

## Work Package 3: "Modeling"

# openETCS Architecture and Design Specification

## Software Component Design and Internal Interface Specification

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**Work Package 3: “Modeling”****OETCS/WP3/D3.5.3  
September 2015**

# openETCS Architecture and Design Specification

## Software Component Design and Internal Interface Specification

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Architecture and Design Specification

**Abstract:** This document describes the architecture and design specification of the openETCS onboard unit (OBU) model. The functional scope of the openETCS OBU model is to cover the functionality required for running on the ETCS level 2 Utrecht Amsterdam track. The OBU model is developed iteratively and the system model is documented in D3.5.x and the functional model is documented in D3.5.x, where x denotes the iteration.

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## Modification History

Version	Sections	Modification / Description	Author	Date
0.1	all	Initial document providing structure	Peter Mahlmann	27.05.2015
0.2	2	New template for design descriptions	Peter Mahlmann	10.06.2015
0.3	all	Transferred existing documentation to new template	Peter Mahlmann	22.06.2015
0.4	5	Updated component hierarchy to match current SCADE model	Peter Mahlmann	15.09.2015

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# 1 Introduction

A primary goal of the openETCS ITEA2 project is to provide a formal specification and a non-vital reference implementation of an ETCS onboard unit (OBU) according to the specification described in Subset-026 [1], defined by the European Railway Agency (ERA).

This deliverable, i.e. D3.5.x, describes the architecture and design specification of the openETCS onboard (OBU) model. As the development of the OBU model is done iteratively according to a SCRUM process, the last digit of the deliverable identifier, i.e. x, denotes the current iteration of the model. This document should be considered as a complement to the following project outcomes respectively deliverables:

- the corresponding SysML and SCADE models, available at <https://github.com/openETCS/modeling/tree/master/model/Scade/System>,
- the corresponding functional design description, i.e. D3.6.x, and
- the documentation of the generic openETCS Application Programming Interface (API), available at <https://github.com/openETCS/modeling/blob/master/API/description/api-description.pdf>.

## 1.1 Input Documents

The following documents have been the basis for the analysis, functional decomposition, and design of the openETCS OBU model:

- ERA Subset-026 [1]
- ERA TSI CCS Documents
- openETCS API documentation, available at <https://github.com/openETCS/modeling/blob/master/API/description/api-description.pdf>
- openETCS requirements, i.e. D2.1...9, available at <https://github.com/openETCS/requirements/tree/master/Reference>

list has to be completed

## 1.2 Software and Tools used for Development

The following software and tools have been used in the openETCS development process:

**SCADE System** Version 16.1b of SCADE System has been used for the the generation of SysML models.

**SCADE Suite** Version 16.1b of SCADE Suite has been used for the functional modelling of the openETCS OBU components. Executable models are generated via the SCADE Suite code generator (KCG), which has been certified for CENELEC EN 50128 at SIL 3/4.

list and descriptions have to be checked for completeness

- 32 **SCADE Display** Version 16.1b of SCADE Display has been used for the development of the  
33 Driver Machine Interface (DMI).
- 34 **GitHub** The web based Git repository hosting service GitHub has been used for distributed  
35 revision control and source code respectively model management.

### 1.3 36 General Remarks on the openETCS OBU Model

- 37 The openETCS OBU model has been developed according the specification given in ERA Subset-  
38 026 [1]. The software release of the openETCS OBU documented and described in this document  
39 is publicly available at <https://github.com/openETCS/modeling/tree/master/model>  
40 and refers to the commit corresponding to the following hashtag:

41 1c06cc2d4a0d8f27569e065e2a9edf924b453ff1

- 42 In particular, the root of the SCADE System SysML model is located at [https://github.com/](https://github.com/openETCS/modeling/tree/master/model/system)  
43 [openETCS/modeling/tree/master/model/system](https://github.com/openETCS/modeling/tree/master/model/system) and the root of the functional SCADE  
44 Suite model is located at [https://github.com/openETCS/modeling/tree/master/model/](https://github.com/openETCS/modeling/tree/master/model/Scade)  
45 [Scade](https://github.com/openETCS/modeling/tree/master/model/Scade).

- 46 Note that all components of the openETCS OBU have been developed from scratch, no existing  
47 components have been reused.

Hashtag has to be updated once the model and document are ready for release

48

## **Part I**

49

# **System Architecture and Functional Breakdown**

50



## 2 System Architecture

has to be completed

The system architecture of the openETCS OBU is adopted from the system structure defined in ERA Subset-026, Chapter 2.5 [1]. Figure 1 shows which parts of the reference architecture are in the scope of the openETCS OBU model. Note that also specific parts of the ETCS trackside (e.g. Eurobalise and RBC blocks) have been modeled to have an integrated test environment, cf. dashed blue line in Figure 1.

### 2.1 Top Level Architecture and External Interfaces

Figure 2 shows the top level architecture with external interfaces E1, E2, ..., E9. The external interfaces are used for the communication between the openETCS OBU (dashed red line) and systems out of the scope of the openETCS project and the ETCS Onboard Unit System. In the following we give brief overview of the interfaces:

paragaphoh has to be checked and extended to be more clear

**E1:** In- and out flow between the Interlocking and the Eurobalise. Only relevant for controlled Eurobalises.

**E2:** In- and out flow between the Interlocking and Radio Block Control. This interface ensures the states or logics directly to the Radio Block Control and the other way back from the train to the interlocking.

**E3:** Input flow from the Eurobalise to the Balise Transmission Module or Antenna Unit (BTM) into the ETCS OBU.

**E4:** In- and out flow between the Radio Block Control and the Euroradio modul into the ETCS OBU. This interface is not active in ETCS levels 0 and 1 since there is no ETCS radio interaction between track and train in these levels.

**E5:** This interface is used for the interaction between the driver and the display (Driver Machine Interface, DMI), cf. Figure 3.

**E6:** This interface is a compound structure and combines the interfaces E3 and E4.

**E7:** Input interface to the odometry subsystem of the ETCS OBU. Used for sending information to the train if there is any movement outside the ETCS System, e.g. "cold movement".

**E8:** Input interface to the ETCS OBU to set configuration data such as fixed values, system values, national values and train configuration.

**E9:** In- and Out flow between the ETCS OBU and the train. This interface is used for the interaction between the Train and the ETCS OBU such as brake control, traction control, door control, etc.

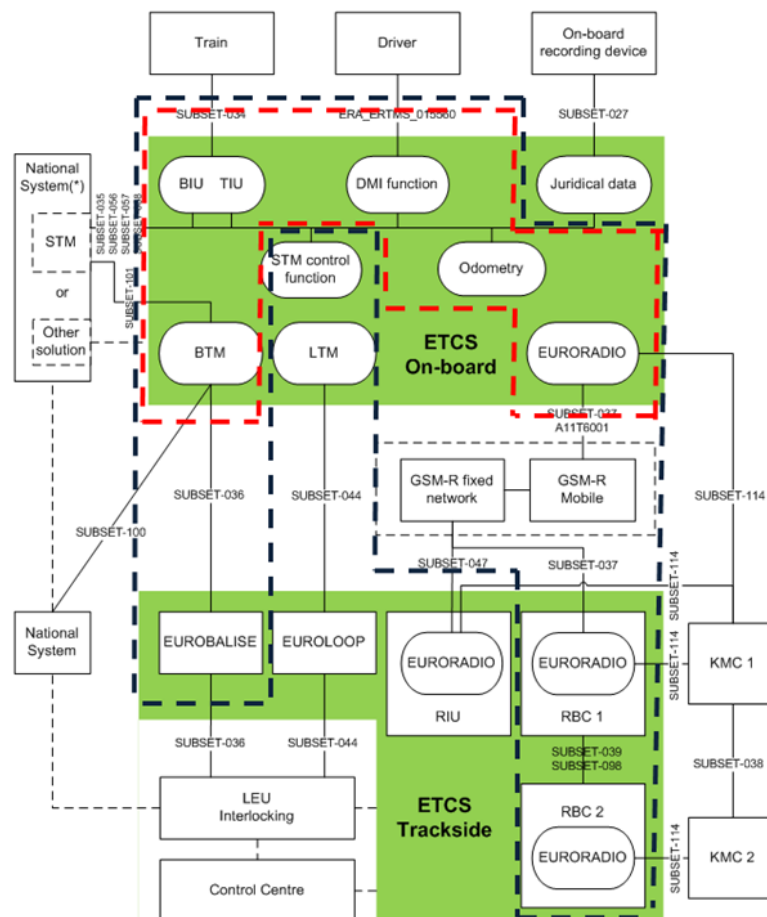
check if figure is correct. Do we need this figure anyway? If so, make it more appealing.

### 2.2 Functional breakdown of the ETCS OBU

Figure 4 depicts the functional breakdown of the ETCS OBU block shown in Figure 2. The internal interfaces

Figure is incomplete and erroneous... F2 is not connected, F2 exists twice

Should this block be described using the new compo-



**Figure 1. Scope of openETCS OBU model system according to ERA TSI Chapter 2.5. Functional blocks in the scope of openETCS have been marked by the dashed blue line. The dashed red line shows the OBU blocks in the scope of openETCS.**

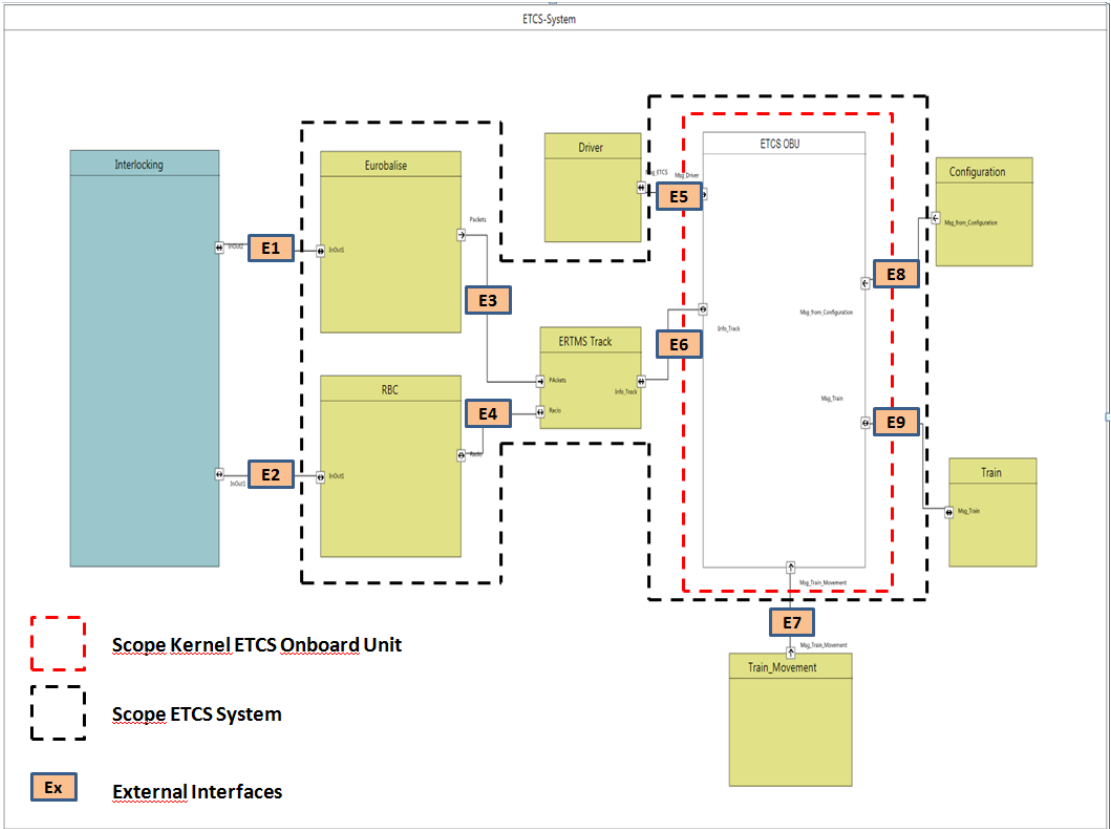


Figure 2. Top level architecture with external interfaces.

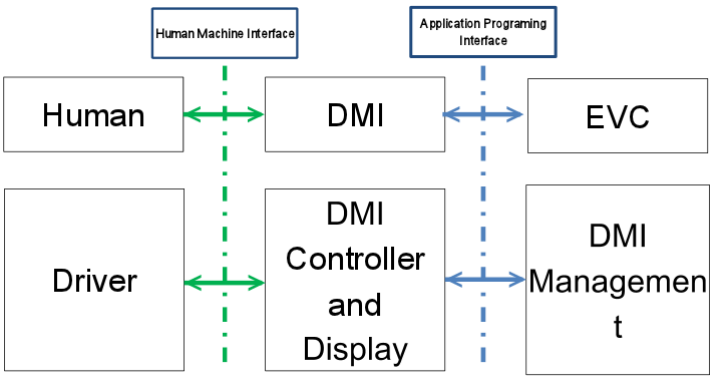


Figure 3. DMI Interfaces.

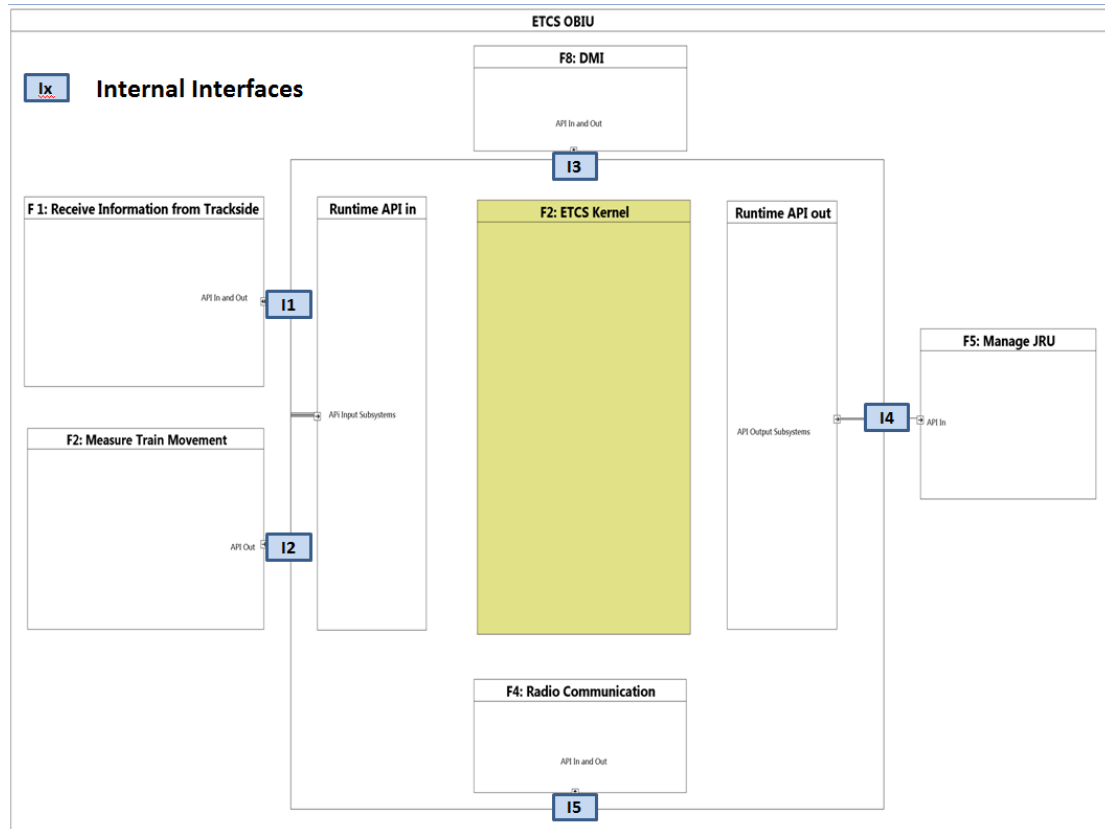


Figure 4. 2nd level system architecture view.

- 86 **I1:** In flow from the Balise Transmission Module (BTM or Antenna) to the "F2 ETCS Kernel"  
 87 through Runtime API in. Transmitted data are information from the Eurobalise.
- 88 **I2:** In flow from the Odometrie (ODO) to the "F2 ETCS Kernel" through Runtime API in.  
 89 Transmitted data are information from the movement of the train.
- 90 **I3:** In- and Out flow between the DMI Controller and the "F2 ETCS Kernel" through Runtime  
 91 API in and out. Transmitted data are information of driver action and display. See description  
 92 in figure of "External Interface E5".
- 93 **I4:** Out flow from "F2 ETCS Kernel" to the JRU manager through Runtime API out. Transmitted  
 94 data are all necessary information for a juridical recorder unit "black box".
- 95 **I5:** In- and Out flow between the Euroradio and "F2 ETCS Kernel" through Runtime API in and  
 96 out. Transmitted data are radio track information (RBC) and information to the track (RBC).

## **Part II**

# **Design Description**

### 3<sup>99</sup> General Design Decisions

100

to be completed

# 4 F1: Receive Information from Trackside

## 4.1 ETCS Messaging: TrackMessages

section needs to be completed

### 4.1.1 Component Requirements

Component name	TrackMessages::Read_P005
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ETCS_Messaging/TrackMessages">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ETCS_Messaging/TrackMessages</a>
SCADE designer	Jakob Gärtner, LEA Railergy Mairamou Haman Adj, LEA Railergy
Description	<p>TrackMessages is a library containing functionality to:</p> <ul style="list-style-type: none"><li>• Transport TrainToTrack and TrackToTrain messages and packets using a compressed format which is conceptually close to the ETCS language as defined in Subset-026</li><li>• Compress trackside information and decompress it in the on-board unit, taking into account different baseline versions and providing transparent translation.</li><li>• Compress trainside information and decompress it in the track-side simulation models, taking into account different baseline versions and providing transparent translation.</li></ul> <p>As TrackMessages is a library with various components supporting all packets and messages defined in Subset-026, we have selected one exemplary function to document the concept. As only the packet/ message- related functionality is specific, this approach will allow a first understanding of the concept and the related interfaces. For a full discussion of the library, refer to the [specific chapter? document?]</p> <p>The function Read_P005 extracts a packet 5 (Gradient Profile) from the compressed packets data flow, if present. It translates the integer-coded compressed data with the help of the metadata in the header section of the CompressedPackets_T formatted data flow. After performing variable-level translation and exception detection, a baseline-3 conformal packet 5 is available for use within the relevant OBU functions.</p>

Input documents	Subset-026, Chapter 6 Subset-026, Chapter 7 Subset-026, Chapter 8  The objective of this component (the full TrackMessages library) is to provide a full formalisation of above chapters in Subset-026
Safety integrity level	4
Time constraints	n/a (for the provided example function)
API requirements	In the demonstrator context, the API is fully defined on SCADE model level. For integration with external systems (BTM, Radio, Subset-076 or Subset-94), additional conversion to/ from bit-level representation will be required

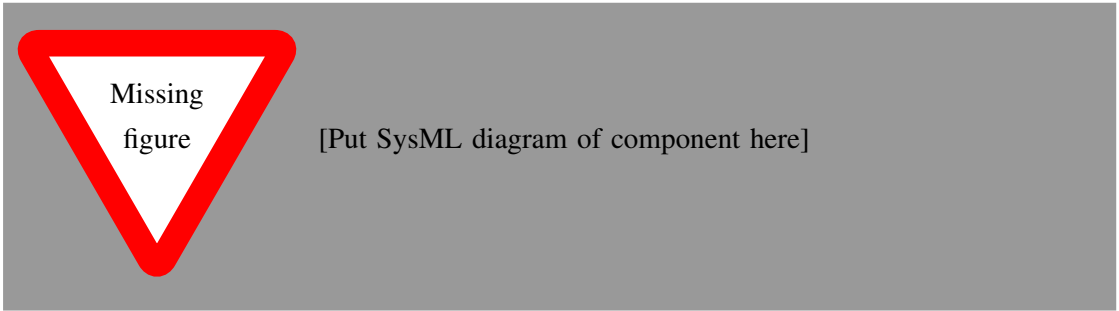
105 **4.1.2 Interface**

106 An overview of the interface of component [component name] is shown in Figure 5. The inputs  
107 and outputs are described in detail in Section 4.1.2.1 respectively 4.1.2.2.

108 **4.1.2.1 Inputs**

109 **4.1.2.1.1 Message\_In**

Input name	Message_In
Description	Message_In takes the compressed track-to-train messages that have either been compressed by the trackside simulation components of the TrackMessages library, or have been filled by the API. All packets that are part of the same message are transmitted within one cycle of the model's execution. Message_IN is taking the compressed packet information from the track to train dataflow.
Source	Manage_TrackSideInformation_Integration
Type	Common_Types_Pkg::CompressedPackets_T



**Figure 5. TrackMessages SysML diagram**



Valid range of values	The consistency of the metadata is checked at the input side. The ranges of the transported variables are checked at the conversion step (from integer format to SRS-conform format)
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	The content of this input is not checked, as any issues will be found at conversion level. If the metadata are not matching the search criteria the packet will be considered as non existent and will therefore be ignored.

#### 110 4.1.2.2 Outputs

##### 111 4.1.2.2.1 received

Output name	received
Description	Flag to indicate reception of a packet 5 from trackside in the current cycle.
Destination	Any calling component. components should be listed here
Type	bool
Valid range of values	to be checked  <b>true</b> Packet 5 has been received in the current cycle. <b>false</b> Packet 5 has not been received in the current cycle.
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	n/a

##### 112 4.1.2.2.2 P005\_OBU\_out

Output name	P005_OBU_out
Description	Gradient Profile (Packet 5) according to 7.4.2.2
Destination	Any calling operator

Type	TM::P005_OBU_T
Valid range of values	<p>TM::P005_OBU_T is a complex data type. Values are given for each element. Format is: Type Name: range/list of values</p> <ul style="list-style-type: none"> <li>• bool valid: [true   false]</li> <li>• q_dir Q_DIR: [Q_DIR_Both_directions   Q_DIR_Nominal   Q_DIR_Reverse]</li> <li>• l_packet L_PACKET: (0-8191)</li> <li>• q_scale Q_SCALE: [ENUM_Q_SCALE_10cm   ENUM_Q_SCALE_1m   ENUM_Q_SCALE_10m]</li> <li>• n_iter N_ITER: (0-33) (<i>Remark: start section from the original packet is integrated into the list of sections</i>)</li> </ul> <p>The structured element sections is an array of type P005_section_enum_T. For each element, the valid range of values is as follows:</p> <ul style="list-style-type: none"> <li>• bool valid: [true   false] (<i>Remark: Check for consistency with the value of n_iter</i>)</li> <li>• d_link D_LINK: (0-32767)</li> <li>• q_newcountry Q_NEWCOUNTRY: [TM_conversions::ENUM_Q_NEWCOUNTRY_same   TM_conversions::ENUM_Q_NEWCOUNTRY_not_same]</li> <li>• nid_c NID_C: (0-1023)</li> <li>• nid_bg NID_BG: (0-16383)</li> <li>• q_linkorientation Q_LINKORIENTATION: [TM_conversions::ENUM_Q_LINKORIENTATION_reverse   TM_conversions::ENUM_Q_LINKORIENTATION_nominal]</li> <li>• q_linkreaction Q_LINKREACTION: [TM_conversions::ENUM_Q_LINKREACTION_Train_trip   TM_conversions::ENUM_Q_LINKREACTION_Apply_service_brake TM_conversions::ENUM_Q_LINKREACTION_No_Reaction]</li> <li>• q_locacc Q_LOCACC: (0-63)</li> </ul> <p><i>Only an output structure with the structured element "valid" set to "true" is to be considered as received. If this field is set to true, the Output 1 (received) must equally be set to "true".</i></p>

Behaviour when value is at boundary n/a

Behaviour for values out of valid range

The component is prepared for the upcoming error/exception handling concept. An error flag is, at the moment, raised internally if any of the compressed input values is out of range. A hierarchical error processing is foreseen.

The types that have been defined in the package S026\_7 do not provide any default/ invalid value. The following fields are therefore set to an arbitrary value upon reception of an out-of-range value from track side, and the internal error flag is raised:

- q\_dir Q\_DIR:  
set to: Q\_DIR\_Both\_directions
- q\_scale Q\_SCALE:  
set to: ENUM\_Q\_SCALE\_10cm
- q\_newcountry Q\_NEWCOUNTRY:  
set to:[TM\_conversions::ENUM\_Q\_NEWCOUNTRY\_same | TM\_conversions::ENUM\_Q\_NEWCOUNTRY\_not\_same]
- q\_newcountry Q\_NEWCOUNTRY:  
set to: TM\_conversions::ENUM\_Q\_NEWCOUNTRY\_not\_same
- q\_linkorientation Q\_LINKORIENTATION:  
set to: TM\_conversions::ENUM\_Q\_LINKORIENTATION\_reverse
- q\_linkreaction Q\_LINKREACTION:  
set to: TM\_conversions::ENUM\_Q\_LINKREACTION\_Train\_trip

Behaviour when value is erroneous, absent or unwanted (i.e. spurious) n/a

### 113 4.1.3 Subcomponents

#### 114 4.1.3.1 Read\_Packets

##### 115 4.1.3.1.1 Component Requirements

Component name	TM_lib_internal::RECV_ReadPackets
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ETCS_Messaging/TrackMessages">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ETCS_Messaging/TrackMessages</a>
SCADE designer	Jakob Gärtner, LEA Railergy

Description	<p>RECV_ReadPackets extracts packet data information and raw compressed packet data from the compressed packets data flow, using filter criteria provided through parameter inputs:</p> <ul style="list-style-type: none"> <li>• NID_PACKET: search for a specific packet.</li> <li>• Version Number: search for a specific version number.</li> <li>• Q_DIR: search for packets that are only valid for a specific direction.</li> <li>• Serial number: search for a specific packet instance, if several instances of a given packet type exist.</li> <li>• F_Version: Flag to decide whether to evaluate or ignore packet version information.</li> <li>• F_id: Flag whether to evaluate or ignore packet serial number information.</li> </ul> <p>The operator TM_lib_internal::RECV_ReadPackets takes a set of parameter data to:</p> <ol style="list-style-type: none"> <li>1. Search the metadata of the compressed packets data flow using the provided parameters to determine if a matching packet is contained in any given cycle.</li> <li>2. Output the flag "received" exactly in any cycle a matching packet is found</li> <li>3. Output an array of compressed packet data that is filled with the data from the identified packet.</li> </ol>
-------------	--

Input documents	Subset-026, Chapter 7 This function is not directly traceable to Subset-026, but is built from derived requirements.
Safety integrity level	4
Time constraints	n/a
API requirements	In the demonstrator context, the API is fully defined on SCADE model level. For integration with external systems (BTM, Radio, Subset-076 or Subset-94), additional conversion to/ from bit-level representation will be required.

#### 116 4.1.3.1.2 Interface

117 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
118 above) respectively the SCADE generated documentation.

#### 119 4.1.3.2 Extract Packet 5

#### 120 4.1.3.2.1 Component Requirements

Component name	TM_conversions::trackside.C_P005_compr_onboard
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ETCS_Messaging/TrackMessages">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ETCS_Messaging/TrackMessages</a>
SCADE designer	Jakob Gärtner, LEA Railergy
Description	If a matching packet 5 has been received, TM_conversions::trackside.C_P005_compr_onboard: takes the compressed packet data and converts them to an SRS conformal onboard packet format. Trailing 0 beyond the valid length of the packet are ignored.
Input documents	Subset-026, Chapter 7
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 121 4.1.3.2.2 Interface

122 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
 123 above) respectively the SCADE generated documentation.

# 5 F2: ETCS Kernel

In this chapter we describe the main components of the openETCS OBU model. Section 5.1 gives an overview of the external interfaces of this functional block and briefly describes the subcomponents. A detailed description of the subcomponents is given in Sections 5.2 to 5.14.

## 5.1 ETCS Kernel Overview

The ETCS Kernel module consists of the 13 subcomponents F1.1 to F1.13 as depicted in Figure 6. In the following we briefly describe the functionality of these subcomponents (for a more detailed description we refer to Sections 5.2 to 5.14)

**F2.1: Manage\_TrackSideInformation\_Integration** This component is responsible for receiving Eurobalise telegrams and Euroradio messages from the API and performs several consistency checks on the inputs.

to be checked

**F2.2: Manage\_ETCS\_Procedures** This component describes the Start of Mission procedure of the train until the current status will change to another mode, level or other procedure.

descriptions needs to be improved

**F2.3: trainData** Implementation of the train data with the corresponding interfaces to track, driver and RBC.

descriptions needs to be improved

**F2.4: TrackAtlas** t.b.d.

to be completed

**F2.5: Mode\_and\_Level** Defines the status of the ETCS regarding on-board functional status and track infrastructure.

descriptions needs to be improved

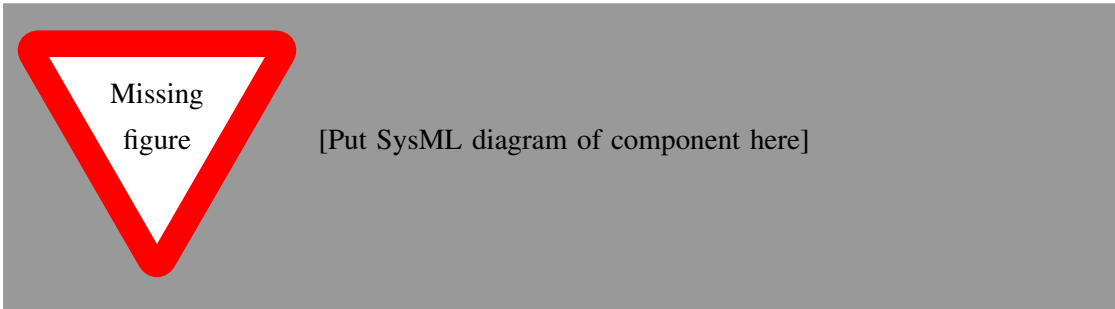


Figure 6. F2: ETCS Kernel SysML diagram

147 **F2.6: calculateTrainPosition** The purpose of this component is to calculate the locations of  
 148 linked and unlinked balise groups (BGs) and the current train position while the train is  
 149 running along the track.

150 **F2.7: SpeedSupervision\_Integration** This component monitors the speed of the train and the  
 151 train location to ensure that the speed remains within the given speed and distance limits.

152 to be checked

153 **F2.8: Provide\_Position\_Report** The component builds a position report for the RBC, i.e.,  
 154 message 132, and provides it as an output.

155 to be checked

156 **F2.9: Manage\_Radio\_Communication** This component implements the onboard management  
 157 of a single communication session with the track, i.e. a single RBC. It controls the estab-  
 158 lishment, maintenance and termination process of a radio communication session and steers  
 159 the underlying communication safety layer as well as the mobile device. Those and the data  
 160 transfer itself are not part of this component.

161 **F2.10: ManageDMIInput** t.b.d.

162 to be completed

163 **F2.11: ManageDMIOutput** t.b.d.

164 to be completed

165 **F2.12: ManageTIUInput** t.b.d.

166 to be completed

167 **F2.13: ManageTIUOutput** t.b.d.

168 to be completed

## 169 5.1.1 External Interfaces

170 This section gives a detailed overview of the external inputs and outputs of module F2: ETCS  
 171 Kernel.

### 172 5.1.1.1 External Inputs

#### 173 5.1.1.1.1 [Input 1 name]

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at bound-ary]

Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

174 **5.1.1.1.2 [Input 2 name]**

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

175 **5.1.1.2 External Outputs**

176 **5.1.1.2.1 [Output 1 name]**

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]



---

177 **5.1.1.2.2 [Output 2 name]**

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

---

178 **5.2 F2.1: Manage\_TrackSideInformation\_Integration**

179 **5.2.1 Component Requirements**

180 Clarify detail for documentation with the trackMessages concept

Component name	Manage_TrackSideInformation_Integration
Link to SCADE model	<a href="https://github.com/openETCS/modeling/blob/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/BaliseGroup/Manage_TrackSideInformation_Integration/Manage_TrackSideInformation_Integration.etp">https://github.com/openETCS/modeling/blob/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/BaliseGroup/Manage_TrackSideInformation_Integration/Manage_TrackSideInformation_Integration.etp</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	<p>The block “Manage_TrackSideInformation_Integration” is responsible for receiving Eurobalise telegrams and Euroradio messages from the API and performs several consistency checks on the inputs.</p> <p>The block collects the telegrams of balises in order to build balise group messages. Euroradio messages are always delivered as a whole message. On each message, a consistency check is performed, before the data is validated according to the driving direction of the train. In general, messages not designated for the current driving direction of the train are not forwarded to the further processing. After applying consistency checks, the data direction is validated.</p>

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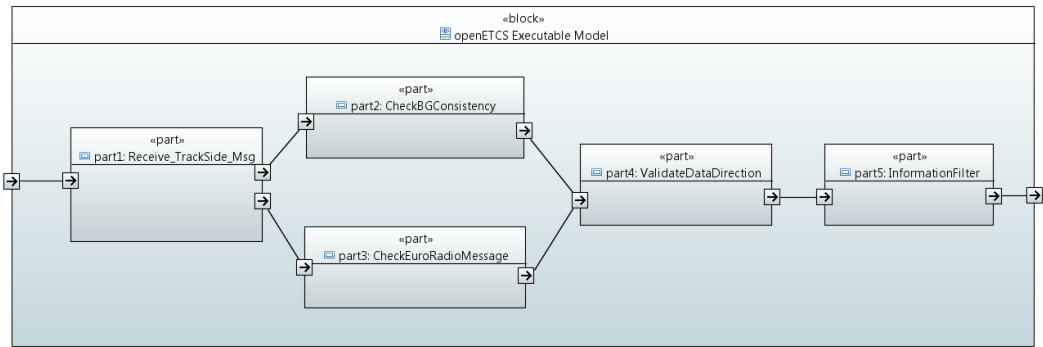


Figure 7. Manage\_TrackSideInformation\_Integration component SysML diagram.

Input documents	See subcomponents.
Safety integrity level	4
Time constraints	The component has to be able to receive balise telegrams and radio messages according to the ETCS [ ? ] performance requirements). In highspeed traffic, a group of 8 balises must be read in about 250 msec. In addition, 1 message per sec. on the radio interface is to be expected.
API requirements	Interfaces to this unit are defined in the API sections [BTM], [EU-RORADIO], [ODO].In these sections, also a detailed definition of the concepts implemented on those interfaces is documented.

5.2.2 Interface

Manage\_TrackSideInformation\_Integration SysML diagram needs to be updated.

An overview of the interface of component Manage\_TrackSideInformation\_Integration is shown in Figure 7. The inputs and outputs are described in detail in Section 5.2.2.1 respectively 5.2.2.2. Subcomponents are described in Section 5.2.3.

5.2.2.1 Inputs

5.2.2.1.1 fullChecks

Input name	fullChecks
Description	Indicates, if all checks on the message should be performed.
Source	This item is only relevant in verification phases. In a real system checks are always activated.
Type	bool

Valid range of values

**true** All checks are performed.

**false** Component InformationFilter is deactivated.

Behaviour when value is at boundary

n/a

Behaviour for values out of valid range

n/a

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)

[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

To be completed

#### 188 5.2.2.1.2 Receive\_trackSide\_Message

Input name

API\_trackSide\_Message

Description

Track side message received from the API. The API performs pre-processing of RTM and BTM messages and delivers a maximum of a single message per cycle. The structure of this message is defined in the API [BTM] and [EURORADIO] sections.

Source

API

Type

API\_Msg\_Pkg::API\_TrackSideInput\_T

Valid range of values

[Complete list of valid values]

To be completed

Behaviour when value is at boundary

[Description of components behaviour when input value is at boundary]

To be completed

Behaviour for values out of valid range

[Description of components behaviour when input value is out of valid range]

To be completed

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)

[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

To be completed

189 **5.2.2.1.3 ActualOdometry**

Input name	ActualOdometry
Description	Provided by the external odometry module of the train. It contains relative location information with inaccuracies.
Source	Odometer
Type	Obu_BasicTypes_Pkg::odometry_T
Valid range of values	[Complete list of valid values] To be completed
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary] To be completed
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range] To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed

190 **5.2.2.1.4 reset**

Input name	reset
Description	To delete all data stored in the module (e.g. collected balise telegrams, which do not yet form a complete message), a reset input can be used. If the input is set to true, all data kept in the module is deleted and no input is accepted.
Source	Environment
Type	bool
Valid range of values	<b>true</b> All data kept in the module is deleted and no input is accepted. <b>false</b> No action. Data at input is accepted.

Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
	To be completed

Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
	To be completed

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]
	To be completed

#### 191 5.2.2.1.5 trainPosition

Input name	trainPosition
Description	Contains the current position of the train.
Source	CalculateTrainPosition
Type	TrainPosition_Types_Pck::trainPosition_T
Valid range of values	To be completed

Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
	To be completed

Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
	To be completed

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]
	To be completed

#### 192 5.2.2.1.6 modeAndLevel

Input name	modeAndLevel
Description	Provides the current level and mode of the EVC.

Source	ModeAndLevel
Type	BG_Types_Pkg::ModeAndLevelStatus_T
Valid range of values	[Complete list of valid values] To be completed
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary] To be completed
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range] To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed

193 **5.2.2.1.7 tNvContact**

Input name	tNvContact
Description	For monitoring the safe radio connection, this national value is needed as an input.
Source	Database
Type	Obu_BasicTypes_Pkg::T_internal_Type
Valid range of values	[Complete list of valid values] To be completed
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary] To be completed
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range] To be completed

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed
---	--

#### 194 5.2.2.1.8 lastRelevantEventTimestamp

Input name	lastRelevantEventTimestamp
Description	For monitoring the safe radio connection, it is necessary that the time between two packets is less than the value of T_NVCONTACT. In situations like level-changes or announced radio holes, not the timestamp of the last message is relevant for comparison, but the timestamp of the last relevant event. This can for example be the timestamp of the level change or the timestamp of the moment, when the train was passing the end of the radiohole. For performing this check, the timestamp of the last relevant event is provided to the model as an T_internal_Type-type.
Source	Database
Type	Obu_BasicTypes_Pkg::T_internal_Type
Valid range of values	[Complete list of valid values] To be completed
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary] To be completed
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range] To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed

#### 195 5.2.2.1.9 connectionStatus

Input name	connectionStatus
Description	Status information about the radio connection. The information is needed to perform the timing check, which depends on the connection state.

Source	ManageRadioCommunication
Type	Radio_Types_Pkg::sessionStatus_Type
Valid range of values	<p><b>DISCONNECTED</b> The OBU is currently not connected to a RBC.</p> <p><b>CONNECTING</b> The OBU is currently connecting to the RBC. Received messages belong to the process of establishing a connection.</p> <p><b>CONNECTION_ESTABLISHED</b> The connection to the RBC is established.</p>
Behaviour when value is at boundary	<p>[Description of components behaviour when input value is at boundary]</p> <p>To be completed</p>
Behaviour for values out of valid range	<p>[Description of components behaviour when input value is out of valid range]</p> <p>To be completed</p>
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	<p>[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]</p> <p>To be completed</p>

#### 196 5.2.2.1.10 inSupervisingRbcId

Input name	inSupervisingRbcId
Description	For the subcomponent InformationFilter, the information which radio messages are sent by the supervising RBC is needed. To recognize these messages, the identifier of the supervising RBC is needed.
Source	<p>Database</p> <p>consider using the exact component name in the SCADE model</p>
Type	int
Valid range of values	<p>[Complete list of valid values]</p> <p>To be completed</p>



Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
	To be completed

Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
	To be completed

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]
	To be completed

#### 197 5.2.2.1.11 inAnnouncedBGs

Input name	inAnnouncedBGs
Description	Provides information about balise groups which will be passed by the train soon. This information is generated by Calculate Train Position based on the linking information received from trackside.
Source	CalculateTrainPosition
Type	TrainPosition_Types_Pck::positionedBGs_T
Valid range of values	[Complete list of valid values] To be completed
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary] To be completed
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range] To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed

#### 198 5.2.2.1.12 q\_nvlocacc

Input name	q_nvlocacc
Description	The national value determines the location accuracy.
Source	Database consider using the exact component name in the SCADE model
Type	Q_NVLOCACC
Valid range of values	[Complete list of valid values] To be completed
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary] To be completed
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range] To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed

### 199 5.2.2.2 Outputs

#### 200 5.2.2.2.1 outputMessage

Output name	outputMessage
Description	Combines both balise and radio messages to one common datatype. This datatype contains all variables and packets, which are possible for the given scenario.
Destination	[Name of the destination component(s)] To be completed
Type	Common_Types_Pkg::ReceivedMessage_T
Valid range of values	[Complete list of valid values] To be completed

Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary] To be completed
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range] To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed

#### 201 5.2.2.2.2 ApplyServiceBrake

Output name	ApplyServiceBrake
Description	Indicates if the balise group the train just passed could not be processed correctly. The check results in the request for a service break.
Destination	[Name of the destination component(s)] To be completed
Type	bool
Valid range of values	[Complete list of valid values] To be completed
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary] To be completed
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range] To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed

202 **5.2.2.2.3 BadBaliseMessageToDMI**

Output name	BadBaliseMessageToDMI
Description	Information to be passed to the DMI to indicate the reception of a “bad balise” to the driver.
Destination	DMI
Type	bool
Valid range of values	<p><b>true</b> ???</p> <p><b>false</b> ???</p> <p>To be completed</p>
Behaviour when value is at boundary	<p>[Description of components behaviour when output value is at boundary]</p> <p>To be completed</p>
Behaviour for values out of valid range	<p>[Description of components behaviour when output value is out of valid range]</p> <p>To be completed</p>
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	<p>[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]</p> <p>To be completed</p>

203 **5.2.2.2.4 errorLinkedBG**

Output name	errorLinkedBG
Description	<p>[Brief description of the output]</p> <p>To be completed</p>
Destination	<p>[Name of the destination component(s)]</p> <p>To be completed</p>
Type	<p>[Type of the output]</p> <p>To be completed</p>

Valid range of values

**true** An error in a linked balise group was detected.

**false** No error in a linked balise group was detected.

Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
-------------------------------------	--

To be completed

Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
---	---

To be completed

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]
---	---

To be completed

#### 204 5.2.2.2.5 errorUnlinkedBG

Output name	errorUnlinkedBG
-------------	-----------------

Description	[Brief description of the output]
-------------	-----------------------------------

To be completed

Destination	[Name of the destination component(s)]
-------------	--

To be completed

Type	bool
------	------

Valid range of values

**true** An error in a unlinked balise group was detected.

**false** No error in a unlinked balise group was detected.

Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
-------------------------------------	--

To be completed

Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range] To be completed
---	--

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed
---	--

#### 205 5.2.2.2.6 passedBG

Output name	passedBG
Description	Provides the received balise group message in a special format needed by the component CalculateTrainPosition.
Destination	[Name of the destination component(s)] To be completed
Type	BG_Types_Pkg::passedBG_T
Valid range of values	[Complete list of valid values] To be completed
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary] To be completed
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range] To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed

#### 206 5.2.2.2.7 outPositionParams

Output name	outPositionParams
Description	Provides the parameters for the position report in a special format needed by the component ProvidePositionReport.

Destination	[Name of the destination component(s)] To be completed
Type	Common_Types_Pkg::PositionReportParameter_T To be completed
Valid range of values	[Complete list of valid values] To be completed
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary] To be completed
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range] To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed

#### 207 5.2.2.2.8 outRadioManagement

Output name	outRadioManagement
Description	Provides the messages for radio session management in a special format needed by the component ManagementOfRadioCommunication.
Destination	[Name of the destination component(s)] To be completed
Type	Common_Types_Pkg::radioManagementMessage_T
Valid range of values	[Complete list of valid values] To be completed

Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary] To be completed
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range] To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed

#### 208 5.2.2.2.9 radioSequenceError

Output name	radioSequenceError
Description	[Brief description of the output] To be completed
Destination	[Name of the destination component(s)] To be completed
Type	bool
Valid range of values	<p><b>true</b> A sequence error or a timeout has been detected in the radio message.</p> <p><b>false</b> No error in the radio message sequence was detected.</p>
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary] To be completed
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range] To be completed



Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed
---	--

#### 209 5.2.2.2.10 radioMessageConsistencyError

Output name	radioMessageConsistencyError
Description	[Brief description of the output] To be completed
Destination	[Name of the destination component(s)] To be completed
Type	bool
Valid range of values	<p><b>true</b> A consistency error has been detected in the radio message.</p> <p><b>false</b> No consistency error in the radio message was detected.</p>
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary] To be completed
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range] To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] To be completed

### 210 5.2.3 Subcomponents

#### 211 5.2.3.1 Receive\_TrackSide\_Msg

##### 212 5.2.3.1.1 Component Requirements

Component name	Receive_TrackSide_Msg
----------------	-----------------------

Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/BaliseGroup/Receive_TrackSide_Msg">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/BaliseGroup/Receive_TrackSide_Msg</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	<p>This function defines the interface of the OBU model to the openETCS generic API for Eurobalise and Euroradio messages. On the interface, either a valid telegram/message is provided or a telegram/message is indicated which could not be received correct when passing the balise or receiving the radio message. The function passes a balise telegram without major changes of the information to the next entity for collecting the balise group information. This entity collects telegrams received via the interface into Balise Group Information. In case of a radio message, the message is converted to an internal format for further processing and passed without changing the information contained.</p> <ul style="list-style-type: none"> <li>• The decoding of balises is done at the API. Also, packets received via the interface are already transformed into a usable shape.</li> <li>• Only packets used inside the current model are passed via the interface.</li> <li>• Treatment of Packet 5: Linking Information. Linking Information is added to the linking array starting from index 0 without gaps. Used elements are marked as valid. Elements are sorted according to the order given by the telegram sequence.</li> <li>• Telegrams received as invalid are passed to the “Check-Function” to process errors in communication with the track side according to the requirements and in a single place. Telegrams are added to the telegram array starting from index 0 without gaps. Used elements are marked as valid. Elements are stored according to the order given by the telegram sequence.</li> <li>• This function does not process information from the packets. The information is passed to the check without further processing of the values.</li> </ul>
Input documents	<p>Subset-026, Chapter 7 and 8: Definition of the Balise Telegram</p> <p>Subset-026, Chapter 4.2.2, 4.2.4, 4.2.9: Interface to the BTM</p> <p>Subset-026, Chapter 3.4.1 - 3.4.3, 3.16.2: Handling of Balise Telegrams</p> <p>Subset-026, Chapter 3.16.2: Check of the balise group</p> <p>Subset-026, Chapter 3.4.2: Determining the orientation</p> <p>Subset-026, Chapter 4.5.2 Active Functions Table</p> <p>Subset-026, Chapter 8.4.4: Rules for Euroradio messages</p>
Safety integrity level	4
Time constraints	n/a

API requirements	n/a
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#### 213 **5.2.3.1.2 Interface**

214 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
215 above) respectively the SCADE generated documentation.

#### 216 **5.2.3.2 CheckBGConsistency**

##### 217 **5.2.3.2.1 Component Requirements**

Component name	CheckBGConsistency
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/BaliseGroup/CheckBGConsistency">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/BaliseGroup/CheckBGConsistency</a>
SCADE designer	Peyman Farhangi, DB Netz AG

Description	<p>The function "Receive_TrackSide_Msg" collects the telegrams in an array. If one or more telegrams are received multiple times, either whole the array or single telegram should be deleted.(e.g.if the train moves back.) The balises in a group are to be expected in a certain distance from each other. The function "Receive_TrackSide_Msg" checks if the telegrams has been received in due time and at the right expected location.</p> <p>The function "CheckBGConsistency" verifies the completeness and correctness of the received telegrams from balise groups and composes the balise message from the received telegram array (input from "Receive_TrackSide_Msg"). A balise message is built from at least one telegram and a maximum of 8 telegrams. When linking information is used on-board, only balise groups marked as linked and included in the linking information and balise groups marked as unlinked shall be taken into account.</p> <ul style="list-style-type: none"> <li>• A message is still complete and correct, if a telegram is missing (or not decoded or incompletely decoded), and this telegram is duplicated within the balise group and the duplicating one is correctly read.</li> <li>• In case of multiple balises, the order of the balises must be either ascending (nominal) or descending (reverse).</li> <li>• A message is not correct, if a message counters (M_MCOUNT) equals 254 (that means: The telegram never fits any message of the group). A message counter can equal 255 (that means: The telegram fits with all telegrams of the same balise group) and all other values must be the same.</li> </ul> <p>The orientation of the BG and the running direction of the train are calculated in this block. When linking information is used on-board, the check, if the message of linked balise group has been received in due time and at the expected location, will be performed in "Calculate Train Position". The checks on the validity of the data in the packets and the validity with respect to the direction of motion will be performed in other modules, e.g. "Validate Data Direction".</p>
Input documents	<p>Subset-026, Chapter 7 and 8: Definition of the Balise Telegram</p> <p>Subset-026, Chapter 3.4.1-3, 3.16.2: Handling of Balise Telegrams</p> <p>Subset-026, Chapter 3.16.2: Check of the balise group</p> <p>Subset-026, Chapter 4.5.2: Active Functions Table</p>
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 218 5.2.3.2.2 Interface

For an overview of the interface of this internal component we refer to the SCADE model (cf. link above) respectively the SCADE generated documentation.

### 5.2.3.3 CheckEuroradioMessage

#### 5.2.3.3.1 Component Requirements

Component name	CheckEuroradioMessage
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/b9c31ce6fdf702b412bbeab3032a8a4dc7c92e5c/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/BaliseGroup/CheckEuroRadioMessage">https://github.com/openETCS/modeling/tree/b9c31ce6fdf702b412bbeab3032a8a4dc7c92e5c/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/BaliseGroup/CheckEuroRadioMessage</a>
SCADE designer	Stefan Karg, LEA Railergy
Description	<p>The component “CheckEuroradioMessage” performs consistency and timing checks on the received radio message. These checks are:</p> <ul style="list-style-type: none"> <li>• checking the message sequence</li> <li>• check if the message violates timing constraints (T_NVCONTACT)</li> <li>• check if all mandatory elements are included</li> <li>• check if no elements are included, which are forbidden for the given message id</li> </ul> <p>Messages, which violate one or more of these criteria are marked as invalid in the message header and the component signals the reason for the invalidation via different flags as described in the SCADE model.</p>
Input documents	Subset-026, Chapter 3.16 Subset-026, Chapter 8.4.4
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 5.2.3.3.2 Interface

For an overview of the interface of this internal component we refer to the SCADE model (cf. link above) respectively the SCADE generated documentation.

### 5.2.3.4 ValidateDataDirection

#### 5.2.3.4.1 Component Requirements

Component name	ValidateDataDirection
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Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/BaliseGroup/ValidateDataDirection">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/BaliseGroup/ValidateDataDirection</a>
SCADE designer	Stefan Karg, LEA Railergy
Description	<p>The component filters an input message in order to mark all elements as invalid, which are not designated for the current driving direction of the train.</p> <ul style="list-style-type: none"> <li>• The operator contains two processing paths for different message types. Radio messages and balise group messages are handled in a different way. For validating the data direction of a radio message, the check is performed using the balise group referenced in the radio message header as relevant balise group. For balise group message, the LRBG is used.</li> <li>• The metadata of packets, which are recognized as not valid for the current driving direction, is invalidated.</li> </ul>
Input documents	Subset-026, Chapter 3.6.3
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 228 5.2.3.4.2 Interface

229 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
230 above) respectively the SCADE generated documentation.

#### 231 5.2.3.5 InformationFilter

##### 232 5.2.3.5.1 Component Requirements

233 Information filter component description needs to be checked, i.e. is the description still up to date? Should more documentation provided for this component in the ADD (please check with Bernd Hekele)?

Component name	CheckEuroradioMessage
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/BaliseGroup/InformationFilter">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/BaliseGroup/InformationFilter</a>
SCADE designer	Christian Stahl, TWT Alexander Stante, FhG

**Description** The filter receives track information (balise and radio) and filters them depending of the mode, level and source of the message. Only messages that pass the filter are valid and should be considered by other ETCS subsystems. Figure 8 shows the highlevel decomposition of the functionality. The filter is consists of four components: FirstFilter, SecondFilter, ThirdFilter and TransitionBuffer.

**FirstFilter** This filter performs filtering of messages based on the current ETCS level. The decisions taken process is described via a big decision table which contains rows for every packet and columns for every ETCS level. This table encodes also if certain additional information is necessary to filter a message like pending ETCS Level transitions. Based on this filter packets of an incoming message is either rejected, accepted or the whole message is put in the TransitionBuffer. Messages are put in the TransitionBuffer if there is an announced level transition and the received message is only valid for the upcoming level.

**SecondFilter** The SecondFilter mainly considers messages that are received via Euroradio. Certain messages are directly rejected while other may be stored in the TransitionBuffer. The buffer is used to store messages that are received from non supervising RBCs, but will be reevaluated after a RBC transition.

**ThirdFilter** The last filter is functionally very similiar the the First-Filter, however it filters depending on the mode. It also contains a decision table with rows for every packet but the columns are modes.

**TransitionBuffer** The InformationFilter uses two Transition-Buffers. One is used to store up to three messages for the ETCS level transition and the other buffer is used for RBC transitions. The buffer is designed as a ring buffer and message are read in FIFO order.

Input documents	Subset-026, Chapter 4.8
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

### 234 5.2.3.5.2 Interface

235 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
236 above) respectively the SCADE generated documentation.

## 5.3<sub>237</sub> F2.2: Manage\_ETCS\_Procedures

### 238 5.3.1 Component Requirements

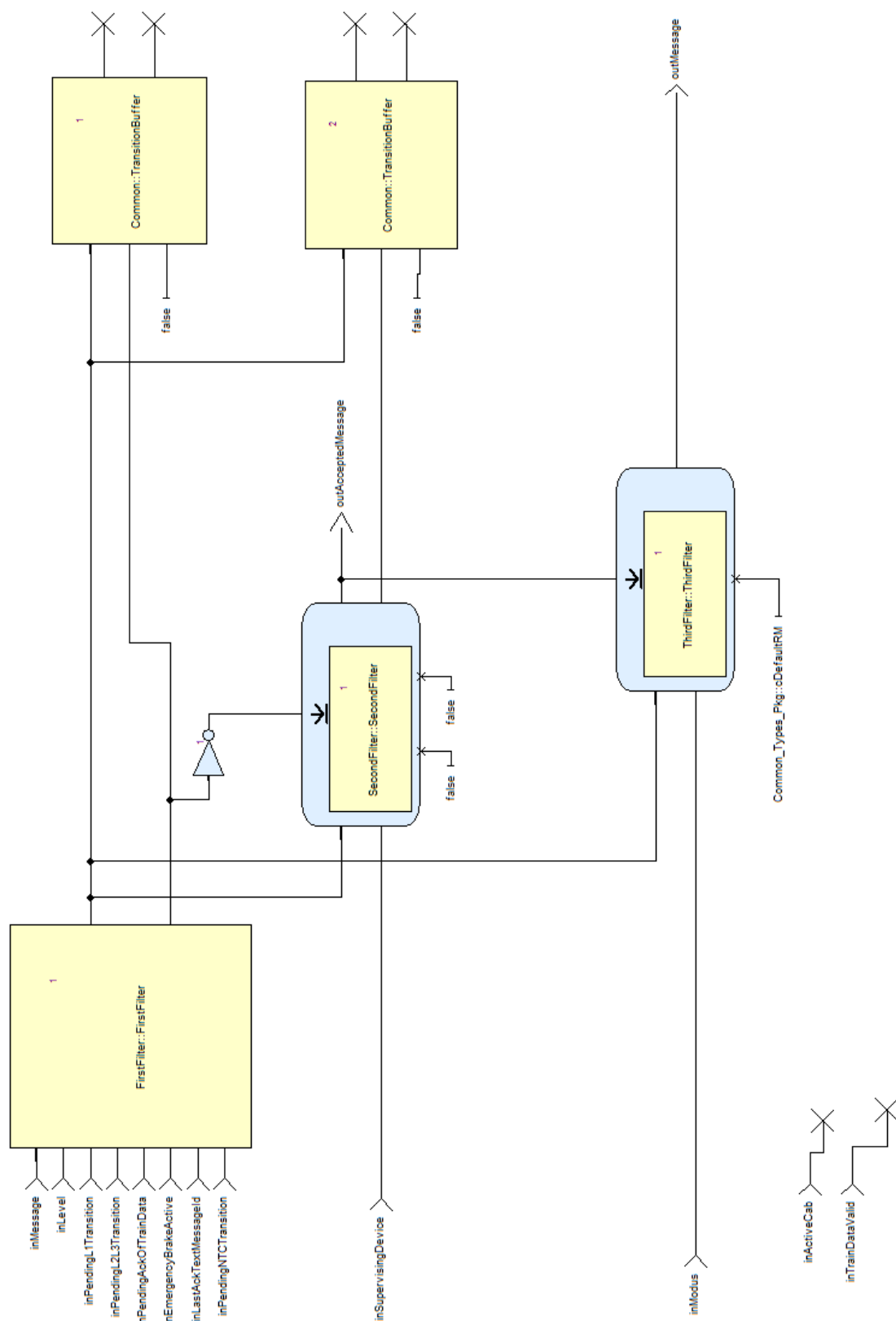


Figure 8. High level overview of the InformationFilter components.





Figure 9. Manage\_ETCS\_Procedures component SysML diagram

Component name	Manage_ETCS_Procedures
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/Procedures">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/Procedures</a>
SCADE designer	Baseliyos Jacob, DB Netz AG
Description	This function describes the Start of Mission procedure of the train until the current status will change to another mode, level or other procedure.
Input documents	Subset-026, Chapter 5.4
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

5.3.2 Interface

An overview of the interface of component Manage\_ETCS\_Procedures is shown in Figure 9. The inputs and outputs are described in detail in Section 5.3.2.1 respectively 5.3.2.2. Subcomponents are described in Section 5.3.3.

5.3.2.1 Inputs

5.3.2.1.1 statusDMI\_from\_DMI

Input name	statusDMI_from_DMI
Description	Input interface of DMI Controller status.
Source	manageDMI
Type	DMI_Types_Pkg::DMI_EVC_status_T
Valid range of values	To be completed

Behaviour when value is at boundary	n/a
-------------------------------------	-----

Behaviour for values out of valid range	Function will not be triggered.
---	---------------------------------

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Function will not be triggered.
---	---------------------------------

#### 245 5.3.2.1.2 Status\_MA\_FS\_SR\_OS\_LS\_SH\_from\_MA\_L2\_Management

Input name	Status_MA_FS_SR_OS_LS_SH_from_MA_L2_Management
Description	Status of MA, Mode and Level from Level and Mode Management.
Source	ManageLevelsAndModes
Type	bool

Valid range of values

**true** Movement Authority for Level 2 FS is valid

**false** Movement Authority for Level 2 FS is not valid

Behaviour when value is at boundary	n/a
-------------------------------------	-----

Behaviour for values out of valid range	n/a
---	-----

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	n/a
---	-----

#### 246 5.3.2.1.3 systemtime

Input name	systemtime
Description	Standardized system time used for all internal calculations.
Source	Obu_BasicTypes
Type	Obu_BasicTypes_Pkg::T_internal_Type
Valid range of values	[0, maximum positive int value of target platform]
Behaviour when value is at boundary	System time is assumed to be valid.

Behaviour for values out of valid range      System time is assumed to be valid.

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)      System time is assumed to be valid.

#### 247 5.3.2.1.4 StatusModeandLevel\_from\_Level\_and\_Mode\_Management

Input name	StatusModeandLevel_from_Level_and_Mode_Management
Description	Status of Mode and Level.
Source	ManageLevelsAndModes
Type	Level_And_Mode_Types_Pkg::T_Mode_Level
Valid range of values	To be completed
Behaviour when value is at boundary	To be completed
Behaviour for values out of valid range	To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	To be completed

#### 248 5.3.2.1.5 mobileSwStatus\_p\_from\_MoRC

Input name	mobileSwStatus_p_from_MoRC
Description	Information about SW status from Management of Radio Communication function.
Source	MoRC
Type	MoRC_Pck::mobileSWStatus_Type
Valid range of values	To be completed
Behaviour when value is at boundary	To be completed

Behaviour for values out of valid range

To be completed

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)

To be completed

#### 249 5.3.2.1.6 statusRBCSessionEstablished\_status\_from\_MoRC

Input name	statusRBCSessionEstablished_status_from_MoRC
Description	Information about RBC Session status from the Management of Radio Communication function.
Source	MoRC exact name of component in the SCADE model has be used
Type	Radio_Types_Pkg::sessionStatus_Type
Valid range of values	To be completed
Behaviour when value is at boundary	To be completed
Behaviour for values out of valid range	To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	To be completed

#### 250 5.3.2.1.7 cabStatus\_from\_TIU

Input name	cabStatus_from_TIU
Description	Information about cab desk status from Train Interface Unit function.
Source	manageTIUInput
Type	TIU_Types_Pkg::TIU_trainStatus_T

Valid range of values

To be completed

Behaviour when value is at boundary

To be completed

Behaviour for values out of valid range

To be completed

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)

To be completed

251

**5.3.2.1.8 statusValid\_Position\_from\_Position\_Calculation**

Input name	statusValid_Position_from_Position_Calculation
Description	Information about validity status of the train position calculation.
Source	TrainPosition exact name of component in the SCADE model has be used
Type	bool
Valid range of values	<p><b>true</b> Calculated train position is valid</p> <p><b>false</b> Calculated train position is not valid</p>
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	n/a

252

**5.3.2.1.9 status\_DMILEvel\_from\_DMI**

Input name	status_DMILEvel_from_DMI
Description	Information about the status of DMI menu and level request from DMIController function.

Source	ManageDMIInput
Type	DMI_Messages_DMI_to_EVC_Pkg::DMI_Driver_Request_T
Valid range of values	To be completed
Behaviour when value is at boundary	To be completed
Behaviour for values out of valid range	To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	To be completed

253

#### 5.3.2.1.10 LevelValid\_from\_Level\_and\_Mode\_Management

Input name	LevelValid_from_Level_and_Mode_Management
Description	Information about the validity status of the StatusModeandLevel_from_Level_and_Mode_Management input.
Source	ManageLevelsAndModes exact name of component in the SCADE model has be used
Type	bool
Valid range of values	<b>true</b> Level and Mode information are valid <b>false</b> Level and Mode information are not valid
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	n/a

### 254 5.3.2.2 Outputs

#### 255 5.3.2.2.1 DMI\_Entry\_Request\_to\_DMI

Output name	DMI_Entry_Request_to_DMI
Description	Information about input request to the driver.
Destination	ManageDMIOutput
Type	DMI_Messages_EVC_to_DMI_Pkg::DMI_Entry_Request_T
Valid range of values	To be completed
Behaviour when value is at boundary	To be completed
Behaviour for values out of valid range	To be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	To be completed

#### 256 5.3.2.2.2 request\_Start\_Mobile\_Terminal\_and\_RBC\_Registration\_to\_MoRC

Output name	request_Start_Mobile_Terminal_and_RBC_Registration_to_MoRC
Description	This output is a trigger to start the mobile terminal and RBC session registration within the Management of Radio Communication function.
Destination	MoRC exact name of component in the SCADE model has be used
Type	Common_Types_Pkg::radioManagementMessage_T
Valid range of values	To be completed
Behaviour when value is at boundary	To be completed

Behaviour for values out of valid range

To be completed

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)

To be completed

#### 257 5.3.2.2.3 powerUp\_to\_MoRC

Output name	powerUp_to_MoRC
Description	This output is the trigger to activate the Management of Radio Communication function.
Destination	MoRC exact name of component in the SCADE model has be used
Type	bool
Valid range of values	<b>true</b> MoRC will be activated <b>false</b> no action
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	n/a

#### 258 5.3.2.2.4 statusstartofmissionongoing\_to\_MoRC

Output name	statusstartofmissionongoing_to_MoRC
Description	This output gives the information about the start of mission status procedure to the Management of Radio Communication function.
Destination	MoRC exact name of component in the SCADE model has be used
Type	bool



Valid range of values

**true** Start of mission procedure is currently ongoing

**false** Start of mission procedure is currently not ongoing

Behaviour when value is at boundary n/a

Behaviour for values out of valid range n/a

Behaviour when value is erroneous, absent or unwanted (i.e. spurious) n/a

#### 259 5.3.2.2.5 powerOff\_to\_MoRC

Output name powerOff\_to\_MoRC

Description This output is the trigger to de-activate the Management of Radio Communication function.

Destination MoRC  
exact name of component in the SCADE model has be used

Type bool

Valid range of values

**true** MoRC will be deactivated

**false** no action

Behaviour when value is at boundary n/a

Behaviour for values out of valid range n/a

Behaviour when value is erroneous, absent or unwanted (i.e. spurious) n/a

#### 260 5.3.2.2.6 start\_ack\_to\_TIU

Output name start\_ack\_to\_TIU

Description This output indicates that the start of mission procedure is completed.

Destination	ManageTIUOutput
Type	bool
Valid range of values	<b>true</b> Start of mission procedure is completed
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	n/a

### 261 5.3.3 Subcomponents

#### 262 5.3.3.1 Awakness\_of\_Train

##### 263 5.3.3.1.1 Component Requirements

Component name	Awakness_of_Train
Link to SCADE model	<a href="https://github.com/openETCS/modeling/blob/master/model/Scade/System/ObuFunctions/Procedures/ManageProcedure_Pkg.xscade">https://github.com/openETCS/modeling/blob/master/model/Scade/System/ObuFunctions/Procedures/ManageProcedure_Pkg.xscade</a>
SCADE designer	Baseliyos Jacob, DB Netz AG
Description	This component describes the Start of Mission procedure of the train until the status of the awakening is completed. From this point on the train will be able to switch to further modes, levels and procedures.
Input documents	Subset-026, Chapter 5, § 5.4
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

##### 264 5.3.3.1.2 Interface

265 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
266 above) respectively the SCADE generated documentation.

##### 267 5.3.3.2 NP

### 268 5.3.3.2.1 Component Requirements

Component name	NP
Link to SCADE model	<a href="https://github.com/openETCS/modeling/blob/master/model/Scade/System/ObuFunctions/Procedures/ManageProcedure_Pkg.xscade">https://github.com/openETCS/modeling/blob/master/model/Scade/System/ObuFunctions/Procedures/ManageProcedure_Pkg.xscade</a>
SCADE designer	Baseliyos Jacob, DB Netz AG
Description	This component implements the No Power status of the train before the driver opens the cab desk.
Input documents	Subset-026, Chapter 5, § 5.4
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

### 269 5.3.3.2.2 Interface

270 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
271 above) respectively the SCADE generated documentation.

### 272 5.3.3.3 SoM\_L2\_3\_FS\_SR\_OS\_LS\_SH

#### 273 5.3.3.3.1 Component Requirements

Component name	SoM_L2_3_FS_SR_OS_LS_SH
Link to SCADE model	<a href="https://github.com/openETCS/modeling/blob/master/model/Scade/System/ObuFunctions/Procedures/ManageProcedure_Pkg.xscade">https://github.com/openETCS/modeling/blob/master/model/Scade/System/ObuFunctions/Procedures/ManageProcedure_Pkg.xscade</a>
SCADE designer	Baseliyos Jacob, DB Netz AG
Description	This component switch to Level 2 or 3 and Mode FS, SR, OS, LS and SH after completion of the awakening of the train.
Input documents	Subset-026, Chapter 5, § 5.4
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 274 5.3.3.3.2 Interface

275 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
276 above) respectively the SCADE generated documentation.

### 277 5.3.3.4 SoM\_NTC\_SN

#### 278 5.3.3.4.1 Component Requirements

Component name	SoM_NTC_SN
Link to SCADE model	<a href="https://github.com/openETCS/modeling/blob/master/model/Scade/System/ObuFunctions/Procedures/ManageProcedure_Pkg.xscade">https://github.com/openETCS/modeling/blob/master/model/Scade/System/ObuFunctions/Procedures/ManageProcedure_Pkg.xscade</a>
SCADE designer	Baseliyos Jacob, DB Netz AG
Description	This component switch to Level NTC and Mode SN after completion of the awakening of the train.
Input documents	Subset-026, Chapter 5, § 5.4
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 279 5.3.3.4.2 Interface

280 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
281 above) respectively the SCADE generated documentation.

### 5.4<sub>282</sub> F2.3: trainData

#### 283 5.4.1 Component Requirements

Component name	trainData
Link to SCADE model	<a href="https://github.com/openETCS/modeling/blob/master/model/Scade/System/ObuFunctions/manageData/trainData/trainData.etp">https://github.com/openETCS/modeling/blob/master/model/Scade/System/ObuFunctions/manageData/trainData/trainData.etp</a>
SCADE designer	Bernd Hekele, DB Netz AG



Figure 10. trainData component SysML diagram

Description	<p>Implementation of the train data with the corresponding interfaces to track, driver and RBC.</p> <div>descriptions needs to be improved to be more comprehensive</div> <p>Data first is received from the train (TIU). Second step: train data is sent to the driver (DMI). The part relevant for driver interface is confirmed by the driver and sent back to the EVC. Data received via this interface is merged with the data received via TIU. Message Flow:</p> <ul style="list-style-type: none"><li>• sending Message 129 (Validated Train Data)</li><li>• receiving Message 8 (Acknowledgment of Train Data) is processed as apart of the validation procedure with the RBC.</li><li>• sending Message 146 (Acknolwedement) in the context of this message flow. T_TRAIN parameter of the messages is used to confirm the association of the messages.</li></ul> <p>The trainData component uses a dedicated state for controlling the reception of the acknowledgement.</p>
Input documents	Subset-026, Chapter 3.18.3
Safety integrity level	4
Time constraints	n/a
API requirements	Train Data needs systemtime for stamping messages, access to input from the track messages and access to the output of RBC messages.

284 **5.4.2 Interface**

285 An overview of the interface of component trainData is shown in Figure 10. The inputs and  
286 outputs are described in detail in Section 5.4.2.1 respectively 5.4.2.2. Subcomponents are  
287 described in Section 5.4.3.

288 **5.4.2.1 Inputs**

289 **5.4.2.1.1 reset**

Input name	reset
Description	Triggers the reset of the train data and the train data status data.
Source	Persistent data status management.
Type	bool
Valid range of values	<p><b>true</b> Perform reset of train data and train data status.</p> <p><b>false</b> No reset of data in this cycle.</p>
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	n/a

#### 290 5.4.2.1.2 trainDatafromTIU

Input name	trainDatafromTIU
Description	Train data received via TIU. The availability of data is indicated with the valid flag. This data is expected to be received in the first place. In the current implementation it is not supported to change data after a mission has been started.
Source	Train Interface Unit (TIU)
Type	TIU_Types_Pkg::trainData_T
Valid range of values	<p>Input with valid information is indicated with the valid flag.</p> <p>Looking at this input this seems to be a complex structure. Consider describing the structure instead of referring to the valid flag only.</p>
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	When valid flag indicates false the data to be used is assumed to be default values. The component is not used when valid flag is false.
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Information is only expected at Start of Mission Procedure. Once the information is successfully received it is not considered any more. Change of train data by train during mission is not supported by this version of the openETCS OBU model.

291 **5.4.2.1.3 trainDatafromDriver**

Input name	trainDatafromDriver
Description	Train data received via DMI from the driver. The availability of data is indicated with the valid flag. This data is expected to be received in the first place. In the current implementation it is not supported to change data after a mission has been started.
Source	Driver Machine Interface (DMI)
Type	DMI_Messages_Bothways_Pkg::DMI_Train_Data_T
Valid range of values	Input with valid information is indicated with the valid flag. Looking at this input this seems to be a complex structure. Consider describing the structure instead of referring to the valid flag only.
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	When valid flag indicates false the data to be used is assumed to be default values. The component is not used when valid flag is false.
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	No checks on individual values is done in this part of the openETCS EVC. We assume - if necessary - appropriate checks are part of the interface layer (e.g., CRC checks) This type of checks is not in the scope of the openETCS project.

292 **5.4.2.1.4 trainDataAckfromDriver**

Input name	trainDataAckfromDriver
Description	During start of mission the driver has to validate the train data. The confirmation is visible based on this input. Presence of the input is indicated with the valid flag. Looking at this input this seems to be a complex structure. Consider describing the structure instead of referring to the valid flag only.
Source	Driver Machine Interface (DMI)
Type	DMI_Messages_DMI_to_EVC_Pkg::DMI_Train_Data_Ack_T
Valid range of values	Input with valid information is indicated with the valid flag. In addition, the ack parameter has to be evaluated in order to recognise the decision of the driver.
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	when valid flag indicates false the data to be used is assumed to be default values. The component is not used when valid flag is false.

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	no checking on individual values is done in this part of the openETCS EVC. We assume - if necessary - appropriate checks are part of the interface layer (e.g., CRC checks) This type of checks is not in the scope of the openETCS project.
---	--

#### 293 5.4.2.1.5 trackMessages

Input name	trackMessages
Description	Information carries the message received from RBC. Information is only used when the valid flag is true and the message source is Radio. Other information is not relevant. Information is evaluated as long as the validation procedure is not completed and a validation request with the RBC is pending.
Source	Radio Transmission Module (RTM)
Type	Common_Types_Pkg::ReceivedMessage_T
Valid range of values	Input with valid information is indicated with the valid flag. Looking at this input this seems to be a complex structure. Consider describing the structure instead of referring to the valid flag only.
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	When valid flag indicates false the data to be used is assumed to be default values. The component is not used when valid flag is false.
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	No checking on individual values is done in this part of the openETCS EVC. We assume - if necessary - appropriate checks are part of the interface layer (e.g., CRC checks) This type of checks is not in the scope of the openETCS project.

#### 294 5.4.2.1.6 timeStamp

Input name	timeStamp
Description	Timestamp for messaging to the RBC.
Source	Derived from train time.
Type	T_TRAIN
Valid range of values	Positive non-zero real
Behaviour when value is at boundary	Parameter is not used for computation or addressing. No impact in this model.
Behaviour for values out of valid range	No impact in the EVC. Communication to the RBC will be broken.



Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Communication to the RBC will be broken. No safety issue in the EVC since RBC connection errors are covered by the EVC function.
---	--

#### 295 5.4.2.1.7 eventsForTrainData

Input name	eventsForTrainData
Description	<p>Timestamp for messaging to the RBC. Information of the EVC relevant for train data handling according to Section 3.18.3. In the current state of implementation the following events are evaluated:</p> <ul style="list-style-type: none"> <li>• train stand-still</li> <li>• communication Session established</li> </ul> <p>The MoRC ready input is used to indicate the evc:morec function is ready with acknowledgment of the communication session.</p>
Source	EVC model.
Type	trainData_Types_pkg::trainData_Events_T
Valid range of values	Structure of a set of bool. Each component may be true or false.
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	n/a

#### 296 5.4.2.2 Outputs

297 section needs to be completed

##### 298 5.4.2.2.1 [Output 1 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]

Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

#### 299 5.4.2.2.2 [Output 2 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

#### 300 5.4.3 Subcomponents

301 section needs to be completed

### 5.5<sub>302</sub> F2.4: TrackAtlas

303 Section needs to be completed

#### 304 5.5.1 Component Requirements

Component name	TrackAtlas
Link to SCADE model	???
SCADE designer	Jakob Gärtner, LEA
Description	???
Input documents	Subset-026, Chapter ???



Figure 11. TrackAtlas component SysML diagram

Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

5.5.2 Interface

An overview of the interface of component TrackAtlas is shown in Figure 11. The inputs and outputs are described in detail in Section 5.5.2.1 respectively 5.5.2.2. Subcomponents are described in Section 5.5.3.

5.5.2.1 Inputs

5.5.2.1.1 [Input 1 name]

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

5.5.2.1.2 [Input 2 name]

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]
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## 312 5.5.2.2 Outputs

### 313 5.5.2.2.1 [Output 1 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

### 314 5.5.2.2.2 [Output 2 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

### 315 5.5.3 Subcomponents

#### 316 5.5.3.1 StoreRaw\_NV

##### 317 5.5.3.1.1 Component Requirements

Component name	StoreRaw_NV
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Jakob Gärtner, LEA
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

##### 318 5.5.3.1.2 Interface

319 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
320 above) respectively the SCADE generated documentation.

#### 321 5.5.3.2 Build\_GradientProfile

##### 322 5.5.3.2.1 Component Requirements

Component name	Build_GradientProfile
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Jakob Gärtner, LEA
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

##### 323 5.5.3.2.2 Interface

324 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
325 above) respectively the SCADE generated documentation.

### 326 5.5.3.3 Build\_MA

#### 327 5.5.3.3.1 Component Requirements

Component name	Build_MA
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Jakob Gärtner, LEA
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 328 5.5.3.3.2 Interface

329 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
330 above) respectively the SCADE generated documentation.

### 331 5.5.3.4 Build\_MRSP

#### 332 5.5.3.4.1 Component Requirements

Component name	Build_MRSP
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Jakob Gärtner, LEA
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 333 5.5.3.4.2 Interface

334 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
335 above) respectively the SCADE generated documentation.

### 336 5.5.3.5 Manage\_EmergencyStop

#### 337 5.5.3.5.1 Component Requirements

Component name	Manage_EmergencyStop
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Jakob Gärtner, LEA
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 338 5.5.3.5.2 Interface

339 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
340 above) respectively the SCADE generated documentation.

### 341 5.5.3.6 C\_P003V1\_OBU\_P003\_OBU

#### 342 5.5.3.6.1 Component Requirements

Component name	C_P003V1_OBU_P003_OBU
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Jakob Gärtner, LEA
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 343 5.5.3.6.2 Interface

344 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
345 above) respectively the SCADE generated documentation.

### 346 5.5.3.7 GradientProfile\_to\_DMI

#### 347 5.5.3.7.1 Component Requirements

Component name	GradientProfile_to_DMI
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Jakob Gärtner, LEA
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 348 5.5.3.7.2 Interface

349 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
350 above) respectively the SCADE generated documentation.

### 351 5.5.3.8 Manage\_MA\_Request

#### 352 5.5.3.8.1 Component Requirements

Component name	Manage_MA_Request
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Jakob Gärtner, LEA
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 353 5.5.3.8.2 Interface



354 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
355 above) respectively the SCADE generated documentation.

### 356 5.5.3.9 TA\_to\_ML

#### 357 5.5.3.9.1 Component Requirements

Component name	TA_to_ML
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Jakob Gärtner, LEA
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 358 5.5.3.9.2 Interface

359 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
360 above) respectively the SCADE generated documentation.

### 361 5.5.3.10 SSP\_to\_MRSP

#### 362 5.5.3.10.1 Component Requirements

Component name	SSP_to_MRSP
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Jakob Gärtner, LEA
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 363 5.5.3.10.2 Interface

364 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
365 above) respectively the SCADE generated documentation.

### 366 5.5.3.11 MRSP\_to\_MRSP\_to\_DMI

#### 367 5.5.3.11.1 Component Requirements

Component name	MRSP_to_MRSP_to_DMI
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Jakob Gärtner, LEA
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 368 5.5.3.11.2 Interface

369 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
370 above) respectively the SCADE generated documentation.

## 5.6<sub>371</sub> F2.5: Mode\_and\_Level

### 372 5.6.1 Component Requirements

Component name	Mode_and_Level
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLevelsAndModes">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLevelsAndModes</a>
SCADE designer	Marielle Petit-Doche and Matthias Güdemann, Systerel
Description	Modes and levels define the status of the ETCS regarding on-board functional status and track infrastructure.
Input documents	Subset-026, Chapter 4 Subset-026, Chapter 5
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

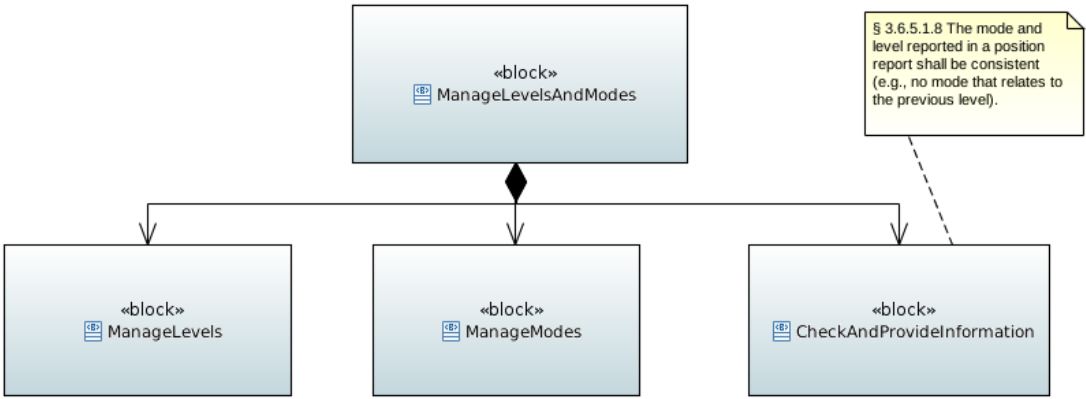


Figure 12. Mode\_and\_Level component SysML diagram

5.6.2 Interface

An overview of the interface of component Mode\_and\_Level is shown in Figure 12. The inputs and outputs are described in detail in Section 5.6.2.1 respectively 5.6.2.2. Subcomponents are described in Section 5.6.3.

5.6.2.1 Inputs

5.6.2.1.1 Data\_From\_TIU

table has been truncated. Please do not remove rows from the table template. Just use "n/a" if a row is not relevant for a particular input or output.

Input name	Data_From_TIU
Description	Set of data providing by TIU
Source	input_from_TIU_API_Pkg::manageTIU_input
Type	TIU_Types_Pkg::Message_Train_Interface_to_EVC_T
Valid range of values	It is a complex type more detail should be given here
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary] to be completed
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range] to be completed

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] to be completed
---	--

#### 380 5.6.2.1.2 Cab\_In

381 table has been truncated. Please do not remove rows from the table template. Just use "n/a" if a row is not relevant for a particular input or output.

Input name	Cab_In
Description	Identification of the cabine where the EVC is implemented
Source	??? to be completed
Type	TIU_Types_Pkg::cab_ID_T
Valid range of values	[CabUndefined, CabA, CabB]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary] to be completed
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range] to be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] to be completed

#### 382 5.6.2.1.3 Data\_From\_DMI

383 table has been truncated. Please do not remove rows from the table template. Just use "n/a" if a row is not relevant for a particular input or output.

Input name	Data_From_DMI
Description	Set of data transmitted from DMI (driver acknowledgements and requests to switch modes and level)
Source	manage_DMI_Input_Pkg::manageDMI_Input

Type	DMI_Types_Pkg::DMI_To_Modes_T
Valid range of values	<p>It is a complex type :</p> <ul style="list-style-type: none"> <li>• valid : bool, flag to inform of the freshness of the information</li> <li>• DriverAck : DMI_DriverAck_T, indicate which mode is acknowledged</li> <li>• DriverRequest : DMI_DriverRequest_T, table of boolean values for all the driver request related to mode changes.</li> <li>• LevelAck : bool, indication of Level change acknowledgement</li> </ul>
Behaviour when value is at boundary	<p>[Description of components behaviour when input value is at boundary]</p> <p>to be completed</p>
Behaviour for values out of valid range	<p>[Description of components behaviour when input value is out of valid range]</p> <p>to be completed</p>
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	<p>[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]</p> <p>to be completed</p>

#### 384 5.6.2.1.4 driver\_level\_transition\_in

385 table has been truncated. Please do not remove rows from the table template. Just use "n/a" if a row is not relevant for a particular input or output.

Input name	driver_level_transition_in
Description	Request of level transition given by the driver for example at start of mission
Source	manage_DMI_Input_Pkg::manageDMI_Input
Type	Level_And_Modes_Types_Pkg::T_LevelTransition
Valid range of values	It is a complex type
Behaviour when value is at boundary	<p>[Description of components behaviour when input value is at boundary]</p> <p>to be completed</p>

Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range] to be completed
---	---

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] to be completed
---	--

#### 386 5.6.2.1.5 Data\_From\_Track\_Packets

387 table has been truncated. Please do not remove rows from the table template. Just use "n/a" if a row is not relevant for a particular input or output.

Input name	Data_From_Track_Packets
Description	Packets received from trackside containing information for modes and levels switches
Source	???? to be completed
Type	Level_And_Mode_Types_Pkg::T_Data_From_Track_Packet
Valid range of values	It is a complex type containing the information of packets : 12, 15, 21, 27, 41, 46, 63, 80, 135, 137, 138 and 139
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary] to be completed
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range] to be completed
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)] to be completed

#### 388 5.6.2.1.6 Data\_From\_speed\_and\_Supervision

389 table has been truncated. Please do not remove rows from the table template. Just use "n/a" if a row is not relevant for a particular input or output.

Input name	Data_From_speed_and_Supervision
Description	Data provided by the speed and supervision function
Source	Speed and Supervision function Please use exact component name from SCADE model.
Type	Level_And_Mode_Types_Pkg::T_Data_From_Speed_Supervision
Valid range of values	<p>Input type a complex type</p> <ul style="list-style-type: none"> <li>• <i>Estim_front_End_overpass_SR_Dist : bool</i>: the train overpass the SR distance with its estimated front end (from SR to trip mode condition 42)</li> <li>• <i>Estim_Front_End_Rear_SSP : bool</i>: estimated front end is rear of the start location of either SSP or gradient profile stored on-board (from FS, LS, OS to trip mode condition 69)</li> <li>• <i>Override_Function_Active</i>: boolean to indicate the state of the activation function</li> <li>• <i>EOA_Antenna_Overpass : bool</i>: the train overpasses the EOA with min safe antenna position Level 1 (from FS, LS, OS to trip mode condition 12)</li> <li>• <i>EOA_Front_End : bool</i> the train overpasses the EOA with min safe front end, Level 2 or 3 (from FS, LS, OS to trip mode condition 16)</li> <li>• <i>Train_Speed_Under_Override_Limit : bool</i> supervision when override function is active (to SR mode condition 37)</li> </ul>
Behaviour when value is at boundary	<p>[Description of components behaviour when input value is at boundary]</p> <p>to be completed</p>
Behaviour for values out of valid range	<p>[Description of components behaviour when input value is out of valid range]</p> <p>to be completed</p>
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	<p>[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]</p> <p>to be completed</p>

Description of outputs needs to be completed

391

#### 392 5.6.2.2.1 [Output 1 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

#### 393 5.6.2.2.2 [Output 2 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

### 394 5.6.3 Subcomponents

#### 395 5.6.3.1 Level\_Management

##### 396 5.6.3.1.1 Component Requirements



Component name	Level_Management
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/openETCSArchitectureAndDesign/WorkGroups/Group3/SCADE/LevelManagement/">https://github.com/openETCS/modeling/tree/master/openETCSArchitectureAndDesign/WorkGroups/Group3/SCADE/LevelManagement/</a>
SCADE designer	Marielle Petit-Doche and Matthias Güdemann, Systerel
Description	<p>The level management subsystem receives level transition order tables and selects the order with the highest probability. It stores the information about the selected transition order and transits to the requested level once the train passes the location of the level transition.</p> <p>If required, the driver is asked to acknowledge the transition, in case of no acknowledgment or if conditions for the level transition are not fulfilled, the train gets tripped.</p> <p>On the most abstract level the design consists of the <i>manage_priorities</i> function which takes the level transition order priority tables as inputs and computes the highest priority transition.</p> <p>This transition order is fed to the <i>computeLevelTransitions</i> operator. This operator consists of three main parts. The <i>ComputeTransitionConditions</i> operator that emits the fulfilled conditions to change from a given level to a new level, the <i>LevelStateMachine</i> that stores the current level and takes the computed change conditions as input for possible level transitions and finally the <i>driverAck</i> operator which contains a state machine that stores the information whether the system is currently waiting for a driver acknowledge and emits the train trip information if necessary.</p>
Input documents	Subset-026, Chapter 5.10
Safety integrity level	4
Time constraints	<p>[If applicable description of time constraints, otherwise n/a]</p> <p>to be completed</p>
API requirements	<p>[If applicable description of API requirements, otherwise n/a]</p> <p>to be completed</p>

### 397 5.6.3.1.2 Interface

398 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
399 above) respectively the SCADE generated documentation.

## 400 5.6.3.2 Mode\_Management

### 401 5.6.3.2.1 Component Requirements

Component name	Mode_Management
----------------	-----------------

Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLevelsAndModes/Modes">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLevelsAndModes/Modes</a>
SCADE designer	Marielle Petit-Doche, Systerel
Description	<p>This function is in charge of the computation of new mode to apply according to conditions from inputs (track information, driver interactions, train data,...) and other functions.</p> <p>Three subfunctions are defined:</p> <p><b>Inputs</b> proceeds to inputs check and preparation.</p> <p><b>ComputeModesCondition</b> performs all specific procedure linked to mode management and defined in [1] sections 5.4, 5.5, 5.6, 5.7, 5.8, 5.9, 5.11, 5.12, 5.13, 5.19 and specifies the conditions to define a mode transition according condition table of section 4.6.3 of [1]</p> <p><b>SwitchModes</b> performs the mode selection according the conditions and priorities defined in transition table section 4.6.2 of [1]</p> <p><b>Outputs</b> prepares packet of outputs.</p>
Input documents	Subset-026, Chapter 4.4, 4.6, 5.4, 5.5, 5.6, 5.7, 5.8, 5.9, 5.11, 5.12, 5.13, 5.19
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a] to be completed
API requirements	[If applicable description of API requirements, otherwise n/a] to be completed

#### 402 5.6.3.2.2 Interface

403 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
404 above) respectively the SCADE generated documentation.

#### 405 5.6.3.3 Check\_and\_Provide\_Mode\_and\_Level

##### 406 5.6.3.3.1 Component Requirements

Component name	Check_and_Provide_Mode_and_Level
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLevelsAndModes/Modes">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLevelsAndModes/Modes</a>

SCADE designer	Marielle Petit-Doche, Systerel
Description	Checks compatibility between mode and level and provides outputs.
Input documents	Subset-026, Chapter 3.6.5
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a] to be completed
API requirements	[If applicable description of API requirements, otherwise n/a] to be completed

#### 407 5.6.3.3.2 Interface

408 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
409 above) respectively the SCADE generated documentation.

### 5.7<sub>410</sub> F2.6: calculateTrainPosition

#### 411 5.7.1 Component Requirements

Component name	calculateTrainPosition
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition</a>
SCADE designer	Uwe Steinke, Siemens AG

Description	<p>The main purpose of the function is to calculate the locations of linked and unlinked balise groups (BGs) and the current train position while the train is running along the track. In detail, the calculateTrainPosition function provides a couple of essential subfunctions for the onboard unit. These are mainly:</p> <ul style="list-style-type: none"> <li>• Creating and maintaining an obu internal coordinate system for all types of location based data.</li> <li>• Storing all linked and unlinked balise groups resulting from over passing or from announcements (linking information) from the track.</li> <li>• Calculating and maintaining the locations of all stored balise groups during the train trip, based on odometry and linking information.</li> <li>• Permanently calculating the current train position based on odometry and passed balise group information.</li> <li>• Providing the last recently passed linked balise group as the LRBG.</li> <li>• Providing additional position attribute information.</li> <li>• Deleting stored balise groups, when appropriate.</li> <li>• Detecting linking consistency errors.</li> <li>• Determining, if linking is used on board.</li> </ul> <p>The calculation algorithms for locations and positions are implemented as specified in <a href="https://github.com/openETCS/SRS-Analysis/blob/master/System%20Analysis/WorkingRepository/Group4/SUBSET_26_3-6/DetermineTrainLocationProcedures.pdf">https://github.com/openETCS/SRS-Analysis/blob/master/System%20Analysis/WorkingRepository/Group4/SUBSET_26_3-6/DetermineTrainLocationProcedures.pdf</a></p>
Input documents	Subset-026, Chapter 3.6
Safety integrity level	4
Time constraints	All events at the calculateTrainPosion inputs must be applied strictly in the correct chronological order.
API requirements	The currentOdometry input as well as the odometry stamps within msgFromTrack must be fed with odometry values strictly adhering to <a href="https://github.com/openETCS/SRS-Analysis/blob/master/System%20Analysis/WorkingRepository/Group4/SUBSET_26_3-6/DetermineTrainLocationProcedures.pdf">https://github.com/openETCS/SRS-Analysis/blob/master/System%20Analysis/WorkingRepository/Group4/SUBSET_26_3-6/DetermineTrainLocationProcedures.pdf</a> , chapt. 3.

## 412 5.7.2 Interface

413 An overview of the interface of component calculateTrainPosition is shown in Figure ???. The  
 414 inputs and outputs are described in detail in Section 5.7.2.1 respectively 5.7.2.2. Subcomponents  
 415 are described in Section 5.7.3.

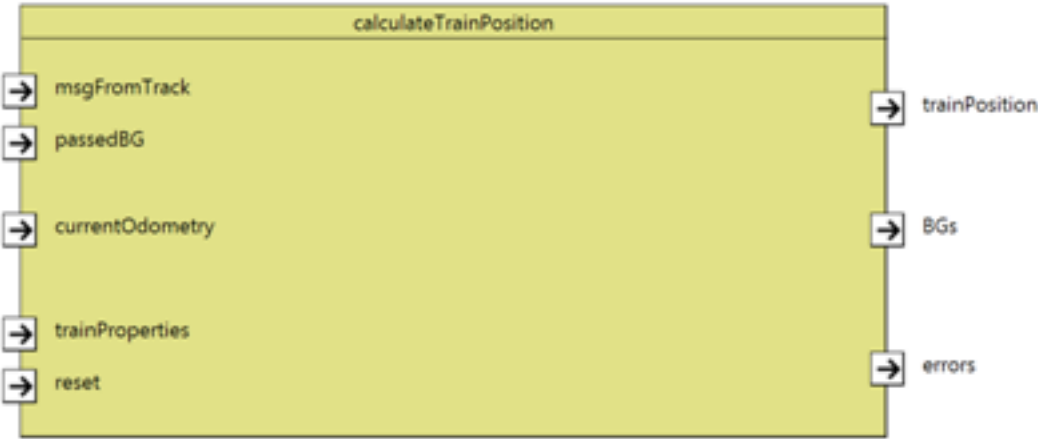


Figure 13. calculateTrainPosition SysML diagram

416 **5.7.2.1 Inputs**

417 **5.7.2.1.1 currentOdometry**

Input name	currentOdometry
Description	currentOdometry is the actual odometry information as known by the whole EVC model and provided by the models external interface.
Source	External model interface input
Type	Obu_BasicTypes_Pkg::odometry_T

Valid range of values	<p>Obu_BasicTypes_Pkg::odometry_T is a complex data type. Values are given for each element. Format is: Type Name: range / list of values.</p> <ul style="list-style-type: none"> <li>• bool valid: [true   false]. Must be permanently set to "true".</li> <li>• timestamp: (0 - 2147483647). Current time in ms, must be monotonically increasing.</li> <li>• odo: Obu_BasicTypes_Pkg::OdometryLocations_T: current odometry log values with uncertainties; must behave according to <a href="https://github.com/openETCS/SRS-Analysis/blob/master/System%20Analysis/WorkingRepository/Group4/SUBSET_26_3-6/DetermineTrainLocationProcedures.pdf">https://github.com/openETCS/SRS-Analysis/blob/master/System%20Analysis/WorkingRepository/Group4/SUBSET_26_3-6/DetermineTrainLocationProcedures.pdf</a> [[ 3.1 ]]. Members of OdometryLocations_T are: <ul style="list-style-type: none"> <li>– o_nominal: L_internal_Type: nominal value in cm.</li> <li>– o_min: L_internal_Type: min. distance = o_min2 - o_min1</li> <li>– o_max: L_internal_Type: max distance = o_max2 - o_max1</li> </ul> </li> <li>• speed: Obu_BasicTypes_Pkg::OdometrySpeeds_T: not used by calculateTrainPosition</li> <li>• acceleration: Obu_BasicTypes_Pkg::A_internal_Type: not used by calculateTrainPosition</li> <li>• motionState: [noMotion   Motion]</li> <li>• motionDirection: Obu_BasicTypes_Pkg::odoMotionDirection_T [ unknownDirection   cabAFirst   cabBFirst ]</li> </ul> <p><i>calculateTrainPosition requires consistent value sets of currentOdometry. calculateTrainPosition itself does not check.</i></p>
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	Enumerated values out of range prohibit code generation. In all other cases, calculateTrainPosition does not have the knowledge for out-of-range checks.
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Leads to misbehaviour.

#### 418 5.7.2.1.2 msgFromTrack

Input name	msgFromTrack
Description	With msgFromTrack calculateTrainPosition receives datagrams from balise groups and RBC.

Source	Manage_TrackSideInformation_Integration_Pkg:: Manage_TrackSideInformation_Integration/
Type	Common_Types_Pkg::ReceivedMessage_T
Valid range of values	<p>Common_Types_Pkg::ReceivedMessage_T is a complex data type. Values are given for each element. Format is: Type Name: range / list of values.</p> <ul style="list-style-type: none"> <li>• bool valid: [true   false]. "true" flags a datagram as received and to be evaluated by calculateTrainPosition. Must be set for exactly 1 clock for each received datagram and stay unset otherwise.</li> <li>• source: Common_Types_Pkg::MsgSource_T: Designates the source of the datagram: ( msrc_undefined   msrc_Euroradio   msrc_Eurobalise   msrc_RadioInfillUnit   msrc_OBU )</li> <li>• radioMetaData: Common_Types_Pkg::radioMetaData_T: not used by calculateTrainPosition.</li> <li>• BG_Common_Header: BG_Types_Pkg::BG_Header_T: Header information received from balise groups, refer to Manage_TrackSideInformation_Integration_Pkg:: Manage_TrackSideInformation_Integration</li> <li>• Radio_Common_Header: Radio_Types_Pkg::Radio_TrackTrain_Header_T: Header information received from RBC via radio, refer to Manage_TrackSideInformation_Integration_Pkg:: Manage_TrackSideInformation_Integration</li> <li>• packets: Common_Types_Pkg::CompressedPackets_T: datagram packets, refer to Manage_TrackSideInformation_Integration_Pkg:: Manage_TrackSideInformation_Integration. calculates-TrainPosition extracts packet 5 (linking information), if available.</li> <li>• sendingRBC: Common_Types_Pkg::RBC_Id_T: designates the origin RBC and the mobile modem channel used onboard, if received via radio. Refer to Manage_TrackSideInformation_Integration_Pkg:: Manage_TrackSideInformation_Integration for more detailed information.</li> </ul> <p><i>calculateTrainPosition expects the received information to be consistent and validated before applied to. It does not check, if the information is appropriate due to current EVC mode, level, train or balise orientation. Received balise group or linking information already known by calculateTrainPosition overrides former data. All messages must be applied in the correct chronological order</i></p>

Behaviour when value is at boundary n/a

Behaviour for values out of valid range Enumerated values out of range prohibit code generation. In all other cases, calculateTrainPosition does not have the knowledge for out-of-range checks.

Behaviour when value is erroneous, absent or unwanted (i.e. spurious) Causes misbehaviour.

#### 419 5.7.2.1.3 trainProperties

Input name	trainProperties
Description	Supplies calculateTrainPosition with train specific properties required for position calculation.
Source	EVC_Support_Pkg::maintainTrainProperties
Type	TrainPosition_Types_Pck::trainProperties_T
Valid range of values	<p>TrainPosition_Types_Pck::trainProperties_T is a complex data type. Values are given for each element. Format is: Type Name: range / list of values.</p> <ul style="list-style-type: none"> <li>• nid_engine:: NID_ENGINE as defined by subset 026-7.</li> <li>• nid_operational: NID_OPERATIONAL as defined by subset 026-7.</li> <li>• l_train: L_TRAIN as defined by subset 026-7.</li> <li>• d_baliseAntenna_2_frontend: Obu_BasicTypes_Pkg::LocWithInAcc_T: Distance from the trains balise antenna to the trains front end, in cm with uncertainties.</li> <li>• d_frontend_2_rearend: Obu_BasicTypes_Pkg::LocWithInAcc_T: Distance from the trains Distance from the trains front end to rear end, in cm with uncertainties.</li> <li>• locationAccuracy_DefaultValue: Obu_BasicTypes_Pkg::LocWithInAcc_T: Default location accuracy of balise groups (subset 026, 3.6.4.3.2), in cm with uncertainties.</li> <li>• centerDetectionAcc_DefaultValue: Obu_BasicTypes_Pkg::LocWithInAcc_T: Default accuracy of balise groups detection of the BTM, in cm with uncertainties. Will be applied, if centerDetectionInaccuracy from BTM is not available, especially for announced and not yet passed BGs.</li> </ul>

*calculateTrainPosition expects this information to be consistent and validated before applied to.*



Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	Enumerated values out of range prohibit code generation. In all other cases, calculateTrainPosition does not have the knowledge for out-of-range checks.
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Causes misbehaviour.

#### 420 5.7.2.1.4 passedBG

Input name	passedBG
Description	Deprecated alternative input to msgFromTrack. Must not be used any more and is subject to be removed in subsequent releases.

#### 421 5.7.2.1.5 reset

Input name	reset
Description	Resets and keeps calculateTrainPosition at its initial state and deletes all internally stored data.
Source	To whom it may concern/
Type	bool
Valid range of values	[ false   true ]
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	Enumerated values out of range prohibit code generation.
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Causes misbehaviour.

### 422 5.7.2.2 Outputs

#### 423 5.7.2.2.1 trainPosition

Output name	trainPosition
-------------	---------------

Description	Provides the current train position and LRBG with its attributes. All distance and location computations of the OBU must be based on this information.
Destination	Any drain component which needs the current train position or LRBG.
Type	TrainPosition_Types_Pck::trainPosition_T

Valid range of values	<p>TrainPosition_Types_Pck::trainPosition_T is a complex data type. Values are given for each element. Format is: Type Name: range / list of values.</p> <ul style="list-style-type: none"> <li>• valid: bool: [true   false]. Always true, except for exceptional circumstances.</li> <li>• timestamp: Obu_BasicTypes_Pkg::T_internal_Type: latest time in ms.</li> <li>• trainPositionIsUnknown: bool: true, if the train position is evaluated as "unknown" (refer to subset-026, 3.6.3.1.3.1).</li> <li>• noCoordinateSystemHasBeenAssigned: bool: refer to subset 026, 3.4.2, 3.6.3.1.4.</li> <li>• trainPosition: Obu_BasicTypes_Pkg::LocWithInAcc_T: The calculated train position with uncertainties</li> <li>• estimatedFrontEndPosition: Obu_BasicTypes_Pkg::Location_T: Train front end position in cm.</li> <li>• minSafeFrontEndPosition: Obu_BasicTypes_Pkg::Location_T: Train front end position in cm.</li> <li>• maxSafeFrontEndPosition: Obu_BasicTypes_Pkg::Location_T: Train front end position in cm.</li> <li>• LRBG: TrainPosition_Types_Pck::positionedBG_T: the current LRBG.</li> <li>• prvLRBG: TrainPosition_Types_Pck::positionedBG_T: the balise group passed previously to LRBG. For type definition, see below.</li> <li>• nominalOrReverseToLRBG: Q_DLRBG: Orientation of the train in relation to the direction of the LRBG, see subset 026-7.</li> <li>• trainOrientationToLRBG: Q_DIRLRBG: Orientation of the train in relation to the direction of the LRBG, see subset 026-7.</li> <li>• trainRunningDirectionToLRBG: Q_DIRTRAIN: Direction of train movement in relation to the LRBG orientation, see subset 026-7.</li> <li>• linkingIsUsedOnboard: bool: Designates, if at least one announced linked BG is ahead.</li> </ul> <p><i>calculateTrainPosition provides the train position to whom it concerns and recalculates it in every clock cycle.</i></p>
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a

Behaviour when value is erroneous, absent or unwanted n/a

#### 424 5.7.2.2.2 BGs

Output name	BGs
Description	A list of all linked and unlinked balise groups - known to calculate-TrainPosition - in the order they are arranged on the track.
Destination	Any subsequent component which needs the current collection of balises groups.
Type	array of TrainPosition_Types_Pck::positionedBG_T
Valid range of values	<p>TrainPosition_Types_Pck::positionedBG_T is a complex data type. Values are given for each array element. Format is: Type Name: range / list of values.</p> <ul style="list-style-type: none"> <li>• valid: bool: [true   false]. "true" for every existing balise group.</li> <li>• nid_c: NID_C: refer to subset 026-7.</li> <li>• nid_bg: NID_BG: refer to subset 026-7.</li> <li>• q_link: Q_LINK: refer to subset 026-7.</li> <li>• location: Obu_BasicTypes_Pkg::LocWithInAcc_T: The best known location (with inaccuracies) calculated from linking and from passing information.</li> <li>• seqNoOnTrack: int: Sequence number, specifies the order of the BG passed or expected to be passed.</li> <li>• infoFromLinking: TrainPosition_Types_Pck::infoFromLinking_T: Describes a linked BG as announced from the linking BG. Mainly, this information is taken from the linking packet.</li> <li>• infoFromPassing: BG_Types_Pkg::passedBG_T: If the balise group has been passed already, this is the relevant information received from the BG.</li> </ul> <p><i>calculateTrainPosition provides the list of balise groups to whom it concerns.</i></p>
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a

Behaviour when value is erroneous, absent or unwanted n/a

#### 425 5.7.2.2.3 errors

Output name	errors
Description	Provides a collection of error flags, raised by calculateTrainPosition.
Destination	Error handlers and components which need to know of common and linking consistency errors.
Type	TrainPosition_Types_Pck::positionErrors_T
Valid range of values	<p>TrainPosition_Types_Pck::positionErrors_T is a complex data type. Values are given for each array element. Format is: Type Name: range / list of values.</p> <ul style="list-style-type: none"> <li>• outOfMemSpace: bool: Memory overrun: a passed or announced BG could not be stored.</li> <li>• passedBG_foundNotWhereExpected: bool: The currently passed linked BG location does not match its expectation window.</li> <li>• positionCalculation_inconsistent: A consistency problem arose during position calculation.</li> <li>• linkedBGMissed: bool: The expectation window for an announced BG was passed without detecting the BG.</li> <li>• BGpassedInUnexpectedDirection: bool: The BG was passed in a different orientation than announced via linking.</li> <li>• BG_LinkingConsistencyError: bool: Linking consistency error (ref. subset 026, 3.16.2.3).</li> <li>• twoConsecutiveLinkedBGs_missed: bool: 2 consecutive linked balise groups announced by linking are not detected and the end of the expectation window of the second balise group has been passed (subset 026, 3.16.2.7.1).</li> <li>• doubleRepositioningError: bool: Double repositioning error (3.16.2.7.2).</li> <li>• bg: TrainPosition_Types_Pck::positionedBG_T: The corresponding balise group in the case of an error.</li> </ul>

Behaviour when value is at boundary n/a

Behaviour for values out of valid range n/a

---

Behaviour when value is erroneous, absent or unwanted	n/a
---	-----

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### 426 5.7.3 Subcomponents

#### 427 5.7.3.1 msg\_2\_passedBG

##### 428 5.7.3.1.1 Component Requirements

Component name	msg_2_passedBG
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition</a>
SCADE designer	Uwe Steinke, Siemens AG
Description	Converts msgFromTrack from ReceivedMessage_T to passedBG_T and determines, if the message was received from a just overpassed balise group or if it only announces balise groups via radio.
Input documents	n/a
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

##### 429 5.7.3.1.2 Interface

430 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
431 above) respectively the SCADE generated documentation.

#### 432 5.7.3.2 calculateBGLocations

##### 433 5.7.3.2.1 Component Requirements

Component name	calculateBGLocations
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition</a>
SCADE designer	Uwe Steinke, Siemens AG

Description	<p>Calculates the location of a just overpassed balise group related to the list of all so far known balise groups. If the just overpassed balise group has been announced via linking (packet 5) previously, it's location is adjusted to the best-of combination of linking and odometry information. If the just overpassed BG is a linked balise group, the locations of all known balise groups ahead and astern are recalculated with the just overpassed balise group as the one with minimized location uncertainties.</p> <p>If the overpassed balise group announces balise groups ahead via linking (packet 5), these balise groups are added to the list of known balise groups.</p>
Input documents	<p>Subset-026, Chapter 3.6</p> <p>Subset-026, Chapter 3.6.4</p>
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 434 5.7.3.2.2 Interface

435 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
436 above) respectively the SCADE generated documentation.

#### 437 5.7.3.3 delDispensableBGs

##### 438 5.7.3.3.1 Component Requirements

Component name	delDispensableBGs
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition</a>
SCADE designer	Uwe Steinke, Siemens AG
Description	Deletes balise groups not needed any more from the list of known balise groups
Input documents	Subset-026, Chapter 3.6.2.2.2 c)
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 439 5.7.3.3.2 Interface

440 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
441 above) respectively the SCADE generated documentation.

#### 442 **5.7.3.4 addAnnouncedBGs**

##### 443 **5.7.3.4.1 Component Requirements**

Component name	addAnnouncedBGs
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition</a>
SCADE designer	Uwe Steinke, Siemens AG
Description	When balise groups ahead are announced via radio, addAnnounced-BGs adds these balise groups to the list of known balises groups and calculates their locations.
Input documents	Subset-026, Chapter 3.6
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

##### 444 **5.7.3.4.2 Interface**

445 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
446 above) respectively the SCADE generated documentation.

#### 447 **5.7.3.5 calculateTrainpositionInfo**

##### 448 **5.7.3.5.1 Component Requirements**

Component name	calculateTrainpositionInfo
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition</a>
SCADE designer	Uwe Steinke, Siemens AG
Description	Calculates the current train position based on the odometry and the list of known balise groups. Provides the last passed linked balised group and the linked balise group passed previously to the last passed linked balise group. Provides the last passed unlinked balise group. Determines, if linking is used on board.
Input documents	Subset-026, Chapter 3.6
Safety integrity level	4



Time constraints	n/a
API requirements	n/a

#### 449 5.7.3.5.2 Interface

450 For an overview of the interface of this internal component we refer to the SCADE model  
451 (c.f. link above) respectively the SCADE generated documentation.

#### 452 5.7.3.6 calculateTrainPositionAttributes

##### 453 5.7.3.6.1 Component Requirements

Component name	calculateTrainPositionAttributes
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition</a>
SCADE designer	Uwe Steinke, Siemens AG
Description	Enhances the current train position information with additional attributes as if the train position is unknown, if no coordinate system has been assigned, the trains front end position with attributes, determines the LRBG and the previous LRBG, if the train front end is located nominal or reverse to the LRBG, the train orientation and the train movement direction.
Input documents	Subset-026, Chapter 3.6
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 454 5.7.3.6.2 Interface

455 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
456 above) respectively the SCADE generated documentation.

#### 457 5.7.3.7 linkedBG\_missed

##### 458 5.7.3.7.1 Component Requirements

Component name	linkedBG_missed
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition</a>
SCADE designer	Uwe Steinke, Siemens AG

Description	Detects, when the range of a linked BG (where it is expected to be found) is left and the BG has not been passed yet. Steadily observes the current train position and detects, when the train leaves the expectation window of any BG. When this happens, checks whether it is a linked BG and has been marked as passed. If not, it was not found within its expectation window.
Input documents	Subset-026, Chapter 3.6 Subset-026, Chapter 3.16.2.3
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 459 5.7.3.7.2 Interface

460 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
461 above) respectively the SCADE generated documentation.

#### 462 5.7.3.8 twoconsecutiveLinkedBGs\_missed

##### 463 5.7.3.8.1 Component Requirements

Component name	twoconsecutiveLinkedBGs_missed
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/TrainPosition/CalculateTrainPosition</a>
SCADE designer	Uwe Steinke, Siemens AG
Description	Detects, if 2 subsequent linked BGs are missed. The criterium is fulfilled, when 2 consecutive linked balise groups announced by linking have not been detected and the end of the expectation window of the second balise group has been passed.
Input documents	Subset-026, Chapter 3.6 Subset-026, Chapter 3.16.2.3
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 464 5.7.3.8.2 Interface

465 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
466 above) respectively the SCADE generated documentation.

## 5.8<sup>467</sup> F2.7: SpeedSupervision\_Integration

### 468 5.8.1 Component Requirements

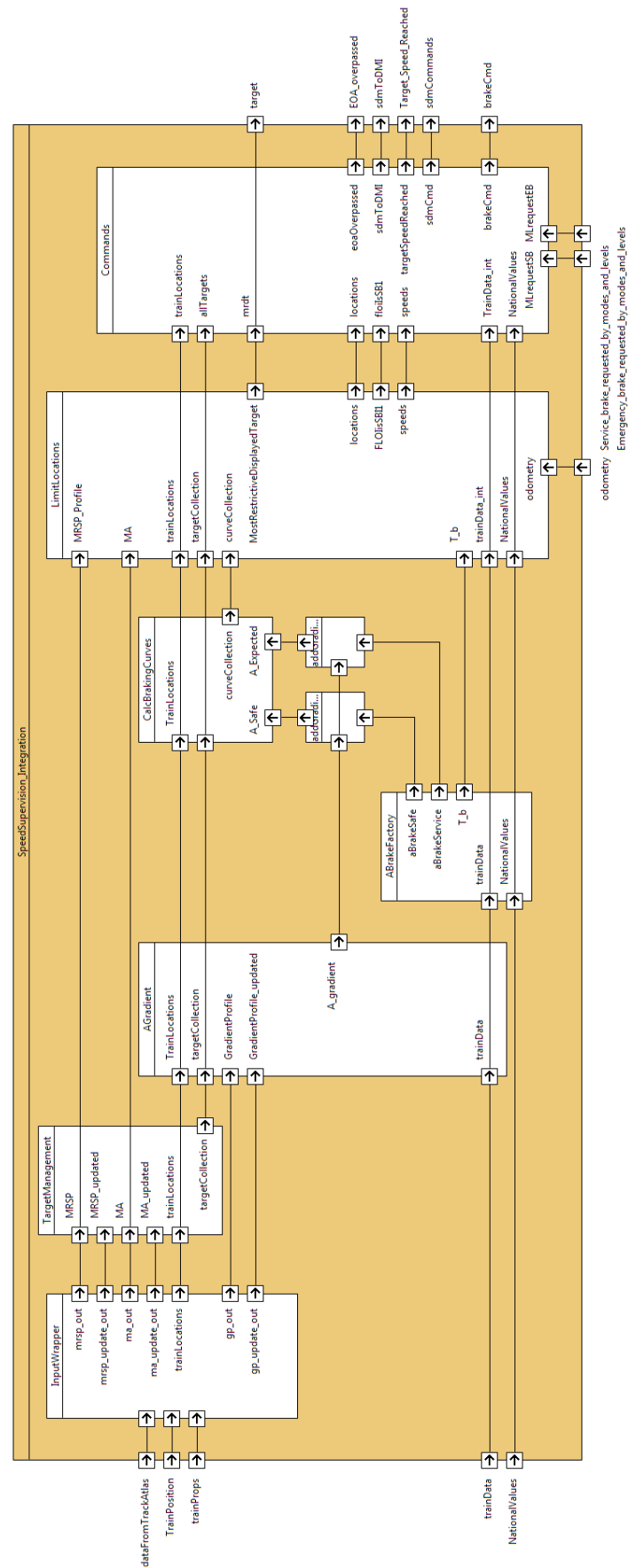
Component name	SpeedSupervision_Integration
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision</a>
SCADE designer	Benjamin Beichler, University of Rostock Christian Stahl, TWT Thorsten Schulz, University of Rostock
Description	<p>The task of SDM is to monitor the speed of the train and the train location and as such to ensure that the speed remains within the given speed and distance limits. This block is based on [1, Chapt. 3.13]. The integration node “SpeedSupervision_Integration” takes as input (1) movement related information such as train speed, train position and acceleration, (2) train related information such as brake information and train length, and (3) track related information such as speed and distance limits and national values.</p> <p>Based on this information a speed profile is calculated. Speed restrictions create target speeds (targets) that have to be followed. For each such target braking curves are generated to supervise at which location of the track the train must apply the brake. In case of no target restrictions the train may accelerate to the supervised maximum speed of the speed profile. These calculations lead to commands being sent to the driver and the brake system.</p> <p>The functionality is modeled using eight subcomponents, as shown in Figure 14, which are explained in Section 5.8.3.</p> <p>The current status of the analysis of “SDM” and a functional breakdown can be found in a separate document, SpeedSupervision_analysis.pdf.</p>
Input documents	Subset-026, Chapter 3.13: Speed and distance monitoring
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

### 469 5.8.2 Interface

470 An overview of the interface of component SpeedSupervision\_integration is shown in Figure 14.  
 471 The inputs and outputs are described in detail in Section 5.8.2.1 respectively 5.8.2.2. Sub  
 472 components are described in Section 5.8.3.

#### 473 5.8.2.1 Inputs

##### 474 5.8.2.1.1 National Values



**Figure 14. Structure of component SpeedSupervision\_Integration.**

Input name	NationalValues
Description	This input is packet 3 or 203 of [1, Chapt. 8], describing the national values.
Source	TrackAtlas; current release, hard wired constant: cP3NationalValuesUtrechtAmsterdam
Type	P3_NationalValues_T
Valid range of values	P3_NationalValues_T is a complex data type, valid ranges are specified in SRS Subset-026-7, no further checks are done here.
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Not checked; node must not be called without reasonable National Value.

#### 475 5.8.2.1.2 Train Position

Input name	TrainPosition
Description	This input is the current train position.
Source	calculateTrainPosition
Type	trainPosition_T
Valid range of values	<p>trainPosition_T is a complex data type. Value valid must not be false for proper function and it may not be properly checked in current release. Furthermore, reversing (decreasing positions, reverse flag set) is currently NOT supported and leads to undefined behaviour. No brake will be thrown in this occasion.</p> <div style="background-color: #90EE90; border: 1px solid black; border-radius: 10px; padding: 2px 10px; display: inline-block;">To be completed</div>
Behaviour when value is at boundary	Not checked, may overflow.
Behaviour for values out of valid range	Currently not checked.
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Not checked; node must not be called without reasonable position data. Valid flag is not checked (bug), as SDM has not yet implemented exception handling on unacceptable input data.

476 **5.8.2.1.3 Odometry**

Input name	odometry
Description	This input is the odometry data.
Source	API_Odometry
Type	odometry_T
Valid range of values	complex data type used fields are: - acceleration: Obu_BasicTypes_Pkg::A_internal_Type. No valid range defined, neither checked. - motionState: [noMotion   Motion] (enum type) - motionDirection: is NOT evaluated currently which leads to erroneous behaviour when driving anti-nominal direction.
Behaviour when value is at boundary	Possible overflow not evaluated.
Behaviour for values out of valid range	Not checked.
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Not handled, valid data is expected for valid function. Valid flag is not checked (bug), as SDM has not yet implemented exception handling on unacceptable input data.

477 **5.8.2.1.4 Train Properties**

Input name	trainProps
Description	This input is a set of train related properties.
Source	maintainTrainProperties
Type	trainProperties_T
Valid range of values	trainProperties_T is a complex type but referenced only d_baliseAntenna_2_frontend.nominal: Obu_BasicTypes_Pkg::L_internal_Type No valid range defined, neither checked.
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Value is only evaluated in Level 1. Low values (e.g. invalid-default 0) will lead to early trip, brake and alike. Larger values will lead to late braking, possibly numeric overflow.

478 **5.8.2.1.5 Train Data**

Input name	trainData
Description	This input is a set of train related inputs from the TIU.
Source	manageTrainData
Type	trainData_T
Valid range of values	trainData_T is a complex type. No valid range defined, neither checked. The source is trusted.
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Must be valid for SDM to function. Valid flag is not checked (bug), as SDM has not yet implemented exception handling on unacceptable input data.

479 **5.8.2.1.6 Track Data**

Input name	dataFromTrackAtlas
Description	This input is a set of track related input data, containing the MRSP, the Gradient Profile and the Movement Authority. And its associated update flags to optimize data handling.
Source	TrackAtlas
Type	DataForSupervision_nextGen_t
Valid range of values	<p>DataForSupervision_nextGen_t is a wrapper the three mentioned complex types. The fresh-flags are seen as an optimization hint. From specification, all three containers must contain valid data for SDM to function. Ranges or sanity are not checked. The source is trusted.</p> <p><b>MA</b> Must always contain a valid Movement Authority, else the brake is commanded.</p> <p><b>GradientProfile</b> As per SRS, this must always contain a valid description up to the end of the MA.</p> <p><b>MRSP</b> Must at least a profile for the train's maximum speed, if no other restriction is known.</p>
Behaviour when value is at boundary	n/a

Behaviour for values out of valid range	If the MA is not valid the brake should be commanded.
---	---

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Absence of minimal MRSP is not detected but trusted. Validity of MA is not checked up front.
---	--

## 480 5.8.2.2 Outputs

### 481 5.8.2.2.1 sdmToDMI

Output name	sdmToDMI
Description	This output contains information about different speeds and positions and the current supervision status. This information shall be displayed to the driver.
Destination	<ul style="list-style-type: none"> <li>TrackAtlas (5.5.2.1)</li> <li>manageDMI_output (18)</li> <li>ROOT_integration</li> </ul>
Type	speedSupervisionForDMI_T (complex)
Valid range of values	<p>speedSupervisionForDMI_T is a complex data type. Values are given for each element. Format is: Type Name: range/list of value.</p> <ul style="list-style-type: none"> <li>bool valid: [true, false] true, if internal state of speed monitoring is defined [CSM, TSM, RSM]; false, if it is undefined</li> <li>V_internal_Type targetSpeed, permittedSpeed, releaseSpeed, interventionSpeed: 0 or above, not internally limited; set to cDMIUnknownSpeed (-1) if not defined</li> <li>L_internal_Type location_brake_curve_starting_point, location-BrakeTarget, distanceIndicationPoint: calculated locations</li> <li>M_SupervisionDisplay_T supervisionDisplay: [supDis_normal, supDis_indication, supDis_overspeed, supDis_warning, supDis_intervention]</li> <li>M_SUPERVISION_STATUS sup_status: [CSM, TSM, RSM, unknown], PIM is not referenced</li> </ul>
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	Location values may not be meaningful in some situations. This is not directly linked to the specific items but maybe accessible from further context such as supervisionDisplay and sup_status.



Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Valid can be false in case of initialization. All values must be disregarded then.
---	--

#### 482 5.8.2.2.2 target

Output name	target
Description	This output is the most restrictive displayed target (MRDT).
Destination	n/a, null-sink
Type	Target_T (complex)
Valid range of values	<p>Target_T is a complex data type. Values are given for each element. Format is: Type Name: range/list of value.</p> <ul style="list-style-type: none"> <li>• bool valid: [true, false] true, if targetType is other than invalid</li> <li>• V_internal_Type speed: permitted speed from target location</li> <li>• L_internal_Type distance: location of brake target</li> <li>• TargetType_T targetType: <ul style="list-style-type: none"> <li><b>EoA</b> End of Authority (speed must be = 0)</li> <li><b>SvL</b> Supervised Location (speed must be = 0)</li> <li><b>MRSP</b> Speed Profile, Speed restriction (speed &gt; 0)</li> <li><b>LoA</b> Limit of Authority (speed &gt; 0)</li> <li><b>invalid</b> currently no brake target known (e.g. after trip)</li> </ul> </li> </ul>
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	Valid target values of speed and distance are not artificially limited to a sane range and are passed through data from track input.
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	.valid may be false if no target is supervised or known, other values of this output must be ignored then.

#### 483 5.8.2.2.3 sdmCommands

Output name	sdmCommands
Description	This output gives some intermediate results of operator SDM_Commands. It is currently used for test purposes only.
Destination	n/a, null-sink

Type	SDM_Commands_T (complex)
Valid range of values	Containing values are either boolean command-trigger flags, the internal state of the SDM_commands state-machine or speed/distance types with guarding bool valid flag. For in-depth description see generated documentation.
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	<ul style="list-style-type: none"> <li>• Bool are always in range.</li> <li>• The internal state SupervisionStatus_T is Undefined_Supervision at initialization and renders the output sdmToDMI's valid flag to false.</li> <li>• Speeds estimatedSpeed, permittedSpeed, releaseSpeed, mrdt-Speed, sbiSpeed and distance targetDistance must be ignored and contain invalid values if the corresponding valid-flag is false. Valid-marked outputs are not artificially limited to a sane range and rely on correctly specified algorithms.</li> </ul>
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	Overall .valid is always set, individual speeds have their corresponding valid flag. Values may not have a valid output depending on the situation.

#### 484 5.8.2.2.4 brakeCmd

Output name	brakeCmd
Description	This output is the brake command, indicating whether performing the service brake and/or the emergency brake have been commanded.
Destination	<ul style="list-style-type: none"> <li>• TIU_OutputIntegration (20)</li> <li>• manageDMI_output (18)</li> <li>• ROOT_integration</li> </ul>
Type	Brake_command_T (complex)

Valid range of values	<p>Brake_command_T is a complex data type. Values are given foreach element. Format is: Type Name: range/list of value</p> <ul style="list-style-type: none"> <li>• bool valid: true (constant)</li> <li>• M_brake_signal_command_T m_servicebrake_cm: <ul style="list-style-type: none"> <li><b>brake_signal_command_not_defined</b> No change of brake state requested, keep last.</li> <li><b>apply_brake</b> service brakes must be applied</li> <li><b>release_brake</b> service brakes must be released</li> </ul> </li> <li>• M_brake_signal_command_T m_emergencybrake_cm: <ul style="list-style-type: none"> <li><b>brake_signal_command_not_defined</b> No change of brake state requested, keep last.</li> <li><b>apply_brake</b> emergency brakes must be applied</li> <li><b>release_brake</b> emergency brakes must be released</li> </ul> </li> </ul> <p>Brake commands are edge triggered and may only be defined in a single cycle.</p>
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	brakeCmd is constantly valid, but may not contain a command change.

#### 485 5.8.2.2.5 EOA\_overpassed

Output name	EOA_overpassed
Description	This output is true if the end of authority has been overpassed and false otherwise. In Level 1 this is compensated by the antenna offset.
Destination	n/a, null-sink in current release
Type	bool
Valid range of values	<p><b>true</b> The train's front end has passed the end of authority</p> <p><b>false</b> The end of authority is ahead of the train.</p>
Behaviour when value is at boundary	n/a

Behaviour for values out of valid range n/a

Behaviour when value is erroneous, absent or unwanted (i.e. spurious) n/a

#### 486 5.8.2.2.6 Target\_Speed\_Reached

Output name	Target_Speed_Reached
Description	This output is true if the current speed is greater than or equal the target speed and false otherwise.
Destination	n/a, null-sink in current release
Type	bool
Valid range of values	<p><b>true</b> The current speed is greater than or equal to the target speed or target is invalid</p> <p><b>false</b> The current speed is less than the target speed</p> <p>Value must be ignored, if output target (5.8.2.2.2) is invalid.</p>
Behaviour when value is at boundary	n/a
Behaviour for values out of valid range	n/a
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	n/a

### 487 5.8.3 Subcomponents

#### 488 5.8.3.1 SDM\_InputWrapper

##### 489 5.8.3.1.1 Component Requirements

Component name	SDM_InputWrapper
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/SpeedSupervision_Integration">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/SpeedSupervision_Integration</a>
SCADE designer	Benjamin Beichler, University of Rostock Thorsten Schulz, University of Rostock

Description	<p>The motivation for this operator is to convert all inputs of SDM that contain information about length, speed, distance, and acceleration defined as integer into <code>real</code> to allow automatically the highest precision in the calculations by the meaning of floating point operations. In addition, to ease the modeling, inside block “Speed Supervision” only units meters (<math>[m]</math>), seconds (<math>[s]</math>), meters per second (<math>[\frac{m}{s}]</math>), and meters per square second (<math>[\frac{m}{s^2}]</math>) are used. This operator forwards input messages, takes data from complex data types or transforms inputs messages into an internal type thereby converting int to real.</p>
Input documents	Subset-026, Chapter 3.13, (not specific, helper function)
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 490 5.8.3.1.2 Interface

491 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
 492 above) respectively the SCADE generated documentation.

#### 493 5.8.3.2 TargetManagement

##### 494 5.8.3.2.1 Component Requirements

Component name	TargetManagement
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/TargetManagement">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/TargetManagement</a>
SCADE designer	Benjamin Beichler, University of Rostock Thorsten Schulz, University of Rostock

**Description**

This operator calculates/updates the list of targets to be supervised by SDM. Taking the current movement authority, the most restrictive speed profile and the current maximum safe front end position as an input, the operator outputs a list of MRSP-Targets and a Limit-of-Authority-Target (LoA) or, if an End of Authority is known, the End-of-Authority-Target (EoA) and the Supervised Location (SvL). Since LoA and SvL are mutually exclusive but both result in a trip-target, they use the same flow.

#### **Derivation of Targets from Movement Authority**

The *Movement Authority* creates three types of targets:

**Limit of Authority (LoA)** if the End of Authority is not yet known to the RBC and is accompanied by a speed limit for the given location.

**End Of Authority (EoA)** requires the train to stop and creates a Service Brake Target

**Supervised Location (SvL)** is derived from the EoA but results in an emergency brake target and on passing in a trip. The SvL may be offset from the EoA to the Overlap (OL) or the Dangerpoint (DP).

#### **Derivation of Targets from MRSP**

According to [1, Chapt. 3.13.8.2], every speed decrease of the MRSP is used to derive a target. Therefore in every cycle in which the MRSP is updated, the operator iterates through the entire MRSP searching for all MRSP targets. For this purpose, every element of the MRSP is compared with its successor.

#### **Update of Targets**

In every cycle the operator monitors whether all targets are already passed. To this end, it iterates over the list of targets comparing the current front end position with the target's location.

Input documents	Subset-026, Chapter 3.13.8.2: Determination of the supervised targets
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

### 495 **5.8.3.2.2 Interface**

496 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
497 above) respectively the SCADE generated documentation.

### 498 **5.8.3.3 AGradient**

#### 499 **5.8.3.3.1 Component Requirements**

Component name	AGradient
----------------	-----------

Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervisionSDM_GradientAcceleration">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervisionSDM_GradientAcceleration</a>
SCADE designer	Benjamin Beichler, University of Rostock
Description	This operator translates the incoming gradient profile from track data to acceleration values under consideration of train length compensation.
Input documents	Subset-026, Chapter 3.13.4: Acceleration / Deceleration due to gradient
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 500 5.8.3.3.2 Interface

501 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
502 above) respectively the SCADE generated documentation.

#### 503 5.8.3.4 ABrakeFactory

##### 504 5.8.3.4.1 Component Requirements

Component name	ABrakeFactory
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/SDM_Models">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/SDM_Models</a>
SCADE designer	Thorsten Schulz, University of Rostock
Description	This operator implements the braking models. At this stage only the lamda trains (conversion) model is implemented. The output of the conversion model are a location independent, but highly National Values dependent, braking curves. One for the service brake and one for the emergency brake. As a side product, the model related brake build-up times are also generated.
Input documents	Subset-026, Chapter 3.13.2.2.3 Braking Models, Chapter 3.13.2.2.4,5 Brake Position, Percentage, Chapter 3.13.2.3.7 National Values for SDM, Chapter 3.13.3 Conversion Models, 3.13.6 Calculation of the deceleration and brake build-up times
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 505 **5.8.3.4.2 Interface**

506 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
507 above) respectively the SCADE generated documentation.

#### 508 **5.8.3.5 addGradient**

##### 509 **5.8.3.5.1 Component Requirements**

Component name	addGradient
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/SDM_Models">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/SDM_Models</a>
SCADE designer	Thorsten Schulz, University of Rostock
Description	This operator is part of SDM_Models and is merging the gradient acceleration into the curve brake model curve, producing a location dependent braking curve. It twice, for the emergency curve and the service braking curve respectively
Input documents	Subset-026, Chapter 3.13.6.2.1.3 and 3.13.6.4.3 Calculation of the deceleration and brake build-up times
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 510 **5.8.3.5.2 Interface**

511 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
512 above) respectively the SCADE generated documentation.

#### 513 **5.8.3.6 CalcBrakingCurves\_Integration**

##### 514 **5.8.3.6.1 Component Requirements**

Component name	CalcBrakingCurves_Integration
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/CalcBrakingCurves">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/CalcBrakingCurves</a>
SCADE designer	Benjamin Beichler, University of Rostock



Description	For each type of target a certain braking curve has to be calculated. This curve enables proactive monitoring of the train's speed. A reverse lookup on this braking curve indicates, where the train has to start braking given the current speed. The braking curve does not depend on the actual train status. As a consequence the braking curve stays constant over time. As a legitimate simplification the calculation of the braking curve is not extended past the estimated front end position of the train.
Input documents	Subset-026, Chapter 3.13.8.3: Emergency Brake Deceleration curves (EBD) Subset-026, Chapter 3.13.8.4: Service Brake Deceleration curves (SBD) Subset-026, Chapter 3.13.8.5: Guidance curves (GUI)
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 515 **5.8.3.6.2 Interface**

516 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
517 above) respectively the SCADE generated documentation.

#### 518 **5.8.3.7 SDMLimitLocations**

##### 519 **5.8.3.7.1 Component Requirements**

Component name	SDMLimitLocations
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/SDM_TargetLimits">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/SDM_TargetLimits</a>
SCADE designer	Thorsten Schulz, University of Rostock

Description	<p>This operator calculates the various locations and speeds needed to determine the speed and distance monitoring commands. The current implementation of functionality is stateless and requires a complete recalculation each cycle.</p> <p>This operator gathers all necessary input values and computes some frequently used intermediate values in the operators <code>surplusTractionDeltas</code> and <math>v_{bec}</math>. The other input preparation operator is the <code>TargetSelector</code> whose main task is to dissect the list of targets to find the Most Restrictive Target. The accompanying braking curves are extracted and promoted to trailing location calculations. Also the special values of the EOA are exposed.</p> <p>The operator creates the requested values for the commands package. These are in particular the preindication locations for EBD and SBD based targets, the release speed monitoring start locations, the locations for target speed monitoring of the I-, W-, P- and FLOI-curve, the related FLOI speed and the location of the permitted speed supervision limit. Included in the output are also certain flags for the validity of linked values.</p>
Input documents	<p>Subset-026, Chapter 3.13.9: Supervision Limits</p> <p>Subset-026, Chapter 5.3.1.2: <math>f_{41}</math> – accuracy of speed known on-board</p> <p>Subset-026, Chapter 3.13.10: Monitoring Commands as reference for required outputs of this module</p>
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

### 520 5.8.3.7.2 Interface

521 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
 522 above) respectively the SCADE generated documentation.

### 523 5.8.3.8 SDM\_Commands

#### 524 5.8.3.8.1 Component Requirements

Component name	SDM_Commands
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/SDM_Commands">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/SpeedSupervision/SDM_Commands</a>
SCADE designer	Christian Stahl, TWT Thorsten Schulz, University of Rostock

Description	<p>This operator models the speed and distance monitoring commands. More precisely, it triggers the service or emergency brake and outputs the current supervision status of the OBU together with information on speeds and locations to the driver.</p> <p>The OBU can be in any of three types of speed and distance monitoring modes: ceiling speed monitoring, release speed monitoring and target speed monitoring. We use a state machine to model the switching between the three modes: each state models a mode and a transition between two states is enabled if the condition two switch between the two corresponding modes is evaluated to true. In each mode, the OBU can be in up to five different supervision states. The behavior of changing from one status to another is also modeled as a state machine. As a result, the model is a hierarchical state machine.</p>
Input documents	Subset-026, Chapter 3.13.10: Speed and distance monitoring commands
Safety integrity level	4
Time constraints	n/a
API requirements	n/a

#### 525 5.8.3.8.2 Interface

526 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
527 above) respectively the SCADE generated documentation.

### 5.9<sub>528</sub> F2.8: Provide\_Position\_Report

#### 529 5.9.1 Component Requirements

Component name	Provide_Position_Report
Link to SCADE model	<p>???</p> <p>Link has to be provided.</p>
SCADE designer	Christian Stahl, TWT GmbH
Description	<p>The component builds a position report for the RBC, i.e., message 132, and provides it as an output. There are two triggers for sending message 132:</p> <ol style="list-style-type: none"> <li>1. at least one of the triggers of the position report parameters (packet 58) holds or</li> <li>2. one of the events enabling the sending of the report occurs. As the core position report (i.e., packet 0 or 1) is added to other packets, the component also provides in every clock cycle this core position report. At most one of the two packets is valid.</li> </ol>

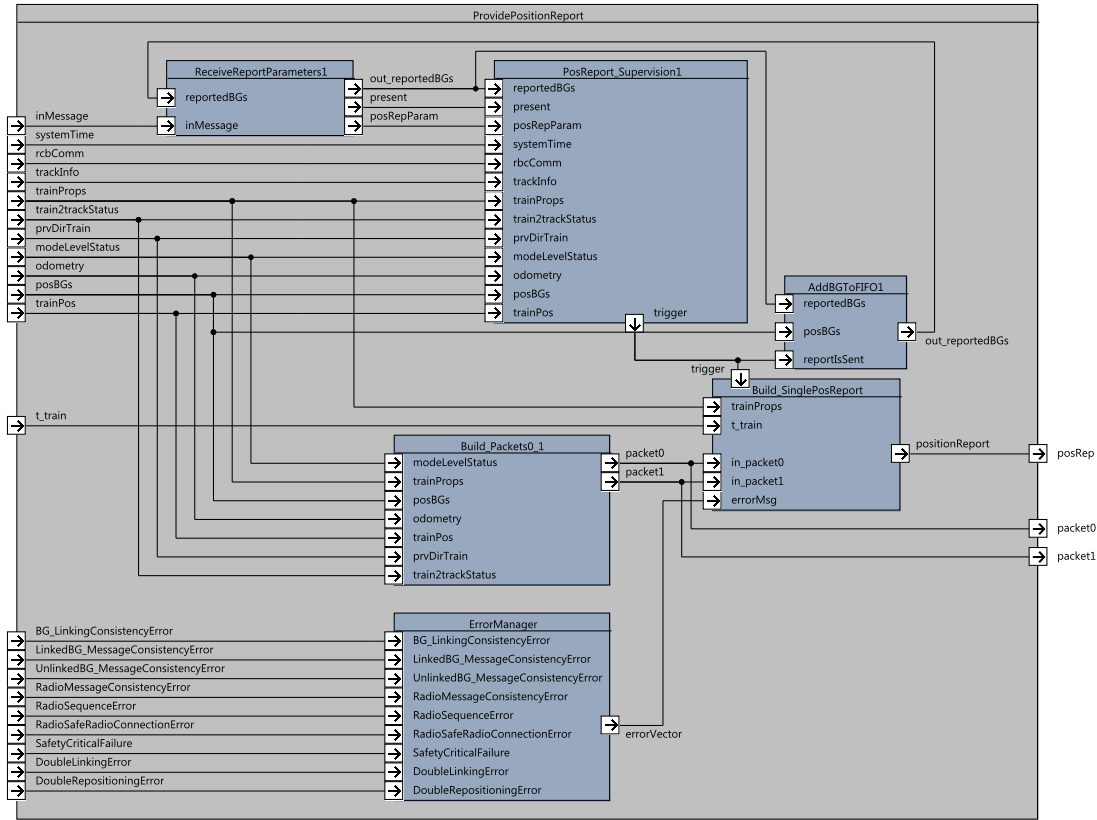


Figure 15. Provide\_Position\_Report component SysML diagram

Input documents	Subset-026, Chapter 3.6.5
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a] To be completed.
API requirements	[If applicable description of API requirements, otherwise n/a] To be completed.

5.9.2 Interface

An overview of the interface of component Provide\_Position\_Report is shown in Figure 15. The inputs and outputs are described in detail in Section 5.9.2.1 respectively 5.9.2.2. Subcomponents are described in Section 5.9.3.

5.9.2.1 Inputs

section has to be completed

5.9.2.1.1 [Input 1 name]

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

537 **5.9.2.1.2 [Input 2 name]**

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

538 **5.9.2.2 Outputs**

539 section has to be completed

540 **5.9.2.2.1 [Output 1 name]**

Output name	[Name of the output]
Description	[Brief description of the output]

Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

#### 541 5.9.2.2.2 [Output 2 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

### 542 5.9.3 Subcomponents

543 section has to be completed

#### 544 5.9.3.1 ReceiveReportParameters

##### 545 5.9.3.1.1 Component Requirements

Component name	ReceiveReportParameters
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Christian Stahl, TWT

Description	The component reads the position report parameters (i.e., packet 58) from the message bus. When a report is received, the BG information provided is used to update the location of respective BG. This BG is being stored in the list of the last 8 BGs.
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

### 546 5.9.3.1.2 Interface

547 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
548 above) respectively the SCADE generated documentation.

### 549 5.9.3.2 PosReport\_Supervision

#### 550 5.9.3.2.1 Component Requirements

Component name	PosReport_Supervision
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Christian Stahl, TWT
Description	The component supervises trigger (i.e., position report parameter) and events that trigger the sending of a position report. If the output is true, then a report has to be sent.
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

### 551 5.9.3.2.2 Interface

552 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
553 above) respectively the SCADE generated documentation.

### 554 5.9.3.3 ErrorManager

#### 555 5.9.3.3.1 Component Requirements

Component name	ErrorManager
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Christian Stahl, TWT
Description	The component takes all nine possible error messages as an input and aggregates them to a vector.
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 556 5.9.3.3.2 Interface

557 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
558 above) respectively the SCADE generated documentation.

#### 559 5.9.3.4 Build\_Packets0\_1

##### 560 5.9.3.4.1 Component Requirements

Component name	Build_Packets0_1
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Christian Stahl, TWT
Description	The component builds packets 0 and 1; at most one of them is valid.
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 561 5.9.3.4.2 Interface

562 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
563 above) respectively the SCADE generated documentation.

#### 564 5.9.3.5 Build\_PosReport



565 **5.9.3.5.1 Component Requirements**

Component name	Build_PosReport
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Christian Stahl, TWT
Description	The component builds nine position report messages—there can be up to nine errors, and for each error an individual report has to be sent.
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

566 **5.9.3.5.2 Interface**

567 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
568 above) respectively the SCADE generated documentation.

569 **5.9.3.6 AddBGToFIFO**570 **5.9.3.6.1 Component Requirements**

Component name	AddBGToFIFO
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Christian Stahl, TWT
Description	The component adds the current reported BG to the list of BGs for which a report has been sent. Adding of this BG is performed according to the FIFO method.
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

571 **5.9.3.6.2 Interface**

572 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
573 above) respectively the SCADE generated documentation.

5.10<sub>4</sub> **F2.9: Manage\_Radio\_Communication and RBC\_Handover**

575 section has to be completed. The level of this component in final architecture has been fixed.

576 **5.10.1 Component Requirements**

Component name	MoRC_HO
Link to SCADE model	???
SCADE designer	Uwe Steinke, Siemens AG
Description	<div>to be checked</div> <p>The management of radio communication MoRC implements the onboard management part of a single communication session with the track, i.e. a single RBC. It controls the establishing, maintaining and termination process of a radio communication session and steers the underlying communication safety layer and the mobile device. Those and the data transfer itself are not part of the function.</p> <p>The kernel function of the MoRC component is <i>managementOfRadioCommunication</i> (figure ??). The implementation is kept close to the prose of Subset-026, chap. 3.5. Since chap. 3.5 rarely refers to terms, variable types, packets and messages of the ETCS language as specified in Subset-026, chap. 7 and 8, <i>managementOfRadioCommunication</i> does neither.</p> <p>To be capable of being integrated with other OBU software components, <i>MoRC</i> had to be wrapped with a transformer between the ETCS and the "chap. 3.5" language. This is the purpose of the main function of <i>MoRC</i>, <i>MoRC_Main</i>.</p>
Input documents	Subset-026, Chapter 4 Subset-026, Chapter 5
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

577 **5.10.2 Interface**

578 An overview of the interface of component Manage\_Radio\_Communication is shown in Figure 16.  
579 The inputs and outputs are described in detail in Section 5.10.2.1 respectively 5.10.2.2. Sub  
580 components are described in Section 5.10.3.

581 **5.10.2.1 Inputs**



Figure 16. Manage\_Radio\_Communication component SysML diagram

582 **5.10.2.1.1 [Input 1 name]**

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at bound-ary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or un- wanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

583 **5.10.2.1.2 [Input 2 name]**

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at bound-ary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or un- wanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

584 **5.10.2.2 Outputs**

Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

#### 586 5.10.2.2.2 [Output 2 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

#### 587 5.10.3 Subcomponents

588 Maybe more subcomponents have to be added. Please check this.

#### 589 5.10.3.1 Management\_of\_Radio\_Communication

##### 590 5.10.3.1.1 Component Requirements

Component name	Management_of_Radio_Communication
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/Radio/MoRC">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/Radio/MoRC</a>
SCADE designer	Uwe Steinke, Siemens

Description

to be checked

The function *managementOfRadioCommunication* implements the session states establishing, maintaining and termination as described in Subset-026, chap. 3.5. A SCADE state machine reflects this state model (Figure ???) accurately. Within each of the states, the activities needed as long as the state is active, are performed. When there is no communication session (state *NoSession*) currently, the state machine waits for events that initiate a session (subfunction *initiate\_a\_Session*). When the appropriate conditions are fulfilled, the state machine moves to the *Establishing* state. Here in, it runs through the sequence required fore establishing a session (subfunction *establish\_a\_Session*. Dependent on the results, the state machine changes over to the *Maintaining* or *Terminating* state. While in *Maintaining*, the communication connection is monitored. When an event triggering the session termination occurs, the state machine switches to the state *Terminating* with the subfunction *terminating\_a\_CommunicationSession* and performs the session termination sequence.

In parallel to the main state machine, *managementOfRadioCommunication* monitors all the time whether the session has to be terminated (subfunction *initiateTerminatingASession*) or if the session has the be terminated and subsequently established (subfunction *terminateAndEstablishSession*). *registeringToTheRadioNetwork* is responsible for connection to the radio network. *safeRadioConnectionIndication* controls the radio connection indication for the driver.

Input documents	Subset-026, Chapter 3.5
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

591 **5.10.3.1.2 Interface**

592 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
593 above) respectively the SCADE generated documentation.

594 **5.10.3.2 genMSGToRBC**

595 **5.10.3.2.1 Component Requirements**

Component name	genMSGToRBC
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/Radio/MoRC">https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/Radio/MoRC</a>
SCADE designer	Uwe Steinke, Siemens

Description

to be completed

Input documents	Subset-026, Chapter 3.5
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

### 5.10.3.2.2 Interface

For an overview of the interface of this internal component we refer to the SCADE model (cf. link above) respectively the SCADE generated documentation.

## 5.11 F2.10: ManageDMIInput

section and corresponding subsections have to be completed

### 5.11.1 Component Requirements

Component name	ManageDMIInput
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of the components functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

### 5.11.2 Interface

An overview of the interface of component ManageDMIInput is shown in Figure 17. The inputs and outputs are described in detail in Section 5.11.2.1 respectively 5.11.2.2. Subcomponents are described in Section 5.11.3.

#### 5.11.2.1 Inputs

##### 5.11.2.1.1 [Input 1 name]



Figure 17. ManageDMIInput SysML diagram

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at bound-ary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or un- wanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

608 5.11.2.1.2 [Input 2 name]

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at bound-ary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or un- wanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

609 5.11.2.2 Outputs

610 5.11.2.2.1 [Output 1 name]

Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

#### 611 5.11.2.2.2 [Output 2 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

#### 612 5.11.3 Subcomponents

613 Currently ManageDMIInput does not have any subcomponents.

### 5.12<sup>4</sup> F2.11: ManageDMIOutput

615 section and corresponding subsections have to be completed

#### 616 5.12.1 Component Requirements

Component name	ManageDMIOutput
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of the components functionality]





Figure 18. ManageDMIOOutput SysML diagram

Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

5.12.2 Interface

An overview of the interface of component ManageDMIOOutput is shown in Figure 18. The inputs and outputs are described in detail in Section 5.12.2.1 respectively 5.12.2.2. Subcomponents are described in Section 5.12.3.

5.12.2.1 Inputs

5.12.2.1.1 [Input 1 name]

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

5.12.2.1.2 [Input 2 name]

Input name	[Name of the input]
------------	---------------------

Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

#### 624 5.12.2.2 Outputs

##### 625 5.12.2.2.1 [Output 1 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

##### 626 5.12.2.2.2 [Output 2 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]
---	---

### 627 5.12.3 Subcomponents

#### 628 5.12.3.1 cyclicReportToDMI

##### 629 5.12.3.1.1 Component Requirements

Component name	cyclicReportToDMI
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

##### 630 5.12.3.1.2 Interface

631 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
632 above) respectively the SCADE generated documentation.

#### 633 5.12.3.2 ManageTextMessages

##### 634 5.12.3.2.1 Component Requirements

Component name	ManageTextMessages
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of the components functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]

API requirements	[If applicable description of API requirements, otherwise n/a]
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#### 635 5.12.3.2.2 Interface

636 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
637 above) respectively the SCADE generated documentation.

#### 638 5.12.3.3 copyTrackDescription

##### 639 5.12.3.3.1 Component Requirements

Component name	copyTrackDescription
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 640 5.12.3.3.2 Interface

641 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
642 above) respectively the SCADE generated documentation.

#### 643 5.12.3.4 toEntryRequest

##### 644 5.12.3.4.1 Component Requirements

Component name	toEntryRequest
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4

Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 645 5.12.3.4.2 Interface

646 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
647 above) respectively the SCADE generated documentation.

#### 648 5.12.3.5 sendBrakesToDMI

##### 649 5.12.3.5.1 Component Requirements

Component name	sendBrakesToDMI
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 650 5.12.3.5.2 Interface

651 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
652 above) respectively the SCADE generated documentation.

#### 653 5.12.3.6 manageDMI\_Output

##### 654 5.12.3.6.1 Component Requirements

Component name	manageDMI_Output
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???

Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 655 5.12.3.6.2 Interface

656 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
657 above) respectively the SCADE generated documentation.

#### 658 5.12.3.7 sendTrainData

##### 659 5.12.3.7.1 Component Requirements

Component name	sendTrainData
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 660 5.12.3.7.2 Interface

661 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
662 above) respectively the SCADE generated documentation.

#### 663 5.12.3.8 sendVersion

##### 664 5.12.3.8.1 Component Requirements

Component name	sendVersion
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of functionality]

Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 665 5.12.3.8.2 Interface

666 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
667 above) respectively the SCADE generated documentation.

#### 668 5.12.3.9 sendLevelListPkg

##### 669 5.12.3.9.1 Component Requirements

Component name	sendLevelListPkg
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 670 5.12.3.9.2 Interface

671 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
672 above) respectively the SCADE generated documentation.

### 5.13<sub>3</sub> F2.12: ManageTIUInput

674 section and corresponding subsections have to be completed

#### 675 5.13.1 Component Requirements

Component name	ManageTIUInput
Link to SCADE model	<a href="http://???">http://???</a>

SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of the components functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

5.13.2 Interface

An overview of the interface of component ManageTIUInput is shown in Figure 19. The inputs and outputs are described in detail in Section 5.13.2.1 respectively 5.13.2.2. Subcomponents are described in Section 5.13.3.

5.13.2.1 Inputs

5.13.2.1.1 [Input 1 name]

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at bound-ary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]

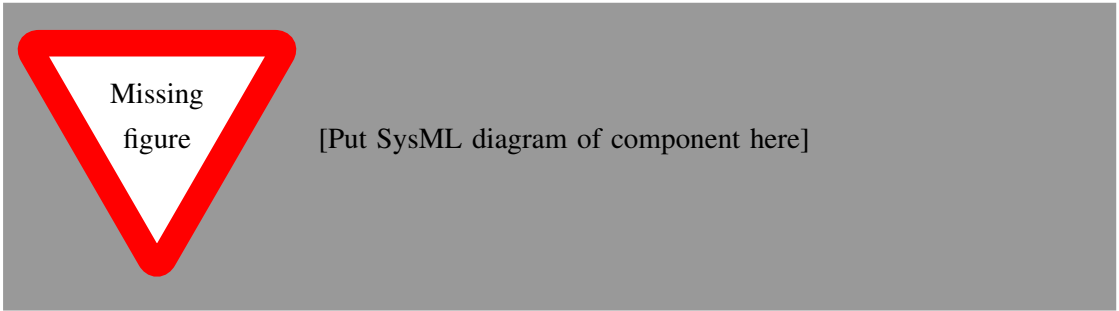


Figure 19. ManageTIUInput SysML diagram



Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]
---	---

#### 682 5.13.2.1.2 [Input 2 name]

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

#### 683 5.13.2.2 Outputs

##### 684 5.13.2.2.1 [Output 1 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

##### 685 5.13.2.2.2 [Output 2 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

### 686 5.13.3 Subcomponents

#### 687 5.13.3.1 mergeTIU\_Info

##### 688 5.13.3.1.1 Component Requirements

Component name	mergeTIU_Info
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

##### 689 5.13.3.1.2 Interface

690 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
691 above) respectively the SCADE generated documentation.

#### 692 5.13.3.2 getTIUStatusFromData

##### 693 5.13.3.2.1 Component Requirements

Component name	getTIUStatusFromData
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 694 5.13.3.2.2 Interface

695 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
696 above) respectively the SCADE generated documentation.

### 5.14 F2.13: ManageTIUOutput

698 section and corresponding subsections have to be completed

#### 699 5.14.1 Component Requirements

Component name	ManageTIUOutput
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of the components functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 700 5.14.2 Interface



Figure 20. ManageTIUOutput SysML diagram

701 An overview of the interface of component ManageTIUOutput is shown in Figure 20. The inputs  
702 and outputs are described in detail in Section 5.14.2.1 respectively 5.14.2.2. Subcomponents are  
703 described in Section 5.14.3.

704 **5.14.2.1 Inputs**

705 **5.14.2.1.1 [Input 1 name]**

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at bound-ary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or un-wanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

706 **5.14.2.1.2 [Input 2 name]**

Input name	[Name of the input]
Description	[Brief description of the input]
Source	[Name of the source component]
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at bound-ary]

Behaviour for values out of valid range [Description of components behaviour when input value is out of valid range]

Behaviour when value is erroneous, absent or unwanted (i.e. spurious) [Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

#### 709 5.14.2.2.2 [Output 2 name]

Output name	[Name of the output]
Description	[Brief description of the output]
Destination	[Name of the destination component(s)]
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

### 710 5.14.3 Subcomponents

#### 711 5.14.3.1 handleTraction

##### 712 5.14.3.1.1 Component Requirements

Component name	handleTraction
Link to SCADE model	<a href="http://???">http://???</a>

SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 713 5.14.3.1.2 Interface

714 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
715 above) respectively the SCADE generated documentation.

#### 716 5.14.3.2 manageTIU\_output

##### 717 5.14.3.2.1 Component Requirements

Component name	manageTIU_output
Link to SCADE model	<a href="http://???">http://???</a>
SCADE designer	Bernd Hekele, DB Netz AG
Description	[Brief description of functionality]
Input documents	Subset-026, Chapter ?? Subset-026, Chapter ?? Subset-026, Chapter ???
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

##### 718 5.14.3.2.2 Interface

719 For an overview of the interface of this internal component we refer to the SCADE model (cf. link  
720 above) respectively the SCADE generated documentation.

## 6<sup>721</sup> F3: Measure Train Movement

<sup>722</sup> This component is not part of the openETCS OBU currently and therefore no detailed description  
<sup>723</sup> is provided here.

## 7<sup>724</sup> F4: Manage Radio Communication

<sup>725</sup> This component is not part of the openETCS OBU currently and therefore no detailed description  
<sup>726</sup> is provided here.



## 8 <sup>727</sup> F5: Manage JRU

<sup>728</sup> This component is not part of the openETCS OBU currently and therefore no detailed description  
<sup>729</sup> is provided here.

## 9 F6: DMI Controller

This chapter needs to be completed and a responsible developer has to be identified.

### 9.1 DMI

#### 9.1.1 Component Requirements

Component name	DMI
Link to SCADE model	<a href="https://github.com/openETCS/modeling/tree/master/model/Scade/System/DMI_Control">https://github.com/openETCS/modeling/tree/master/model/Scade/System/DMI_Control</a>
SCADE designer	Valerio D'Angelo, DB Netz AG
Description	The DMI controller interacts with the DMI display and is responsible for all procedures between the DMI display and Driver. Furthermore, the DMI controller will interact with the DMI Management to compute the received information (e.g. driver number request, ...) and send, if necessary, data or reports to the DMI Management (acknowledge, text messages...). The DMI Controller is a passive module, this means that all the processing are performed EVC-side, therefore the DMI Controller simply responds to the requests of the EVC or Driver and performs some checks according with the information received from EVC.
Input documents	ERA_ERTMS_015560
Safety integrity level	4
Time constraints	[If applicable description of time constraints, otherwise n/a]
API requirements	[If applicable description of API requirements, otherwise n/a]

#### 9.1.2 Interface

An overview of the interface of component DMI is shown in Figure 21. The inputs and outputs are described in detail in Section 9.1.2.1 respectively 9.1.2.2.

##### 9.1.2.1 Inputs

###### 9.1.2.1.1 DMI\_entry\_request

Input name	DMI_entry_request
Description	Request to input data (e.g. driver id, Train running number etc.)
Source	DMI Management

Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

739 **9.1.2.1.2 DMI\_identifier\_request**

Input name	DMI_identifier_request
Description	Request of the DMI informations
Source	DMI Management
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

740 **9.1.2.1.3 DMI\_menu\_request**

Input name	DMI_menu_request
Description	Request to enable or disable buttons
Source	DMI Management
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]
---	---

#### 741 9.1.2.1.4 DMI\_dynamic

Input name	DMI_dynamic
Description	Contains informations about current speed, current mode etc.
Source	DMI Management
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

#### 742 9.1.2.1.5 DMI\_text\_message

Input name	DMI_text_message
Description	Contains predefined or plain text messages
Source	DMI Management
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

#### 743 9.1.2.1.6 DMI\_icons

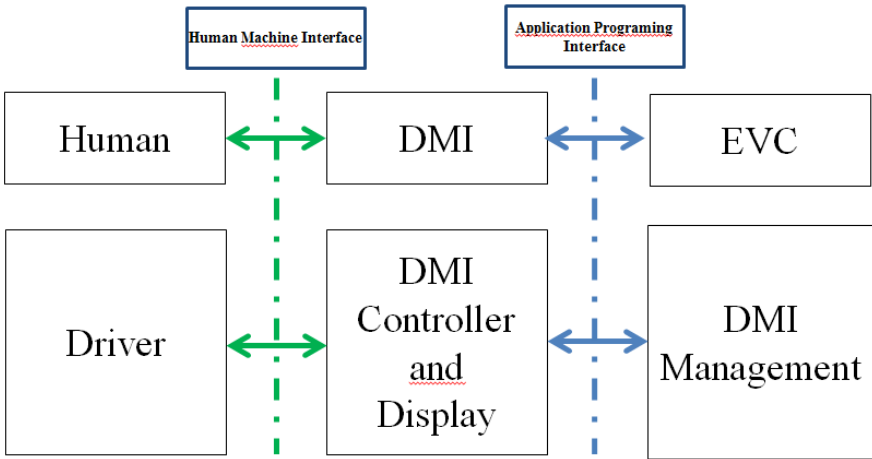


Figure 21. DMI component SysML diagram

Input name	DMI_icons
Description	Request to display one or more icons in any area
Source	DMI Management
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at bound-ary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or un- wanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

744 9.1.2.1.7 DMI\_driver\_identifier

Input name	DMI_driver_identifier
Description	Contains the default or entered driver identifier
Source	DMI Management
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at bound-ary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or un- wanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

746 **9.1.2.1.9 DMI\_train\_data**

Input name	DMI_train_data
Description	Contains the default or entered train data
Source	DMI Management
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

747 **9.1.2.1.10 TIU\_trainStatus**

Input name	TIU_trainStatus
Description	Open/close Desk signal
Source	TIU
Type	[Type of the input]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when input value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when input value is out of valid range]

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]
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## 748 9.1.2.2 Outputs

### 749 9.1.2.2.1 DMI\_identifier

Output name	DMI_identifier
Description	Information about DMI (e.g. version, cabin identifier etc.)
Destination	DMI Management
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

### 750 9.1.2.2.2 DMI\_driver\_request

Output name	DMI_driver_request
Description	Driver request or acknowledgement
Destination	DMI Management
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

### 751 9.1.2.2.3 DMI\_train\_data\_ack

Output name	DMI_train_data_ack
Description	Train data acknowledgement
Destination	DMI Management
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

752 **9.1.2.2.4 DMI\_status\_report**

Output name	DMI_status_report
Description	The actual status of DMI (keep alive)
Destination	DMI Management
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

753 **9.1.2.2.5 DMI\_text\_message\_ack**

Output name	DMI_text_message_ack
Description	Text message acknowledgement
Destination	DMI Management
Type	[Type of the output]
Valid range of values	[Complete list of valid values]



Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

754 **9.1.2.2.6 DMI\_icons\_ack**

Output name	DMI_icons_ack
Description	Icon acknowledgement
Destination	DMI Management
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

755 **9.1.2.2.7 DMI\_driver\_identifier**

Output name	DMI_driver_identifier
Description	Contains the default or entered driver identifier
Destination	DMI Management
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]

Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]
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756 **9.1.2.2.8 DMI\_train\_running\_number**

Output name	DMI_train_running_number
Description	Contains the default or entered train running number
Destination	DMI Management
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

757 **9.1.2.2.9 DMI\_train\_data**

Output name	DMI_train_data
Description	Contains the default or entered train data
Destination	DMI Management
Type	[Type of the output]
Valid range of values	[Complete list of valid values]
Behaviour when value is at boundary	[Description of components behaviour when output value is at boundary]
Behaviour for values out of valid range	[Description of components behaviour when output value is out of valid range]
Behaviour when value is erroneous, absent or unwanted (i.e. spurious)	[Description of components behaviour when value is erroneous, absent or unwanted (i.e. spurious)]

## References

- <sup>759</sup> [1] ERA. *System Requirements Specification, SUBSET-026*, v3.3.0 edition, March 2012.