in demand because of their growing popularity. Statistically, almost 80.00% of agricultural output [2] is attributed to small farmers. However, diseases and pests wipe out approximately half

of these farmers' harvests every year. Research into field crop disease detection is crucial because the diseases and insects that parasitize tomatoes have a profound impact on their growth. According to a 2020 study compiled by the Food and Agricultural Organization Corporate Statistical Database (FAOSTAT), 186,821 million tons of tomatoes were produced globally [1]. Agriculture is the fundamental contributor to economic expansion as well as the foundation upon which human civilization was built. The many different kinds of plant diseases that farmers have to protect their crops against have proven to be a significant obstacle for agricultural production. Understanding how to prevent plant diseases and implementing preventative measures are the two most important factors in crop yield optimization. Early detection of plant diseases is essential if one wants to achieve maximum agricultural output while at the same time preserving financial resources and reducing the amount of crop loss. The fact that everything is handled by computers also makes it simple to put into action. On the one hand, accurate diagnosis and categorization of diseases within a reasonable amount of time is highly important for preserving both the quality and quantity of tomatoes.

Environmental conditions may play a role in the development of a wide range of plant diseases. The disease triangle is a conceptual model that represents the relationship between three crucial factors: the environment, the host, and the infectious agent. The disease triangle was developed to explain how diseases spread. This type was created in the 1950s and has been widely used since its introduction. It follows that disease cannot occur, since it is impossible for it to take place if any one of these three requirements is absent from the triangle. Many abiotic factors, including air movement, temperature, humidity, pH, and watering, could potentially have significant effects on plants. Fungus, bacteria, and viruses are some organisms that may attack a plant. The infectious agent is an organism that causes the plant to become diseased. The term "host" refers to a plant that is infected with a disease. Disease development is the consequence of all the risk factors converging simultaneously [3]. In general, infections are defined by symptoms that manifest by working their way up through the plant, and as a result, the majority of diseases have rapid transmission rates once they have infected a plant.

Pathogenic fungi, bacteria, and viruses, as well as poor climatic conditions, are some of the many potential causes of plant diseases. Because of the presence of these diseases, a plant's fundamental functions, such as photosynthesis, pollination, fertilization, and germination, may be disrupted. This emphasizes the critical need to accurately diagnose diseases as early as medical science currently allows.

Technology has advanced to the point that it is possible to use tools to diagnose whether a plant is diseased, and if so, what kind of disease it has, rather than relying only on the judgment of a human expert. Results from procedures such as object recognition and classification, as well as image processing and artificial intelligence algorithms, are becoming increasingly high quality as the quality of photos obtained by technological equipment continues to improve. Machine learning (ML) and deep learning (DL) have proved much more effective than traditional methods of optimization and prediction. First, unlike traditional techniques that require humans to extract characteristics and are limited by the amount of data, new systems may learn automatically from large quantities of data. Second, ML and DL models may generalize well to data that have not yet been seen, which is a significant improvement on prior methods. In contrast to more traditional methods, machine learning and deep learning models may pick up on nonlinear and intricate connections in the data. Hence, ML excels at handling situations with many moving parts, especially those with complex interactions. Nowadays, AI (Artificial intelligence) is extensively used in many fields, including communication, building, magnetism, physics, and biology [4–8]. It is crucial to accurately identify plant diseases and classify them in a timely manner in this approach [9]. AI has progressed to the point that it can now automatically identify plant diseases from raw images [10,11].

To date, there has been much research on determining the causes of plant diseases. Most studies used preexisting datasets, models, and libraries to conduct their experiments.

To automate the processes of identifying and classifying plant leaf diseases, Singh and Misra [12] devised an algorithm for the picture segmentation technique. Using a genetic algorithm, they achieved an overall success rate of 97.60% across five different diseases while trying to identify them. Zhang et al. [13] analyzed a database of cucumber leaf samples to identify diseases. In this study, the researchers segmented diseased leaves using k-means clustering to obtain shape and color information that could be utilized for disease diagnosis. When classifying these damaged leaves using the sparse representation method, an 86.00% accuracy rate was attained. Convolutional neural network (CNN) models, a kind of AI, can be used for disease detection and diagnosis in plants [14]. Model training was performed using a dataset that included a total of 87,848 images. The collection also includes 58 unique plant–disease combinations, which are applied to 25 different plant species. A 99.53% success rate was calculated from the data.

Image processing [15,16], pattern recognition [17,18], and computer vision [19,20] have all seen rapid development and use in agriculture in recent years, with a particular emphasis on automating disease- and pest-detection processes. These tasks often cause problems due to the complexity and time commitment involved in preprocessing and constructing picture features for traditional computer vision models. The accuracy with which the feature extraction processes and with which the learning algorithm have been built also affects the efficacy of these systems [21–23]. Deep learning is gaining momentum in sickness detection as a result of increased processing power, increased storage capacity, and the availability of large datasets. This method has recently been applied to the detection of plant diseases; a problem that has proven difficult to solve. As a subset of machine learning, deep learning is a term with a specific meaning. CNNs are among the most popular algorithms used in deep learning for tasks, including picture classification, object recognition, and semantic segmentation [24,25]. CNNs are helpful for discovering patterns in images, objects, and sceneries because they learn to classify based on data from the image, so the user is no longer required to laboriously isolate the desired features within the image [26,27].

This article will assess and explain a selection of the many different approaches to deep learning that are currently in use. Although a number of studies have been conducted to investigate the impact of disease detection on tomato crops, the existing model still requires improvement. Consequently, we proposed a CNN model with two convolution layers, two max pooling layers, a disease in tomato plants by analyzing data from the hidden layer, and a flattening layer for tomato plants. Farmers can now solve problems independently without seeking advice from agriculture industry specialists. This entails identifying the many diseases that might affect crops. Our model was developed to assist in early-stage diagnoses of plant diseases. This will increase the overall productivity of agricultural activities, and as a result, food availability.

The need for an automated technique for diagnosing diseases that might impact tomato plants is the key driver of this project. The following are some of this study's contributions that fill some of the gaps in existing research:

- Evaluating a wide variety of characteristics, including a crop's production, yield capacity, grain quality, and nutrient retention, leads to an accurate plant disease diagnosis.
- Providing advice on constructing new CNN models and creating new ensemble structures using the proposed CNNs.
- Using an advanced transform learning lie to detect tomato leaf disease is critical to saving food security.
- Increasing the accuracy percentage of the proposed model in comparison to earlier studies in the field that were reported in academic journals.
- Increasing categorization reliability and reducing the amount of time required for training and examinations.

This paper presents an architecture for early disease identification and classification in tomato leaves that is based on three different deep learning models—DenseNet169, ResNet50V2, and transform ViT model and data augmentation. To properly forecast the

kind of diseases that will impact the tomato leaves, this study aims to build a trustworthy framework for screening photographs of tomato leaves for indicators of disease.

2. Study Background

Researchers from a wide variety of institutions have developed automated diseases detection systems using cutting-edge technologies, such as machine learning and neural network designs like Inception V3 net, VGG 16 net, and Squeeze Net. They use highly accurate procedures to diagnose plant diseases in tomato leaf tissues.

In order to detect and categorize tomato diseases, a pretrained network model has an accuracy of 94.00% to 95.00% [28,29]. Using a dataset of 300 images and the Tree Classification Model and Segmentation, six types of tomato leaf disease were identified and classified [30]. It has been proposed [31] that we can classify leaf-affecting plant diseases with 93.75% accuracy using a specific approach. Plant leaf diseases may be accurately identified and categorized using image processing software and a classification scheme [32]. A smartphone with an 8-megapixel camera was used to photograph a variety of conditions and then divide the resulting data into two groups: healthy and sick. The image processing procedure was composed of three distinct actions: boosting contrast, image segmentation, and distinctive feature locating. An artificial neural network with several layers and a feed-forward neural net was used to conduct classification tasks, and the results of these networks are compared. Compared to the findings obtained by the multilayer perceptron (MLP) network and the radial basis function (RBF) network, they are much more favorable. Over the course of the study, the image of the plant blade was dissected into healthy and sick sections. However, this did not allow pinpointing the cause of the problem. In order to diagnose leaf diseases, researchers used color space analysis, color time, a histogram, and color coherence as a classifier, which achieved 87.2% in terms of accuracy.

Researchers have used AlexNet and VGG 19 models with a frame size of 13,262 to detect diseases that are hurting tomato harvests. The model was utilized to achieve 97.49% accuracy [33]. To obtain a 95.00% detection rate for viruses that damage dairy crops [34], we used transfer learning and a CNN model. With the goal of identifying and categorizing the conditions of tomato plants' leaf surfaces, an AlexNet-based deep learning mechanism using neural network-trained transfer learning achieved an accuracy of 95.75% [35,36]. Resnet-50 was created to identify 1000 unique diseases that may harm tomato leaves by presenting 3000 images, each of which was tagged with a disease name, such as "lesion blight", "late blight", or "yellow curl leaf". The first convolution layer's kernel size was increased to 11×11 , and the comparing network activation function was switched to Leaky ReLU. The model has been refined over many iterations, and its performance in classifying diseases has improved to an accuracy of 98.30% and a precision of 98.00% [37]. Simplified eight-layer CNN models have been proposed for disease detection and classification in tomato leaves [38]. This research used the PlantVillage dataset [39], a compilation of data on various agricultural products. By applying deep learning to the tomato leaf dataset, the author focused on disease diagnoses to improve performance.

In recent years, CNNs have emerged as a reliable tool for diagnosing plant diseases [40,41]. Some research [42,43] has concentrated on improving feature detection quality by removing obstacles caused by inconsistencies in illumination and background homogeneity in high-stakes scenarios. Feature detection improvements have been the subject of other investigations that have sought to implement them by detecting complicated contexts. Few authors have developed real-time models to hasten plant disease detection [44,45]. Other authors' work has also led to the early identification of plant diseases via model development [46,47]. In Ref. [48], the authors investigate digital photos of tomato leaves to determine the presence of various diseases. The authors implement a classification model based on CNN and AI-derived algorithms that is 96.55% accurate in recognizing five different diseases. In several studies, deep neural network models have been used to identify diseases in tomato leaves. In Ref. [49], for example, the authors compare four alternative models (LeNet, VGG16, ResNet, and Xception) and conclude that the VGG16 model

achieves the greatest performance (99.25% accuracy) when used to categorize nine distinct disorders. The effectiveness of deep neural network models for diagnosing diseases in tomato leaves has been studied in other research. According to Ref. [50], an identical issue was solved with 95.00% or higher accuracy using the AlexNet, GoogleNet, and LeNet models. Agarwal et al. [51] built CNN architecture and compared it to other ML models (such as random forest and decision trees) and DL models for classifying data into 10 groups (VGG16, Inceptionv3, and MobileNet). The result was a 99.20% accuracy boost.

Many research efforts have focused on improving classification accuracy by combining random forests, support vector machines, and multinomial logistic regression, which are just a few examples of the classification networks that may be employed with the obtained leaf characteristics [52]. With the help of MobileNetv2 and NASNetMobile, we were able to successfully extract leaf features. Researchers have shown that classification accuracy may be greatly improved by combining these two techniques. Many studies have successfully diagnosed plant diseases using algorithms such as Mask R-CNN [53]. Computing costs and model sizes have been decreased via the use of several techniques namely K-nearest neighbors and Gabor filters and K-nearest neighbors (KNN). Both methods have been used to attempt to reduce the time and resources needed to run deep learning calculations. To reduce computational costs, the authors of Ref. [54] used a SqueezeNet architecture with only 33 filters. YOLO-Tomato, which is based on YOLOv3 and was utilized by the authors of Refs. [55–57] to improve tomato identification, has been presented as a solution for dealing with these issues. YOLOv3 has been designed with a thick architecture in order to make the reuse of features easier and to assist in learning a model that is both more accurate and more compact.

3. Materials and Methods

Due to tomato leaves' complicated designs and the wide variety of diseases that affect tomatoes, the disease identification process can be difficult. Deep learning has emerged as a strong technology in recent years as support for the computer-assisted detection of diseases affecting tomatoes. This technique uses deep neural networks, which can learn complicated patterns from extensive volumes of picture data. The recommended approach for detecting tomato diseases via deep learning includes several essential stages. To begin, a tomato leaf picture dataset is gathered. This dataset will comprise examples of various diseased and healthy leaves. After preprocessing, the photos are utilized to teach a deep neural network, such as a CNN, to recognize intricate patterns within images. After the model has been trained, it can categorize newly acquired pictures as belonging to either the healthy class or one of the disease classes. Adjustments to the model's parameters and the inclusion of new data may both enhance the model's performance and make it more accurate. In conclusion, model performance may be tested using a test set of pictures to determine its accuracy and generalization capacity. The fundamental architecture of the suggested system for the classification and detection of tomato plant leaf diseases is presented in Figure 1.

3.1. Dataset

This study used the Tomato Leaf Diseases Dataset, consisting of 11,000 images of tomato leaves affected by 10 distinct diseases. Each class, including tomato mosaic virus, target spot, bacterial spot, tomato yellow leaf curl virus, late blight, leaf mold, early blight, spider mites (two-spotted spider mite), tomato healthy, and Septoria leaf spot, contains 1100 images. The dataset is publicly accessible on Kaggle. Table 1 displays the tomato leaf features, and the sample numbers of each class, and a sample of the tomato leaf diseases is presented in Figure 2. The dataset is available here <https://www.kaggle.com/datasets/kaustubhb999/tomatoleaf> (accessed on 20 January 2023).

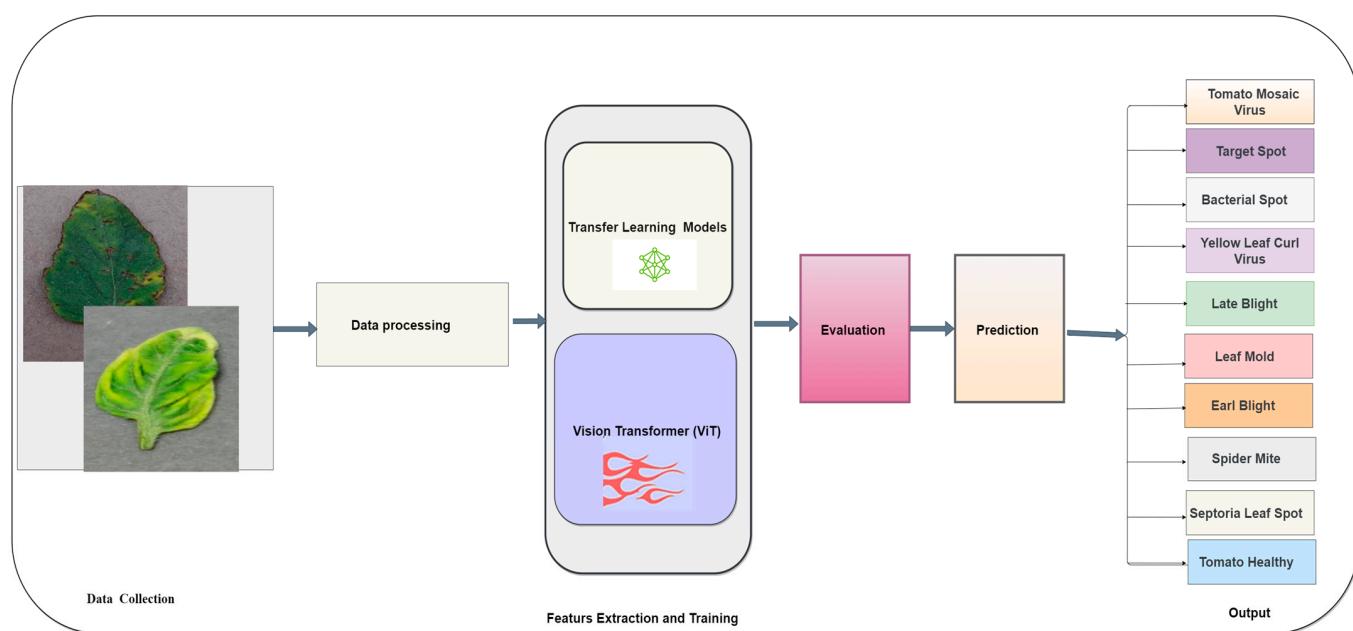


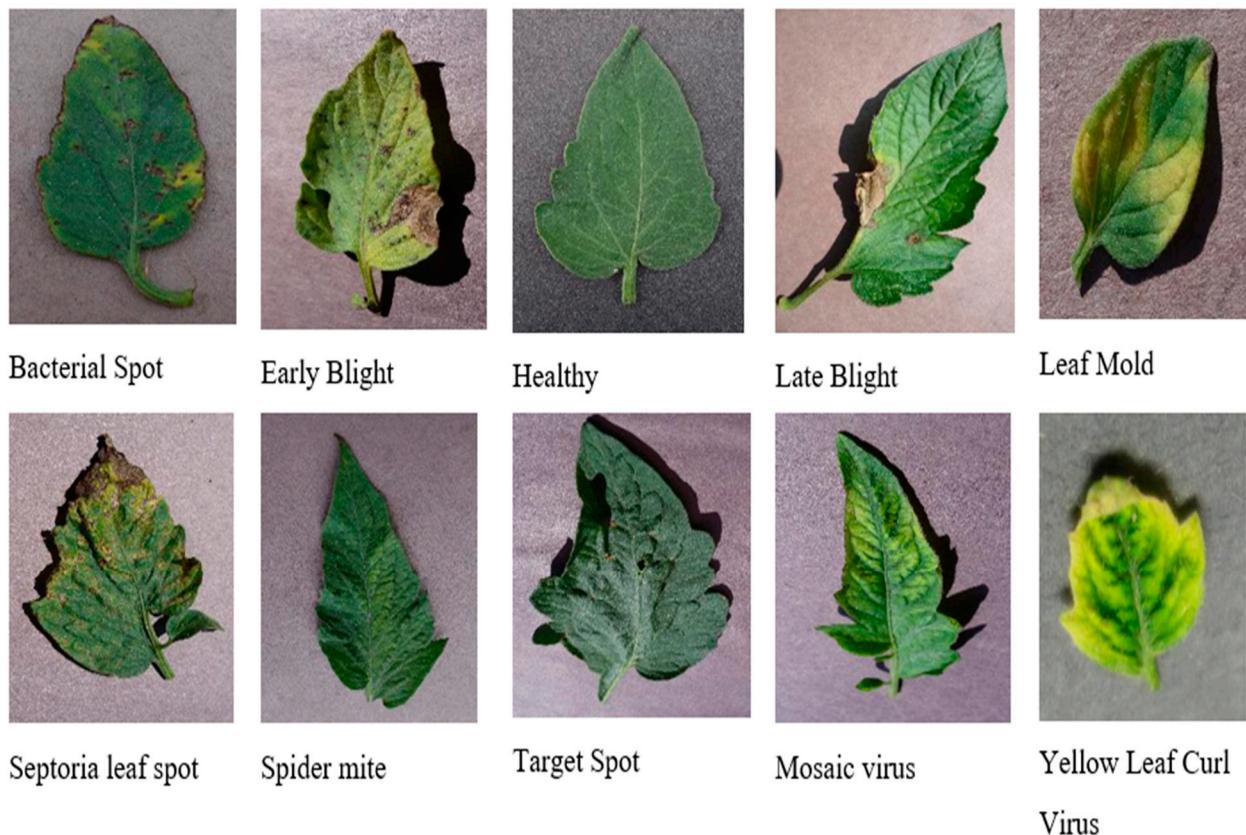
Figure 1. The structure of the suggested approach.

Table 1. Tomato leaf features.

Class	Number of Samples	Description
Mosaic virus	1100	This is a viral disease that can cause significant damage to tomato plants, leading to reduced growth and yield. Symptoms include mosaic-like patterns of light and dark green on leaves, stunted growth, and deformed fruit. The disease is transmitted by contact with infected plant material and can be managed using resistant tomato varieties and cultural practices, such as sanitation.
Target spot	1100	This disease is caused by the fungus <i>Corynespora cassiicola</i> and can cause circular, sunken lesions with concentric rings on leaves and stems. It can lead to defoliation and reduced fruit yield, but it can be managed using fungicides and cultural practices, such as crop rotation and sanitation.
Bacterial spot	1100	This is a common disease that can cause severe damage to tomato plants, leading to reduced yields and poor fruit quality. Symptoms include brown, sunken lesions on leaves and fruit, which eventually turn black and crusty. The disease is caused by the bacterium <i>Xanthomonas campestris</i> pv. <i>vesicatoria</i> and can be controlled using copper-based fungicides and cultural practices, such as crop rotation and sanitation.
Yellow leaf curl virus	1100	This is a viral disease that can cause significant damage to tomato plants, leading to stunted growth and reduced fruit yield. Symptoms include leaf yellowing and curling as well as distorted fruit. The disease is transmitted by the whitefly <i>Bemisia tabaci</i> , and it can be managed using insecticides, resistant tomato varieties, and cultural practices, such as crop rotation and sanitation.
Late blight	1100	This disease is caused by the fungus <i>Phytophthora infestans</i> and can cause rapid and devastating damage to tomato plants. Symptoms include water-soaked lesions on leaves and stems, which quickly turn brown and necrotic. The disease can be managed using fungicides and cultural practices, such as crop rotation, sanitation, and removal of infected plant material.
Leaf mold	1100	This disease is caused by the fungus <i>Passalora fulva</i> and can cause significant damage to tomato leaves, reducing plant growth and yield. Symptoms include yellowing and brown lesions on the plant's lower leaves. The disease can be managed using fungicides and cultural practices, such as crop rotation and sanitation.

Table 1. Cont.

Class	Number of Samples	Description
Early blight	1100	This disease is caused by the fungus <i>Alternaria solani</i> and is characterized by concentric rings of dark brown spots on the plant's lower leaves. It can cause defoliation and reduced fruit yield but can be managed using fungicides and cultural practices, such as crop rotation and pruning.
Spider mites	1100	These are tiny arachnids that can cause significant damage to tomato plants by feeding on the undersides of leaves, causing yellowing and stunted growth. They can be managed using predatory mites, insecticidal soaps, and cultural practices, such as crop rotation and sanitation.
Tomato healthy	1100	This class contains images of healthy tomato leaves, which can be used as references for comparison with diseased leaves.
Septoria leaf spot	1100	This disease is caused by the fungus <i>Septoria lycopersici</i> and is characterized by small, circular lesions with dark brown centers and yellow halos on the lower leaves of the plant. It can cause significant defoliation and yield loss, but can be managed using fungicides and cultural practices, such as crop rotation and sanitation.

**Figure 2.** Demonstrated dataset samples.

3.2. Data Preprocessing

The data preprocessing step is essential because it improves both the data quality and overall performance of the classification methods used for the picture categorization process. The primary goal of data preprocessing is to prepare images for the deep learning model by removing any discrepancies, noise, or outliers that could negatively impact the model's accuracy. This is accomplished by organizing data in a way that makes it easier for the model to analyze. In deep learning models for image classification, several common data preprocessing approaches are applied, such as image resizing and normalization. Image

resizing involves adjusting the size of the images to ensure that they are of a standard size for the model's training. This helps reduce model complexity and ensures that it is trained on images of the same size. Images normalization entails adjusting the brightness and contrast levels of each picture so that they are uniform across all of them. This is done to guarantee that the model is trained on photos that have comparable qualities. Applying data preprocessing techniques results in a more consistent and high-quality dataset, which can improve the model's accuracy. These techniques can be implemented using various image-processing libraries, such as PIL and OpenCV.

3.3. Transfer Learning Algorithms

Transfer learning approaches allow a model to be trained on one task and then applied to a different but related task. This is particularly useful when there is a lack of labeled data for a specific task or when the task is similar to one that has already been solved. It can save a lot of time and resources by leveraging the knowledge and features learned from a pretrained model. Additionally, transfer learning can improve model performance by reducing the risk of overfitting and allowing the model to be better generalized to a new dataset. Both the quantity of labeled data available for the new task and the degree of similarity between the pretrained model and the new task should be taken into account before deciding to use transfer learning. It may be preferable to retrain the model from scratch if the new job is quite different from the one the pretrained model was built for, or if there is a huge quantity of labeled data available. Model performance may be enhanced via transfer learning, and the need for labeled data can be reduced. It is applicable to many different models, including CNNs, and may be implemented using either feature-based or fine-tuning approaches.

3.3.1. DenseNet121 Model

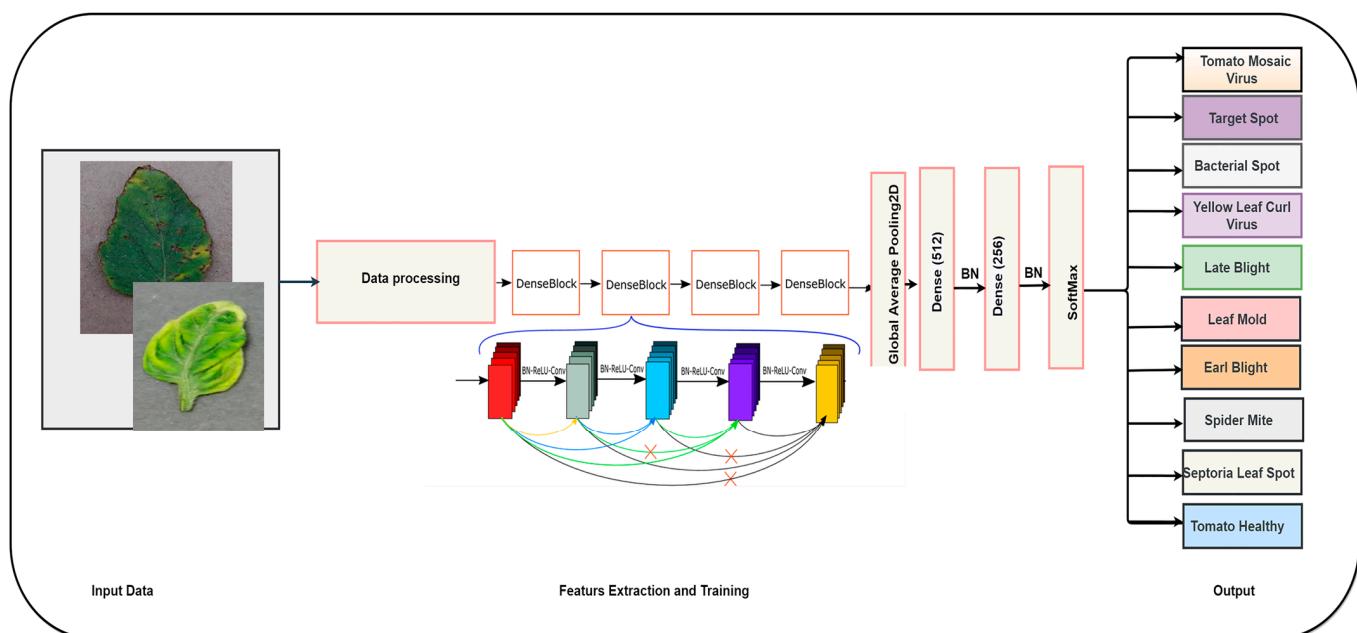
DenseNet121 is a popular CNN architecture that Huang et al. introduced in 2017 as part of the DenseNet family. The network is based on the concept of dense connections between layers, which allow information to flow more efficiently through the network and improve its accuracy. The DenseNet121 architecture consists of multiple dense blocks, each containing a set of convolutional layers that are densely connected to all subsequent layers [58–61].

In this research, we employ a pretrained DenseNet121 model for disease identification in tomatoes. It is common practice to apply transfer learning, and this was done to initialize the pretrained model using weights learned from the huge ImageNet dataset. A new set of layers, consisting of a global average pooling layer, two fully connected layers with 512 and 256 neurons, and two batch normalization layers, was added after the top layer of the pretrained model was eliminated and replaced. Once the second layer was completely linked, the ReLU activation function was applied to a new layer that served as an activation layer. Finally, a softmax activation layer was added to the output layer, which comprised of 10 neurons that corresponded to the 10 different types of tomato diseases. Figure 3 illustrates this point.

This architecture was chosen because DenseNet models have shown strong performance in various image classification tasks and have a compact architecture suitable for transfer learning. The global average pooling layer was used to reduce the number of parameters in the model, and batch normalization layers were added to improve the stability and convergence of the training process. The important parameters of DenseNet121 model are presented in Table 2.

Table 2. Describe DenseNet121 model parameters.

DenseNet121 Parameters	Value
Batch_Size	8
Optimizer	SGD
Learning Rate (lr)	0.0001
Momentum	0.9
Early Stopping (es)	Yes
Model Checkpoint (mc)	Yes
Number of Epochs	100

**Figure 3.** DenseNet121 model for tomato disease detection.

3.3.2. ResNet50V2 Model

ResNet50V2 is a convolutional neural network architecture that has been used for computer vision for analysis and classification images, including disease classification in plants. The pretrained model was initialized with weights learned from the large image processing dataset, which is a common practice in transfer learning. The top layer of the pretrained model was removed and replaced with a new set of layers. The classifier that we added on top of the pretrained ResNet50V2 model is designed to adapt the network to a new image classification task. The pretrained model output is passed through a GlobalAveragePooling2D layer that reduces feature maps' spatial dimensions by averaging them along the height and width axes. This results in a fixed-length feature vector that encodes the most important features of the input image.

The feature vector is processed by two fully connected layers with 512 and 256 neurons, respectively, which learn to map the feature vector to a high-level representation that captures the discriminative information for the new image classification task. Batch normalization layers are added after each fully connected layer to stabilize the training process and accelerate convergence. After the second fully connected layer, nonlinearity is introduced into the network by adding an activation layer using the ReLU activation function. This allows the network to acquire more nuanced representations.

Finally, the second fully connected layer's output is passed through a fully connected layer with 10 neurons and a softmax activation function, which outputs a probability distribution over the 10 classes in the dataset. This layer learns to map the high-level representation to the final output of the network, which is the predicted class label for the

input image. The structure of ResNet50V2 model to detect tomato diseases is presented in Figure 4. The parameters of developing the ResNet50V2 model for detecting tomato disease are presented in Table 3.



Figure 4. DenseNet121 model for tomato disease detection.

Table 3. Describe ResNet50V2 model parameters.

Parameters	Values
#Optimizer	SGD
#Learning Rate (lr)	0.0001
#Momentum	0.9
#Early Stopping (es)	Yes
#Model Checkpoint (mc)	Yes
#Number of Epochs	100

3.3.3. Vision Transformer

Vision transformer (ViT) is a new architecture for image classification that has gained significant attention in the deep learning community. Unlike traditional CNNs, ViTs use transformer-based architecture, which has been highly successful in natural language processing tasks.

ViT architecture consists of several key components. First, the input image is divided into a sequence of fixed-sized patches. Each patch is then flattened into a 1D vector and passed through an embedding layer, which maps the patch to a higher-dimensional feature space. These patch embeddings are then fed into a transformer encoder, which applies a series of self-attention mechanisms to learn the contextual relationships between the patches, as shown in Figure 5.

The following steps outline the process we used to train our data and input it into the ViT model for classification. The input image is passed through a “patches” layer, which divides the image into a grid of non-overlapping 6×6 patches. This turns the 2D image into a 3D tensor of shape (batch size, patch size \times patch size \times number of channels) and the number of color channels (typically 3 for RGB images). The patch tensor is then fed through a “patch encoder” layer, which applies a learned linear transformation (via a dense layer) to each patch and adds a learnable position embedding to each patch. This step helps the model capture spatial relationships between patches and makes it aware of their relative positions within the image.

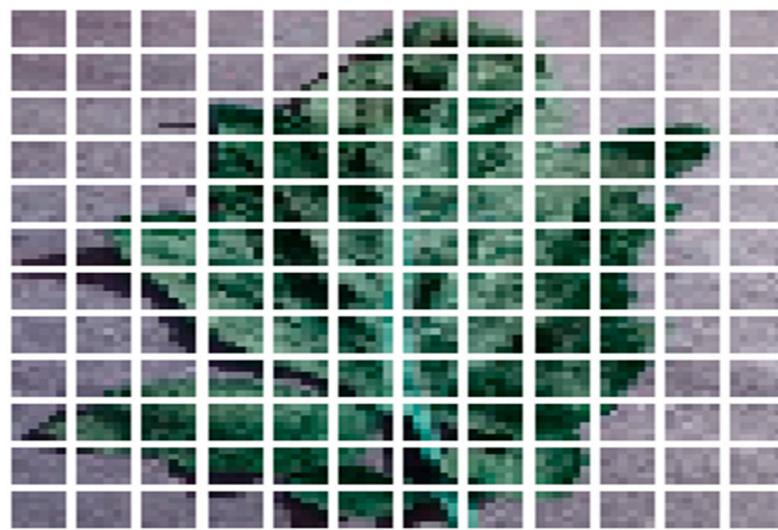


Figure 5. Image after transformer encoder.

This layer produces the model's predictions for each input image. During training, the model is optimized using the AdamW optimizer, a variant of the Adam optimizer that includes weight decay regularization. The loss function used is sparse categorical cross-entropy, which is a common choice for multiclass classification problems. Figure 6 shows the structure of ViT transform model used to detect tomato disease. The significant parameters of ViT model are shown in Table 4.

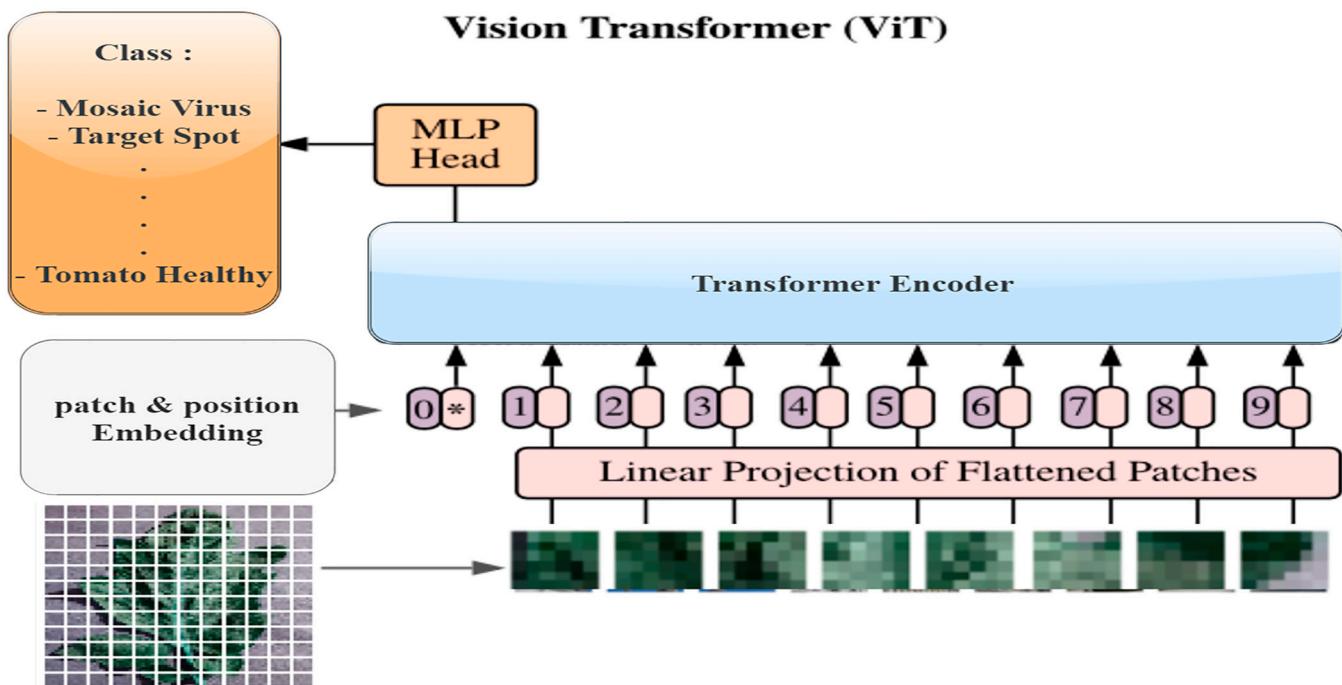


Figure 6. ViT model for tomato disease detection.

Table 4. Describe ViT model parameters.

Parameter	Value
Learning_Rate	0.001
Weight_Decay	0.0001
Batch_Size	128
Number_Epochs	50
Image_Size	72
Patch_Size	6
Number_Patches	144
Projection_Dimension	64
Number_Heads	4
Transformer_Units	(128, 64)

4. Experiment

The effectiveness of DenseNet121, ResNet50V2, and VIT, three deep learning classification algorithms, was assessed within the context of this research as they relate to the diagnosis of tomato diseases. The models were trained, tested, and validated using a dataset that included photographs of both healthy and sick tomatoes. The configuration for training a model was done on a laptop equipped with an 8th generation Core i7 CPU and a GPU 1070 utilized and 8GBs RAM. The TensorFlow and transformer architecture library was used for developing the models. Both the training and testing sets were created from the dataset utilized for this investigation. These two sets were then compared. This division's mission was to verify that the deep learning models generated for this research could correctly categorize new photographs. To do this, every category in the dataset was broken up into 1000 photographs that would be used for training, and 100 images that would be used for testing. The primary goal of this division was to supply the deep learning models with a diverse set of photographs from which they could learn, with the end goal of evaluating the models' capacity to generalize their findings to images that they had not seen before.

4.1. Performance Measurement

To measure the success of a deep learning model, its accuracy is often measured against a gold standard. It is a measure of the model's predictive efficacy that may be calculated by dividing the number of accurate forecasts by the total number of predictions.

$$\text{Accuracy} = \frac{\text{TP} + \text{TN}}{\text{FP} + \text{FN} + \text{TP} + \text{TN}} \times 100\% \quad (1)$$

It is standard practice to utilize precision as a measure of a deep learning model's success, particularly when the job at hand is one of categorization. This metric assesses the reliability of the model's positive predictions by dividing the number of correct forecasts by the total number of correct predictions. It can be collated by Formula (2).

$$\text{Precision} = \frac{\text{TP}}{\text{TP} + \text{FP}} \times 100\% \quad (2)$$

Deep learning models make extensive use of the assessment statistic known as recall, particularly when dealing with categorization issues. It provides a numerical representation of the fraction of the dataset's positive instances that correspond to accurate positive predictions generated by the model. In plainer language, it calculates the number of true positive predictions as a fraction of the total number of positive cases included in the dataset.

$$\text{Recall} = \frac{\text{TP}}{\text{TP} + \text{FN}} \times 100\% \quad (3)$$

The F1 score is a commonly used evaluation metric in deep learning models, especially for classification problems. It is a way to balance the trade-off between precision and recall

by taking the harmonic mean of the two metrics. This makes it a useful metric when dealing with imbalanced datasets or when trying to identify rare classes.

$$F1 - \text{score} = 2 \times \frac{\text{precision} \times \text{Sensitivity}}{\text{precision} + \text{Sensitivity}} \times 100 \quad (4)$$

where:

- FP: false positive
- TP: True positive
- FN: false negative
- TN: true negative.

4.2. Results

4.2.1. Results of the DenseNet121 Model

Table 5 shows the DenseNet121 model's high performance in 90% training and 10% testing. The DenseNet121 model was trained using eight batch sizes and the SGD optimizer for 100 epochs. To prevent overfitting and minimize training time, the early-stop method was employed, which ended the training after 34 epochs. DenseNet121 scored high in accuracy (99.88%) in the training phase, whereas its testing accuracy was 0.99%. Table S1 shows the result of DenseNet121 with 90% training and 10 testing; it is observed that the accuracy of the DenseNet121 model is (98%).

Table 5. Results of DenseNet121 model (90% training and 10% testing).

Class Name	Precision%	Recall%	F1-Score%	Support
Bacterial_Spot	96	100	98	100
Early_Blight	99	100	00	100
Late_Blight	100	100	100	100
Leaf_Mold	100	100	100	100
Septoria_Leaf_Spot	97	100	99	100
Spider_Mites_Two-Spotted_Spider_Mite	99	99	99	100
Target_Spot	100	93	96	100
Yellow_Leaf_Curl_Virus	100	98	99	100
Mosaic_Virus	99	100	100	100
Healthy	00	100	100	100
Accuracy of DenseNet121			99	1000
DenseNet121_Macro Avg	99	99	99	1000
DenseNet121_Weighted Avg	99	99	99	1000

Figure 7 illustrates how well DenseNet121 model performed throughout the 90% training and 10% validation phases for the purpose of recognizing and categorizing diseases that may affect tomato leaf tissue. A training accuracy beginning at 72.00% and increasing to 99.98% was attained as a consequence of these findings. According to the graphic representation, the accuracy at the validation phase started at 86.00% and reached 99.00%. The accuracy loss of the DenseNet121 model was 0.2 in validation. The performance of the DenseNet121 model with 80% training and 20% validation phases is presented in Figure S1; it is noted that the mode achieved accuracy 98.45% and validation loss was decreased from 0.8 to 0.1.

The proposed Dense-Net121 model and its evaluation yielded a confusion matrix, as shown in Figures 8 and S2. The evaluation parameters were (90%, 80% as training and 10%, 20% as testing). The confusion matrix displays the tTP, TN, FP, and FN values that were gathered for each class. The target_spot class has high environment misclassification based on the multiple-graphics processing unit (MGPU) architecture. In terms of leaf disease categorization, the suggested model attained a validation accuracy of 99.64% with 90% training and 10% testing whereas the Dense-Net121 model was attained accuracy 98.45% with 80% training and 20% testing.

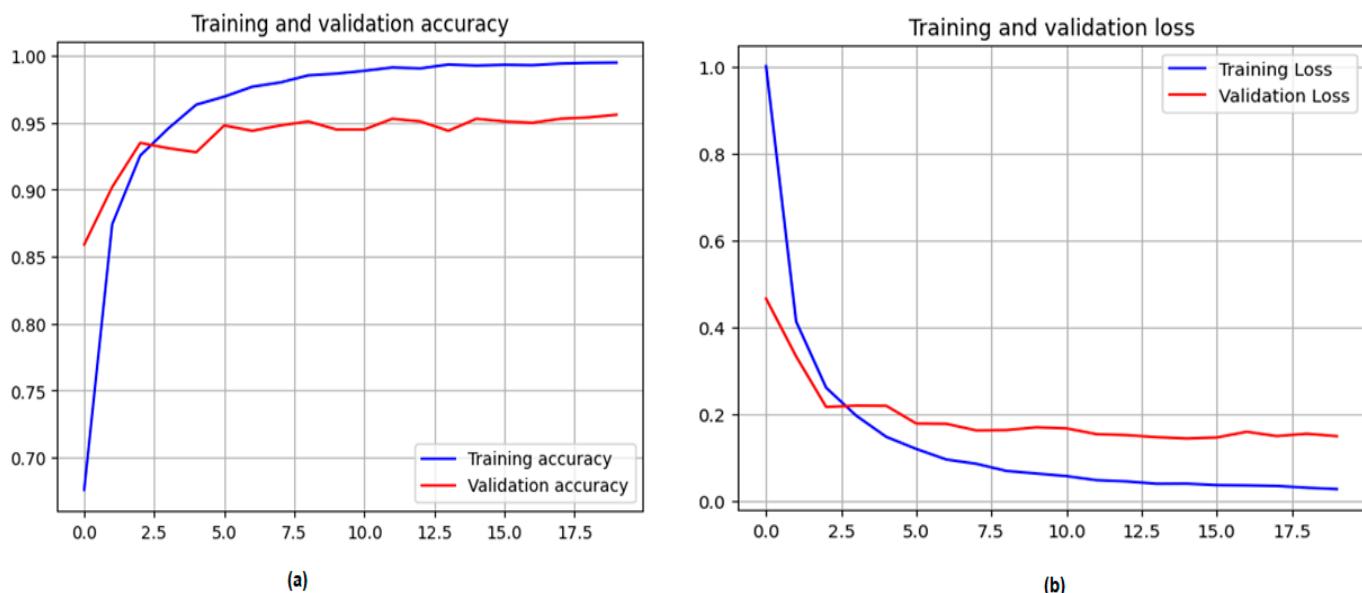


Figure 7. Performance of DenseNet121 model; (a) DenseNet121 model accuracy and (b) DenseNet121 mode loss (90% training and 10% testing).

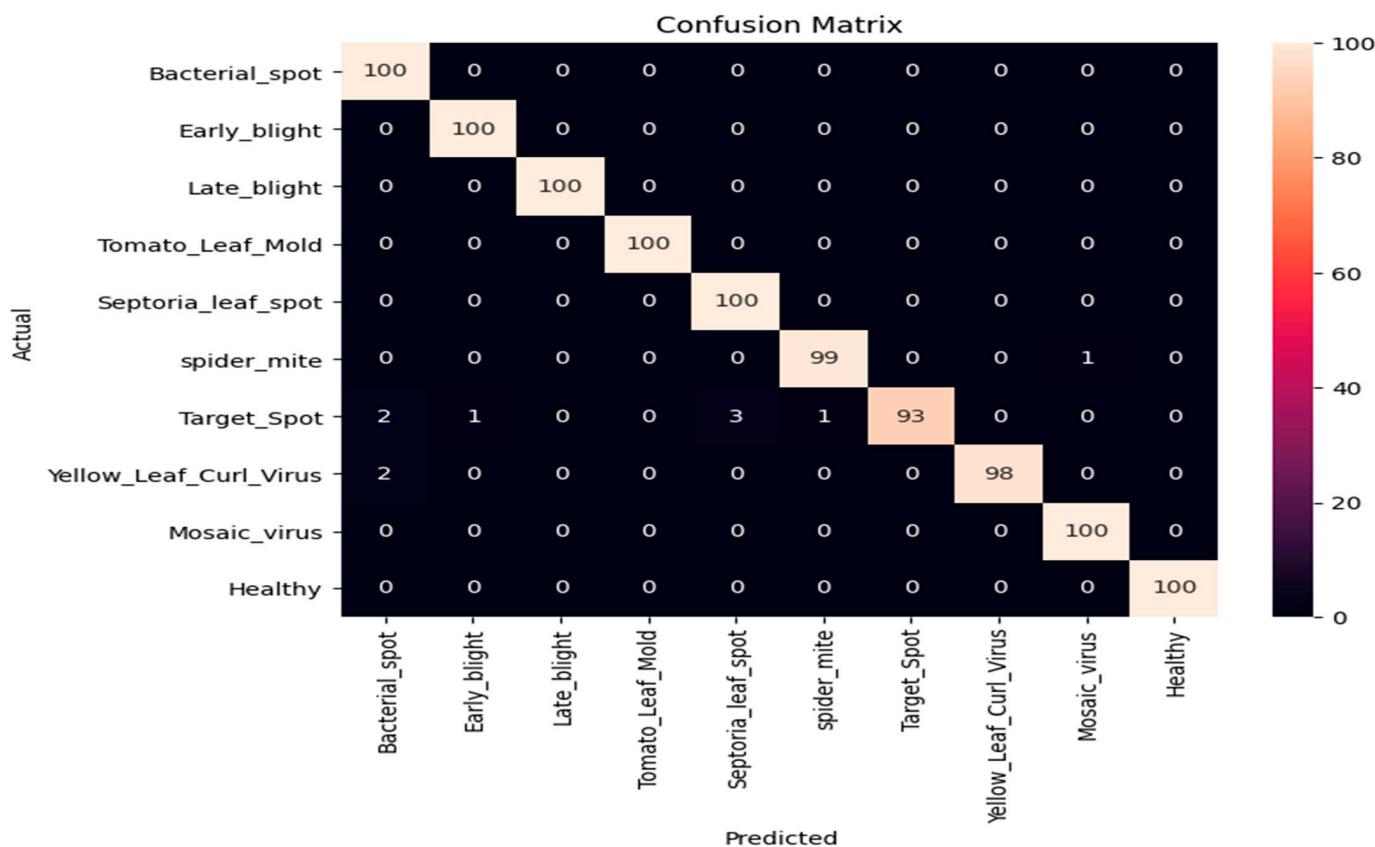


Figure 8. Confusion matrix of DenseNet121 (90% training and 10% testing).

4.2.2. Results of the ResNet50V2 Model

The results of the ResNet50V2 model with 90% training and 10% testing are presented in Table 6. The ResNet50V2 model was trained using eight batch sizes and the SGD optimizer for 100 epochs. To prevent overfitting and minimize training time, the early-stop method was employed, which ended the training after 20 epochs. The ResNet50V2 model achieved accuracies of 99.49% in training and 95.60% in testing. The results of

ResNet50V2 with 80% training and 20% testing is shown Table S2; the ResNet50V2 successfully achieved 94.31%.

Table 6. Results of ResNet50V2 model (90% training and 10% testing).

Class Name	Precision (%)	Recall (%)	F1-Score (%)	Support
Bacterial_Spot	99	100	100	100
Early_Blight	97	93	95	100
Late_Blight	88	100	93	100
Leaf_Mold	96	95	95	100
Septoria_Leaf_Spot	96	96	96	100
Spider_Mites_Two-Spotted_Spider_Mite	96	90	93	100
Target_Spot	98	87	92	100
Yellow_Leaf_Curl_Virus	100	98	99	100
Mosaic_Virus	89	100	94	100
Healthy	00	97	98	100
Accuracy			96	1000
DenseNet121_Macro Avg	0.96	96	96	1000
DenseNet121_Weighted Avg	0.96	96	96	1000

Figure 9 illustrates the effectiveness of the ResNet50V2 model in identifying tomato leaf diseases by dividing the dataset into 90% training and 10% testing. ResNet50V2's validation accuracy is 96.00%, whereas its training accuracy was initially 78.00% and reached a maximum of 99.49%. At this point in the validation process, the ResNet50V2 model's accuracy loss is less than 0.1.

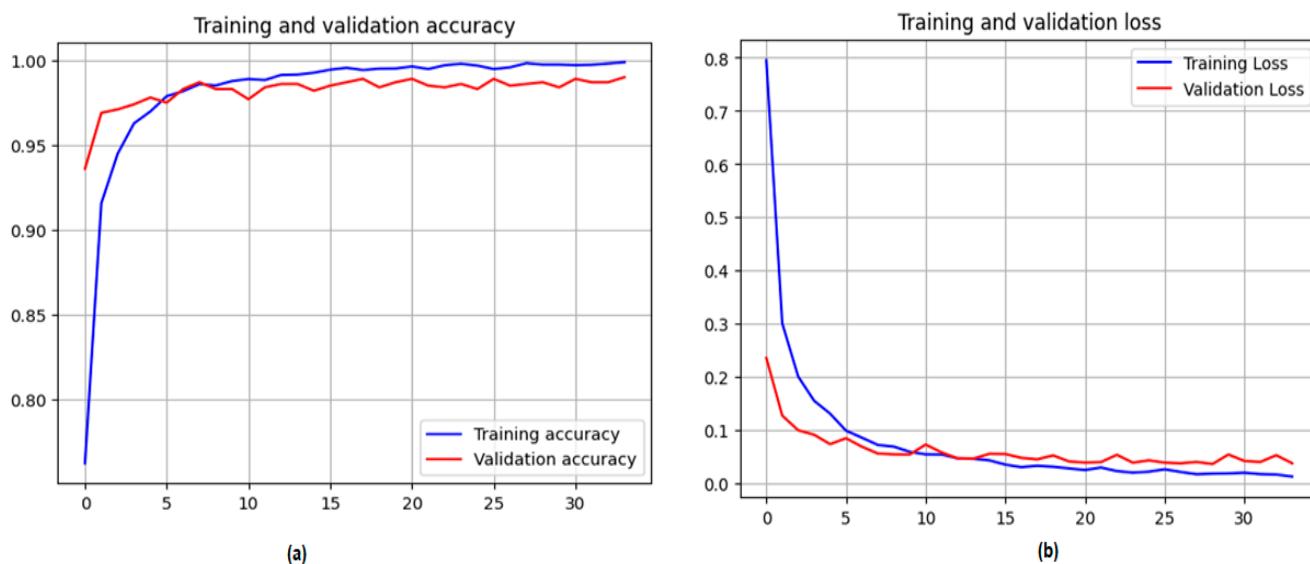


Figure 9. Performance of the ResNet50V2 model; (a) ResNet50V2 model accuracy and (b) ResNet50V2 mode loss (90% training and 10% testing).

The efficiency of the ResNet50V2 model in determining the presence of tomato leaf diseases with 80% training and 20% testing is seen in Figure S3. The accuracy of ResNet50V2 model in validation test is 94.30%. At this stage in the validation process, the accuracy loss associated with the ResNet50V2 model is less than 0.2.

The ResNet50V2 model's confusion matrix is shown in Figures 10 and S4 by dividing the dataset in 90%, 80% as training and 10%, 20% as testing. This matrix demonstrates that the model has a strong positive impact on tomato disease detection and that it misclassifies 42 out of every 1000 samples. The suggested ResNet50V2 model can predict the tested classes using the training dataset with 99.49% accuracy, as shown by the results represented

in the confusion matrix, 90% as training and 10% testing, whereas the misclassification of ResNet50V2 model with 80% training and 20% testing is 54 simples for all the classes.

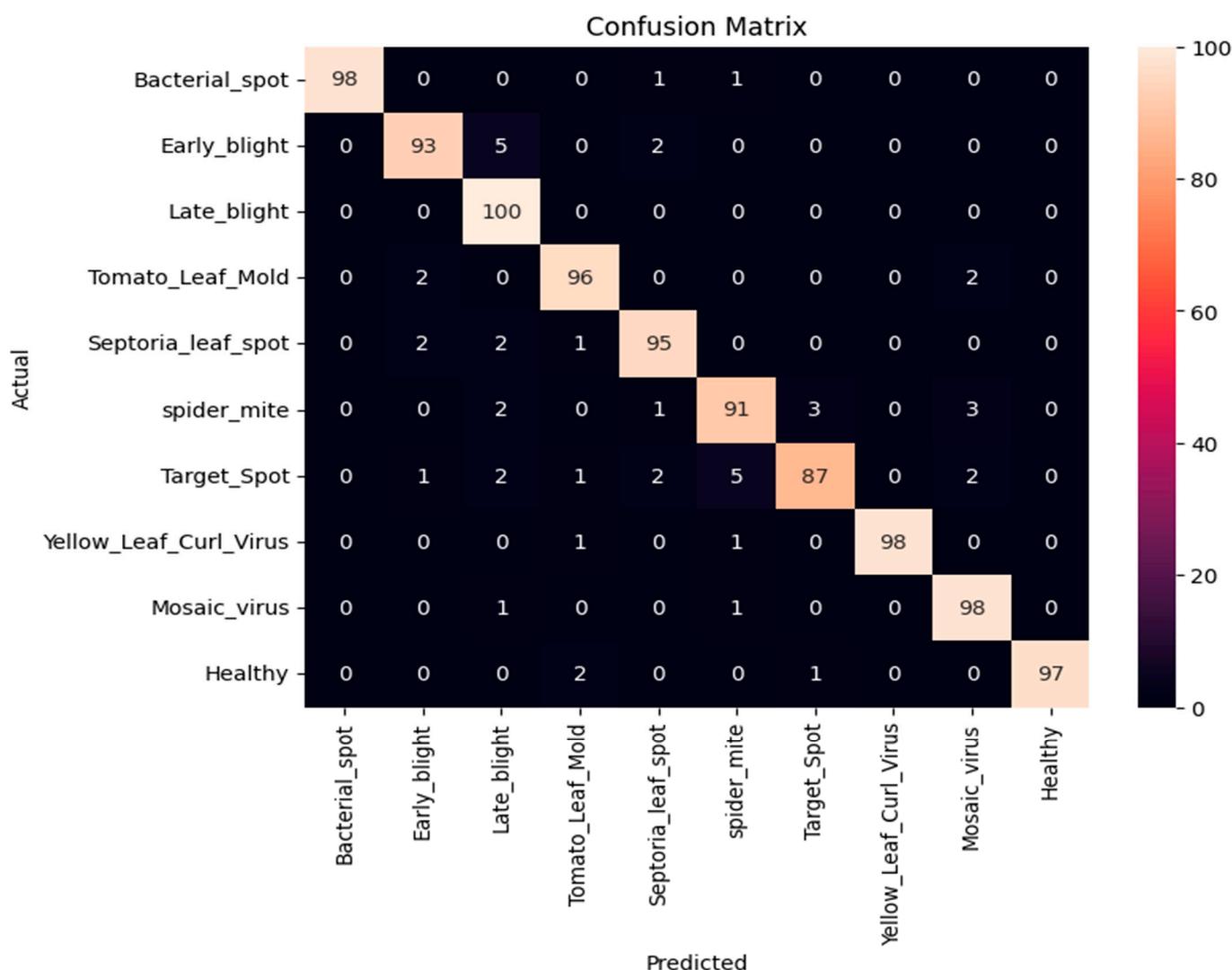


Figure 10. The ResNet50V2 model's confusion matrix (90% training and 10% testing).

This is the case because the results show that the model was able to predict the classes correctly. Examining the findings enables us to make this observation for ourselves. The confusion matrix that DenseNet121 produces demonstrates that the model has a strong positive impact on tomato disease detection, with only 10 misclassified samples out of a total of 1000 samples.

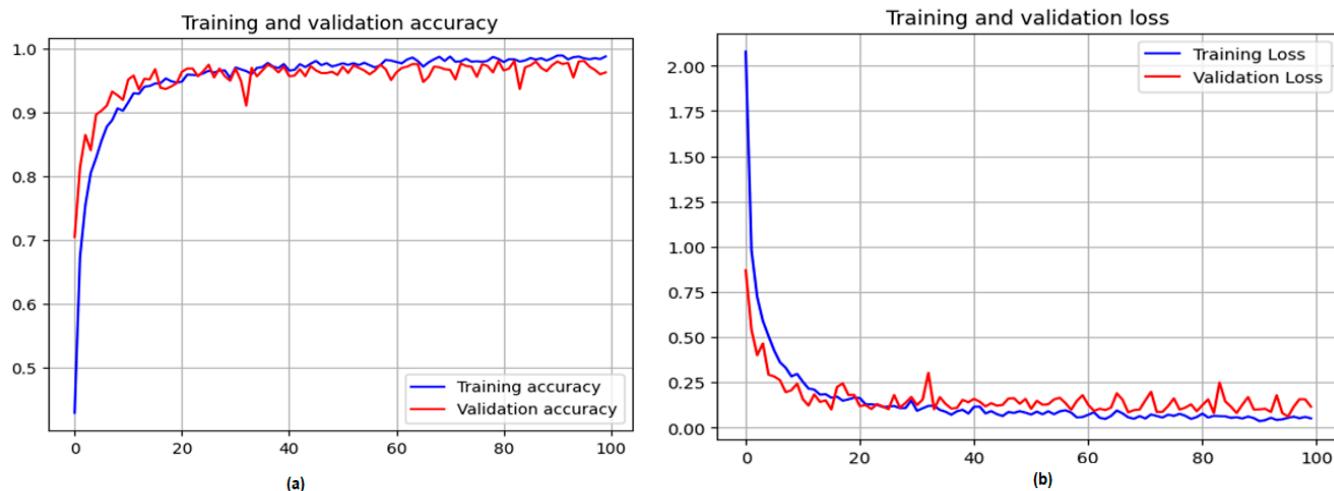
4.2.3. VIT Model Results

The results achieved by the VIT model's classification performance for each class described with 9% training and 210% testing within the experimental dataset are shown in Table 7. Because of this, we are able to deduce the performance of the suggested model, which has the ability to categorize diseases with an accuracy that is more than 98.00%. Based on the data that are reflected in the table, it can be seen that the resulting recall metric value is high for each category that is specified in the dataset. The VIT model was trained using eight batch sizes and the SGD optimizer for 100 epochs. The model achieved 98.00% accuracy on the training and testing data. The results of the VIT model, by splitting the dataset into 80% training and 20% testing, are shown in Table S3.

Table 7. Results of ViT model (90% training and 10% testing).

Class Name	Precision (%)	Recall (%)	F1-Score (%)	Support
Bacterial_Spot	99	94	96	100
Early_Blight	97	99	98	100
Late_Blight	98	100	99	100
Leaf_Mold	99	96	97	100
Septoria_Leaf_Spot	99	99	99	100
Spider_Mites_Two-Spotted_Spider_Mite	00	98	99	100
Target_Spot	95	99	97	100
Yellow_Leaf_Curl_Virus	98	97	97	100
Mosaic_Virus	100	100	100	100
Healthy	95	98	97	100
Accuracy				
DenseNet121_Macro Avg			98	1000
DenseNet121_Weighted Avg	98	98	98	1000
Bacterial_Spot	98	98	98	1000

Figure 11 shows a comparison of the training and validation accuracies by dividing the dataset in 90% training and 10% testing. Figure 11a demonstrates that an accuracy rate of 98.00% may be obtained by setting the training stop at 100 epochs and keeping the rate of learning at 0.0001. Figure 11b compares validation and training losses. Consequently, given the study's methodology, it is reasonable to predict that increasing the number of iterations would lead to an increase in data accuracy. Conversely, if the training phase duration increases, so will the total number of epochs. Figure S5 shows the accuracy and loss performance of the ViT model using 80% training and 20% testing.

**Figure 11.** ViT model performance; (a) ViT model accuracy and (b) ViT mode loss (90% training and 10% testing).

As seen in Figure 12, the confusion matrix was devised to provide a visual representation of the classification performance of the tomato leaf dataset obtained from the ViT model, or the number of images that were correctly categorized in a given number of iterations during validation and training, respectively. According to the ViT model's confusion matrix, the model has a strong positive impact on tomato disease detection, with only 20 misclassified samples out of 1000 samples. Figure S6 shows the confusion matrix of ViT model in 80% training and 20% testing.

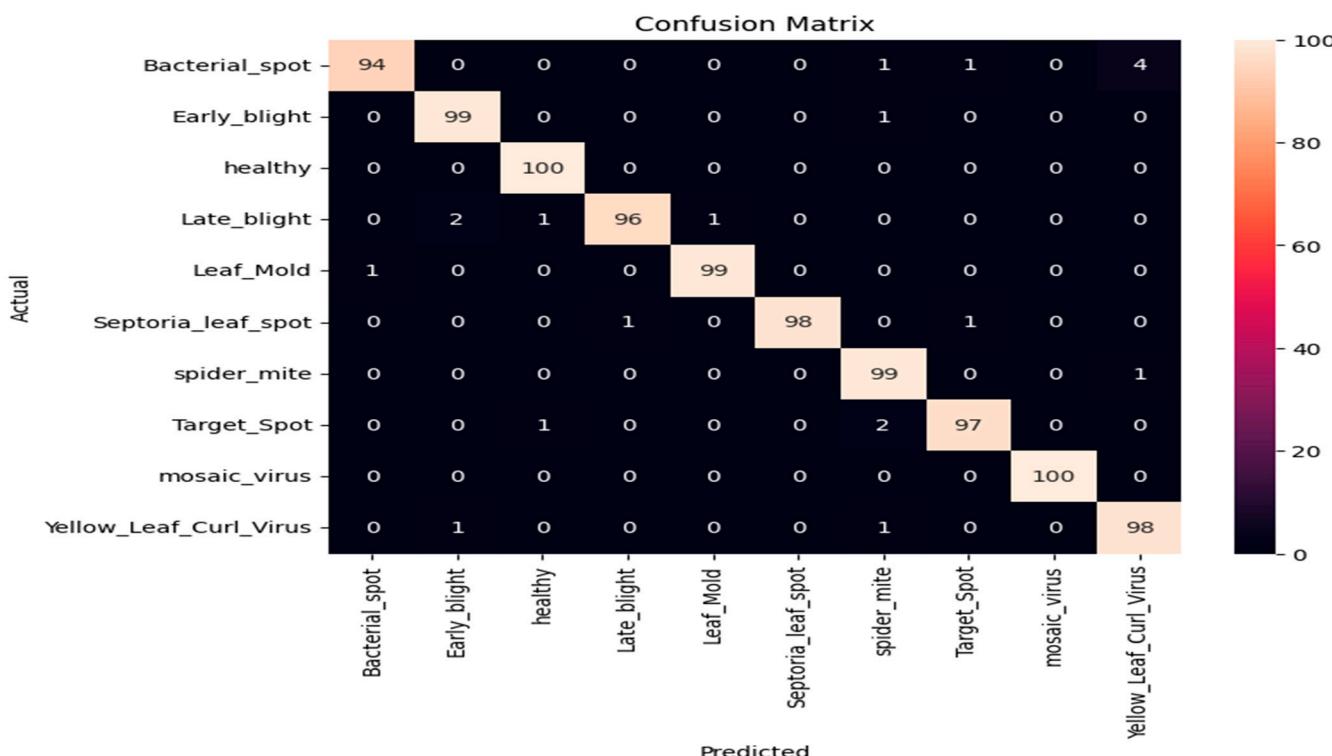


Figure 12. Confusion matrix of ViT model (90% training and 10% testing).

5. Discussion

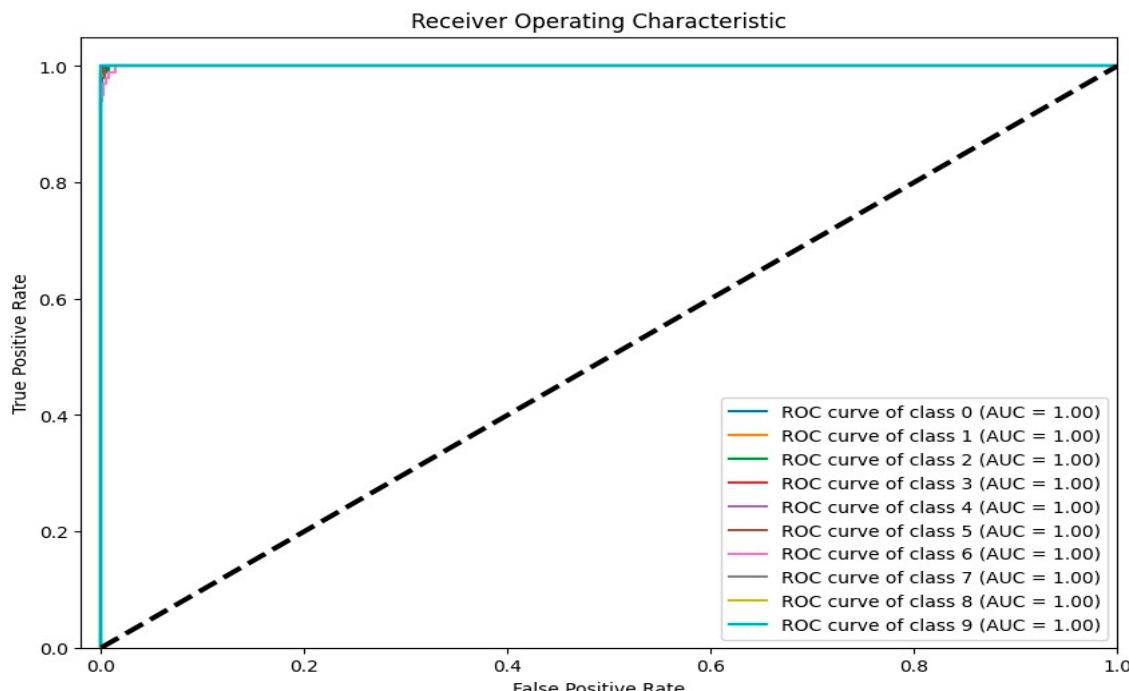
Tomato is one of the most important crops worldwide and has high economic and nutritional value. However, it is often affected by various diseases, which can reduce both yield and quality. Early detection and accurate diagnosis of tomato diseases are crucial for effective disease management and prevention.

This research further confirms the effectiveness of proposed approaches to tomato disease detection and provides valuable insight into different models' performance. The results of this study have shown significant accuracy for developing of automated systems that can detect and manage tomato plant diseases in the early stages, ultimately improving the efficiency and sustainability of tomato production.

To diagnose tomato leaf diseases, this research examined multiple CNN models that had been pretrained on the ImageNet dataset and then compared those models to the dataset. Three alternative CNN models—DenseNet121, ResNet50V2, and VIT—were trained via transfer learning. Each model was educated and validated using the same collection of tomato disease images, which included both infected and healthy examples. Table 8 shows the final result of the proposed deep leaning model at training and testing phase for detecting tomato disease. According to the findings, DenseNet121 successfully attained the highest possible training (99.88%) and test (99.00%) accuracies. In addition, its recall, accuracy, and F1 score were all above average, reaching 99.00%, 99.00%, and 98.99%, respectively. ResNet50V2 obtained a training accuracy of 99.49% and a test accuracy of 95.60%, both of which were lower than its predecessor. Its recall, accuracy, and F1 score were all lower than those of DenseNet121, reaching 95.60%, 94.80%, and 95.59%, respectively. The accuracy of the VIT's training and tests was also 98.00%. It had a recall of 98.00%, a precision score of 98.00%, and an F1 score of 98.00%. The findings indicate that DenseNet121 performed the best overall in identifying tomato diseases, followed by VIT and then ResNet50V2. The ROC plot of DenseNet121 is presented in Figure 13.

Table 8. Summarized results of proposed deep learning in training and testing phases.

Performance of Model Using 90% Training and 10% Testing of Dataset					
Model Name	Training Accuracy%	Test Accuracy%	Recall%	Precision%	F1 Score%
DenseNet121	99.88	99	99	99	98.99
ResNet50V2	99.49	95.60	95.60	95.8	95.59
ViT	98	98	98	98	97
Performance of Model Using 80% Training and 20% Testing of Dataset					
Model Name	Training Accuracy%	Test Accuracy%	Recall%	Precision%	F1 Score%
DenseNet121	99.99	98.45	98.45	94.32	98.45
ResNet50V2	99.99	94.43	94.31	98.46	94.31
ViT	99.27	94.90	94.90	94.97	94.89

**Figure 13.** ROC curve DenseNet121 model.

Additionally, a contrast was drawn between the level of difficulty provided by the suggested model and that of a number of other models. The section devoted to accuracy rates shows the individual successes of tomato leaf diseases in the datasets found in the literature. The results of the proposed DenseNet121 model, which had the best rate of accuracy (99.88%) in studies using a variety of methods other than the research recommended, are shown in Table 9 and Figure 14.

Table 9. Comparison of results of DenseNet121 against different CNN models.

References	Model	Dataset	Accuracy%
Ref. [62]	Inception-v3	Same dataset	96.60
Ref. [63]	ResNet-50		98.77
Ref. [64]	MobileNet		88.4
Ref. [65]	VGG16		93.5
Ref. [66]	CNN		98.2
Ref. [67]	ResNet50 + SeNet		96.81
Propose system	Proposed DenseNet121 model		99.64

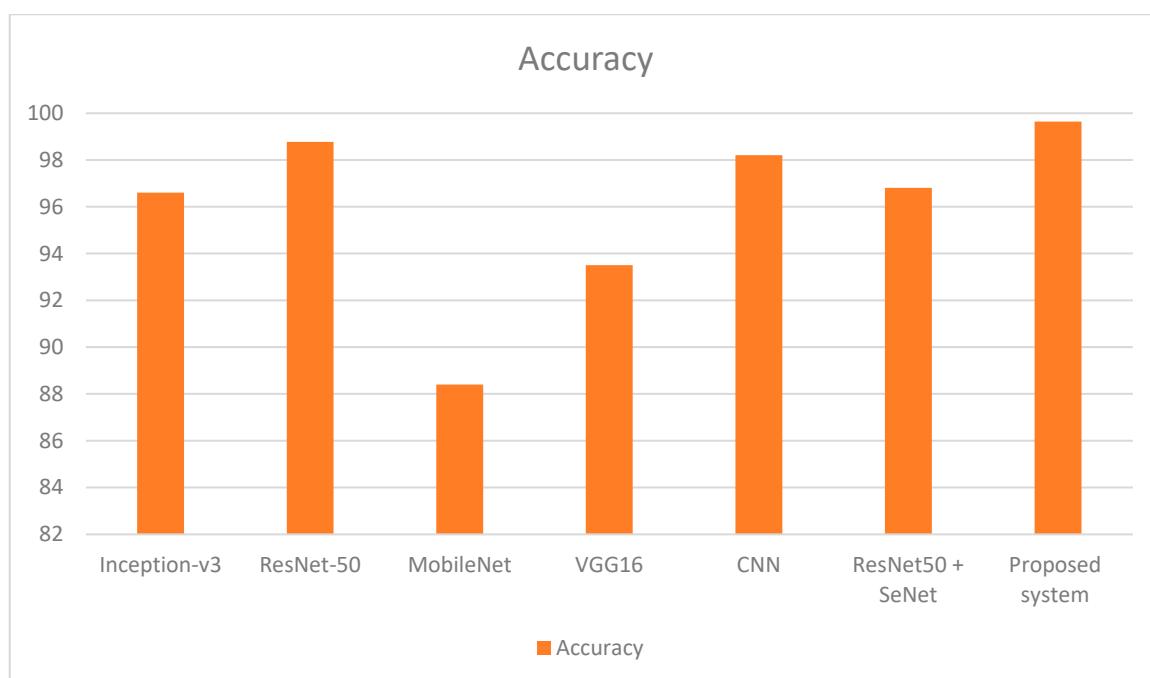


Figure 14. Comparison of results of DenseNet121 against different CNN models in terms of accuracy.

6. Conclusions

The purpose of this research was to analyze and apply many different deep-learning models to the task of diagnosing diseases that affect tomato plants. The dataset from Kaggle, which is readily accessible, was selected since it contains information on ten different diseases that might affect tomato plant leaves. Three novel CNN architectures were proposed for disease prediction and classification in tomato plants using this dataset, alongside the specialized deep learning architectures DenseNet121, ResNet50V2, and ViT models.

Deep learning has emerged as a powerful tool for detecting diseases in plants, including tomatoes. Using neural networks to analyze large datasets of plant images, deep learning models can learn to identify patterns and features that are characteristic of specific diseases. This can help farmers and researchers quickly and accurately diagnose plant diseases, allowing for more targeted treatment and prevention strategies. Based on the results of this study, it can be concluded that deep learning models, including DenseNet121, ResNet50V2, and ViT, are effective for tomato disease detection. Among these models, DenseNet121 showed the highest accuracy, with 99.88% on training data and 99% on testing data. The ResNet50V2 and ViT models also showed high accuracy, but their performance was lower than DenseNet121. These findings suggest that deep learning models can provide accurate and efficient solutions for tomato disease detection, which can ultimately benefit the agriculture industry. The obtained results of the analysis showed that the suggested model performed better than alternative models. The method that has been presented for recognizing the diseases that affects tomatoes is an innovative one. One of the limitations of this research is that the system has not been incorporated into a mobile application. However, it does provide a simple and low-cost method for diagnosing tomato leaf diseases by only requiring the user to take an image of the affected plant's leaf. In the future, we want to enhance the model by using more advanced forms of artificial intelligence that are supported by internet of things (IoT) technology.

Supplementary Materials: The following supporting information can be downloaded at: <https://www.mdpi.com/article/10.3390/agronomy13051184/s1>; Figure S1: Performance of DenseNet121 model; (a) DenseNet121 model accuracy, (b) DenseNet121 mode loss with (80% training and 20% testing); Figure S2: Confusion matrix of DenseNet121 with (80% training and 20 testing); Figure S3: Performance

of the ResNet50V2 model; (a) ResNet50V2 model accuracy and (b) ResNet50V2 mode loss with (80% training and 20% testing); Figure S4: The ResNet50V2 model's confusion matrix with (80% training and 20% testing); Figure S5: ViT model performance; (a) ViT model accuracy and (b) ViT mode loss with (80% training and 20% testing); Figure S6: Confusion matrix of ViT model with (80% training and 20% testing); Table S1: Results of DenseNet121 model in (80% training and 20% testing); Table S2: Results of ResNet50V2 model with (80% training and 20% testing); Table S3: Results of ViT model with (80% training and 20% testing).

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