



Department of Computer Engineering
Vishwakarma Institute Of Technology, Pune

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Title 161 - Blending Motion Capture and 3D Human Reconstruction
Techniques for Enhanced Character Animation

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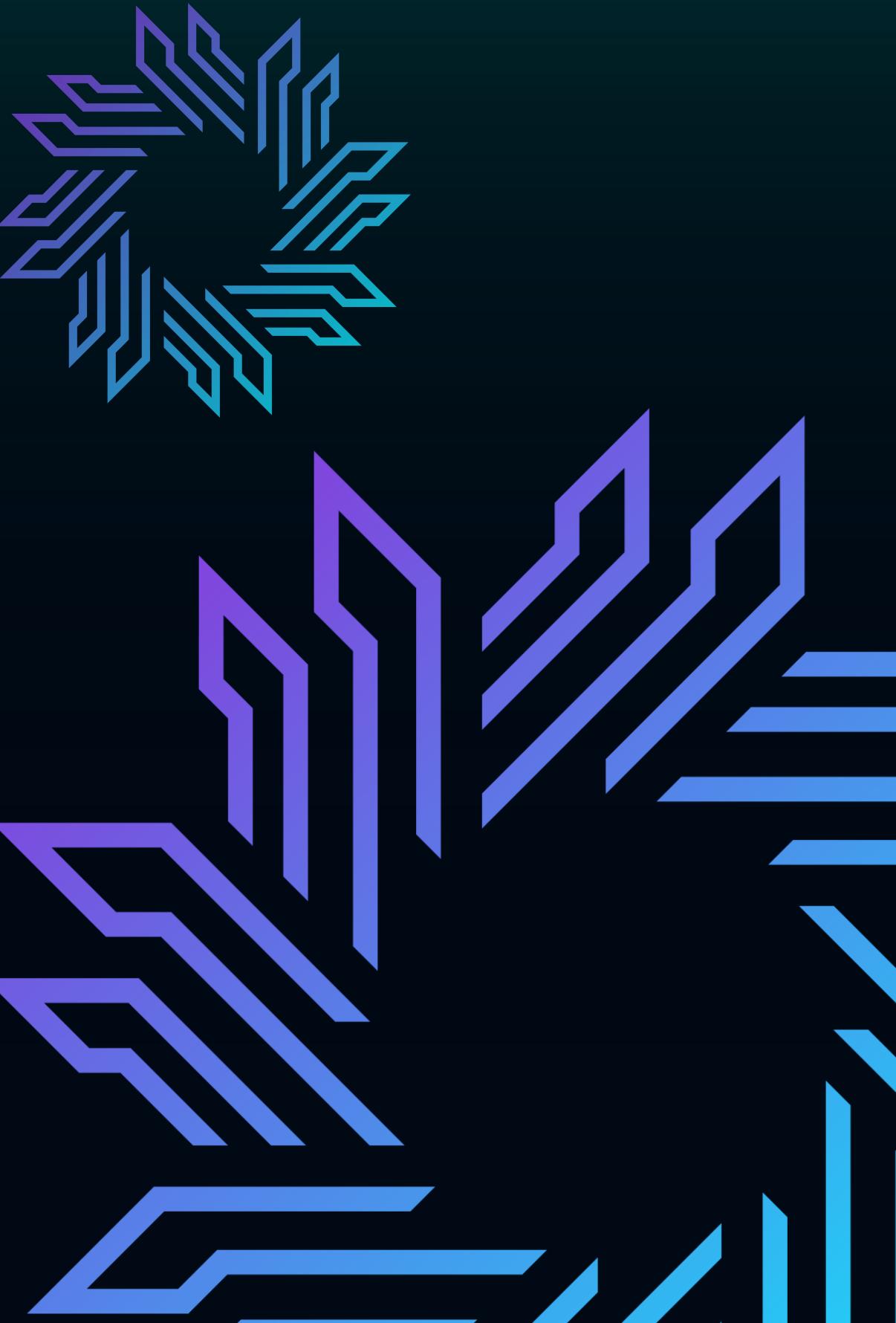


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Open Innovation

**Blending Motion Capture and 3D
Human Reconstruction Techniques
for Enhanced Character Animation**

VIT, Pune





PROBLEM STATEMENT

We aim to revolutionize motion capture by combining 3D modeling and real-time motion tracking. With state-of-the-art algorithms and hardware, we provide an efficient solution for film and video game production. Our system enables precise tracking and generates high-quality 3D models with minimal lag time, reducing production costs and increasing development speed.



Proposed Solution

Generating 3D human models from 2D images is costly, time-consuming, and requires specialized software and hardware. That's where our solution comes into limelight.

PIFuHD(Pixel aligned Implicit Function for High Resolution 3D Human Digitization) generates 3D models in seconds, greatly improving workflow efficiency compared to traditional methods. 3DDFA is a powerful facial analysis technique that utilizes deep learning algorithms to accurately capture facial landmarks and reconstruct detailed 3D facial structures, enabling realistic and dynamic facial animations.

MeshMarvel Mocap captures precise motion data, useful for animation and virtual reality with high accuracy and fidelity.

Open-source PIFuHD can be modified and used by anyone, allowing for community contributions and improvements.

PIFuHD and MeshMarvel Mocap definitely prove to be affordable and work with standard hardware, unlike expensive traditional motion capture and 3D modeling methods.



Objectives:

- To demonstrate how PIFuHD and 3DDFA can be used to build a high-quality 3D model from a single 2D image and show examples of the resulting models.
- To show how the 3D model built using PIFuHD and 3DDFA can be combined with real-time motion capture data using MeshMarvel to create a realistic and dynamic animation.
- To discuss the potential applications of this technology in various fields, such as virtual reality, gaming, film, and medicine.
- To highlight the challenges and limitations of the project and suggest areas for future research and development .
- To engage the audience by using visual aids, demonstrations, and interactive elements, such as a live motion capture performance or a virtual reality simulation.

What is Machine Learning?



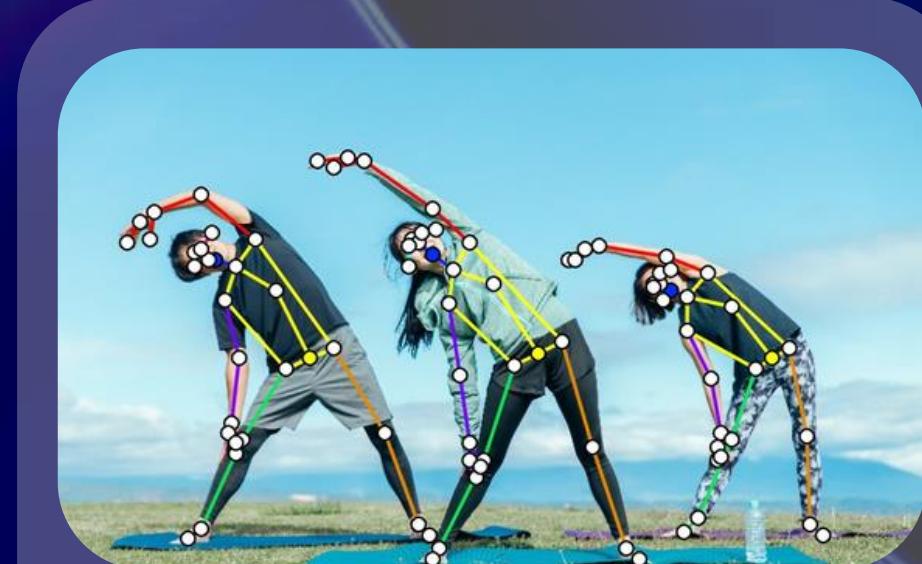


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PIFuHD and 3DDFA through Blender

PifuHD and 3DDFA generates 3D models from 2D images, Blender adds armature and prepares models, while Python automates the workflow.



MeshMarvel MoCap

MeshMarvel MotionCap is a plugin which we have built for Blender to create AR scenes. Import models, add camera, preview on mobile, and export.



Intel® Iris® and Git

Git was used for version control and team collaboration, and computation during the project was performed using Intel Iris Pro 1536MB.



UNDERLYING MATH: PIFUHD

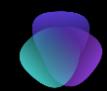
- Consider Image as a variable input I . The 3D space is defined as $\mathbf{X} = (X_x, Y_y, Z_z) \forall X_x, X_y, X_z \in \mathbb{R}$
- The Occupancy Values are calculated using the given function:
- The functional image embeddings are extracted from a loci $\mathbf{x} = (X_x, X_y)$ from the image I , thus defined as $\Phi(\mathbf{x}, I)$.
- Now for \mathbf{X} space in mesh, the function f is given:

$$f(\mathbf{X}, I) = \begin{cases} 1 & \text{if } \mathbf{X} \text{ is inside mesh surface} \\ 0 & \text{otherwise,} \end{cases}$$

$$f(\mathbf{X}, I) = g(\Phi(\mathbf{x}, I), Z),$$

Note: The functions Φ is implemented in the system using CNN architecture and the g function is implemented through Multilayer Perceptron (MLP).

These functions are multi-aligned and used twice: for a lower image resolution (for global structure) as a source and a higher image resolution (for fine detailing).



UNDERLYING MATH: 3DDFA

- The traditional 3D Mutable Structure (3DMM) S can be delineated as

$$S = \bar{S} + A_{id}\alpha_{id} + A_{exp}\alpha_{exp},$$

- $T = f [R; t_3]$, where $T \in R^{3 \times 4}$ is constructed by a scale factor f , a rotation matrix R and a translation vector $t_3 = ?^d$
 $[t_{2d} O]$

$$V_{2d}(p) = Pr * T * \begin{bmatrix} S + A\alpha \\ 1 \end{bmatrix}$$

- Our regression objective is described as
 $p = [T, \alpha]$

- For meta-joint optimization of p :

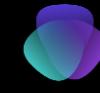
- The VDC minimizes the vertex distances between the fitted 3D face and the ground truth

$$\mathcal{L}_{vdc} = \|V_{3d}(p) - V_{3d}(p^g)\|^2$$

- The fWPDC assigns different weights w to each parameter.

$$\mathcal{L}_{fwpdc} = \|w_T \cdot (T - T^g)\|^2 + \|w_\alpha \cdot (\alpha - \alpha^g)\|^2$$

$$w = (w_1, w_2, \dots, w_i, \dots, w_n),
p_{de,i} = (p_g 1, p_g 2, \dots, p_i, \dots, p_g n)$$



UNDERLYING MATH: MESHMARVEL MOCAP

- Quaternions are used for implying rotations.

$$Q = a + bi + cj + dk$$

here a, b, c, d denote real number coordinates in the 3D arena.

- For a quaternion q, the quaternion rotations are calculated using the formula

$$Q_{rotated} = Q \cdot Q_v \cdot Q_{conjugate}$$

- Q_v is the vector along which rotations are taking place, expressed in quaternion format for rotatory estimation.

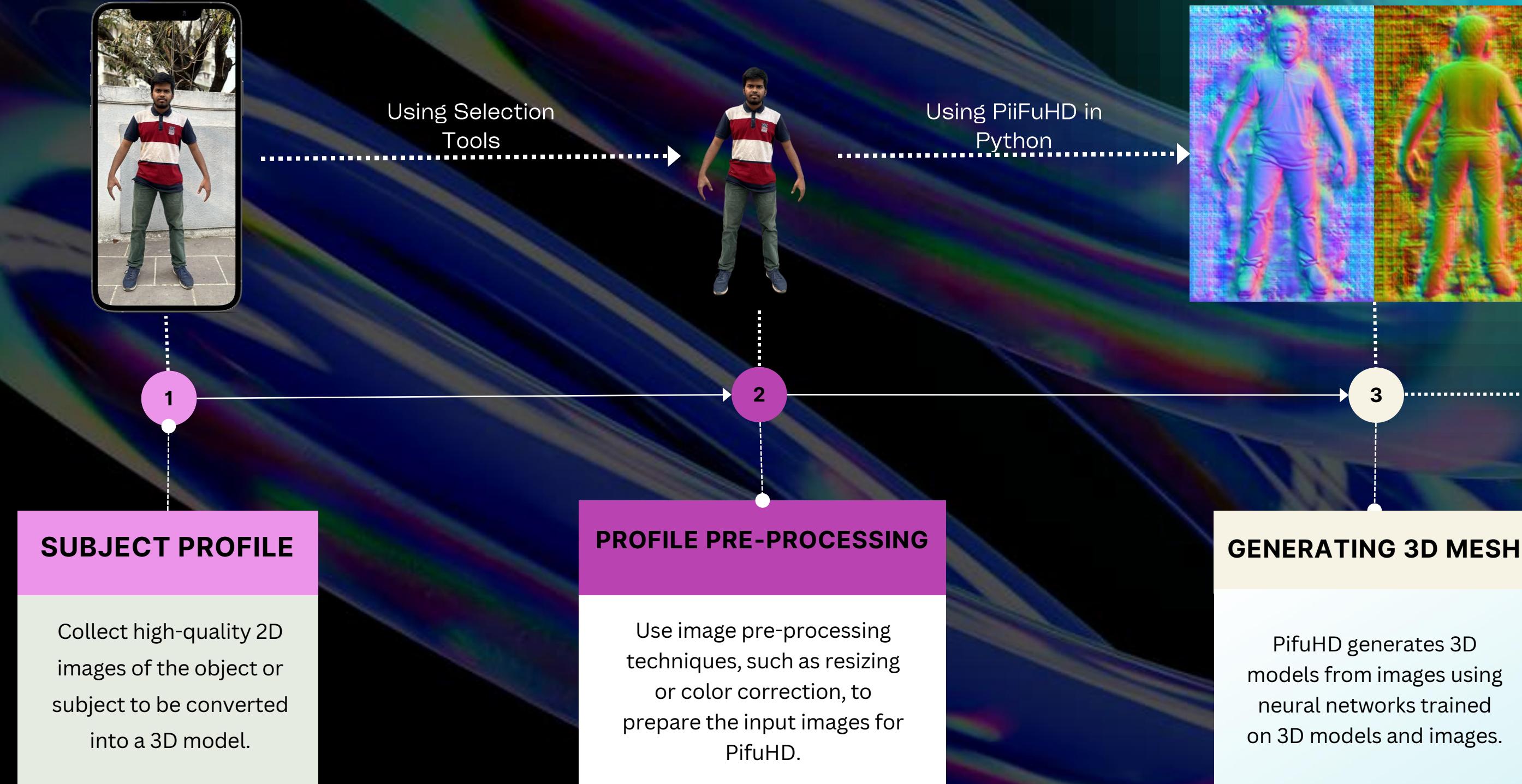
- The quaternions are converted to matrices. For a quaternion $q = a + bi + cj + dk$, the matrix can be represented as

$$Mq = \begin{bmatrix} 1 - 2c^2 - 2d^2 & 2bc - 2ad & 2bd + 2ac \\ 2bc + 2ad & 1 - 2b^2 - 2d^2 & 2cd - 2ab \\ 2bd - 2ac & 2cd + 2ab & 1 - 2b^2 - 2c^2 \end{bmatrix}$$

- The importance of quaternion units in Mocap is their inherent ability to circumvent gimbal lock and facilitate smooth interpolation.

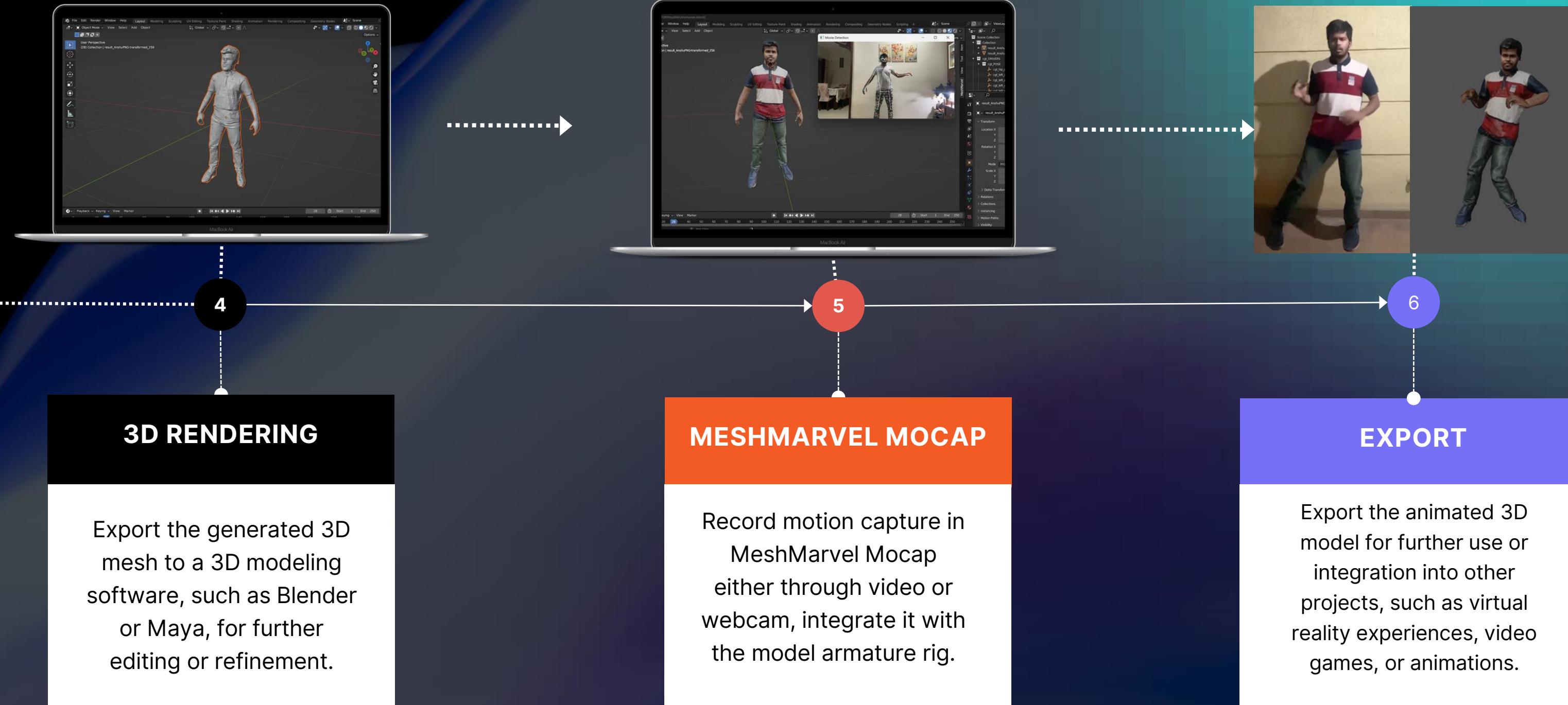


Flowchart for model creation:





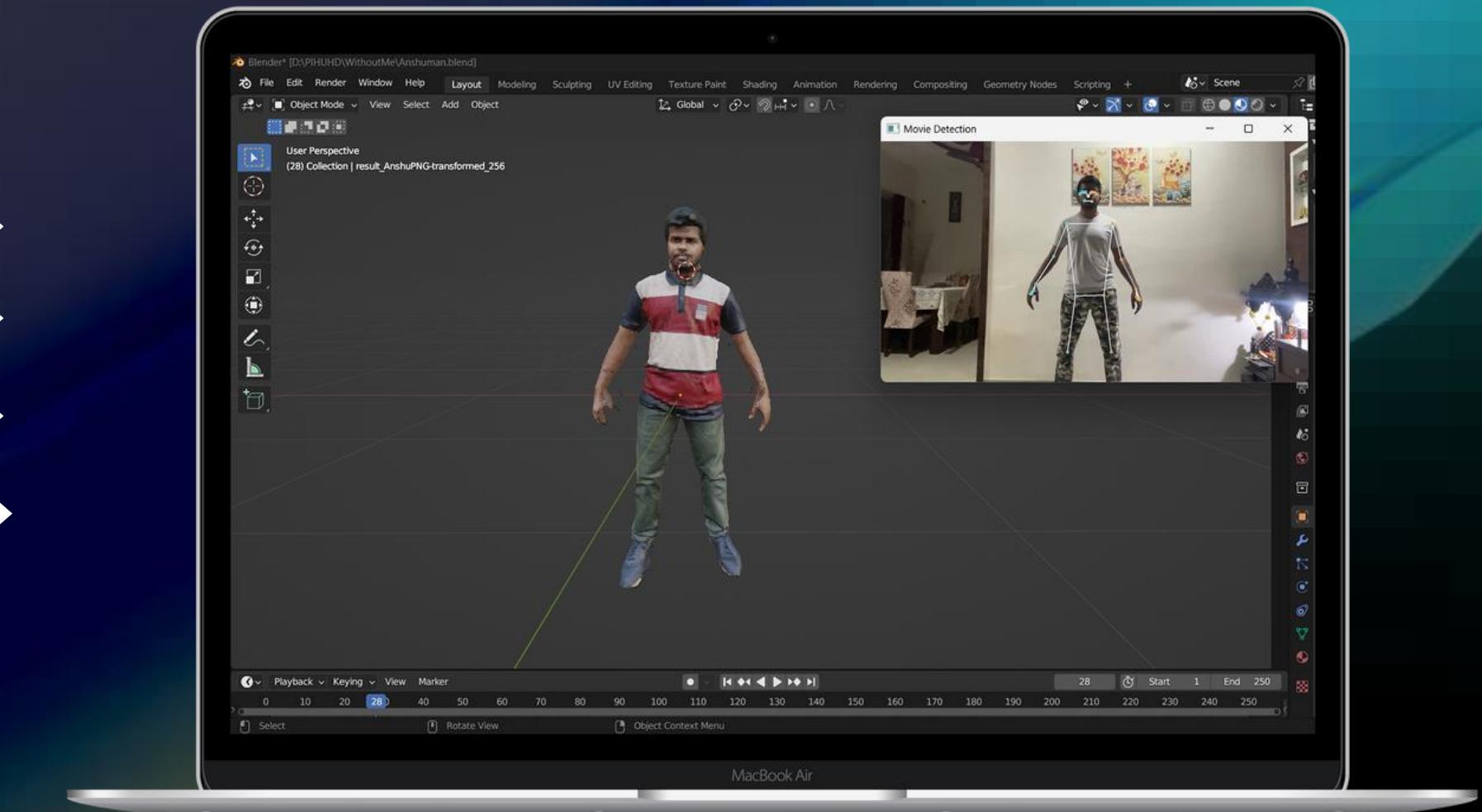
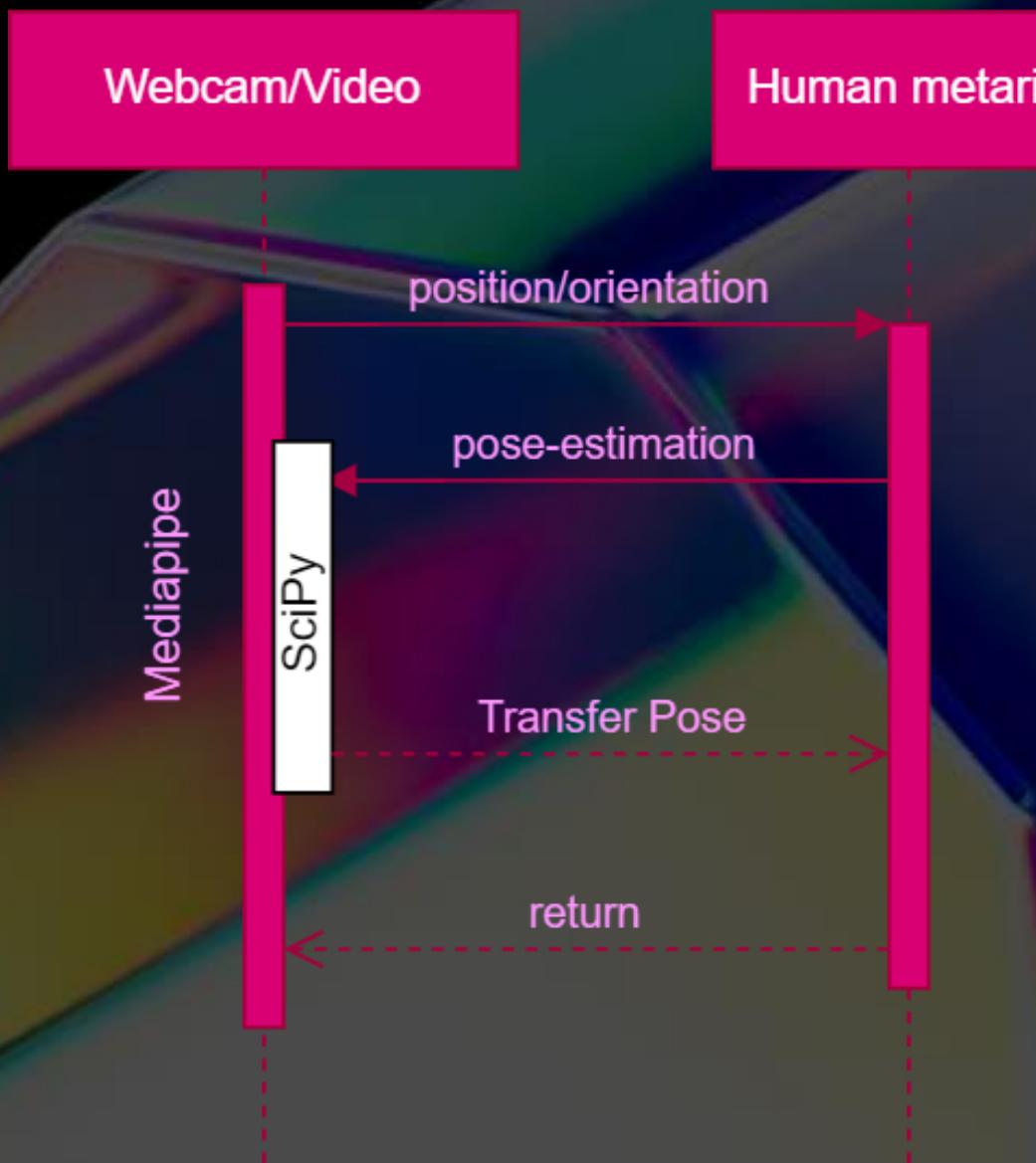
Flowchart for model creation(Contd.):





Flowchart for Motion Capture:

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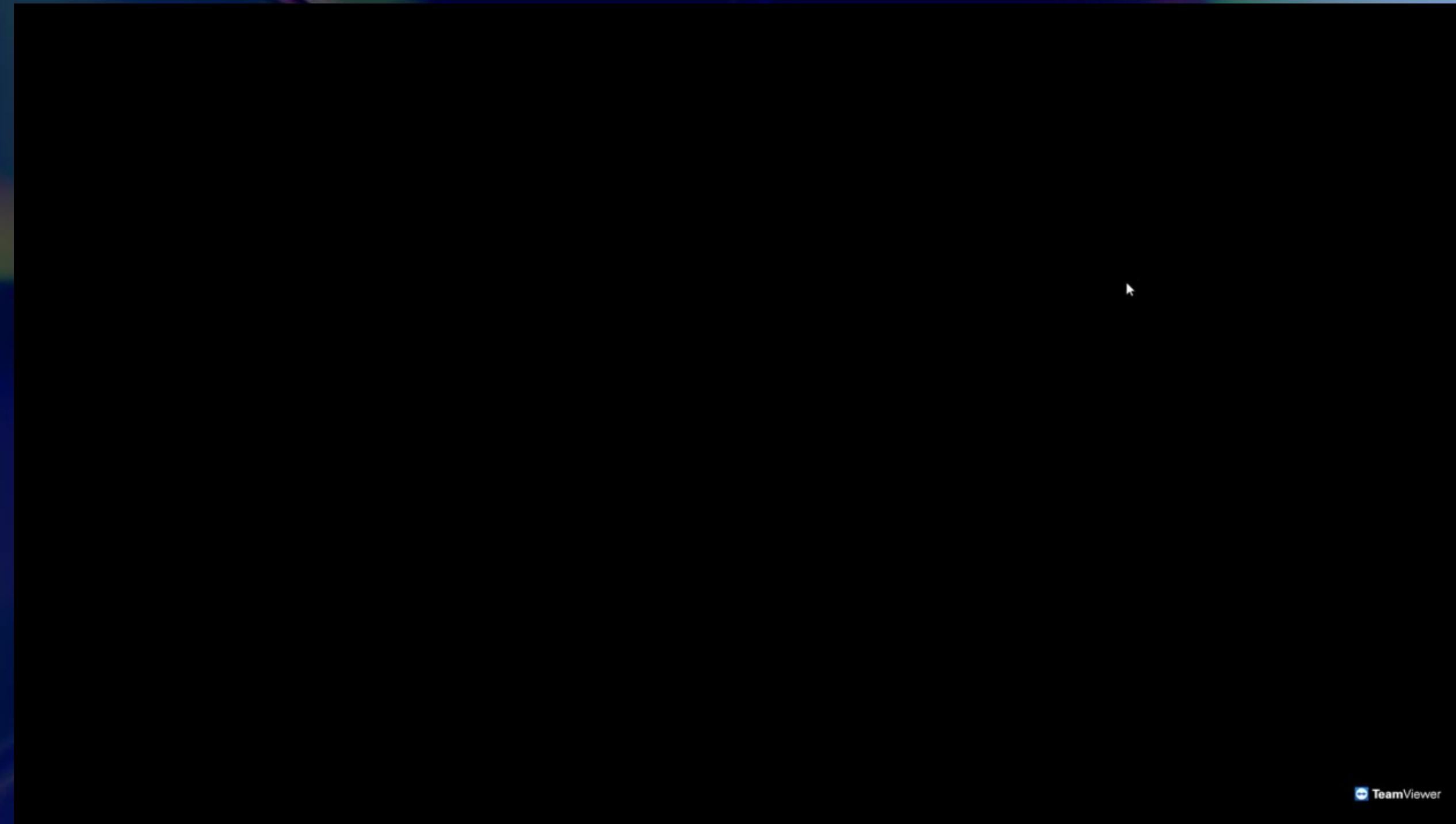
Achieved Result (3DDFA Made Model):





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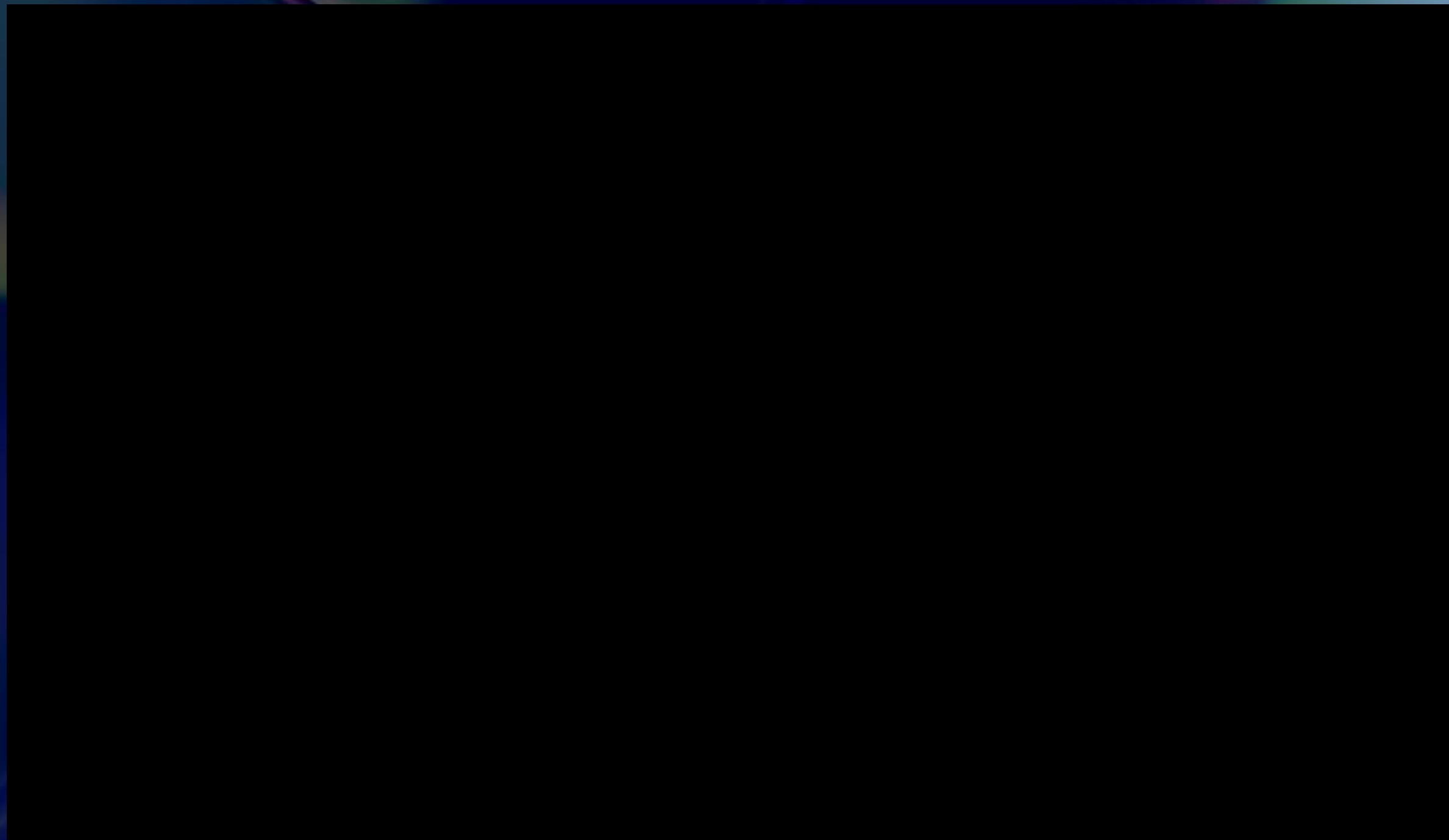
Achieved Result (PIFuHD Made Model):

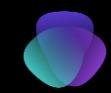




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Achieved Result (3DDFA Made Model):





Challenges Encountered:

Output quality can be affected by input image

Generative Adversarial Networks (GANs) are used to convert low-quality images to high-quality using ML algorithms by training neural networks on a dataset of high-quality images.

Removal of Image background and resolution amplification.

Convolutional neural networks (CNNs) trained on labeled images with foreground and background regions can accurately remove image background

Limited pose estimation accuracy

Blender Mocap will make use of OpenCv and Mediapipe can be used to add motion capture data to the 3D model



Challenges Encountered:

Hardware setup and real-time performance:

Research and carefully select appropriate hardware components based on your requirements and budget. Optimize your code by leveraging parallel processing, multithreading, or GPU acceleration.

Marker tracking alongwith data synchronization:

Implement robust computer vision algorithms for marker detection and tracking. Explore techniques like Kalman filtering or model-based tracking to handle occlusions and marker dropout.

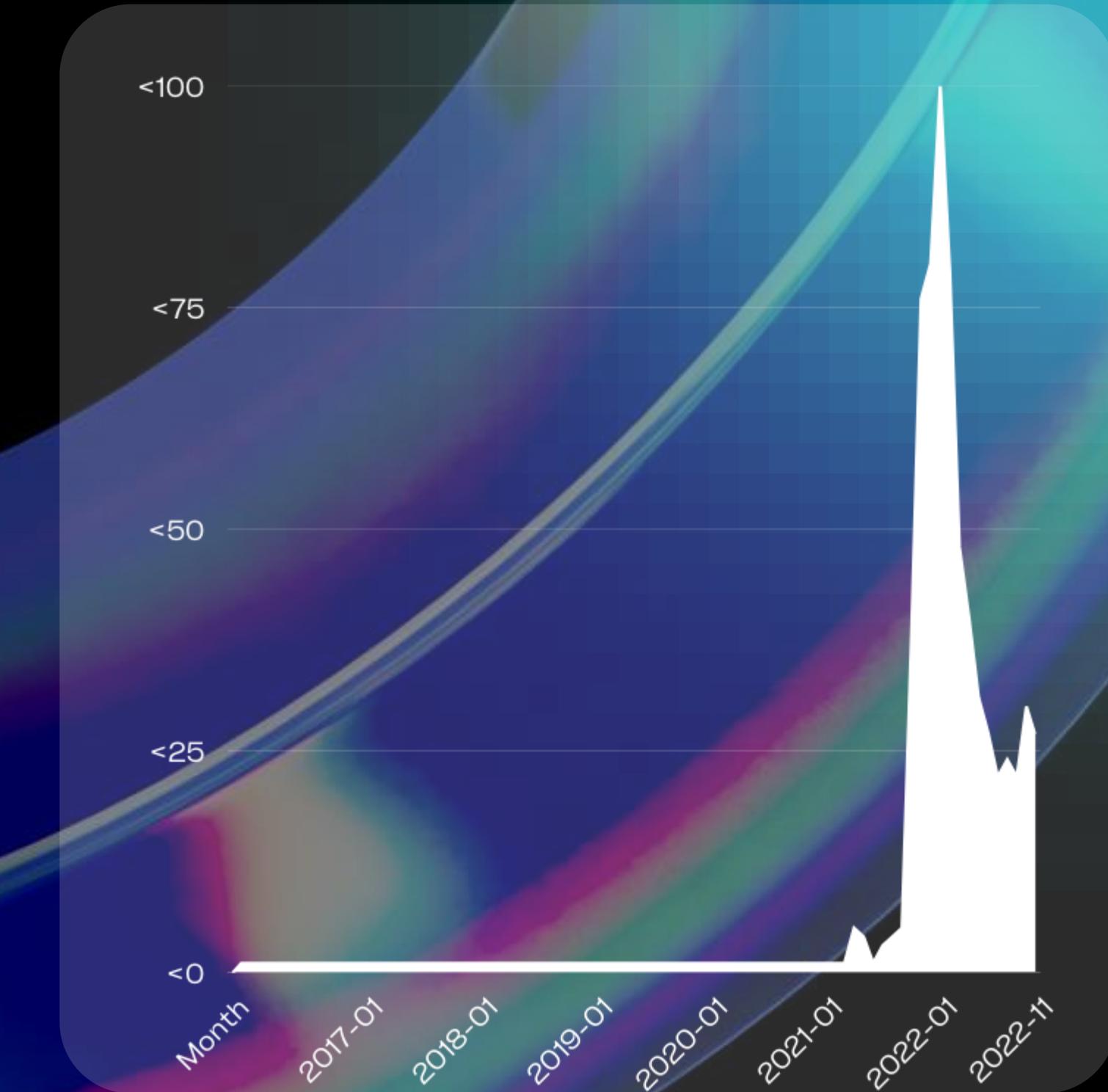
Noise and outliers:

Explore signal processing techniques such as low-pass filters or statistical approaches like median filtering to mitigate noise and outliers.



Revenue Model

To offer our tool as a subscription-based service to companies and individuals who require high-quality 3D models of humans with motion capture data. We plan to offer different pricing tiers based on usage and feature access. We also plan to offer customization services and support to enterprise clients.





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