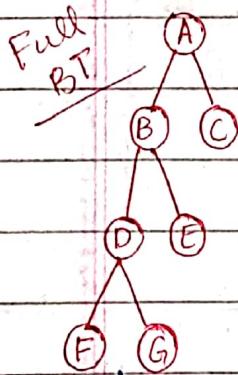


⇒ Array and linked ~~list~~ based implementation of binary tree.

Structurally, binary trees are of three types:-

- Full binary Tree (Each node has either 0 child or 2 children)
- Complete BT
- Perfect BT

~~extremes~~
Full BT: • Each node has either zero ^{no} child or has 2 children.
 • No ~~or~~ node in the tree has 1 ^{child} ~~node~~.



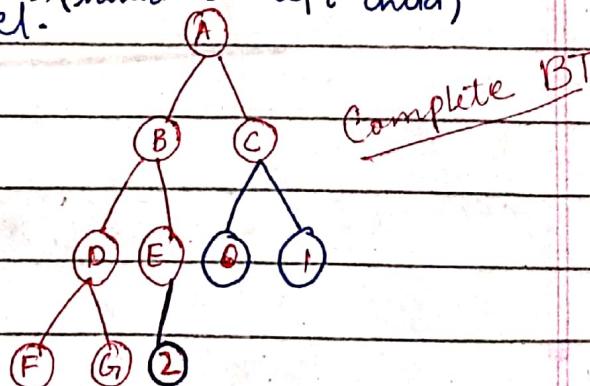
Complete BT:

⇒ Leaf node is allowed only on last and second last level.

⇒ Single child is allowed only on last level. (should be left child)

converting it

to 'complete' BT.

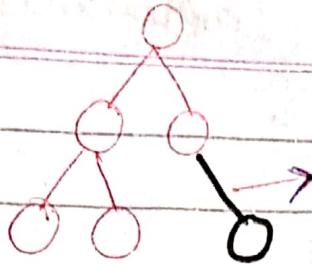


single child is allowed at last level.

Examples :-

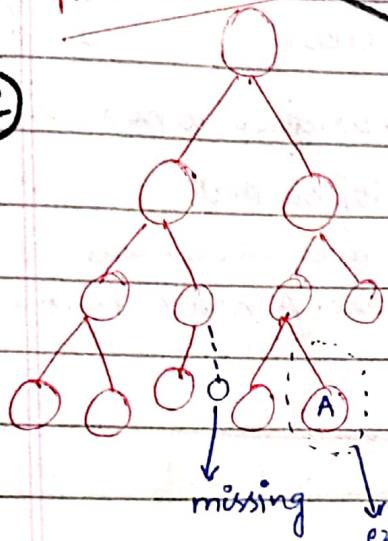
① ~~NOT complete~~

NOT complete



This is not a complete BT.
To make it complete, the single node should be left child and not right.

②



This is not a ~~complete~~ binary tree because

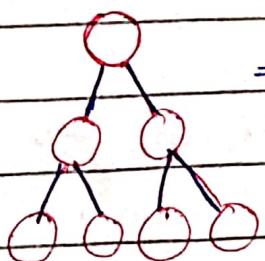
a condition for complete BT is that The nodes at last level should be as left as possible.

In this tree, node A could be missing. But jahan tak nodes hain, wahan tak poori filled hono chahiye.

Perfect BT:

⇒ Each node can have either zero child or 2 children.

⇒ All leaf nodes should only be at last level.



⇒ Internal nodes have 2 children.

⇒ Leaf nodes have 0 child.

⇒ Every perfect binary Tree is also a full binary tree

Implementation of BT

Array-based :-

Class BT

{
 T * arr; → stores tree

 bool * status; → tells whether a node is present
 or not.

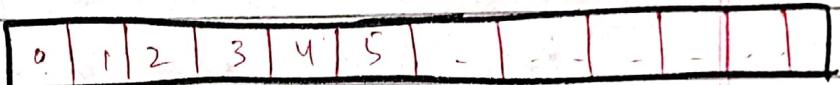
 int height; → keep it, so that

we may calculate

Methods ...

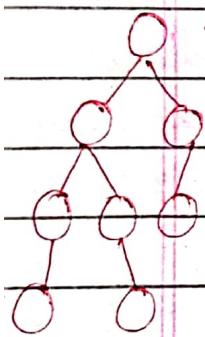
no. of nodes through it.

}



* Height = 4.

* So, max. nodes = $2^h - 1 = 15$ nodes



* So, create an array of 15 size in
the constructor.

constructor();

* setRoot(v);

* Left child of any node = $2i + 1$.

Right child = $2i + 2$

(3) * void setLeftChild (parent index/i, val);

(4) * void setRightChild (//);

*

void setLeftChild (i, val)

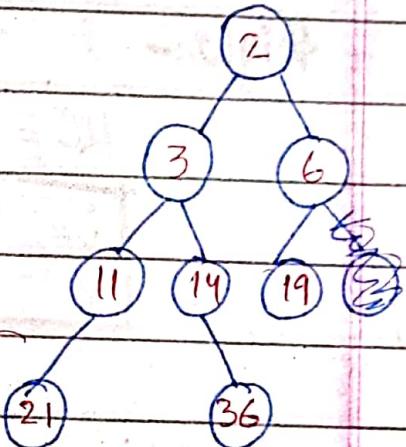
{

 left-index = $2^i + 1$;

 arr [left-index] = val;

 status [left-index] = true;

}



Tree arr:

2	3	6	11	14	19	-	21	-	36	-	-	-	-	-
---	---	---	----	----	----	---	----	---	----	---	---	---	---	---

Status arr:

T	T	T	T	T	T	F	T	F	F	T	F	F	F	F
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

* setRightChild is same except formula $2^i + 2$.

⑤

* getLeftChild (parent index) ;

⑥

* getRightChild (" ") ;

To get parent when child is given:

Left :-

$$LC = 2i + 1$$

$$\boxed{i = \frac{LC - 1}{2}}$$

LC = leftchild

i = parentindex = ?

(7)

* `getParent(LC)`

{ return arr[$\frac{LC-1}{2}$]; }

Right :-

$$RC = 2i + 2$$

$$\boxed{i = \frac{RC - 2}{2}}$$

* `getParent(RC)`

{ return arr[$\frac{RC-2}{2}$]; }

* Demerit of array based implementation:-

* No resize function.

D. \Rightarrow New array of data & status is to be formed everytime which is space & time taking.

\Rightarrow Hence, linked list based implementation is preferred.

-VR

16

linked list based :

Struct TreeNode

```
{ int data;  
    TreeNode* left;  
    TreeNode* right;  
}
```

Class BinaryTree

```
{  
    TreeNode* root;  
public:
```

① *BinaryTree()

```
{ root = NULL; }
```

② *BinaryTree(int v)

```
{ root = new TreeNode(v); }
```

or

root->data = v;

}

③ void setleftChild(TreeNode* parent, int v)

```
{ p->left = new TreeNode(v); }
```

④ void deleterightChild(TreeNode* p)

```
{
```

if (p->right)

delete p->right;

p->right = NULL;

```
}
```

⑤ void deletenode(TreeNode* N)

```
{ if (N->left)
```

STEP 2

if (N->right)

delete N->left;

```
{ delete N->right; }
```

STEP 1

Point to NULL

Delete that pointer of parent of N, which
is pointing to N.

STEP 3

For this purpose, we need to traverse the Tree. * Stack or recursion will be used.

Pre-order Traversal

Recall ... theory

→ implementation :-

~~Through~~ Start

void preOrder()

{

stack<TreeNode> s;

TreeNode *temp = root;

if (temp)

{ s.push (temp);

while (! s.isEmpty())

{

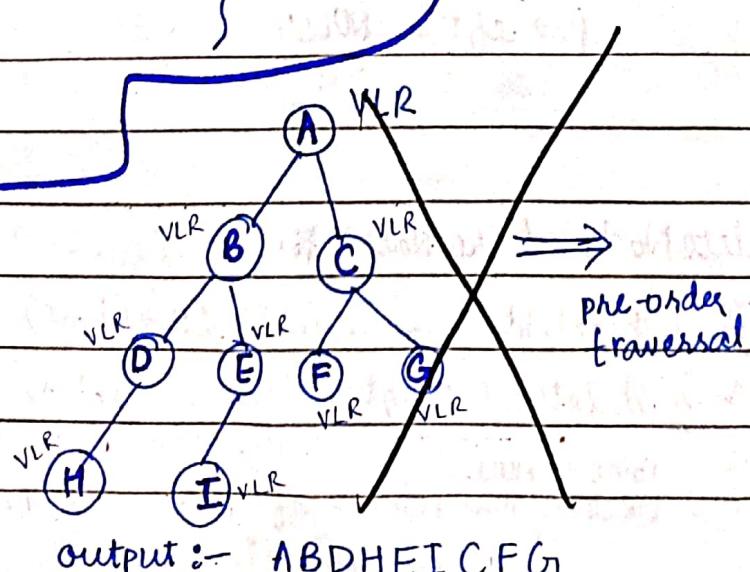
temp = s.pop();

```
cout << temp->data;
```

8.push (temp) right);

so push ($\text{temp} \rightarrow$ ~~left~~ left) ;

~~anode~~
output



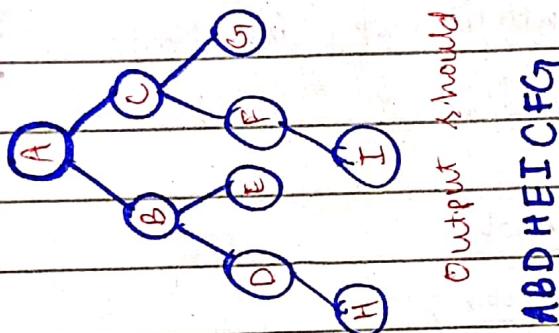
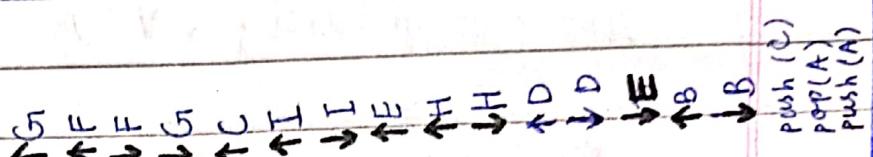
pop (G)	
pop (F)	
push (F)	
push (G)	
pop (C)	
pop (I) β	I
pop (E) push (I)	E
pop (H)	H
8 pop (D) push (H)	D
1 push (D)	
5 pop (B) push (E) δ	B
4 push (B)	
3 push (right) ϵ	
1 push (fp) 2 pop (A)	A

(3) 7

(7)

How preOrder function works with stack:-

↑ = pop
↓ = push



Output should be :-

A B D H E I C F G

* Right child

Ko left se perly
push karna hai

tak pop/print
karte huye sahi
wala order aaye

Through Recursion (Pre order)

void PreOrder (Tree Node * root)

{ if (!root)

return;

cout << root -> data ; $\Rightarrow V$
PreOrder (root -> left) ; $\Rightarrow L$
PreOrder (root -> right) ; $\Rightarrow R$

}

PreOrder (root -> left) ; $\Rightarrow L$
cout << root -> data ; $\Rightarrow V$
PreOrder (root -> right) ; $\Rightarrow R$

\Rightarrow in order

PreOrder (left) ; $\Rightarrow L$ }
 PreOrder (right) ; $\Rightarrow R$ } Post Order
 cout \ll temp \rightarrow data ; $\Rightarrow V$

* iterative = using stack

* recursion = whi chota wala code

* Recursive implementation of in order :-

void InOrder (Tree Node* Root)

{

if (!root)

return;

InOrder (root \rightarrow left); (L)

cout \ll root \rightarrow data; (V)

InOrder (root \rightarrow right); (R)

}

* You're to write iterative implementation
of 'In Order' (Do yourself)

* Iterative implementation of level order

(DO yourself,
using queue.)

Completed

Lecture # 22

Two implementations of tree :-

→ Array-based } → revise
→ Link based }

$$p = 2i + 2$$

* left-child = $2 * \text{parent} + 1$

* right-child = $2 * \text{parent} + 2$

* level order traversal :-

① Enqueue a parent

② Dequeue it.

③ Enqueue left & right children

Code :-

```
Queue <TreeNode*> q;  
q.enqueue(root);  
while (!q.isEmpty())  
{  
    dequeue();  
    cout << ;  
    Enqueue left child;  
    Enqueue right child;  
}
```

* BSTs are optimized for searching

For simple binary tree :- $O(n)$ is complexity

For BST: $O(\log n)$ is time complexity.

* BST :-

- ① They are binary
- ② Parent $>$ left child
- ③ Parent \leq right child
- ④ Properties 2 & 3 apply for sub-Trees too.

* insertion in BST (revise)

* search in BST (revise) (efficient)

* Tail recursive function (internet)

* searching of BST is in $O(h)$ \Rightarrow worst bhi kam hota

* smallest value \rightarrow left most leaf (hai)

* largest value \rightarrow right most leaf

* Degree of smallest and largest children are 1 or 0 and can't be 2.

* n is the max height of BST. (skewed trees)

* $\log(n)$ is min/ideal height

* LVR (inorder traversal) on BST provides us the sorted data.

* implementation of BST (revise)

* If you insert data in a BST in increasing sorted order \Rightarrow right skewed tree.

* insertion in decreasing sorted order \Rightarrow left skewed order

* If $h = n$, complexity of insertion & search is $O(n)$.

* If height is not balanced (skewed trees), then $O(n)$.

* If height is balanced then $O(h)$, $O(\log n)$ between $O(\log n) - O(n)$.

* Dangling pointers (internet)

(Lec # 22)
55 min

* BST mein jab parent's ~~me~~ meela hai, to children ko ancestors adopt kr lety hain

* jisjy delete kringa hai, us k parent ko dangling bony se bchana hai.

* Deletion in BST,

case 1 :- No child (degree 0)

case 2 :- One child (degree 1)

\downarrow
ancestor adopt kr lega

case 3 :- (two children) degree = 2

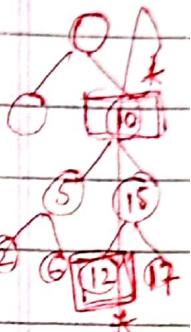
Q:- How to delete such a node? ?

us K right child ki tree me se smallest

number dhaond K us K sath swap kr

dena hai or phir jo needy chali gyi,

smallest wali, usy delete kr dena hai



~~Lecture # 23~~

①
31/5/2021

Monday

Lecture # 23

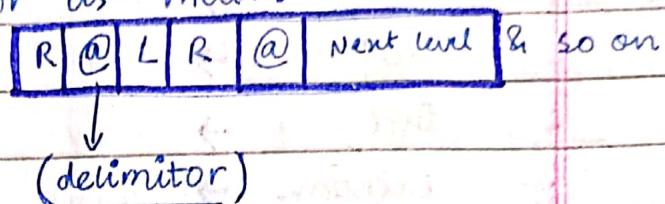
→ height balanced trees AVL
→ concept & terminology of balance
factors: LL, LR, RL, RR.
(rotations)

Print BST Functions

①

Next level kb shuru horaha hai? Is k liye :-

Queue rkha lain or us main :-



After each level, queue me delimiter rkha den.

②

Spaces of keys manage karna hai?

Tab spaces (Use escape sequences)

* Binary Tree → Void remove function → post order

traversal will be used for cascade delete.

(cruel approach) parent meri jaye to sayya bachhi bhi maar do.

'h' can be as good as $\log n$ and as bad as n .

→ Search operation in simple binary tree

costs. $O(n)$ ($n = \text{no. of nodes}$)

→ While in BST, it takes $O(h)$ where ' h ' = height.

worst case: $O(n)$ $\because h = n$

Best case: $O(\log n)$

→ FindSmallestElement() $\Rightarrow O(h)$ (left most child)

→ FindLargestElement() $\Rightarrow O(h)$ (right most child)

→ InOrderTraversal() gives sorted data.

→ insertion() $\Rightarrow O(h)$

→ deletion() $\Rightarrow O(h)$

Time complexity of operations in BST

Searching $\rightarrow O(h)$

FindMin $\rightarrow O(h)$

FindMax $\rightarrow O(h)$

Insertion $\rightarrow O(h)$

Deletion $\rightarrow O(h)$

Best case :-

$$h = \log n$$

Worst case :-

$$h = n \rightarrow \text{Skewed trees}$$

Best case $\Rightarrow h = \log n$

Worst case $\Rightarrow h = n$ (Skewed tree)



\Rightarrow We are to apply some properties on BST to take its complexity to $\log n$ for all cases. (As that of binary search)

\Rightarrow We will use such properties which will ensure that height of BST will always be $\log n$.

To ensure that $h = \log n$.

Demerit of BST:

Time complexity is same as that of simple binary tree. Worst case: $O(n)$.

It should be $O(\log n)$.

AVL Trees

Balanced height
 $n = \log n$

* Those BSTs whose height is balanced. (around $\log n$)

* AVL is BST with some extra properties?

* BST is binary tree with the property

that parent \rightarrow left is less than parent and parent \rightarrow right is greater than parent.

AVL: For n number of nodes, height of tree is around $\log n$.

or deleted

- * Whenever a node will be inserted, it would be ensured that height is not get unbalanced.

AVL

Adelson

Velski

Lendis

→ people

who made

AVL trees

→ Height should always be around $\log n$.

Balance Factor

- * Each node has its own balance factor.

- * $= \text{height of left sub tree} - \text{height of right sub tree}$

- * Bal. Factor is always an integer.

- * If value of balance factor = -1 or 0 or 1, then it means that height of tree is balanced, else unbalanced.

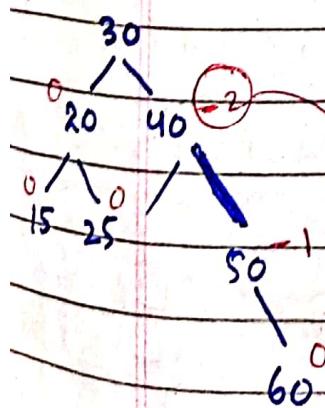
0 = perfectly balanced

- * If unbalanced, we balance tree through some [methods].

On each node, we check balance factor.

1 = when left side ka ek level right subtree se ek ziyada hota hai

⇒ Example: Check whether height of this tree is balanced or not.



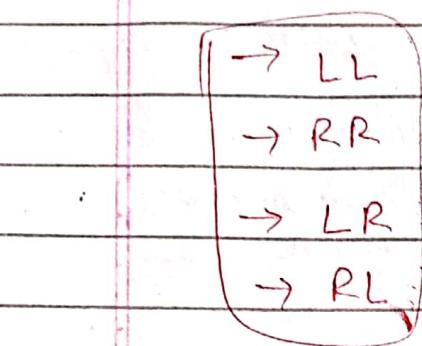
We got that tree is unbalanced, so we will now first balance it.

-1 = when right subtree ka ek level. right left subtree se ek ziyad ho

dy go'

Methods →

Rotations are used to ~~balance~~ thæk balance factor.



① Is node pe balance factor kharab hua, us pe ek pointer point krwa den

B
P1

② Us node ki left or right node ko check krna hai, k

P
P2

kis ki waja se balance kharab hua, jis taraf height ziyada hoga, us ki waja se.

Us child pe bhi ek pointer point krwa den.

A
P3

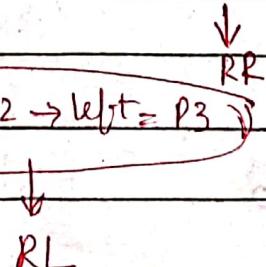
③ Ab jis child pe pointer point kia hai, us ke left subtree ya right subtree mein se jiski height ziyada hai, teesra pointer us child pe point krwa dena hai.

④ Now, we are to figure out, that which rotation to be applied.

If:

$P1 \rightarrow \text{right} = P2 \rightarrow \text{right} = P3$

$P1 \rightarrow \text{right} = P2 \rightarrow \text{left} = P3$



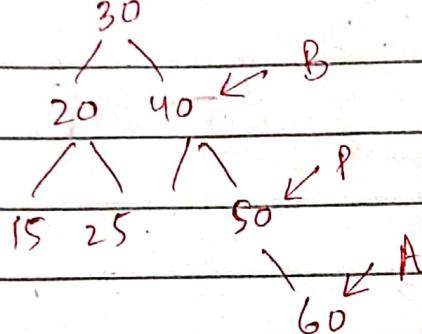
LR
LL

Make P node parent

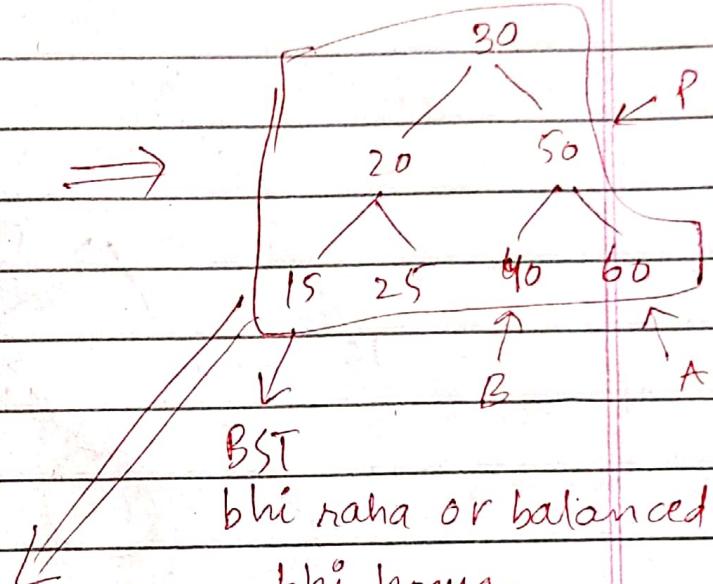
Make B its left child

Make A its right child

lets apply it to
our unbalanced tree.

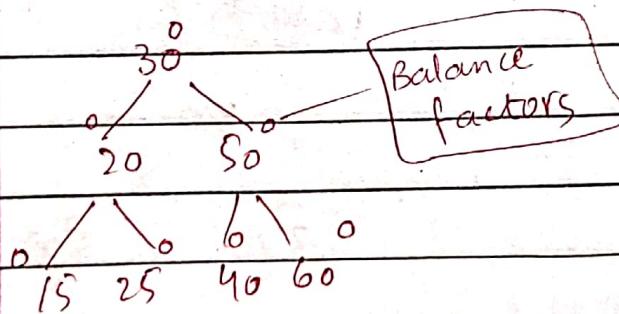


⇒



lets check either

its height is balanced or not.



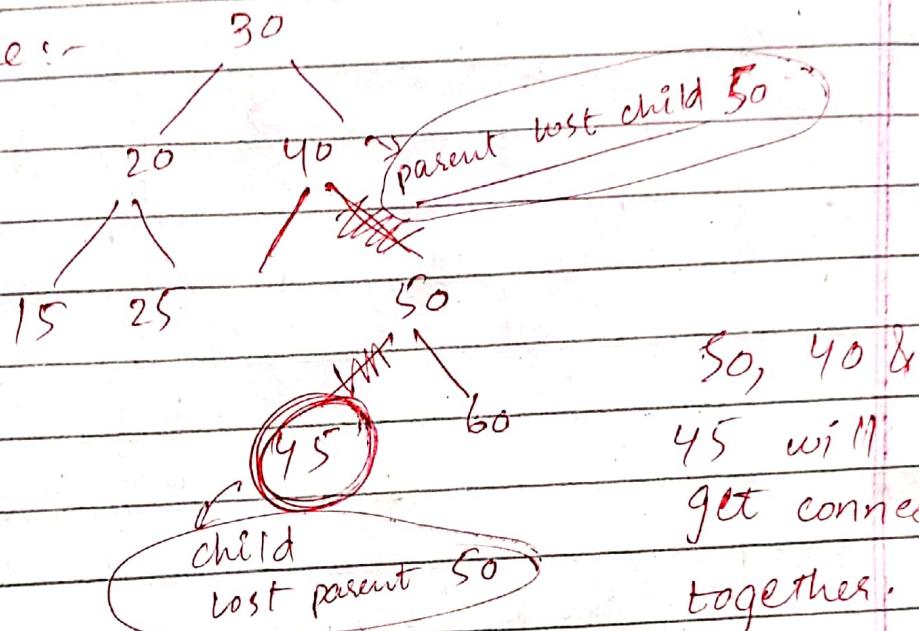
Parent (P)

Add'l Question:- what if (50) already
has a left child. Where will 40 go?

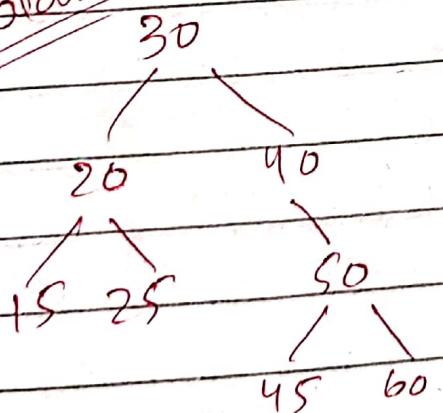
Answer →

⇒ BST wala concept apply hoga. K agr ek node ne apna child lose kia hai or ek ne apna parent lose kia hai, to wo dono parent or child apne me connect hojaty hain. Matlab ancestors adopt kr lety hain grand children ko.

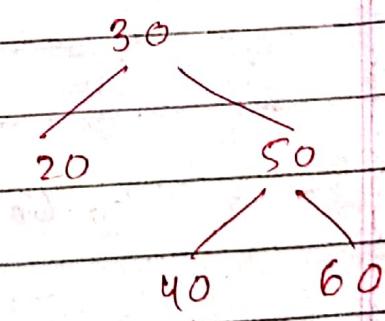
Example:-



Unbalanced



Balanced



Jesa k (40)ne

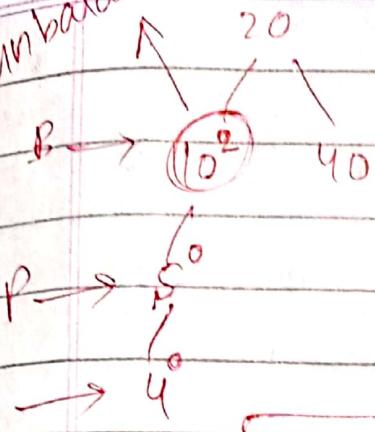
apna right

child loose kia tha

to usy new right child mil gyा.

→ tries to balance height of tree
* Rotations & Insertion

Unbalanced



EL Rotation

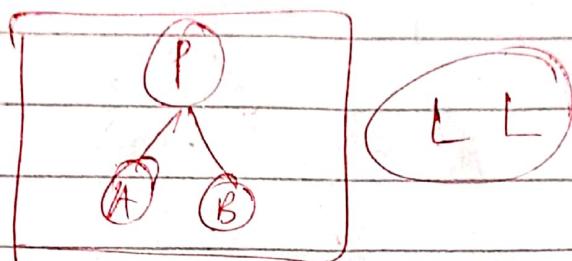
$$B \rightarrow \text{left} = P \rightarrow \text{left} = A$$

||

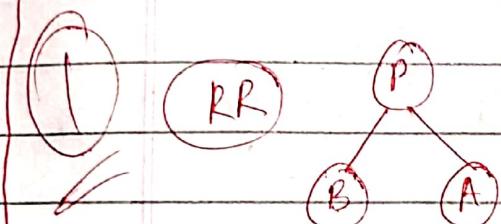
Means

$$A < P < B$$

Property of BST



&

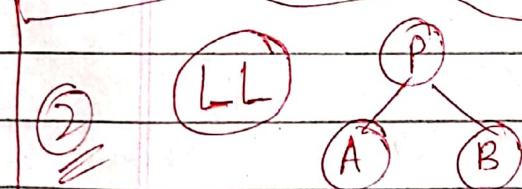


Because it is right side

$$B < P < A$$

Right most wali node yaan k (A)
subse bari hogi

or islie wo right child bn jaye gi.



Because it is right left side

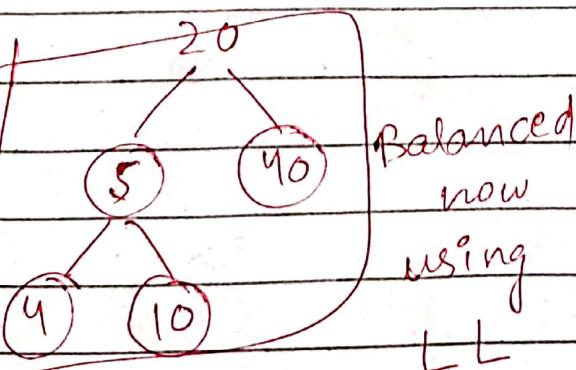
$$A < P < B$$

left most wali node ki

value sub se choti hogi

(A) or islie wo

left child bn jaye gi



Balanced now

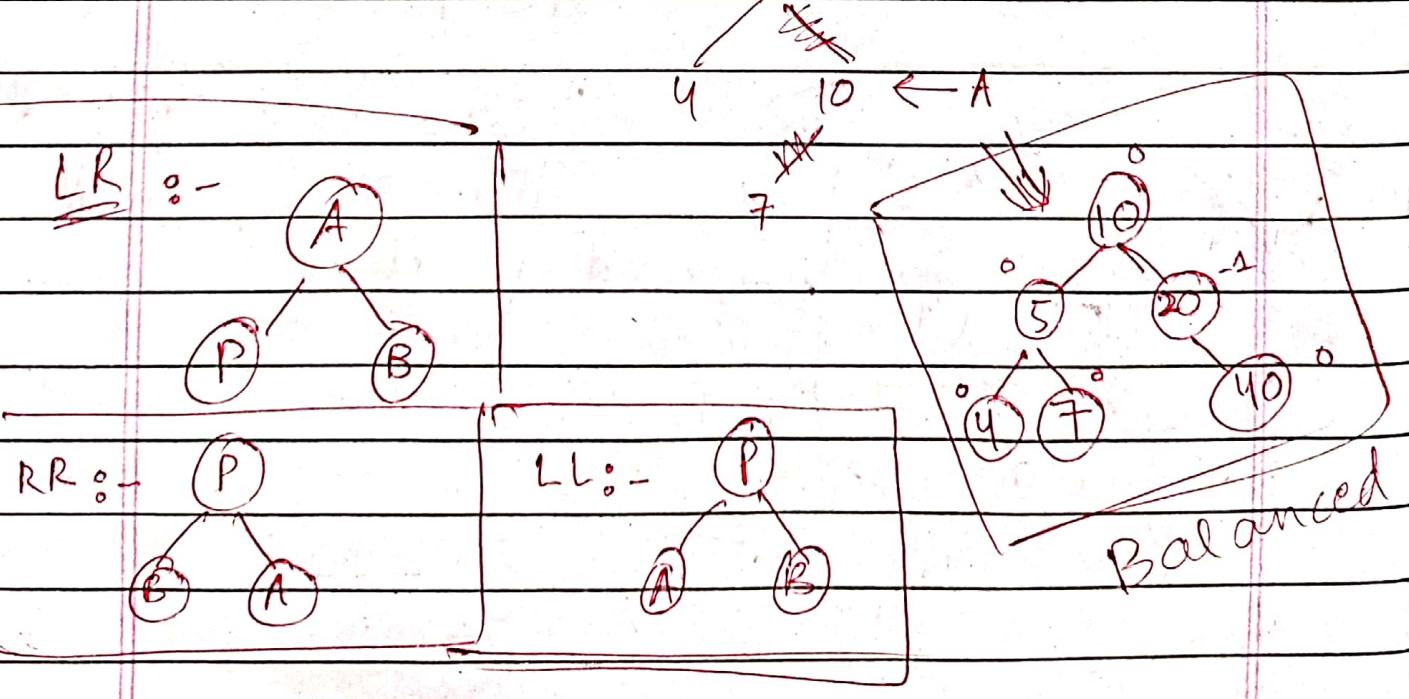
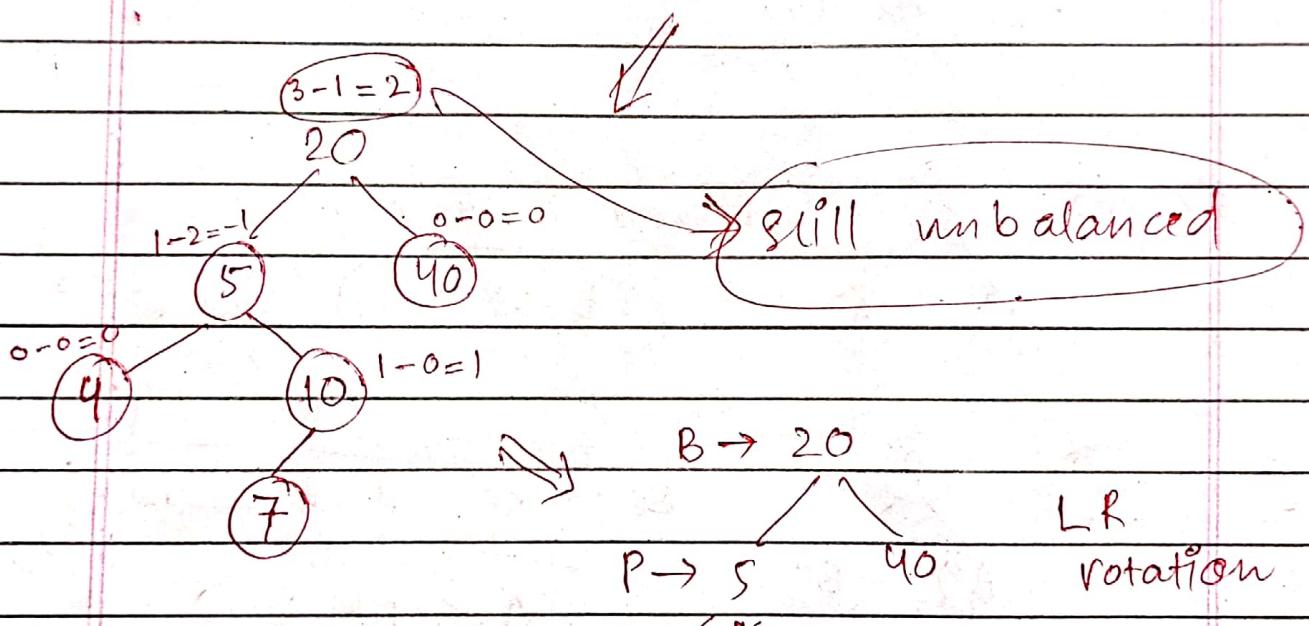
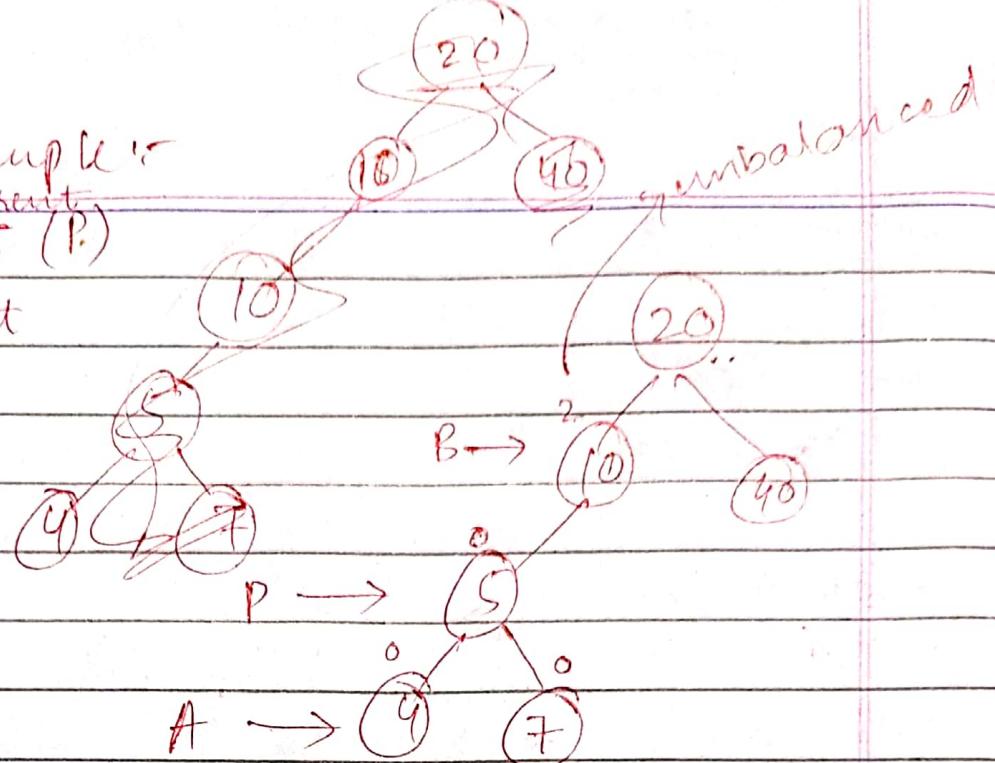
using
LL

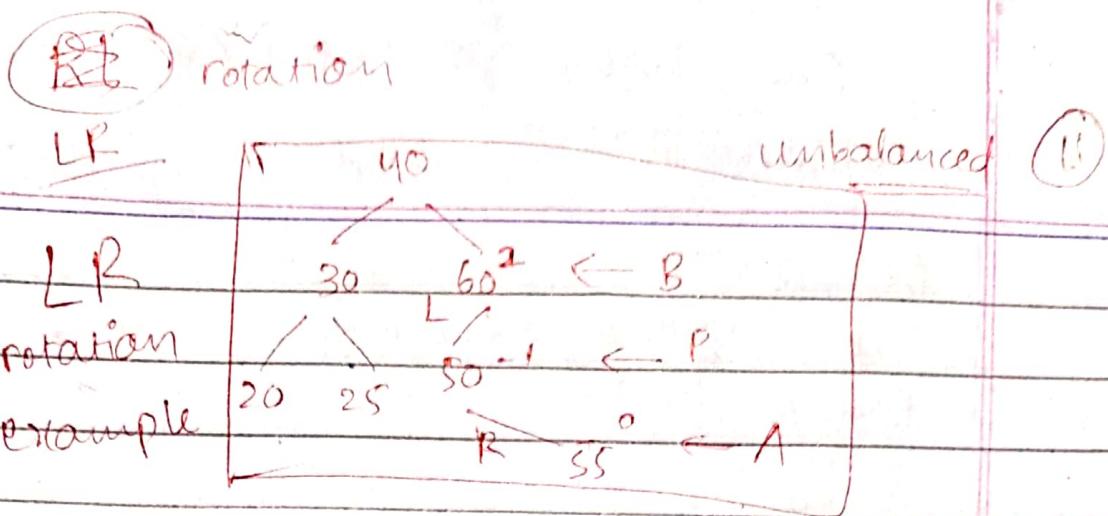
mi
gya.

Example 15

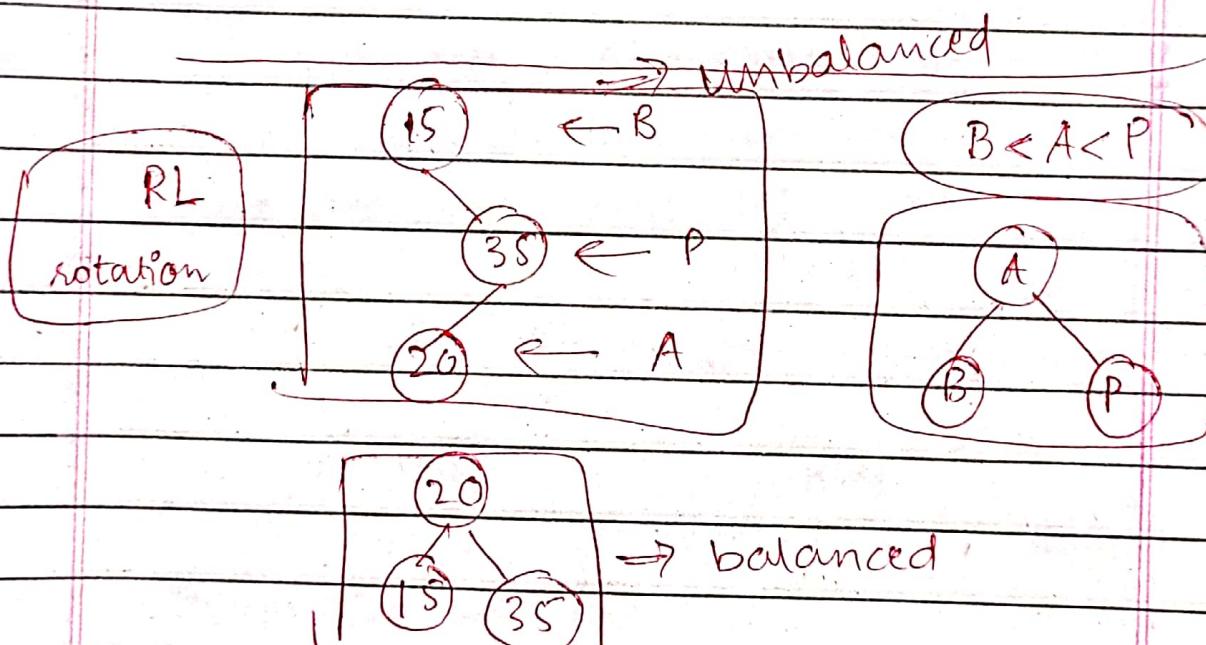
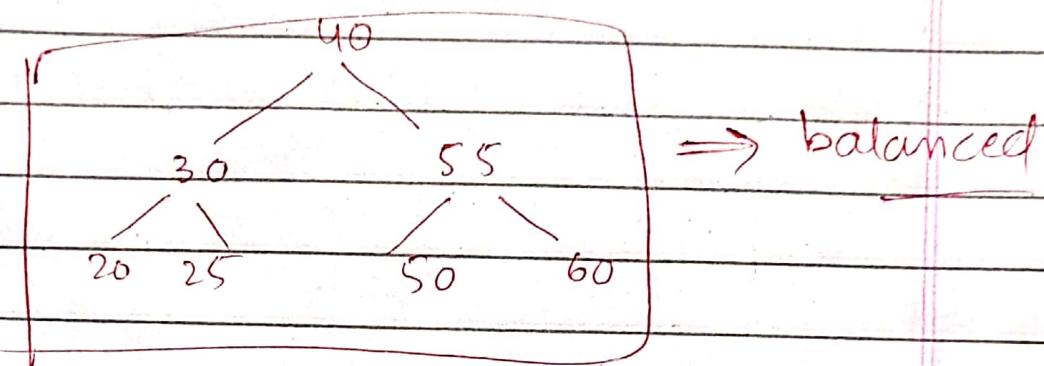
What if 5 (P.) has a right child too?

has a right
child too?





LR
rotation
example



What if ^{parent} (A) already has a child?



Whi process jo preechay
use krti da rhy hain

Ancestor adapt kr

le ga wala process

p