Assignment # 05

Data Structures and Algorithms

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L1F23BSSE0388

Section:

Hssignment #05

Scenerio 1: Student ID Management System:

__(a)>-Insest they given students IDs 9 nTo an initially empty AVL Tree:

40,20,10,25,30,22,50,60

2 (20) 1-0=1 Unbadamed

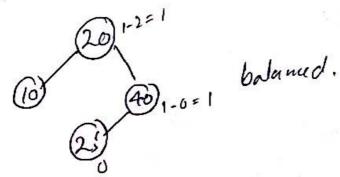
Balance factor height of lept sustree height of right subtree

> Apply Legi legi Rolation To balance this

[-1,0,1]

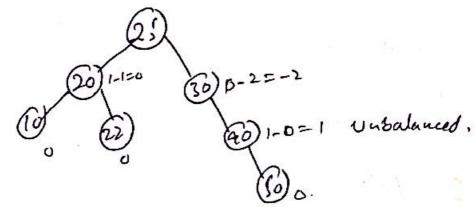
(20)4-1=0 to Lanced.

siep 2: insert 25

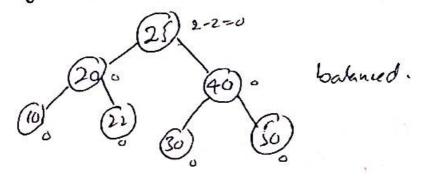


Step 3: insert lest fight rotation to SEP 4: insel = S APPY Right Rest rotation

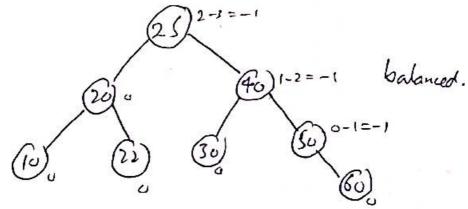
Step So insert So



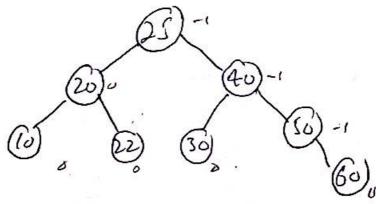
=> Apply Pigut Right rotation



Step 6: insett 60



Final balanced Tree:

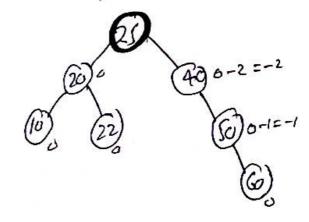


{((b)}≥

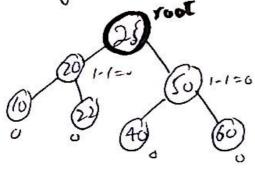
Now delete the Jollowing student IDs from your tree:

step 1: Delete 30,

=> 30 is child node/ leaf node, so it remove diratly:



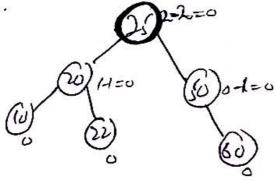
Après delesion Tree & unbalamed, so we balance it by Right Right rotation



Delete 40.

leaf node, so delete

it directly.



So, it is balance apres deletion

perform search operations on the AVL tree you obtained after part B.

.d(C)> =

25, 40,60

Step 1:

Search for ID = 25

=> 25 is a root node, so it bound in Arl Tree

Path:

Start at 25

Step 2:

Search for ID = 40

-> 40725, So go right side

→40250, su go lest 06 50

Not bound

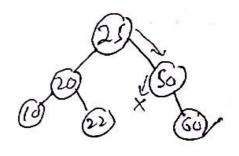
Step 3:

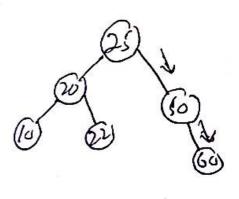
Serach yor ID = 60

>> STart from 25,60725, go right

→ 60750, go right, it matches

Found.





Scenerio 2:

Store unique Book IDs in Library System:

Insert the Jollowing Book IDs Pato an empty
AND Tree:

45,20,60,10,30,25,35,50,70,65,80,55

Step 1:

Pake root node As:

ingert 45,20,00,10,30

(0) (2) (0) balanced.

Step 2:

Puser 25

(a) 2-2=0

(b) (a) 1-2=0

(c) (a) 1-2=0

(d) (a) 1-2=0

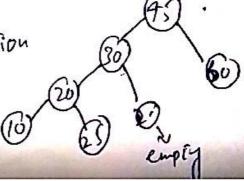
(d) (a) 1-2=0

(e) (a) 1-2=0

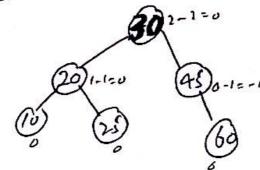
(f) (a) 1-2=0

> Apply Left Pight rotation
To balance this

· First by volate

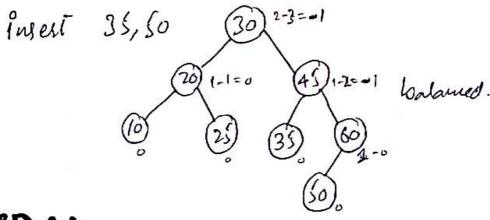


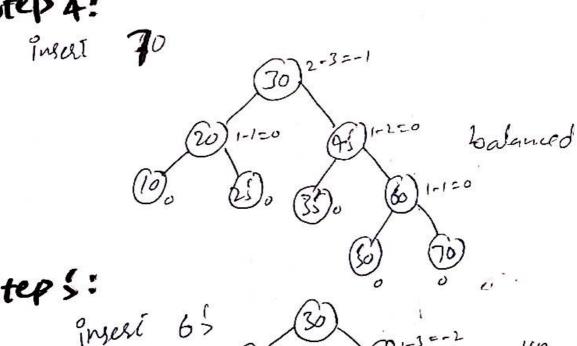
· Pignt rotate



go next insertion. So, it is

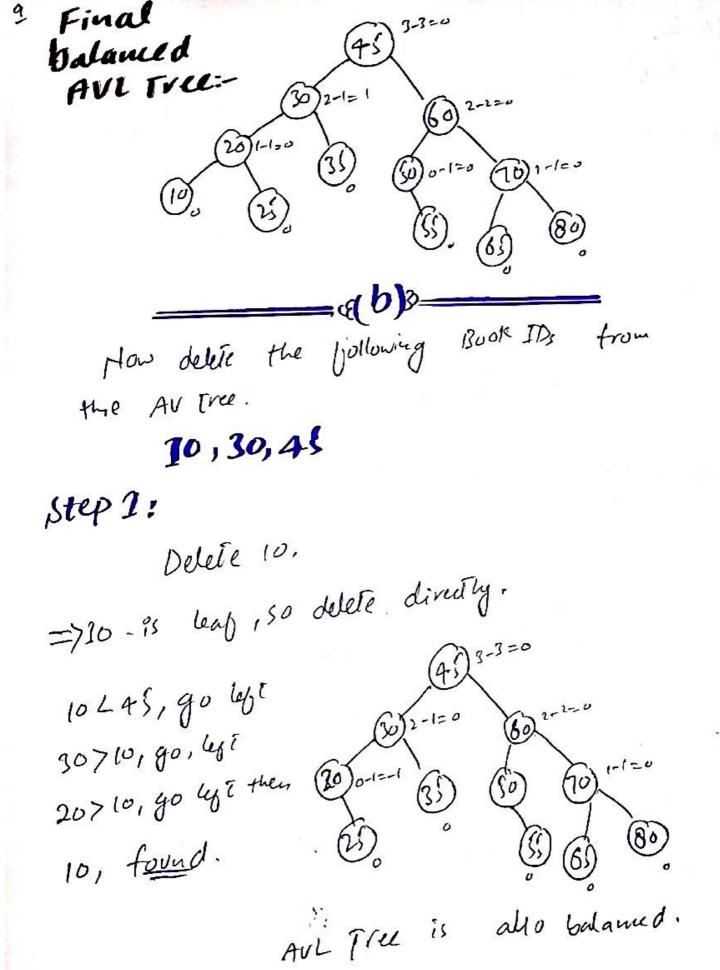
Step 3:





insert 65

=> Apply Right Right rotation .. balanced. step 6: Inselt 80 injert ss Moderned 12 ignt legt volation

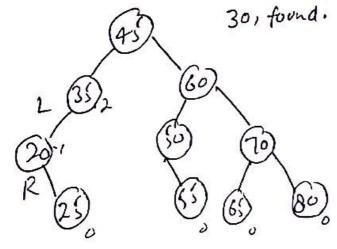


CS CamScanner

Step 2:

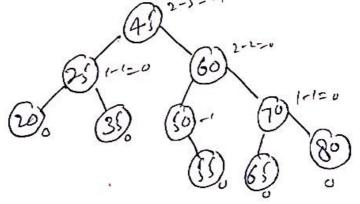
Delete 30,

Peplace 30 with 35 and delete 30 (a leap).



Afrier deletion of 30 AUL Tree become unbabance.

=> Apply left right rotation to make



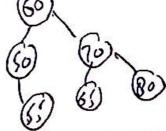
balanced.

Step 3:

Delete 45, .

We in-order produces or = 35 replaced with 45 and delete 45

NOW, We replace.





Final Tree:

45, replaced with 35 2-3=-1

predevisor 35 vignt 35-1

most node:
Tree is bladame.

Now, felled the following Book SD; from AVI tree.

25,45,55,100

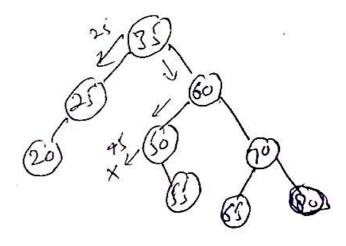
Step 1: Search 25.

State from root 35

\$\frac{1}{2}\lequip 2\lequip 12\lequip 12\lequ

Step 2: Search 45,

45735, go right then
60>45, go lest then
50>45, go lest
we matched, not found.



Step 3:

Search SS

SS > 35,50 go right then 35

SS 260, go left then 25 1/60

SS > 50, go right 20 (5) (0)

it matches found.

Step4:

Search 100,

(2)

(3)

(3)

(4)

(5)

(6)

(8)

(4)

(100 > 33, so go right then hot bond

(100 > 60, go right then

(100 > 70, go right then

(100 > 80, go right

ho matched, Not found.

Building a smart parking System and assign stot of Each (1)

Table size = 10 => means wo slots available

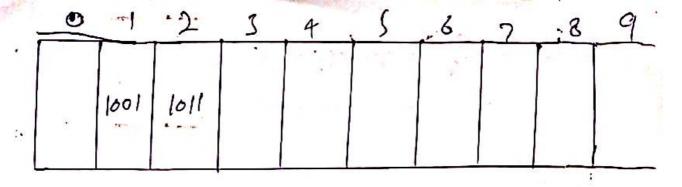
h (license-plate) = license-plate % 10

you decided to first implement linear probing to resolve collisions.

Insertion in hash table using linear probing=1001, 1011, 1021, 1002, 1003

1. Show the hash table after insertion. 1001% 10=1

	O		2	3	4	5.	6.	7	8	9
		1001		,		5.				
L										



1011/10=1

collision occur so we use

linear probing. (1+1)% 10 = 2, no collision put is inthe

0	1	2	1 3	4	. }	6	7	8	9
· · ·	100!	1011	1021						
									i.

1621 % 16=1 , collision at 2

(1+1)%, 10=2, collision at 2

(1+2) /10=3, no collision, pw in lable

ī	0	7	2	3	4	5	6	7	8	9
	*	1001	1011	1021	1002				-	
	_								•	

10027.10 = 2, collision at 2.

(2+1)/10= 3, collisoin at 3

(-2 +2)% 10 = 4, 40 Collision, PW in Gold

(4037, 10 = 3 , collision occur

(3+2)%, 10 = 4., collision at 4. (3+2)%, 10 = 5, no Collision, Put in Cable

0	1	5	1 3	4	1	6	7	8 9
	1001	1011	1021	1002	1003			

2. check collision points:

- · 1011 Collision at Slot 1
- · 1021 collision at sot 1,2
- · 1002 Collision at 2, 3
- . 1003 collision at 3, 4 stols.

3. what does 1003 end up in?

At the Slot Sinden, 1003.

end UD.

4. Search (01 1021

Slot 1, not match,
Slot 2, not match,
Slot 3, not match bound
slot 3, match bound
path: 1 -> 2 -> 3.

Quadratic Probing:

Forunta: (461) + i) % Size of 1966.

1. insertion steb-by-step

@ insut pool

1001%10=1, no collision.

·	ပ	1	2	3	. 4	5	6	. 7.	B	9	
		1001				:					7
_	- 1							l . 1			1

O Evert 1011

1011/10=1 , collision occul.

(1+12)/10=2, no collision.

01	2 3	4	5	6.	7	8	9
1001	1011						T
				1	- 1		ļ.,

Oinsut 1021

-1021 % 10= 1 , collision-occur

(1+1) 1.10=2, collision occur at 1.

(1+(2))/10=5, no collision pulsa Cable

0	<u>'</u>	2	3	4	,	6	7	8	9	
, re-	lwl	1011	à.		1021				٠.	

17 @ Poselt 1002

1002/10=2, (ollision occur at 2.

(2+1)/10=3, no collision. pwin last.

0	ſ	2	· · · · · · · · · · · · · · · · · · ·	. 4	1.	6	7.7	7	, 9
	1001	1011	1002		(021	5 0 0			<u> </u>

@ Porest 1003

1008/10=3 , collision of s

(3+1)/10= 4 ino collision Pulis R64.

G	T^{-1}	-2	3	4	5	. 6 .	7	. 8	9
	1001	1011	1002	(003	1021		40	-	

2. final 560 for 1003

AT the stot 4 index, 1003

end or?

3. probs for 1021

(lineal probing, 3 probs 1->2->3

@ Quadrasic Probing:

1-2-5, 3 Probs as well.

=> Same number of probes, but Quadratic spread data

_{((C))

Separale chainings-1. insurt these license plates:

. 1001; 1011, 1111, 1211, 1311

- . 100 1% 10 = 1
- . 1.011%-10= 1
 - . 11117, 10 =1
 - . 1211/10=7
 - 1311/10=1

All map to stat 1.

O	
. 1	1001
2	
7	
4	
{	
6-	
7	
8	
9	

→ 1011→1111→1211 → 1311·

2.5101 with multiple

Slot I contains all says slots.

3.

Remove 1211

we simply unlink the node with 1211 from the List. New GIF at Slot ! 1001 -> 1011 -> 1111 -> 1371

4. Search 1377

· Hash = 1

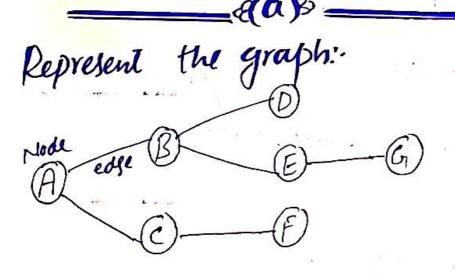
. Travelle list 1001 -> 1011 -> 1111 -> 1311

Path. 1-32-3-34 sieps in the list walking paths using graph:

Building (Node) = A,B,C,O,E,F,G

Paths (edges) = A-B,A-C,B-D,B-E,C-F

E-G



O Adjacency List:Node Adjacent node

$$A: \longrightarrow B, C$$

$$B: \longrightarrow A, D, E$$

$$C: \longrightarrow A, F$$

$$D: \longrightarrow B$$

$$E: \longrightarrow B, C$$

$$F: \longrightarrow C$$

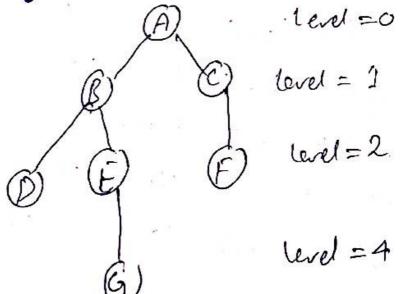
$$G: \longrightarrow C$$

@ Adjacent Matrix

⇒ (A,A) means self loop.

	A	13	<u>_</u>	D	E	F	G
· A	10	1			0		
B	1	O	O	2	1	0	0
C	1	O	O	0	0	1_	0
D	C	1	0	O	O	Ö	1
0.000		1	0	0	O	O	1
F	U	O	1	O	O	O	0
	CO		O .	O	1	O.	Ų

Breadth-first Search (BFS)



=> BFJ uses Queue and visit levely by lend.

A, B, C, D, E, F, G

orderlist = A > 13->c ->D ->E->F ->G

process:

2. Start at A -> enqueue A

2. Visit A -> Enquene B, C

3. Visi B. -> Enqueul D, E

4. VisiT C -> Enquene F

S. visit D -> no child

6. Vist E -> Enquene G

7. Visit F -> Now child

8. VIIT G -> No new child.

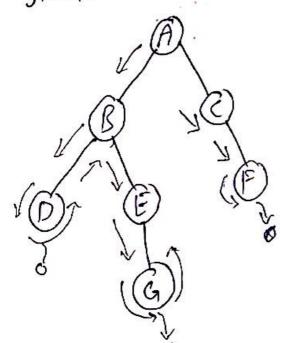
=> SU, BFS wes Quenes as a date straversal level by level:

23/

Depth-First Search (DFS)

DFS Wes Stack and Travelle book (raking.

Stack FILO (First in Lost on)



		sla	
-	0	0	
	-	A A	E
		R	
351		A	

List: D, G, E, B, F, C, A

DFS ordes

= A -> B -> D->E->G->F

Process:

1. start at A,

2. 90 [0 13 .

3. go To 1)

4. D have no leap node, so, back Track

6. GO TO E

6. Go To Go

· 7 · 4 have no leaf node, box truck.

O. B. is done -> Backtrack to A

9. Go TO C

10. GO TO-F

