



NANYANG
TECHNOLOGICAL
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MSAI-6124

Neuro Evolution & Fuzzy Intelligence

Week 4 – Part 2

ANFIS

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Neuro Fuzzy Inference System (NFIS)



- Also known as fuzzy neural network (FNN)
- It combines the advantages of both fuzzy system (FS) and neural network (NN):
 - From FS: A set of comprehensive fuzzy rules for interpretable computations (*transparency*)
 - From NN: A well defined network structure to facilitate parameter tuning (*learning capability*)



What is ANFIS?

- Adaptive Neuro Fuzzy Inference System
 - J-S Roger Jang, “ANFIS: Adaptive-Network-based Fuzzy Inference System”, *IEEE Transactions on Systems, Man and Cybernetics*, 23(3), 665-685, 1993.
 - Usually refer to the above specific model, but may refer to a family of FNNs adopting the same network architecture
- It employs TS type of fuzzy rules



Different Types of Fuzzy Rules

- Mamdani type:
 - Assuming there are N input features
 - The i th rule takes the form of

IF x_1 is $A_{(1,i)}$ and \dots and x_n is $A_{(n,i)}$ and \dots and x_N is $A_{(N,i)}$

THEN y_i is B_i

Both in the form of fuzzy membership function

The aggregated output to be defuzzified as an area under the curve



Different Types of Fuzzy Rules

- Takagi-Sugeno (TS) type:

- Also known as Takagi-Sugeno-Kang (TSK) type, or simply Sugeno type

IF x_1 is $A_{(1,i)}$ and \dots and x_n is $A_{(n,i)}$ and \dots and x_N is $A_{(N,i)}$

fuzzy membership function

THEN $y_i = \alpha_{(0,i)} + \alpha_{(1,i)}x_1 + \dots + \alpha_{(n,i)}x_n + \dots + \alpha_{(N,i)}x_N$

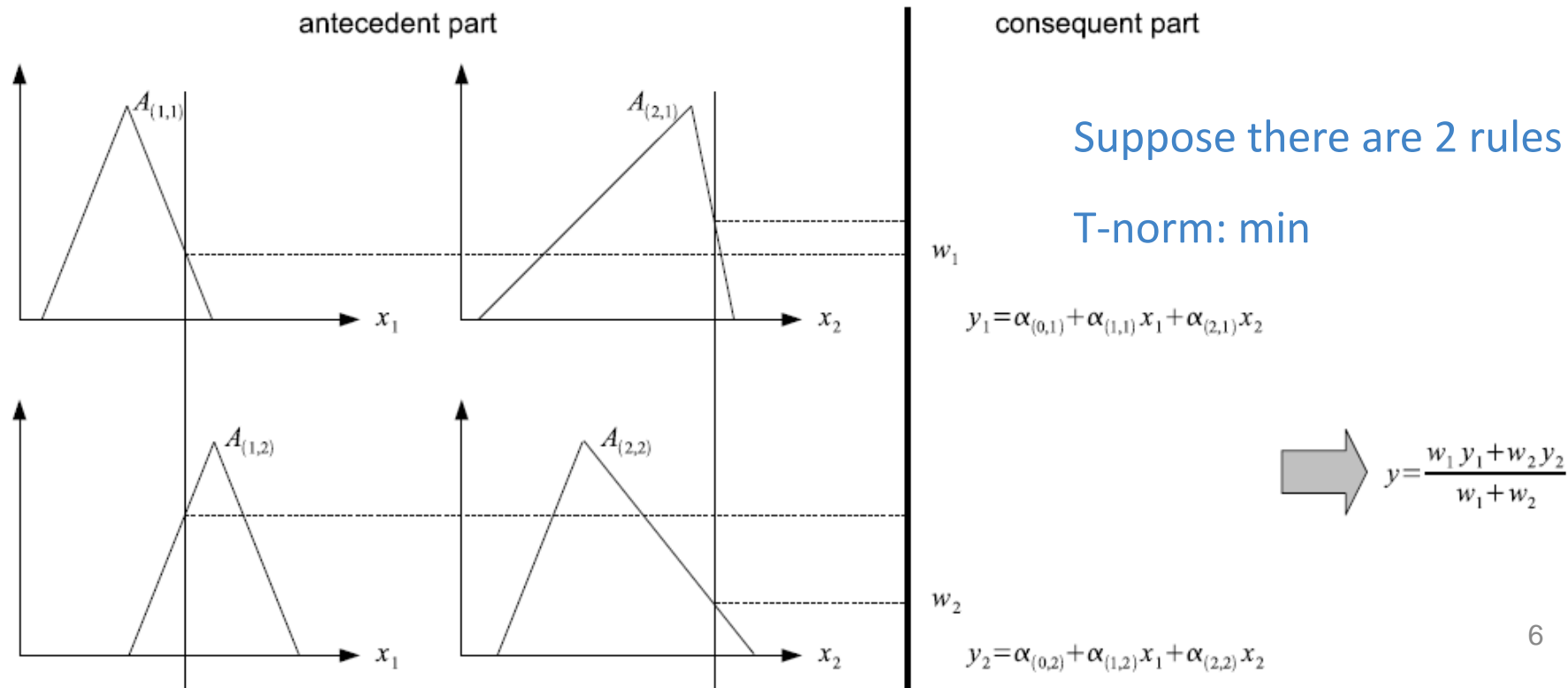
(first-order)
linear function

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The aggregated output is directly defuzzified as the weighted average



Inference in ANFIS: An Illustration





Advantages of Each Type

- Mamdani type:
 - More intuitive
 - The rule base is more interpretable
 - Well-suited to capture human experts' domain knowledge
- TS type:
 - Computationally efficient
 - Guarantees output surface continuity
 - Well-suited to mathematical analysis (e.g., linear optimization)



Essence of ANFIS

- Creates a set of fuzzy rules to model data samples using p^n linear regression functions (the antecedent part is non-linear) to minimize the overall error, e.g., the sum of squared errors (SSE):

$$SSE = \sum_j e_j^2$$

where p denotes the number of membership functions per input feature and n denotes the number of input features

Curse of dimensionality



A Zero-Order ANFIS

- Assume we have 2 inputs
 - Each has 2 membership functions
- Then we can obtain the following 4 rules

Rule 1: IF x_1 is A_1 AND x_2 is B_1 THEN $y_1 = r_1$

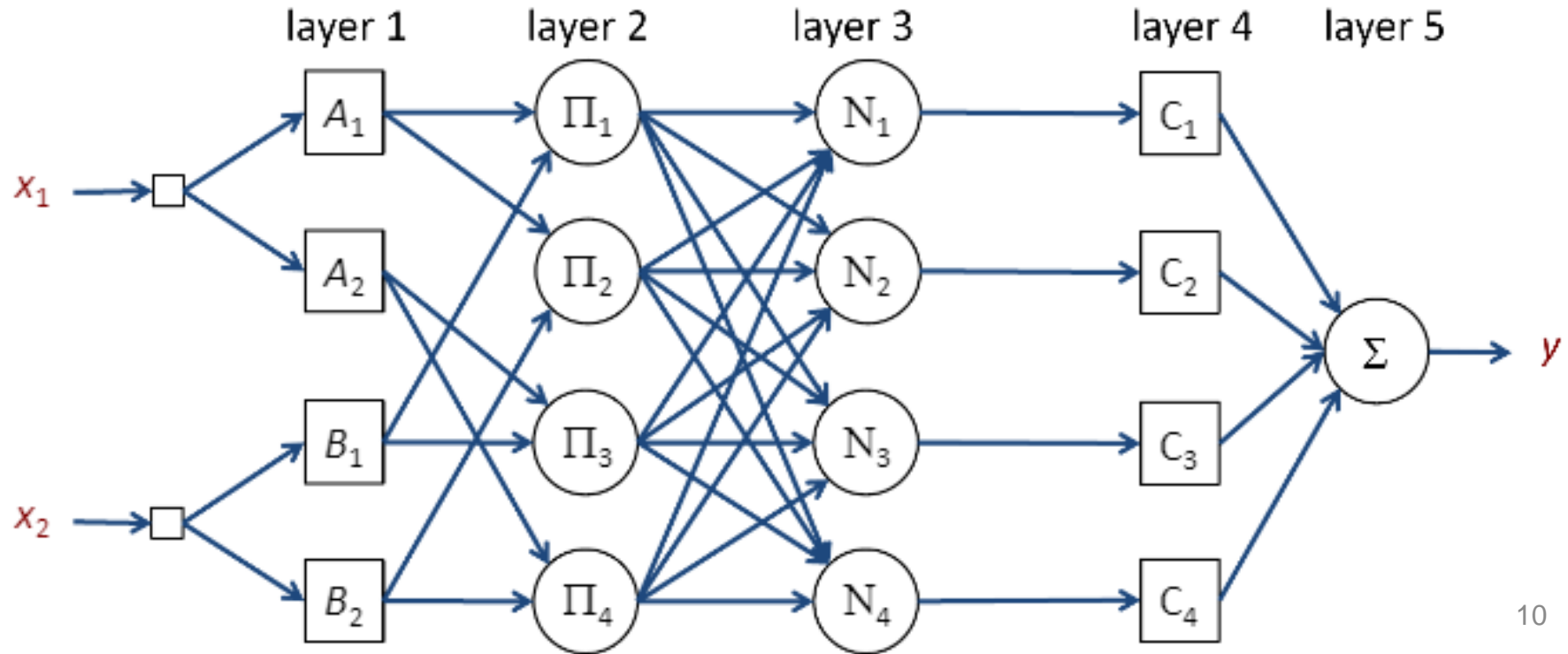
Rule 2: IF x_1 is A_1 AND x_2 is B_2 THEN $y_2 = r_2$

Rule 3: IF x_1 is A_2 AND x_2 is B_1 THEN $y_3 = r_3$

Rule 4: IF x_1 is A_2 AND x_2 is B_2 THEN $y_4 = r_4$



Corresponding ANFIS Architecture





ANFIS Layers

- L_0 (not a layer) presents the input features to ANFIS
- L_1 , **input layer** (or antecedent layer), computes the corresponding membership values w.r.t the embedded fuzzy membership functions
- L_2 , **rule-firing layer**, obtains the fuzzy rule firing (activation) strength by applying the T-norm operation
- L_3 , **normalization layer**, normalizes the obtained rule firing strengths across all fuzzy rules
- L_4 , **consequent layer**, generates the weighted output of each rule
- L_5 , **output layer**, aggregates all rules' outputs and output a single value (the summation) as the network's output



Layer 1: Input Layer

- Compute the membership values in the antecedents

$$O_{1,i} = \mu_{A,i}(x_1) \text{ for } i = 1, 2$$

$$O_{1,i} = \mu_{B,i-2}(x_2) \text{ for } i = 3, 4$$

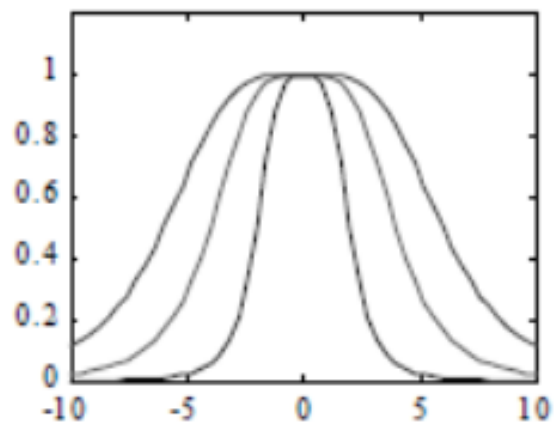
where A , B are linguistic labels

e.g., using bell-shape fmf: $\mu_A(x_1) = \frac{1}{1 + \left| \frac{x_1 - c_i}{a_i} \right|^{2b}}$

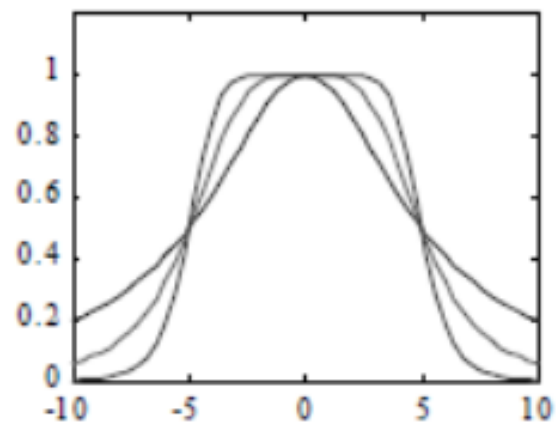
Convention of the subscripts: The first one denotes the index of the layer, and the second one denotes the index of the neuron (node)

- The output is the membership value

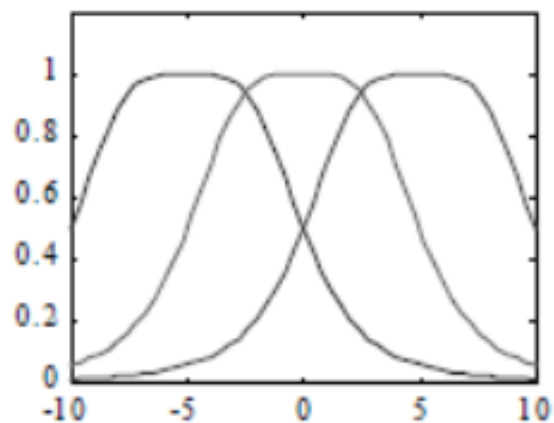
(a) Changing 'a'



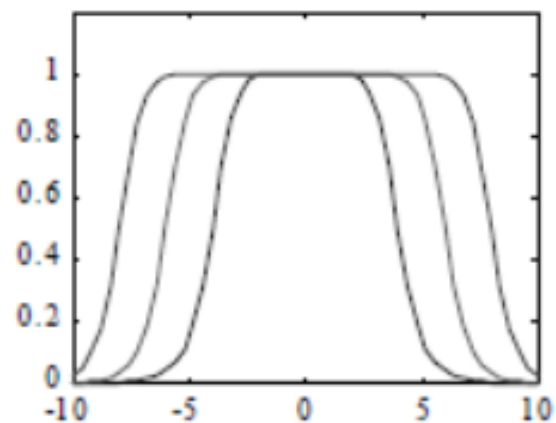
(b) Changing 'b'



(c) Changing 'c'



(d) Changing 'a' and 'b'





Layer 2: Rule-Firing Layer

- Use *T-norm* (min, **product**, etc.) operation to combine the separated antecedents into a single rule firing strength

$$O_{2,i} = w_i = \mu_{A,i}(x_1) \mu_{B,i}(x_2)$$

- The output is the firing strength of the rule
- #neurons in this layer = #rules



Layer 3: Normalization Layer

- Compute the ratio of the i th rule's firing strength over all rules' firing strengths

$$O_{3,i} = \overline{w_i} = \frac{w_i}{\sum_{j=1}^4 w_j}$$

- The output is the normalized rule firing strength
- #neurons in this layer = #rules



Layer 4: Consequent Layer

- Compute the weighted fuzzy rule output
$$O_{4,i} = \overline{w}_i f_i = \overline{w}_i (p_i x_1 + q_i x_2 + r_i)$$
 - Consequent parameters for first-order TS rule: (p_i, q_i, r_i)
 - If zero-order: $p_i = q_i = 0$
- The output is the weighted output of each rule
- #neurons in this layer = #rules



Layer 5: Output Layer

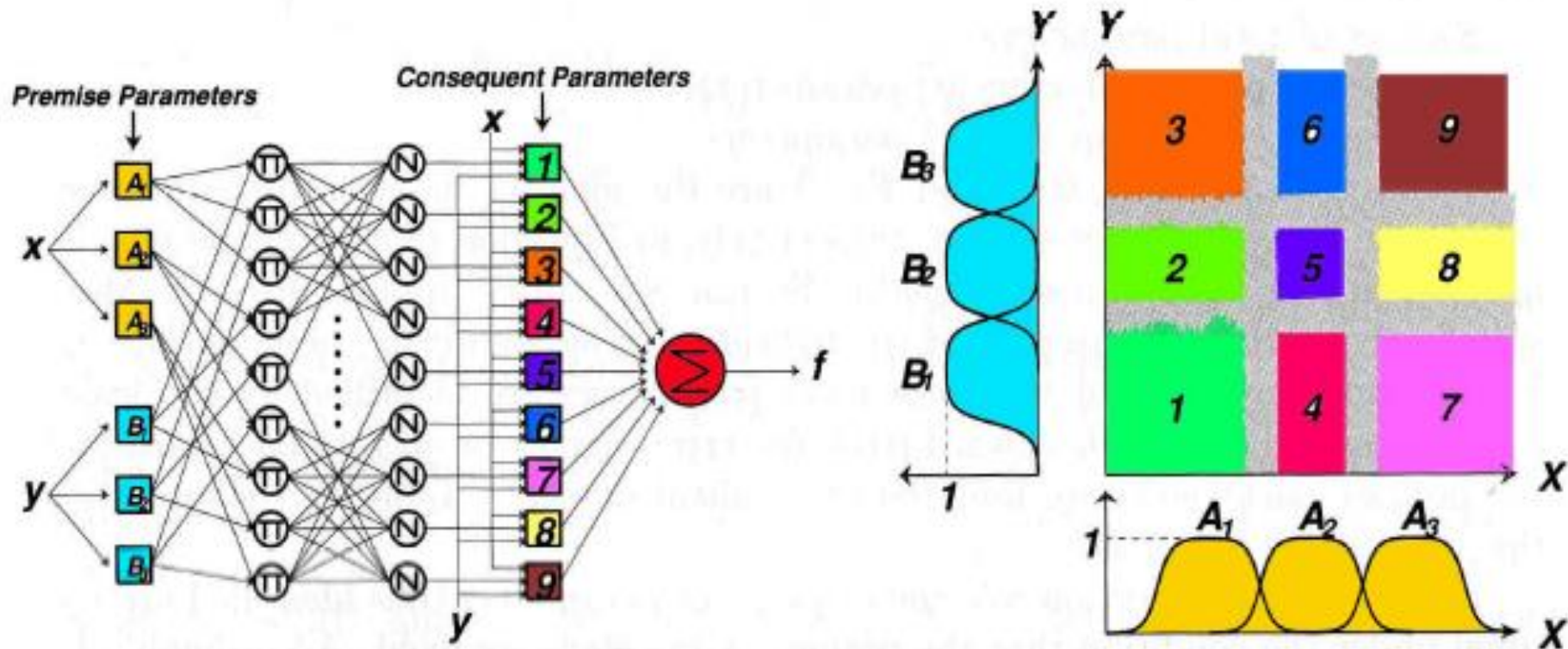
- Compute the *crisp* overall network output

$$O_{5,1} = \sum_i \bar{w}_i f_i = \frac{\sum_i w_i f_i}{\sum_i w_i}$$

- The output is the sum of all weighted fuzzy rules' outputs
- #neurons in this layer = 1



An Illustration of ANFIS with Two Inputs





Example

Rule 1: IF x is small (A1) AND y is small (B1) THEN f1=small

Rule 2: IF x is large (A2) AND y is large (B2) THEN f2=large

$$A1: \mu_{A1}(x) = \frac{1}{1 + \left| \frac{x-1}{2} \right|^2}$$

$$B1: \mu_{B1}(y) = \frac{1}{1 + \left| \frac{y-2}{2} \right|^2}$$

$$f1 = 0.1x + 0.1y + 0.1$$

$$A2: \mu_{A2}(x) = \frac{1}{1 + \left| \frac{x-9}{2} \right|^2}$$

$$B2: \mu_{B2}(y) = \frac{1}{1 + \left| \frac{y-14}{2} \right|^2}$$

$$f2 = 10x + 10y + 10$$

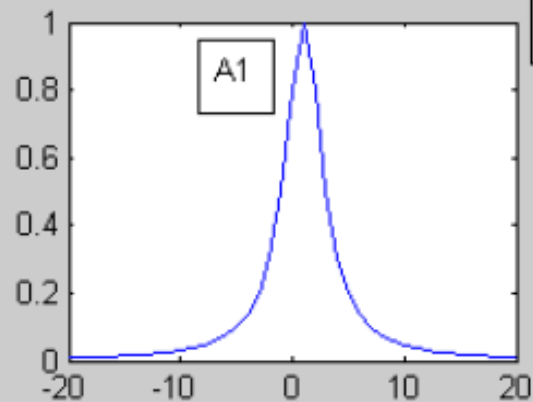
Given the trained fuzzy system above and input values of $x=3$ and $y=4$, find output of the Sugeno fuzzy system

THEN

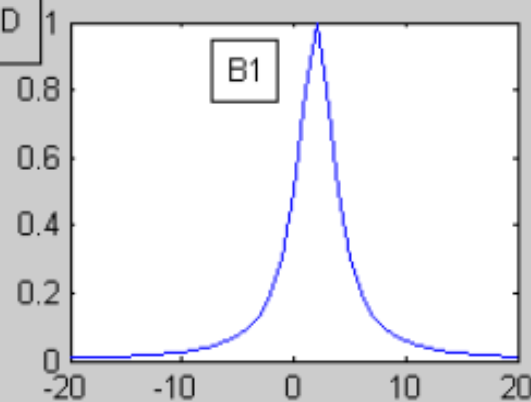
$$f1=0.1x+0.1y+0.1$$

$$f2=10x+10y+10$$

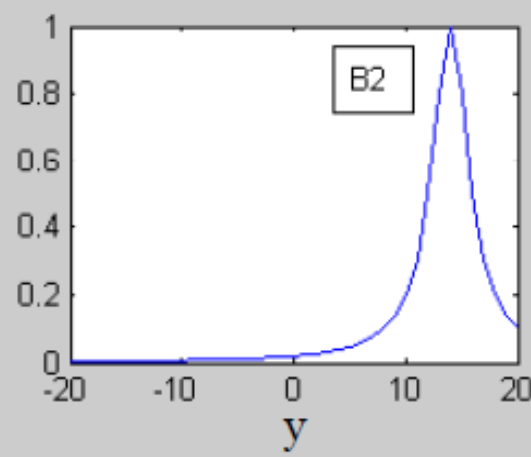
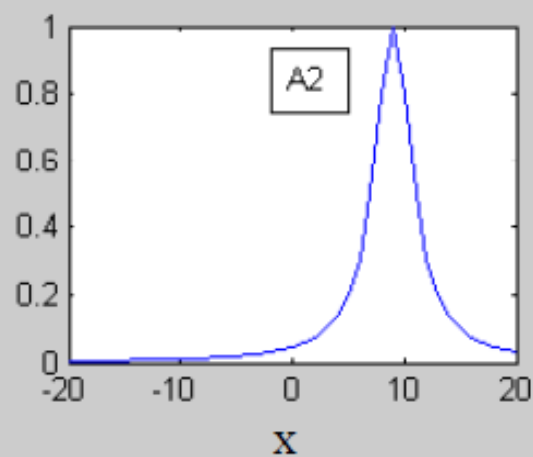
IF



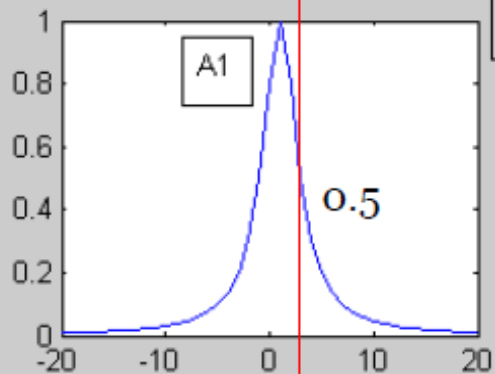
AND



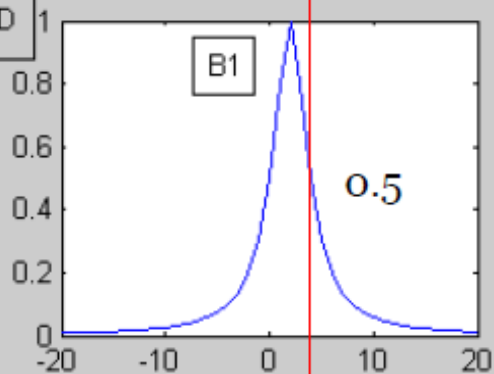
IF



IF



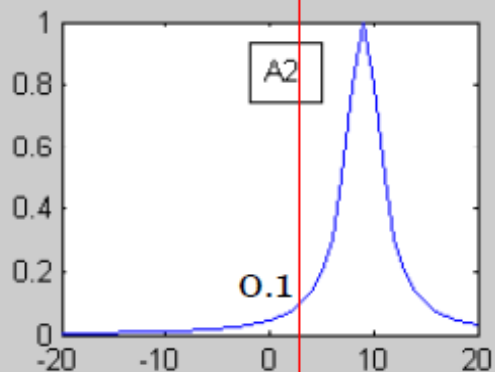
AND



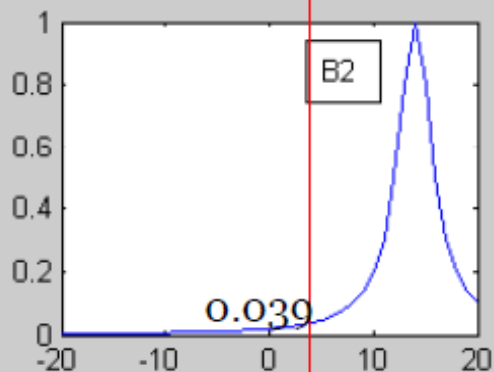
THEN

$$f1=0.1x+0.1y+0.1$$

IF



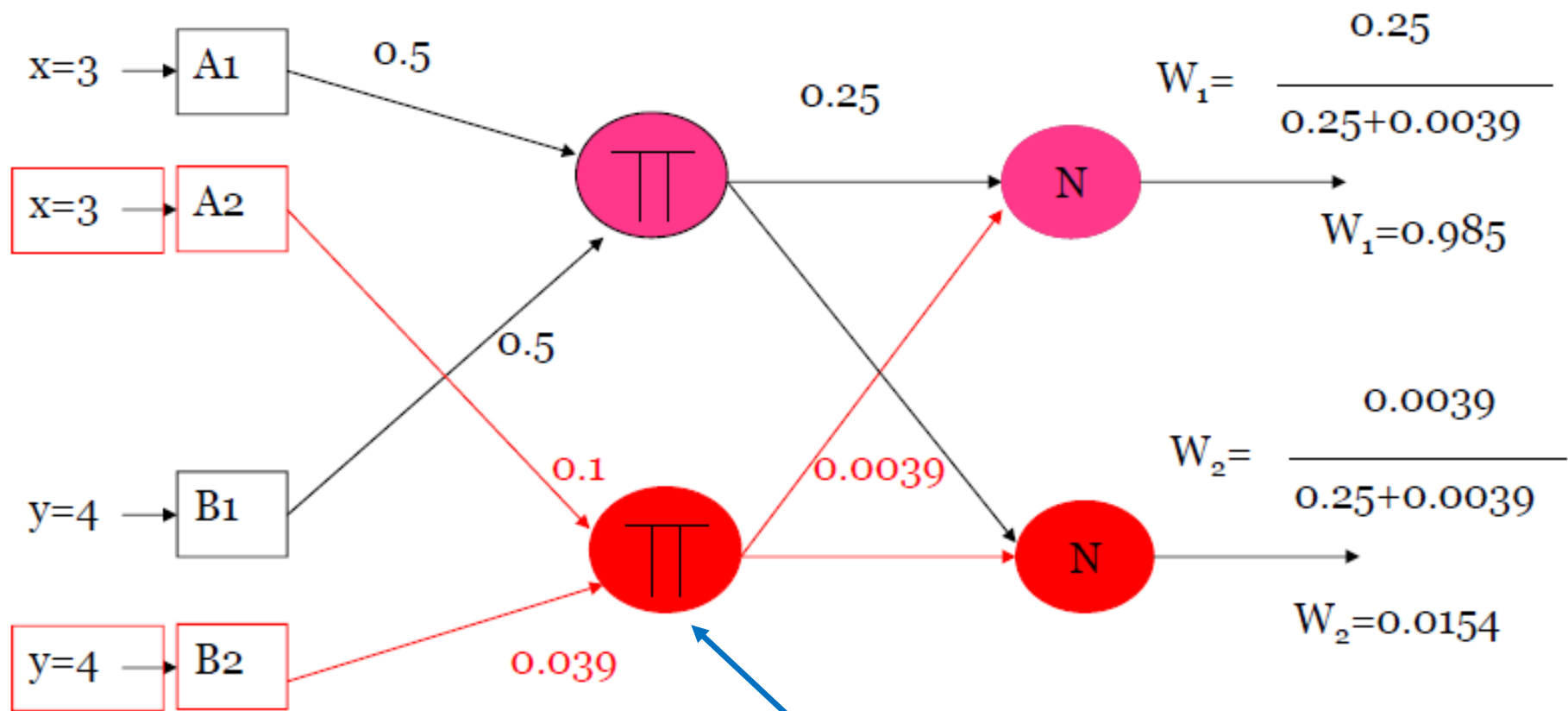
B2



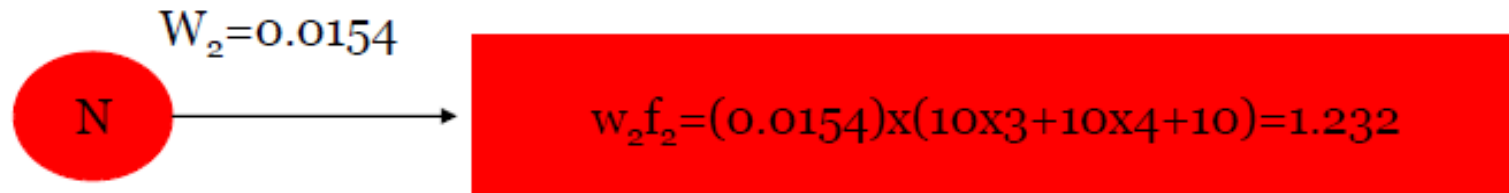
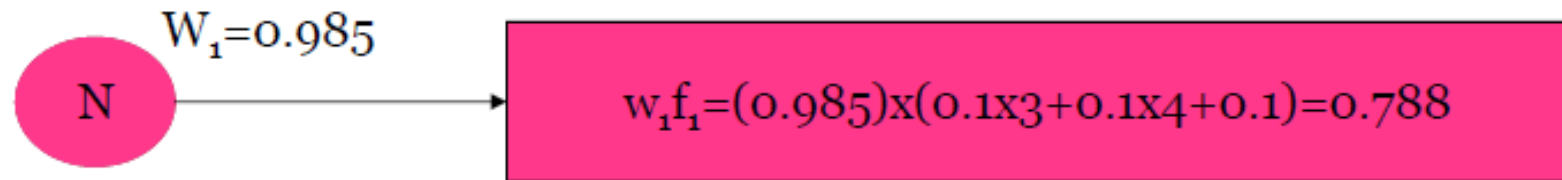
$$f2=10x+10y+10$$

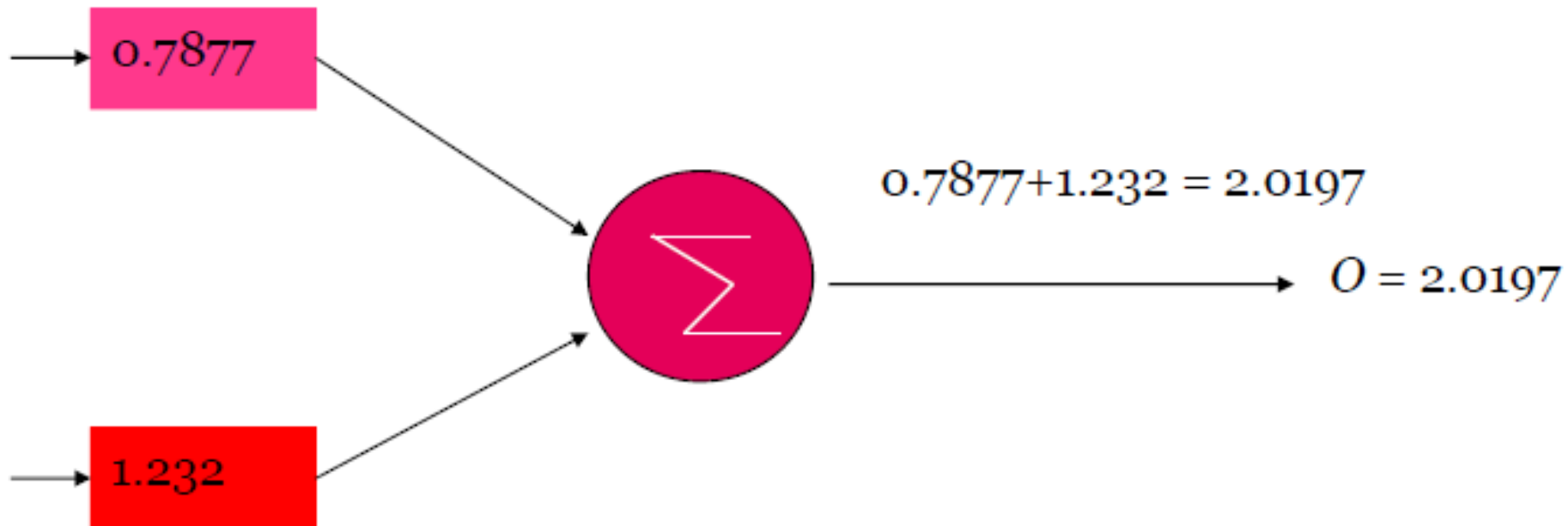
x=3

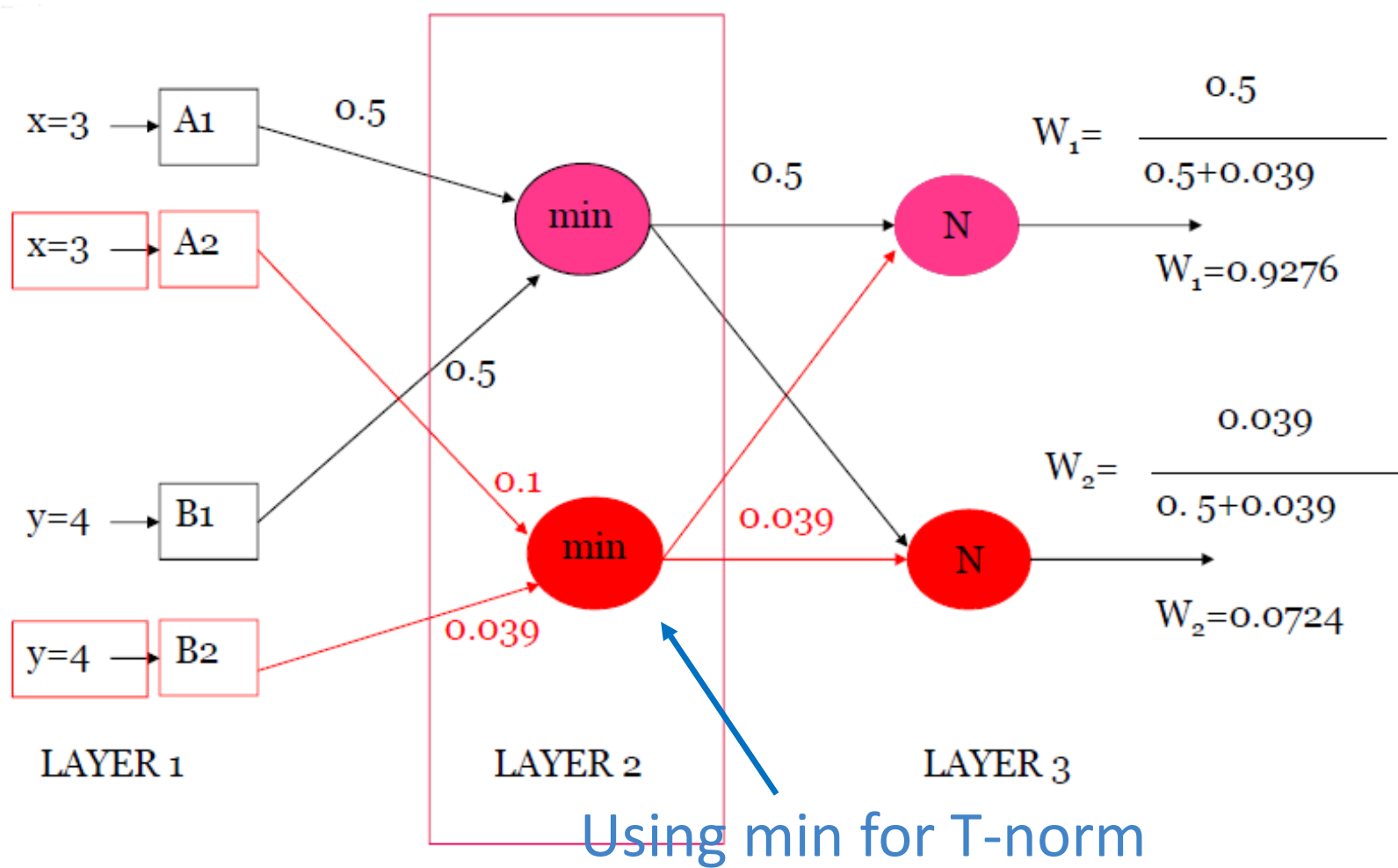
y=4

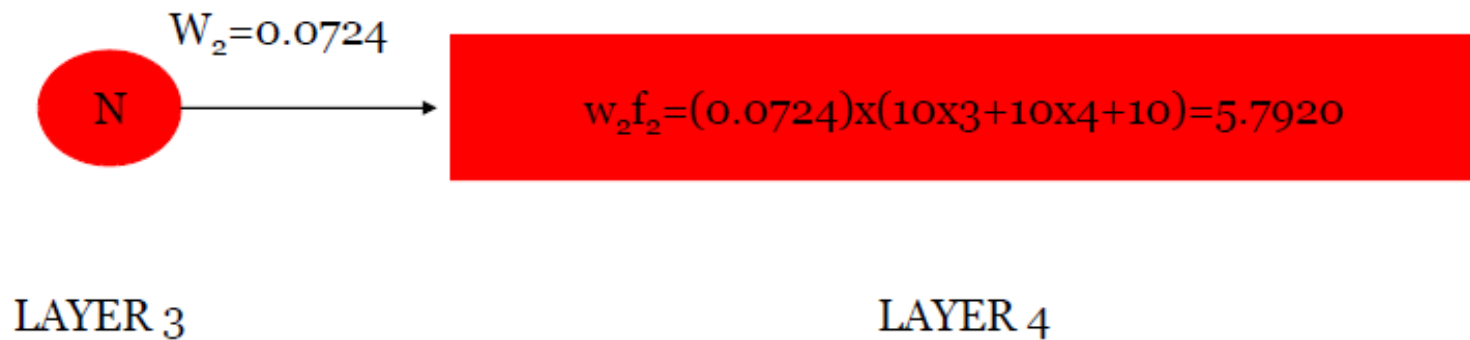
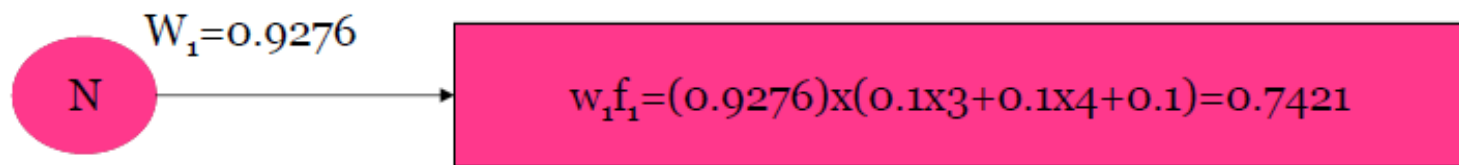


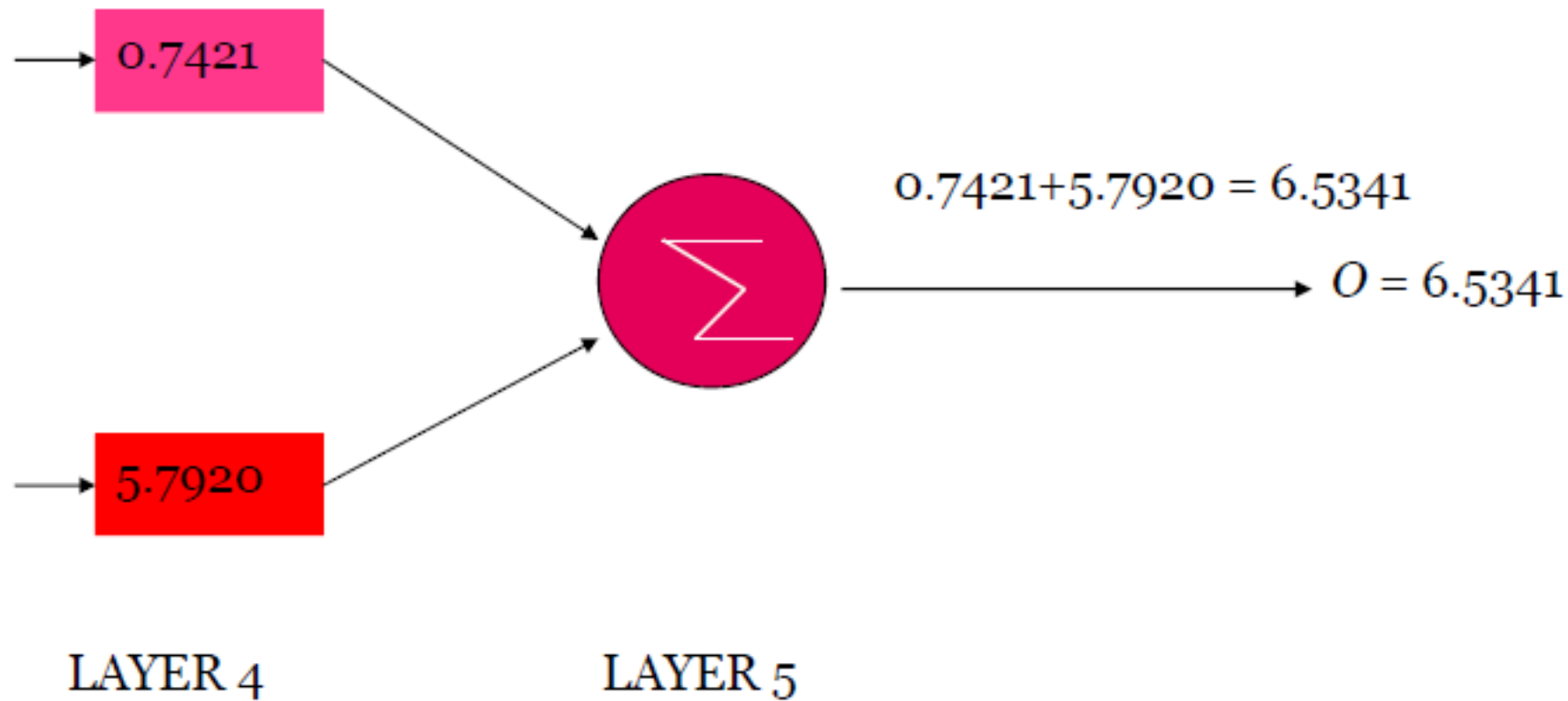
Using product for T-norm





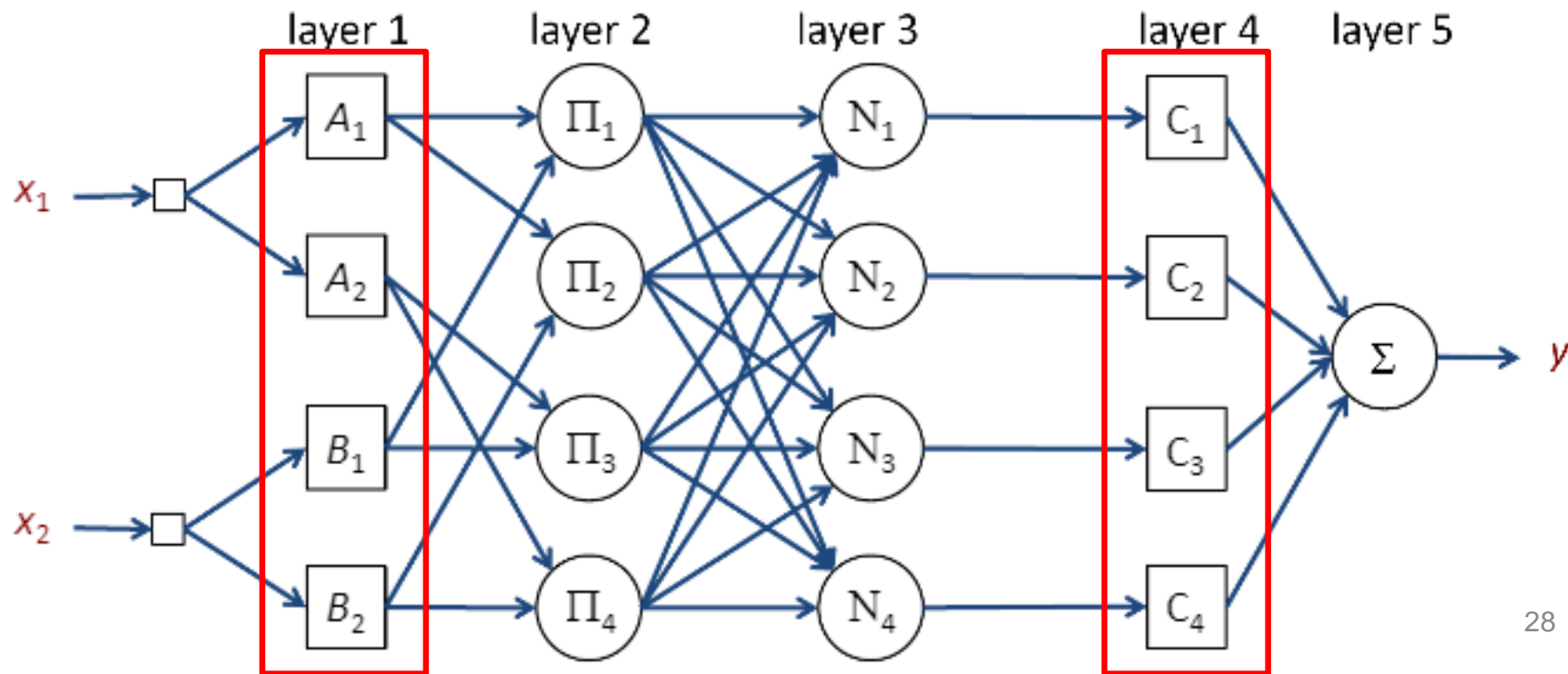








Parameters to be Tuned





Two Sets of Parameters in ANFIS

- Set 1 (S1):
 - Parameters in the fuzzy membership functions (antecedent part)
 - For non-linear functions
 - Updated by applying the gradient descent algorithm in the backward pass
- Set 2 (S2):
 - Parameters in the linear functions (consequent part)
 - For linear functions
 - Updated by applying the iterative least square error estimation algorithm in the forward pass



Number of Parameters

<u>Layer #</u>	<u>L-Type</u>	<u># Nodes</u>	<u># Param</u>
L ₀	Inputs	n	0
L ₁	Values	$(p \cdot n)$	$3 \cdot (p \cdot n) = S1 $
L ₂	Rules	p^n	0
L ₃	Normalize	p^n	0
L ₄	Lin. Funct.	p^n	$(n+1) \cdot p^n = S2 $
L ₅	Sum	1	0



Two Passes in Hybrid Training

	Forward Pass	Backward Pass
Premise Parameters (nonlinear)	Fixed	Gradient descent
Consequent parameters (linear)	Least-square estimator	Fixed
Signals	Node outputs	Error signals

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Least Square Error (LSE) Estimation

- For given parameter values of S1, we can rewrite the output of ANFIS as $B = AX$, where
 - B denotes the target outputs
 - A denotes outputs produced by Layer 3
 - X denotes the parameters in S2
- $LSE = ||AX - B||^2$, which is to be minimized
- Solving X (S2) by obtaining $X = (A^T A)^{-1} A^T B$ is computationally very heavy and often infeasible
 - where $(A^T A)^{-1} A^T$ is called pseudo inverse of A (if $(A^T A)^{-1}$ is non-singular)

Recursive Least Square (RLS) Estimator



- X can be estimated iteratively (recursively):

$$S_{i+1} = S_i - \frac{S_i a_{i+1} a_{i+1}^T S_i}{1 + a_{i+1}^T S_i a_{i+1}}$$

$$X_{i+1} = X_i + S_{i+1} a_{i+1} (b_{i+1}^T - a_{i+1}^T X_i)$$

$$S_0 = \gamma I$$

where S_{i+1} denotes the error covariance matrix when the new data sample (indexed at $i + 1$) is processed, a_{i+1} denotes the output produced by Layer 3, b_{i+1} denotes the target output, γ is a large positive number, and I is the identity matrix

Gradient Descent in Back-propagation



$$F = \sum_i \overline{w_i} f_i = \frac{\sum_i w_i f_i}{\sum_i w_i}$$

$i=1,2,3, \dots R$ # of rules

F is the calculated/estimated output value
(by ANFIS)

$$\text{Error} = e = (d - F)^2$$

d = Actual/Real Output

$$\frac{\partial e}{\partial(x, y, \dots)}$$

Gradient of ANFIS's output: Making
ANFIS's output (O) closer to actual
output (AO)

$$a(n+1) = a(n) - \eta \frac{\partial e}{\partial a}$$

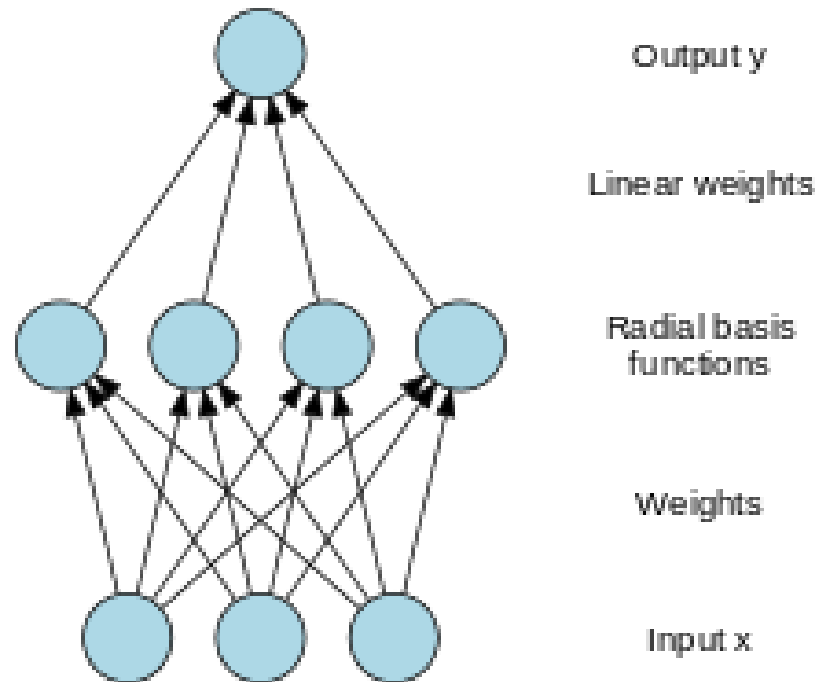
This can be done by updating values of
the parameters (e.g., a, c,...) over n
(iteration/step)

η : learning rate



ANFIS vs RBFN

- RBFN: Radial Basis Function Network
- Under certain conditions, ANFIS is functionally equivalent to RBFN



ANFIS as an Universal Approximator



- When the number of rules is not restricted, a zero-order Sugeno model has unlimited approximation power for matching any nonlinear function arbitrarily well on a compact set
- However, to give a mathematical proof, we need to apply the Stone-Weierstrass theorem



ANFIS Has Been Widely Applied

- E.g., in the financial domain:
 - Prediction of stock market return: [1](#), [2](#)
 - Prediction of stock market index: [1](#), [2](#)
 - Prediction of stock price: [1](#), [2](#)