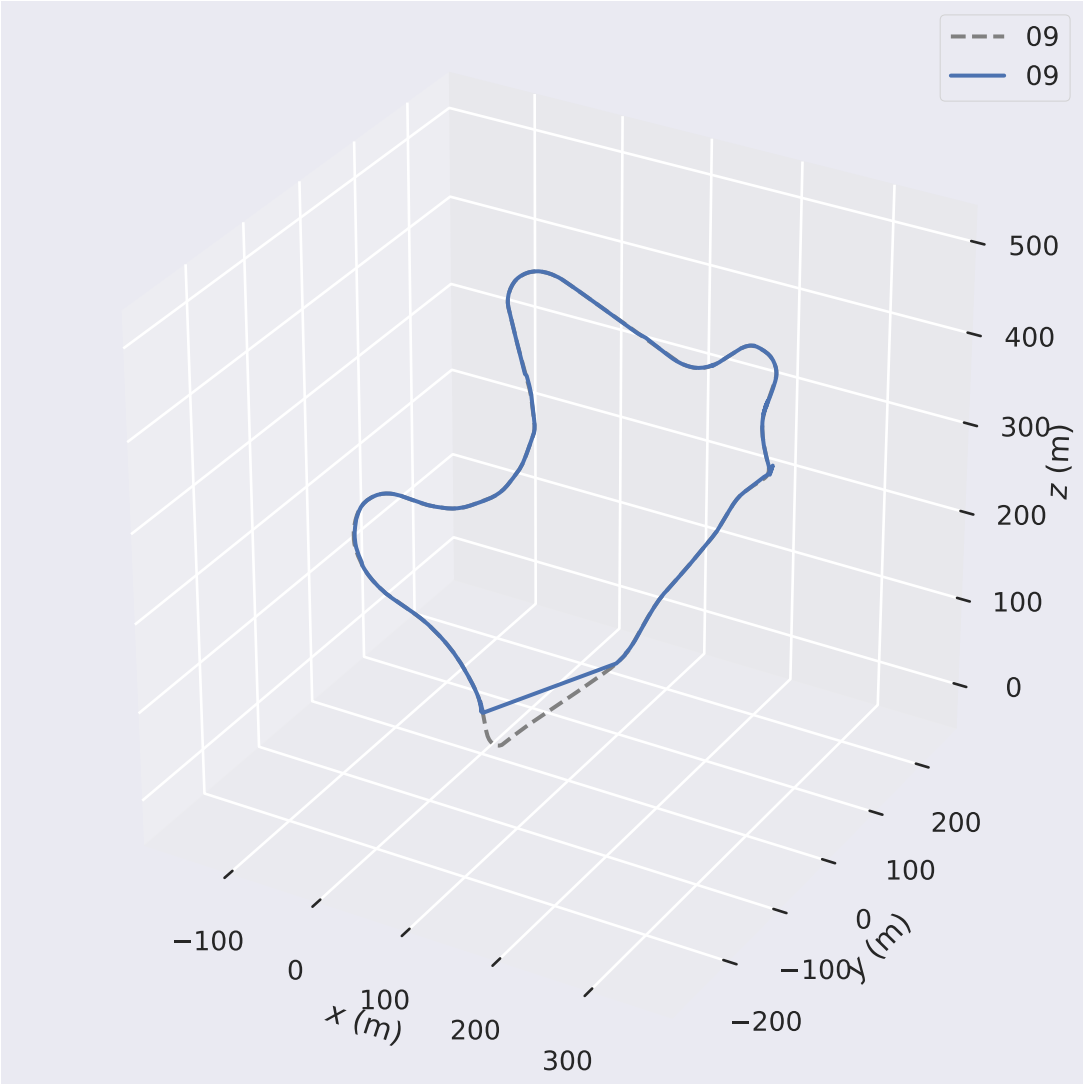
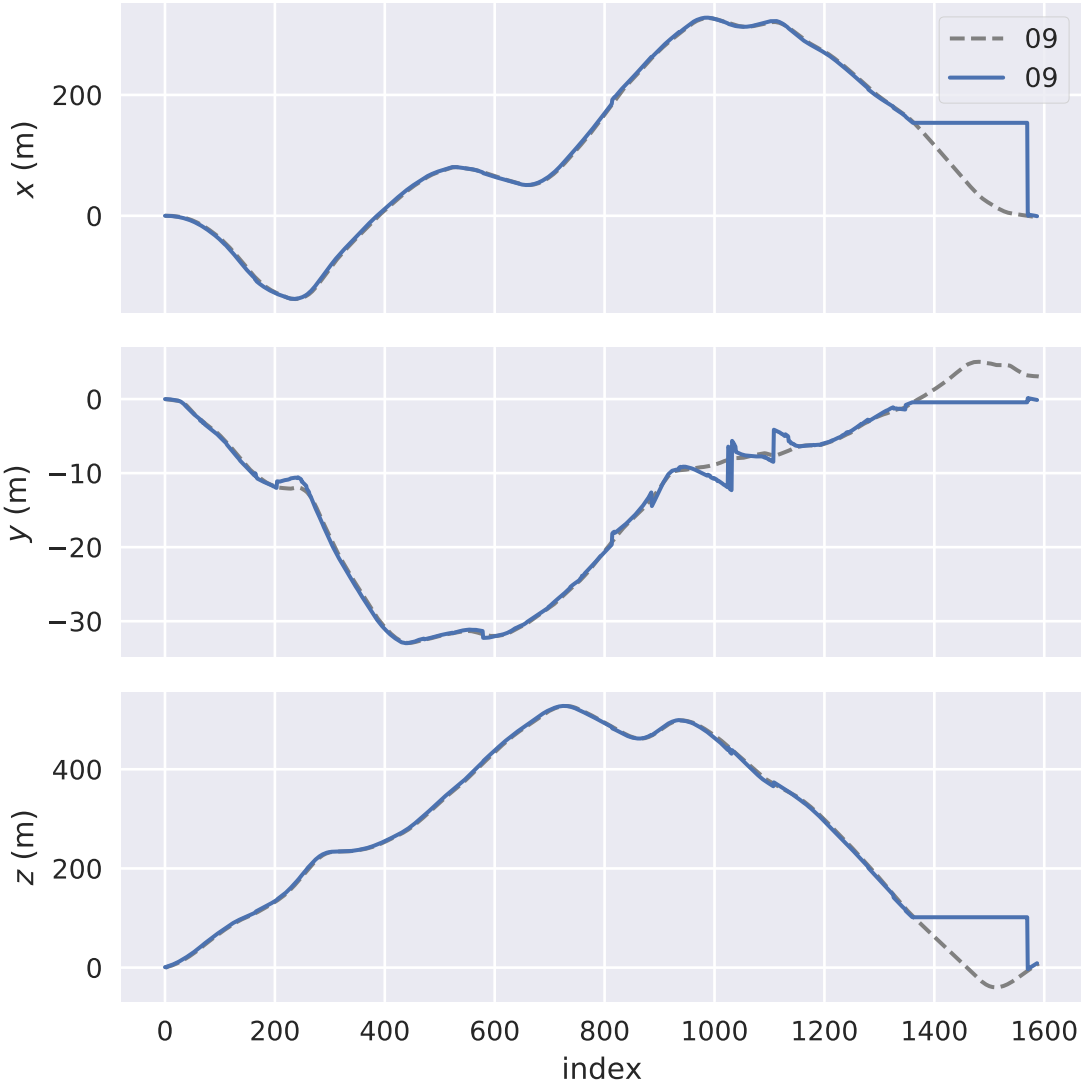
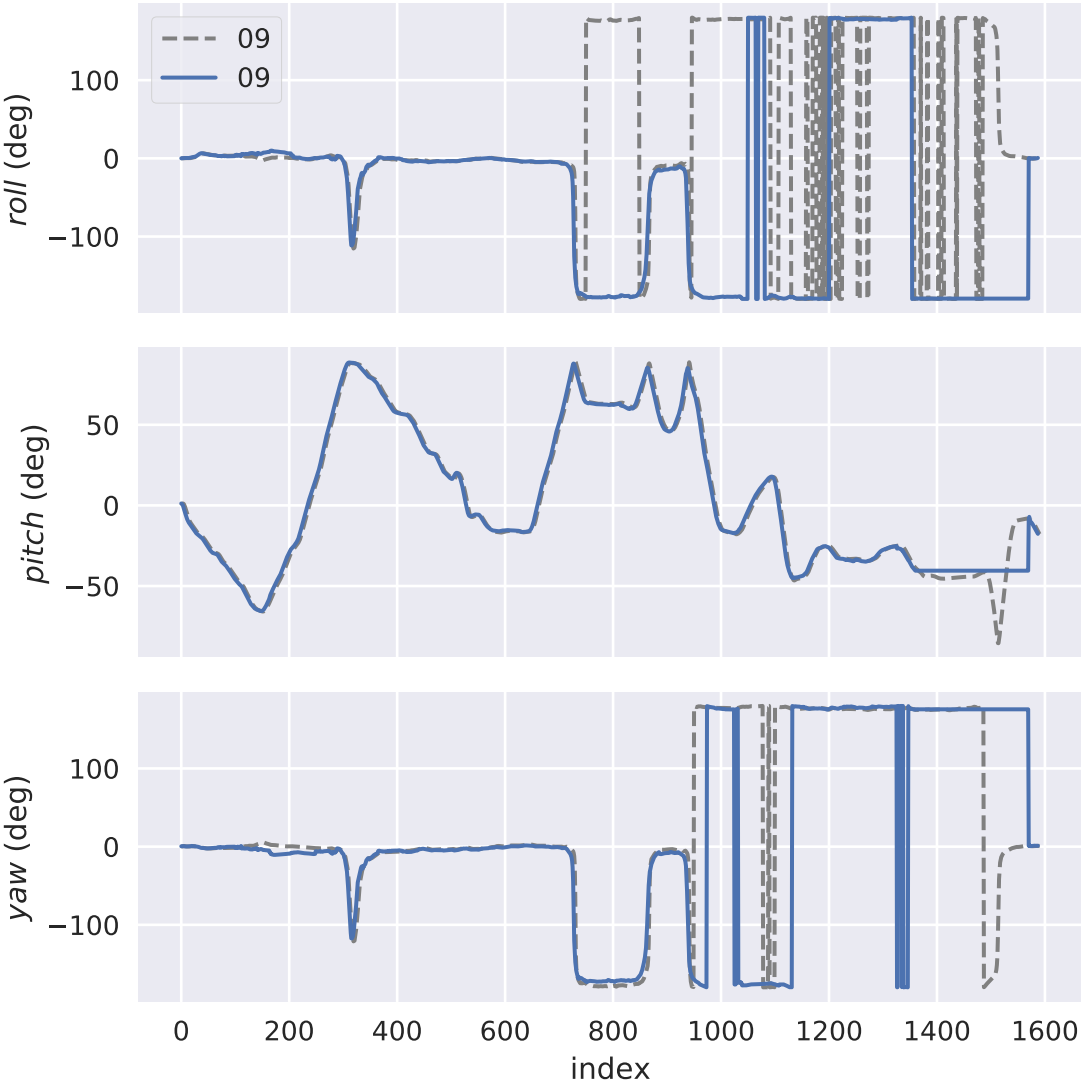

09
09
500
400
300
200
100
0
z (m)
200
100
0
−100
−200
y (m)
−100
0
100
200
300
x (m)


09
09
x (m)
200
0
y (m)
0
−10
−20
−30
z (m)
400
200
0
0
200
400
600
800
1000
1200
1400
1600
index


09
09
roll (deg)
100
0
−100
pitch (deg)
50
0
−50
yaw (deg)
100
0
−100
0
200
400
600
800
1000
1200
1400
1600
index