

openETCS WP3 Model Design Description

openETCS: WP3-Initial-Architecture

Balise Channel Reception and Train Positioning

Summary:

ETCS OBU Kernel Function Implementation

The train moves on a track equipped with balises and determines its position

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1. General Project Description

Minimum OBU Kernel Function Implementation:

The train moves on a track equipped with balises and determines its position

Implemented functions:

- Receive and manage balise information
- Determine train position
- ETCS language data types

References:

- <https://github.com/openETCS/SRS-Analysis/issues/9>
- <https://github.com/openETCS/SRS-Analysis/issues/36>
- <https://github.com/openETCS/SRS-Analysis/issues>
- <https://github.com/openETCS/modeling/blob/master/openETCS%20ArchitectureAndDesign/FirstIteration/openETCSArchitectureAndDesignSpecification.pdf>
- <https://github.com/openETCS/validation/issues/227>
- https://github.com/openETCS/modeling/tree/master/model/Scade/System/ObuFunctions/ManageLocationRelatedInformation/MLRI_Integration

This document reflects the current implementation status.

- Name: MLRI_Integration.etp
- Description: SUBSET-026, ISSUE : 3.3.0
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- Gist URL: ---
- Cryptography: No
- Author(s): Uwe Steinke

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THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.

2. Software Architecture

2.1. Project Architecture

This section displays the package hierarchy of projects.

Project MLRI_Integration
MLRI_Integration_Pkg

Project Library BasicLocationFunctions
BasicLocationFunctions_Pkg

Project Library BG_Types
BG_Types_Pkg

Project Library BuildBGMessage
BuildBGMessage_Pkg
BaliseSupport

Project Library CalculateTrainPosition
CalculateTrainPosition_Pkg
BG_relocation_Pkg
BG_utilities_Pkg
gp_functions_Pkg

Project Library CheckBGConsistency
CheckPGConsistency_Pkg

Project Library DetermineBG_Orientation_and_LRBG
DetermineBGOrientation_LRBG

Project Library ManageBaliseInfomation_Integration
ManageBaliseInfomation_Integration_Pkg

Project Library Obu_BasicTypes
Obu_BasicTypes_Pkg

Project Library ProvidePositionReport
ProvidePositionReport_Pkg

Project Library ReceiveEuroBaliseFromAPI
btmSupportPkg
ReceiveEuroBaliseFromAPI_Pkg

Project Library SelectUsableInfo
SelectUsableInfo_Pkg

Project Library TrainPosition_Integration
TrainPosition_Integration_Pkg

Project Library TrainPosition_Types
TrainPosition_Types_Pck

Project Library ValidateDataDirection
ValidateDataDirection_Pkg

2.2. Call Graph

This Call Graph displays the dependency tree of model operators.

1. MLRI_Integration_Pkg::LocationRelatedInformation
 - 1.1. ManageBaliseInformation_Integration_Pkg::ManageBaliseInformation
 - 1.2. TrainPosition_Integration_Pkg::ManageTrainPosition

3. MLRI_Integration Project

3.1. MLRI_Integration_Pkg Package

3.1.1. LocationRelatedInformation Operator

Declared as **public node**

3.1.1.1. Comments and Information

LocationRelatedInformation Comments:

- Integrates all subfunctions of the Block "ManageLocationRelatedInformation"

3.1.1.2. Interface

Table 1: Inputs of LocationRelatedInformation

| Name | Type | Comments and Information |
|--------------------------|--|--|
| currentOdometry | Obu_BasicTypes_Pkg::odometry_T | Comments: The current odometry values |
| passedBG | BG_Types_Pkg::passedBG_T | Comments: Input event reporting a balise group during its passage, if there is one. |
| LRBG | TrainPosition_Types_Pkg::positionedBG_T | Comments: The LRBG used for RBC communication. |
| prevLRBG | TrainPosition_Types_Pkg::positionedBG_T | Comments: A previously used LRBG used in RBC communication. |
| reset | bool | Comments: Resets all to an initials state and deletes all stored BGs. |
| systemTime | ProvidePositionReport_Pkg::SystemTime_T | |
| errorMsg | ProvidePositionReport_Pkg::ErrorMessage_T | |
| posRepPara | ProvidePositionReport_Pkg::PositionReportParameter_T | |
| trackInfo | ProvidePositionReport_Pkg::TrackInfo_T | |
| trainProps | TrainPosition_Types_Pkg::trainProperties_T | |
| rcbComm | ProvidePositionReport_Pkg::RBC_Communication_T | |
| linkingInfoUsed | ProvidePositionReport_Pkg::LinkingInfoUsedOnBoard | |
| API_balise | API_Telegram_T | |
| incenterOfBalisePosition | BG_Types_Pkg::centerOfBalisePosition_T | |
| CurrentLRBG_ | BG_Types_Pkg::CurrentLRBG | |
| ListOfBGs_ | BG_Types_Pkg::ListOfBG | |

| Name | Type | Comments and Information |
|-----------------------|--------------------------------------|--------------------------|
| TrainInfo_ | BG_Types_Pkg::TrainToTrackStatus_T | |
| RBCOrientationReport_ | BG_Types_Pkg::RBCOrientationReport_T | |

Table 2: Outputs of LocationRelatedInformation

| Name | Type | Comments and Information |
|----------------|--|--|
| posRep | ProvidePositionReport_Pkg::PositionReport_T | |
| trainPosition | TrainPosition_Types_Pkg::trainPosition_T | |
| trainPosInfo | TrainPosition_Types_Pkg::trainPositionInfo_T | Comments: The resulting train position with reference to the LRBG |
| trainPosErrors | TrainPosition_Types_Pkg::positionErrors_T | Comments: Errors and inconsistencies detected by the calculation. |
| BGs | TrainPosition_Types_Pkg::positionedBGs_T | Comments: The collection of currently known BGs. |
| BG_Message | BG_Types_Pkg::BG_Message_T | |
| RBCReport_ | Radio_TrainToTrack::Train_Position_Report | |

3.1.1.3. Locals

Table 3: Locals of LocationRelatedInformation

| Name | Type | Properties | | Comments and Information |
|---------|--|------------|--|--------------------------|
| BGs_loc | TrainPosition_Types_Pkg::positionedBGs_T | last | CalculateTrainPosition_Pkg::cNoPositionedBGs | |

3.1.1.4. Operator Hierarchy

diagram : diagram_LocationRelatedInformation_1

3.1.1.5. Graphical and Textual Diagrams

3.1.1.5.1. View of diagram_LocationRelatedInformation_1 (LocationRelatedInformation)

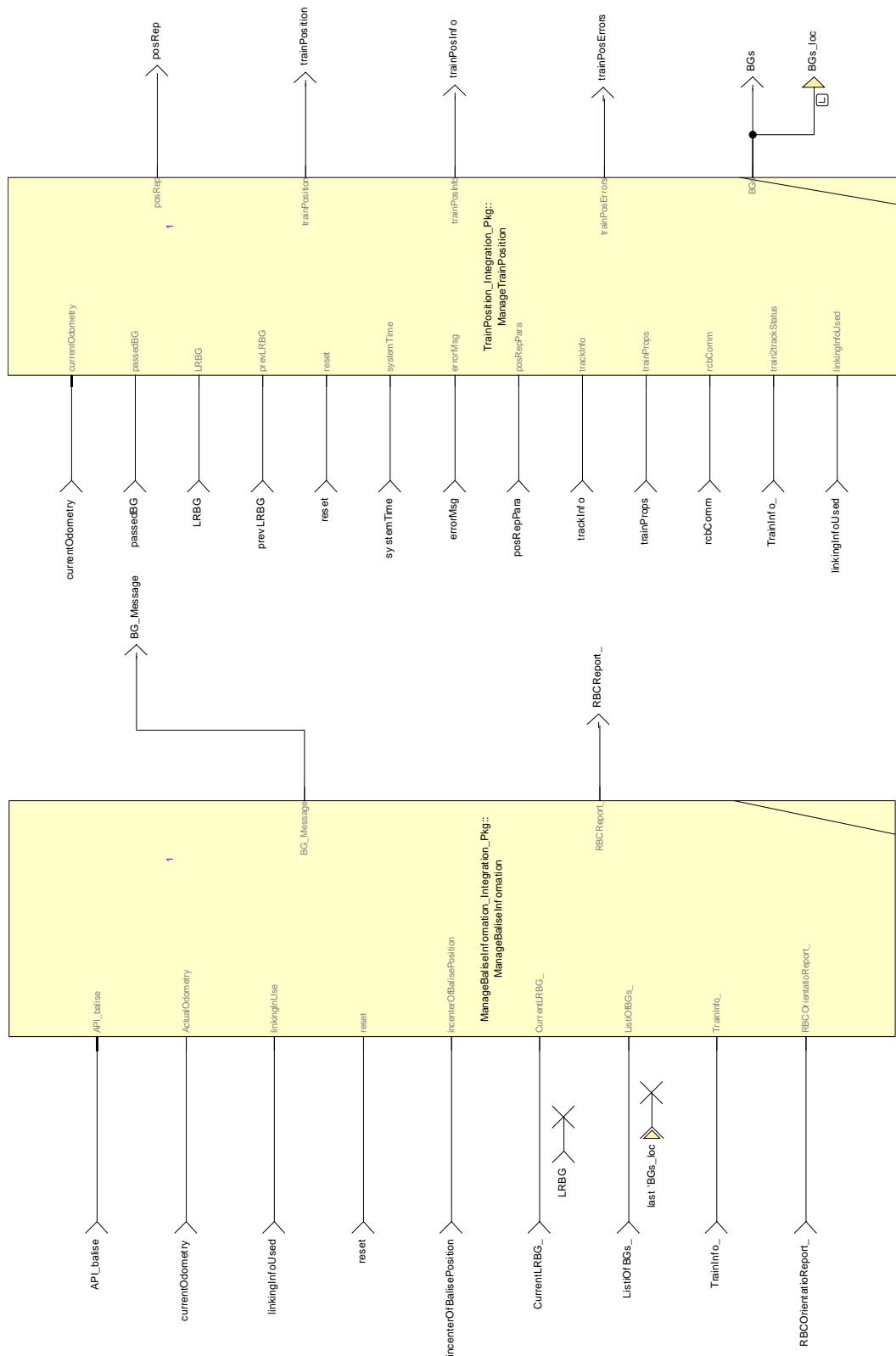


Figure 1: View of diagram_LocationRelatedInformation_1 (LocationRelatedInformation)

4. Project Library: BG_Types

4.1. BG_Types_Pkg Package

4.1.1. Types

Table 4: Public Types of BG_Types_Pkg

| Name | Definition | Comments and Information |
|--------------------------|--|---|
| AdditionalInformation_T | {addInfo : int, linkingPackets : BG_Types_Pkg::LinkedBGs_T} | Comments: Packets received from balises addInfo Comments: This type is not yet defined |
| BG_Header_T | {q_updown : Q_UPDOWN, m_version : M_VERSION, q_media : Q_MEDIA, n_pig : N_PIG, n_total : N_TOTAL, m_dup : M_DUP, m_mcount : M_MCOUNT, nid_c : NID_C, nid_bg : NID_BG, q_link : Q_LINK} | Comments: Common header of the balise group datagram |
| BG_Message_T | {present : bool, TelegramHeaders : BG_Types_Pkg::TelegramHeaderArray_T, AddInfo : BG_Types_Pkg::AdditionalInformation_T, numberBalises : int, centerOfBalisePosition : BG_Types_Pkg::centerOfBalisePosition_T, BGOrientation : Q_DIRTRAIN} | present Comments: indicates whether the bg-message present is. TelegramHeaders Comments: headers of all received telegrams filled up from the start of the array AddInfo Comments: For all balises of the group: Packets collected into a combined information numberBalises Comments: additional packets received with the balises centerOfBalisePosition Comments: position of the balise group BGOrientation Comments: Orientation of the balise group |
| centerOfBalisePosition_T | {centerOfBalisePosition : Obu_BasicTypes_Pkg::OdometryLocations_T, BG_centerDetectionInaccuracies : Obu_BasicTypes_Pkg::LocWithInAcc_T, timestamp : Obu_BasicTypes_Pkg::T_internal_Type} | Comments: Gives the information for location and accuracy of measurements centerOfBalisePosition Comments: Location BG_centerDetectionInaccuracies Comments: Location inaccuracies caused by the balise group center detection timestamp Comments: timestamp when measurement was taken |
| CurrentLRBG | {filteredBGMessage : BG_Types_Pkg::BG_Message_T, position : BG_Types_Pkg::Position_T} | |

| Name | Definition | Comments and Information |
|---------------|---|---|
| LinkedBG_T | <pre>{ valid : bool, nid_LRBG : NID_LRBG, nid_packet : NID_PACKET, q_dir : Q_DIR, l_packet : L_PACKET, q_scale : Q_SCALE, d_link : D_LINK, q_newcountry : Q_NEWCOUNTRY, nid_c : NID_C, nid_bg : NID_BG, q_linkorientation : Q_LINKORIENTATION, q_linkreaction : Q_LINKREACTION, q_locacc : Q_LOCACC }</pre> | <p>Comments:</p> <p>7.4.2.2: Single, but complete, element from LinkingPacket_Type</p> <p>valid Comments:</p> <p>This element has valid data</p> <p>nid_LRBG Comments:</p> <p>8.4.4.6.1: ID of the reference LRBG (refers to radio message)</p> <p>nid_packet Comments:</p> <p>Packet identifier: probably not needed here: Packet 5 = constant</p> <p>q_dir Comments:</p> <p>Validity direction of transmitted data with reference to directionality of the balise group sending the information or to directionality of the LRBG</p> <p>l_packet Comments:</p> <p>7.3.3.2 Number of bits in the packet.</p> <p>q_scale Comments:</p> <p>7.5.1.129: Qualifier for the distance scale: 10 cm, 1 m, 10 m</p> <p>d_link Comments:</p> <p>7.5.1.10: Incremental linking distance to next linked balise group</p> <p>q_newcountry Comments:</p> <p>7.5.1.121: New Country Qualifier</p> <p>nid_c Comments:</p> <p>Identity number of the country or region</p> <p>nid_bg Comments:</p> <p>Identity number of the balise group</p> <p>q_linkorientation Comments:</p> <p>7.5.1.116: Qualifier for the direction of the linked balise group: Indicates whether the linked balise group will be overpassed by the train in nominal or reverse direction.</p> <p>q_linkreaction Comments:</p> <p>7.5.1.117: Qualifier for the reaction to be performed if a linking or a balise group message consistency problem occurs with the balise group linked to</p> <p>q_locacc Comments:</p> <p>7.5.1.115: defines the absolute value of the accuracy of the Balise location (max +/- 63 m)</p> |
| LinkedBGs_T | <pre>BG_Types_Pkg::LinkedBG_T ^cMaxNoOfLinkedBGs</pre> | <p>Comments:</p> <p>Array of linked balise groups. This array replaces the linking packet (TrackToTrain::Linking)</p> |
| ListOfBG | <pre>BG_Types_Pkg::CurrentLRBG ^cMaxListBGs</pre> | |
| Orientation_T | <pre>enum {Single_Balise_Group, DIR_Nominal, DIR_Reverse}</pre> | |

| Name | Definition | Comments and Information |
|------------------------|--|--|
| passedBG_T | <pre> {valid : bool, timestamp : Obu_BasicTypes_Pkg::T_internal_Type, odometristamp : Obu_BasicTypes_Pkg::OdometryLocations_T, BG_centerDetectionInaccuracies : Obu_BasicTypes_Pkg::LocWithInAcc_T, BG_Header : BG_Types_Pkg::BG_Header_T, linkedBGs : BG_Types_Pkg::LinkedBGs_T, noCoordinateSystemHasBeenAssigned : bool, trainOrientationToBG : Q_DIRLRBG, trainRunningDirectionToBG : Q_DIRTRAIN, passingSpeed : Obu_BasicTypes_Pkg::Speed_T} </pre> | <p>Comments:</p> <p>Information received from a BG passed</p> <p>odometristamp Comments:</p> <p>Odometry values when the balise group was passed</p> <p>BG_centerDetectionInaccuracies Comments:</p> <p>Location inaccuracies caused by the balise group center detection</p> <p>BG_Header Comments:</p> <p>Common header of the balise group datagram</p> <p>linkedBGs Comments:</p> <p>The linked balise groups announced from this BG.</p> <p>noCoordinateSystemHasBeenAssigned Comments:</p> <p>3.4.2, 3.6.3.1.4: Every balise group has its own co-ordinate system</p> <p>trainOrientationToBG Comments:</p> <p>3.6.1.3: Orientation of the train in relation to the direction of the BG</p> <p>trainRunningDirectionToBG Comments:</p> <p>3.6.1.3: Direction of train movement in relation to the BG orientation</p> <p>passingSpeed Comments:</p> <p>Train speed while passing the BG; its sign characterizes the passing direction based on odometry information</p> |
| Position_T | int | |
| RBCOrientationReport_T | {assignment_of_coordinate_system : Radio_TrackToTrain::Assignment_of_coordinate_system} | |
| RBCReport_T | {train_position_report : Radio_TrainToTrack::Train_Position_Report} | |
| Telegram_T | <pre> {present : bool, valid : bool, telegramheader : BG_Types_Pkg::TelegramHeader_T, packets : BG_Types_Pkg::AdditionalInformation_T} </pre> | <p>present Comments:</p> <p>Flag indicates whether the parameter is present in the interfaces</p> <p>valid Comments:</p> <p>The element has valid data</p> <p>telegramheader Comments:</p> <p>Information received from the balise</p> <p>packets Comments:</p> <p>Packets received via the balises</p> |
| TelegramHeader_T | <pre> {q_updown : Q_UPDOWN, m_version : M_VERSION, q_media : Q_MEDIA, n_pig : N_PIG, n_total : N_TOTAL, m_dup : M_DUP, m_mcount : M_MCOUNT, nid_c : NID_C, nid_bg : NID_BG, q_link : Q_LINK} </pre> | <p>Comments:</p> <p>This structure is not "packed" to bit boundaries</p> |

| Name | Definition | Comments and Information |
|-----------------------|---|--|
| TelegramHeaderArray_T | BG_Types_Pkg::TelegramHeaderFlag_T ^cMaxNoBalises | |
| TelegramHeaderFlag_T | {valid : bool, header : BG_Types_Pkg::TelegramHeader_T} | |
| TrainToTrackStatus_T | {m_mode : M_MODE, m_level : M_LEVEL, m_leveltr : M_LEVELTR, nid_ntc : NID_NTC, q_length : Q_LENGTH} | Comments: structure capturing modi, leves and train integrity |

4.1.2. Constants

Table 5: Public Constants of BG_Types_Pkg

| Name | Type | Value | Comments and Information |
|------|------|-------|--------------------------|
|------|------|-------|--------------------------|

| Name | Type | Value | Comments and Information |
|----------|---------------------------------------|--|--------------------------|
| cAddInfo | BG_Types_Pkg::AdditionalInformation_T | {addInfo : 0, linkingPackets : [{ valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_scale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_Same_country_or_railway_administration_no_NID_C_follows, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATION_The_balise_group_is_seen_by_the_train_in_reverse_direction, q_linkreaction : Q_LINKREACTION_Train_trip, q_locacc : 0}, { valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_scale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_Same_country_or_railway_administration_no_NID_C_follows, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATION_The_balise_group_is_seen_by_the_train_in_reverse_direction, q_linkreaction : Q_LINKREACTION_Train_trip, q_locacc : 0}, { valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_scale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_Same_country_or_railway_administration_no_NID_C_follows, nid_c : 0, nid_bg : 0, | |

| Name | Type | Value | Comments and Information |
|------------------|--------------------------|---|--------------------------|
| cEmpty_BaliseTlg | BG_Types_Pkg::Telegram_T | { present : false, valid : false, telegramheader : { q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previous_versions_according_to_e_g_EEIG_SRS_and_UIC_A200_SRS, q_media : Q_MEDIA_Balise, n_pig : N_PIG_I_am_the_1st, n_total : N_TOTAL_1_balise_in_the_group, m_dup : M_DUP_No_duplicates, m_mcount : 0, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked}, packets : { addInfo : 0, linkingPackets : [{ valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_scale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_Same_country_or_railway_administration_no_NID_C_follows, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATION_The_balise_group_is_seen_by_the_train_in_reverse_direction, q_linkreaction : Q_LINKREACTION_Train_trip, q_locacc : 0}, { valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_scale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_Same_country_or_railway_administration_no_NID_C_follows, nid_c : 0, nid_bg : 0, q_linkorientation : | |

| Name | Type | Value | Comments and Information |
|------|------|--|--------------------------|
| | | <pre>{present : false, TelegramHeaders : [{valid : false, header : {q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previo us_versions_accordi ng_to_e_g_EEIG_S RS_and_UIC_A200_ SRS, q_media : Q_MEDIA_Balise, n_pig : N_PIG_I_am_the_1 st, n_total : N_TOTAL_1_balise_ in_the_group, m_dup : M_DUP_No_duplicat es, m_mcount : 0, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked}} , {valid : false, header : {q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previo us_versions_accordi ng_to_e_g_EEIG_S RS_and_UIC_A200_ SRS, q_media : Q_MEDIA_Balise, n_pig : N_PIG_I_am_the_1 st, n_total : N_TOTAL_1_balise_ in_the_group, m_dup : M_DUP_No_duplicat es, m_mcount : 0, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked}} , {valid : false, header : {q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previo us_versions_accordi ng_to_e_g_EEIG_S RS_and_UIC_A200_ SRS, q_media : Q_MEDIA_Balise, n_pig : N_PIG_I_am_the_1 st, n_total : N_TOTAL_1_balise_ in_the_group, m_dup : M_DUP_No_duplicat es, m_mcount : 0,</pre> | |

| Name | Type | Value | Comments and Information |
|--------------|------------------------------------|---|--------------------------|
| cEmptyHeader | BG_Types_Pkg::TelegramHeaderFlag_T | { valid : false, header : { q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previous_versions_according_to_e_g_EEIG_SRS_and_UIC_A200_SRS, q_media : Q_MEDIA_Balise, n_pig : N_PIG_I_am_the_1st, n_total : N_TOTAL_1_balise_in_the_group, m_dup : M_DUP_No_duplicates, m_mcount : 0, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked} } | |

| Name | Type | Value | Comments and Information |
|------|------|---|--------------------------|
| | | <pre>[{valid : false, header : {q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previo us_versions_accordi ng_to_e_g_EEIG_S RS_and_UIC_A200_ SRS, q_media : Q_MEDIA_Balise, n_pig : N_PIG_I_am_the_1 st, n_total : N_TOTAL_1_balise_ in_the_group, m_dup : M_DUP_No_duplicat es, m_mcount : 0, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked}} , {valid : false, header : {q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previo us_versions_accordi ng_to_e_g_EEIG_S RS_and_UIC_A200_ SRS, q_media : Q_MEDIA_Balise, n_pig : N_PIG_I_am_the_1 st, n_total : N_TOTAL_1_balise_ in_the_group, m_dup : M_DUP_No_duplicat es, m_mcount : 0, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked}} , {valid : false, header : {q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previo us_versions_accordi ng_to_e_g_EEIG_S RS_and_UIC_A200_ SRS, q_media : Q_MEDIA_Balise, n_pig : N_PIG_I_am_the_1 st, n_total : N_TOTAL_1_balise_ in_the_group, m_dup : M_DUP_No_duplicat es, m_mcount : 0, nid_c : 0, nid_bg : 0, q_link :</pre> | |

| Name | Type | Value | Comments and Information |
|-----------------------------|---|---|---|
| cemptyPosition | BG_Types_Pkg::centerOfBalisePosition_T | {centerOfBalisePosition : {o_nominal : 0, o_min : 0, o_max : 0}, BG_centerDetectionInaccuracies : {nominal : 0, d_min : 0, d_max : 0}, timestamp : 0} | |
| cInitOrientation | Q_DIRTRAIN | Q_DIRTRAIN_Unknown | |
| cInvalidIndex | int | -1 | |
| cMaxDistanceBalisesInGroup | Obu_BasicTypes_Pkg::OdometryLocations_T | {o_nominal : 1200, o_min : 1200, o_max : 1200} | Comments: Maximum distance between balises within a group: Subset 40 section 4.1.1.2 |
| cMaxListBGs | int | 20 | |
| cMaxNoBalises | int | 8 | Comments: Max. number of balises in a balise group |
| cMaxNoOfLinkedBGs | int | 4 | Comments: Max. number of linked balise groups announced by a BG (arbitrary value); Must be 33, but set to 4 to ease debugging !!! |
| cNID_BG_unknown | NID_BG | 16383 | Comments: type NID_BG = int /* MinVal = 0, MaxVal = 16382 */ -- 16383 = Identity_is_unknown_(only_to_be_used_for_Linking_information) |
| cNID_LRBG_14Bits_Multiplier | int | 16384 | Comments: 16384: Serves to calculate NID_LRBG = 16384 * NID_C + NID_BG |
| cNID_LRBG_unknown | NID_LRBG | 16777215 | Comments: type NID_LRBG = int -- 16777215 = Unknown |

5. Project Library: Obu_BasicTypes

5.1. Obu_BasicTypes_Pkg Package

5.1.1. Comments and Information

Obu_BasicTypes_Pkg Comments:

- Standardized basic type definitions to be used within all internal OBU functions

5.1.2. Types

Table 6: Public Types of Obu_BasicTypes_Pkg

| Name | Definition | Comments and Information |
|---------------------|--|--|
| A_internal_Type | int | Comments: Standardized acceleration type for all internal calculations: in 0.01 m/s ² |
| G_internal_Type | int | Comments: Standardized gradient type for all internal gradient calculations: in per 0.1 mill |
| L_internal_Type | int | Comments: Standardized length type for all internal length, distance and location calculations: in cm |
| Location_T | Obu_BasicTypes_Pkg::L_internal_Type | Comments: Generic for all length, distance and location calculation: in cm |
| LocWithInAcc_T | { nominal : Obu_BasicTypes_Pkg::L_internal_Type, d_min : Obu_BasicTypes_Pkg::L_internal_Type, d_max : Obu_BasicTypes_Pkg::L_internal_Type } | Comments: Location with +/- tolerance nominal Comments: Nominal location d_min Comments: Min Location = nominal + d_min (typically < 0) d_max Comments: Max Location = nominal + d_max |
| odometry_T | { valid : bool, timestamp : Obu_BasicTypes_Pkg::T_internal_Type, odo : Obu_BasicTypes_Pkg::OdometryLocations_T, speed : Obu_BasicTypes_Pkg::Speed_T } | Comments: Odometry values with time stamp odo Comments: Odometry values |
| OdometryLocations_T | { o_nominal : Obu_BasicTypes_Pkg::L_internal_Type, o_min : Obu_BasicTypes_Pkg::L_internal_Type, o_max : Obu_BasicTypes_Pkg::L_internal_Type } | Comments: Location information provided by odometry o_nominal Comments: Nominal odometry value o_min Comments: Min. distance = o_min2 - o_min1 o_max Comments: Max distance = o_max2 - o_max1 |
| Speed_T | Obu_BasicTypes_Pkg::V_internal_Type | Comments: General speed type: in km/h. |

| Name | Definition | Comments and Information |
|-----------------|------------|---|
| T_internal_Type | int | Comments: Standardized system time type used for all internal time calculations: in ms |
| V_internal_Type | int | Comments: Standardized speed type used for all internal speed calculations: in km/h |

5.1.3. Constants

Table 7: Public Constants of Obu_BasicTypes_Pkg

| Name | Type | Value | Comments and Information |
|-----------------------|---|---------------------------------------|--------------------------------------|
| cLocWithInAcc_0 | Obu_BasicTypes_Pkg::LocWithInAcc_T | {nominal : 0, d_min : 0, d_max : 0} | |
| cOdometryInitialValue | Obu_BasicTypes_Pkg::OdometryLocations_T | {o_nominal : 0, o_min : 0, o_max : 0} | Comments: Initial odometry values |

6. Project Library: ManageBaliseInformation_Integration

6.1. ManageBaliseInformation_Integration_Pkg Package

6.1.1. ManageBaliseInformation Operator

Declared as **public node**

6.1.1.1. Interface

Table 8: Inputs of ManageBaliseInformation

| Name | Type | Comments and Information |
|--------------------------|--|--------------------------|
| API_balise | API_Telegram_T | |
| ActualOdometry | Obu_BasicTypes_Pkg::odometry_T | |
| linkingInUse | bool | |
| reset | bool | |
| incenterOfBalisePosition | BG_Types_Pkg::centerOfBalisePosition_T | |
| CurrentLRBG_ | BG_Types_Pkg::CurrentLRBG | |
| ListOfBGs_ | BG_Types_Pkg::ListOfBG | |
| TrainInfo_ | BG_Types_Pkg::TrainToTrackStatus_T | |
| RBCOrientationReport_ | BG_Types_Pkg::RBCOrientationReport_T | |

Table 9: Outputs of ManageBaliseInformation

| Name | Type | Comments and Information |
|------------|---|--------------------------|
| BG_Message | BG_Types_Pkg::BG_Message_T | |
| RBCReport_ | Radio_TrainToTrack::Train_Position_Report | |

6.1.1.2. Operator Hierarchy

diagram : diagram_ManageBaliseInformation_1

6.1.1.3. Graphical and Textual Diagrams

6.1.1.3.1. View of diagram_ManageBaliseInformation_1 (ManageBaliseInformation)

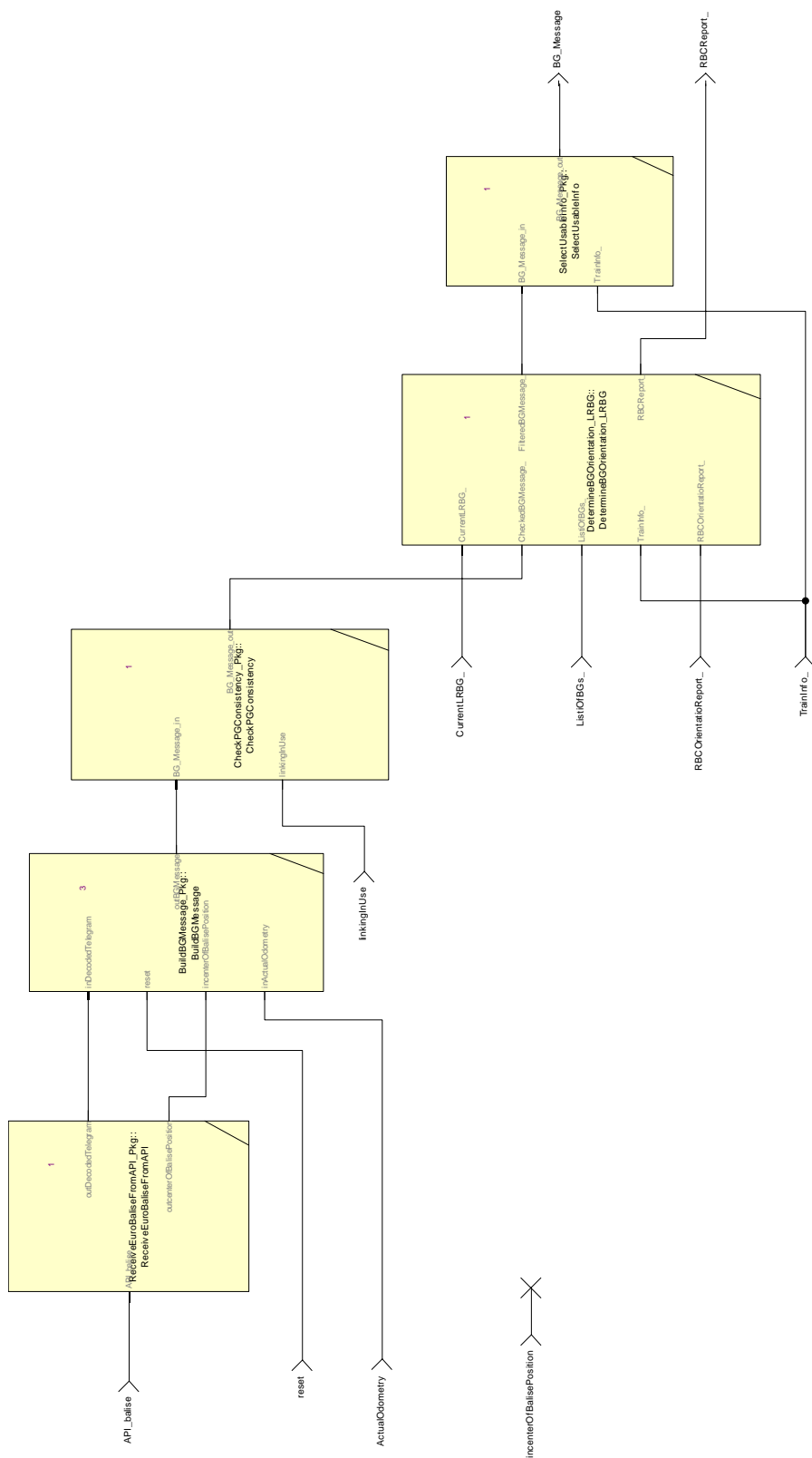


Figure 2: View of diagram_ManageBaliseInformation_1 (ManageBaliseInformation)

7. Project Library: BuildBGMessage

7.1. BuildBGMessage_Pkg Package

7.1.1. Open Packages

- BuildBGMessage_Pkg: : BaliseSupport

7.1.2. Types

Table 10: Public Types of BuildBGMessage_Pkg

| Name | Definition | Comments and Information |
|-----------------|---|--|
| BGCollector_T | {BG_ID : NID_BG, totalTelegrams : int, balisePosition : BG_Types_Pkg::centerOfBalisePosition_T, collectedTelegrams : int} | Comments: This data structure is used internally to collect balise telegrams balisePosition Comments: Information where the first telegram of the bg has been received. The information will be used to calculate whether a BG is already passed completely. collectedTelegrams Comments: Gives the number of telegrams collected in the bg-message |
| TelegramStore_T | {valid : bool, telegram : BG_Types_Pkg::Telegram_T, position : BG_Types_Pkg::centerOfBalisePosition_T} | valid Comments: data is valid (i.e., stored by purpose) position Comments: Information on where the balise was positioned |

7.1.3. Constants

Table 11: Public Constants of BuildBGMessage_Pkg

| Name | Type | Value | Comments and Information |
|----------------|-----------------------------------|---|--------------------------|
| cCollectorInit | BuildBGMessage_Pkg::BGCollector_T | {BG_ID : 0, totalTelegrams : 0, balisePosition : {centerOfBalisePosition : {o_nominal : 0, o_min : 0, o_max : 0}, BG_centerDetectionInaccuracies : {nominal : 0, d_min : 0, d_max : 0}, timestamp : 0}, collectedTelegrams : 0} | |

| Name | Type | Value | Comments and Information |
|------|------|--|--------------------------|
| | | <pre>{valid : false, telegram : {present : false, valid : false, telegramheader : {q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previo us_versions_accordi ng_to_e_g_EEIG_S RS_and_UIC_A200_ SRS, q_media : Q_MEDIA_Balise, n_pig : N_PIG_I_am_the_1 st, n_total : N_TOTAL_1_balise_ in_the_group, m_dup : M_DUP_No_duplicat es, m_mcount : 0, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked}, packets : {addInfo : 0, linkingPackets : [{valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_s cale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_S ame_country_or_ railway_administrati on_no_NID_C_follo ws, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATIO N_The_balise_grou p_is_seen_by_the_t rain_in_reverse_dir ection, q_linkreaction : Q_LINKREACTION_ Train_trip, q_locacc : 0}, {valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_s cale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_S ame_country_or_ railway_administrati on_no_NID_C_follo ws, nid_c : 0, nid_bg : 0,</pre> | |

7.1.4. addTelegram Operator

Declared as **public function**

7.1.4.1. Interface

Table 12: Inputs of addTelegram

| Name | Type | Comments and Information |
|------------------|---------------------------------------|--------------------------|
| newTelegram | BG_Types_Pkg::Telegram_T | |
| inoldHeaderArray | BG_Types_Pkg::TelegramHeaderArray_T | |
| inoldAddInfo | BG_Types_Pkg::AdditionalInformation_T | |
| doUpdate | bool | |
| inCollector | BuildBGMessage_Pkg::BGCollector_T | |

Table 13: Outputs of addTelegram

| Name | Type | Comments and Information |
|-----------------|---------------------------------------|--------------------------|
| outBGisComplete | bool | |
| outCollector | BuildBGMessage_Pkg::BGCollector_T | |
| outHeaderArray | BG_Types_Pkg::TelegramHeaderArray_T | |
| outaddInfo | BG_Types_Pkg::AdditionalInformation_T | |

7.1.4.2. Operator Hierarchy

diagram : diagram_addTelegram_1

7.1.4.3. Graphical and Textual Diagrams

7.1.4.3.1. View of diagram_addTelegram_1 (addTelegram)

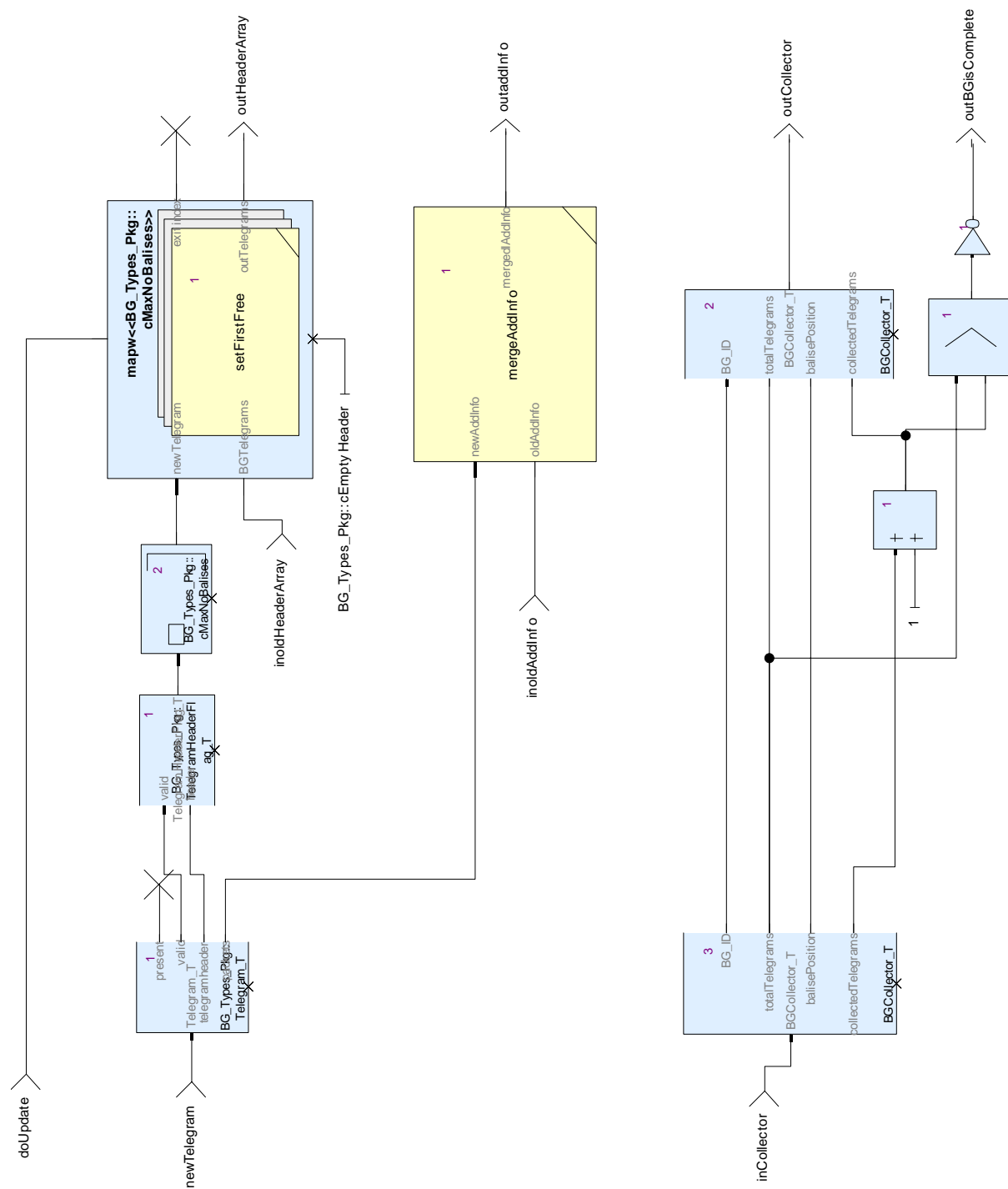


Figure 3: View of diagram_addTelegram_1 (addTelegram)

7.1.5. BuildBGMessage Operator

Declared as **public node**

7.1.5.1. Interface

Table 14: Inputs of BuildBGMessage

| Name | Type | Comments and Information |
|--------------------------|--|--------------------------|
| inDecodedTelegram | BG_Types_Pkg::Telegram_T | |
| reset | bool | |
| incenterOfBalisePosition | BG_Types_Pkg::centerOfBalisePosition_T | |
| inActualOdometry | Obu_BasicTypes_Pkg::odometry_T | |

Table 15: Outputs of BuildBGMessage

| Name | Type | Comments and Information |
|--------------|----------------------------|--------------------------|
| outBGMessage | BG_Types_Pkg::BG_Message_T | |

7.1.5.2. Locals

Table 16: Locals of BuildBGMessage

| Name | Type | Properties | Comments and Information |
|--------------|----------------------|------------------------|--------------------------|
| BGisChanged | bool | | |
| BGisComplete | bool | | |
| locStore | BuildBGMessage_Pkg:: | default cemptyStore | Comments: |

| Name | Type | Properties | | Comments and Information |
|--------------------|--|------------|--------------------------------|---|
| | TelegramStore_T | last | emptyStore | <p>This memory is used to store an additional telegram. The store is needed when:</p> <ul style="list-style-type: none"> - the end of the previous BG is indicated by a new bg <p>In this situation, first the new telegram is stored but not immediately processed. In the same cycle the BG-Message of the now complete balise group is processed. This implies, there might be a balise telegram left over from the previous run of the procedure which needs to be taken care of before being able to handle the next one. Practically, this means:</p> <ul style="list-style-type: none"> - if no (or new odometry info) is present: first empty the store. - if a new telegram is received, swap the telegrams in the store and proceed with the elder telegram. |
| needTelegramStore | bool | | | <p>Comments:</p> <p>This flag is used for showing if the data in the telegram store is still to be used.</p> |
| positionToUse | BG_Types_Pkg::centerOfBalisePosition_T | | | |
| storeBGAddInfo | BG_Types_Pkg::AdditionalInformation_T | default | BG_Types_Pkg::cAddInfo | |
| | | last | BG_Types_Pkg::cAddInfo | |
| storeBGHeaderArray | BG_Types_Pkg::TelegramHeaderArray_T | default | BG_Types_Pkg::emptyHeaderArray | |
| | | last | BG_Types_Pkg::emptyHeaderArray | |
| storeCollector | BuildBGMessage_Pkg::BGCollector_T | default | cCollectorInit | |
| | | last | cCollectorInit | |
| telegramPresent | bool | | | |
| telegramToUse | BG_Types_Pkg::Telegram_T | | | |
| tempBGAddInfo | BG_Types_Pkg::AdditionalInformation_T | default | BG_Types_Pkg::cAddInfo | |

| Name | Type | Properties | | Comments and Information |
|--------------------|-------------------------------------|------------|--------------------------------|--------------------------|
| tempBGHeaderArray | BG_Types_Pkg::TelegramHeaderArray_T | default | BG_Types_Pkg::emptyHeaderArray | |
| tempCollectorStore | BuildBGMessage_Pkg::BGCollector_T | default | cCollectorInit | |

7.1.5.3. Operator Hierarchy

diagram : diagram_BuildBGMessage_1

```

    activate if : IfBlock1
      branch : then
      branch : else
    activate if : IfBlock2
      branch : then
      branch : else
        activate if : IfBlock3
          branch : then
          branch : else

```

7.1.5.4. Graphical and Textual Diagrams

7.1.5.4.1. View of diagram_BuildBGMessage_1 (BuildBGMessage)

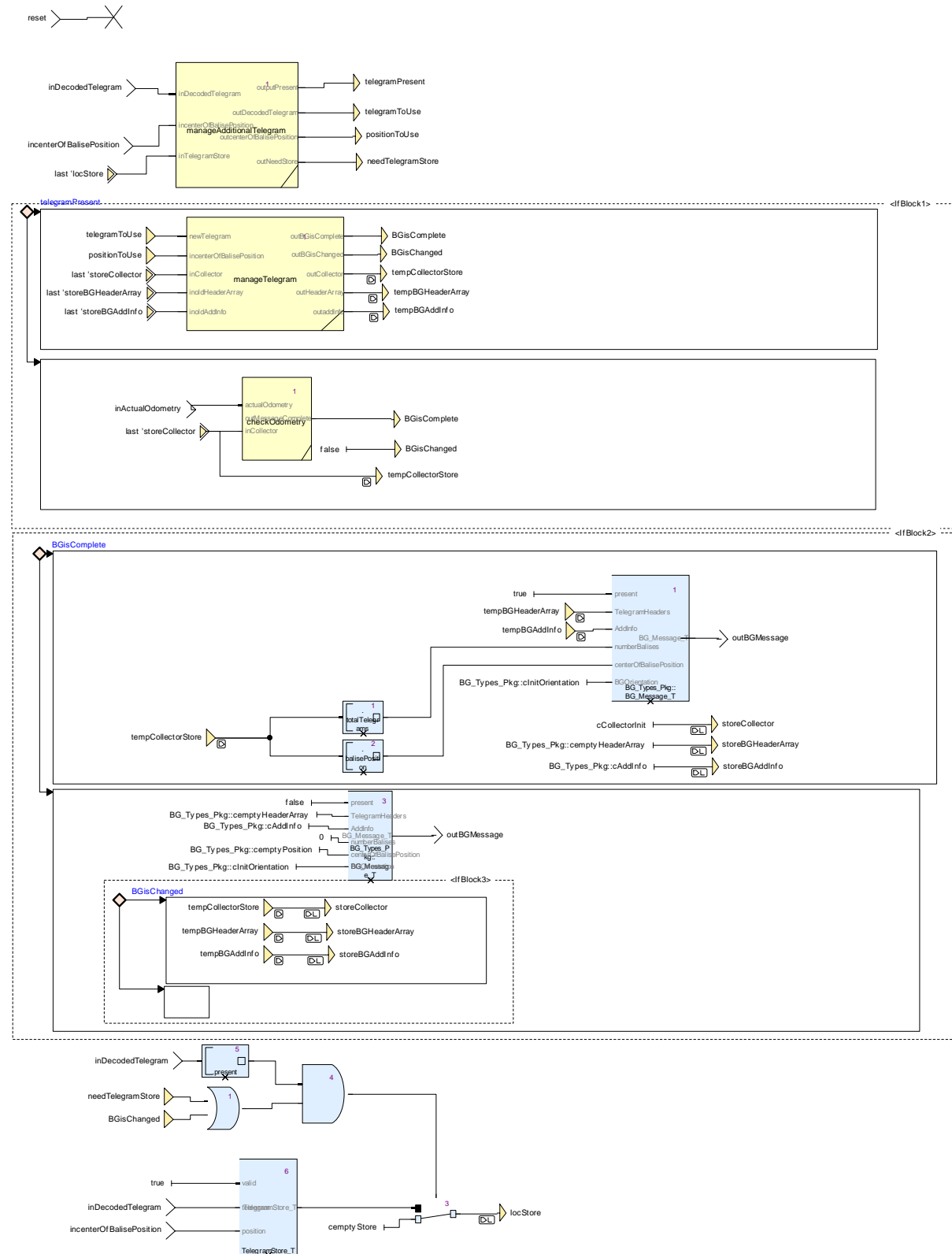


Figure 4: View of diagram_BuildBGMessage_1 (BuildBGMessage)

Table 17: Conditional Blocks of diagram_BuildBGMessage_1

| Conditional Block | Comments and Information |
|--------------------------|--------------------------|
| IfBlock1 | |
| IfBlock2 | |
| IfBlock2: else: IfBlock3 | |

Table 18: Actions of diagram_BuildBGMessage_1

| Conditional Block Action | Comments and Information |
|--------------------------------|--------------------------|
| IfBlock1: then | |
| IfBlock1: else | |
| IfBlock2: then | |
| IfBlock2: else | |
| IfBlock2: else: IfBlock3: then | |
| IfBlock2: else: IfBlock3: else | |

7.1.6. checkInit Operator

Declared as **public function**

7.1.6.1. Comments and Information

checkInit Comments:

- This block check on valid data in the collector. If data has init values collector is set to information from new balise.

7.1.6.2. Interface

Table 19: Inputs of checkInit

| Name | Type | Comments and Information |
|-------------|--|--------------------------|
| newTelegram | BG_Types_Pkg::Telegram_T | |
| inCollector | BuildBGMessage_Pkg::BGCollector_T | |
| inPosition | BG_Types_Pkg::centerOfBalisePosition_T | |

Table 20: Outputs of checkInit

| Name | Type | Properties | Comments and Information |
|--------------|-----------------------------------|------------------------|--------------------------|
| outCollector | BuildBGMessage_Pkg::BGCollector_T | default cCollectorInit | |

7.1.6.3. Locals

Table 21: Locals of checkInit

| Name | Type | Comments and Information |
|-----------|------|--------------------------|
| isDefined | bool | |

7.1.6.4. Operator Hierarchy

diagram : diagram_checkInit_1

activate if : IfBlock1

branch : then

branch : else

7.1.6.5. Graphical and Textual Diagrams

7.1.6.5.1. View of diagram_checkInit_1 (checkInit)

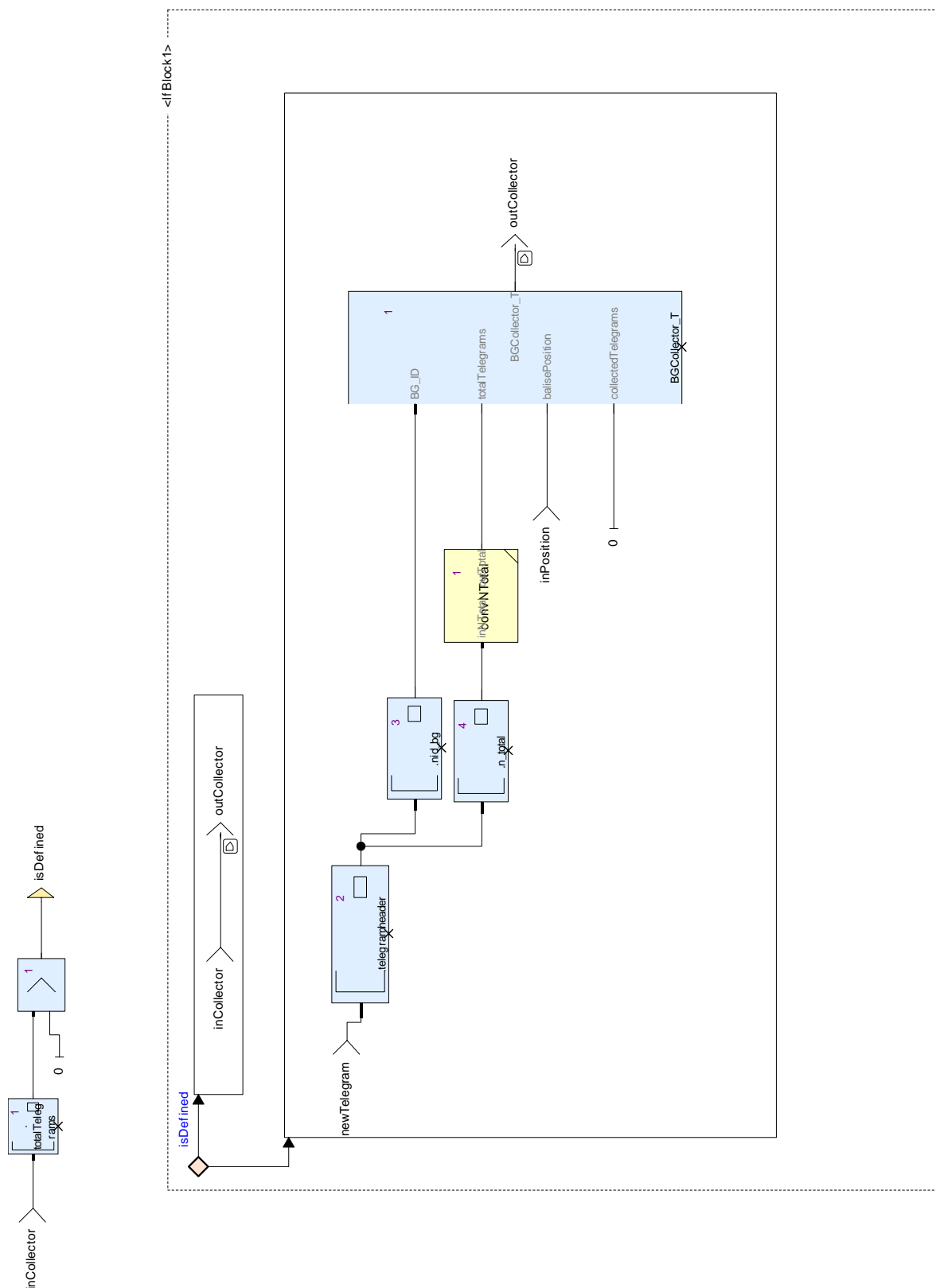


Figure 5: View of diagram_checkInit_1 (checkInit)

Table 22: Conditional Blocks of diagram_checkInit_1

| Conditional Block | Comments and Information |
|-------------------|--------------------------|
| IfBlock1 | |

Table 23: Actions of diagram_checkInit_1

| Conditional Block Action | Comments and Information |
|--------------------------|--------------------------|
| IfBlock1:then | |
| IfBlock1:else | |

7.1.7. checkOdometry Operator

Declared as **public function**

7.1.7.1. Comments and Information

checkOdometry Comments:

- The operator checks whether the absolute distance between two odometry values is less than cMaxDistance.
- The check is needed to determine whether the antenna of the train is still in the allowed range for collecting balises in a balise group.
- The check is requested in section 3.16.2 . Details are defined in subset 40 section 4.1.1.2.

7.1.7.2. Interface

Table 24: Inputs of checkOdometry

| Name | Type | Comments and Information |
|----------------|-----------------------------------|--------------------------|
| actualOdometry | Obu_BasicTypes_Pkg::odometry_T | |
| inCollector | BuildBGMessage_Pkg::BGCollector_T | |

Table 25: Outputs of checkOdometry

| Name | Type | Comments and Information |
|--------------------|------|--------------------------|
| outMessageComplete | bool | |

7.1.7.3. Locals

Table 26: Locals of checkOdometry

| Name | Type | Comments and Information |
|---------|------|--------------------------|
| isValid | bool | |

7.1.7.4. Operator Hierarchy

diagram : diagram_checkOdometry_1

activate if: IfBlock1
branch : then
branch : else

7.1.7.5.1. View of diagram_checkOdometry_1 (checkOdometry)

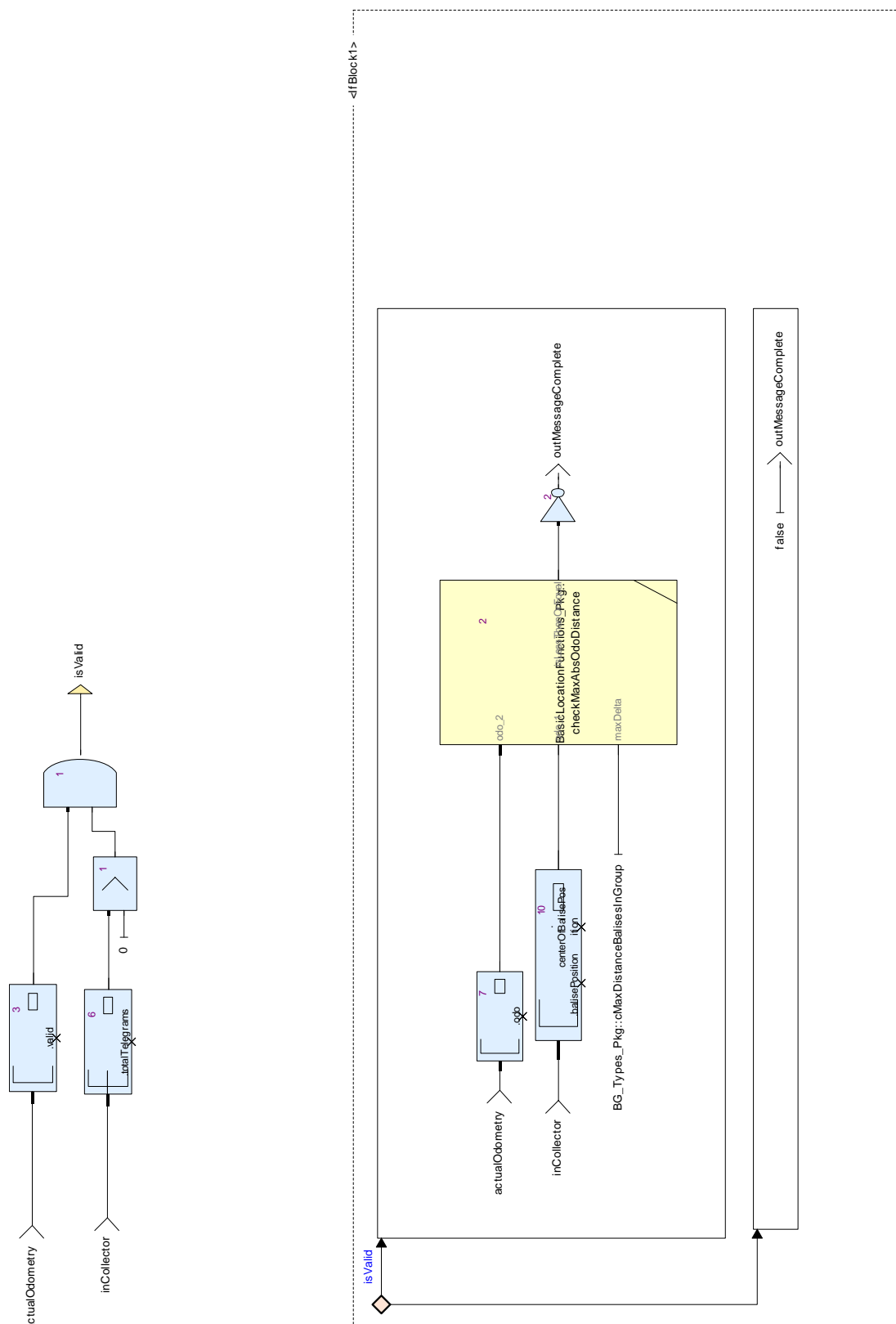


Figure 6: View of diagram_checkOdometry_1 (checkOdometry)

Table 27: Conditional Blocks of diagram_checkOdometry_1

| Conditional Block | Comments and Information |
|-------------------|--------------------------|
| IfBlock1 | |

Table 28: Actions of diagram_checkOdometry_1

| Conditional Block Action | Comments and Information |
|--------------------------|--------------------------|
| IfBlock1:then | |
| IfBlock1:else | |

7.1.8. checkTelegram Operator

Declared as **public function**

7.1.8.1. Comments and Information

checkTelegram Comments:

- Procedure checks for consistency of the input data (valid) and looks for the telegram in the group.

7.1.8.2. Interface

Table 29: Inputs of checkTelegram

| Name | Type | Comments and Information |
|---------------|-------------------------------------|--------------------------|
| newTelegram | BG_Types_Pkg::Telegram_T | |
| BGHeaderArray | BG_Types_Pkg::TelegramHeaderArray_T | |
| BGCollector | BuildBGMessage_Pkg::BGCollector_T | |

Table 30: Outputs of checkTelegram

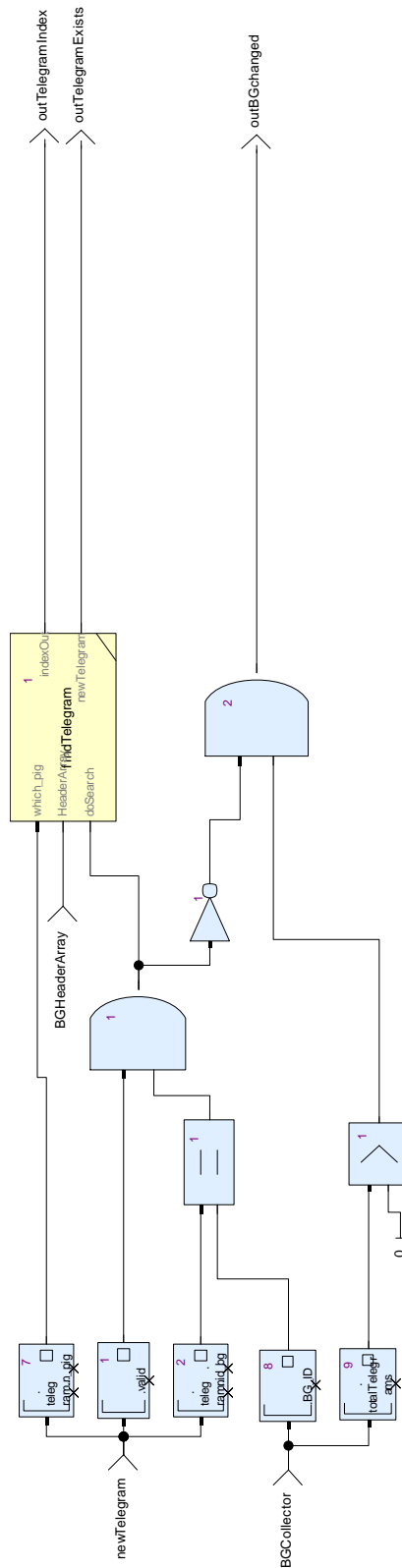
| Name | Type | Comments and Information |
|-------------------|------|--------------------------|
| outTelegramExists | bool | |
| outBGchanged | bool | |
| outTelegramIndex | int | |

7.1.8.3. Operator Hierarchy

diagram : diagram_checkTelegram_1

7.1.8.4. Graphical and Textual Diagrams

7.1.8.4.1. View of diagram_checkTelegram_1 (checkTelegram)



- Provides control data for the balise group collection.

7.1.9. manageAdditionalTelegram Operator

Declared as **public function**

7.1.9.1. Interface

Table 31: Inputs of manageAdditionalTelegram

| Name | Type | Comments and Information |
|--------------------------|--|--------------------------|
| inDecodedTelegram | BG_Types_Pkg::Telegram_T | |
| incenterOfBalisePosition | BG_Types_Pkg::centerOfBalisePosition_T | |
| inTelegramStore | BuildBGMessage_Pkg::TelegramStore_T | |

Table 32: Outputs of manageAdditionalTelegram

| Name | Type | Comments and Information |
|---------------------------|--|--------------------------|
| outputPresent | bool | |
| outDecodedTelegram | BG_Types_Pkg::Telegram_T | |
| outcenterOfBalisePosition | BG_Types_Pkg::centerOfBalisePosition_T | |
| outNeedStore | bool | |

7.1.9.2. Locals

Table 33: Locals of manageAdditionalTelegram

| Name | Type | Comments and Information |
|------------|------|--------------------------|
| storeValid | bool | |

7.1.9.3. Operator Hierarchy

diagram : diagram_manageAdditionalTelegram_1

7.1.9.4. Graphical and Textual Diagrams

7.1.9.4.1. View of diagram_manageAdditionalTelegram_1 (manageAdditionalTelegram)

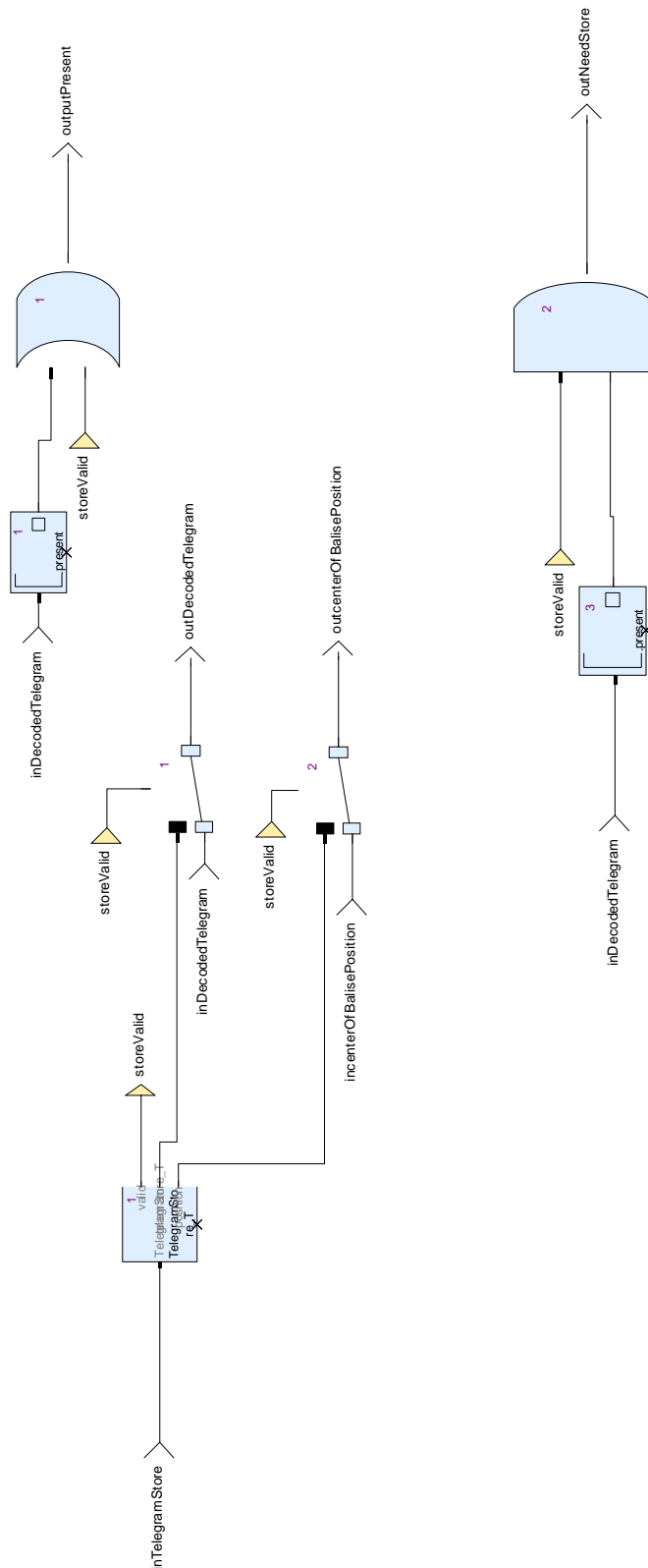


Figure 8: View of diagram_manageAdditionalTelegram_1 (manageAdditionalTelegram)

7.1.10. manageTelegram Operator

Declared as **public function**

7.1.10.1. Interface

Table 34: Inputs of manageTelegram

| Name | Type | Comments and Information |
|--------------------------|--|--------------------------|
| newTelegram | BG_Types_Pkg::Telegram_T | |
| incenterOfBalisePosition | BG_Types_Pkg::centerOfBalisePosition_T | |
| inCollector | BuildBGMessage_Pkg::BGCollector_T | |
| inoldHeaderArray | BG_Types_Pkg::TelegramHeaderArray_T | |
| inoldAddInfo | BG_Types_Pkg::AdditionalInformation_T | |

Table 35: Outputs of manageTelegram

| Name | Type | Comments and Information |
|-----------------|---------------------------------------|--------------------------|
| outBGisComplete | bool | |
| outBGisChanged | bool | |
| outCollector | BuildBGMessage_Pkg::BGCollector_T | |
| outHeaderArray | BG_Types_Pkg::TelegramHeaderArray_T | |
| outaddInfo | BG_Types_Pkg::AdditionalInformation_T | |

7.1.10.2. Operator Hierarchy

diagram : diagram_manageTelegram_1

7.1.10.3. Graphical and Textual Diagrams

7.1.10.3.1. View of diagram_manageTelegram_1 (manageTelegram)

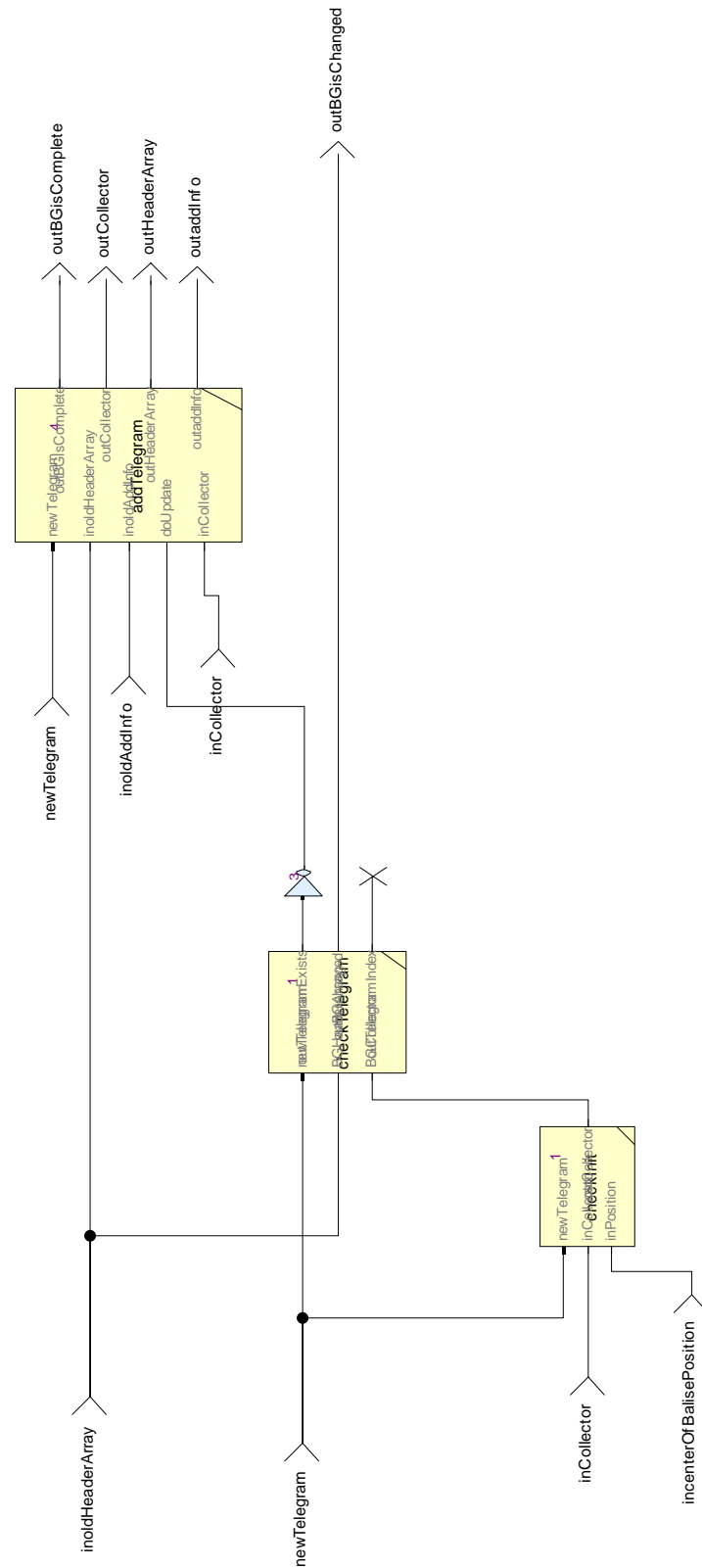


Figure 9: View of diagram_manageTelegram_1 (manageTelegram)

7.1.11. memBGMessage Operator

Declared as **public node**

7.1.11.1. Interface

Table 36: Inputs of memBGMessage

| Name | Type | Comments and Information |
|--------------------|---------------------------------------|--------------------------|
| reset | bool | |
| updatedHeaderArray | BG_Types_Pkg::TelegramHeaderArray_T | |
| updatedAddInfo | BG_Types_Pkg::AdditionalInformation_T | |
| storeInfo | bool | |

Table 37: Outputs of memBGMessage

| Name | Type | Comments and Information |
|-------------------|---------------------------------------|--------------------------|
| actualHeaderArray | BG_Types_Pkg::TelegramHeaderArray_T | |
| actualAddInfo | BG_Types_Pkg::AdditionalInformation_T | |

7.1.11.2. Operator Hierarchy

diagram : diagram_memBGMessage_1

7.1.11.3. Graphical and Textual Diagrams

7.1.11.3.1. View of diagram_memBGMessage_1 (memBGMessage)

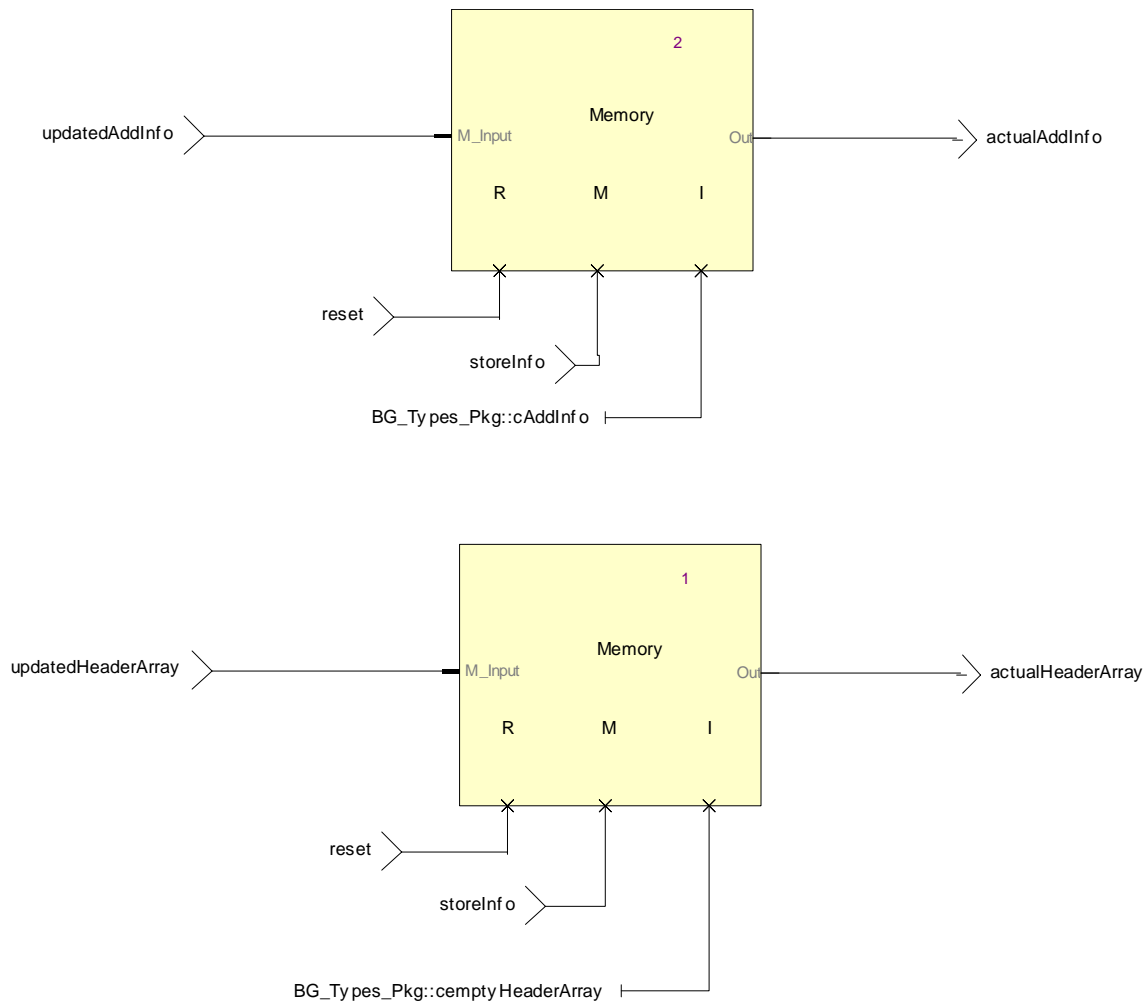


Figure 10: View of diagram_memBGMessage_1 (memBGMessage)

diagram_memBGMessage_1 Comments:

- Provides control data for the balise group collection.

7.2. BuildBGMessage_Pkg: : BaliseSupport Package

7.2.1. Constants

Table 38: Public Constants of BaliseSupport

| Name | Type | Value | Comments and Information |
|-------------|------|-------|--|
| cMaxLinking | int | 31 | Comments: Value corresponds to 5 bit adressing |

7.2.2. convNTotal Operator

Declared as **public function**

7.2.2.1. Interface

Table 39: Inputs of convNTotal

| Name | Type | Comments and Information |
|----------|---------|--------------------------|
| inNTotal | N_TOTAL | |

Table 40: Outputs of convNTotal

| Name | Type | Comments and Information |
|----------|------|--------------------------|
| outTotal | int | |

7.2.2.2. Operator Hierarchy

diagram : diagram_convNTotal_1

activate if : IfBlock1

branch : then

branch : else

branch : then

branch : else

branch : then

branch : else

branch : then

branch : else

branch : then

branch : else

branch : then

branch : else

branch : then

branch : else

branch : then

branch : else

7.2.2.3. Graphical and Textual Diagrams

7.2.2.3.1. View of diagram_convNTotal_1 (convNTotal)

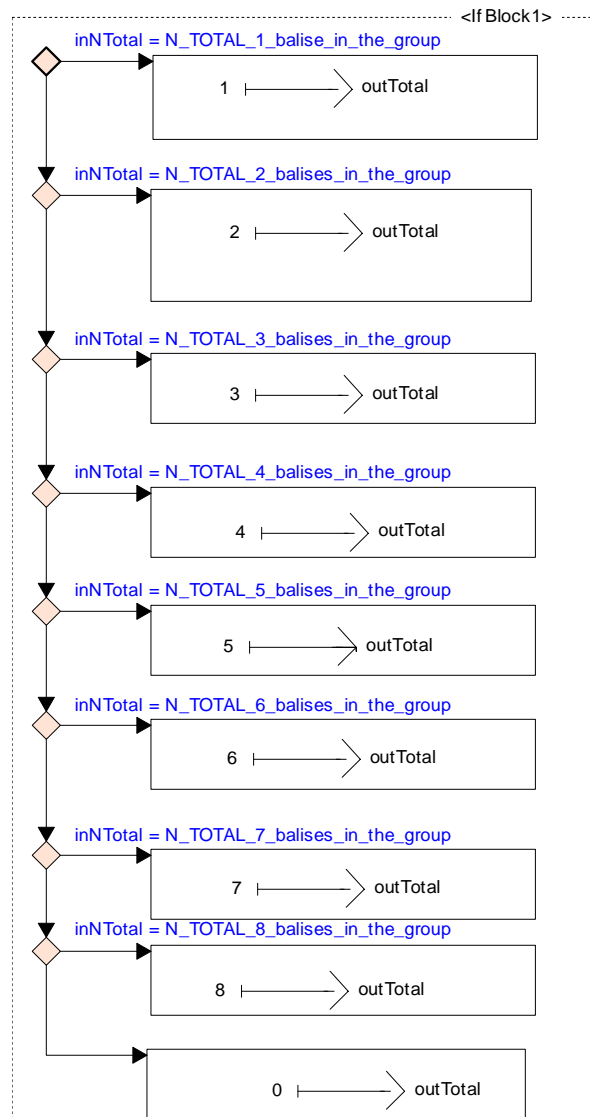


Figure 11: View of diagram_convNTotal_1 (convNTotal)

Table 41: Conditional Blocks of diagram_convNTotal_1

| Conditional Block | Comments and Information |
|-------------------|--------------------------|
| IfBlock1 | |

Table 42: Actions of diagram_convNTotal_1

| Conditional Block Action | Comments and Information |
|--|--------------------------|
| IfBlock1: then | |
| IfBlock1: else: then | |
| IfBlock1: else: else: then | |
| IfBlock1: else: else: else: then | |
| IfBlock1: else: else: else: else: then | |
| IfBlock1: else: else: else: else: else: then | |

| Conditional Block Action | Comments and Information |
|--|--------------------------|
| IfBlock1: else: else: else: else: else: else: the n | |
| IfBlock1: else: else: else: else: else: else: else : then | |
| IfBlock1: else: else: else: else: else: else: else : else | |

7.2.3. findTelegram Operator

Declared as **public function**

7.2.3.1. Interface

Table 43: Inputs of findTelegram

| Name | Type | Comments and Information |
|-------------|---|--------------------------|
| which_pig | N_PIG | |
| HeaderArray | BG_Types_Pkg::Telegr amHeaderArray_T | |
| doSearch | bool | |

Table 44: Outputs of findTelegram

| Name | Type | Comments and Information |
|-------------|------|--------------------------|
| indexOut | int | |
| newTelegram | bool | |

7.2.3.2. Locals

Table 45: Locals of findTelegram

| Name | Type | Comments and Information |
|-------|------|--------------------------|
| valid | bool | |

7.2.3.3. Operator Hierarchy

diagram : diagram_findTelegram_1

activate if : IfBlock1

branch : then

branch : else

7.2.3.4.1. View of diagram_findTelegram_1 (findTelegram)

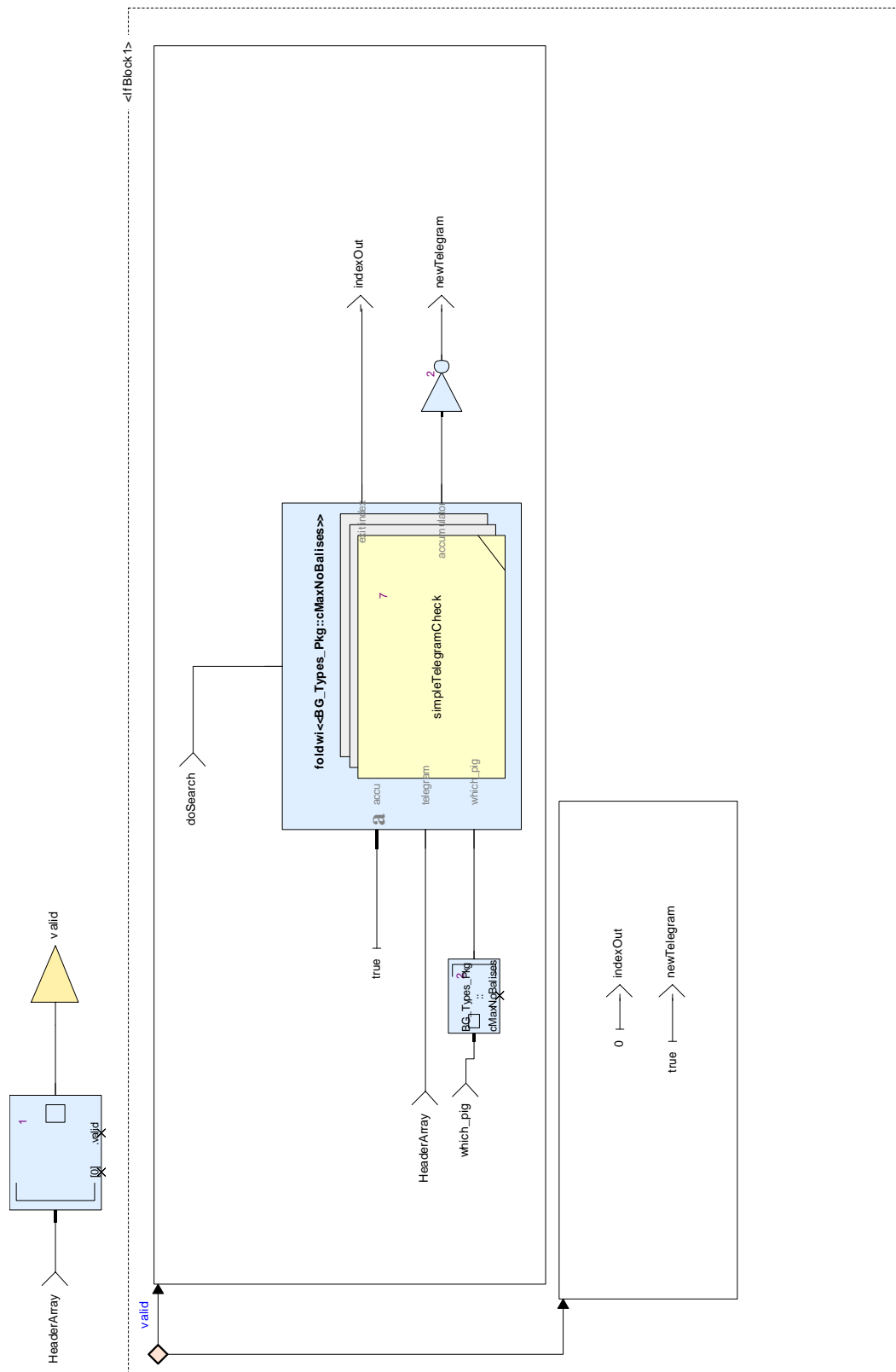


Figure 12: View of diagram_findTelegram_1 (findTelegram)

Table 46: Conditional Blocks of diagram_findTelegram_1

| Conditional Block | Comments and Information |
|-------------------|--------------------------|
| IfBlock1 | |

Table 47: Actions of diagram_findTelegram_1

| Conditional Block Action | Comments and Information |
|--------------------------|--------------------------|
| IfBlock1: then | |
| IfBlock1: else | |

7.2.4. mergeAddInfo Operator

Declared as **public function**

7.2.4.1. Comments and Information

mergeAddInfo Comments:

- This function combines packets received in the telegrams of a balise group.
- The function is limited to the packets used in the respective scope of the model:
 - - linking packet (5).
 -
- The behaviour is according to the subset 26, section
 - - 8.4.2 (rules for balise telegrams) and
 - - 8.4.1 (multiplicity of packets in a balise group message).
- We interpret the term "message" in this context as a balise message consisting of several telegrams. This implies in general, only single packets are to be expected for the whole balise group message (respecting documented exceptions).

7.2.4.2. Interface

Table 48: Inputs of mergeAddInfo

| Name | Type | Comments and Information |
|------------|---------------------------------------|--------------------------|
| newAddInfo | BG_Types_Pkg::AdditionalInformation_T | |
| oldAddInfo | BG_Types_Pkg::AdditionalInformation_T | |

Table 49: Outputs of mergeAddInfo

| Name | Type | Comments and Information |
|---------------|---------------------------------------|--------------------------|
| mergedAddInfo | BG_Types_Pkg::AdditionalInformation_T | |

7.2.4.3. Operator Hierarchy

diagram : diagram_mergeAddInfo_1

7.2.4.4.1. View of diagram_mergeAddInfo_1 (mergeAddInfo)

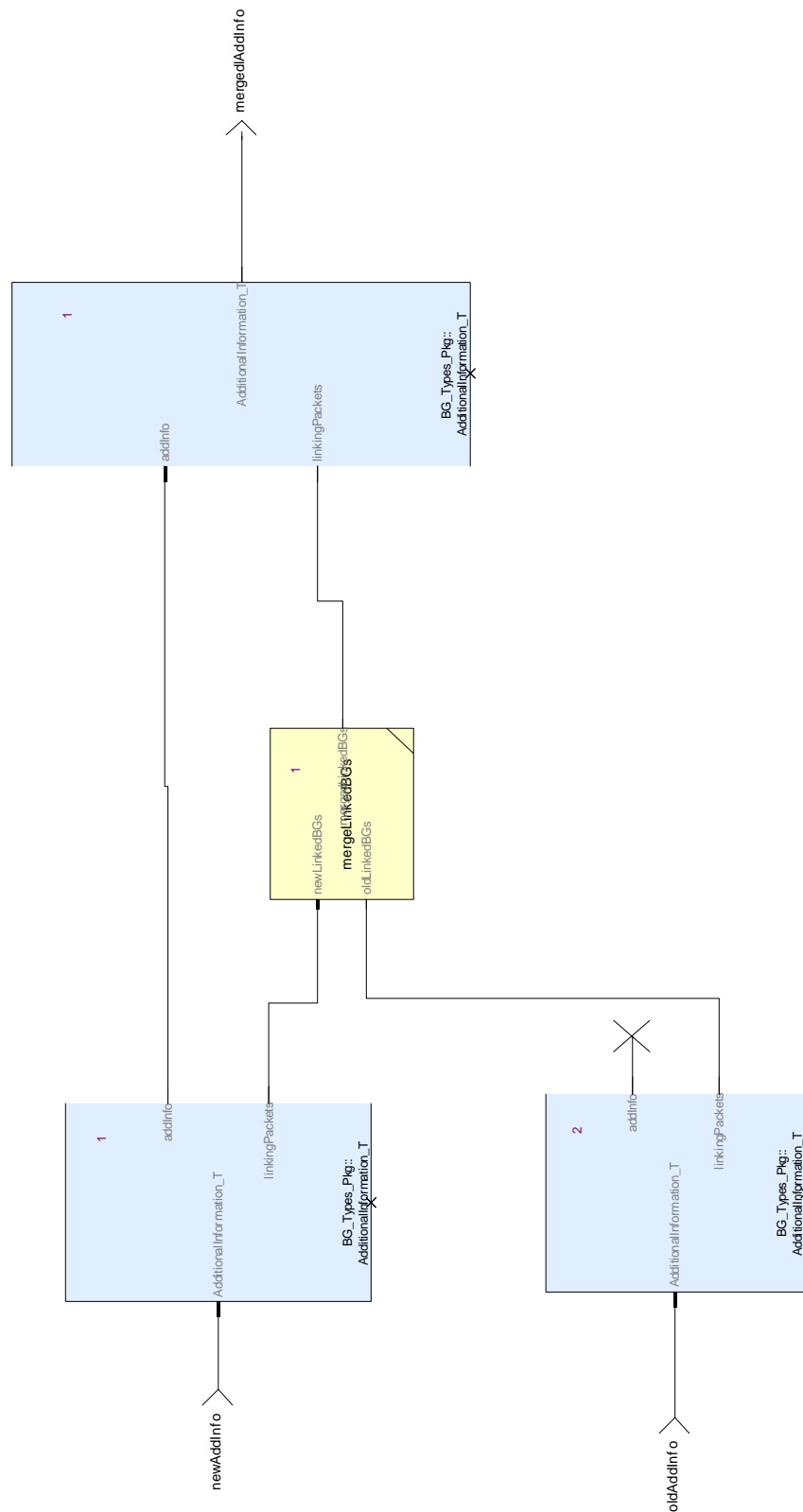


Figure 13: View of diagram_mergeAddInfo_1 (mergeAddInfo)

7.2.5. mergeLinkedBGs Operator

Declared as **public function**

7.2.5.1. Comments and Information

mergeLinkedBGs Comments:

- This information is made up of the linking packet (5) of the btm
- The linking is a list of variable size.
- According to my understanding of the standard the package only appears once in a message and is not allowed to be split across telegrams.
- Therefore, no special procedure for copying is needed.
- (only replace whole list if already received entry is not valid).

7.2.5.2. Interface

Table 50: Inputs of mergeLinkedBGs

| Name | Type | Comments and Information |
|--------------|---------------------------|--------------------------|
| newLinkedBGs | BG_Types_Pkg::LinkedBGs_T | |
| oldLinkedBGs | BG_Types_Pkg::LinkedBGs_T | |

Table 51: Outputs of mergeLinkedBGs

| Name | Type | Comments and Information |
|-----------------|---------------------------|--------------------------|
| mergedLinkedBGs | BG_Types_Pkg::LinkedBGs_T | |

7.2.5.3. Operator Hierarchy

diagram : diagram_mergeLinkedBGs_1

7.2.5.4. Graphical and Textual Diagrams

7.2.5.4.1. View of diagram_mergeLinkedBGs_1 (mergeLinkedBGs)

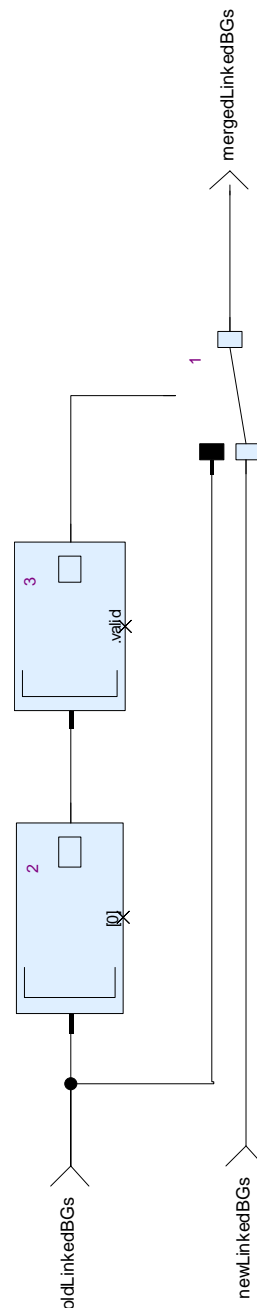


Figure 14: View of diagram_mergeLinkedBGs_1 (mergeLinkedBGs)

7.2.6. setFirstFree Operator

Declared as **public function**

7.2.6.1. Interface

Table 52: Inputs of setFirstFree

| Name | Type | Comments and Information |
|-------------|------------------------------------|--------------------------|
| newTelegram | BG_Types_Pkg::TelegramHeaderFlag_T | |

| Name | Type | Comments and Information |
|-------------|------------------------------------|--------------------------|
| BGTelegrams | BG_Types_Pkg::TelegramHeaderFlag_T | |

Table 53: Outputs of setFirstFree

| Name | Type | Comments and Information |
|--------------|------------------------------------|--------------------------|
| cont | bool | |
| outTelegrams | BG_Types_Pkg::TelegramHeaderFlag_T | |

7.2.6.2. Operator Hierarchy

diagram : diagram_setFirstFree_1

7.2.6.3. Graphical and Textual Diagrams

7.2.6.3.1. View of diagram_setFirstFree_1 (setFirstFree)

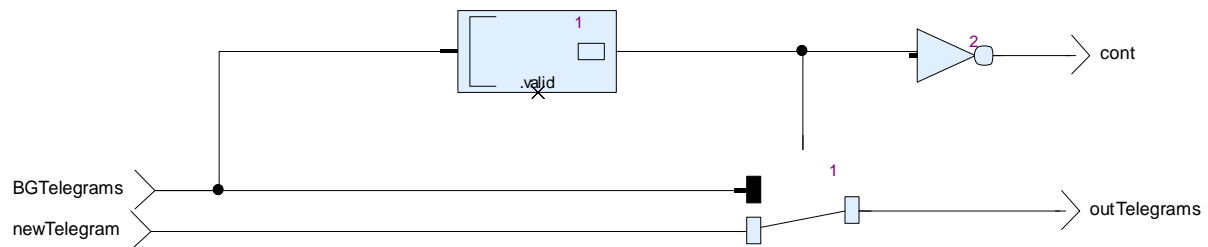


Figure 15: View of diagram_setFirstFree_1 (setFirstFree)

7.2.7. simpleTelegramCheck Operator

Declared as **public function**

7.2.7.1. Interface

Table 54: Inputs of simpleTelegramCheck

| Name | Type | Comments and Information |
|---------------|------------------------------------|--------------------------|
| iteratorIndex | int | |
| accu | bool | |
| telegram | BG_Types_Pkg::TelegramHeaderFlag_T | |
| which_pig | N_PIG | |

Table 55: Outputs of simpleTelegramCheck

| Name | Type | Comments and Information |
|-------|------|--------------------------|
| cont | bool | |
| found | bool | |

7.2.7.2. Operator Hierarchy

diagram : diagram_simpleTelegramCheck_1

7.2.7.3. Graphical and Textual Diagrams

7.2.7.3.1. View of diagram_simpleTelegramCheck_1 (simpleTelegramCheck)

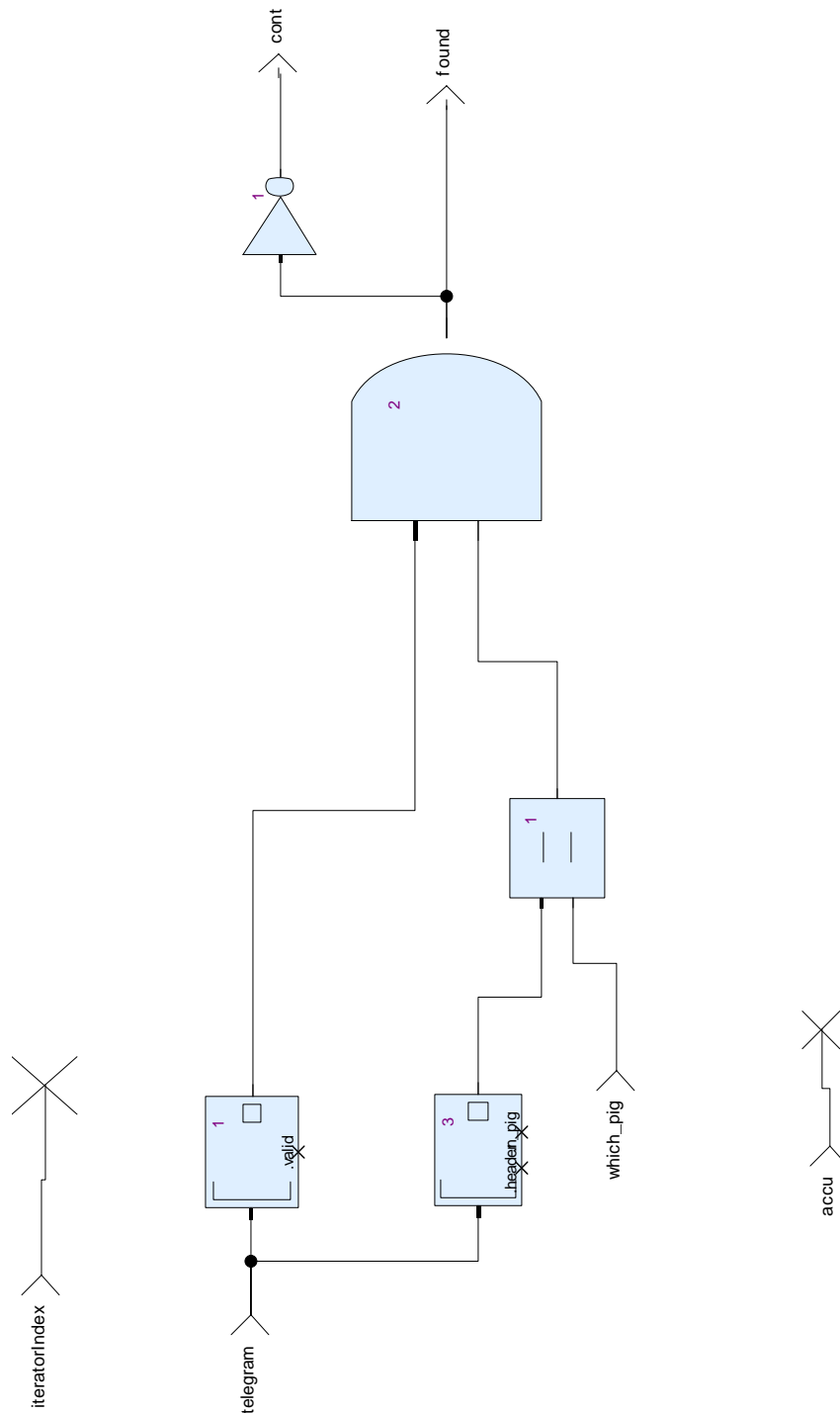


Figure 16: View of diagram_simpleTelegramCheck_1 (simpleTelegramCheck)

8. Project Library: TrainPosition_Types

8.1. TrainPosition_Types_Pck Package

8.1.1. Comments and Information

TrainPosition_Types_Pck Comments:

- This library provides the data type definitions used in train position calculations

Table 56: TrainPosition_Types_Pck Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-06-03 |
| | Version | 00.03.00 |
| | to_c | True |
| Remark_1 | Description | <p>Description : Determines the index of BG in BGs - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke</p> <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

8.1.2. Types

Table 57: Public Types of TrainPosition_Types_Pck

| Name | Definition | Comments and Information |
|-----------------------------|---|--|
| infoFromLinking_T | <pre>{ valid : bool, nid_bg_fromLinkingBG : NID_BG, nid_c_fromLinkingBG : NID_C, expectedLocation : Obu_BasicTypes_Pkg::LocWithInAcc_ T, d_link : Obu_BasicTypes_Pkg::LocWithInAcc_ T, linkingInfo : BG_Types_Pkg::LinkedBG_T }</pre> | <p>Comments: Describes a linked BG as announced from the linking BG. Mainly, this information is taken from the linking packet. nid_bg_fromLinkingBG Comments: ID of the BG, where the linking information originates from expectedLocation Comments: Location, where the BG is expected to be found, calculated from announced linking distance. d_link Comments: Linking distance with inaccuracies, converted from Q_SCALE, D_LINK, Q_LOCACC of the linking packet. linkingInfo Comments: Linking info as announced from the linking BG, where this BG.</p> |
| linkedBGs_asPositionedBGs_T | <pre>TrainPosition_Types_Pck::positionedB G_T ^BG_Types_Pkg::cMaxNoOfLinkedBG s</pre> | <p>Comments: Array of linked balises groups in the format of positioned BGs</p> |
| positionedBG_T | <pre>{ valid : bool, nid_c : NID_C, nid_bg : NID_BG, q_link : Q_LINK, location : Obu_BasicTypes_Pkg::LocWithInAcc_ T, seqNoOnTrack : int, infoFromLinking : TrainPosition_Types_Pck::infoFromLin king_T, infoFromPassing : BG_Types_Pkg::passedBG_T }</pre> | <p>location Comments: The best known location calculated from linking and from passing information seqNoOnTrack Comments: Sequence number: specifies the order of the BG passed or expected to be passed infoFromLinking Comments: If linked, this is the BG info as announced from a linked BG. Most of the data is taken from the linking information. infoFromPassing Comments: If the balise group was passed, this is the relevant information received from the BG.</p> |
| positionedBGs_T | <pre>TrainPosition_Types_Pck::positionedB G_T ^cMaxNoOfStoredBGs</pre> | <p>Comments: All balise groups stored for train position calculation</p> |
| positionErrors_T | <pre>{ outOfMemSpace : bool, passedBG_notFoundWhereExpected : bool, positionCalculation_inconsistent : bool }</pre> | <p>outOfMemSpace Comments: Memory overrun: a passed or announced BG could not be stored passedBG_notFoundWhereExpected Comments: The currently passed linked BG location does not match the expected location positionCalculation_inconsistent Comments: A consistency problem arised during position calculation</p> |

| Name | Definition | Comments and Information |
|-----------------|---|---|
| trainPosition_T | <pre> {valid : bool, timestamp : Obu_BasicTypes_Pkg::T_internal_Type, trainPositionIsUnknown : bool, noCoordinateSystemHasBeenAssigned : bool, trainPosition : Obu_BasicTypes_Pkg::LocWithInAcc_T, estimatedFrontEndPosition : Obu_BasicTypes_Pkg::Location_T, minSafeFrontEndPosition : Obu_BasicTypes_Pkg::Location_T, maxSafeFrontEndPosition : Obu_BasicTypes_Pkg::Location_T, nid_LRBG : NID_BG, nid_PrivLRB : NID_PRIVLRBG, nominalOrReverseToLRBG : Q_DLRBG, trainOrientationToLRBG : Q_DIRLRBG, trainRunningDirectionToLRBG : Q_DIRTRAIN, speed : Obu_BasicTypes_Pkg::Speed_T} </pre> | <p>Comments:</p> <p>3.6.1.3 trainPositionIsUnknown</p> <p>Comments:</p> <p>3.6.3.1.3.1 noCoordinateSystemHasBeenAssigned</p> <p>Comments:</p> <p>3.4.2, 3.6.3.1.4: Every balise group has its own co-ordinate system</p> <p>trainPosition Comments:</p> <p>The calculated train position with inaccuracies.#</p> <p>estimatedFrontEndPosition</p> <p>Comments:</p> <p>3.6.4.4 a): Absolute train front end position since system start</p> <p>minSafeFrontEndPosition</p> <p>Comments:</p> <p>3.6.4.4 c) :Minimum safe front end position</p> <p>maxSafeFrontEndPosition</p> <p>Comments:</p> <p>3.6.4.4.b) :Maximum safe front end position</p> <p>nid_LRBG Comments:</p> <p>Identity of last relevant balise group</p> <p>nid_PrivLRB Comments:</p> <p>Identity of previous LRBG (7.4.3.2, 7.5.1.94), for position report based on 2 balise groups</p> <p>nominalOrReverseToLRBG</p> <p>Comments:</p> <p>7.5.1.106: Q_DLRBG: Qualifier telling on which side of the LRBG the estimated front end is</p> <p>trainOrientationToLRBG</p> <p>Comments:</p> <p>3.6.1.3: Orientation of the train in relation to the direction of the LRBG</p> <p>trainRunningDirectionToLRBG</p> <p>Comments:</p> <p>3.6.1.3: Direction of train movement in relation to the LRBG orientation</p> <p>speed Comments:</p> <p>Actual train speed</p> |

| Name | Definition | Comments and Information |
|---------------------|---|---|
| trainPositionInfo_T | {valid : bool, timestamp : Obu_BasicTypes_Pkg::T_internal_Type, trainPosition : Obu_BasicTypes_Pkg::LocWithInAcc_T, trainPositionDerivedFromLastLinkedBG : Obu_BasicTypes_Pkg::LocWithInAcc_T, trainPositionDerivedFromLastUnlinkedBG : Obu_BasicTypes_Pkg::LocWithInAcc_T, lastPassedLinkedBG : TrainPosition_Types_Pck::positionedBG_T, lastPassedUnlinkedBG : TrainPosition_Types_Pck::positionedBG_T, speed : Obu_BasicTypes_Pkg::Speed_T} | trainPosition Comments: The best known train position trainPositionDerivedFromLastLinkedBG Comments: The train position measured by odometry behind the position of the last passed linked BG trainPositionDerivedFromLastUnlinkedBG Comments: The train position measured by odometry behind the position of the last passed unlinked BG lastPassedLinkedBG Comments: The last passed linked BG lastPassedUnlinkedBG Comments: The last passed unlinked BG speed Comments: Actual train speed |
| trainProperties_T | {nid_engine : NID_ENGINE, nid_operational : NID_OPERATIONAL, l_train : L_TRAIN, d_baliseAntenna_2_frontend : Obu_BasicTypes_Pkg::LocWithInAcc_T, d_frontend_2_rearend : Obu_BasicTypes_Pkg::LocWithInAcc_T} | Comments: Static train properties necessary for train position calculation. nid_engine Comments: 7.5.1.88, Onboard ETCS identity. nid_operational Comments: 7.5.1.92, Train Running Number l_train Comments: 7.5.1.56, train length d_baliseAntenna_2_frontend Comments: Distance from the trains balise antenna to the trains front end. d_frontend_2_rearend Comments: Distance from the trains front end to rear end |

8.1.3. Constants

Table 58: Public Constants of TrainPosition_Types_Pck

| Name | Type | Value | Comments and Information |
|---------------------------|--------------------------------|--|--|
| cMaxNoOfStoredBGs | int | 2 * BG_Types_Pkg::cMaxNoOfLinkedBGs | Comments: Max. number of balise groups stored for position calculation |
| cQ_SCALE_10_cm_resolution | Obu_BasicTypes_Pkg::Location_T | 10 | Comments: 7.5.1.129: Resolution of Q_SCALE::10cm: = 10 cm (Location_Type in cm) |
| cQ_SCALE_10_m_resolution | Obu_BasicTypes_Pkg::Location_T | 1000 | Comments: 7.5.1.129: Resolution of Q_SCALE::10 m: = 1000 cm (Location_Type in cm) |
| cQ_SCALE_1_m_resolution | Obu_BasicTypes_Pkg::Location_T | 100 | Comments: 7.5.1.129: Resolution of Q_SCALE::1 m: = 100 cm (Location_Type in cm) |

| Name | Type | Value | Comments and Information |
|---------------------|--------------------------------|-------|---|
| cQLOCACC_resolution | Obu_BasicTypes_Pkg::Location_T | 100 | Comments: 7.5.1.115: Resolution of Q_LOCACC is in m = 100 cm (Location_Type in cm) |

9. Project Library: BasicLocationFunctions

9.1. BasicLocationFunctions_Pkg Package

9.1.1. Comments and Information

BasicLocationFunctions_Pkg Comments:

- This component provides basic position calculation functions as specified in https://github.com/openETCS/SRS-Analysis/blob/master/System%20Analysis/WorkingRepository/Group4/SUBSET_26_3-6/DetermineTrainLocationProcedures.docx while taking inaccuracies into account.
- ---
- Basic calculation functions for position determination of train and track elements
 - - Name: BasicLocationFunctions.etp
 - - Description: Basic calculation functions for position determination of train and track elements
 - - Copyright Siemens AG, 2014
 - - Licensed under the EUPL V.1.1 (<http://joinup.ec.europa.eu/software/page/eupl/licence-eupl>)
 - - Gist URL: ---
 - - Cryptography: No
 - - Author(s): Uwe Steinke
- The use of this software is limited to non-vital applications.
- It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss.
- THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.

Table 59: BasicLocationFunctions_Pkg Annotations

| Note Name | Attribute | Value |
|-----------|-----------|-----------------------|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |

| Note Name | Attribute | Value |
|-----------|-------------|---|
| Remark_1 | Description | <p>Basic calculation functions for position determination of train and track elements</p> <ul style="list-style-type: none"> - Name: BasicLocationFunctions.etp - Description: Basic calculation functions for position determination of train and track elements - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss.</p> <p>THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

9.1.2. add_2_Distances Operator

Declared as **public function**

9.1.2.1. Comments and Information

add_2_Distances Comments:

- Calculates the sum of 2 distances $\text{dist}_2 + \text{dist}_1$

Table 60: add_2_Distances Annotations

| Note Name | Attribute | Value |
|-----------|-----------|-----------------------|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |

| Note Name | Attribute | Value |
|-----------|-------------|--|
| Remark_1 | Description | <p>Calculates the sum of 2 distances</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

9.1.2.2. Interface

Table 61: Inputs of add_2_Distances

| Name | Type | Comments and Information |
|--------|------------------------------------|--------------------------|
| dist_2 | Obu_BasicTypes_Pkg::LocWithInAcc_T | |
| dist_1 | Obu_BasicTypes_Pkg::LocWithInAcc_T | |

Table 62: Outputs of add_2_Distances

| Name | Type | Comments and Information |
|----------|------------------------------------|--------------------------|
| distance | Obu_BasicTypes_Pkg::LocWithInAcc_T | |

9.1.2.3. Operator Hierarchy

diagram : diagram_add_2_Distances_1

9.1.2.4. Graphical and Textual Diagrams

9.1.2.4.1. View of diagram_add_2_Distances_1 (add_2_Distances)

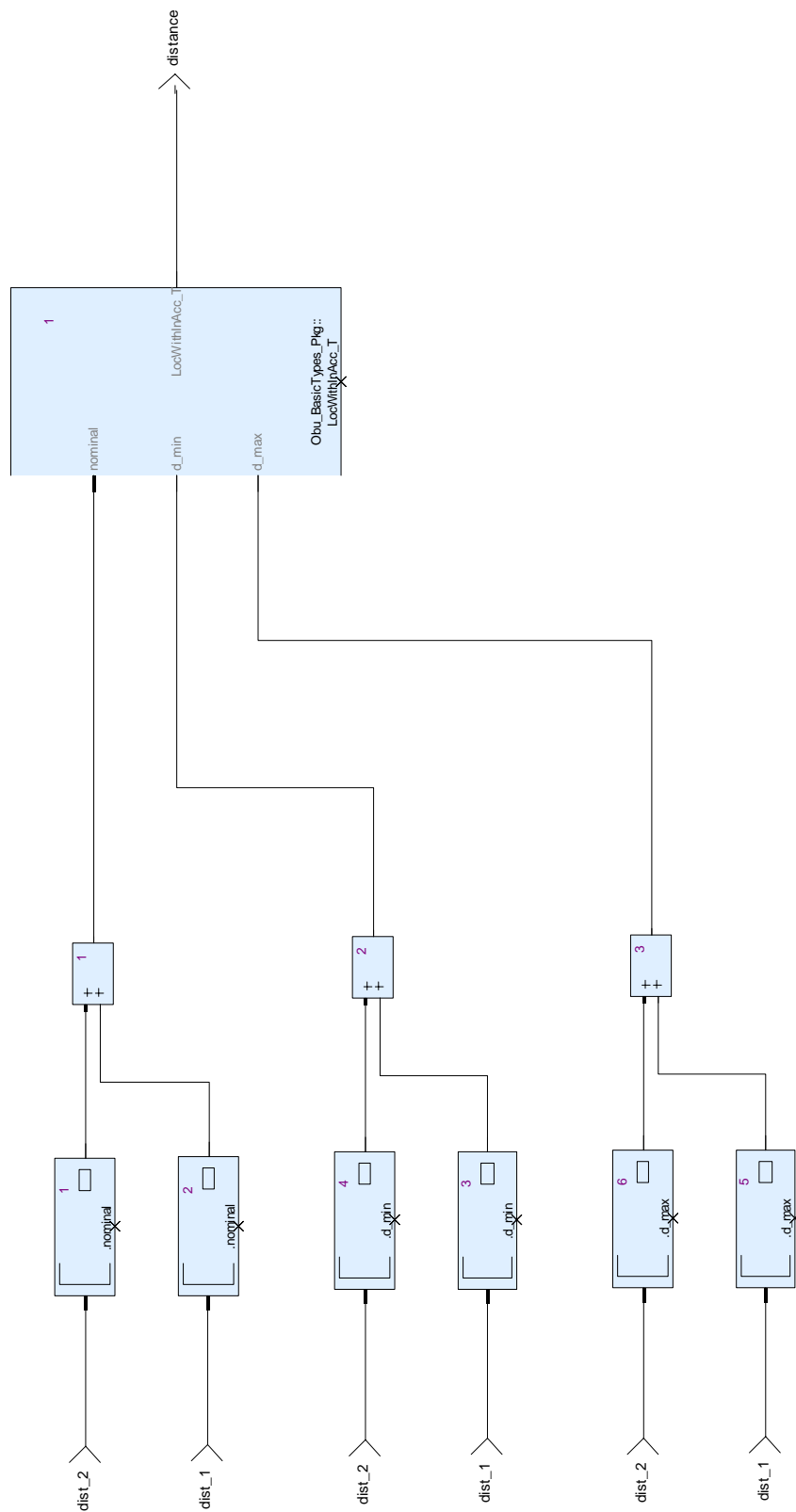


Figure 17: View of diagram_add_2_Distances_1 (add_2_Distances)

9.1.3. add_odo_2_Location Operator

Declared as **public function**

9.1.3.1. Comments and Information

add_odo_2_Location Comments:

- Calculates the target location after a reference location measured by the odometry:
- $\text{location} = \text{refLocation} + (\text{odoValue} - \text{refOdoValue})$.
- Applicable, if a reference location is given and a travel distance behind it is measured with the odometry.

Table 63: add_odo_2_Location Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Calculates the target location after a reference location measured by the odometry</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

9.1.3.2. Interface

Table 64: Inputs of add_odo_2_Location

| Name | Type | Comments and Information |
|-------------|---|---|
| refLocation | Obu_BasicTypes_Pkg::LocWithInAcc_T | Comments: The reference location |
| refOdoValue | Obu_BasicTypes_Pkg::OdometryLocations_T | Comments: The odometry value at refLocation |
| odoValue | Obu_BasicTypes_Pkg::OdometryLocations_T | Comments: The odometry value at the target location "location" |

Table 65: Outputs of add_odo_2_Location

| Name | Type | Comments and Information |
|----------|--|----------------------------------|
| location | Obu_BasicTypes_Pkg:: LocWithInAcc_T | Comments: The target location |

9.1.3.3. Operator Hierarchy

diagram : diagram_add_odo_2_Location_1

9.1.3.4. Graphical and Textual Diagrams

9.1.3.4.1. View of diagram_add_odo_2_Location_1 (add_odo_2_Location)

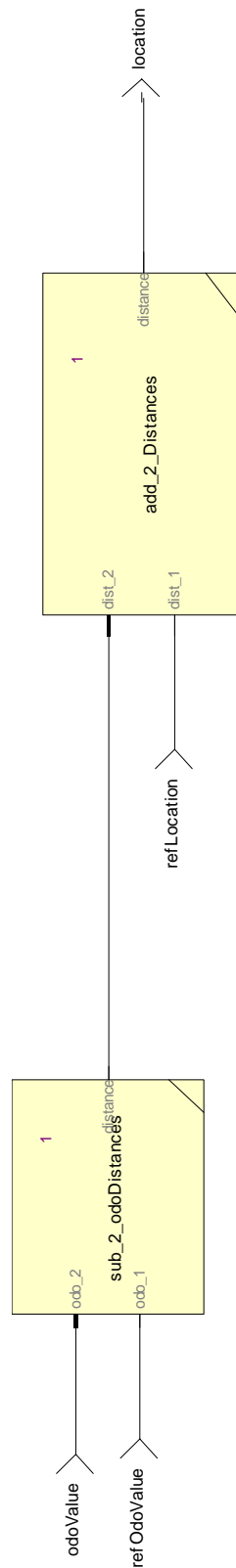


Figure 18: View of diagram_add_odo_2_Location_1 (add_odo_2_Location)

9.1.4. addDistances Operator

Declared as **public function**

9.1.4.1. Comments and Information

addDistances Comments:

- Calculates the sum of an array of distances

Table 66: addDistances Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Calculates the sum of an array of distances</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

9.1.4.2. Interface

Table 67: Inputs of addDistances

| Name | Type | Comments and Information |
|-----------|---|--------------------------|
| distances | Obu_BasicTypes_Pkg::LocWithInAcc_T ^noOfSummands | |

Table 68: Outputs of addDistances

| Name | Type | Comments and Information |
|------|------------------------------------|--------------------------|
| sum | Obu_BasicTypes_Pkg::LocWithInAcc_T | |

Table 69: Size Parameters of addDistances

| Name | Comments and Information |
|--------------|---------------------------------|
| noOfSummands | Comments: Number of summands |

9.1.4.3. Operator Hierarchy

diagram : diagram_sumOfDistances_1

9.1.4.4. Graphical and Textual Diagrams

9.1.4.4.1. View of diagram_sumOfDistances_1 (addDistances)

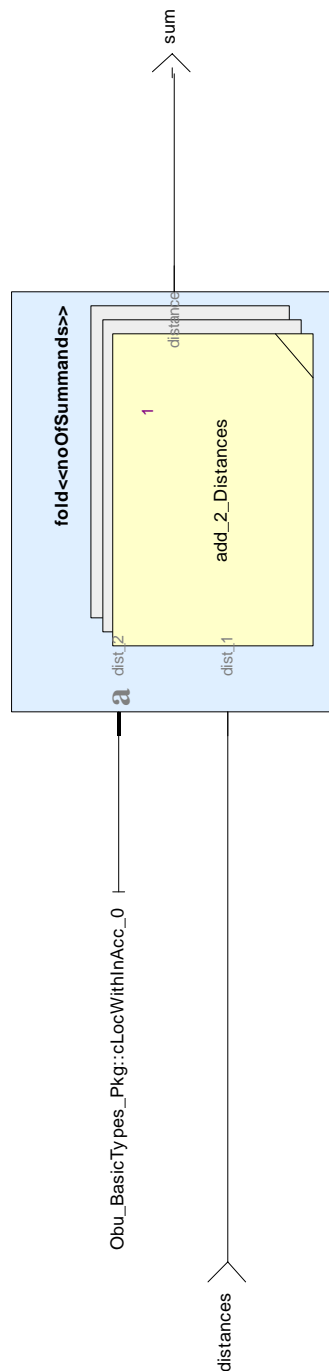


Figure 19: View of diagram_sumOfDistances_1 (addDistances)

9.1.5. addDistancesBetwLinkedElements Operator

Declared as **public function**

9.1.5.1. Comments and Information

addDistancesBetwLinkedElements Comments:

- Calculates the distance between linked elements like linked balise groups by adding their distances,
- Linked elements like balises are – as specified in Subset 026-3.6 – thought to be positioned on an absolutely correct nominal position with a known min/max accuracy around the nominal position.
- The distances of elements not needed in the calculation must be set to 0.

Table 70: addDistancesBetwLinkedElements Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Calculates the distance between linked elements</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

9.1.5.2. Interface

Table 71: Inputs of addDistancesBetwLinkedElements

| Name | Type | Comments and Information |
|-----------|---|--------------------------|
| distances | Obu_BasicTypes_Pkg::LocWithInAcc_T ^noOfLinkedElements | |

Table 72: Outputs of addDistancesBetwLinkedElements

| Name | Type | Comments and Information |
|----------------|------------------------------------|--------------------------|
| sumOfDistances | Obu_BasicTypes_Pkg::LocWithInAcc_T | |

Table 73: Size Parameters of addDistancesBetwLinkedElements

| Name | Comments and Information |
|--------------------|--------------------------|
| noOfLinkedElements | |

9.1.5.3. Operator Hierarchy

diagram : diagram_distanceBetweenLinkedElements_1

9.1.5.4. Graphical and Textual Diagrams

9.1.5.4.1. View of diagram_distanceBetweenLinkedElements_1 (addDistancesBetwLinkedElements)

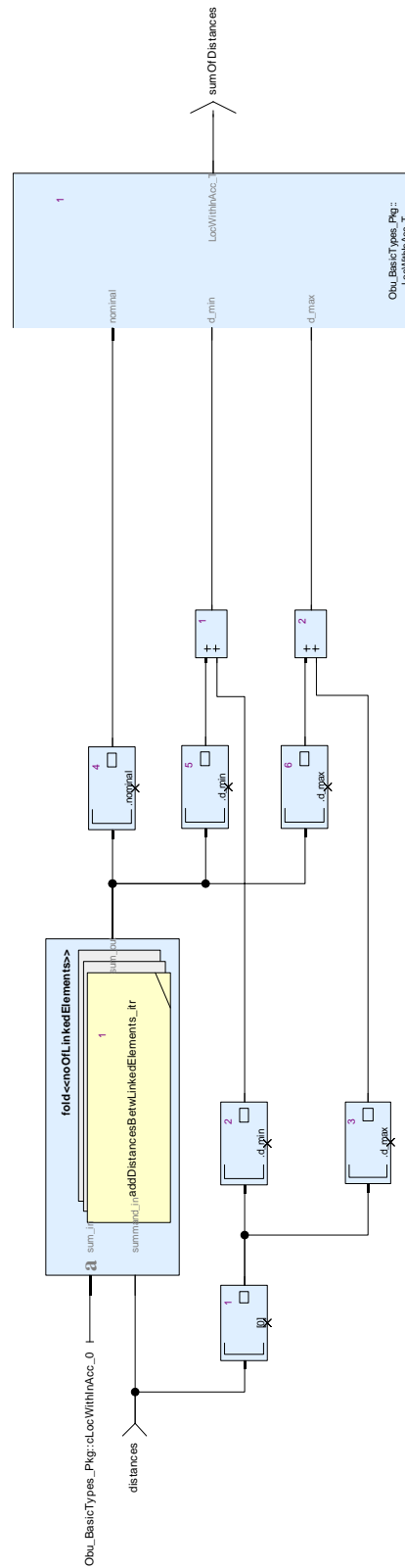


Figure 20: View of diagram_distanceBetweenLinkedElements_1 (addDistancesBetwLinkedElements)

9.1.6. addDistancesBetwLinkedElements_itr Operator

Declared as **private function**

9.1.6.1. Comments and Information

addDistancesBetwLinkedElements_itr Comments:

- distanceBetweenLinkedElements_itr is the iterated function for the distance calculation between linked elements.
- The nominal distances are added.
- d_min and d_max are taken from the summand, if it is $< > 0$ and from the previous sum_in, if $= 0$.
- This assures that the inaccuracies from the last element in the iteration $< > 0$ are forward even if not all iterations are filled with valid data.

Table 74: addDistancesBetwLinkedElements_itr Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>iterated function for the distance calculation between linked elements</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

9.1.6.2. Interface

Table 75: Inputs of addDistancesBetwLinkedElements_itr

| Name | Type | Comments and Information |
|------------|------------------------------------|--------------------------|
| sum_in | Obu_BasicTypes_Pkg::LocWithInAcc_T | |
| summand_in | Obu_BasicTypes_Pkg::LocWithInAcc_T | |

Table 76: Outputs of addDistancesBetwLinkedElements_itr

| Name | Type | Comments and Information |
|---------|--|--------------------------|
| sum_out | Obu_BasicTypes_Pkg:: LocWithInAcc_T | |

9.1.6.3. Operator Hierarchy

diagram : diagram_addDistancesBetwLinkedElements_itr_1

9.1.6.4. Graphical and Textual Diagrams

9.1.6.4.1. View of diagram_addDistancesBetwLinkedElements_itr_1 (addDistancesBetwLinkedElements_itr)

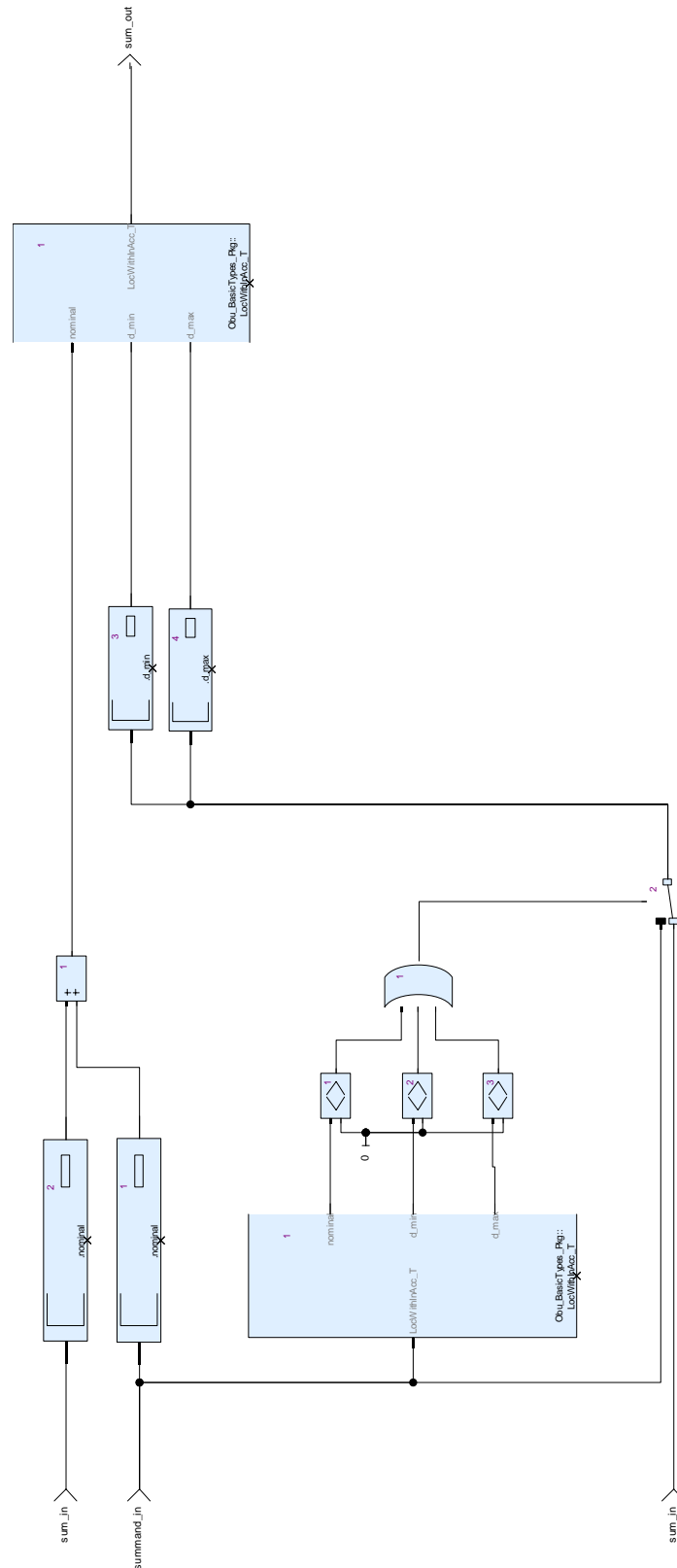


Figure 21: View of diagram_addDistancesBetwLinkedElements_itr_1
(addDistancesBetwLinkedElements_itr)

9.1.7. checkMaxAbsOdoDistance Operator

Declared as **public function**

9.1.7.1. Comments and Information

checkMaxAbsOdoDistance Comments:

- Determines, if the distance between odometry positions `odo_2` and `odo_1` is less than or equal `maxDelta`.
- Please consider the applicable rules for odometry value calculations!

9.1.7.2. Interface

Table 77: Inputs of checkMaxAbsOdoDistance

| Name | Type | Comments and Information |
|-----------------------|--|--------------------------|
| <code>odo_2</code> | <code>Obu_BasicTypes_Pkg::OdometryLocations_T</code> | |
| <code>odo_1</code> | <code>Obu_BasicTypes_Pkg::OdometryLocations_T</code> | |
| <code>maxDelta</code> | <code>Obu_BasicTypes_Pkg::OdometryLocations_T</code> | |

Table 78: Outputs of checkMaxAbsOdoDistance

| Name | Type | Comments and Information |
|--------------------------------|-------------------|--------------------------|
| <code>isLessThanOrEqual</code> | <code>bool</code> | |

9.1.7.3. Operator Hierarchy

diagram : `diagram_checkMaxAbsOdoDistance_1`

9.1.7.4. Graphical and Textual Diagrams

9.1.7.4.1. View of diagram_checkMaxAbsOdoDistance_1 (checkMaxAbsOdoDistance)

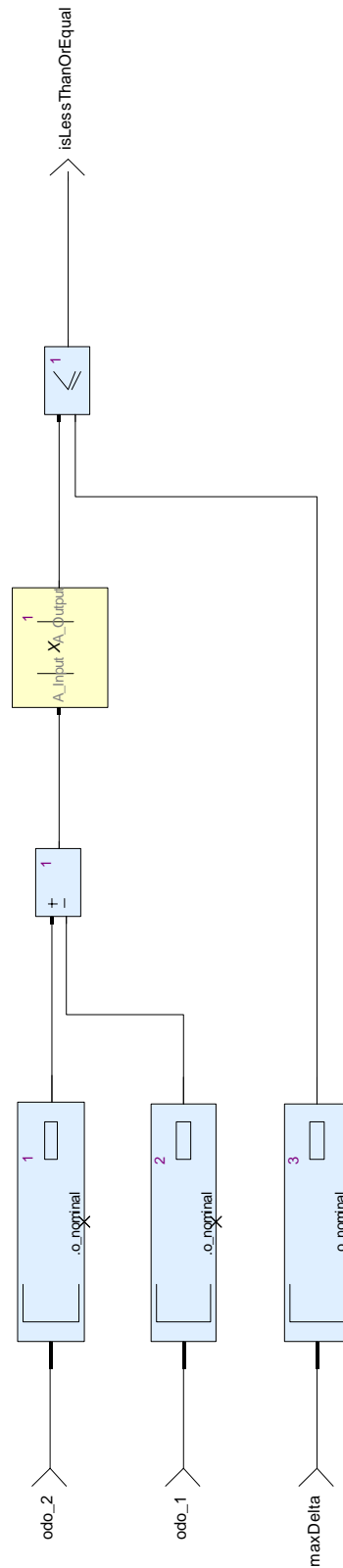


Figure 22: View of diagram_checkMaxAbsOdoDistance_1 (checkMaxAbsOdoDistance)

9.1.8. dTrain2Trackelem_unlinkedBG Operator

Declared as **public function**

9.1.8.1. Comments and Information

dTrain2Trackelem_unlinkedBG Comments:

- Calculates the distance from the actual train position to a track element, that is linked with a previously passed unlinked BG.
- Remark:
- There is no need to determine the distance via a second calculation with reference to the following linked balise group.
- Instead, the input loc_unlinkedBG should be fed via the odoLoc_2_refLocations function, based on two different reference calculations.

Table 79: dTrain2Trackelem_unlinkedBG Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Distance from the actual train position to a track element</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

9.1.8.2. Interface

Table 80: Inputs of dTrain2Trackelem_unlinkedBG

| Name | Type | Comments and Information |
|----------------------------|------------------------------------|---|
| dLink_unlinkedBG2Trackelem | Obu_BasicTypes_Pkg::LocWithInAcc_T | Comments: Linking distance from a previously passed unlinked balise group to the track element |
| loc_unlinkedBG | Obu_BasicTypes_Pkg::LocWithInAcc_T | Comments: Location of a previously passed unlinked balise group |

| Name | Type | Comments and Information |
|----------------|---|---|
| odo_unlinkedBG | Obu_BasicTypes_Pkg:: OdometryLocations_T | Comments: Odometry value at the previously passed unlinked balise group |
| actOdo_train | Obu_BasicTypes_Pkg:: OdometryLocations_T | Comments: Odometry value at the actual train position |

Table 81: Outputs of dTrain2Trackelem_unlinkedBG

| Name | Type | Comments and Information |
|------------------|--|---|
| dTrain2Trackelem | Obu_BasicTypes_Pkg:: LocWithInAcc_T | Comments: Distance from the actual train position to the track element in front |

9.1.8.3. Operator Hierarchy

diagram : diagram_dTrain2Trackelem_unlinkedBG_1

9.1.8.4. Graphical and Textual Diagrams

9.1.8.4.1. View of diagram_dTrain2Trackelem_unlinkedBG_1 (dTrain2Trackelem_unlinkedBG)

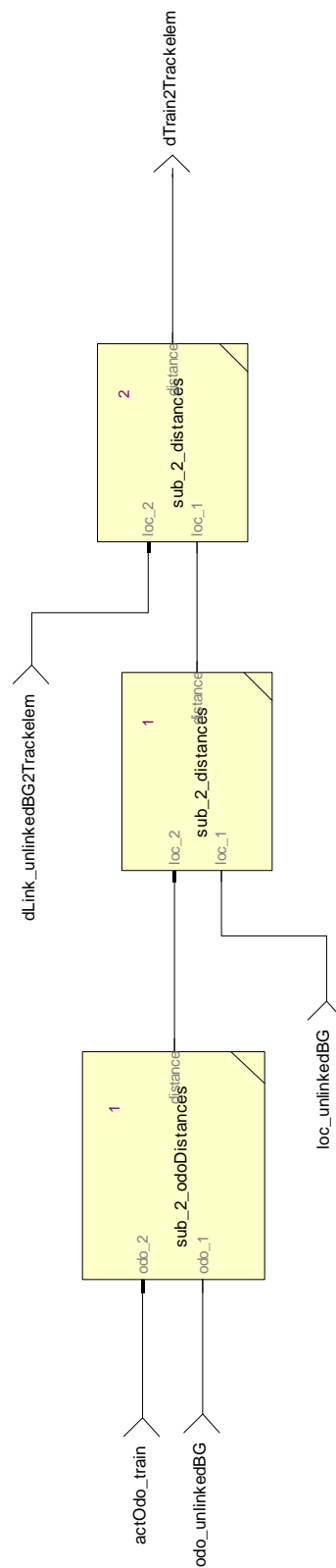


Figure 23: View of diagram_dTrain2Trackelem_unlinkedBG_1 (dTrain2Trackelem_unlinkedBG)

9.1.9. odoLoc_2_refLocations Operator

Declared as **public function**

9.1.9.1. Comments and Information

odoLoc_2_refLocations Comments:

- Determines the location of an element, measured by odometry, with reference to 2 different known reference locations.
- The location of the element can, but must not be necessarily between the two reference locations.
- If the locations, calculated internally from refLoc2 and refLoc1 don't overlap, the resulting location will be selected from refLoc1 alone.
- This function can be used to calculate the location of an unlinked balise group between 2 linked balise groups.

Table 82: odoLoc_2_refLocations Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Determines the location of an element, measured by odometry, with reference to 2 different known reference locations</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

9.1.9.2. Interface

Table 83: Inputs of odoLoc_2_refLocations

| Name | Type | Comments and Information |
|----------|------------------------------------|-----------------------------------|
| refLoc_2 | Obu_BasicTypes_Pkg::LocWithInAcc_T | Comments: Reference location 2 |
| refLoc_1 | Obu_BasicTypes_Pkg::LocWithInAcc_T | Comments: Reference location 1 |

| Name | Type | Comments and Information |
|----------|---|--|
| refOdo_2 | Obu_BasicTypes_Pkg:: OdometryLocations_T | Comments: Odometry value at reference location 2 |
| refOdo_1 | Obu_BasicTypes_Pkg:: OdometryLocations_T | Comments: Odometry value at reference location 1 |
| odo | Obu_BasicTypes_Pkg:: OdometryLocations_T | Comments: Odometry value at the location to be determined |

Table 84: Outputs of odoLoc_2_refLocations

| Name | Type | Comments and Information |
|----------|--|--|
| location | Obu_BasicTypes_Pkg:: LocWithinAcc_T | Comments: The resulting location to be determined |

9.1.9.3. Operator Hierarchy

diagram : diagram_odoLoc_2_refLocations_1

9.1.9.4. Graphical and Textual Diagrams

9.1.9.4.1. View of diagram_odoLoc_2_refLocations_1 (odoLoc_2_refLocations)

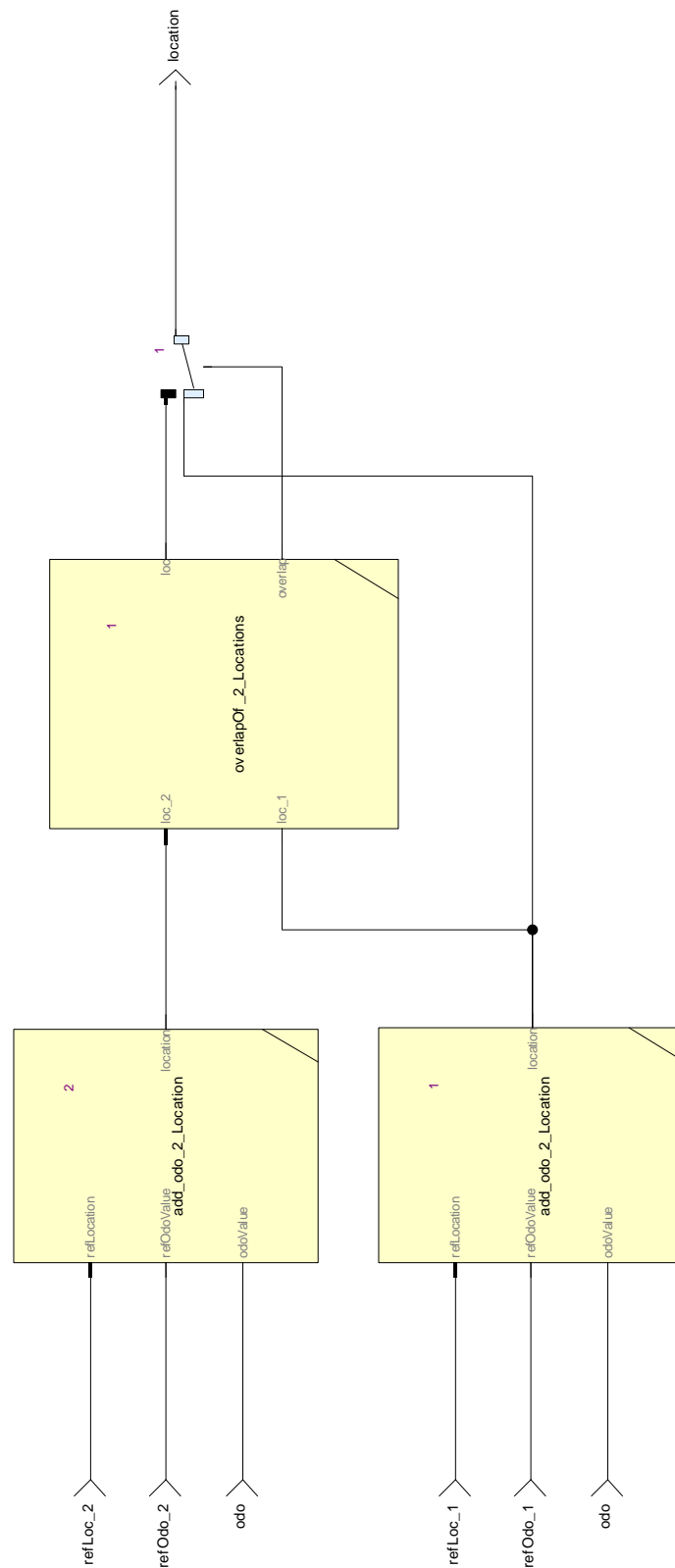


Figure 24: View of diagram_odoLoc_2_refLocations_1 (odoLoc_2_refLocations)

9.1.10. overlapOf_2_Locations Operator

Declared as **public function**

9.1.10.1. Comments and Information

overlapOf_2_Locations Comments:

- Determines the overlapping section of 2 locations, i. e. a more precise location ("best of") than each of the 2 input locations.
- The nominal value of the resulting location is set to the middle of the overlapping section.
- The overlap output is set to true, if an overlapping part exists.
- The overlapping section is seen as the mostAccurateValueOf both locations.

Table 85: overlapOf_2_Locations Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Determines the overlapping section of 2 locations</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

9.1.10.2. Interface

Table 86: Inputs of overlapOf_2_Locations

| Name | Type | Comments and Information |
|-------|------------------------------------|--------------------------|
| loc_2 | Obu_BasicTypes_Pkg::LocWithInAcc_T | |
| loc_1 | Obu_BasicTypes_Pkg::LocWithInAcc_T | |

Table 87: Outputs of overlapOf_2_Locations

| Name | Type | Comments and Information |
|---------|--|--------------------------|
| loc | Obu_BasicTypes_Pkg:: LocWithInAcc_T | |
| overlap | bool | |

9.1.10.3. Operator Hierarchy

diagram : diagram_overlapOf_2_Locations_1

9.1.10.4. Graphical and Textual Diagrams

9.1.10.4.1. View of diagram_overlapOf_2_Locations_1 (overlapOf_2_Locations)

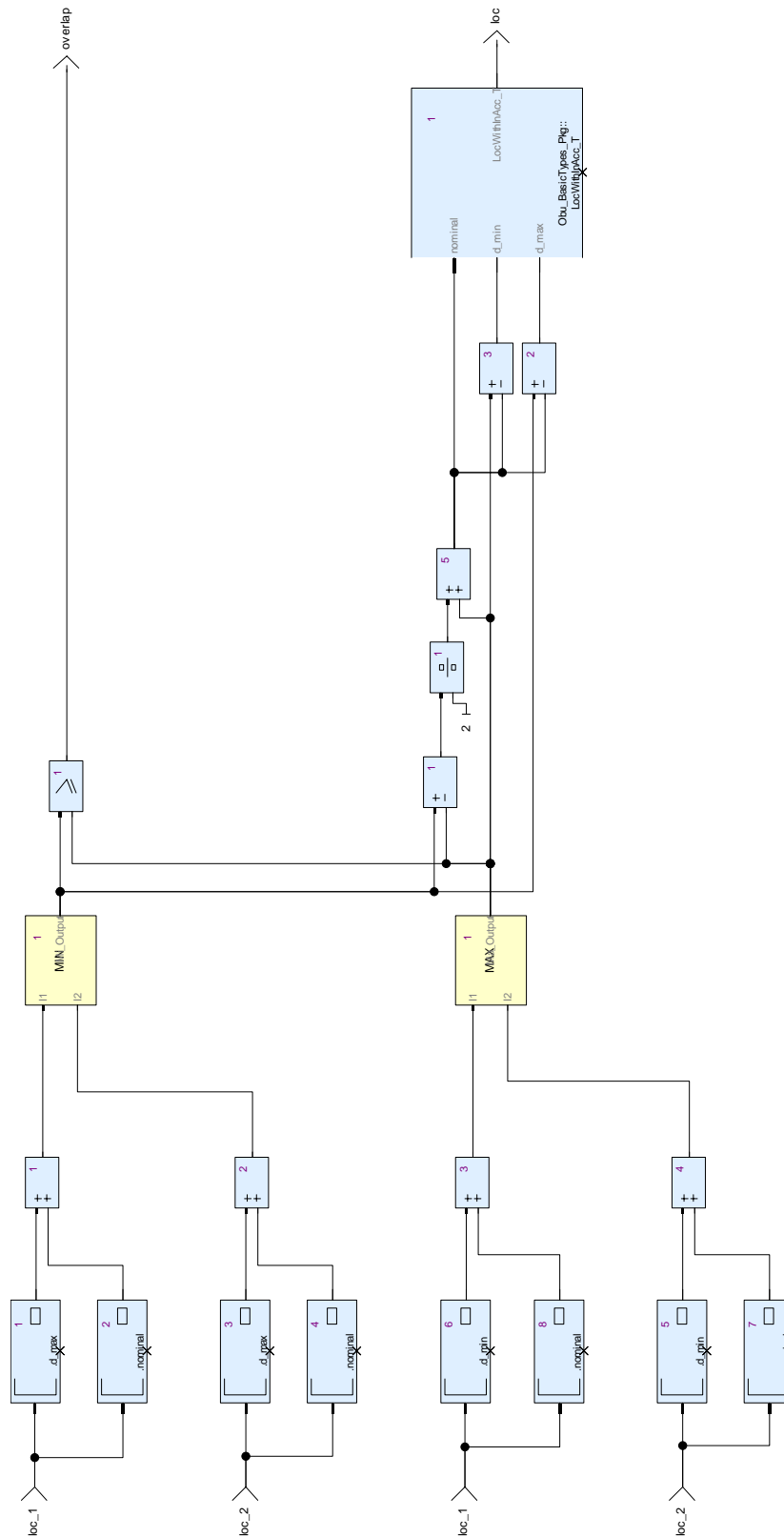


Figure 25: View of diagram_overlapOf_2_Locations_1 (overlapOf_2_Locations)

9.1.11. scaledDLINK_2_dlink Operator

Declared as **public function**

9.1.11.1. Comments and Information

scaledDLINK_2_dlink Comments:

- Converts the linking distance variables into the uniform distance type.

Table 88: scaledDLINK_2_dlink Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Converts the linking distance variables into the uniform distance type</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

9.1.11.2. Interface

Table 89: Inputs of scaledDLINK_2_dlink

| Name | Type | Comments and Information |
|----------|----------|--------------------------|
| q_scale | Q_SCALE | |
| d_link | D_LINK | |
| q_locacc | Q_LOCACC | |

Table 90: Outputs of scaledDLINK_2_dlink

| Name | Type | Comments and Information |
|----------|------------------------------------|--------------------------|
| distance | Obu_BasicTypes_Pkg::LocWithInAcc_T | |

9.1.11.3. Operator Hierarchy

diagram : diagram_scaledDLINK_2_dlink_1

9.1.11.4. Graphical and Textual Diagrams

9.1.11.4.1. View of diagram_scaledDLINK_2_dlink_1 (scaledDLINK_2_dlink)

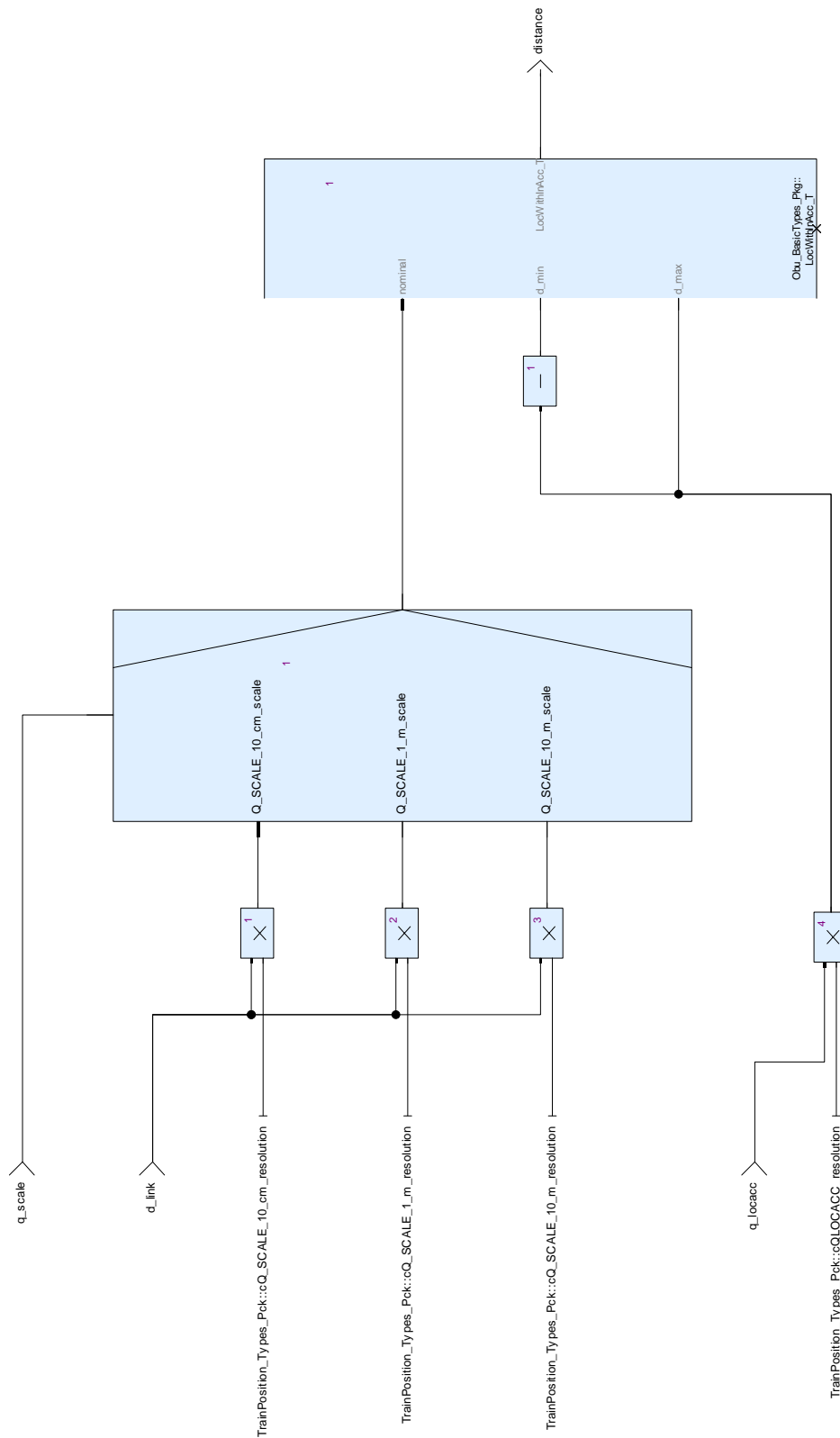


Figure 26: View of diagram_scaledDLINK_2_dlink_1 (scaledDLINK_2_dlink)

9.1.12. sub_2_distances Operator

Declared as **public function**

9.1.12.1. Comments and Information

sub_2_distances Comments:

- Calculates the distance loc_2 - loc_1 between two locations

Table 91: sub_2_distances Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Calculates the distance loc_2 - loc_1 between two locations</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

9.1.12.2. Interface

Table 92: Inputs of sub_2_distances

| Name | Type | Comments and Information |
|-------|------------------------------------|--------------------------|
| loc_2 | Obu_BasicTypes_Pkg::LocWithInAcc_T | |
| loc_1 | Obu_BasicTypes_Pkg::LocWithInAcc_T | |

Table 93: Outputs of sub_2_distances

| Name | Type | Comments and Information |
|----------|------------------------------------|--------------------------|
| distance | Obu_BasicTypes_Pkg::LocWithInAcc_T | |

9.1.12.3. Operator Hierarchy

diagram : diagram_sub_2_distances_1

9.1.12.4. Graphical and Textual Diagrams

9.1.12.4.1. View of diagram_sub_2_distances_1 (sub_2_distances)

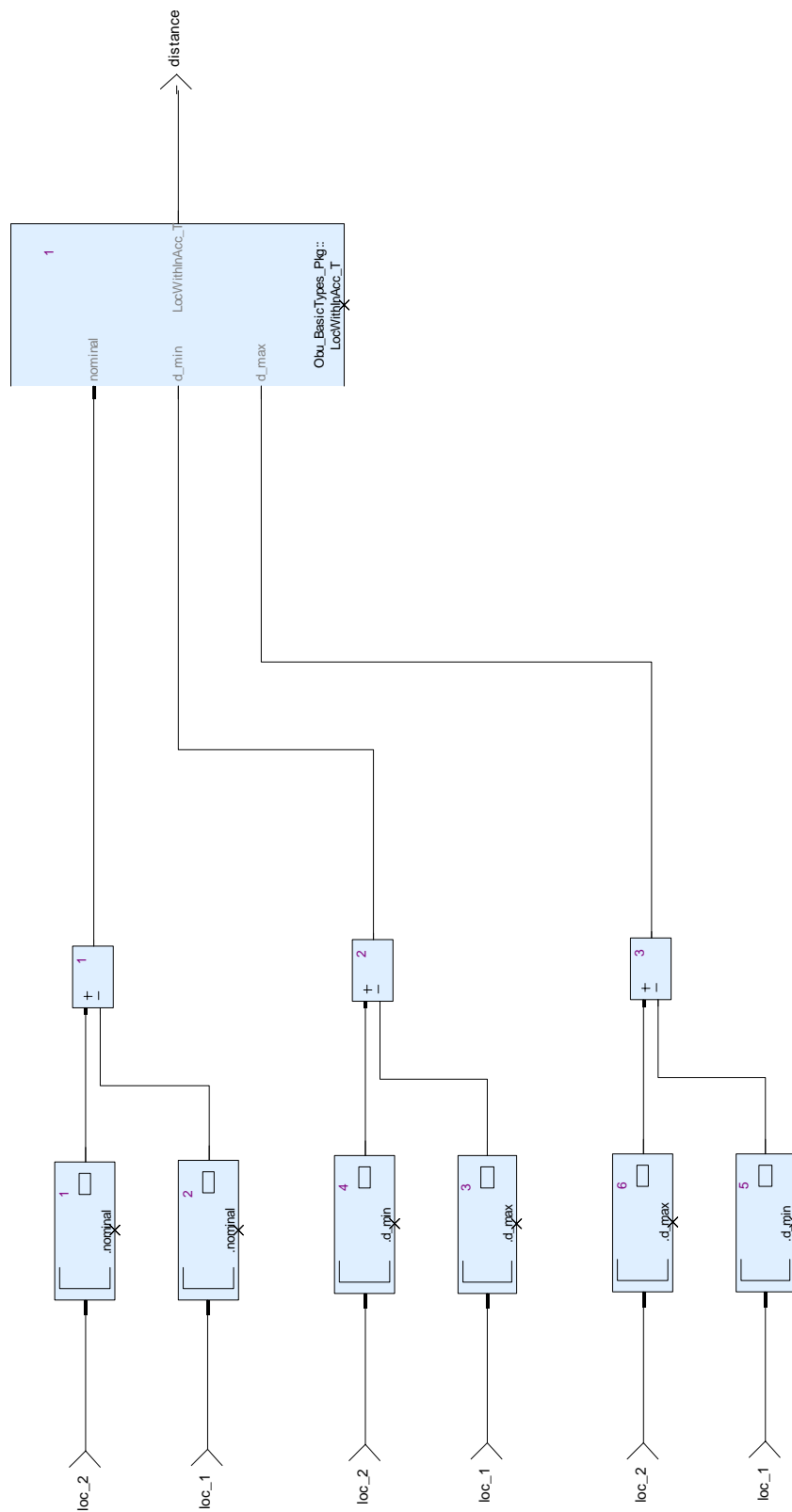


Figure 27: View of diagram_sub_2_distances_1 (sub_2_distances)

9.1.13. sub_2_odoDistances Operator

Declared as **public function**

9.1.13.1. Comments and Information

sub_2_odoDistances Comments:

- Calculates the distance o2 - o1 based on odometry data

Table 94: sub_2_odoDistances Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Calculates the distance o2 - o1 based on odometry data</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

9.1.13.2. Interface

Table 95: Inputs of sub_2_odoDistances

| Name | Type | Comments and Information |
|-------|---|--------------------------|
| odo_2 | Obu_BasicTypes_Pkg::OdometryLocations_T | |
| odo_1 | Obu_BasicTypes_Pkg::OdometryLocations_T | |

Table 96: Outputs of sub_2_odoDistances

| Name | Type | Comments and Information |
|----------|------------------------------------|--------------------------|
| distance | Obu_BasicTypes_Pkg::LocWithInAcc_T | |

9.1.13.3. Operator Hierarchy

diagram : diagram_sub_2_odoDistances_1

9.1.13.4. Graphical and Textual Diagrams

9.1.13.4.1. View of diagram_sub_2_odoDistances_1 (sub_2_odoDistances)

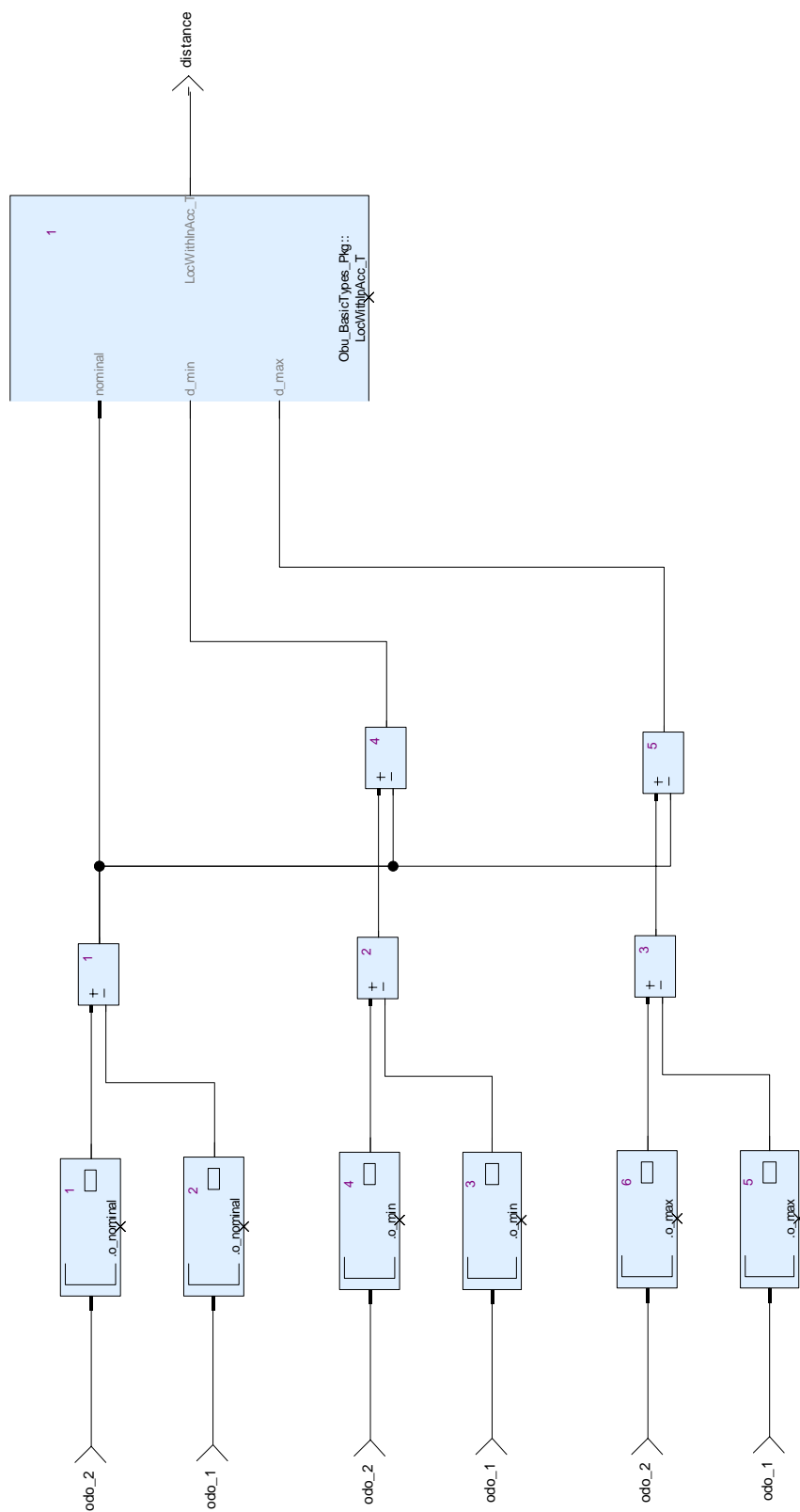


Figure 28: View of diagram_sub_2_odoDistances_1 (sub_2_odoDistances)

10. Project Library: CheckBGConsistency

10.1. CheckPGConsistency_Pkg Package

10.1.1. CheckPGConsistency Operator

Declared as **public function**

10.1.1.1. Interface

Table 97: Inputs of CheckPGConsistency

| Name | Type | Comments and Information |
|---------------|----------------------------|--------------------------|
| BG_Message_in | BG_Types_Pkg::BG_Message_T | |
| linkingInUse | bool | |

Table 98: Outputs of CheckPGConsistency

| Name | Type | Comments and Information |
|----------------|----------------------------|--------------------------|
| BG_Message_out | BG_Types_Pkg::BG_Message_T | |

10.1.1.2. Operator Hierarchy

diagram : diagram_CheckPGConsistency_1

10.1.1.3. Graphical and Textual Diagrams

10.1.1.3.1. View of diagram_CheckPGConsistency_1 (CheckPGConsistency)

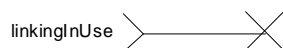
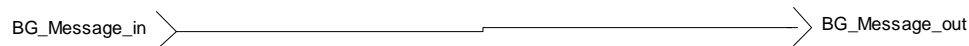


Figure 29: View of diagram_CheckPGConsistency_1 (CheckPGConsistency)

11. Project Library: DetermineBG_Orientation_and_LRBG

11.1. DetermineBGOrientation_LRBG Package

11.1.1. Constants

Table 99: Public Constants of DetermineBGOrientation_LRBG

| Name | Type | Value | Comments and Information |
|-------------|---|---|--------------------------|
| cRBCReports | Radio_TrainToTrack ::Train_Position_Report | {NID_MESSAGE : 0, L_MESSAGE : 0, T_TRAIN : 0.0, NID_ENGINE : 0, PADDING3 : 0, Train_Position_Report_OptionalPackets : 0} | |

11.1.2. ArrCheck Operator

Declared as **public function**

11.1.2.1. Comments and Information

ArrCheck Comments:

- Gets the orientation of the Balise Group from the position in group parameter of the first valid balise
- The check is valid if the bg is not a single bg.

11.1.2.2. Interface

Table 100: Inputs of ArrCheck

| Name | Type | Comments and Information |
|-------|-------|--------------------------------|
| inPIG | N_PIG | Comments: Position in Group |

Table 101: Outputs of ArrCheck

| Name | Type | Comments and Information |
|----------------|-----------------------------|--------------------------|
| outOrientation | BG_Types_Pkg::Orientation_T | |

11.1.2.3. Operator Hierarchy

diagram : diagram_ArrCheck_1

11.1.2.4. Graphical and Textual Diagrams

11.1.2.4.1. View of diagram_ArrCheck_1 (ArrCheck)

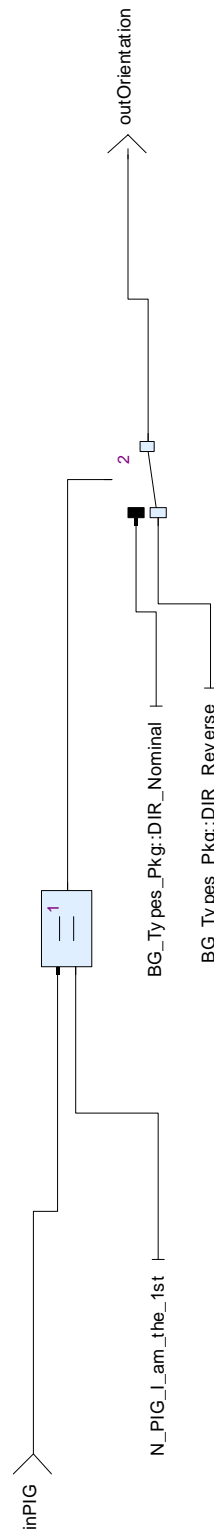


Figure 30: View of diagram_ArrCheck_1 (ArrCheck)

11.1.3. CheckBaliseGroup Operator

Declared as **public function**

11.1.3.1. Interface

Table 102: Inputs of CheckBaliseGroup

| Name | Type | Comments and Information |
|-----------------------|------------------------------------|--------------------------|
| CurrentLRBG_ | BG_Types_Pkg::CurrentLRBG | |
| ListOfBGs_ | BG_Types_Pkg::ListOfBG | |
| TrainInfo_ | BG_Types_Pkg::TrainToTrackStatus_T | |
| BGOrientationAndType_ | BG_Types_Pkg::Orientation_T | |

Table 103: Outputs of CheckBaliseGroup

| Name | Type | Comments and Information |
|--------------|------------|--------------------------|
| Orientation_ | Q_DIRTRAIN | |

11.1.3.2. Operator Hierarchy

diagram : diagram_internal_structure

11.1.3.3. Graphical and Textual Diagrams

11.1.3.3.1. View of diagram_internal_structure (CheckBaliseGroup)

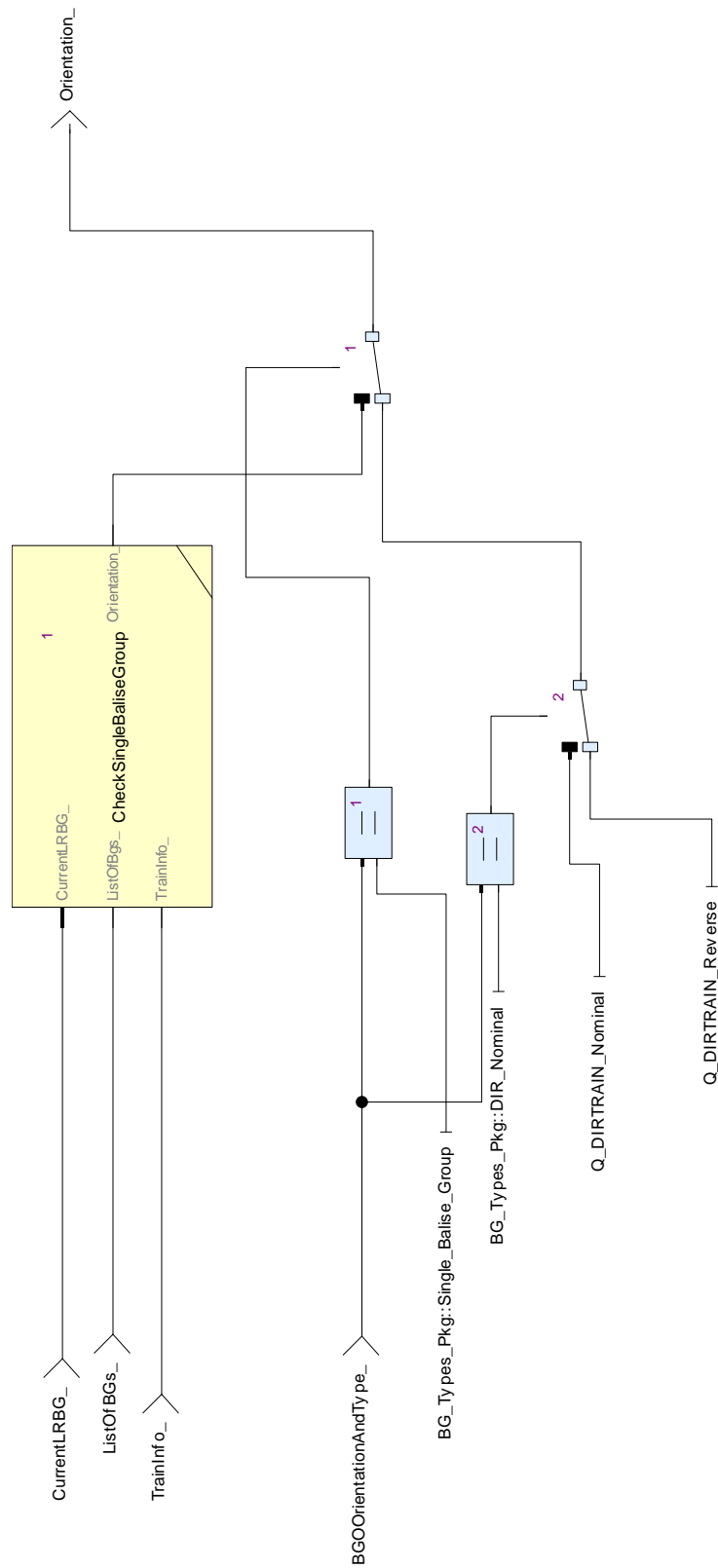


Figure 31: View of diagram_internal_structure (CheckBaliseGroup)

11.1.4. CheckSingleBaliseGroup Operator

Declared as **public function**

11.1.4.1. Interface

Table 104: Inputs of CheckSingleBaliseGroup

| Name | Type | Comments and Information |
|--------------|------------------------------------|--------------------------|
| CurrentLRBG_ | BG_Types_Pkg::CurrentLRBG | |
| ListOfBgs_ | BG_Types_Pkg::ListOfBG | |
| TrainInfo_ | BG_Types_Pkg::TrainToTrackStatus_T | |

Table 105: Outputs of CheckSingleBaliseGroup

| Name | Type | Comments and Information |
|--------------|------------|--------------------------|
| Orientation_ | Q_DIRTRAIN | |

11.1.4.2. Operator Hierarchy

diagram : diagram_CheckSingleBaliseGroup_1

11.1.4.3. Graphical and Textual Diagrams

11.1.4.3.1. View of diagram_CheckSingleBaliseGroup_1 (CheckSingleBaliseGroup)

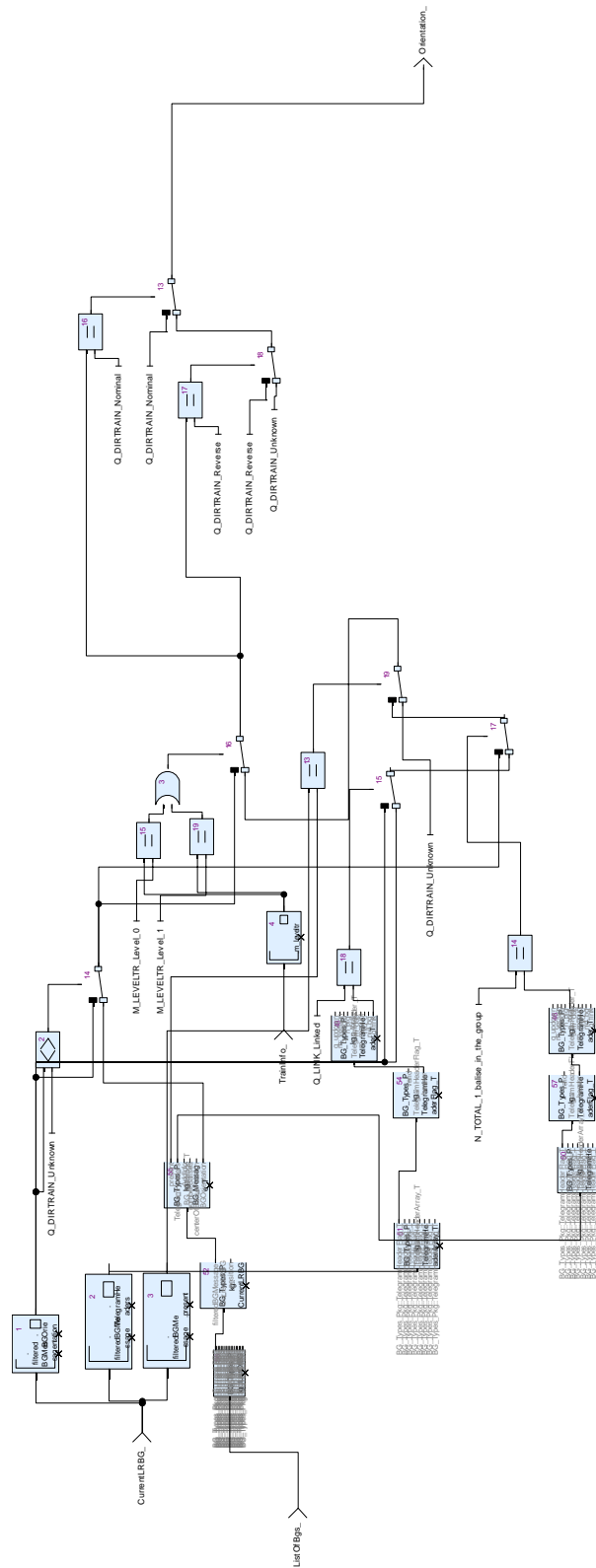


Figure 32: View of diagram_CheckSingleBaliseGroup_1 (CheckSingleBaliseGroup)

11.1.5. DetermineBGOrientation_LRBG Operator

Declared as **public node**

11.1.5.1. Comments and Information

DetermineBGOrientation_LRBG Comments:

- SRS-Subset 26 section 3.4.2: Defines Balise Group Coordinate system.
- Only section related to Level 1 is implemented in this state.

11.1.5.2. Interface

Table 106: Inputs of DetermineBGOrientation_LRBG

| Name | Type | Comments and Information |
|-----------------------|--------------------------------------|--------------------------|
| CurrentLRBG_ | BG_Types_Pkg::CurrentLRBG | |
| CheckedBGMessage_ | BG_Types_Pkg::BG_Message_T | |
| ListOfBGs_ | BG_Types_Pkg::ListOfBG | |
| TrainInfo_ | BG_Types_Pkg::TrainToTrackStatus_T | |
| RBCOrientationReport_ | BG_Types_Pkg::RBCOrientationReport_T | |

Table 107: Outputs of DetermineBGOrientation_LRBG

| Name | Type | Properties | | Comments and Information |
|--------------------|---|------------|-------------|--------------------------|
| FilteredBGMessage_ | BG_Types_Pkg::BG_Message_T | | | |
| RBCReport_ | Radio_TrainToTrack::Train_Position_Report | default | cRBCReports | |

11.1.5.3. Locals

Table 108: Locals of DetermineBGOrientation_LRBG

| Name | Type | Comments and Information |
|-----------|------|--------------------------|
| isPresent | bool | |

11.1.5.4. Operator Hierarchy

diagram : diagram_internal_structure

activate if : IfBlock1

 branch : then

 branch : else

11.1.5.5. Graphical and Textual Diagrams

11.1.5.5.1. View of diagram_internal_structure (DetermineBGOrientation_LRBG)

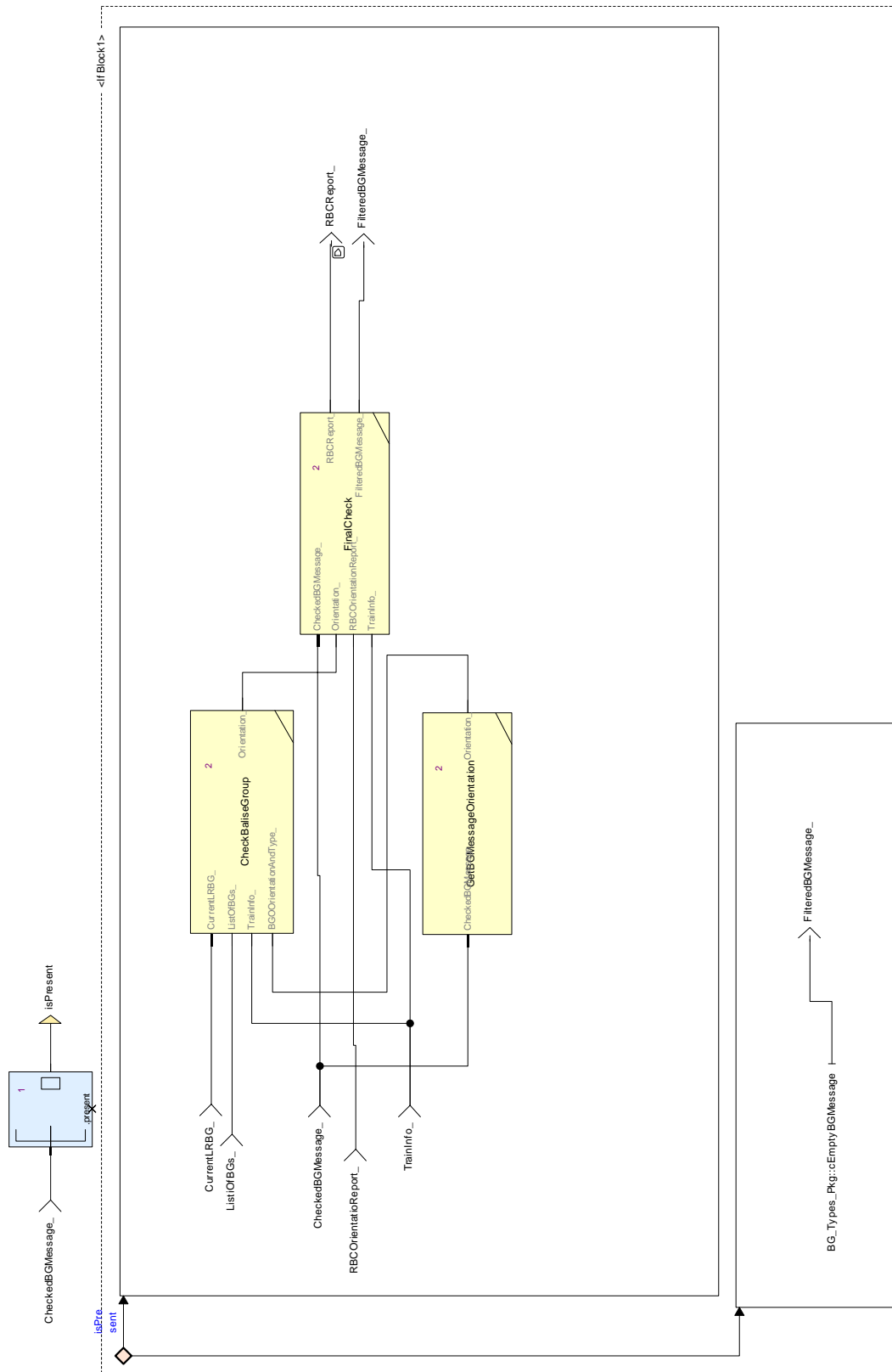


Figure 33: View of diagram_internal_structure (DetermineBGOrientation_LRBG)

Table 109: Conditional Blocks of diagram_internal_structure

| Conditional Block | Comments and Information |
|-------------------|--------------------------|
| IfBlock1 | |

Table 110: Actions of diagram_internal_structure

| Conditional Block Action | Comments and Information |
|--------------------------|--------------------------|
| IfBlock1:then | |
| IfBlock1:else | |

11.1.6. FinalCheck Operator

Declared as **public node**

11.1.6.1. Interface

Table 111: Inputs of FinalCheck

| Name | Type | Comments and Information |
|-----------------------|--------------------------------------|--------------------------|
| CheckedBGMessage_ | BG_Types_Pkg::BG_Message_T | |
| Orientation_ | Q_DIRTRAIN | |
| RBCOrientationReport_ | BG_Types_Pkg::RBCOrientationReport_T | |
| TrainInfo_ | BG_Types_Pkg::TrainToTrackStatus_T | |

Table 112: Outputs of FinalCheck

| Name | Type | Properties | | Comments and Information |
|--------------------|---|------------|-------------------------------|--------------------------|
| RBCReport_ | Radio_TrainToTrack::Train_Position_Report | default | cRBCReports | |
| | | last | cRBCReports | |
| FilteredBGMessage_ | BG_Types_Pkg::BG_Message_T | default | BG_Types_Pkg::cEmptyBGMessage | |

11.1.6.2. Operator Hierarchy

diagram : diagram_FinalCheck_1

state-machine : SM1

 state : Initial

 state : Level0or1

 state : Level2or3

state-machine : SM2

 state : Ack

 state : Init

 state : NoAck

Table 113: State Machines of diagram_FinalCheck_1

| State Machine | Comments and Information |
|-------------------|--------------------------|
| SM1 | |
| SM1:Level2or3:SM2 | |

Table 114: States of diagram_FinalCheck_1

| State | Comments and Information |
|-------------------------|--------------------------|
| SM1:Initial | |
| SM1:Level0or1 | |
| SM1:Level2or3 | |
| SM1:Level2or3:SM2:Ack | |
| SM1:Level2or3:SM2:Init | |
| SM1:Level2or3:SM2:NoAck | |

Table 115: Transitions of diagram_FinalCheck_1

| Source/Target | # | Conditions/Actions | Comments and Information |
|---|---|---|--------------------------|
| Source: SM1:Initial Target: SM1:Level0or1 | 1 | Condition: M_LEVELTR_Level_0 = TrainInfo_.m_leveltr or M_LEVELTR_Level_1 = TrainInfo_.m_leveltr | |
| Source: SM1:Initial Target: SM1:Level2or3 | 2 | Condition: M_LEVELTR_Level_2 = TrainInfo_.m_leveltr or M_LEVELTR_Level_3 = TrainInfo_.m_leveltr | |
| Source: SM1:Level2or3:SM2:Init Target: SM1:Level2or3:SM2:Ack | 1 | Condition: RBCOrientationReport_ .assignment_of_coordi nate_system.M_ACK = 1 | |
| Source: SM1:Level2or3:SM2:Init Target: SM1:Level2or3:SM2:NoAck | 2 | Condition: RBCOrientationReport_ .assignment_of_coordi nate_system.M_ACK = 0 | |

11.1.7. GetBGMessageOrientation Operator

Declared as **public function**

11.1.7.1. Interface

Table 116: Inputs of GetBGMessageOrientation

| Name | Type | Comments and Information |
|-------------------|--------------------------------|--------------------------|
| CheckedBGMessage_ | BG_Types_Pkg::BG_M essage_T | |

Table 117: Outputs of GetBGMessageOrientation

| Name | Type | Comments and Information |
|--------------|---------------------------------|--------------------------|
| Orientation_ | BG_Types_Pkg::Orient ation_T | |

11.1.7.2. Operator Hierarchy

diagram : diagram_GetBGMessageOrientation

11.1.7.3. Graphical and Textual Diagrams

11.1.7.3.1. View of diagram_GetBGMessageOrientation (GetBGMessageOrientation)

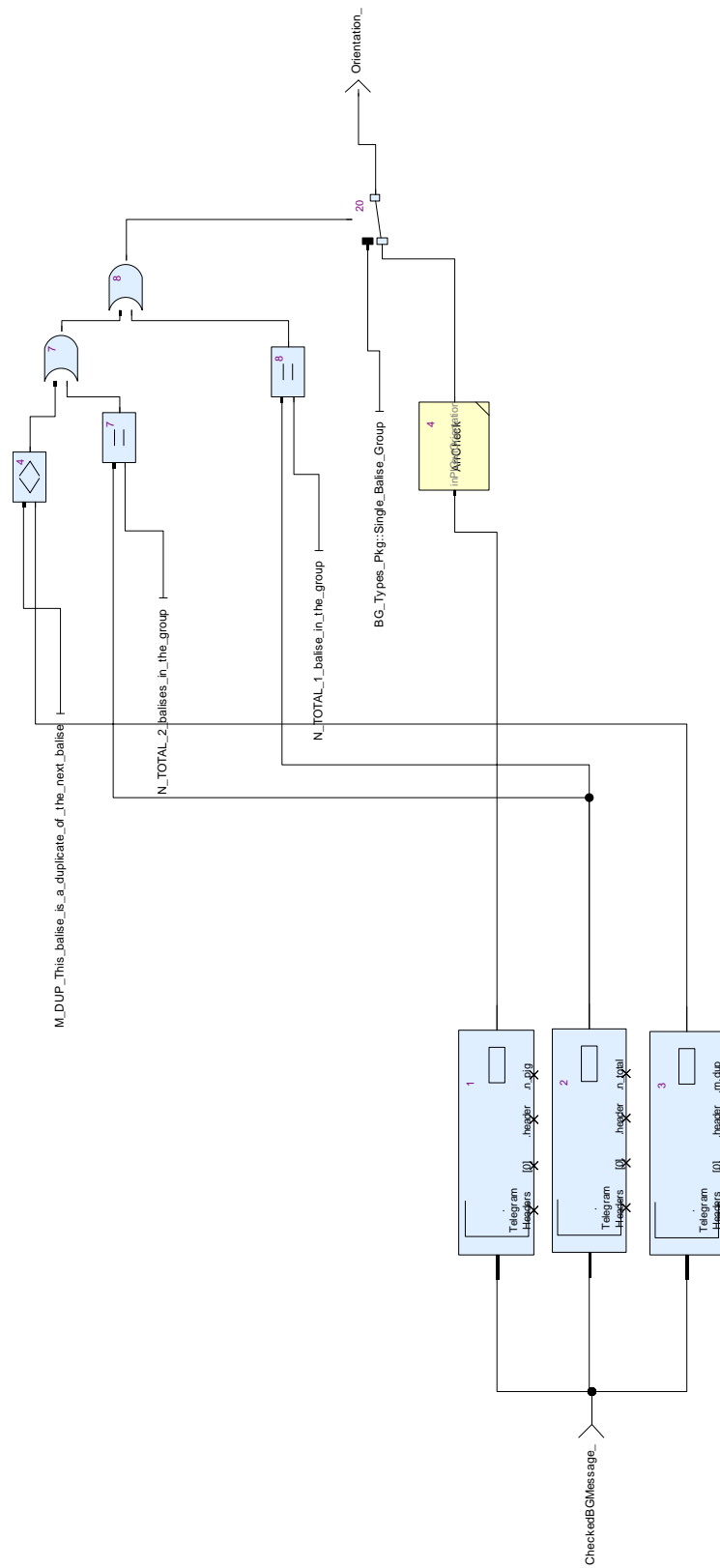


Figure 35: View of diagram_GetBGMessageOrientation (GetBGMessageOrientation)

11.1.8. setOrientation Operator

Declared as **public function**

11.1.8.1. Comments and Information

setOrientation Comments:

- Sets the orientation in a BG-Message base on the input

11.1.8.2. Interface

Table 118: Inputs of setOrientation

| Name | Type | Comments and Information |
|---------------|----------------------------|--------------------------|
| inBGMessage | BG_Types_Pkg::BG_Message_T | |
| inOrientation | Q_DIRTRAIN | |

Table 119: Outputs of setOrientation

| Name | Type | Comments and Information |
|--------------|----------------------------|--------------------------|
| outBGMessage | BG_Types_Pkg::BG_Message_T | |

11.1.8.3. Operator Hierarchy

diagram : diagram_setOrientation_1

11.1.8.4. Graphical and Textual Diagrams

11.1.8.4.1. View of diagram_setOrientation_1 (setOrientation)

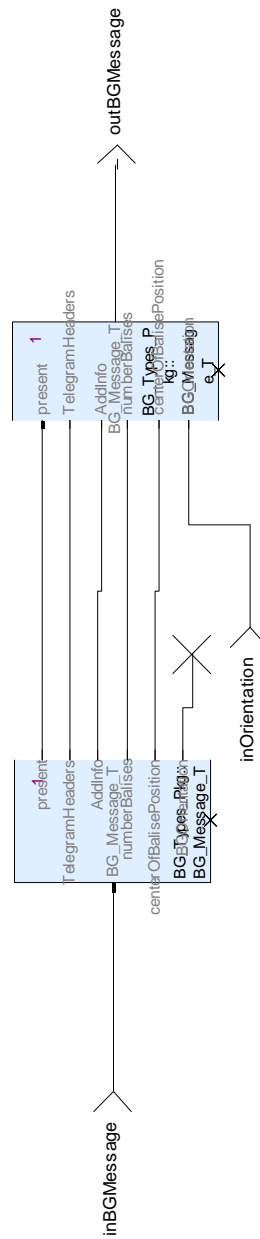


Figure 36: View of diagram_setOrientation_1 (setOrientation)

12. Project Library: ReceiveEuroBaliseFromAPI

12.1. Root Elements

12.1.1. Types

Table 120: Public Types of ReceiveEuroBaliseFromAPI

| Name | Definition | Comments and Information |
|----------------|--|--|
| API_addInfo_T | {listLinking : BG_Types_Pkg::LinkedBGs_T} | Comments: packet information received via telegram listLinking Comments: Linking information received via packet 5. Information is of variable length. |
| API_Telegram_T | {present : bool, api_header : BG_Types_Pkg::TelegramHeader_T, api_packets : API_addInfo_T, api_bad_balise_received : bool, centerOfBalisePosition : BG_Types_Pkg::centerOfBalisePosition_T} | Comments: Telegram as received via the API present Comments: Indicates the presence of new and valid information at the start of the routine api_header Comments: Telegram_Header api_packets Comments: Packets received with this balise api_bad_balise_received Comments: indicates, whether a bad balise has been received. In this scenario, data are not valid. centerOfBalisePosition Comments: actual odometry of where the telegram has been received |

12.1.2. Constants

Table 121: Public Constants of ReceiveEuroBaliseFromAPI

| Name | Type | Value | Comments and Information |
|-----------------|--------------------------------|---|--------------------------|
| bad_balise_init | BG_Types_Pkg::TelegramHeader_T | {q_updown : Q_UPDOWN_Down_link_telegram, m_version : M_VERSION_Previous_versions_according_to_e_g_EEIG_SRS_and_UIC_A200_SRS, q_media : Q_MEDIA_Balise, n_pig : N_PIG_I_am_the_1st, n_total : N_TOTAL_1_balise_in_the_group, m_dup : M_DUP_No_duplicates, m_mcount : 0, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked} | |

| Name | Type | Value | Comments and Information |
|-----------------------------|--------------------------|--|--------------------------|
| cEmptyBaliseTelegram nit | BG_Types_Pkg::Telegram_T | {present : false, valid : false, telegramheader : {q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previous_versions_according_to_e_g_EEIG_SRS_and_UIC_A200_SRS, q_media : Q_MEDIA_Balise, n_pig : N_PIG_I_am_the_1st, n_total : N_TOTAL_1_balise_in_the_group, m_dup : M_DUP_No_duplicates, m_mcount : 0, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked}, packets : {addInfo : 0, linkingPackets : [{valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_scale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_Same_country_or_railway_administration_no_NID_C_folllows, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATION_The_balise_group_is_seen_by_the_train_in_reverse_direction, q_linkreaction : Q_LINKREACTION_Train_trip, q_locacc : 0}, {valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_scale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_Same_country_or_railway_administration_no_NID_C_folllows, nid_c : 0, nid_bg : 0, q_linkorientation : | |

| Name | Type | Value | Comments and Information |
|------|------|---|--------------------------|
| | | <pre>{addInfo : 0, linkingPackets : [{ valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_s cale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_S ame_country__or__ railway_administrati on_no_NID_C_follo ws, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATIO N_The_balise_grou p_is_seen_by_the_t rain_in_reverse_dir ection, q_linkreaction : Q_LINKREACTION_ Train_trip, q_locacc : 0}, { valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_s cale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_S ame_country__or__ railway_administrati on_no_NID_C_follo ws, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATIO N_The_balise_grou p_is_seen_by_the_t rain_in_reverse_dir ection, q_linkreaction : Q_LINKREACTION_ Train_trip, q_locacc : 0}, { valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_s cale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_S ame_country__or__ railway_administrati on_no_NID_C_follo ws, nid_c : 0, nid_bg : 0,</pre> | |

| Name | Type | Value | Comments and Information |
|----------------------|--------------------------|---|--------------------------|
| cInitDecodedTelegram | BG_Types_Pkg::Telegram_T | { present : false, valid : false, telegramheader : { q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previous_versions_according_to_e_g_EEIG_SRS_and_UIC_A200_SRS, q_media : Q_MEDIA_Balise, n_pig : N_PIG_I_am_the_1st, n_total : N_TOTAL_1_balise_in_the_group, m_dup : M_DUP_No_duplicates, m_mcount : 0, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked}, packets : { addInfo : 0, linkingPackets : [{ valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_scale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_Same_country_or_railway_administration_no_NID_C_follows, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATION_The_balise_group_is_seen_by_the_train_in_reverse_direction, q_linkreaction : Q_LINKREACTION_Train_trip, q_locacc : 0}, { valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_scale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_Same_country_or_railway_administration_no_NID_C_follows, nid_c : 0, nid_bg : 0, q_linkorientation : | |

| Name | Type | Value | Comments and Information |
|------|------|--|--------------------------|
| | | <pre>[{ valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_s cale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_S ame_country__or__ railway_administrati on_no_NID_C_follo ws, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATIO N_The_balise_grou p_is_seen_by_the_t rain_in_reverse_dir ection, q_linkreaction : Q_LINKREACTION_ Train_trip, q_locacc : 0}, { valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_s cale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_S ame_country__or__ railway_administrati on_no_NID_C_follo ws, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATIO N_The_balise_grou p_is_seen_by_the_t rain_in_reverse_dir ection, q_linkreaction : Q_LINKREACTION_ Train_trip, q_locacc : 0}, { valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_s cale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_S ame_country__or__ railway_administrati on_no_NID_C_follo ws, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATIO</pre> | |

| Name | Type | Value | Comments and Information |
|--------------------|--|---|--------------------------|
| cInitEmptyPosition | BG_Types_Pkg::centerOfBalisePosition_T | { centerOfBalisePosition : { o_nominal : 0, o_min : 0, o_max : 0 }, BG_centerDetectionInaccuracies : { nominal : 0, d_min : 0, d_max : 0 }, timestamp : 0 } | |

12.2. btmSupportPkg Package

12.2.1. transferPackets Operator

Declared as **public function**

12.2.1.1. Interface

Table 122: Inputs of transferPackets

| Name | Type | Comments and Information |
|-------------|---------------|--------------------------|
| api_packets | API_addInfo_T | |

Table 123: Outputs of transferPackets

| Name | Type | Comments and Information |
|-------------|---------------------------------------|--------------------------|
| out_AddInfo | BG_Types_Pkg::AdditionalInformation_T | |

12.2.1.2. Operator Hierarchy

diagram : diagram_transferPackets_1

12.2.1.3. Graphical and Textual Diagrams

12.2.1.3.1. View of diagram_transferPackets_1 (transferPackets)

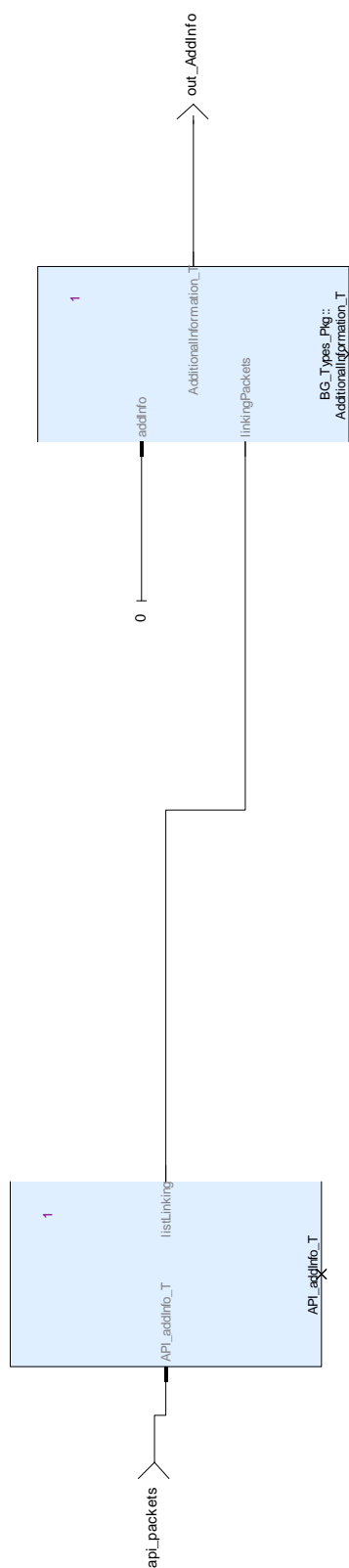


Figure 37: View of diagram_transferPackets_1 (transferPackets)

12.2.2. transferTelegram Operator

Declared as **public function**

12.2.2.1. Interface

Table 124: Inputs of transferTelegram

| Name | Type | Comments and Information |
|------------|----------------|--------------------------|
| API_balise | API_Telegram_T | |

Table 125: Outputs of transferTelegram

| Name | Type | Comments and Information |
|---------------------------|--|--------------------------|
| outDecodedTelegram | BG_Types_Pkg::Telegram_T | |
| outCenterOfBalisePosition | BG_Types_Pkg::centerOfBalisePosition_T | |

12.2.2.2. Operator Hierarchy

diagram : diagram_transferTelegram_1

12.2.2.3. Graphical and Textual Diagrams

12.2.2.3.1. View of diagram_transferTelegram_1 (transferTelegram)

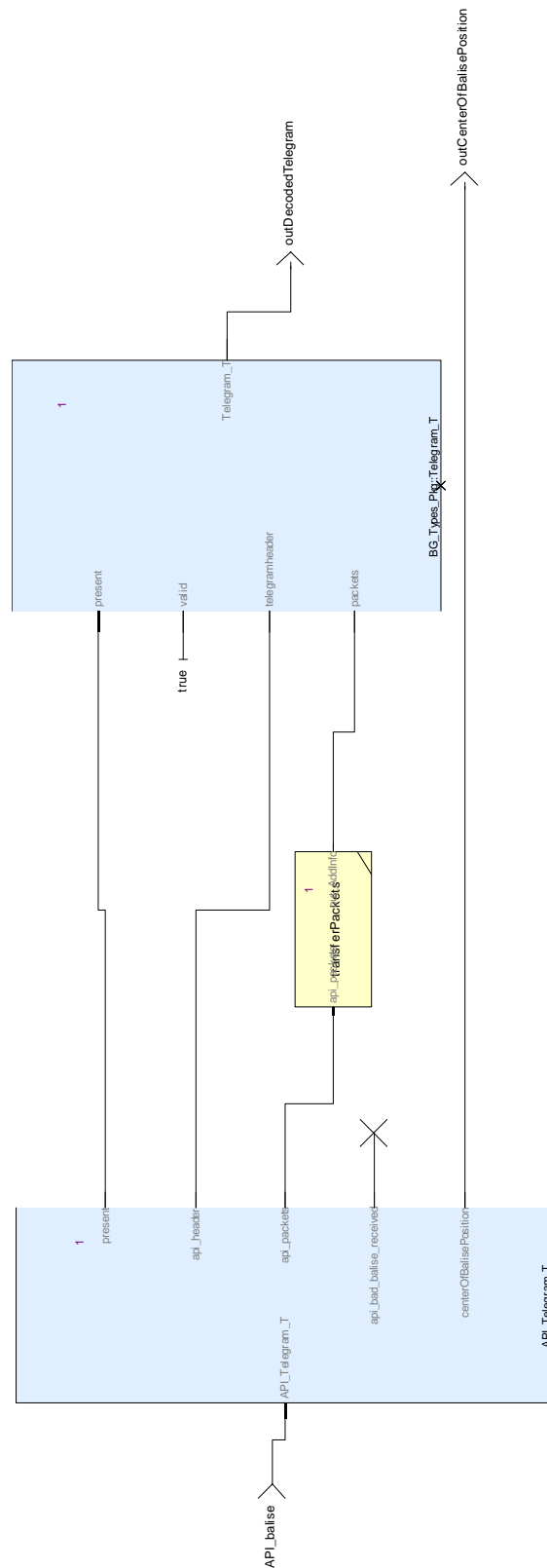


Figure 38: View of diagram_transferTelegram_1 (transferTelegram)

diagram_transferTelegram_1 Comments:

- Transfer of the telegram from api to openETCS model structure.

12.3. ReceiveEuroBaliseFromAPI_Pkg Package

12.3.1. ReceiveEuroBaliseFromAPI Operator

Declared as **public function**

12.3.1.1. Comments and Information

ReceiveEuroBaliseFromAPI Comments:

- This module defines the interface to the API.
- Assumption is we do not perform a decoding in scade. we get proper decoded telegrams from the API.
- Preferred Interface : (Header + Flag + odometry) + addInf

12.3.1.2. Interface

Table 126: Inputs of ReceiveEuroBaliseFromAPI

| Name | Type | Comments and Information |
|------------|----------------|--------------------------|
| API_balise | API_Telegram_T | |

Table 127: Outputs of ReceiveEuroBaliseFromAPI

| Name | Type | Properties | Comments and Information |
|---------------------------|--|------------|--------------------------|
| outDecodedTelegram | BG_Types_Pkg::Telegram_T | default | cInitDecodedTelegram |
| outcenterOfBalisePosition | BG_Types_Pkg::centerOfBalisePosition_T | default | cInitEmptyPosition |

12.3.1.3. Locals

Table 128: Locals of ReceiveEuroBaliseFromAPI

| Name | Type | Comments and Information |
|------------|------|--------------------------|
| bad_balise | bool | |
| is_present | bool | |

12.3.1.4. Operator Hierarchy

diagram : diagram_ReceiveEuroBaliseFromAPI_1

```

    activate if : is_present_blk
    branch : then
        activate if : has_fresh_data_blk
        branch : then
            diagram : diagram_Then_1
        branch : else
            diagram : diagram_Else_1
    branch : else

```

12.3.1.5. Graphical and Textual Diagrams

12.3.1.5.1. View of diagram_ReceiveEuroBaliseFromAPI_1 (ReceiveEuroBaliseFromAPI)

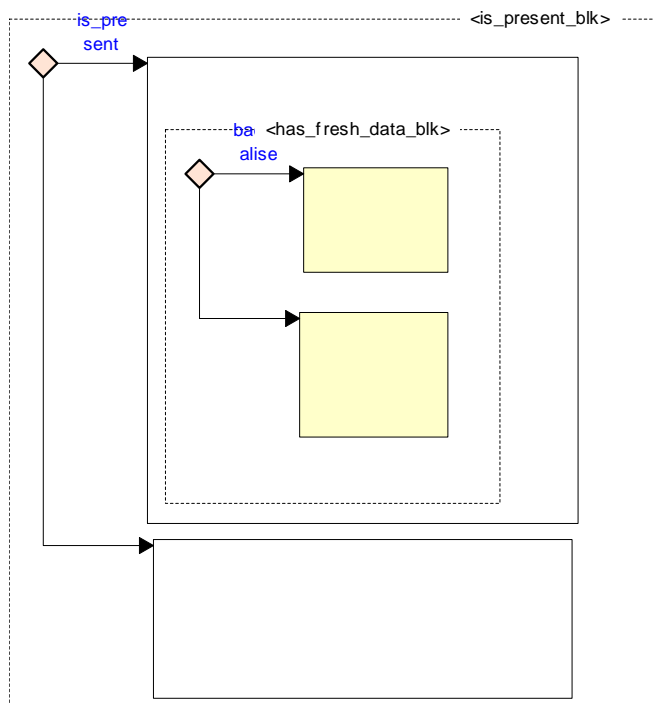
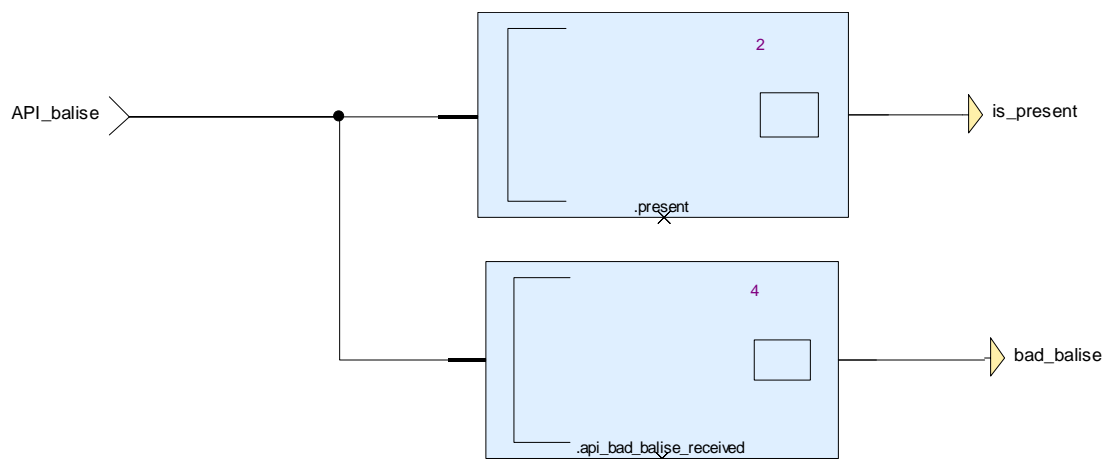


Figure 39: View of diagram_ReceiveEuroBaliseFromAPI_1 (ReceiveEuroBaliseFromAPI)

Table 129: Conditional Blocks of diagram_ReceiveEuroBaliseFromAPI_1

| Conditional Block | Comments and Information |
|--|--------------------------|
| is_present_blk | |
| is_present_blk: then: has_fresh_data_blk | |

Table 130: Actions of diagram_ReceiveEuroBaliseFromAPI_1

| Conditional Block Action | Comments and Information |
|--------------------------|--------------------------|
| is_present_blk: then | |

| Conditional Block Action | Comments and Information |
|--|--------------------------|
| is_present_blk: then: has_fresh_data_blk: then | |
| is_present_blk: then: has_fresh_data_blk: else | |
| is_present_blk: else | |

12.3.1.5.2. View of diagram_Then_1
(ReceiveEuroBaliseFromAPI/is_present_blk: then: has_fresh_data_blk: then:)
Owner diagram: diagram_ReceiveEuroBaliseFromAPI_1



Figure 40: View of diagram_Then_1
(ReceiveEuroBaliseFromAPI/is_present_blk:then:has_fresh_data_blk:then:)

diagram_Then_1 Comments:

- This path is meant to indicate the situation where a bad balise telegram has been received.

- Information about the balise is not known.
- However, information about the event has to be passed to the bg-message builder

12.3.1.5.3. View of diagram_Else_1

(ReceiveEuroBaliseFromAPI/is_present_blk:then:has_fresh_data_blk:else:)

Owner diagram: diagram_ReceiveEuroBaliseFromAPI_1

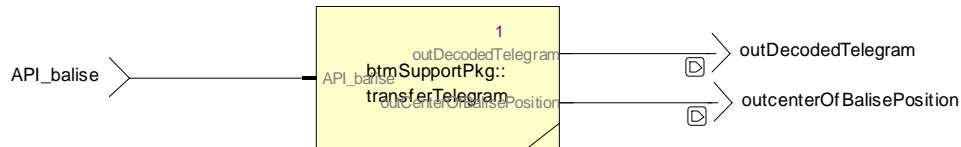


Figure 41: View of diagram_Else_1
(ReceiveEuroBaliseFromAPI/is_present_blk:then:has_fresh_data_blk:else:)

diagram_Else_1 Comments:

- Situation: fresh data have been delivered and balise data are valid.
- In this situation copying of telegram, odometry and packets is to be done.

13. Project Library: SelectUsableInfo

13.1. SelectUsableInfo_Pkg Package

13.1.1. SelectUsableInfo Operator

Declared as **public function**

13.1.1.1. Interface

Table 131: Inputs of SelectUsableInfo

| Name | Type | Comments and Information |
|---------------|------------------------------------|--------------------------|
| BG_Message_in | BG_Types_Pkg::BG_Message_T | |
| TrainInfo_ | BG_Types_Pkg::TrainToTrackStatus_T | |

Table 132: Outputs of SelectUsableInfo

| Name | Type | Comments and Information |
|----------------|----------------------------|--------------------------|
| BG_Message_out | BG_Types_Pkg::BG_Message_T | |

13.1.1.2. Operator Hierarchy

diagram : diagram_SelectUsableInfo_1

13.1.1.3. Graphical and Textual Diagrams

13.1.1.3.1. View of diagram_SelectUsableInfo_1 (SelectUsableInfo)

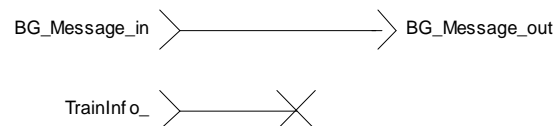


Figure 42: View of diagram_SelectUsableInfo_1 (SelectUsableInfo)

14. Project Library: TrainPosition_Integration

14.1. TrainPosition_Integration_Pkg Package

14.1.1. ManageTrainPosition Operator

Declared as **public node**

14.1.1.1. Interface

Table 133: Inputs of ManageTrainPosition

| Name | Type | Comments and Information |
|-------------------|--|--|
| currentOdometry | Obu_BasicTypes_Pkg::odometry_T | Comments: The current odometry values |
| passedBG | BG_Types_Pkg::passedBG_T | Comments: Input event reporting a balise group during its passage, if there is one. |
| LRBG | TrainPosition_Types_Pkg::positionedBG_T | Comments: The LRBG used for RBC communication. |
| prevLRBG | TrainPosition_Types_Pkg::positionedBG_T | Comments: A previously used LRBG used in RBC communication. |
| reset | bool | Comments: Resets all to an initials state and deletes all stored BGs. |
| systemTime | ProvidePositionReport_Pkg::SystemTime_T | |
| errorMsg | ProvidePositionReport_Pkg::ErrorMessage_T | |
| posRepPara | ProvidePositionReport_Pkg::PositionReportParameter_T | |
| trackInfo | ProvidePositionReport_Pkg::TrackInfo_T | |
| trainProps | TrainPosition_Types_Pkg::trainProperties_T | |
| rcbComm | ProvidePositionReport_Pkg::RBC_Communication_T | |
| train2trackStatus | BG_Types_Pkg::TrainToTrackStatus_T | |
| linkingInfoUsed | ProvidePositionReport_Pkg::LinkingInfoUsedOnBoard | |

Table 134: Outputs of ManageTrainPosition

| Name | Type | Comments and Information |
|---------------|--|--|
| posRep | ProvidePositionReport_Pkg::PositionReport_T | |
| trainPosition | TrainPosition_Types_Pkg::trainPosition_T | |
| trainPosInfo | TrainPosition_Types_Pkg::trainPositionInfo_T | Comments: The resulting train position with reference to the LRBG |

| Name | Type | Comments and Information |
|----------------|---|--|
| trainPosErrors | TrainPosition_Types_Pck::positionErrors_T | Comments: Errors and inconsistencies detected by the calculation. |
| BGs | TrainPosition_Types_Pck::positionedBGs_T | Comments: The collection of currently known BGs. |

14.1.1.2. Locals

Table 135: Locals of ManageTrainPosition

| Name | Type | Properties | | Comments and Information |
|-------------------|--|------------|--|--------------------------|
| trainPosition_loc | TrainPosition_Types_Pck::trainPosition_T | last | CalculateTrainPosition_Pkg::cTrainPosition_0 | |

14.1.1.3. Operator Hierarchy

diagram : diagram_ManageTrainPosition_1

14.1.1.4. Graphical and Textual Diagrams

14.1.1.4.1. View of diagram_ManageTrainPosition_1 (ManageTrainPosition)

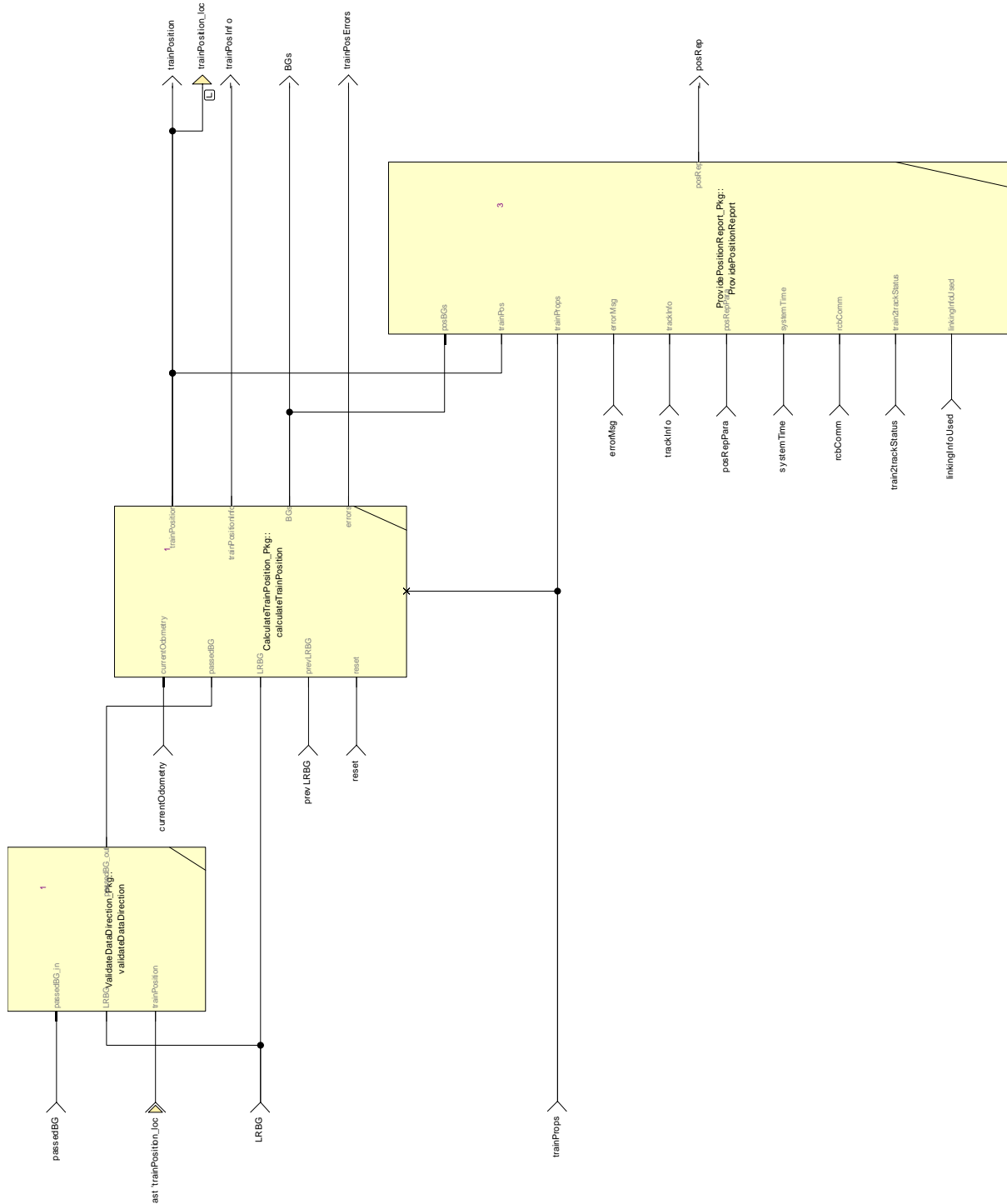


Figure 43: View of diagram_ManageTrainPosition_1 (ManageTrainPosition)

15. Project Library: CalculateTrainPosition

15.1. CalculateTrainPosition_Pkg Package

15.1.1. Comments and Information

CalculateTrainPosition_Pkg Comments:

- Incorporates the functions to calculate the balise group locations and the actual train position.

Table 136: CalculateTrainPosition_Pkg Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-09-01 |
| | Version | 00.09.0 |
| | to_c | True |
| Remark_1 | Description | <p>CalculateTrainPosition</p> <ul style="list-style-type: none"> - Description: Calculates the actual train position based on passed balise groups - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.1.2. Types

Table 137: Public Types of CalculateTrainPosition_Pkg

| Name | Definition | Comments and Information |
|---------------------------|--|--------------------------|
| positionedBGs_w_overrun_T | {BGs : TrainPosition_Types_Pck::positionedBGs_T, overrun : bool} | |

15.1.3. Constants

Table 138: Public Constants of CalculateTrainPosition_Pkg

| Name | Type | Value | Comments and Information |
|----------------------------|--|---|--|
| cNoInfoFromLinking | TrainPosition_Types _Pck::infoFromLinking_T | { valid : false, nid_bg_fromLinkingBG : 0, nid_c_fromLinkingBG : 0, expectedLocation : { nominal : 0, d_min : 0, d_max : 0 }, d_link : { nominal : 0, d_min : 0, d_max : 0 }, linkingInfo : { valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_scale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_Same_country_or_railway_administration_no_NID_C_follows, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATION_The_balise_group_is_seen_by_the_train_in_reverse_direction, q_linkreaction : Q_LINKREACTION_Train_trip, q_locacc : 0 } } | |
| cNoOfAtLeast_8_LRBGs | int | 3 | Comments: Covers 3.6.2.2 c): ??? The on-board equipment shall be able to accept information referring to one of at least eight LRBGONB last reported to the RBC. |
| cNoOfAtLeast_x_unlinkedBGs | int | 2 | Comments: Covers ????: Min no of unlinked BGs to be memorized |

| Name | Type | Value | Comments and Information |
|------|------|---|--------------------------|
| | | <pre>{valid : false, timestamp : 0, odometrystamp : {o_nominal : 0, o_min : 0, o_max : 0}, BG_centerDetection Inaccuracies : {nominal : 0, d_min : 0, d_max : 0}, BG_Header : {q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previo us_versions_accordi ng_to_e_g_EEIG_S RS_and_UIC_A200_ SRS, q_media : Q_MEDIA_Balise, n_pig : N_PIG_I_am_the_1 st, n_total : N_TOTAL_1_balise_ in_the_group, m_dup : M_DUP_No_duplicat es, m_mcount : 0, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked}, linkedBGs : [{valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_s cale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_S ame_country_or_ railway_administrati on_no_NID_C_follo ws, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATIO N_The_balise_grou p_is_seen_by_the_t rain_in_reverse_dir ection, q_linkreaction : Q_LINKREACTION_ Train_trip, q_locacc : 0}, {valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_s cale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_S</pre> | |

| Name | Type | Value | Comments and Information |
|------|------|--|--------------------------|
| | | <pre>{ valid : false, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked, location : { nominal : 0, d_min : 0, d_max : 0}, seqNoOnTrack : 0, infoFromLinking : { valid : false, nid_bg_fromLinking BG : 0, nid_c_fromLinkingB G : 0, expectedLocation : { nominal : 0, d_min : 0, d_max : 0}, d_link : { nominal : 0, d_min : 0, d_max : 0}, linkingInfo : { valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_s cale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_S ame_country__or__ railway_administrati on_no_NID_C_follo ws, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATIO N_The_balise_grou p_is_seen_by_the_t rain_in_reverse_dir ection, q_linkreaction : Q_LINKREACTION_ Train_trip, q_locacc : 0}}, infoFromPassing : { valid : false, timestamp : 0, odometrystamp : {o_nominal : 0, o_min : 0, o_max : 0}, BG_centerDetection Inaccuracies : { nominal : 0, d_min : 0, d_max : 0}, BG_Header : {q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previo us_versions_accordi ng_to_e_g_EEIG_S ome ETCS open and UIC_A200_ SRS, q_media : Q_MEDIA_Balise, n_pig :</pre> | |

| Name | Type | Value | Comments and Information |
|------|------|---|--------------------------|
| | | <pre>[{ valid : false, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked, location : { nominal : 0, d_min : 0, d_max : 0 }, seqNoOnTrack : 0, infoFromLinking : { valid : false, nid_bg_fromLinkingBG : 0, nid_c_fromLinkingBG : 0, expectedLocation : { nominal : 0, d_min : 0, d_max : 0 }, d_link : { nominal : 0, d_min : 0, d_max : 0 }, linkingInfo : { valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_scale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_Same_country_or_railway_administration_no_NID_C_follows, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATION_The_balise_group_is_seen_by_the_train_in_reverse_direction, q_linkreaction : Q_LINKREACTION_Train_trip, q_locacc : 0 } }, infoFromPassing : { valid : false, timestamp : 0, odometrystamp : { o_nominal : 0, o_min : 0, o_max : 0 }, BG_centerDetectionInaccuracies : { nominal : 0, d_min : 0, d_max : 0 }, BG_Header : { q_updown : Q_UPDOWN_Downlink_telegram, m_version : M_VERSION_Previous_versions_according_to_e_g_EEIG_Some_ETCS, q_uic : UIC_A200_SRS, q_media : Q_MEDIA_Balise, n_pig :</pre> | |

| Name | Type | Value | Comments and Information |
|-------------------|---|--|--------------------------------|
| cNoPositionErrors | TrainPosition_Types _Pck::positionErrors _T | { outOfMemSpace : false, passedBG_notFound WhereExpected : false, positionCalculation_ inconsistent : false} | |
| cNoValidIndex | int | -1 | Comments: An invalid index. |
| cTrainPosition_0 | TrainPosition_Types _Pck::trainPosition_ T | { valid : false, timestamp : 0, trainPositionIsUnkn own : false, noCoordinateSyste mHasBeenAssigned : false, trainPosition : { nominal : 0, d_min : 0, d_max : 0}, estimatedFrontEndP osition : 0, minSafeFrontEndPo sition : 0, maxSafeFrontEndPo sition : 0, nid_LRBG : 0, nid_PrivLRB : 0, nominalOrReverseT oLRBG : Q_DLRBG_Reverse, trainOrientationToL RBG : Q_DIRLRBG_Revers e, trainRunningDirecti onToLRBG : Q_DIRTRAIN_Rever se, speed : 0} | |

15.1.4. calculateBGLocations Operator

Declared as **private node**

15.1.4.1. Comments and Information

calculateBGLocations Comments:

- Calculation of the locations of passed and announced BGs

Table 139: calculateBGLocations Annotations

| Note Name | Attribute | Value |
|-----------|-----------|-----------------------|
| GdC_1 | Author | Author : Uwe Steinke |
| | DateC | Created : 2014-15-22 |
| | DateM | Modified : 2014-06-03 |
| | Version | No 00.03.00 |
| | to_c | True |

| Note Name | Attribute | Value |
|-----------|-------------|--|
| Remark_1 | Description | <p>The main function calculating the actual train position.</p> <ul style="list-style-type: none"> - Description: Calculates the actual train position based on passed balise groups - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.1.4.2. Interface

Table 140: Inputs of calculateBGLocations

| Name | Type | Comments and Information |
|----------|--|--|
| passedBG | BG_Types_Pkg::passedBG_T | Comments: Input event reporting a balise group during its passage, if there is one. |
| lastBGs | TrainPosition_Types_Pkg::positionedBGs_T | Comments: The last collection of currently known BGs. |
| reset | bool | Comments: Resets all to an initial state and deletes all stored BGs. |

Table 141: Outputs of calculateBGLocations

| Name | Type | Comments and Information |
|--------|---|---|
| BGs | TrainPosition_Types_Pkg::positionedBGs_T | Comments: The collection of currently known BGs. |
| errors | TrainPosition_Types_Pkg::positionErrors_T | |

15.1.4.3. Locals

Table 142: Locals of calculateBGLocations

| Name | Type | Comments and Information |
|--------------------------------|------|--------------------------|
| outOfMemSpace | bool | |
| passedBG_notFoundWhereExpected | bool | |

15.1.4.4. Operator Hierarchy

diagram : diagram_errorReporting

diagram : diagram_passing_a_BG

15.1.4.5. Graphical and Textual Diagrams

15.1.4.5.1. View of diagram_errorReporting (calculateBGLocations)

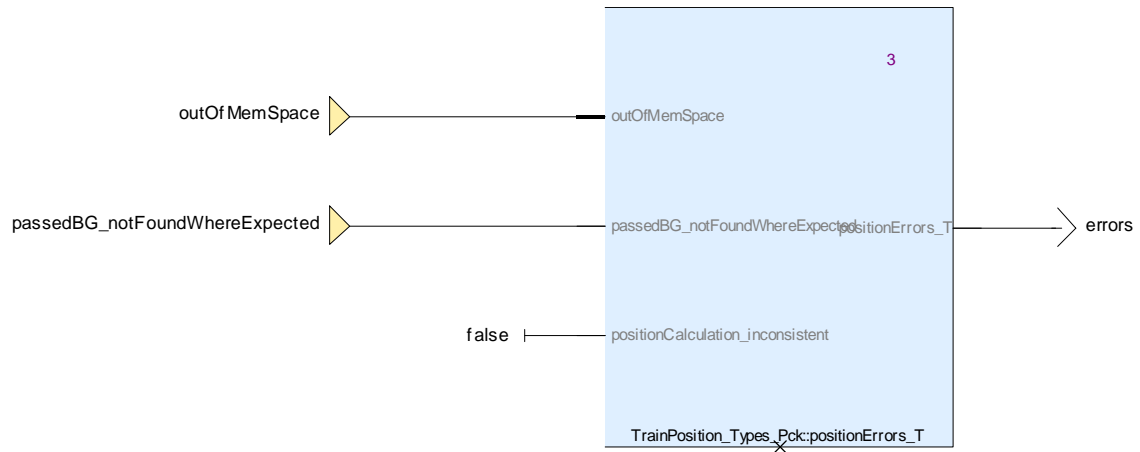


Figure 44: View of diagram_errorReporting (calculateBGLocations)

15.1.4.5.2. View of diagram_passing_a_BG (calculateBGLocations)

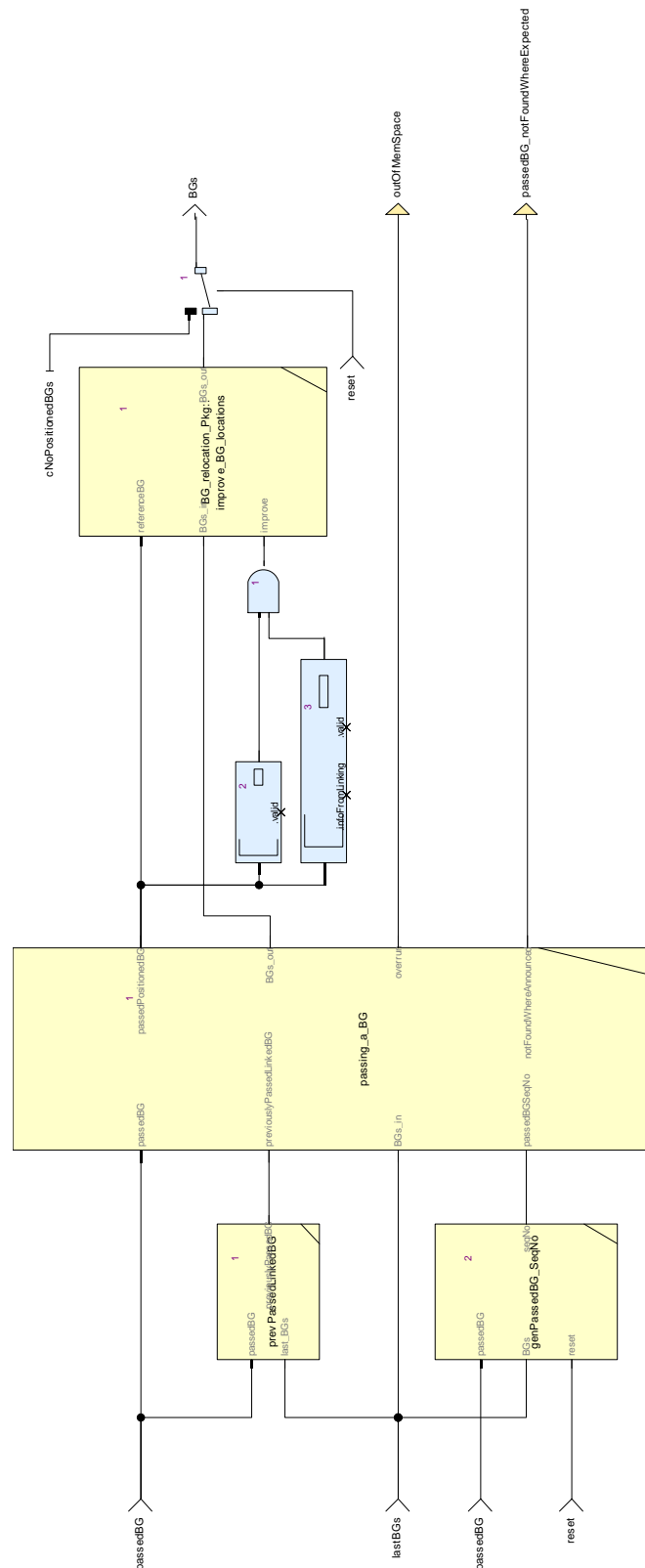


Figure 45: View of diagram_passing_a_BG (calculateBGLocations)

15.1.5. calculateTrainPosition Operator

Declared as **public node**

15.1.5.1. Comments and Information

calculateTrainPosition Comments:

- The main function calculating the locations of balise groups and the actual train position.

Table 143: calculateTrainPosition Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Author : Uwe Steinke |
| | DateC | Created : 2014-15-22 |
| | DateM | Modified : 2014-06-03 |
| | Version | No 00.03.00 |
| | to_c | True |
| Remark_1 | Description | <p>The main function calculating the actual train position.</p> <ul style="list-style-type: none"> - Description: Calculates the actual train position based on passed balise groups - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.1.5.2. Interface

Table 144: Inputs of calculateTrainPosition

| Name | Type | Properties | Comments and Information |
|-----------------|---|------------|--|
| currentOdometry | Obu_BasicTypes_Pkg::odometry_T | | Comments: The current odometry values |
| passedBG | BG_Types_Pkg::passedBG_T | | Comments: Input event reporting a balise group during its passage, if there is one. |
| LRBG | TrainPosition_Types_Pkg::positionedBG_T | | Comments: The LRBG used for RBC communication. |
| prevLRBG | TrainPosition_Types_Pkg::positionedBG_T | | Comments: A previously used LRBG used in RBC communication. |

| Name | Type | Properties | Comments and Information |
|-----------------|--|------------|---|
| reset | bool | | Comments: Resets all to an initials state and deletes all stored BGs. |
| trainProperties | TrainPosition_Types_Pc k::trainProperties_T | hidden | Comments: The trains properties required for train position calculation. |

Table 145: Outputs of calculateTrainPosition

| Name | Type | Comments and Information |
|-------------------|--|--|
| trainPosition | TrainPosition_Types_Pc k::trainPosition_T | Comments: The resulting train position with reference to the LRBG |
| trainPositionInfo | TrainPosition_Types_Pc k::trainPositionInfo_T | Comments: The resulting train position with reference to the known list of balise groups. |
| BGs | TrainPosition_Types_Pc k::positionedBGs_T | Comments: The collection of currently known BGs. |
| errors | TrainPosition_Types_Pc k::positionErrors_T | Comments: Errors and inconsistencies detected by the calculation. |

15.1.5.3. Locals

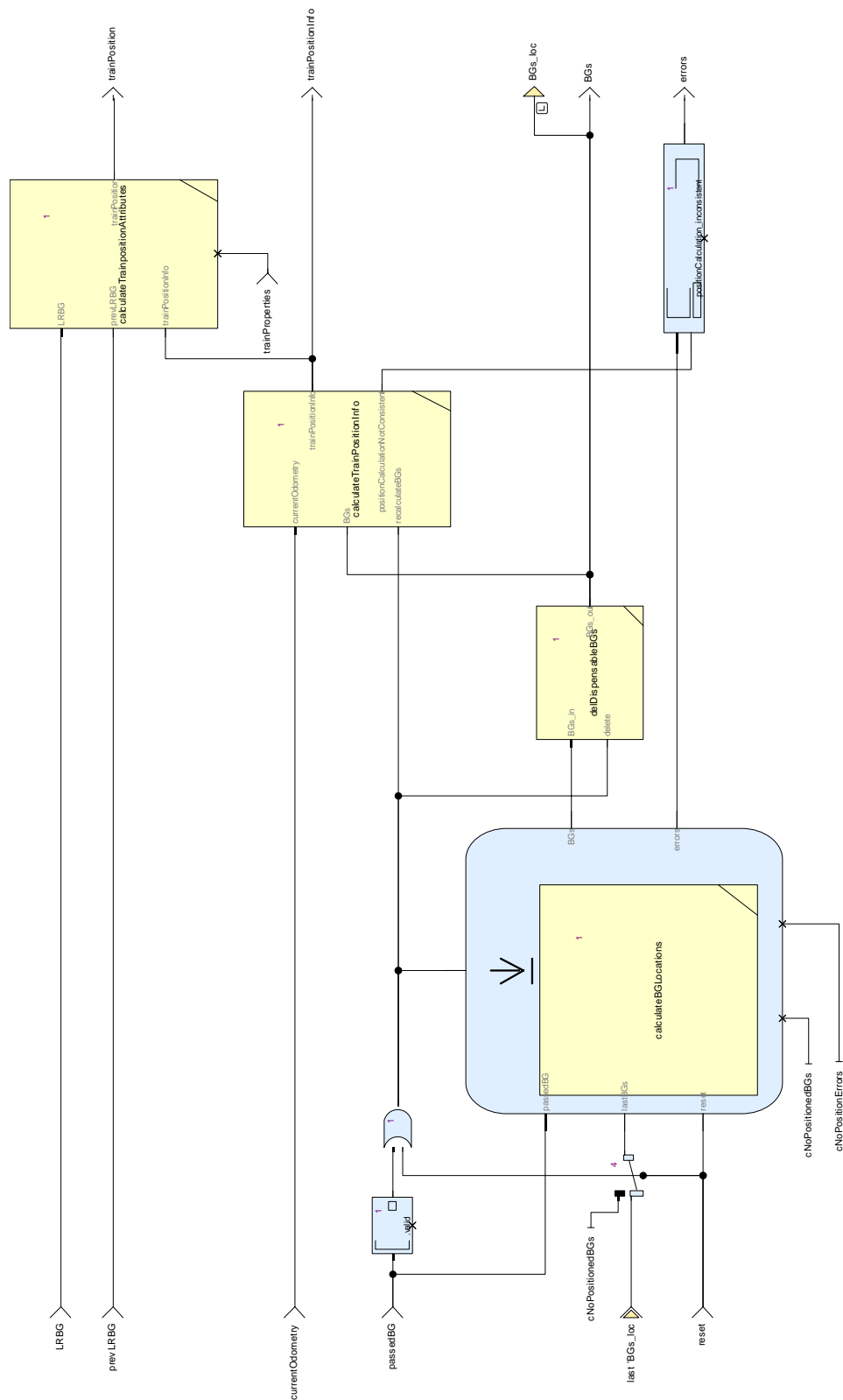
Table 146: Locals of calculateTrainPosition

| Name | Type | Properties | Comments and Information |
|---------|--|------------------------------|--------------------------|
| BGs_loc | TrainPosition_Types_Pc k::positionedBGs_T | last cNoPositioned BGs | |

15.1.5.4. Operator Hierarchy

diagram : diagram_calculateTrainPosition

15.1.5.5.1. View of diagram_calculateTrainPosition (calculateTrainPosition)



15.1.6. calculateTrainpositionAttributes Operator

Declared as **private function**

15.1.6.1. Comments and Information

calculateTrainpositionAttributes Comments:

- Figures out the attributes of the current train position with reference to a given LRBG.

Table 147: calculateTrainpositionAttributes Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Author : Uwe Steinke |
| | DateC | Created : 2014-15-22 |
| | DateM | Modified : 2014-06-03 |
| | Version | No 00.03.00 |
| | to_c | True |
| Remark_1 | Description | <p>The main function calculating the actual train position.</p> <ul style="list-style-type: none"> - Description: Calculates the actual train position based on passed balise groups - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.1.6.2. Interface

Table 148: Inputs of calculateTrainpositionAttributes

| Name | Type | Properties | Comments and Information |
|-------------------|--|------------|--|
| LRBG | TrainPosition_Types_Pc k::positionedBG_T | | Comments: The LRBG used for RBC communication. |
| prevLRBG | TrainPosition_Types_Pc k::positionedBG_T | | Comments: A previously used LRBG used in RBC communication. |
| trainPositionInfo | TrainPosition_Types_Pc k::trainPositionInfo_T | | Comments: The resulting train position with reference to the known list of balise groups. |

| Name | Type | Properties | Comments and Information |
|-----------------|--|------------|--|
| trainProperties | TrainPosition_Types_Pc k::trainProperties_T | hidden | Comments: The trains properties required for train position calculation. |

Table 149: Outputs of calculateTrainpositionAttributes

| Name | Type | Comments and Information |
|---------------|--|---|
| trainPosition | TrainPosition_Types_Pc k::trainPosition_T | Comments: The resulting train position with reference to the LRBG |

15.1.6.3. Operator Hierarchy

diagram : diagram_calculateTrainpositionAttributes

15.1.6.4. Graphical and Textual Diagrams

15.1.6.4.1. View of diagram_calculateTrainpositionAttributes (calculateTrainpositionAttributes)

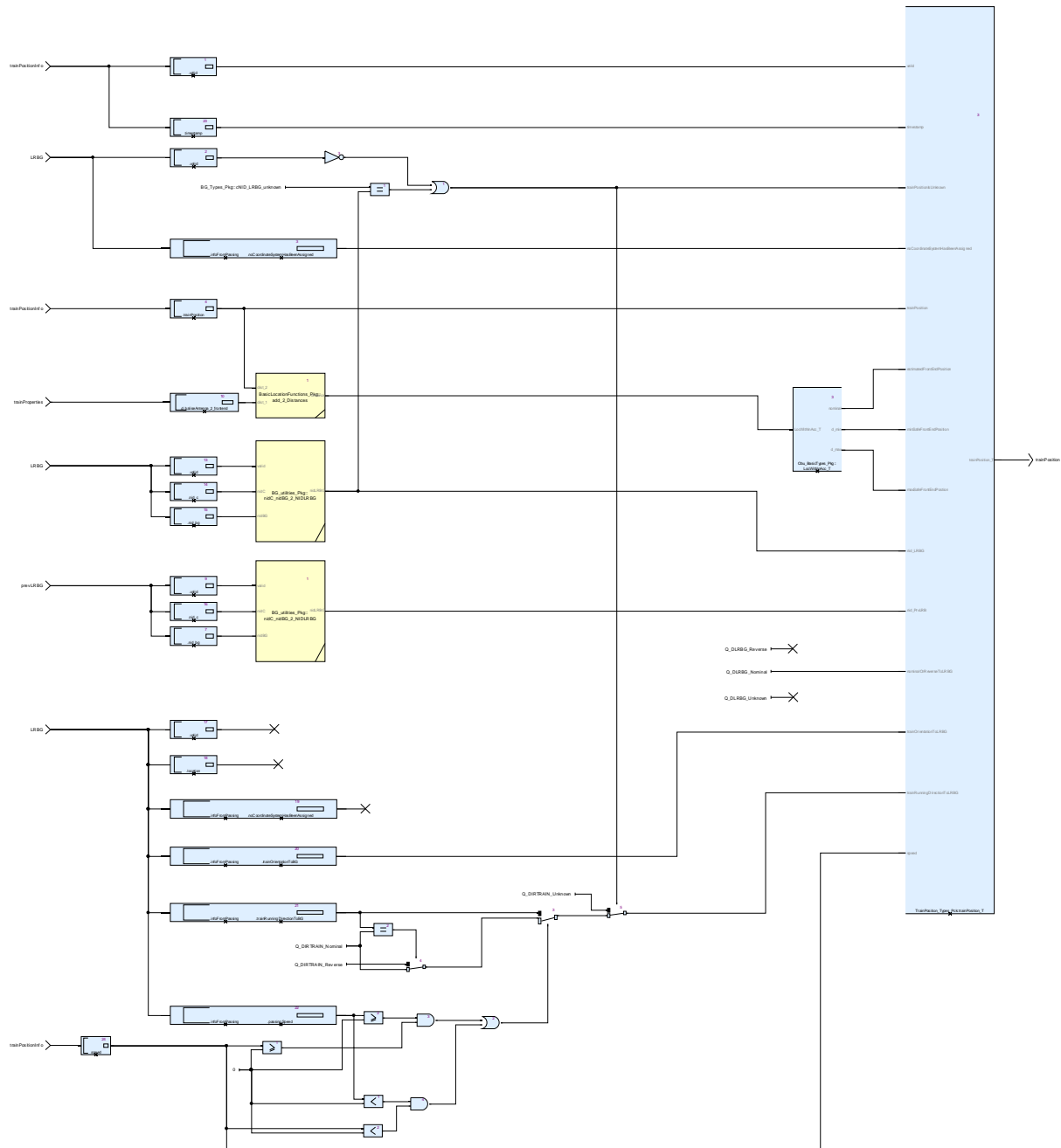


Figure 47: View of diagram_calculateTrainpositionAttributes (calculateTrainpositionAttributes)

15.1.7. calculateTrainPositionInfo Operator

Declared as **private function**

15.1.7.1. Comments and Information

calculateTrainPositionInfo Comments:

- Provides the train position information.

15.1.7.2. Interface

Table 150: Inputs of calculateTrainPositionInfo

| Name | Type | Comments and Information |
|-----------------|--|---|
| currentOdometry | Obu_BasicTypes_Pkg:: odometry_T | Comments: The current odometry values |
| BGs | TrainPosition_Types_Pc k::positionedBGs_T | |
| recalculateBGs | bool | Comments: Triggers the recalculation of the last linked and unlinked BGs. |

Table 151: Outputs of calculateTrainPositionInfo

| Name | Type | Comments and Information |
|--------------------------------------|--|---|
| trainPositionInfo | TrainPosition_Types_Pc k::trainPositionInfo_T | Comments: The resulting train position with reference to the known list of balise groups. |
| positionCalculationNot Consistent | bool | |

15.1.7.3. Operator Hierarchy

diagram : diagram_calculateTrainPositionInfo_1

15.1.7.4.1. View of diagram_calculateTrainPositionInfo_1 (calculateTrainPositionInfo)

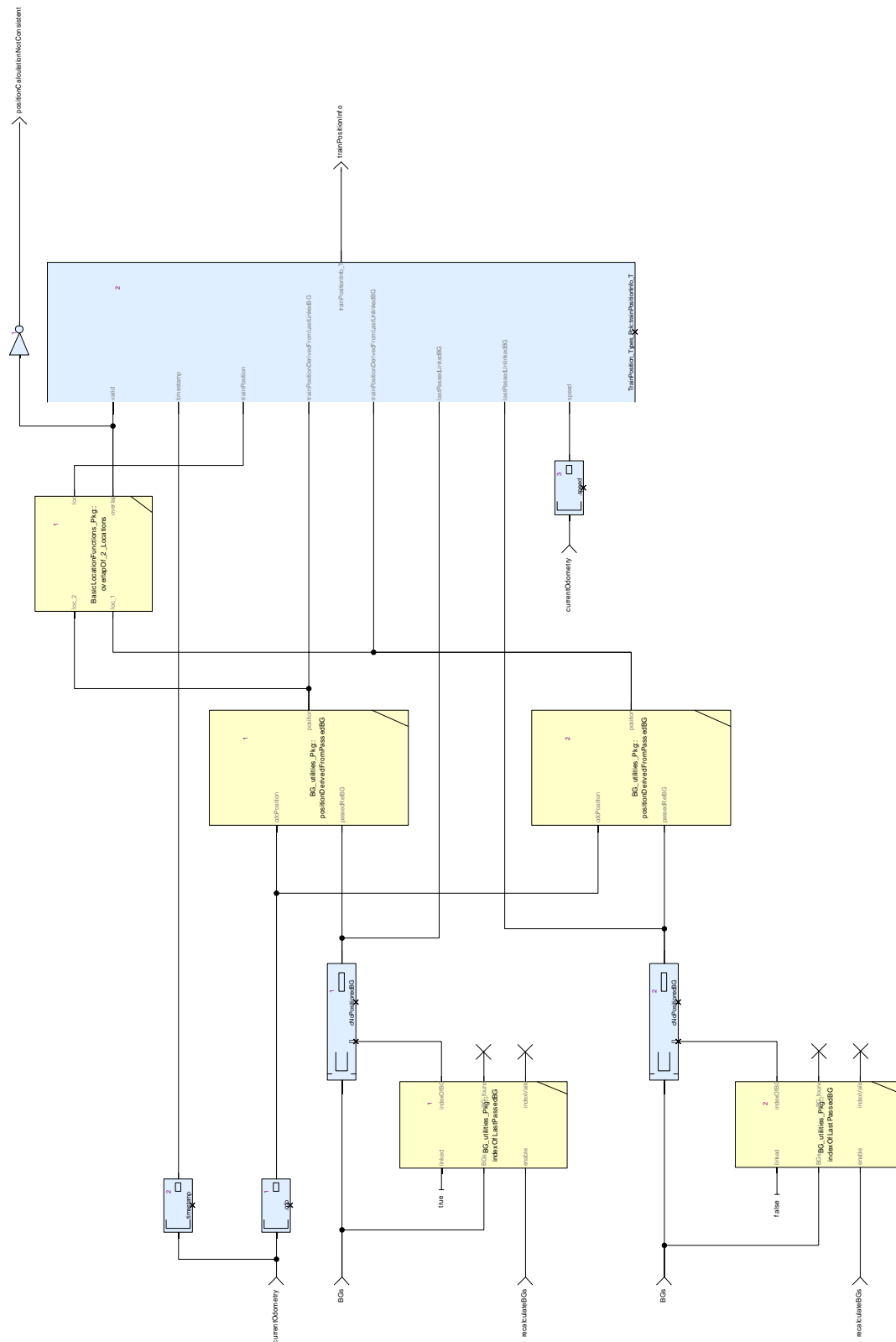


Figure 48: View of diagram_calculateTrainPositionInfo_1 (calculateTrainPositionInfo)

15.1.8. delDispensableBGs Operator

Declared as **private function**

15.1.8.1. Comments and Information

delDispensableBGs Comments:

- Deletes dispensable BGs.
- As dispensable are seen
- - if at least on passed linked BGs exist: all BGs prior to the last cNoOfAtLeast_8_LRBGs linked BGs (covers 3.6.2.2 c)).
- - if no passed linked BGs exist: all BGs prior to the last cNoOfAtLeast_2_unlinkedBGs unlinked BGs.

15.1.8.2. Interface

Table 152: Inputs of delDispensableBGs

| Name | Type | Comments and Information |
|--------|--|---|
| BGs_in | TrainPosition_Types_Pc k::positionedBGs_T | Comments: The collection of BGs as known before passedBG was passed. |
| delete | bool | |

Table 153: Outputs of delDispensableBGs

| Name | Type | Comments and Information |
|---------|--|---|
| BGs_out | TrainPosition_Types_Pc k::positionedBGs_T | Comments: The collection of BGs as known when passedBG was passed. |

15.1.8.3. Locals

Table 154: Locals of delDispensableBGs

| Name | Type | Comments and Information |
|------------------------|------|--------------------------|
| passedLinkedBGsCount | int | |
| passedUnlinkedBGsCount | int | |

15.1.8.4. Operator Hierarchy

diagram : diagram_delDispensableBGs_1

```
activate if : IfBlock1
  branch : then
  branch : else
```

15.1.8.5. Graphical and Textual Diagrams

15.1.8.5.1. View of diagram_delDispensableBGs_1 (delDispensableBGs)

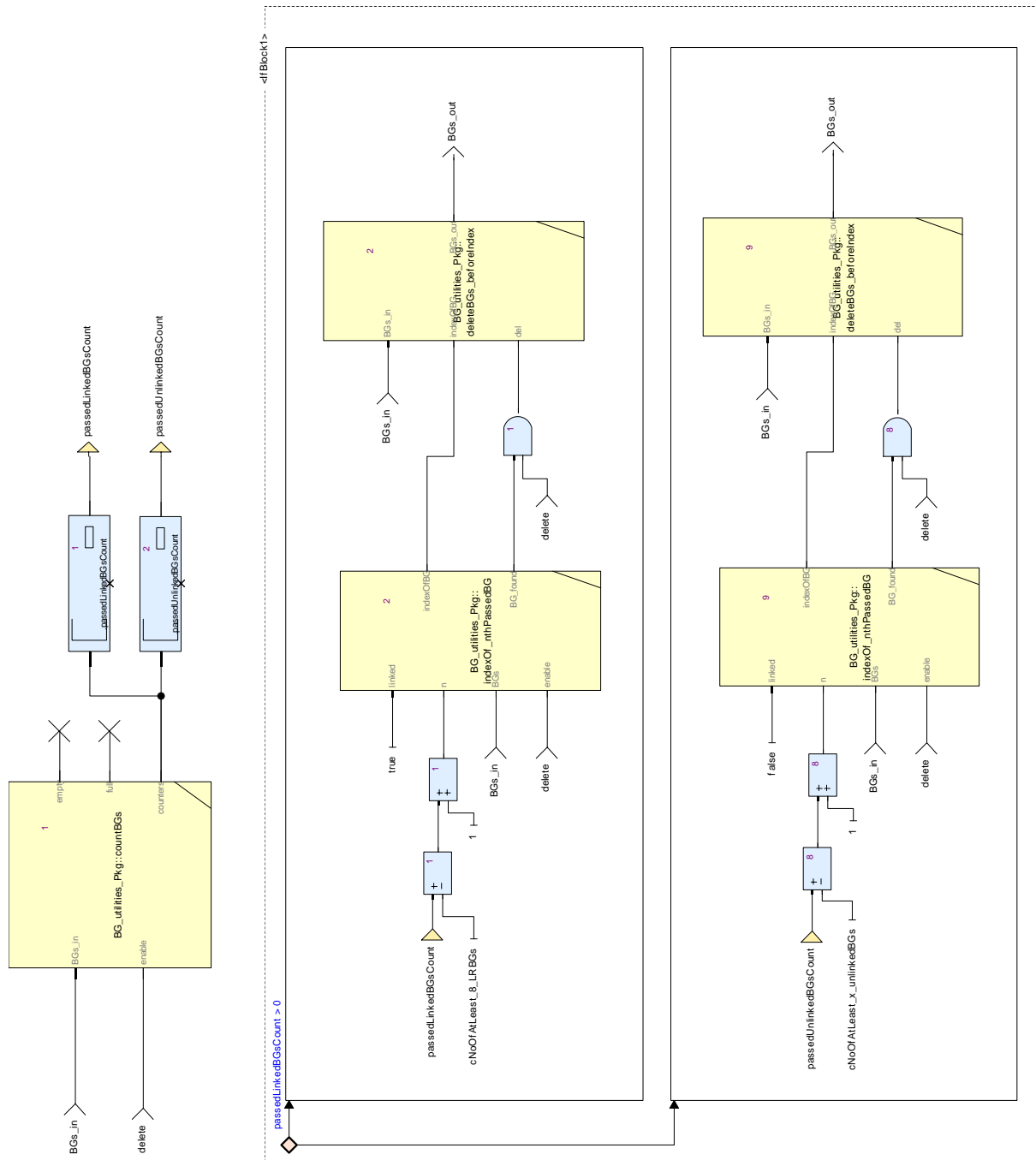


Figure 49: View of diagram_delDispensableBGs_1 (delDispensableBGs)

Table 155: Conditional Blocks of diagram_delDispensableBGs_1

| Conditional Block | Comments and Information |
|-------------------|--------------------------|
| IfBlock1 | |

Table 156: Actions of diagram_delDispensableBGs_1

| Conditional Block Action | Comments and Information |
|--------------------------|--------------------------|
| IfBlock1:then | |

| Conditional Block Action | Comments and Information |
|--------------------------|--------------------------|
| IfBlock1:else | |

15.1.9. genPassedBG_SeqNo Operator

Declared as **private node**

15.1.9.1. Comments and Information

genPassedBG_SeqNo Comments:

- Generates a sequence number for every passed BG. The sequence no is intended to be an order criterion for the BGs on the track.
- If a BG was already passed before, it's sequence no is preserved.

15.1.9.2. Interface

Table 157: Inputs of genPassedBG_SeqNo

| Name | Type | Comments and Information |
|----------|--|--|
| passedBG | BG_Types_Pkg::passedBG_T | Comments: Input event reporting a balise group during its passage, if there is one. |
| BGs | TrainPosition_Types_Pkg::positionedBGs_T | |
| reset | bool | Comments: Resets all to an initials state and deletes all stored BGs. |

Table 158: Outputs of genPassedBG_SeqNo

| Name | Type | Comments and Information |
|-------|------|--------------------------|
| seqNo | int | |

15.1.9.3. Locals

Table 159: Locals of genPassedBG_SeqNo

| Name | Type | Comments and Information |
|-------------------|------|--------------------------|
| incrPassedBGSeqNo | bool | |
| keepPassedBGSeqNo | bool | |

15.1.9.4. Operator Hierarchy

diagram : diagram_genPassedBG_SeqNo_1

15.1.9.5. Graphical and Textual Diagrams

15.1.9.5.1. View of diagram_genPassedBG_SeqNo_1 (genPassedBG_SeqNo)

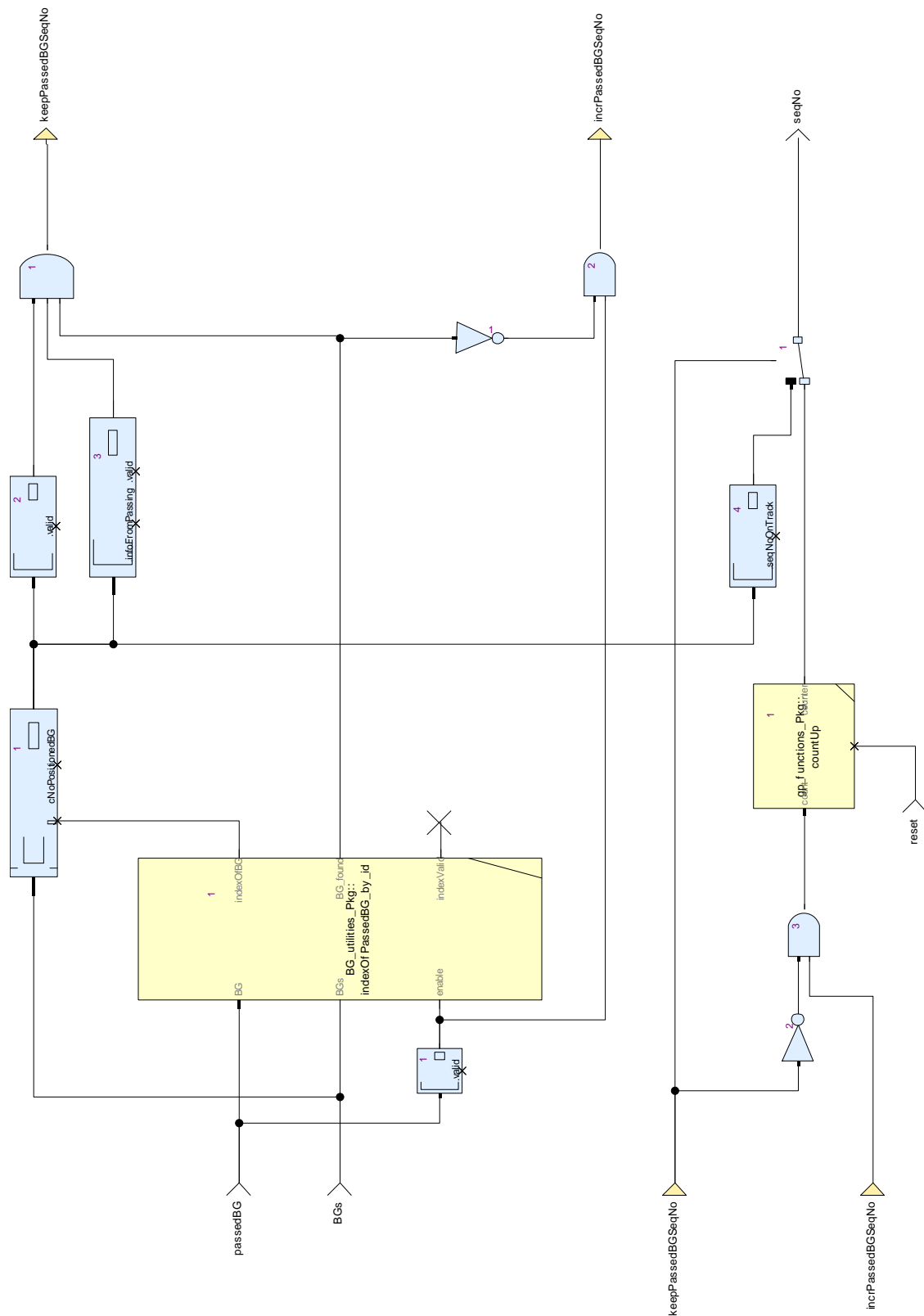


Figure 50: View of diagram_genPassedBG_SeqNo_1 (genPassedBG_SeqNo)

15.1.10. memPassedBG Operator

Declared as **private node**

15.1.10.1. Comments and Information

memPassedBG Comments:

- Memorizes the passed linked and unlinked BG

Table 160: memPassedBG Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Memorizes the passed linked and unlinked BG</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.1.10.2. Interface

Table 161: Inputs of memPassedBG

| Name | Type | Comments and Information |
|--------------------|---|--|
| passedBG | TrainPosition_Types_Pc k::positionedBG_T | |
| prevPassedLinkedBG | TrainPosition_Types_Pc k::positionedBG_T | Comments: The previously passed linked BG as a reference location for improvement of an unlinked BG location. |
| reset | bool | |

Table 162: Outputs of memPassedBG

| Name | Type | Comments and Information |
|----------------|---|--------------------------|
| passedLinkedBG | TrainPosition_Types_Pc k::positionedBG_T | |

| Name | Type | Comments and Information |
|------------------|---|--------------------------|
| passedUnlinkedBG | TrainPosition_Types_Pc k::positionedBG_T | |

15.1.10.3. Locals

Table 163: Locals of memPassedBG

| Name | Type | Properties | | Comments and Information |
|----------------------|---|------------|---------------------|--------------------------|
| passedUnlinkedBG_loc | TrainPosition_Types_Pc k::positionedBG_T | last | cNoPositioned BG | |

15.1.10.4. Operator Hierarchy

diagram : diagram_memPassedBG_1

15.1.10.5. Graphical and Textual Diagrams

15.1.10.5.1. View of diagram_memPassedBG_1 (memPassedBG)

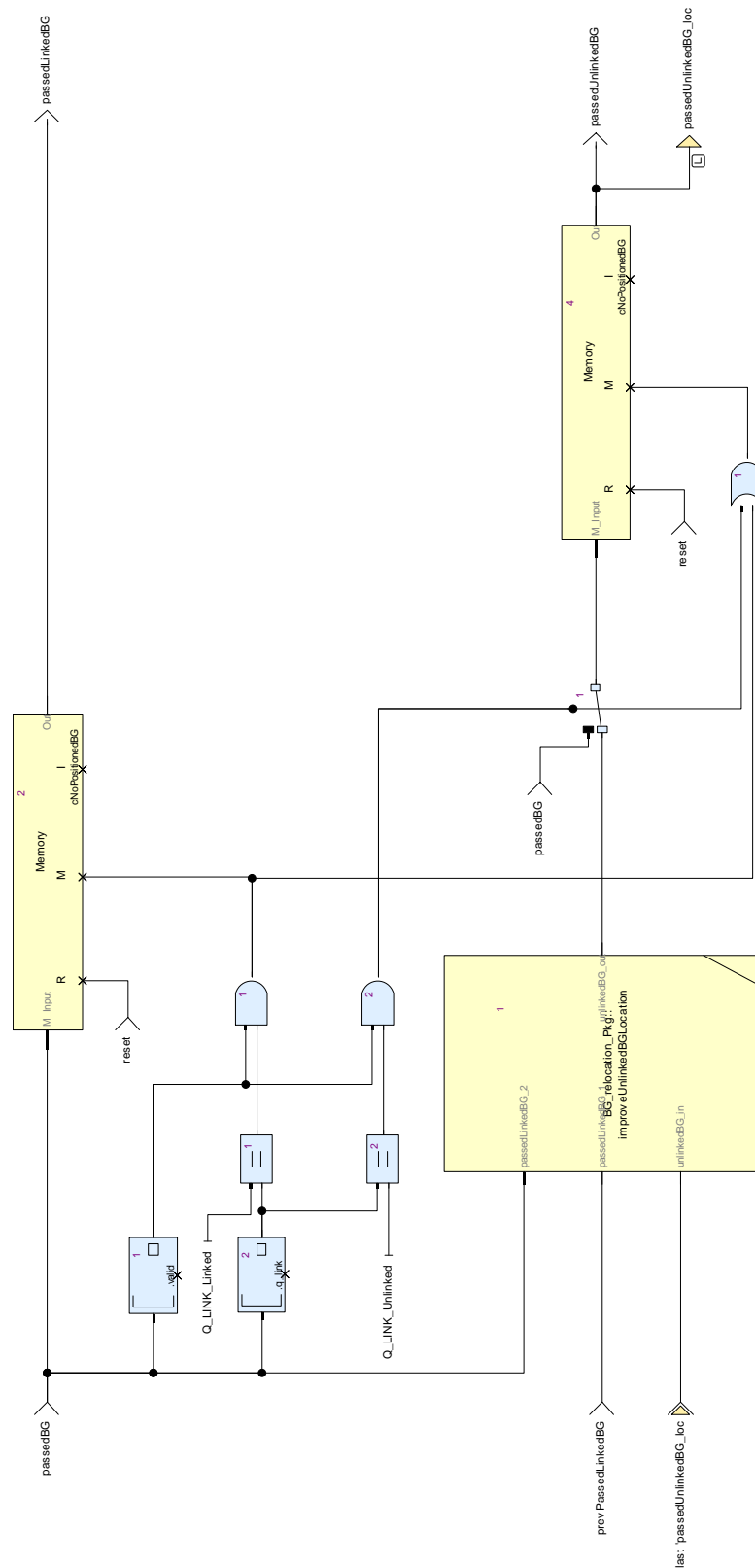


Figure 51: View of diagram_memPassedBG_1 (memPassedBG)

15.1.11. passedBG_2_positionedBG Operator

Declared as **private function**

15.1.11.1. Comments and Information

passedBG_2_positionedBG Comments:

- Converts a passed balise group information to a positioned balise group information and calculates the location of the passed BG.

Table 164: passedBG_2_positionedBG Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Converts a passed balise group to a positioned balise group information</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.1.11.2. Interface

Table 165: Inputs of passedBG_2_positionedBG

| Name | Type | Comments and Information |
|--------------------------|---|---|
| passedBG | BG_Types_Pkg::passedBG_T | Comments: The balise group as actually passed. |
| passedBG_asAnnounced | TrainPosition_Types_Pkg::positionedBG_T | Comments: If the passed balise group was previously announced, this is the passed BG as known before passing. If the passed balise group was not announced, this input has to be set invalid. |
| previouslyPassedLinkedBG | TrainPosition_Types_Pkg::positionedBG_T | Comments: The previously passed linked BG, if there is one. Serves a reference point for location calculation. |

| Name | Type | Comments and Information |
|---------------|------|--|
| passedBGSeqNo | int | Comments: Sequence no of the just passed BG |

Table 166: Outputs of passedBG_2_positionedBG

| Name | Type | Properties | | Comments and Information |
|------------------------|--|------------|-------|---|
| passedPositionedBG | TrainPosition_Types_Pck::positionedBG_T | | | Comments: The passed and positioned balise group. If the BG was announced by linking information previously, the linking and the passing information are merged together. If the BG was not announced before, only the passing information is evaluated. |
| notFoundWhereAnnounced | bool | default | false | Comments: Indicates that the location of the passed BG does not fit into the range, where it was expected by the linking information. |
| linkedBGs | TrainPosition_Types_Pck::linkedBGs_asPositionedBGs_T | | | Comments: The balise groups linked with the passed BG. |

15.1.11.3. Locals

Table 167: Locals of passedBG_2_positionedBG

| Name | Type | Comments and Information |
|-----------------------------|---|--|
| BG_wasAnnounced | bool | Comments: Indicates, that the BG was previously announced with linking information and the signature is consistent. |
| location | Obu_BasicTypes_Pkg::LocWithInAcc_T | |
| passedPositionedBG_location | TrainPosition_Types_Pck::positionedBG_T | |

15.1.11.4. Operator Hierarchy

diagram : diagram_calculateDistance

activate if : ifAnnouncedOrABGWasPreviouslyPassed

 branch : then

 branch : else

 branch : then

 branch : else

 branch : then

 branch : else

diagram : diagram_checkAnnouncedInfo

diagram : diagram_passedBG_2_positionedBG

diagram : diagram_positionLinkedBGs

15.1.11.5. Graphical and Textual Diagrams

15.1.11.5.1. View of diagram_calculateDistance (passedBG_2_positionedBG)

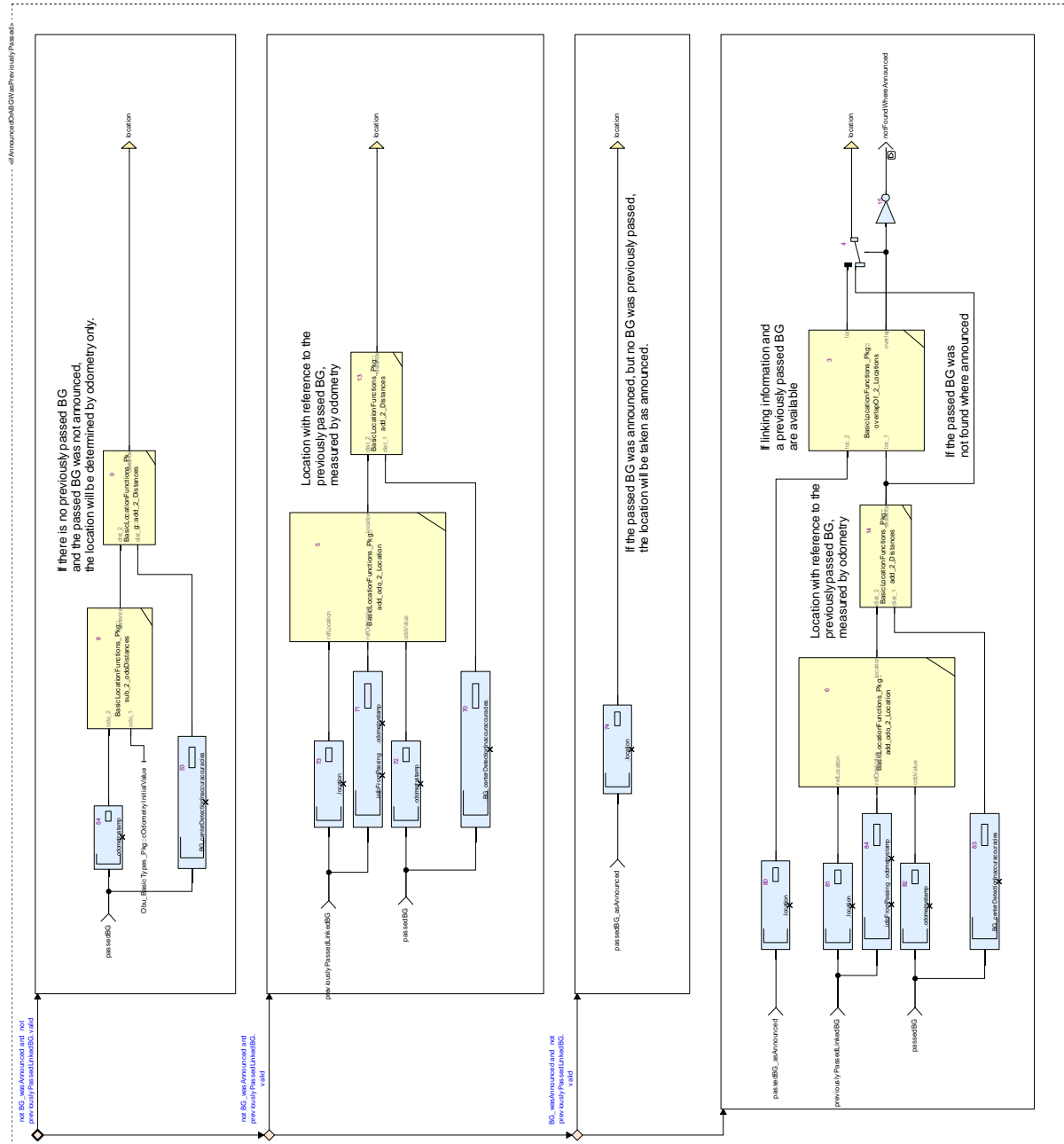


Figure 52: View of diagram_calculateDistance (passedBG_2_positionedBG)

diagram_calculateDistance Comments:

- Calculates the location of the passed balise group, dependant on if it was announced by linking or not and if another BG was previously passed or not.

Table 168: Conditional Blocks of diagram_calculateDistance

| Conditional Block | Comments and Information |
|-------------------------------------|--------------------------|
| ifAnnouncedOrABGWasPreviouslyPassed | |

Table 169: Actions of diagram_calculateDistance

| Conditional Block Action | Comments and Information |
|---|--------------------------|
| ifAnnouncedOrABGWasPreviouslyPassed: then | |
| ifAnnouncedOrABGWasPreviouslyPassed: else: then | |
| ifAnnouncedOrABGWasPreviouslyPassed: else: else: then | |
| ifAnnouncedOrABGWasPreviouslyPassed: else: else: else | |

15.1.11.5.2. View of diagram_checkAnnouncedInfo (passedBG_2_positionedBG)

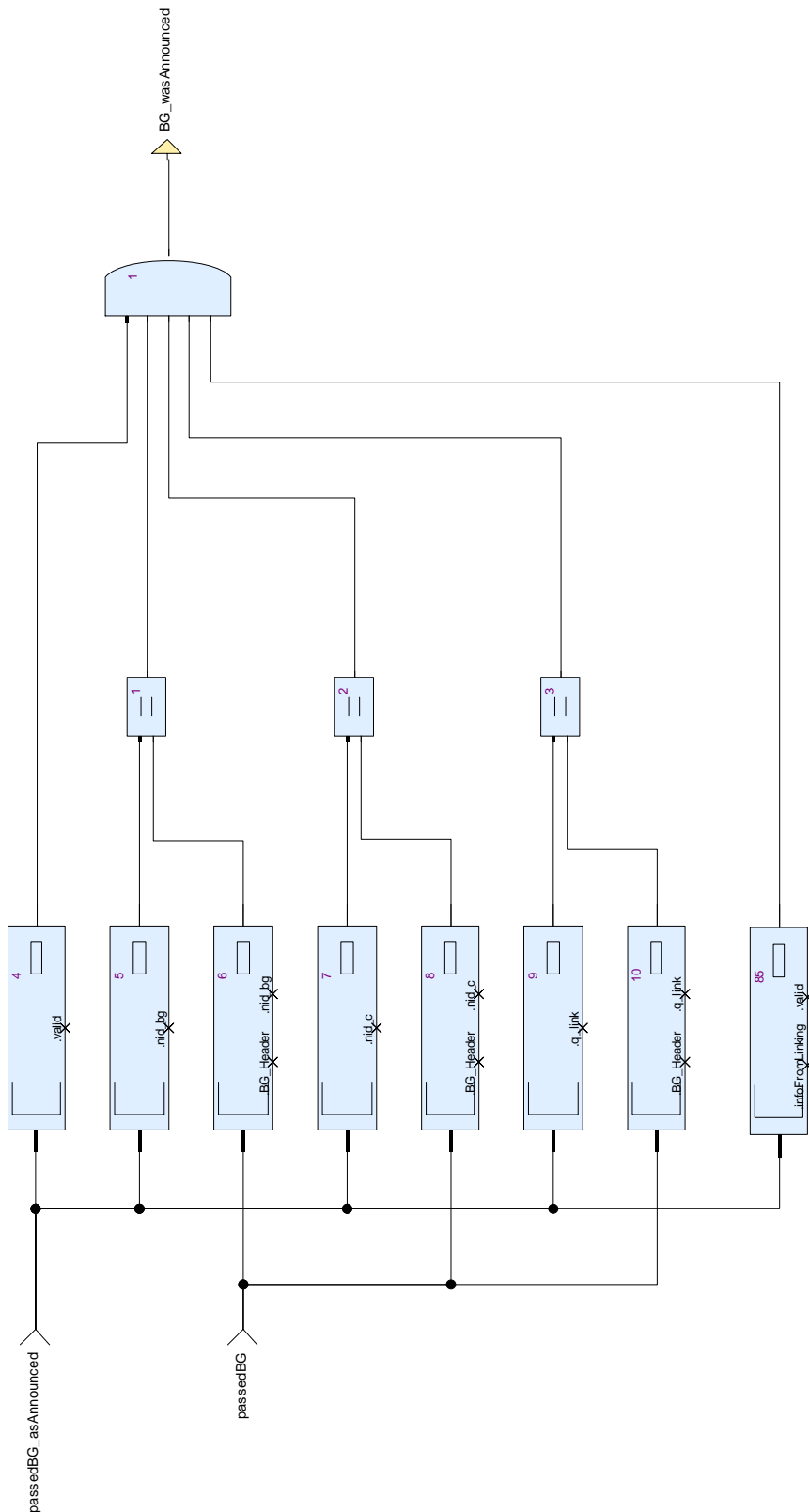


Figure 53: View of diagram_checkAnnouncedInfo (passedBG_2_positionedBG)

diagram_checkAnnouncedInfo Comments:

- Checks if the passed BG was announced with linking information.

[illegible]

Figure 54: View of diagram_passedBG_2_positionedBG (passedBG_2_positionedBG)

15.1.11.5.4. View of diagram_positionLinkedBGs (passedBG_2_positionedBG)

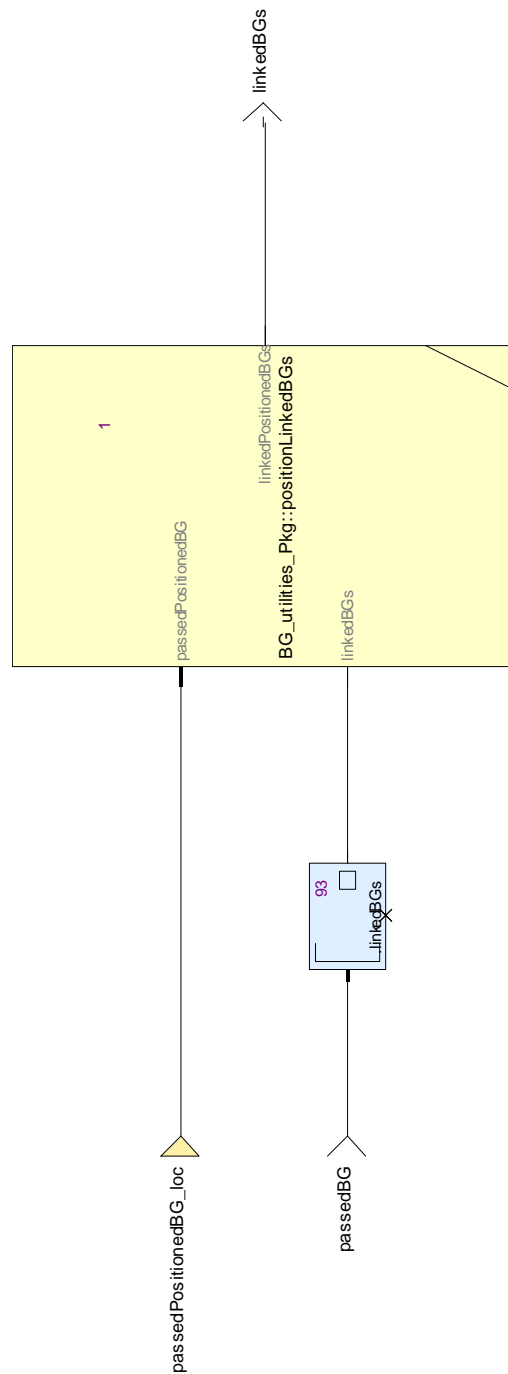


Figure 55: View of diagram_positionLinkedBGs (passedBG_2_positionedBG)

15.1.12. passing_a_BG Operator

Declared as **private function**

15.1.12.1. Comments and Information

passing_a_BG Comments:

- Provides the location calculations while passing a BG

Table 170: passing_a_BG Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Provides the location calculations while passing a BG</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.1.12.2. Interface

Table 171: Inputs of passing_a_BG

| Name | Type | Comments and Information |
|--------------------------|--|---|
| passedBG | BG_Types_Pkg::passedBG_T | |
| previouslyPassedLinkedBG | TrainPosition_Types_Pkg::positionedBG_T | Comments: The previously passed linked BG, if there is one. Serves a reference point for location calculation. |
| BGs_in | TrainPosition_Types_Pkg::positionedBGs_T | Comments: The collection of BGs as known before passedBG was passed. |
| passedBGSeqNo | int | Comments: Sequence no of the just passed BG |

Table 172: Outputs of passing_a_BG

| Name | Type | Comments and Information |
|--------------------|--|---|
| passedPositionedBG | TrainPosition_Types_Pkg::positionedBG_T | Comments: The passed and positioned balise group. If the BG was announced by linking information previously, the linking and the passing information are merged together. If the BG was not announced before, only the passing information is evaluated. |
| BGs_out | TrainPosition_Types_Pkg::positionedBGs_T | Comments: The collection of BGs as known when passedBG was passed. |

| Name | Type | Comments and Information |
|------------------------|------|--|
| overrun | bool | Comments: Indicates, that not all of the elements of BGs_2 could be merged into BGs_out, due to not enough space in BGs_out. |
| notFoundWhereAnnounced | bool | Comments: Indicates that the location of the passed BG does not fit into the range, where it was expected by the linking information. |

15.1.12.3. Operator Hierarchy

diagram : diagram_passing_a_BG_1

15.1.12.4.1. View of diagram_passing_a_BG_1 (passing_a_BG)

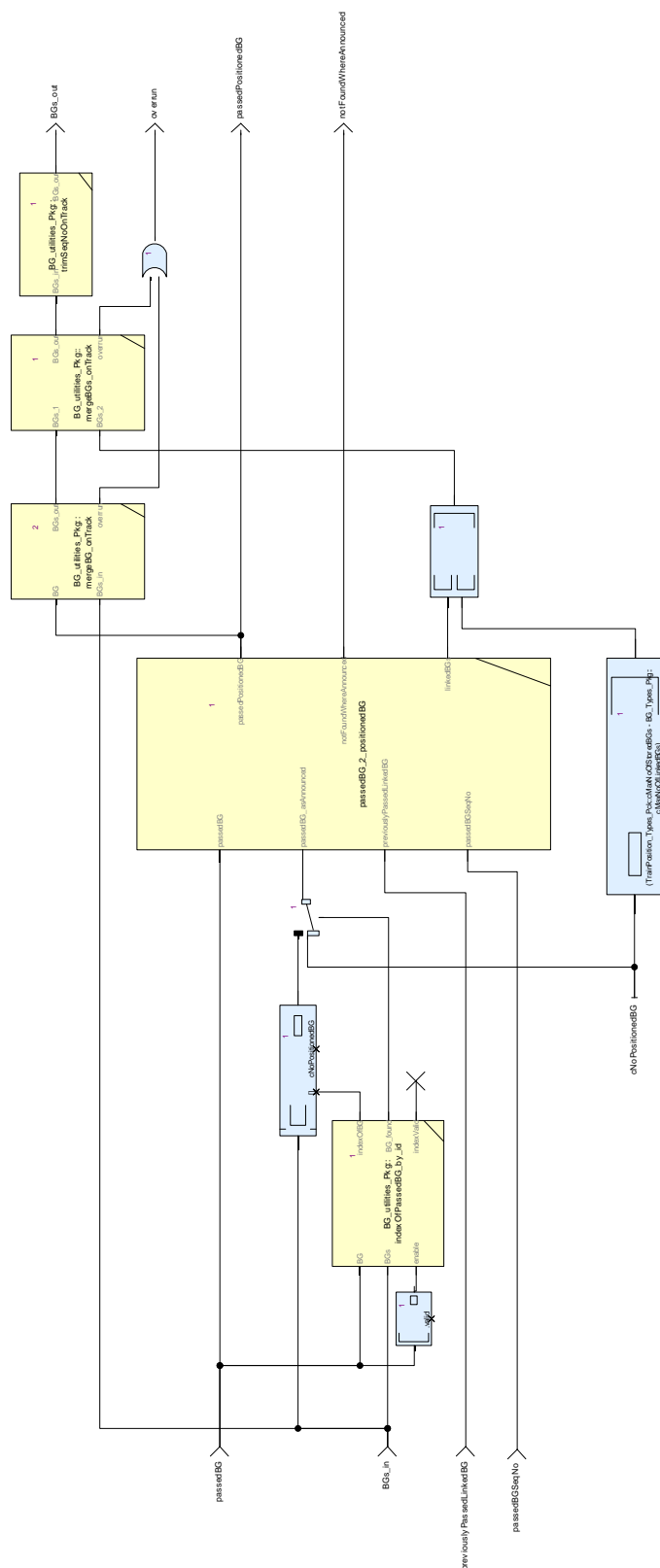


Figure 56: View of diagram_passing_a_BG_1 (passing_a_BG)

15.1.13. prevPassedLinkedBG Operator

Declared as **private function**

15.1.13.1. Comments and Information

prevPassedLinkedBG Comments:

- Memorizes the previously passed BG when a new BG is passed and the IDs are different

Table 173: prevPassedLinkedBG Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Memorizes the previously passed BG when a new BG is passed and the IDs are different.</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.1.13.2. Interface

Table 174: Inputs of prevPassedLinkedBG

| Name | Type | Comments and Information |
|----------|--|--|
| passedBG | BG_Types_Pkg::passedBG_T | Comments: The currently passed BG |
| last_BGs | TrainPosition_Types_Pkg::positionedBGs_T | Comments: The current collection of BGs before the passed BG was found. |

Table 175: Outputs of prevPassedLinkedBG

| Name | Type | Comments and Information |
|--------------------|---|--|
| previouslyPassedBG | TrainPosition_Types_Pkg::positionedBG_T | Comments: The previously passed linked BG |

15.1.13.3. Operator Hierarchy

diagram : diagram_prevPassedLinkedBG_1

15.1.13.4. Graphical and Textual Diagrams

15.1.13.4.1. View of diagram_prevPassedLinkedBG_1 (prevPassedLinkedBG)

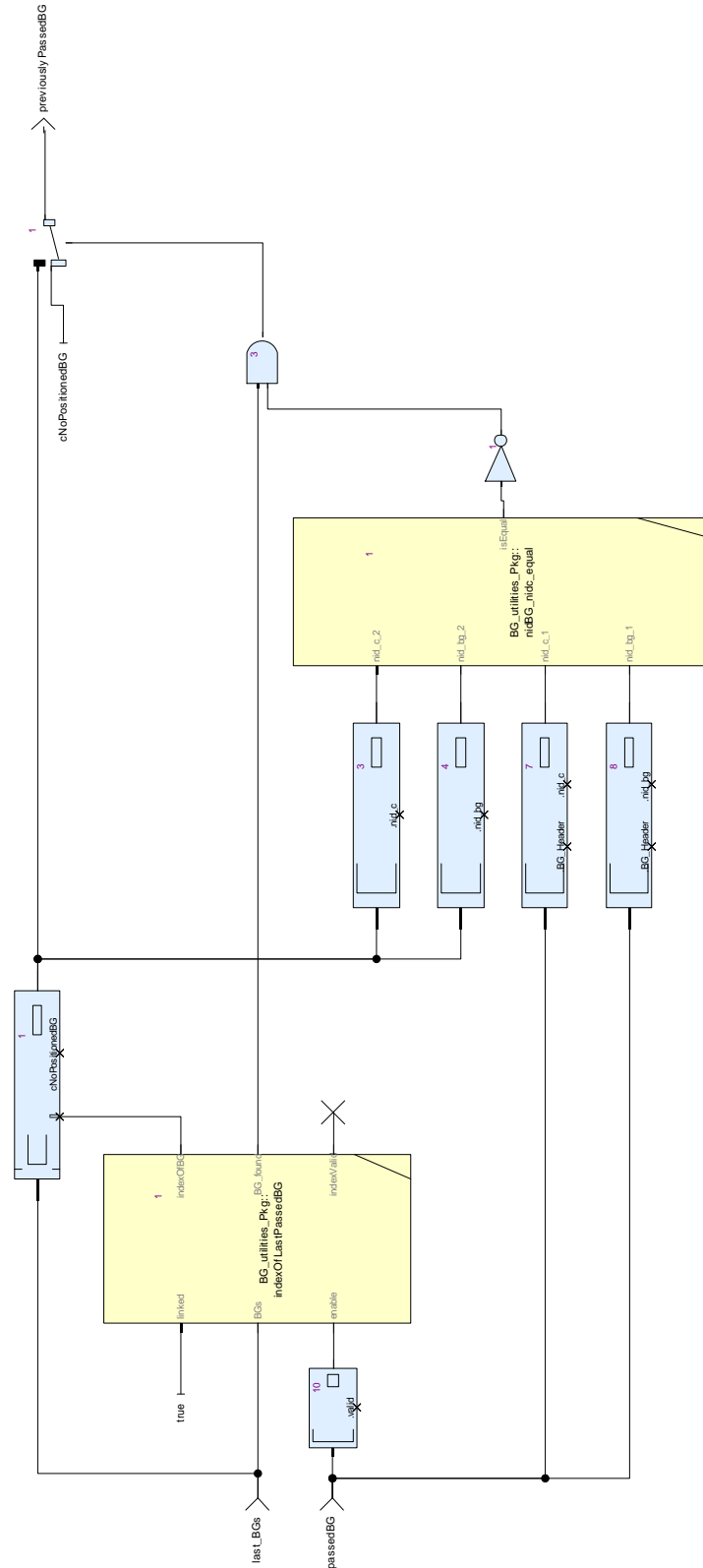


Figure 57: View of diagram_prevPassedLinkedBG_1 (prevPassedLinkedBG)

15.2. CalculateTrainPosition_Pkg::BG_relocation_Pkg Package

15.2.1. Types

Table 176: Public Types of BG_relocation_Pkg

| Name | Definition | Comments and Information |
|----------------------|--|--|
| BGs_forImprovement_T | {prevLinkedBG : TrainPosition_Types_Pck::positionedB G_T, unlinkedBG : TrainPosition_Types_Pck::positionedB G_T, indexofUnlinkedBG : int} | Comments: Serves to map and fold through the BGs prevLinkedBG Comments: The previous linked BG in the map and fold chain unlinkedBG Comments: The previous unlinked BG in the map and fold chain indexofUnlinkedBG Comments: Enables the location recalculation for all BGs subsequent to refBG |
| linkedBG_index_T | {previousLinkedBG_idx : int, currentIndex : int, subsequentLinkedBG_idx : int} | previousLinkedBG_idx Comments: Index of the BG before currentIndex Comments: The current index subsequentLinkedBG_idx Comments: Index of the BG behind |
| linkedBGs_indices_T | CalculateTrainPosition_Pkg::BG_reloc ation_Pkg::linkedBG_index_T ^TrainPosition_Types_Pck::cMaxNoOf StoredBGs | |
| refBGs_T | {refBG : TrainPosition_Types_Pck::positionedB G_T, prevLinkedBG : TrainPosition_Types_Pck::positionedB G_T, prevUnlinkedBG : TrainPosition_Types_Pck::positionedB G_T, recalculate : bool} | Comments: Serves to map and fold through the BGs refBG Comments: The reference BG for the location recalculation. prevLinkedBG Comments: The previous linked BG in the map and fold chain prevUnlinkedBG Comments: The previous unlinked BG in the map and fold chain recalculate Comments: Enables the location recalculation for all BGs subsequent to refBG |

15.2.2. Constants

Table 177: Public Constants of BG_relocation_Pkg

| Name | Type | Value | Comments and Information |
|-------------------|---|---|--------------------------|
| cNoLinkedBG_index | CalculateTrainPosition_Pkg::BG_relocation_Pkg::linkedBG_index_T | {previousLinkedBG_idx : gp_functions_Pkg::noValidIndex, currentIndex : (-1), subsequentLinkedBG_idx : gp_functions_Pkg::noValidIndex} | |

| Name | Type | Value | Comments and Information |
|------|------|--|--------------------------|
| | | <pre> {refBG : { valid : false, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked, location : {nominal : 0, d_min : 0, d_max : 0}, seqNoOnTrack : 0, infoFromLinking : {valid : false, nid_bg_fromLinking BG : 0, nid_c_fromLinkingB G : 0, expectedLocation : {nominal : 0, d_min : 0, d_max : 0}, d_link : {nominal : 0, d_min : 0, d_max : 0}, linkingInfo : {valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_s cale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_S ame_country__or__ railway_administrati on_no_NID_C_follo ws, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATIO N_The_balise_grou p_is_seen_by_the_t rain_in_reverse_dir ection, q_linkreaction : Q_LINKREACTION_ Train_trip, q_locacc : 0}}, infoFromPassing : {valid : false, timestamp : 0, odometrystamp : {o_nominal : 0, o_min : 0, o_max : 0}, BG_centerDetection Inaccuracies : {nominal : 0, d_min : 0, d_max : 0}, BG_Header : {q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previo us_versions_accordi ng_to_e_g_EEIG_S ome ETCS open and SRS, q_media : Q_MEDIA_Balise, n_pig : </pre> | |

15.2.3. findLinkedBG_bckwd_itr Operator

Declared as **private function**

15.2.3.1. Comments and Information

findLinkedBG_bckwd_itr Comments:

- Function for iterating through all BGs in backward direction.
- If BG_in is a linked BG, index_out.subsequentLinkedIndex is set to the current index.
- If not, index_out.subsequentLinkedIndex is taken from the previous iteration.
- index_out.currentIndex is taken from index_in without change.
- index_out.previousLinkedIndex is taken unchanged from index_in.

15.2.3.2. Interface

Table 178: Inputs of findLinkedBG_bckwd_itr

| Name | Type | Comments and Information |
|--------------|---|--|
| index_acc_in | CalculateTrainPosition_ Pkg::BG_relocation_Pk g::linkedBG_index_T | |
| index_in | CalculateTrainPosition_ Pkg::BG_relocation_Pk g::linkedBG_index_T | |
| BG_in | TrainPosition_Types_Pc k::positionedBG_T | Comments: The unlinked BG that's location shall be improved |

Table 179: Outputs of findLinkedBG_bckwd_itr

| Name | Type | Comments and Information |
|---------------|---|--------------------------|
| index_acc_out | CalculateTrainPosition_ Pkg::BG_relocation_Pk g::linkedBG_index_T | |
| index_out | CalculateTrainPosition_ Pkg::BG_relocation_Pk g::linkedBG_index_T | |

15.2.3.3. Operator Hierarchy

diagram : diagram_findLinkedBG_bckwd_itr_1

15.2.3.4. Graphical and Textual Diagrams

15.2.3.4.1. View of diagram_findLinkedBG_bckwd_itr_1 (findLinkedBG_bckwd_itr)

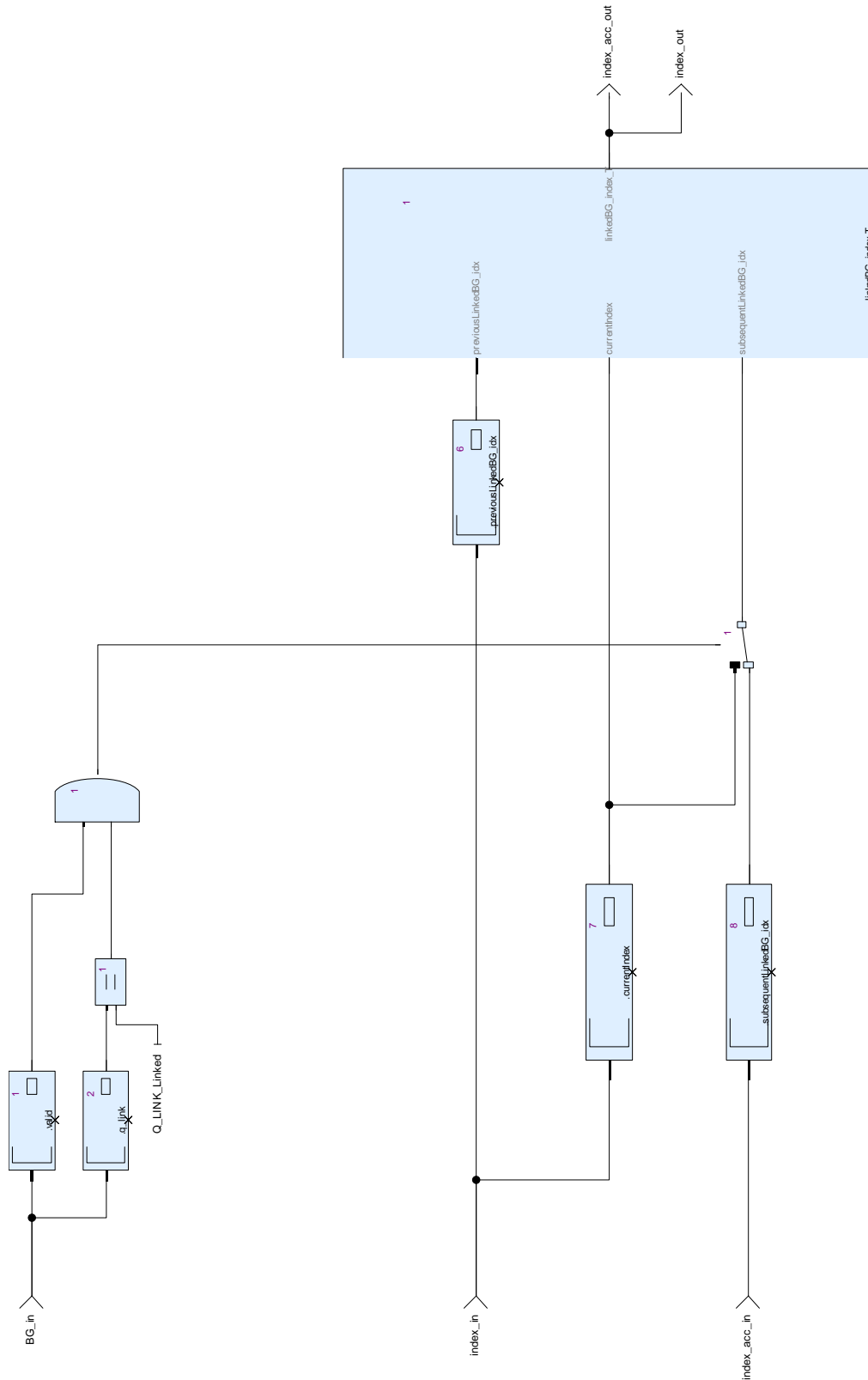


Figure 58: View of diagram_findLinkedBG_bckwd_itr_1 (findLinkedBG_bckwd_itr)

15.2.4. findLinkedBG_fwd_itr Operator

Declared as **private function**

15.2.4.1. Comments and Information

findLinkedBG_fwd_itr Comments:

- Function for iterating through all BGs in forward direction.
- If BG_in is a linked BG, index_out.previousLinked_BG_idx is set to the current index.
- If not, index_out.previousLinked_BG_idx is taken from the previous iteration.
- index_out.currentIndex is generated by incrementing the index from the previous iteration.
- index_out.subsequentLinkedIndex taken unchanged from index_in.

15.2.4.2. Interface

Table 180: Inputs of findLinkedBG_fwd_itr

| Name | Type | Comments and Information |
|----------|---|---|
| index_in | CalculateTrainPosition_ Pkg::BG_relocation_Pk g::linkedBG_index_T | Comments: Indices for the iteration |
| BG_in | TrainPosition_Types_Pc k::positionedBG_T | Comments: The BG to be searched for. |

Table 181: Outputs of findLinkedBG_fwd_itr

| Name | Type | Comments and Information |
|-----------|---|---|
| index_acc | CalculateTrainPosition_ Pkg::BG_relocation_Pk g::linkedBG_index_T | Comments: The results to be transferred to the next iteration. |
| index_out | CalculateTrainPosition_ Pkg::BG_relocation_Pk g::linkedBG_index_T | Comments: The resulting indices |

15.2.4.3. Operator Hierarchy

diagram : diagram_findLinkedBG_fwd_itr_1

15.2.4.4.1. View of diagram_findLinkedBG_fwd_itr_1 (findLinkedBG_fwd_itr)

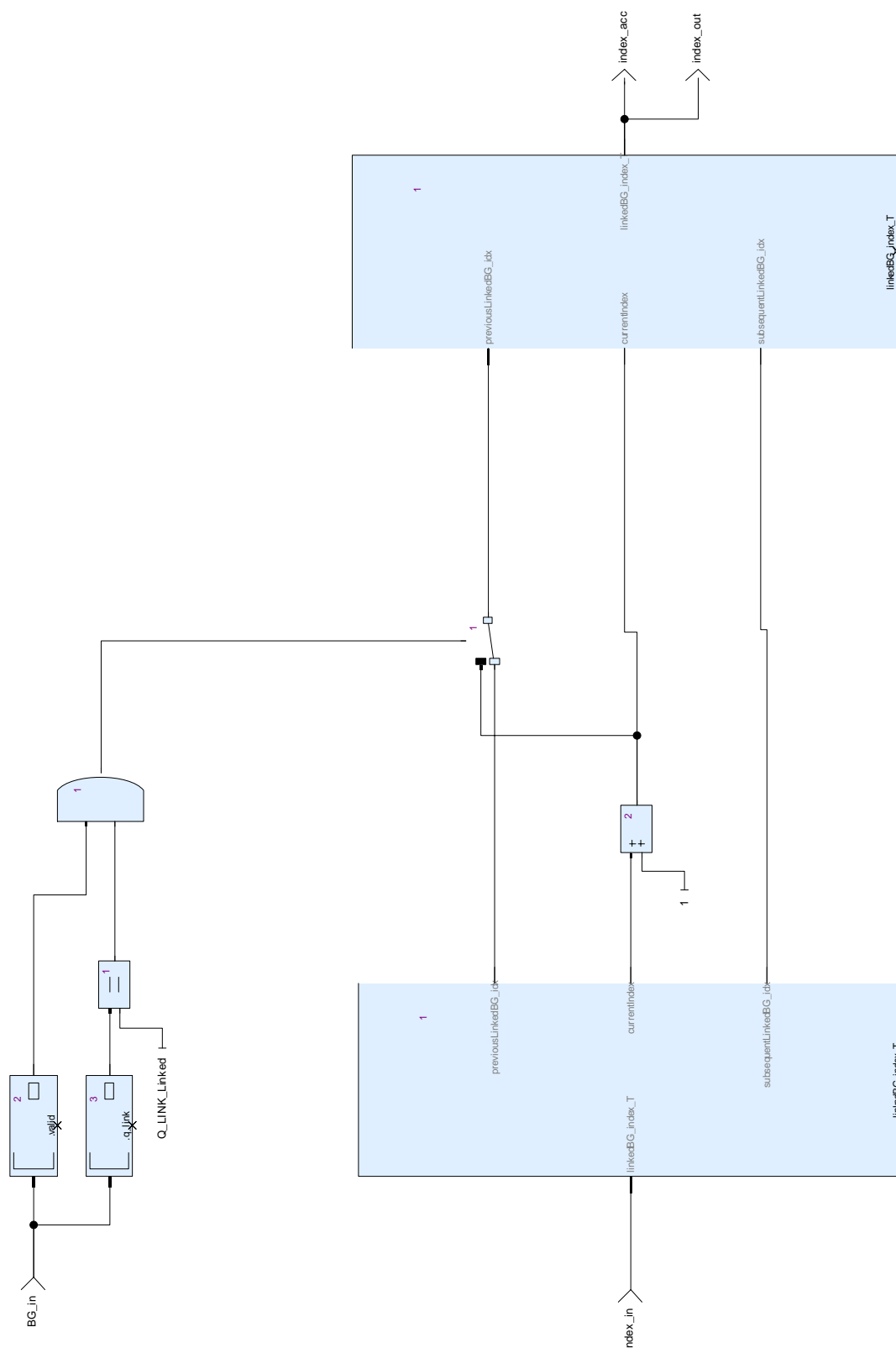


Figure 59: View of diagram_findLinkedBG_fwd_itr_1 (findLinkedBG_fwd_itr)

15.2.5. findLinkedBGs Operator

Declared as **private function**

15.2.5.1. Comments and Information

findLinkedBGs Comments:

- Iterates through BGs_in forward and backward direction and looks for linked BGs.
- The result is an array of indices, where each cell related to an unlinked BG provides the indices of the linked BG before and behind the unlinked BG.

15.2.5.2. Interface

Table 182: Inputs of findLinkedBGs

| Name | Type | Comments and Information |
|--------|--|--------------------------------------|
| BGs_in | TrainPosition_Types_Pkg::positionedBGs_T | Comments: The BGs to be analyzed. |

Table 183: Outputs of findLinkedBGs

| Name | Type | Comments and Information |
|-------------|--|--|
| BGs_indices | CalculateTrainPosition_Pkg::BG_relocation_Pkg::linkedBGs_indices_T | Comments: The resulting array of indices. |

15.2.5.3. Operator Hierarchy

diagram : diagram_findLinkedBGs_1

15.2.5.4. Graphical and Textual Diagrams

15.2.5.4.1. View of diagram_findLinkedBGs_1 (findLinkedBGs)

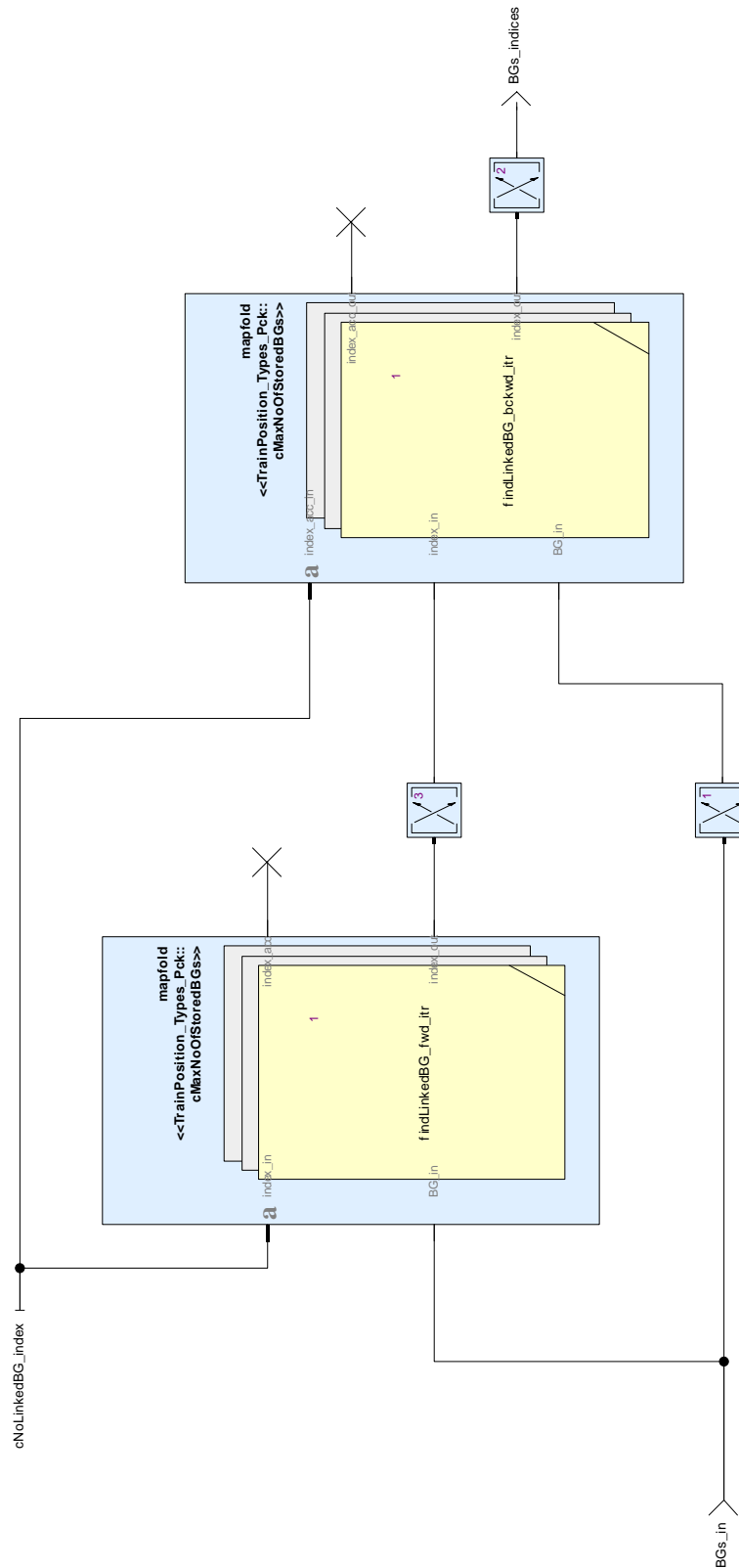


Figure 60: View of diagram_findLinkedBGs_1 (findLinkedBGs)

15.2.6. improve_BG_locations Operator

Declared as **public function**

15.2.6.1. Interface

Table 184: Inputs of improve_BG_locations

| Name | Type | Comments and Information |
|-------------|--|---|
| referenceBG | TrainPosition_Types_Pc k::positionedBG_T | Comments: Recalculates the locations of all BGs with reference to referenceBG. Reduces the inaccuracy of referenceBG to a minimum, while the inaccuracies of all BGs in front and behind are growing in both directions. |
| BGs_in | TrainPosition_Types_Pc k::positionedBGs_T | |
| improve | bool | |

Table 185: Outputs of improve_BG_locations

| Name | Type | Comments and Information |
|---------|--|--------------------------|
| BGs_out | TrainPosition_Types_Pc k::positionedBGs_T | |

15.2.6.2. Operator Hierarchy

diagram : diagram_recalculate_refBG_location

15.2.6.3.1. View of diagram_recalculate_refBG_location (improve_BG_locations)

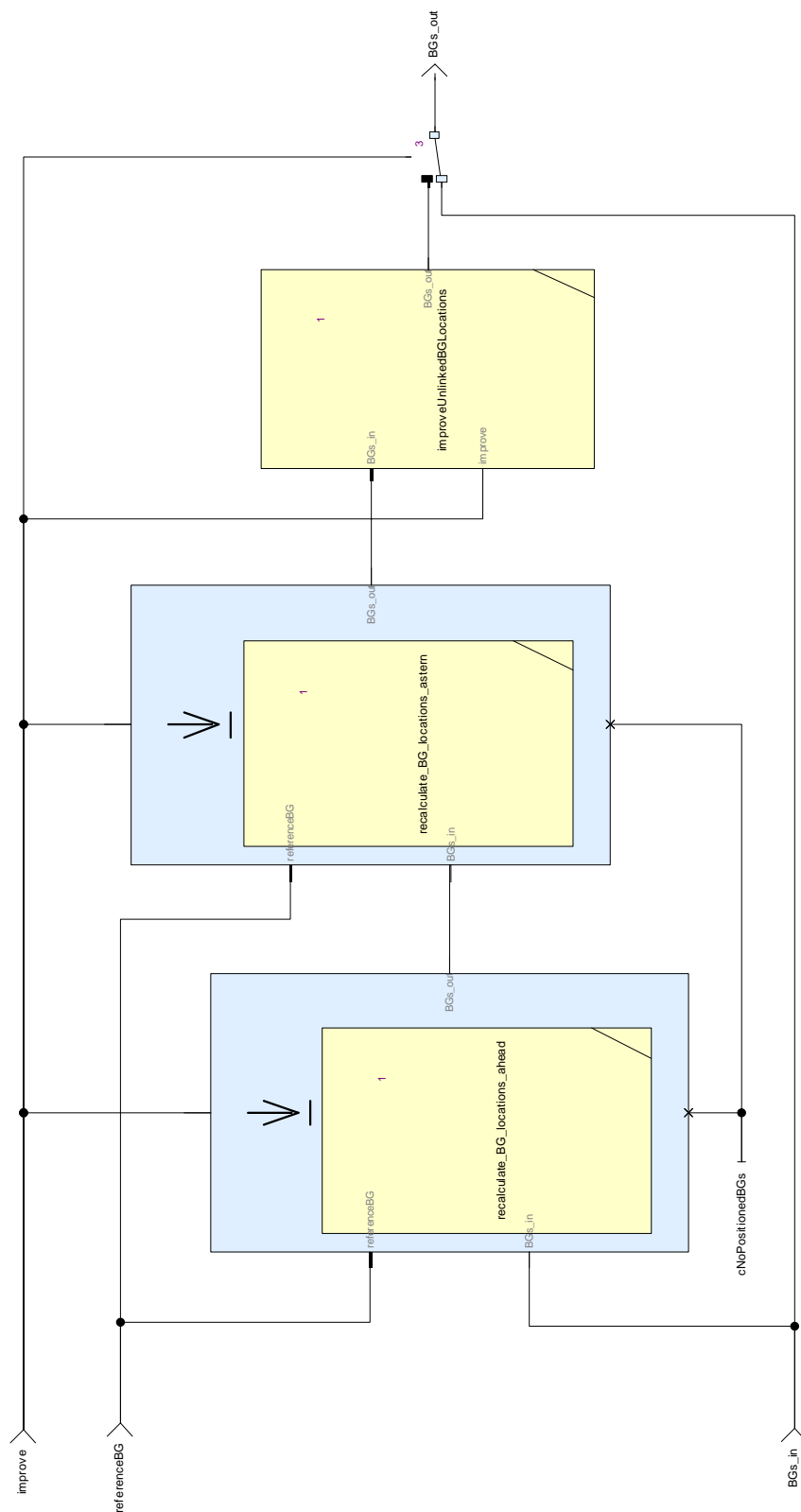


Figure 61: View of diagram_recalculate_refBG_location (improve_BG_locations)

15.2.7. improveUnlinkedBGLocation Operator

Declared as **public function**

15.2.7.1. Comments and Information

improveUnlinkedBGLocation Comments:

- Tries to improve the location of an unlinked BG with reference to two different passed linked BGs.
- If the improvement fails, the location of the unlinked BG will be left unchanged.

15.2.7.2. Interface

Table 186: Inputs of improveUnlinkedBGLocation

| Name | Type | Comments and Information |
|------------------|---|--|
| passedLinkedBG_2 | TrainPosition_Types_Pc k::positionedBG_T | Comments: The second passed linked BG as the second reference location. |
| passedLinkedBG_1 | TrainPosition_Types_Pc k::positionedBG_T | Comments: The first passed linked BG as the first reference location. |
| unlinkedBG_in | TrainPosition_Types_Pc k::positionedBG_T | Comments: The unlinked BG that's location shall be improved |

Table 187: Outputs of improveUnlinkedBGLocation

| Name | Type | Comments and Information |
|----------------|---|---|
| unlinkedBG_out | TrainPosition_Types_Pc k::positionedBG_T | Comments: The unlinked BG that's location might have been improved |

15.2.7.3. Operator Hierarchy

diagram : diagram_improveUnlinkedBGLocation_1

15.2.7.4. Graphical and Textual Diagrams

15.2.7.4.1. View of diagram_improveUnlinkedBGLocation_1 (improveUnlinkedBGLocation)

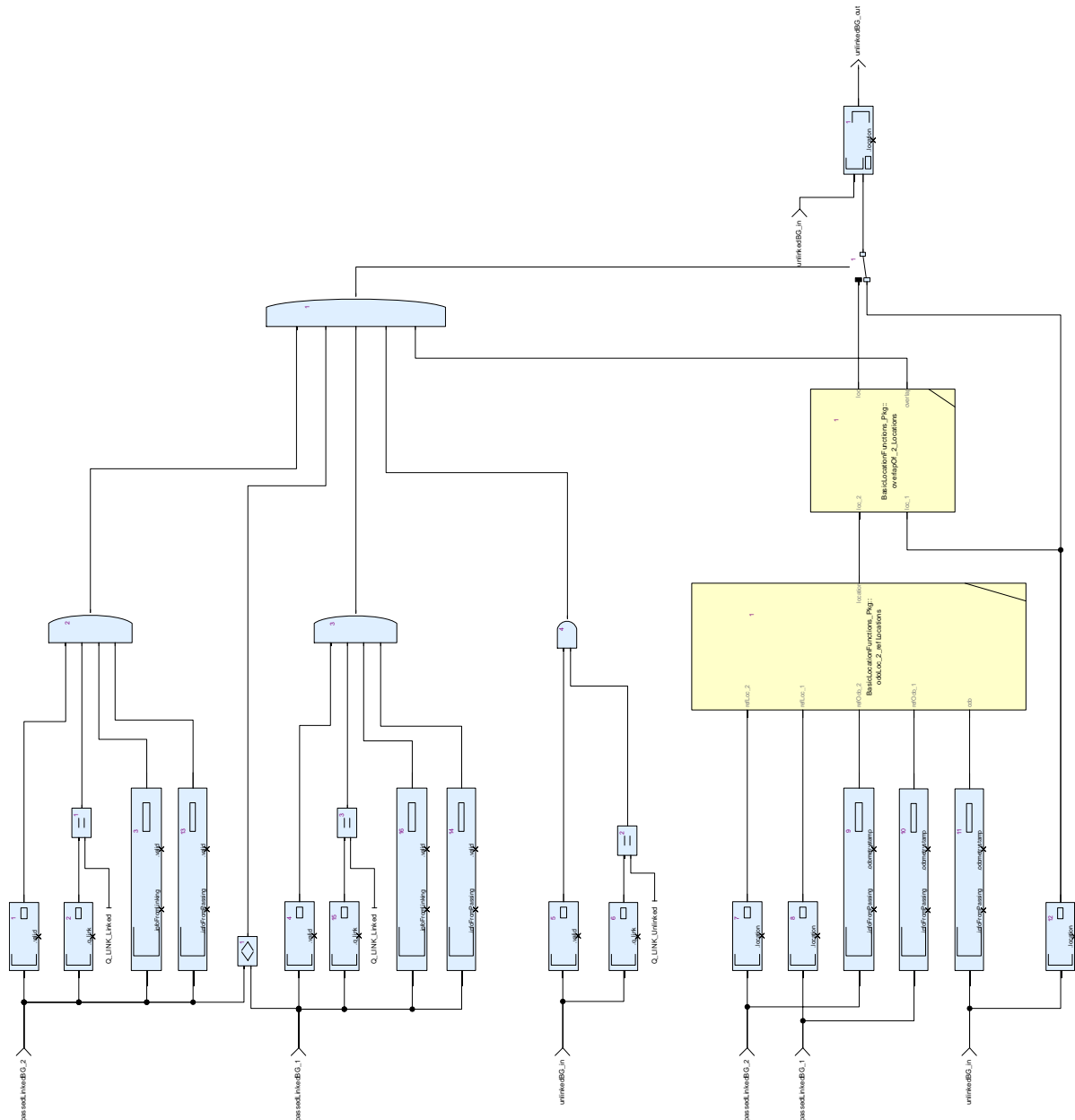


Figure 62: View of diagram_improveUnlinkedBGLocation_1 (improveUnlinkedBGLocation)

15.2.8. improveUnlinkedBGLocations Operator

Declared as **private function**

15.2.8.1. Interface

Table 188: Inputs of improveUnlinkedBGLocations

| Name | Type | Comments and Information |
|---------|--|--------------------------|
| BGs_in | TrainPosition_Types_Pc k::positionedBGs_T | |
| improve | bool | |

Table 189: Outputs of improveUnlinkedBGLocations

| Name | Type | Comments and Information |
|---------|--|--------------------------|
| BGs_out | TrainPosition_Types_Pc k::positionedBGs_T | |

15.2.8.2. Operator Hierarchy

diagram : diagram_improveUnlinkedBGLocations_1

15.2.8.3. Graphical and Textual Diagrams

15.2.8.3.1. View of diagram_improveUnlinkedBGLocations_1 (improveUnlinkedBGLocations)

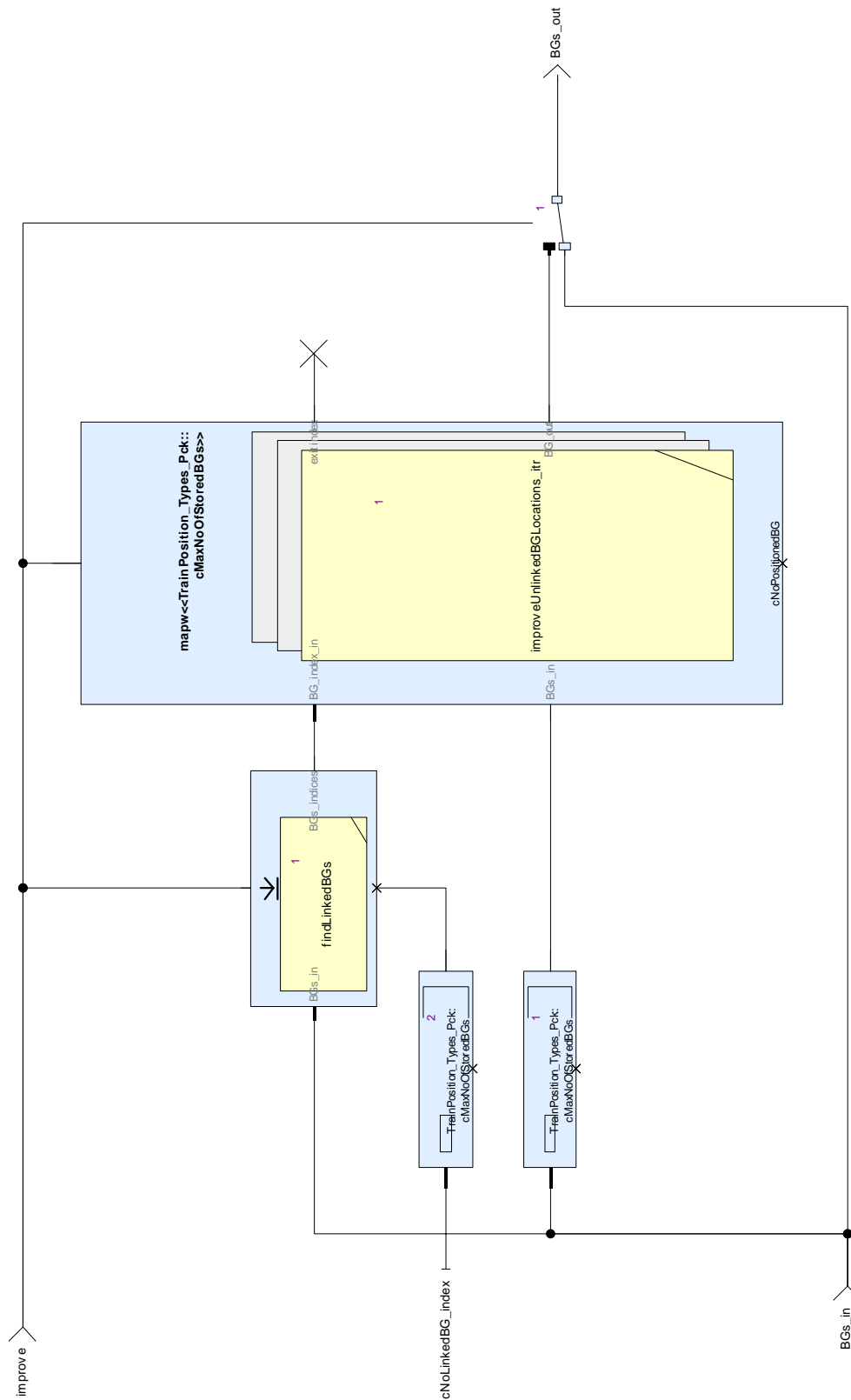


Figure 63: View of diagram_improveUnlinkedBGLocations_1 (improveUnlinkedBGLocations)

15.2.9. improveUnlinkedBGLocations_itr Operator

Declared as **private function**

15.2.9.1. Interface

Table 190: Inputs of improveUnlinkedBGLocations_itr

| Name | Type | Comments and Information |
|-------------|---|--|
| BG_index_in | CalculateTrainPosition_ Pkg::BG_relocation_Pk g::linkedBG_index_T | Comments: Indices for the iteration |
| BGs_in | TrainPosition_Types_Pc k::positionedBGs_T | |

Table 191: Outputs of improveUnlinkedBGLocations_itr

| Name | Type | Comments and Information |
|--------|---|---|
| cont | bool | |
| BG_out | TrainPosition_Types_Pc k::positionedBG_T | Comments: The BG to be searched for. |

15.2.9.2. Operator Hierarchy

diagram : diagram_improveUnlinkedBGLocations_itr_1

15.2.9.3. Graphical and Textual Diagrams

15.2.9.3.1. View of diagram_improveUnlinkedBGLocations_itr_1 (improveUnlinkedBGLocations_itr)

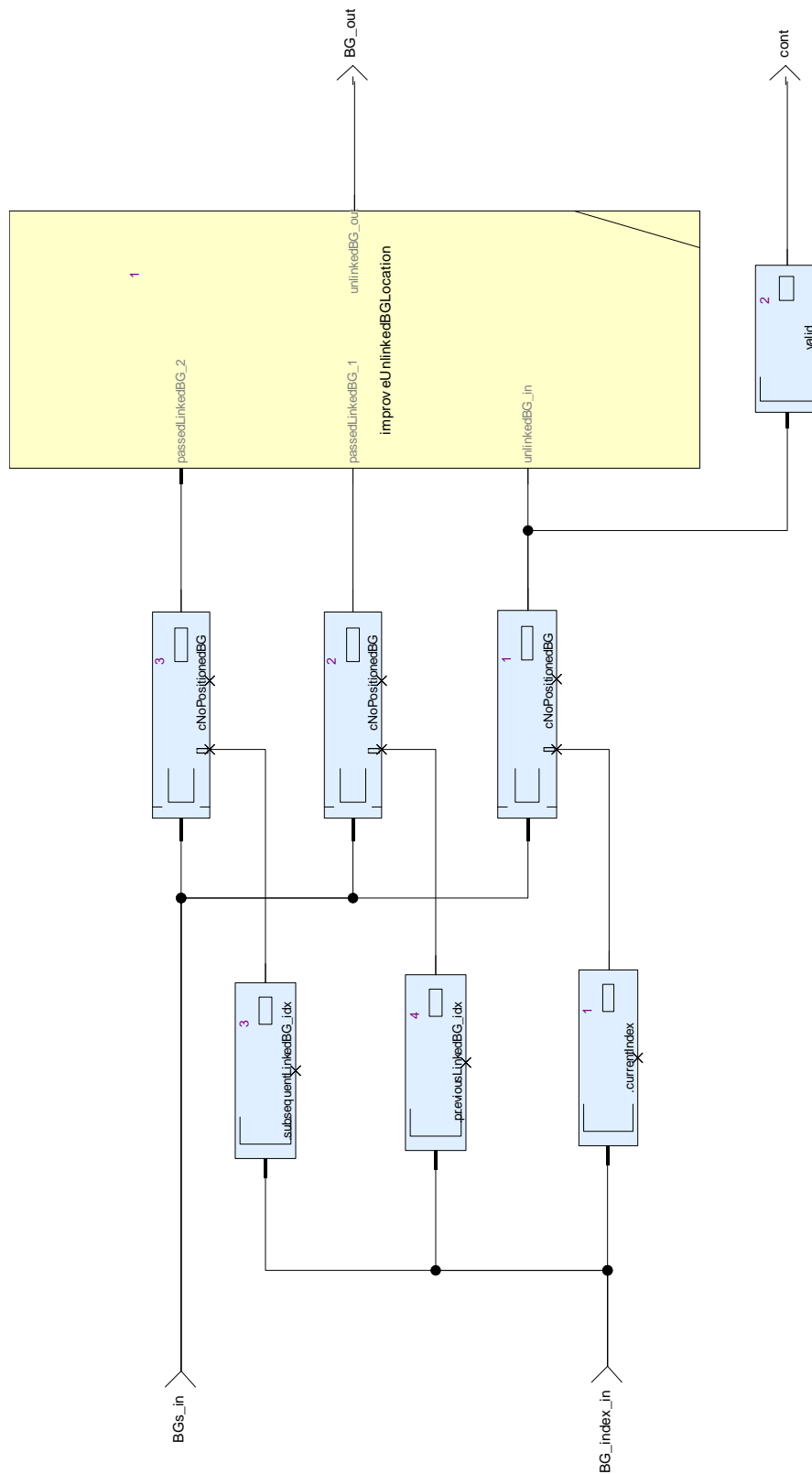


Figure 64: View of diagram_improveUnlinkedBGLocations_itr_1 (improveUnlinkedBGLocations_itr)

15.2.10. recalculate_BG_location_ahead Operator

Declared as **private function**

15.2.10.1. Comments and Information

recalculate_BG_location_ahead Comments:

- Recalculates the location of a BG based on the location of a previous BG.
- If prevBG and BG_in are linked BGs, the linking information will be evaluated for location calculation.
- If prevBG is not a linked BG, the BG location will be calculated from odometry only.
- if prevBG is not valid, the location will remain unchanged.
- Preconditions:
 - - prevBG must have a location assigned.
 - - BG_in and prevBG should have linking and passing information, if appropriate.

15.2.10.2. Interface

Table 192: Inputs of recalculate_BG_location_ahead

| Name | Type | Comments and Information |
|--------|---|--|
| BG_in | TrainPosition_Types_Pkg::positionedBG_T | Comments: The BG that's location has to be recalculated |
| prevBG | TrainPosition_Types_Pkg::positionedBG_T | Comments: The previous BG. |

Table 193: Outputs of recalculate_BG_location_ahead

| Name | Type | Comments and Information |
|--------|---|--|
| BG_out | TrainPosition_Types_Pkg::positionedBG_T | Comments: The BG that's location has been recalculated. |

15.2.10.3. Locals

Table 194: Locals of recalculate_BG_location_ahead

| Name | Type | Comments and Information |
|-------------------------|------------------------------------|--------------------------|
| distance | Obu_BasicTypes_Pkg::LocWithInAcc_T | |
| linked | bool | |
| linkedAndPassed | bool | |
| linkedPassedOverlapping | bool | |
| passed | bool | |

15.2.10.4. Operator Hierarchy

diagram : diagram_decide_linked_passed

diagram : diagram_recalculate_BG_location

15.2.10.5. Graphical and Textual Diagrams

15.2.10.5.1. View of diagram_decide_linked_passed (recalculate_BG_location_ahead)

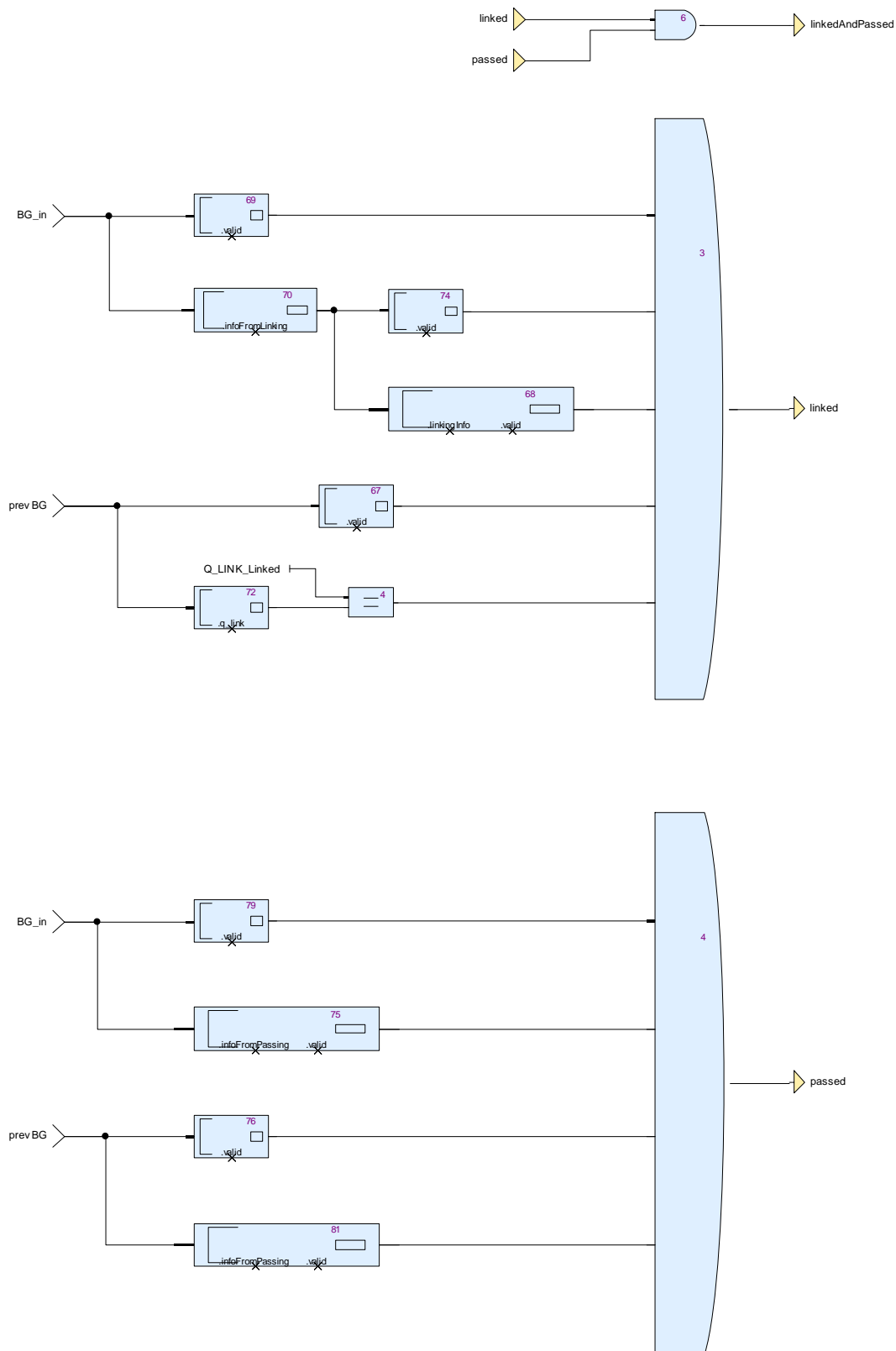


Figure 65: View of diagram_decide_linked_passed (recalculate_BG_location_ahead)

15.2.10.5.2. View of diagram_recalculate_BG_location (recalculate_BG_location_ahed)

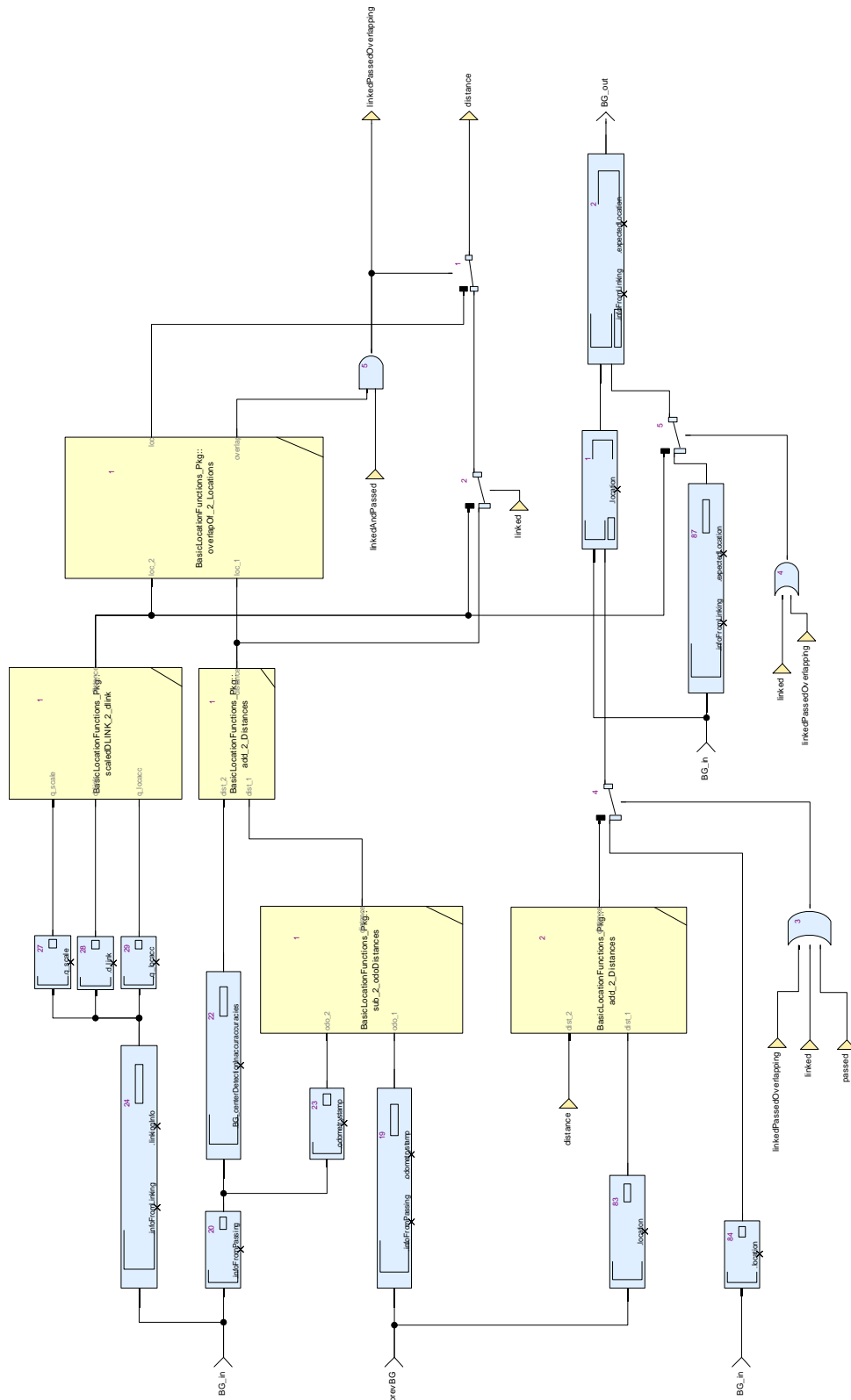


Figure 66: View of diagram_recalculate_BG_location (recalculate_BG_location_ahed)

15.2.11. recalculate_BG_location_astern Operator

Declared as **private function**

15.2.11.1. Comments and Information

recalculate_BG_location_astern Comments:

- Recalculates the location of an astern BG based on the location of an BG ahead.
- If refBG_ahead and BG_in are linked BGs, the linking information will be evaluated for location calculation.
- If refBG_ahead is not a linked BG, the BG location will be calculated from odometry only.
- if refBG_ahead is not valid, the location will remain unchanged.
- Preconditions:
 - - refBG_ahead must have a location assigned.
 - - BG_in and refBG_ahead should have linking and passing information, if appropriate.

15.2.11.2. Interface

Table 195: Inputs of recalculate_BG_location_astern

| Name | Type | Comments and Information |
|-------------|---|--|
| BG_in | TrainPosition_Types_Pkg::positionedBG_T | Comments: The BG that's location has to be recalculated |
| refBG_ahead | TrainPosition_Types_Pkg::positionedBG_T | Comments: The reference BG ahead of BG_in. |

Table 196: Outputs of recalculate_BG_location_astern

| Name | Type | Comments and Information |
|--------|---|--|
| BG_out | TrainPosition_Types_Pkg::positionedBG_T | Comments: The BG that's location has been recalculated. |

15.2.11.3. Locals

Table 197: Locals of recalculate_BG_location_astern

| Name | Type | Comments and Information |
|-------------------------|------------------------------------|--------------------------|
| distance | Obu_BasicTypes_Pkg::LocWithinAcc_T | |
| linked | bool | |
| linkedAndPassed | bool | |
| linkedPassedOverlapping | bool | |
| passed | bool | |

15.2.11.4. Operator Hierarchy

diagram : diagram_decide_linked_passed

diagram : diagram_recalculate_BG_location

15.2.11.5. Graphical and Textual Diagrams

15.2.11.5.1. View of diagram_decide_linked_passed (recalculate_BG_location_astern)

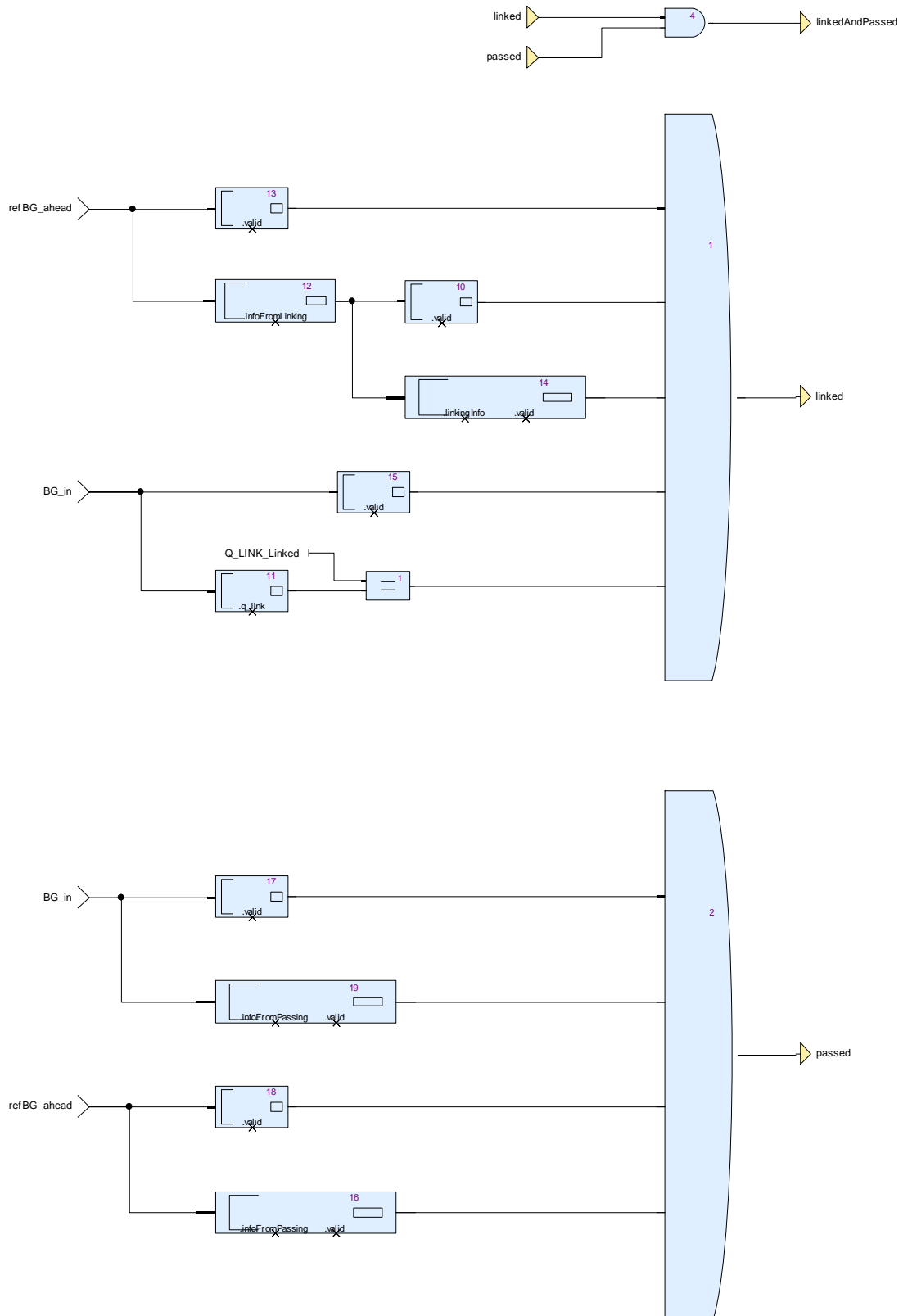


Figure 67: View of diagram_decide_linked_passed (recalculate_BG_location_astern)

15.2.11.5.2. View of diagram_recalculate_BG_location (recalculate_BG_location_astern)

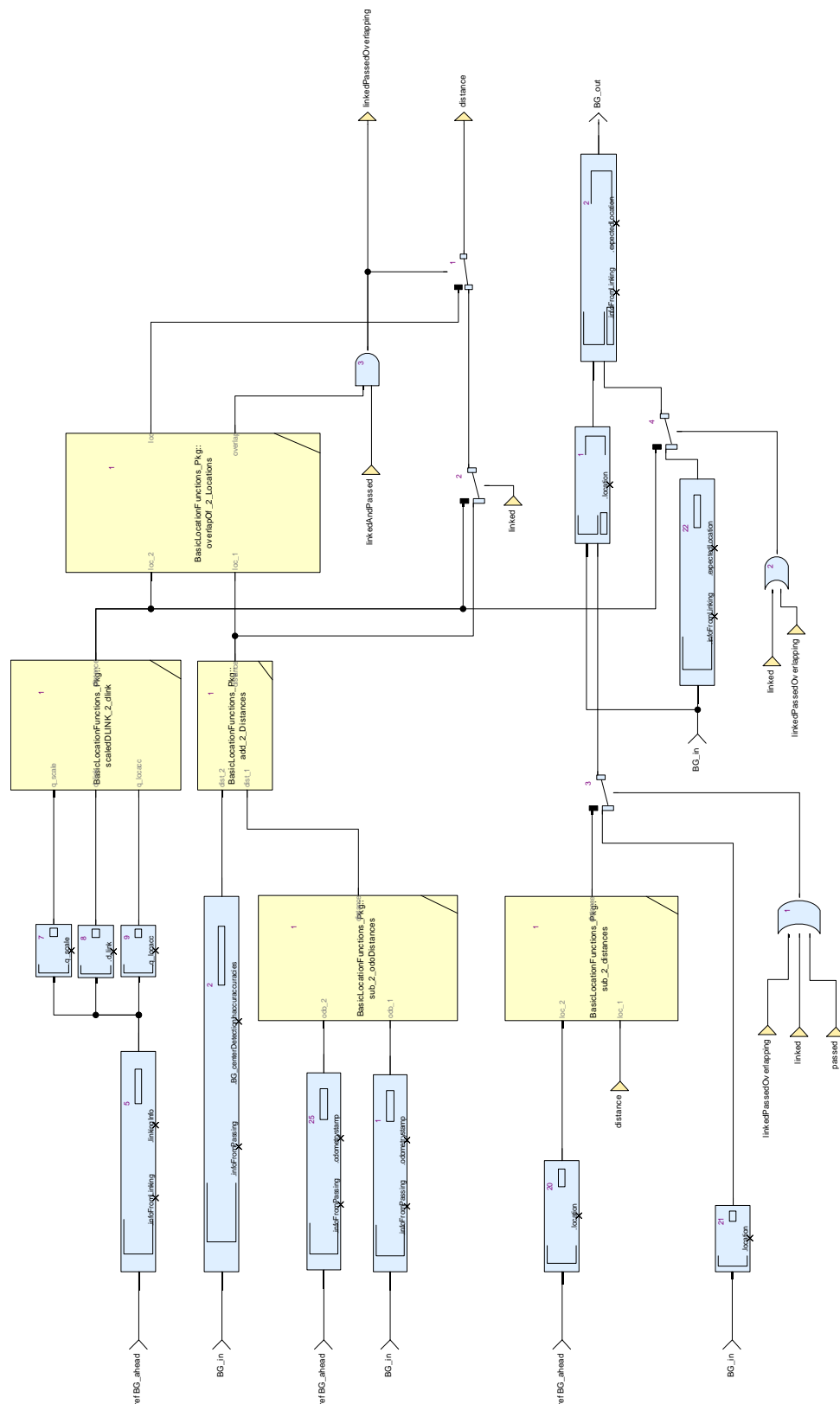


Figure 68: View of diagram_recalculate_BG_location (recalculate_BG_location_astern)

15.2.12. recalculate_BG_locations_ahead Operator

Declared as **private function**

15.2.12.1. Comments and Information

recalculate_BG_locations_ahead Comments:

- Recalculates the BG locations in forward direction, starting from referenceBG to all BGs ahead.
- The location accuracy of referenceBG in BGs is minimized while leaving its nominal location unchanged.
- The locations of all BGs ahead of referenceBG are adjusted relatively to referenceBG.
- The locations of all BGs astern of referenceBG are left unchanged.
- BGs_in should have locations assigned and arranged in increasing order of locations.

15.2.12.2. Interface

Table 198: Inputs of recalculate_BG_locations_ahead

| Name | Type | Comments and Information |
|-------------|--|--|
| referenceBG | TrainPosition_Types_Pc k::positionedBG_T | Comments: Recalculates the locations of all BGs with reference to referenceBG, beginning with the referenceBG and all BGs afterwards. Reduces the inaccuracy of referenceBG to a minimum, while the inaccuracies of all BGs before and after are growing in both directions. |
| BGs_in | TrainPosition_Types_Pc k::positionedBGs_T | |

Table 199: Outputs of recalculate_BG_locations_ahead

| Name | Type | Comments and Information |
|---------|--|--------------------------|
| BGs_out | TrainPosition_Types_Pc k::positionedBGs_T | |

15.2.12.3. Operator Hierarchy

diagram : diagram_recalculate_BG_locations_ahead_1

15.2.12.4. Graphical and Textual Diagrams

15.2.12.4.1. View of diagram_recalculate_BG_locations_ahead_1 (recalculate_BG_locations_ahead)

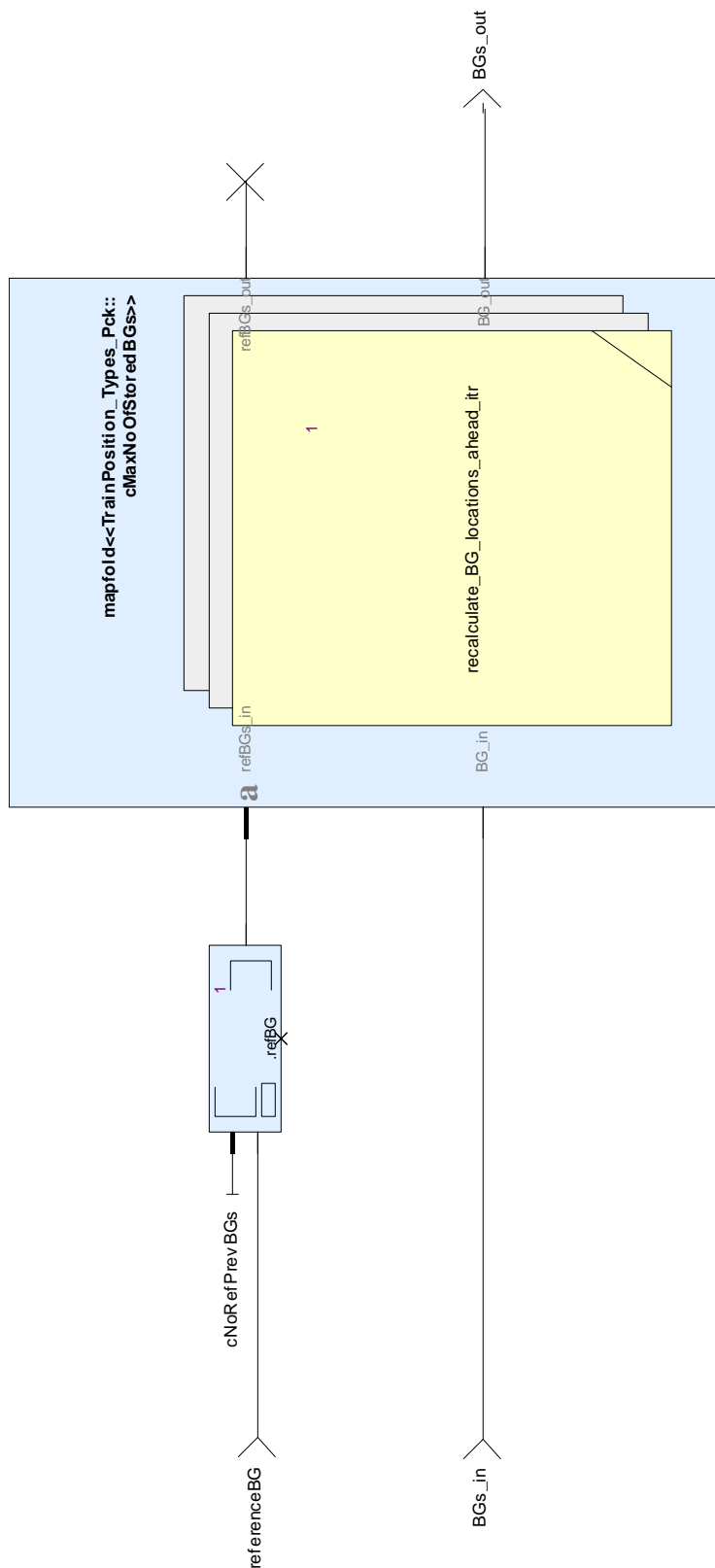


Figure 69: View of diagram_recalculate_BG_locations_ahead_1 (recalculate_BG_locations_ahead)

15.2.13. recalculate_BG_locations_ahead_itr Operator

Declared as **private function**

15.2.13.1. Comments and Information

recalculate_BG_locations_ahead_itr Comments:

- Iterated function for recalculating the locations of all BGs in forward direction, starting from refBGs_in.refBG with all BGs ahead.
- The location accuracy of refBGs_in.refBG is minimized while leaving its nominal location unchanged.
- The location of a BG_in ahead of refBGs_in.refBG is adjusted relatively to refBGs_in.
- The locations of a BG_in astern of refBGs_in.refBG is left unchanged.
- See diagram descriptions for more details.

15.2.13.2. Interface

Table 200: Inputs of recalculate_BG_locations_ahead_itr

| Name | Type | Comments and Information |
|-----------|---|--|
| refBGs_in | CalculateTrainPosition_Pkg::BG_relocation_Pkg::refBGs_T | |
| BG_in | TrainPosition_Types_Pkg::positionedBG_T | Comments: The BG that's location has to be recalculated |

Table 201: Outputs of recalculate_BG_locations_ahead_itr

| Name | Type | Comments and Information |
|------------|---|--|
| refBGs_out | CalculateTrainPosition_Pkg::BG_relocation_Pkg::refBGs_T | |
| BG_out | TrainPosition_Types_Pkg::positionedBG_T | Comments: The BG that's location has been recalculated. |

15.2.13.3. Locals

Table 202: Locals of recalculate_BG_locations_ahead_itr

| Name | Type | Comments and Information |
|--------------------------|---|---|
| BGin_is_refBG | bool | |
| prevLinkedBG | TrainPosition_Types_Pkg::positionedBG_T | |
| prevUnlinkedBG | TrainPosition_Types_Pkg::positionedBG_T | |
| recalculateSubsequentBGs | bool | |
| refBG | TrainPosition_Types_Pkg::positionedBG_T | |
| refLocation | Obu_BasicTypes_Pkg::LocWithInAcc_T | Comments: The recalculated location of the reference BG. |
| relocatedBG | TrainPosition_Types_Pkg::positionedBG_T | |

15.2.13.4. Operator Hierarchy

diagram : diagram_assembleResults

diagram : diagram_assign_refBG

diagram : diagram_determinePreviousLinkedBG

diagram : diagram_determinePreviousUnlinkedBG

diagram : diagram_recalculate_BG_location

diagram : diagram_recalculate_refBG_location

15.2.13.5. Graphical and Textual Diagrams

15.2.13.5.1. View of diagram_assembleResults (recalculate_BG_locations_ahead_itr)

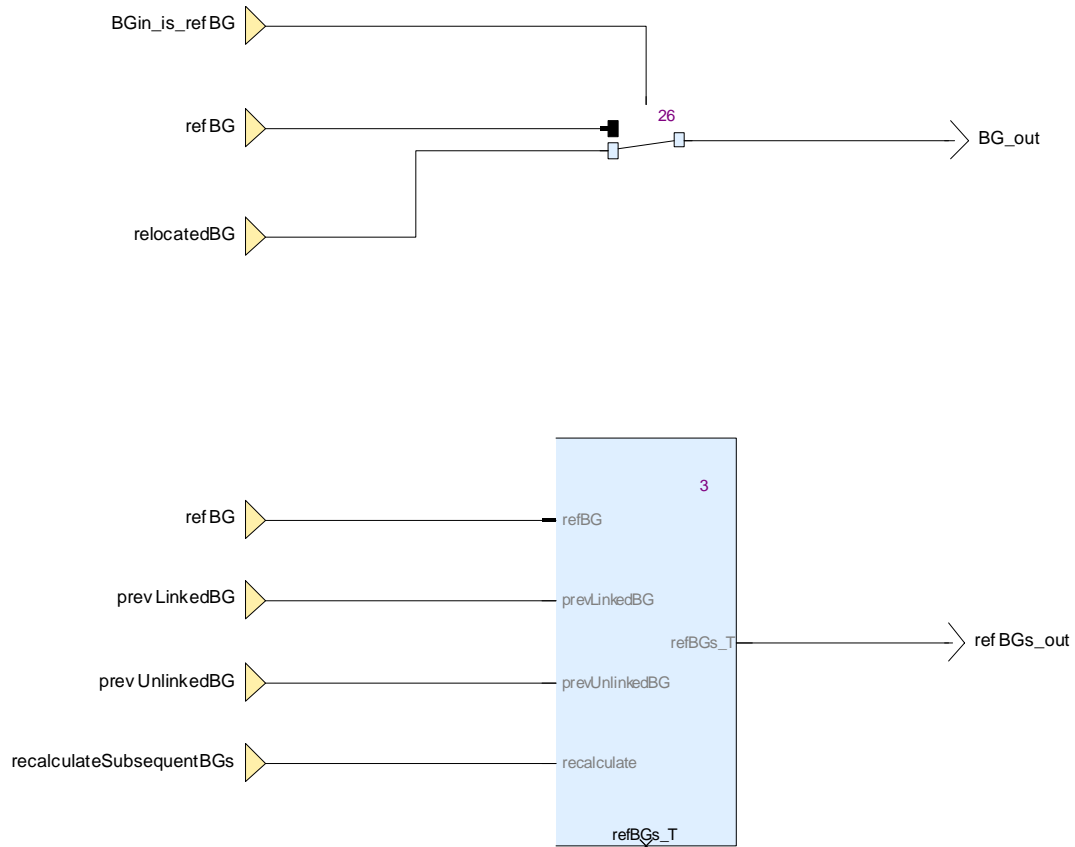


Figure 70: View of diagram_assembleResults (recalculate_BG_locations_ahead_itr)

diagram_assembleResults Comments:

- Assembles the outputs.

15.2.13.5.2. View of diagram_assign_refBG (recalculate_BG_locations_ahead_itr)

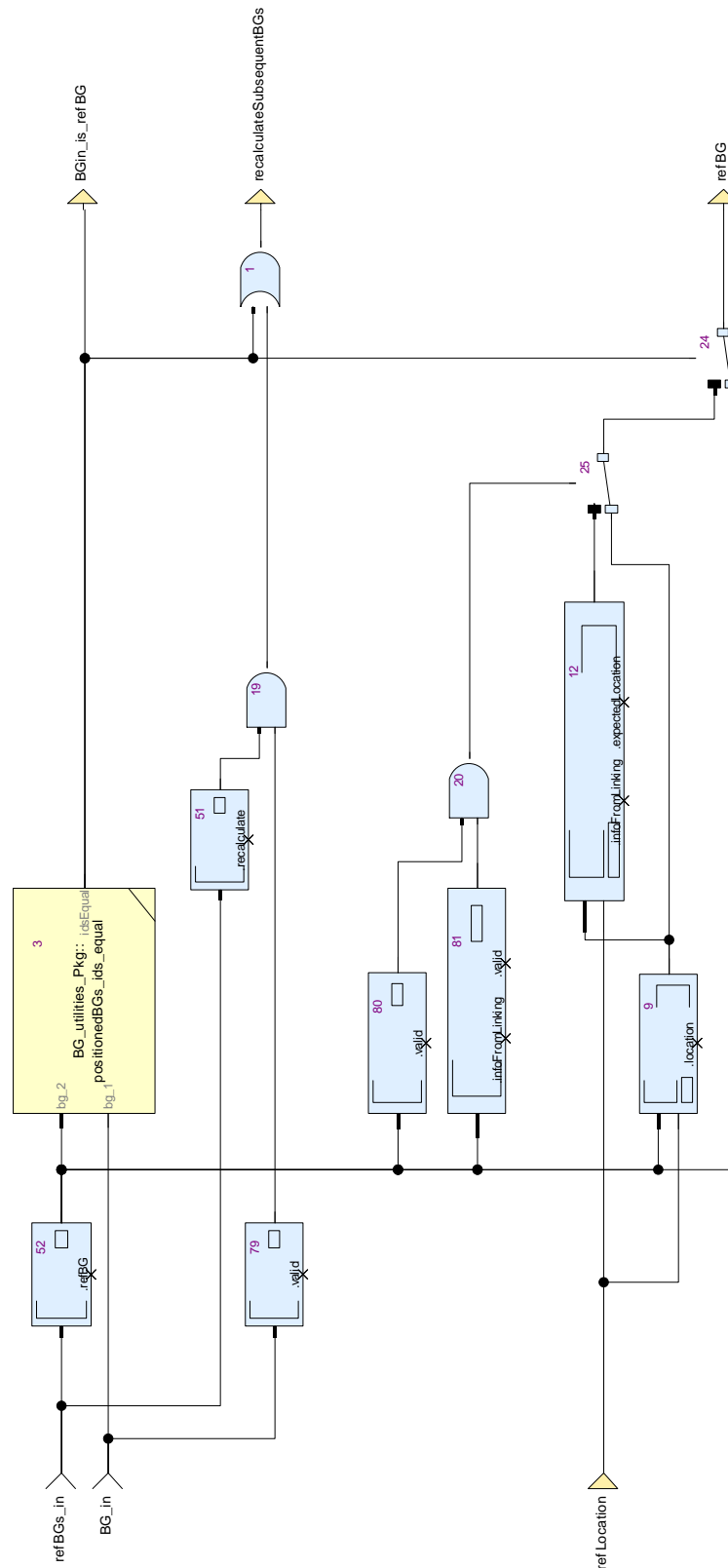


Figure 71: View of diagram_assign_refBG (recalculate_BG_locations_ahrhead_itr)

diagram_assign_refBG Comments:

- Determines if BG_in is the reference BG.

- If yes, the location of the reference BG has to be recalculated.
- For all subsequent BGs in the iteration, the locations have to be recalculated.
- For all BGs in the iteration before the reference BGs, the locations are kept unchanged.

15.2.13.5.3. View of diagram_determinePreviousLinkedBG (recalculate_BG_locations_ahead_itr)

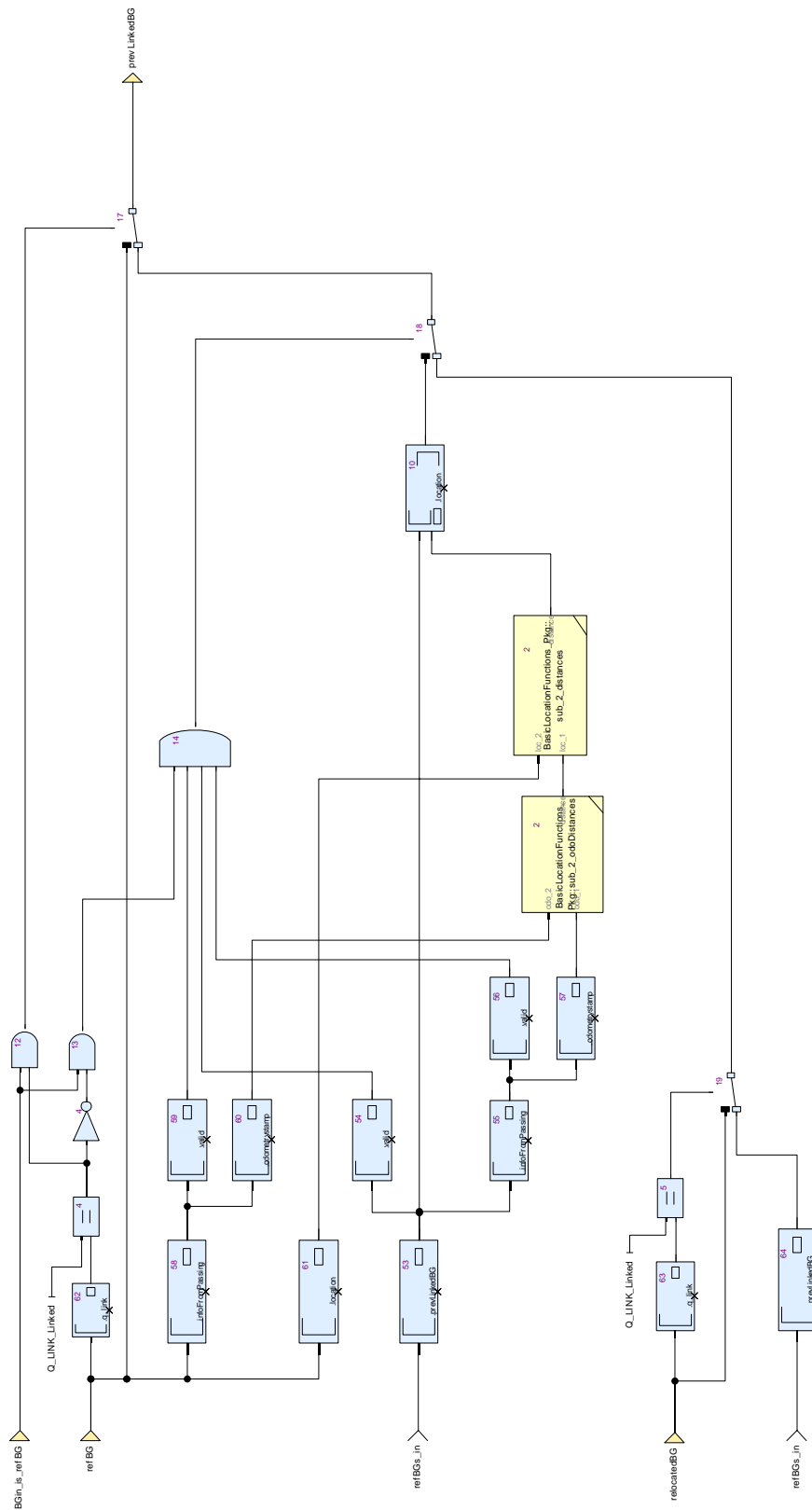


Figure 72: View of diagram_determinePreviousLinkedBG (recalculate_BG_locations_ahead_itr)

diagram_determinePreviousLinkedBG Comments:

- Determines the previous linked BG.
- If BG_in is the reference BG and the reference BG is a linked BG, prevLinkedBG is set to refBG.
- If BG_in is the reference BG and is an unlinked BG or a linked BG without linking information, the location of prevLinkedBG is recalculated from refBG based upon odometry values.
- This is possible, because refBG must have been passed, and therefore prevLinkedBG too.
- If BG_in is not the reference BG and is a linked BG, prevLinkedBG is set to BG_in.
- If BG_in is not the reference BG and is an unlinked BG, prevLinkedBG is taken from refBGs_in.prevLinkedBG.

15.2.13.5.4. View of diagram_determinePreviousUnlinkedBG (recalculate_BG_locations_ahead_itr)

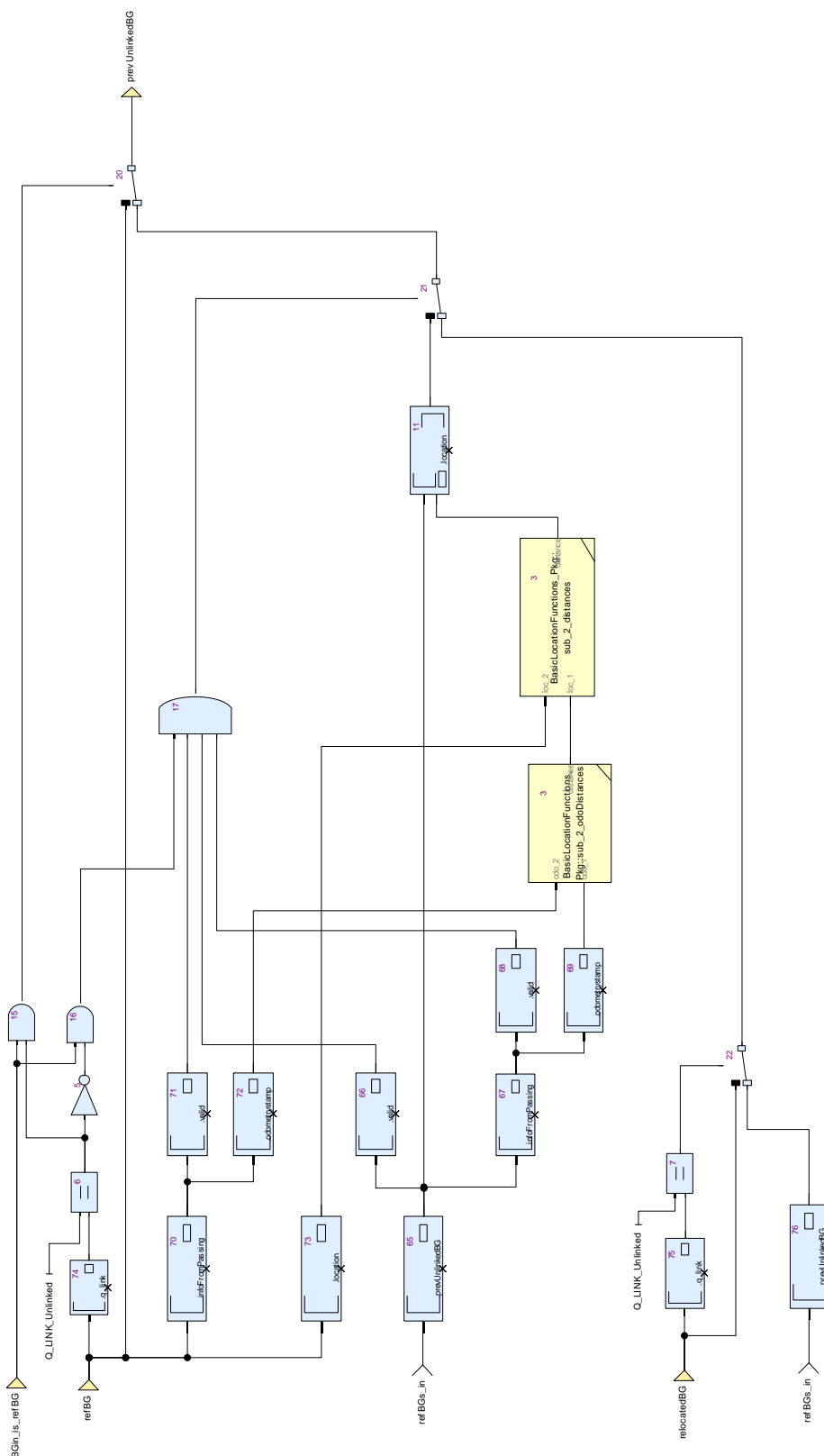


Figure 73: View of diagram_determinePreviousUnlinkedBG (recalculate_BG_locations_ahead_itr)

diagram_determinePreviousUnlinkedBG Comments:

- Determines the previous unlinked BG.
- If BG_in is the reference BG and the reference BG is an unlinked BG, prevUnlinkedBG is set to refBG.
- If BG_in is the reference BG and a linked BG with or without linking information, the location of prevUnlinkedBG is recalculated from refBG based upon odometry values.
- This is possible, because refBG must have been passed, and therefore prevUnlinkedBG too.
- If BG_in is not the reference BG and is an unlinked BG, prevLinkedBG is set to the relocated BG_in.
- If BG_in is not the reference BG and is not an unlinked BG, prevLinkedBG is taken from refBGs_in.prevUnlinkedBG.

15.2.13.5.5. View of diagram_recalculate_BG_location
(recalculate_BG_locations_ahead_itr)

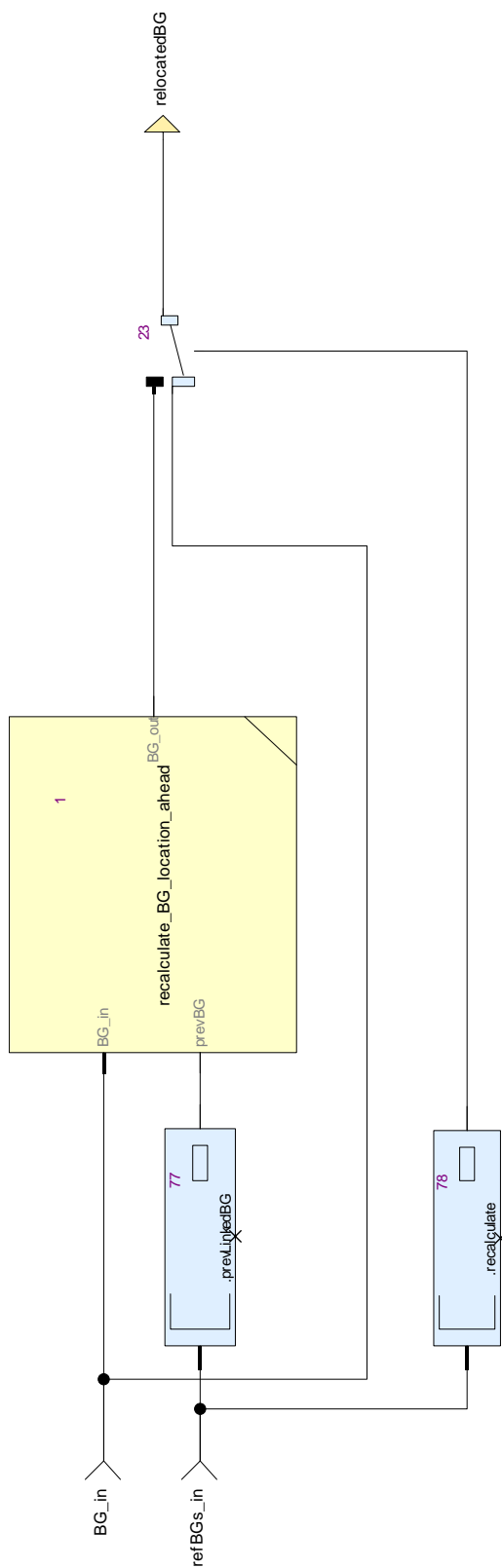


Figure 74: View of diagram_recalculate_BG_location (recalculate_BG_locations_ahead_itr)

15.2.13.5.6. View of diagram_recalculate_refBG_location (recalculate_BG_locations_ahead_itr)

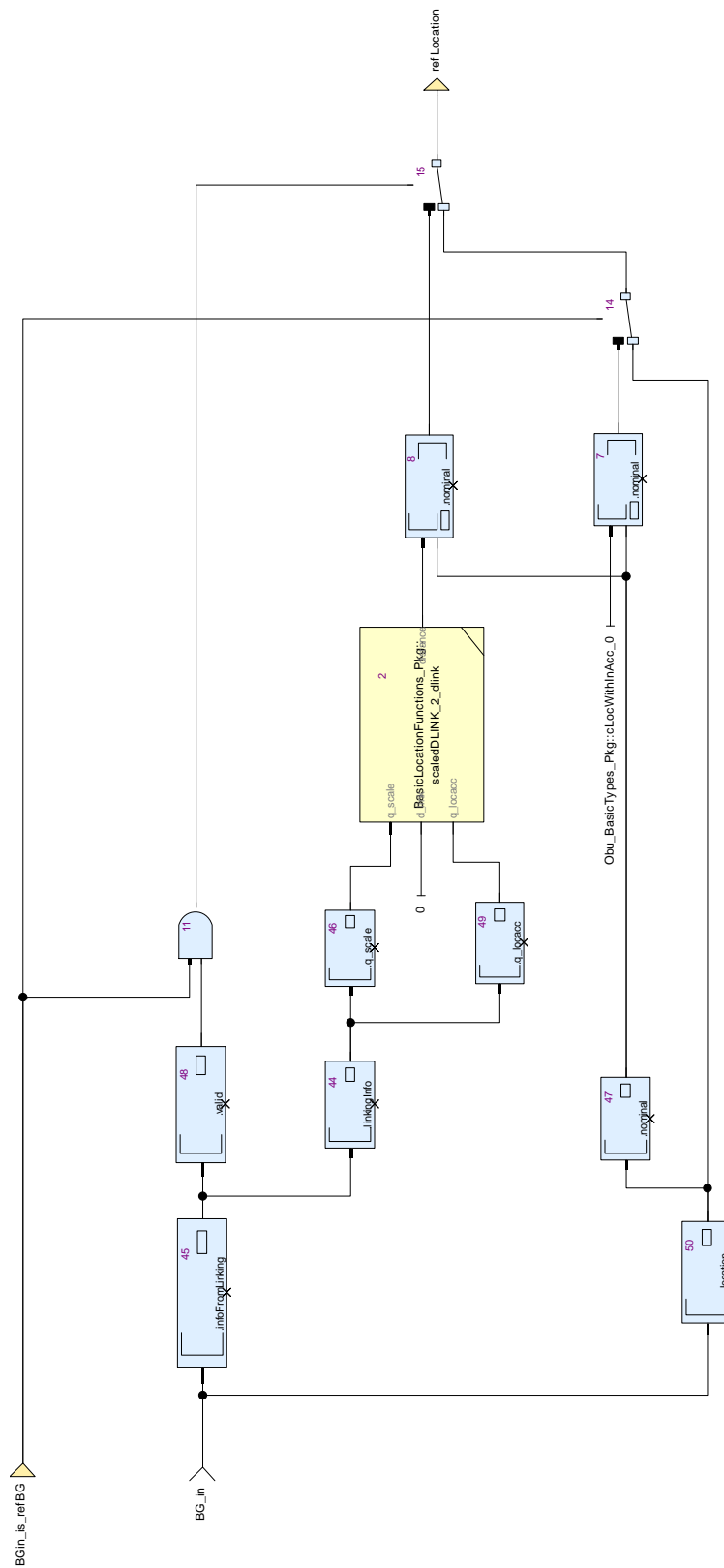


Figure 75: View of diagram_recalculate_refBG_location (recalculate_BG_locations_ahead_itr)

diagram_recalculate_refBG_location Comments:

- Recalculate the location of the reference BG.
- The location of the reference BG will be the origin, from where all other locations have to be recalculated.
- If the refBG is a linked BG with linking information available, its nominal location is kept unchanged with inaccuracies derived from its linking information.
- If the refBG is an unlinked BG or a linked BG without linking information, its nominal location is kept unchanged with inaccuracy 0.

15.2.14. recalculate_BG_locations_astern Operator

Declared as **private function**

15.2.14.1. Comments and Information

recalculate_BG_locations_astern Comments:

- Recalculates the BG locations in backward direction, starting from referenceBG to all previous BGs.
- The location of referenceBG in BGs stays unchanged.
- The locations of all BGs before referenceBG are adjusted relatively to referenceBG.
- The locations of all BGs ahead of referenceBG are left unchanged.
- BGs_in should have locations assigned and arranged in increasing order of locations.

15.2.14.2. Interface

Table 203: Inputs of recalculate_BG_locations_astern

| Name | Type | Comments and Information |
|-------------|--|--|
| referenceBG | TrainPosition_Types_Pc k::positionedBG_T | Comments: Recalculates the locations of all BGs with reference to referenceBG, beginning with the BG before the referenceBG and then all BGs backwards. |
| BGs_in | TrainPosition_Types_Pc k::positionedBGs_T | |

Table 204: Outputs of recalculate_BG_locations_astern

| Name | Type | Comments and Information |
|---------|--|--------------------------|
| BGs_out | TrainPosition_Types_Pc k::positionedBGs_T | |

15.2.14.3. Operator Hierarchy

diagram : diagram_recalculate_BG_locations_astern_1

15.2.14.4. Graphical and Textual Diagrams

15.2.14.4.1. View of diagram_recalculate_BG_locations_astern_1 (recalculate_BG_locations_astern)

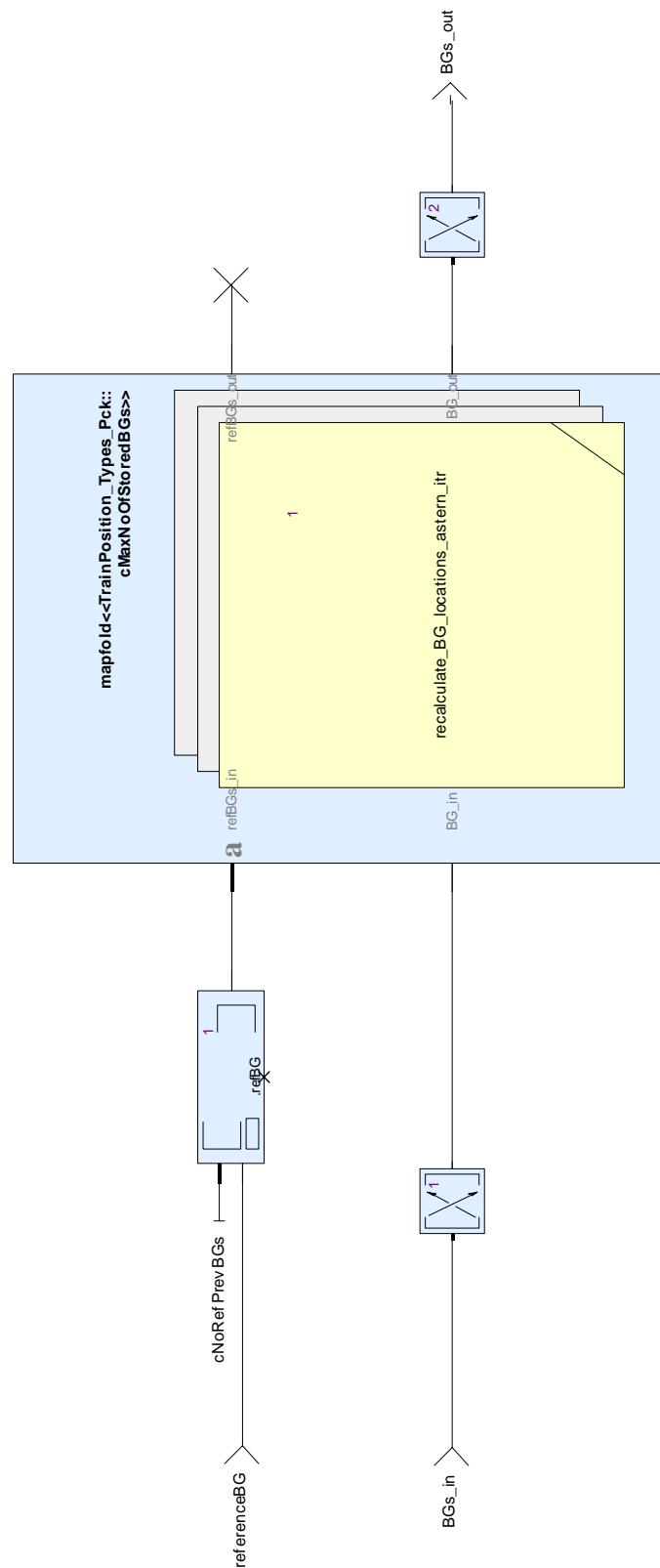


Figure 76: View of diagram_recalculate_BG_locations_astern_1 (recalculate_BG_locations_astern)

15.2.15. recalculate_BG_locations_astern_itr Operator

Declared as **private function**

15.2.15.1. Comments and Information

recalculate_BG_locations_astern_itr Comments:

- Iterated function for recalculating the locations of all BGs in backward direction, starting from refBGs_in.refBG with all BGs astern.
- The location of refBGs_in.refBG is left unchanged.
- The location of a BG_in astern of refBGs_in.refBG is adjusted relatively to refBGs_in.
- The location of a BG_in ahead of refBGs_in.refBG is left unchanged.
- This function is for iterating through the BGs from tail to head, i. e. in backwards direction.
- Therefore, refBGs_in.prevLinkedBG and refBGs_in.prevUnlinkedBG refer to BGs previously in the iteration, i. e. ahead of BG_in.
- See diagram description for more details.

15.2.15.2. Interface

Table 205: Inputs of recalculate_BG_locations_astern_itr

| Name | Type | Comments and Information |
|-----------|---|---|
| refBGs_in | CalculateTrainPosition_ Pkg::BG_relocation_Pk g::refBGs_T | Comments: Note: prevUnlinkedBG and prevLinkedBG are previous for the backward iteration. |
| BG_in | TrainPosition_Types_Pc k::positionedBG_T | Comments: The BG that's location has to be recalculated |

Table 206: Outputs of recalculate_BG_locations_astern_itr

| Name | Type | Comments and Information |
|------------|---|--|
| refBGs_out | CalculateTrainPosition_ Pkg::BG_relocation_Pk g::refBGs_T | |
| BG_out | TrainPosition_Types_Pc k::positionedBG_T | Comments: The BG that's location has been recalculated. |

15.2.15.3. Locals

Table 207: Locals of recalculate_BG_locations_astern_itr

| Name | Type | Comments and Information |
|------------------------------|---|--------------------------|
| BGin_is_refBG | bool | |
| prevLinkedBG | TrainPosition_Types_Pc k::positionedBG_T | |
| prevUnlinkedBG | TrainPosition_Types_Pc k::positionedBG_T | |
| recalculateSubsequent BGs | bool | |
| refBG | TrainPosition_Types_Pc k::positionedBG_T | |
| relocatedBG | TrainPosition_Types_Pc k::positionedBG_T | |

15.2.15.4. Operator Hierarchy

diagram : diagram_assembleResults

diagram : diagram_assign_refBG

diagram : diagram_determinePreviousLinkedBG

diagram : diagram_determinePreviousUnlinkedBG

diagram : diagram_recalculate_BG_location

15.2.15.5. Graphical and Textual Diagrams

15.2.15.5.1. View of diagram_assembleResults (recalculate_BG_locations_astern_itr)

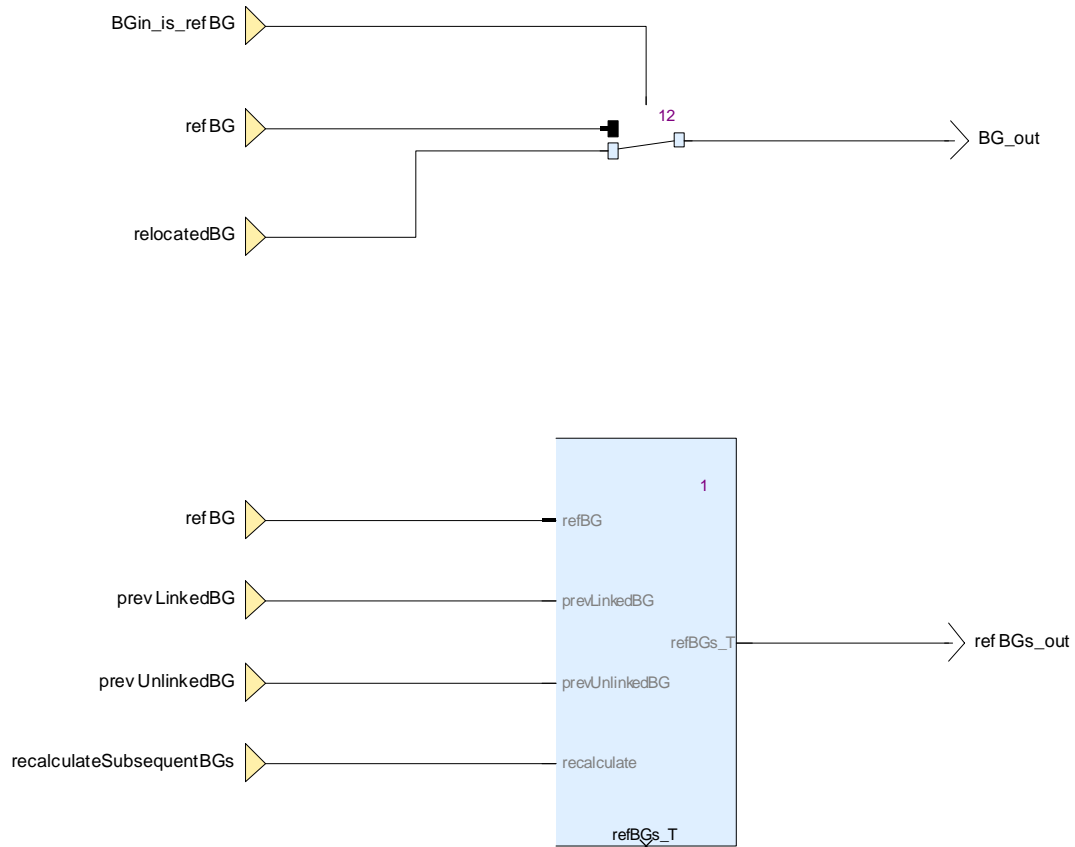


Figure 77: View of diagram_assembleResults (recalculate_BG_locations_astern_itr)

diagram_assembleResults Comments:

- Assembles the outputs.

15.2.15.5.2. View of diagram_assign_refBG (recalculate_BG_locations_astern_itr)

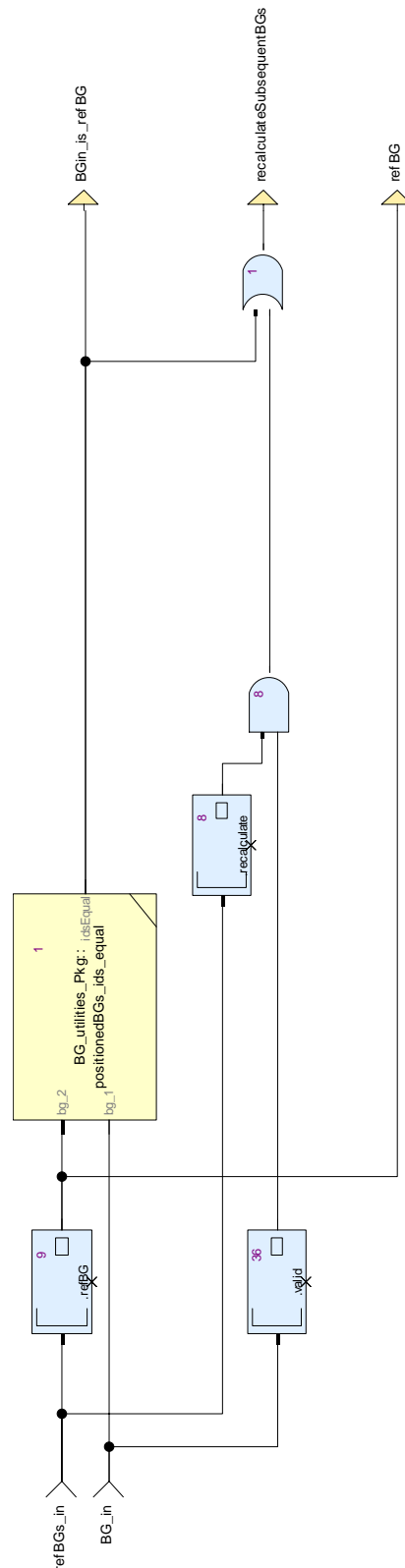


Figure 78: View of diagram_assign_refBG (recalculate_BG_locations_astern_itr)

diagram_assign_refBG Comments:

- Determines if BG_in is the reference BG.
- If yes, the location of the reference BG has to be recalculated.

- For all subsequent BGs in the iteration, the locations have to be recalculated.
- For all BGs in the iteration before the reference BGs, the locations are kept unchanged.

15.2.15.5.3. View of diagram_determinePreviousLinkedBG (recalculate_BG_locations_astern_itr)

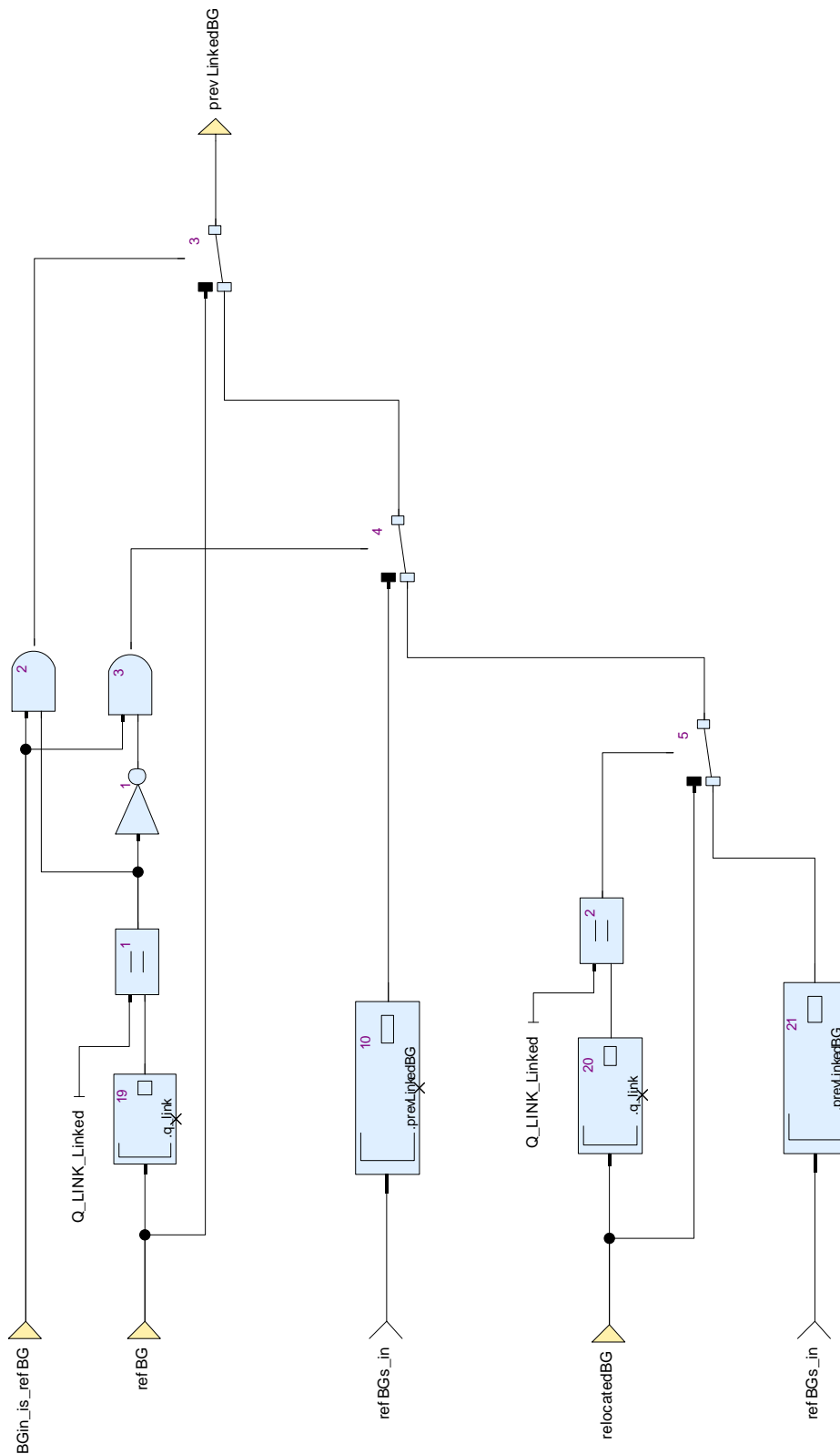


Figure 79: View of diagram_determinePreviousLinkedBG (recalculate_BG_locations_astern_itr)

diagram_determinePreviousLinkedBG Comments:

- Determines the previous linked BG.

- If BG_in is the reference BG and the reference BG is a linked BG, prevLinkedBG is set to refBG.
- If BG_in is the reference BG and is an unlinked BG, prevLinkedBG is taken from refBGs_in.prevLinkedBG
- If BG_in is not the reference BG and is a linked BG, prevLinkedBG is set to the relocated BG_in.
- If BG_in is not the reference BG and is an unlinked BG, prevLinkedBG is taken from refBGs_in.prevLinkedBG.

15.2.15.5.4. View of diagram_determinePreviousUnlinkedBG (recalculate_BG_locations_astern_itr)

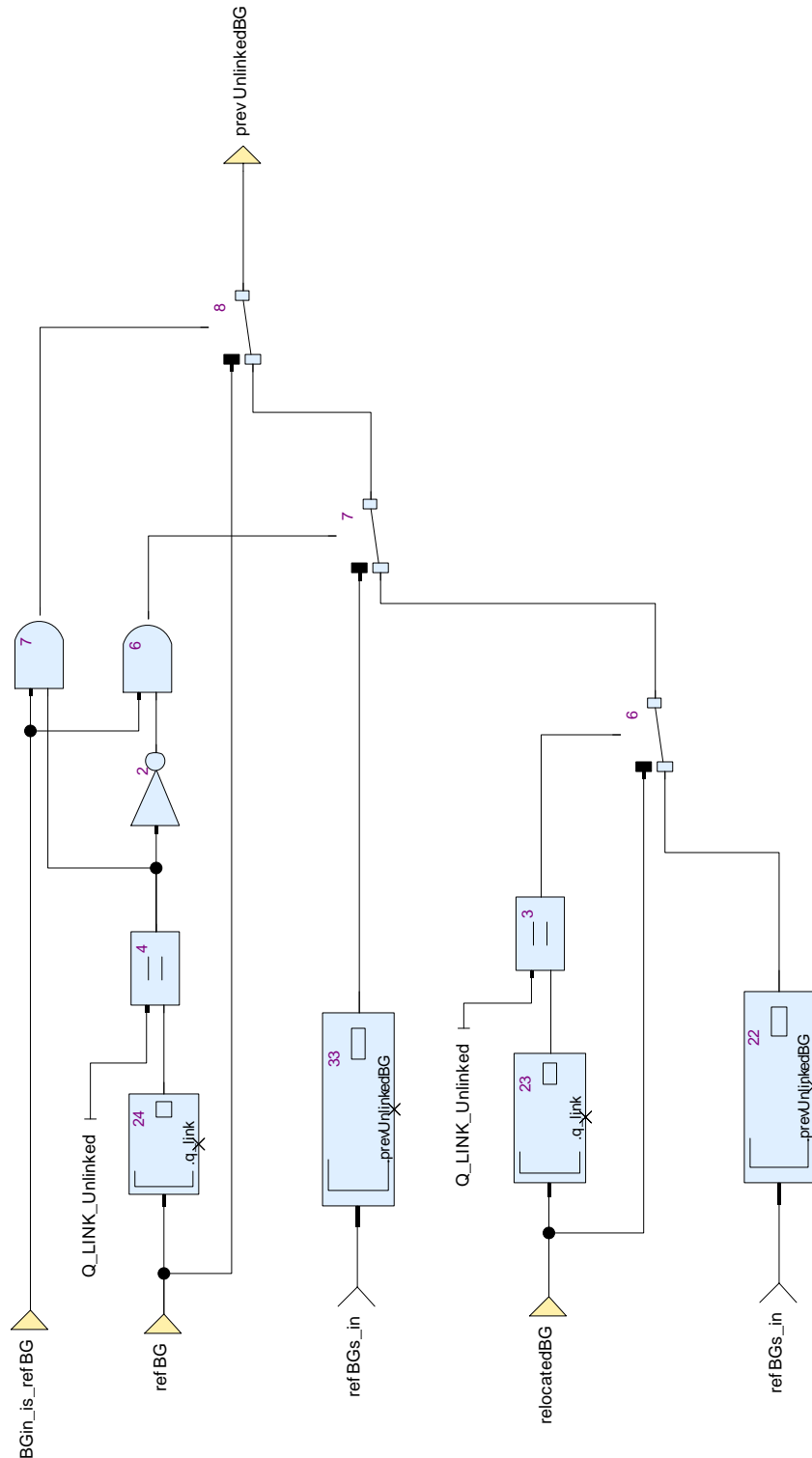


Figure 80: View of diagram_determinePreviousUnlinkedBG (recalculate_BG_locations_astern_itr)

diagram_determinePreviousUnlinkedBG Comments:

- Determines the previous unlinked BG.
- If BG_in is the reference BG and the reference BG is an unlinked BG, prevUnlinkedBG is set to refBG.

- If BG_in is the reference BG and a linked BG with or without linking information, prevUnlinkedBG is taken from refBGs_in.prevUnlinkedBG.
- If BG_in is not the reference BG and is an unlinked BG, prevLinkedBG is set to the relocated BG_in.
- If BG_in is not the reference BG and is not an unlinked BG, prevUnlinkedBG is taken from refBGs_in.prevUnlinkedBG.

15.2.15.5.5. View of diagram_recalculate_BG_location (recalculate_BG_locations_astern_itr)

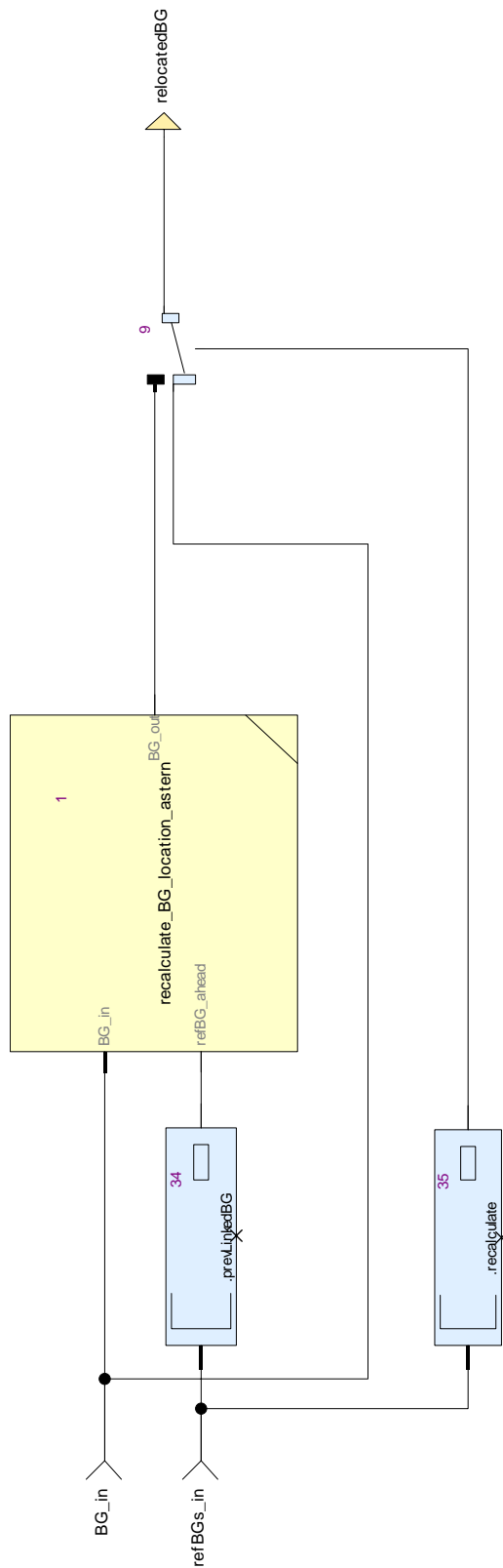


Figure 81: View of diagram_recalculate_BG_location (recalculate_BG_locations_astern_itr)

diagram_recalculate_BG_location Comments:

- Recalculates the location of BG_in.

15.3. CalculateTrainPosition_Pkg::BG_utilities_Pkg Package

15.3.1. Types

Table 208: Public Types of BG_utilities_Pkg

| Name | Definition | Comments and Information |
|---------------|--|---|
| BG_counters_T | {unlinkedBGsCount : int, linkedBGsCount : int, totalBGsCount : int, passedUnlinkedBGsCount : int, passedLinkedBGsCount : int, passedTotalBGsCount : int} | Comments: Serves to count the BGs |
| BG_find_T | {index : int, noOfFoundBGs : int, BGFound : bool} | Comments: Serves to search through the BGs |

15.3.2. Constants

Table 209: Public Constants of BG_utilities_Pkg

| Name | Type | Value | Comments and Information |
|---------------|---|---|--------------------------|
| cBG_find_0 | CalculateTrainPosition_Pkg::BG_utilities_Pkg::BG_find_T | {index : cNoValidIndex, noOfFoundBGs : 0, BGFound : false} | |
| cBGCounters_0 | CalculateTrainPosition_Pkg::BG_utilities_Pkg::BG_counters_T | {unlinkedBGsCount : 0, linkedBGsCount : 0, totalBGsCount : 0, passedUnlinkedBGsCount : 0, passedLinkedBGsCount : 0, passedTotalBGsCount : 0} | |

| Name | Type | Value | Comments and Information |
|------|------|--|--------------------------|
| | | <pre>{valid : false, nid_c : 0, nid_bg : 0, q_link : Q_LINK_Unlinked, location : {nominal : 0, d_min : 0, d_max : 0}, seqNoOnTrack : 0, infoFromLinking : {valid : false, nid_bg_fromLinking BG : 0, nid_c_fromLinkingB G : 0, expectedLocation : {nominal : 0, d_min : 0, d_max : 0}, d_link : {nominal : 0, d_min : 0, d_max : 0}, linkingInfo : {valid : false, nid_LRBG : 0, nid_packet : 0, q_dir : Q_DIR_Reverse, l_packet : 0, q_scale : Q_SCALE_10_cm_s cale, d_link : 0, q_newcountry : Q_NEWCOUNTRY_S ame_country__or__ railway_administrati on_no_NID_C_follo ws, nid_c : 0, nid_bg : 0, q_linkorientation : Q_LINKORIENTATIO N_The_balise_grou p_is_seen_by_the_t rain_in_reverse_dir ection, q_linkreaction : Q_LINKREACTION_ Train_trip, q_locacc : 0}}, infoFromPassing : {valid : false, timestamp : 0, odometrystamp : {o_nominal : 0, o_min : 0, o_max : 0}, BG_centerDetection Inaccuracies : {nominal : 0, d_min : 0, d_max : 0}, BG_Header : {q_updown : Q_UPDOWN_Down_ link_telegram, m_version : M_VERSION_Previo us_versions_accordi ng_to_e_g_EEIG_S ome ETCS open and UIC_A200_ SRS, q_media : Q_MEDIA_Balise, n_pig :</pre> | |

15.3.3. countBGs Operator

Declared as **public function**

15.3.3.1. Comments and Information

countBGs Comments:

- Determines the linked, unlinked and total number of BGs in BG_in.

15.3.3.2. Interface

Table 210: Inputs of countBGs

| Name | Type | Comments and Information |
|--------|--|--------------------------|
| BGs_in | TrainPosition_Types_Pkg::positionedBGs_T | |
| enable | bool | |

Table 211: Outputs of countBGs

| Name | Type | Comments and Information |
|----------|---|---|
| empty | bool | Comments: No BG in BGs_in. |
| full | bool | Comments: BGs_in filled completely with BGs. |
| counters | CalculateTrainPosition_Pkg::BG_utilities_Pkg::BG_counters_T | |

15.3.3.3. Operator Hierarchy

diagram : diagram_countBGs_1

15.3.3.4.1. View of diagram_countBGs_1 (countBGs)

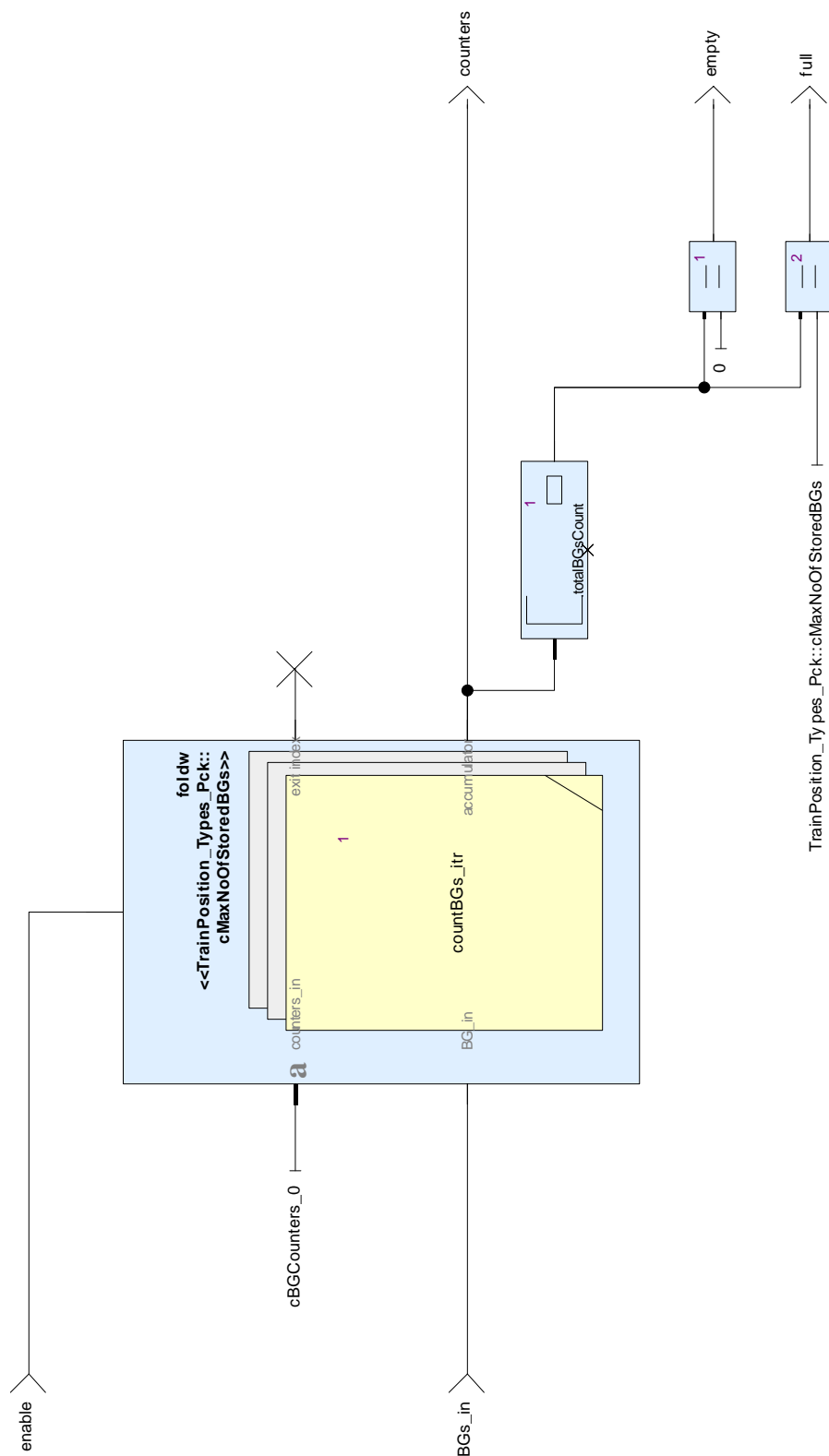


Figure 82: View of diagram_countBGs_1 (countBGs)

15.3.4. countBGs_itr Operator

Declared as **private function**

15.3.4.1. Comments and Information

countBGs_itr Comments:

- Iterated function for countBGs

15.3.4.2. Interface

Table 212: Inputs of countBGs_itr

| Name | Type | Comments and Information |
|-------------|---|--------------------------|
| counters_in | CalculateTrainPosition_ Pkg::BG_utilities_Pkg:: BG_counters_T | |
| BG_in | TrainPosition_Types_Pc k::positionedBG_T | |

Table 213: Outputs of countBGs_itr

| Name | Type | Comments and Information |
|--------------|---|--------------------------|
| cont | bool | |
| counters_out | CalculateTrainPosition_ Pkg::BG_utilities_Pkg:: BG_counters_T | |

15.3.4.3. Operator Hierarchy

diagram : diagram_countBGs_itr_1

15.3.4.4. Graphical and Textual Diagrams

15.3.4.4.1. View of diagram_countBGs_itr_1 (countBGs_itr)

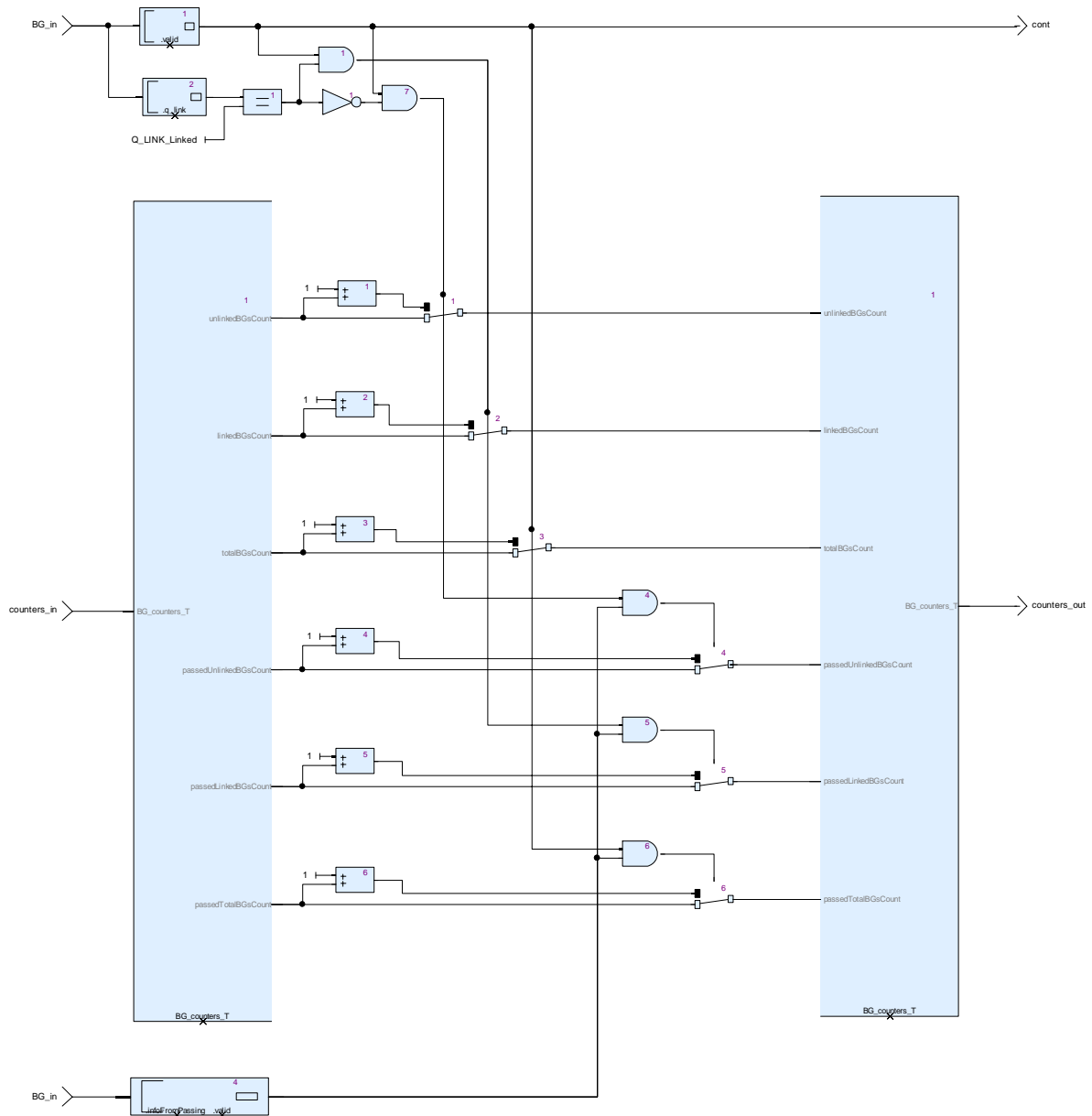


Figure 83: View of diagram_countBGs_itr_1 (countBGs_itr)

15.3.5. deleteBG_atIndex Operator

Declared as **public function**

15.3.5.1. Comments and Information

deleteBG_atIndex Comments:

- Deletes a BG in BGs, designated by indexOfBG.
- The hole caused by the deletion is filled afterwards by shifting the higher part of BGs down by 1, so that no hole is left in BGs_out afterwards.

15.3.5.2. Interface

Table 214: Inputs of deleteBG_atIndex

| Name | Type | Comments and Information |
|-----------|--|--|
| BGs_in | TrainPosition_Types_Pc k::positionedBGs_T | |
| indexOfBG | int | |
| del | bool | Comments: Delete command. Deletion takes place if del = true. |

Table 215: Outputs of deleteBG_atIndex

| Name | Type | Comments and Information |
|---------|--|--------------------------|
| BGs_out | TrainPosition_Types_Pc k::positionedBGs_T | |

15.3.5.3. Operator Hierarchy

diagram : diagram_deleteBG_atIndex_1

15.3.5.4.1. View of diagram_deleteBG_atIndex_1 (deleteBG_atIndex)

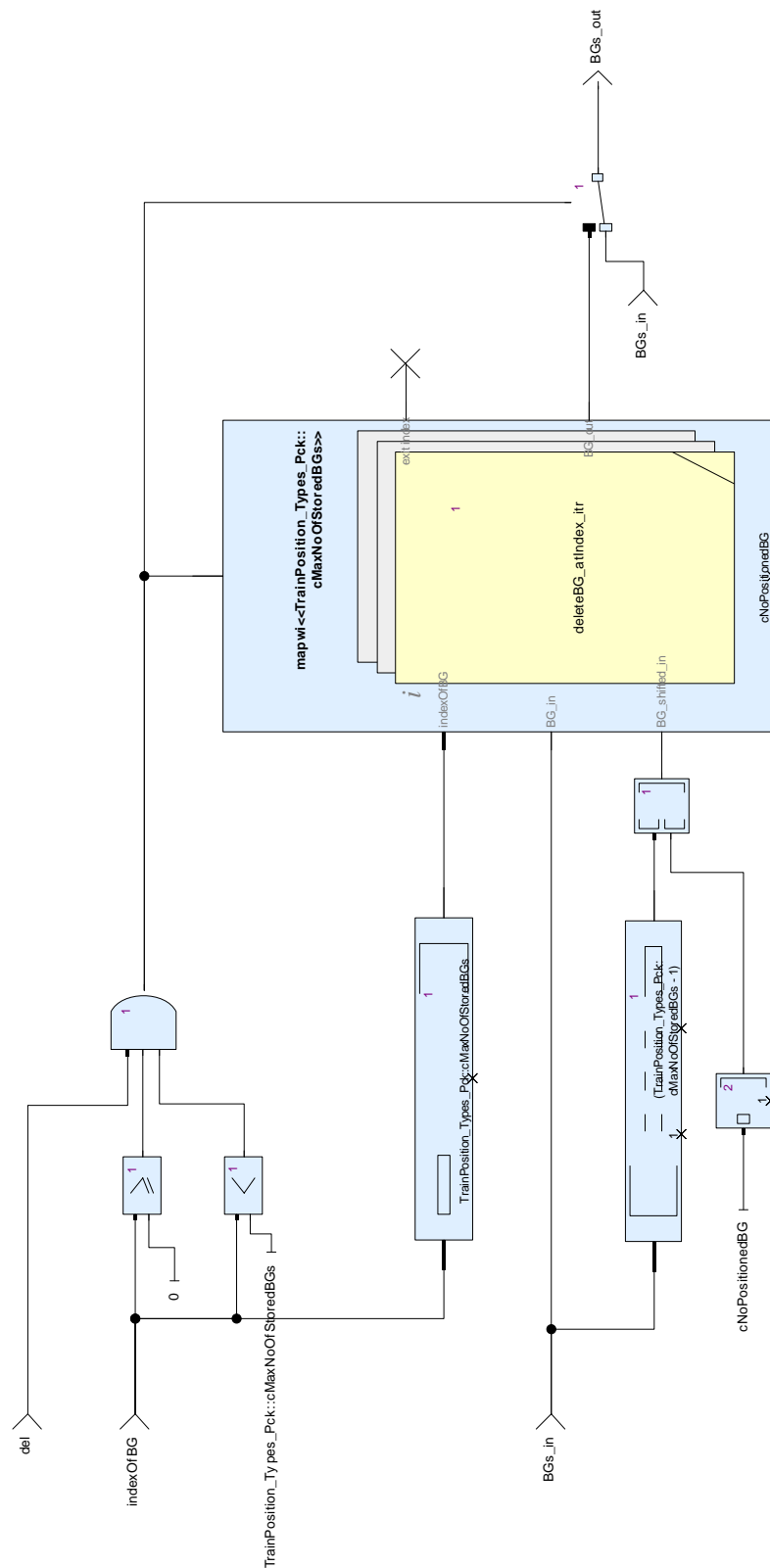


Figure 84: View of diagram_deleteBG_atIndex_1 (deleteBG_atIndex)

15.3.6. deleteBG_atIndex_itr Operator

Declared as **private function**

15.3.6.1. Comments and Information

deleteBG_atIndex_itr Comments:

- Iterated function used by deleteBG_atIndex

15.3.6.2. Interface

Table 216: Inputs of deleteBG_atIndex_itr

| Name | Type | Comments and Information |
|---------------|---|--------------------------|
| iteratorIndex | int | |
| indexOfBG | int | |
| BG_in | TrainPosition_Types_Pc k::positionedBG_T | |
| BG_shifted_in | TrainPosition_Types_Pc k::positionedBG_T | |

Table 217: Outputs of deleteBG_atIndex_itr

| Name | Type | Comments and Information |
|--------|---|--------------------------|
| cont | bool | |
| BG_out | TrainPosition_Types_Pc k::positionedBG_T | |

15.3.6.3. Operator Hierarchy

diagram : diagram_deleteBG_atIndex_itr_1

```

activate if : IfBlock1
  branch : then
  branch : else
    branch : then
    branch : else

```

15.3.6.4. Graphical and Textual Diagrams

15.3.6.4.1. View of diagram_deleteBG_atIndex_itr_1 (deleteBG_atIndex_itr)

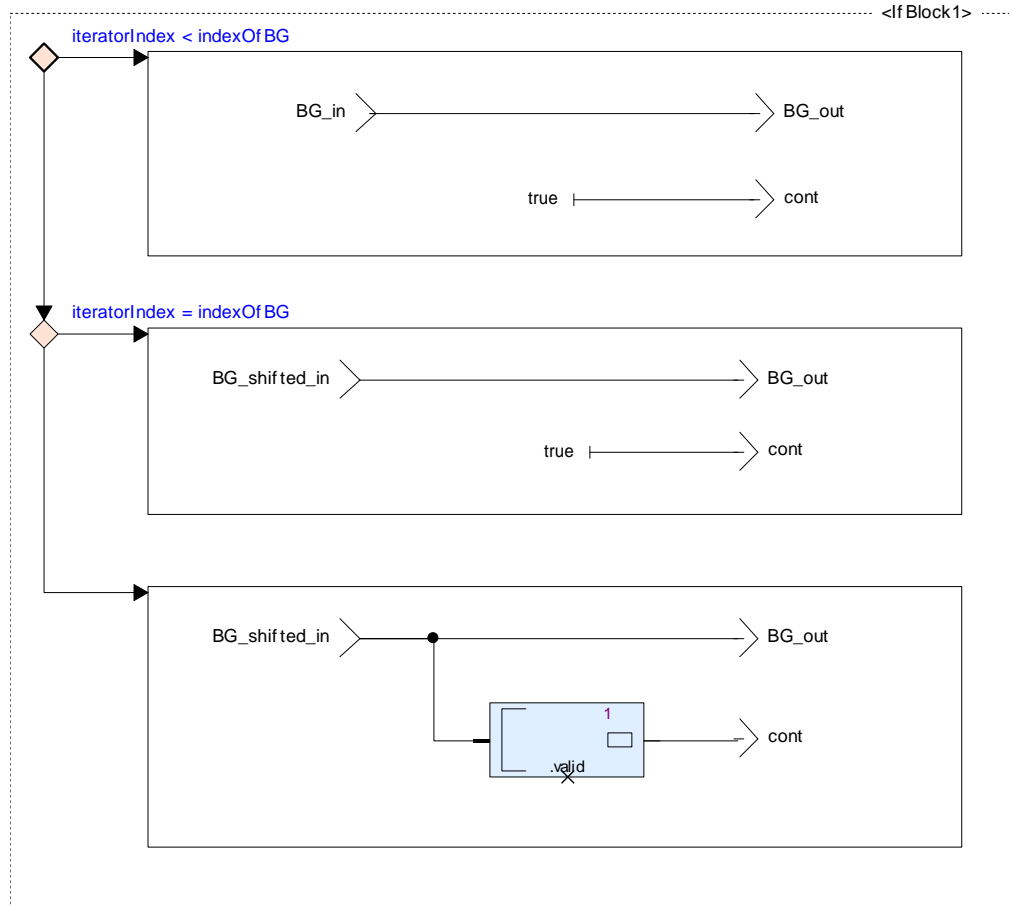


Figure 85: View of diagram_deleteBG_atIndex_itr_1 (deleteBG_atIndex_itr)

Table 218: Conditional Blocks of diagram_deleteBG_atIndex_itr_1

| Conditional Block | Comments and Information |
|-------------------|--------------------------|
| IfBlock1 | |

Table 219: Actions of diagram_deleteBG_atIndex_itr_1

| Conditional Block Action | Comments and Information |
|--------------------------|--------------------------|
| IfBlock1: then | |
| IfBlock1: else: then | |
| IfBlock1: else: else | |

15.3.7. deleteBGs_beforeIndex Operator

Declared as **public function**

15.3.7.1. Comments and Information

deleteBGs_beforeIndex Comments:

- Deletes all BGs in BGs, starting with index 0 until (indexOfBG - 1).

15.3.7.2. Interface

Table 220: Inputs of deleteBGs_beforeIndex

| Name | Type | Comments and Information |
|-----------|--|---|
| BGs_in | TrainPosition_Types_Pc k::positionedBGs_T | |
| indexOfBG | int | |
| del | bool | Comments: Delete command. Deletion takes place if del = true. |

Table 221: Outputs of deleteBGs_beforeIndex

| Name | Type | Comments and Information |
|---------|--|--------------------------|
| BGs_out | TrainPosition_Types_Pc k::positionedBGs_T | |

15.3.7.3. Operator Hierarchy

diagram : diagram_deleteBGs_beforeIndex_1

15.3.7.4. Graphical and Textual Diagrams

15.3.7.4.1. View of diagram_deleteBGs_beforeIndex_1 (deleteBGs_beforeIndex)

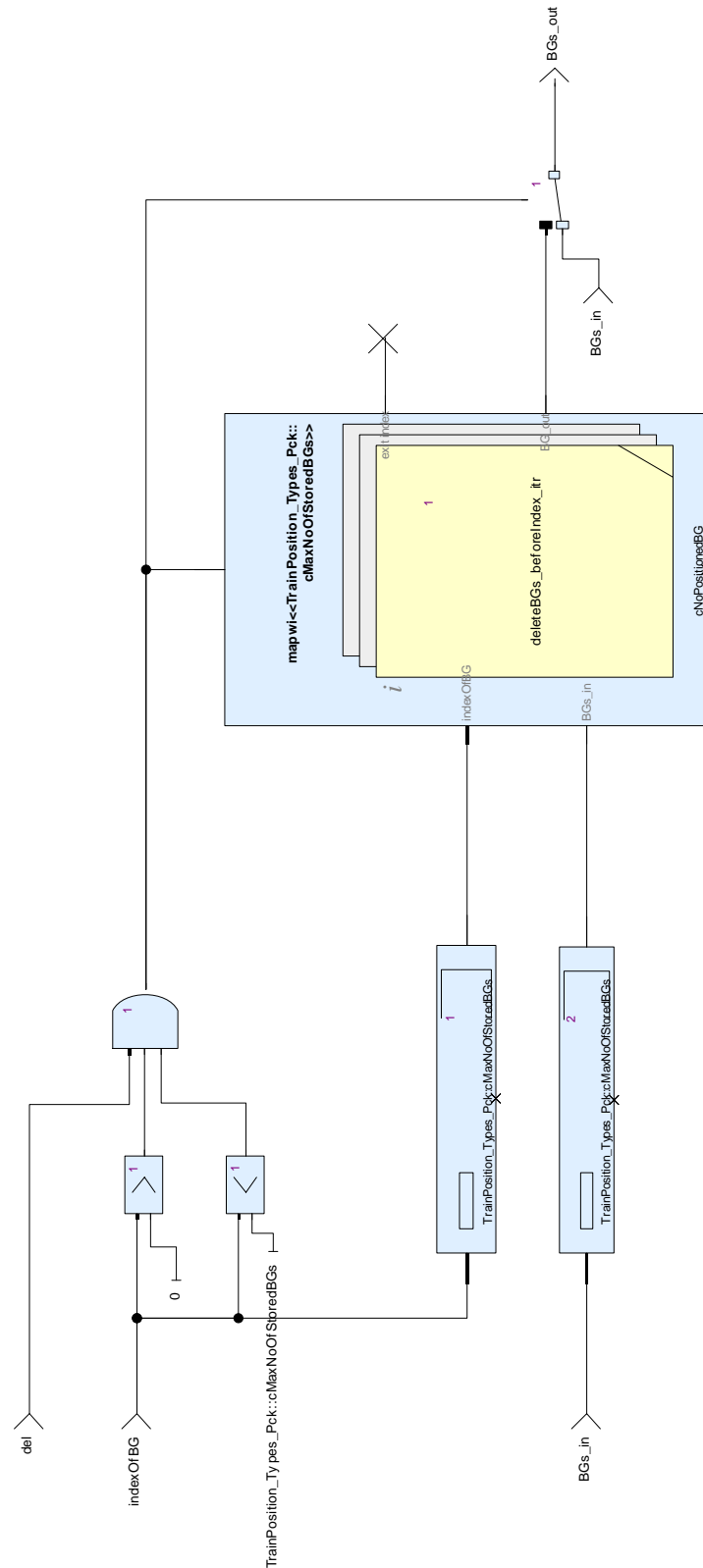


Figure 86: View of diagram_deleteBGs_beforeIndex_1 (deleteBGs_beforeIndex)

15.3.8. deleteBGs_beforeIndex_itr Operator

Declared as **private function**

15.3.8.1. Comments and Information

deleteBGs_beforeIndex_itr Comments:

- Iterated function used by deleteBGs_beforeIndex

15.3.8.2. Interface

Table 222: Inputs of deleteBGs_beforeIndex_itr

| Name | Type | Comments and Information |
|---------------|--|--------------------------|
| iteratorIndex | int | |
| indexOfBG | int | |
| BGs_in | TrainPosition_Types_Pc k::positionedBGs_T | |

Table 223: Outputs of deleteBGs_beforeIndex_itr

| Name | Type | Comments and Information |
|--------|---|--------------------------|
| cont | bool | |
| BG_out | TrainPosition_Types_Pc k::positionedBG_T | |

15.3.8.3. Operator Hierarchy

diagram : diagram_deleteBGs_beforeIndex_itr_1

15.3.8.4. Graphical and Textual Diagrams

15.3.8.4.1. View of diagram_deleteBGs_beforeIndex_itr_1 (deleteBGs_beforeIndex_itr)

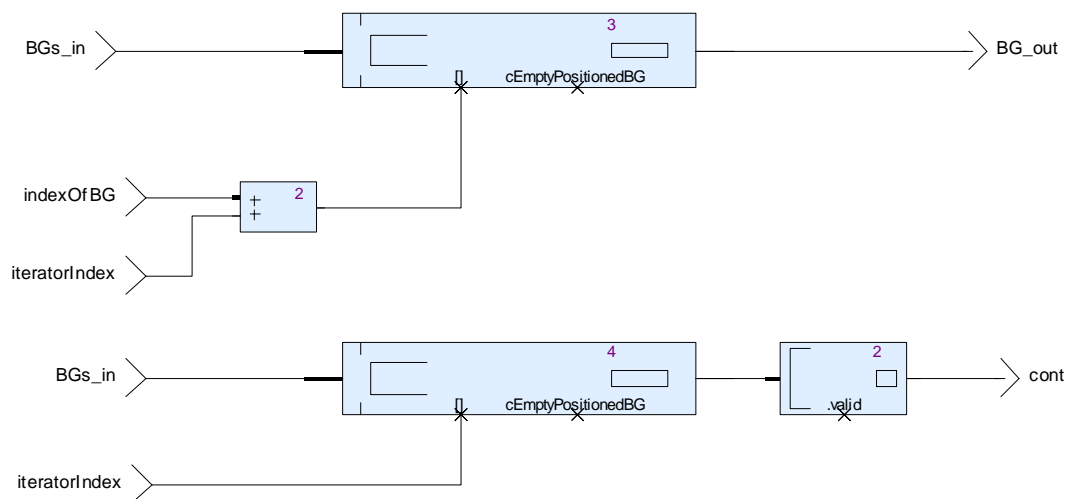


Figure 87: View of diagram_deleteBGs_beforeIndex_itr_1 (deleteBGs_beforeIndex_itr)

15.3.9. deleteBGs_fromIndex Operator

Declared as **public function**

15.3.9.1. Comments and Information

deleteBGs_fromIndex Comments:

- Deletes all BGs in BGs, starting with indexOfBG until the end of the list.

15.3.9.2. Interface

Table 224: Inputs of deleteBGs_fromIndex

| Name | Type | Comments and Information |
|-----------|--|--|
| BGs_in | TrainPosition_Types_Pc k::positionedBGs_T | |
| indexOfBG | int | |
| del | bool | Comments: Delete command. Deletion takes place if del = true. |

Table 225: Outputs of deleteBGs_fromIndex

| Name | Type | Comments and Information |
|---------|--|--------------------------|
| BGs_out | TrainPosition_Types_Pc k::positionedBGs_T | |

15.3.9.3. Operator Hierarchy

diagram : diagram_deleteBGs_fromIndex_1

15.3.9.4. Graphical and Textual Diagrams

15.3.9.4.1. View of diagram_deleteBGs_fromIndex_1 (deleteBGs_fromIndex)

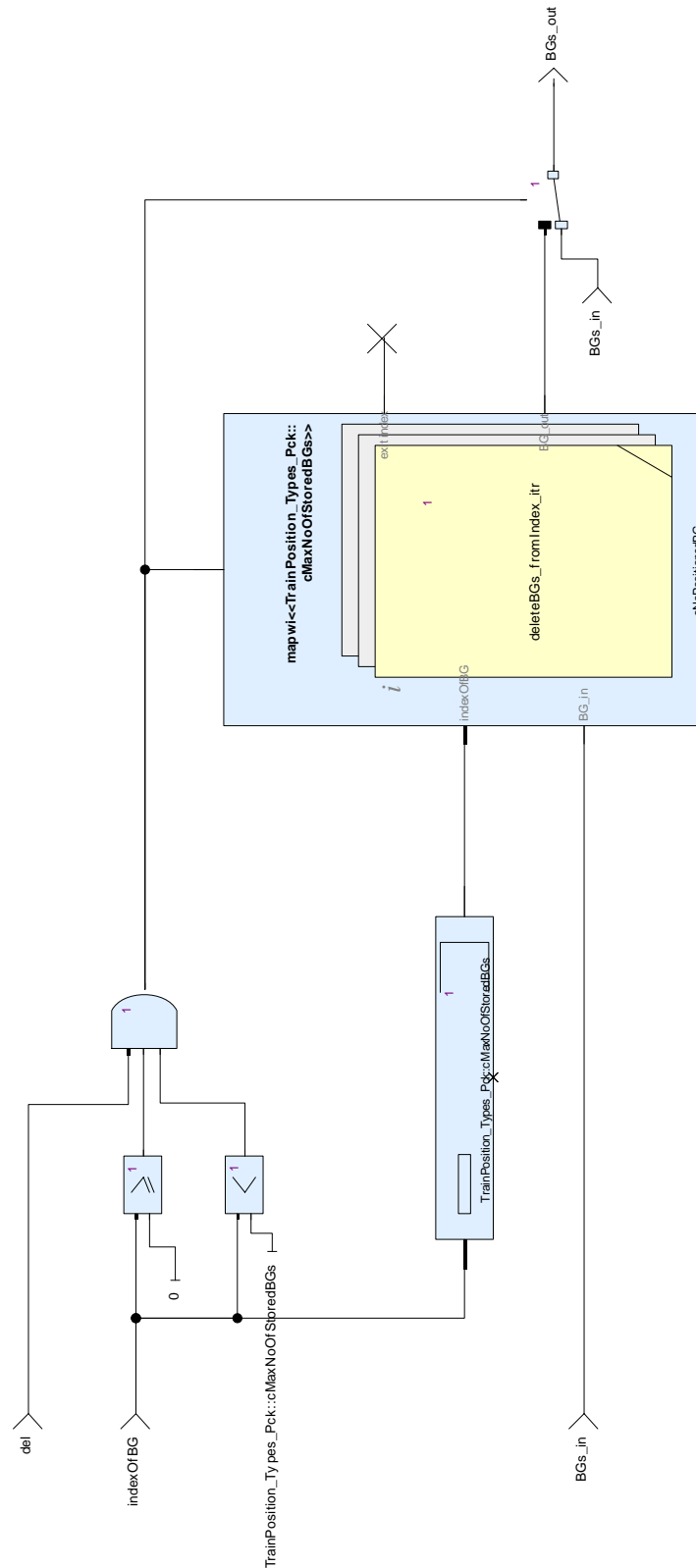


Figure 88: View of diagram_deleteBGs_fromIndex_1 (deleteBGs_fromIndex)

15.3.10. deleteBGs_fromIndex_itr Operator

Declared as **private function**

15.3.10.1. Comments and Information

deleteBGs_fromIndex_itr Comments:

- Iterated function used by deleteBGs_fromIndex

15.3.10.2. Interface

Table 226: Inputs of deleteBGs_fromIndex_itr

| Name | Type | Comments and Information |
|---------------|---|--------------------------|
| iteratorIndex | int | |
| indexOfBG | int | |
| BG_in | TrainPosition_Types_Pc k::positionedBG_T | |

Table 227: Outputs of deleteBGs_fromIndex_itr

| Name | Type | Comments and Information |
|--------|---|--------------------------|
| cont | bool | |
| BG_out | TrainPosition_Types_Pc k::positionedBG_T | |

15.3.10.3. Operator Hierarchy

diagram : diagram_deleteBGs_fromIndex_itr_1

activate if : IfBlock1

 branch : then

 branch : else

 branch : then

 branch : else

15.3.10.4. Graphical and Textual Diagrams

15.3.10.4.1. View of diagram_deleteBGs_fromIndex_itr_1 (deleteBGs_fromIndex_itr)

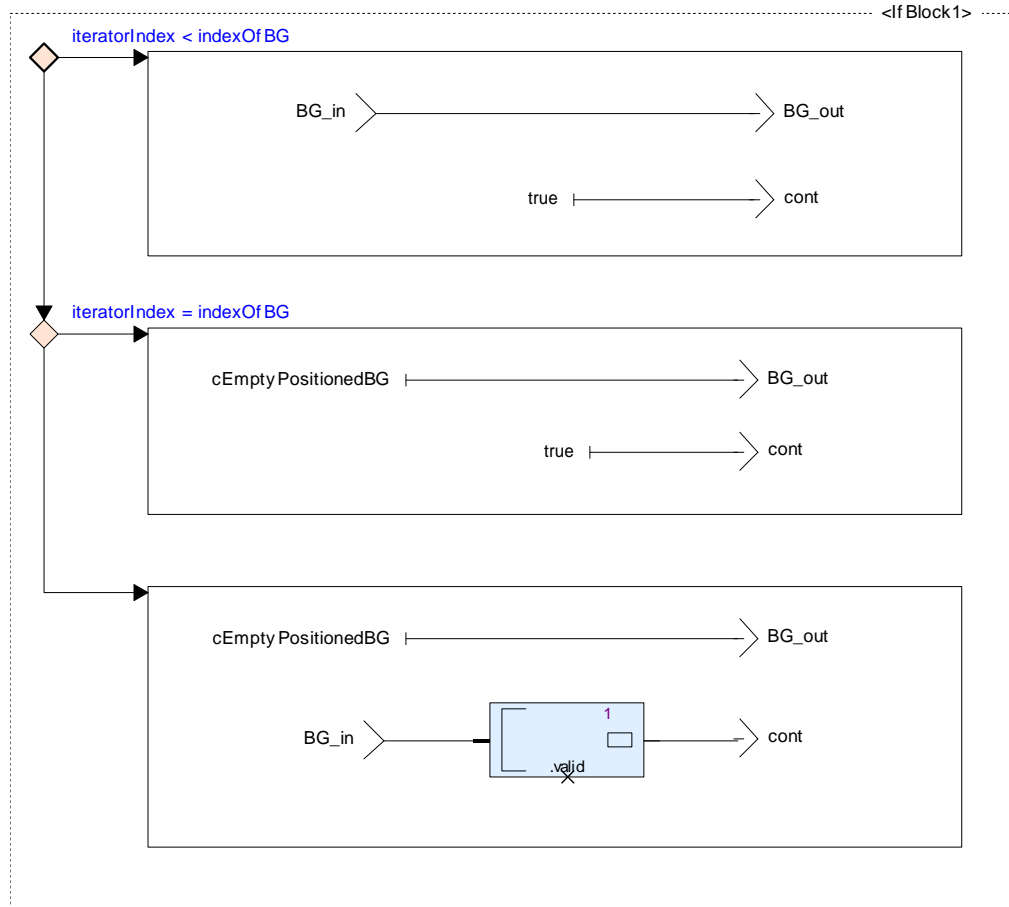


Figure 89: View of diagram_deleteBGs_fromIndex_itr_1 (deleteBGs_fromIndex_itr)

Table 228: Conditional Blocks of diagram_deleteBGs_fromIndex_itr_1

| Conditional Block | Comments and Information |
|-------------------|--------------------------|
| IfBlock1 | |

Table 229: Actions of diagram_deleteBGs_fromIndex_itr_1

| Conditional Block Action | Comments and Information |
|--------------------------|--------------------------|
| IfBlock1: then | |
| IfBlock1: else: then | |
| IfBlock1: else: else | |

15.3.11. indexOf_nthPassedBG Operator

Declared as **public function**

15.3.11.1. Comments and Information

indexOf_nthPassedBG Comments:

- Determines the index of the n-th linked or unlinked passed BG in BGs.

15.3.11.2. Interface

Table 230: Inputs of indexOf_nthPassedBG

| Name | Type | Comments and Information |
|--------|--|---|
| linked | bool | Comments: Condition if the seach is for a linked or unlinked BG. |
| n | int | Comments: The n-th BGs will be searched. This is the related number "n". |
| BGs | TrainPosition_Types_Pc k::positionedBGs_T | |
| enable | bool | |

Table 231: Outputs of indexOf_nthPassedBG

| Name | Type | Comments and Information |
|-----------|------|--|
| indexOfBG | int | |
| BG_found | bool | Comments: Indicates, that BG exists in BGs. |

15.3.11.3. Operator Hierarchy

diagram : diagram_indexOf_nthPassedBG_1

15.3.11.4.1. View of diagram_indexOf_nthPassedBG_1 (indexOf_nthPassedBG)

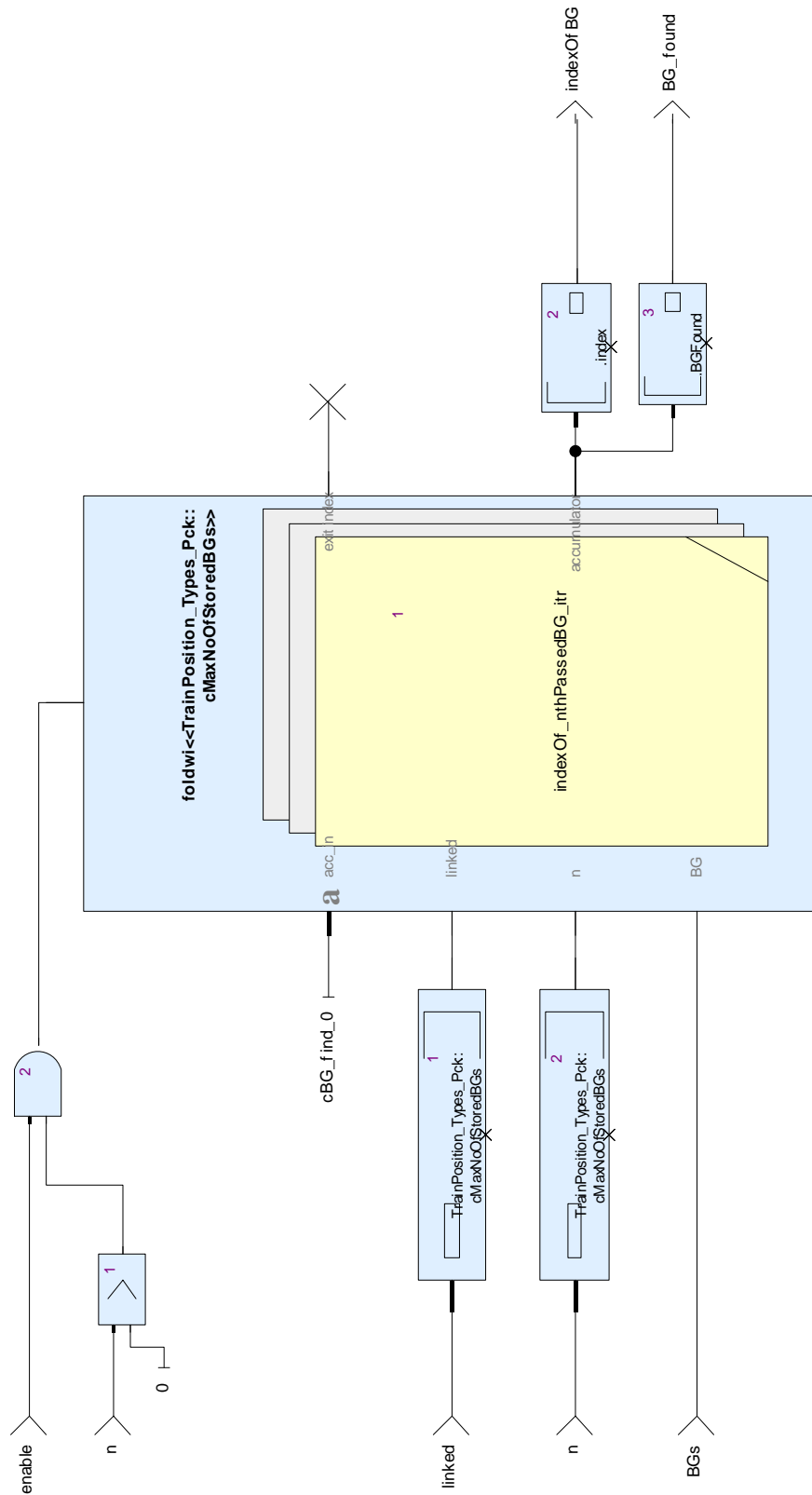


Figure 90: View of diagram_indexOf_nthPassedBG_1 (indexOf_nthPassedBG)

15.3.12. indexOf_nthPassedBG_itr Operator

Declared as **private function**

15.3.12.1. Comments and Information

indexOf_nthPassedBG_itr Comments:

- Iterated function for indexOf_nthPassedBG

Table 232: indexOf_nthPassedBG_itr Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | Version : 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Iterated function for determing the index of BG in BGs</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.12.2. Interface

Table 233: Inputs of indexOf_nthPassedBG_itr

| Name | Type | Comments and Information |
|---------------|---|---|
| iteratorIndex | int | |
| acc_in | CalculateTrainPosition_ Pkg::BG_utilities_Pkg:: BG_find_T | |
| linked | bool | Comments: Condition if the seach is for a linked or unlinked BG. |
| n | int | |
| BG | TrainPosition_Types_Pc k::positionedBG_T | |

Table 234: Outputs of indexOf_nthPassedBG_itr

| Name | Type | Comments and Information |
|---------|---|--------------------------|
| cont | bool | |
| acc_out | CalculateTrainPosition_ Pkg::BG_utilities_Pkg:: BG_find_T | |

15.3.12.3. Operator Hierarchy

diagram : diagram_indexOf_nthPassedBG_itr_1

15.3.12.4. Graphical and Textual Diagrams

15.3.12.4.1. View of diagram_indexOf_nthPassedBG_itr_1 (indexOf_nthPassedBG_itr)

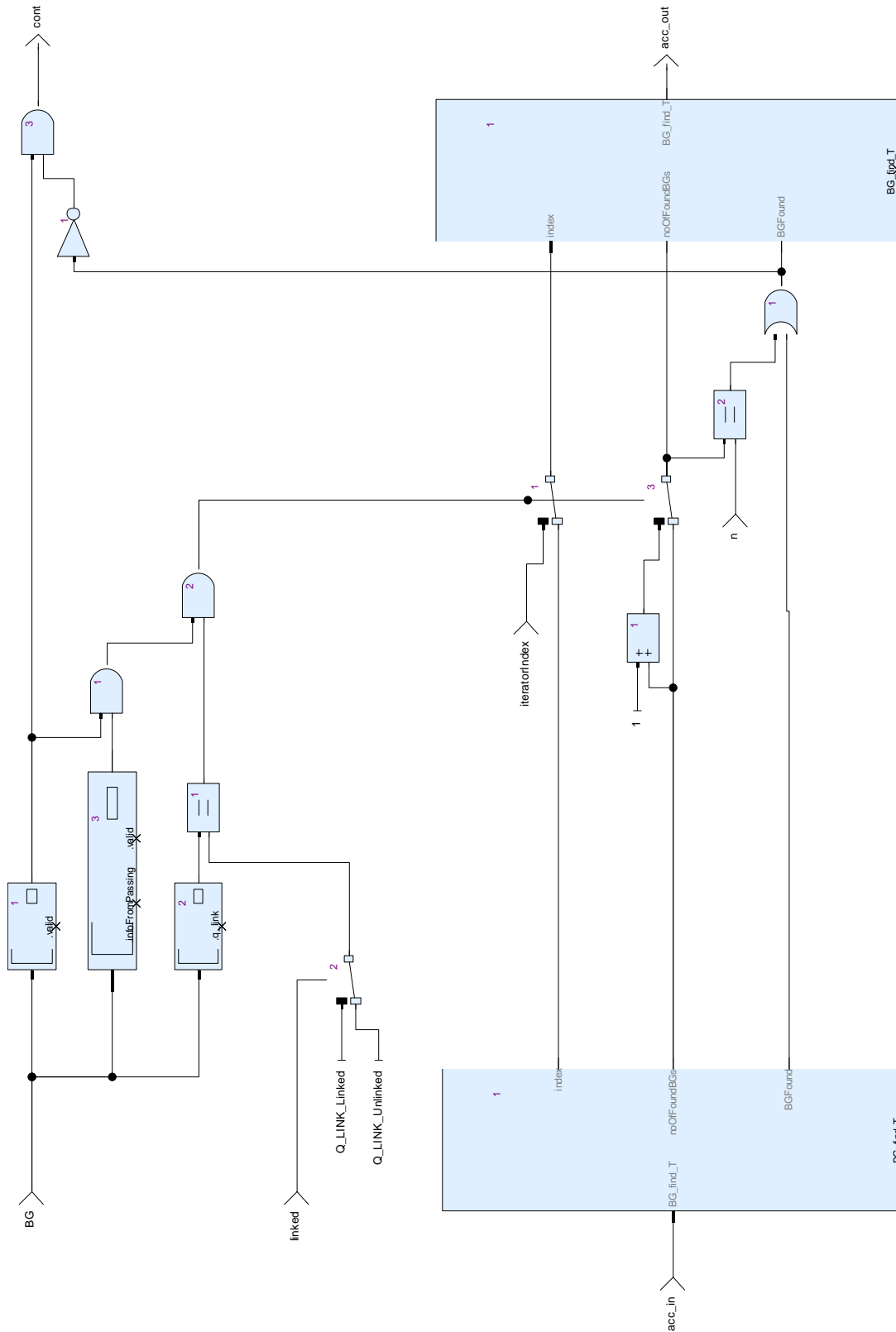


Figure 91: View of diagram_indexOf_nthPassedBG_itr_1 (indexOf_nthPassedBG_itr)

15.3.13. indexOfBG_by_id Operator

Declared as **public function**

15.3.13.1. Comments and Information

indexOfBG_by_id Comments:

- Determines the index of BG in BGs by comparing NID_BG and NID_C.
- If BG is found, the output BG_found is set, otherwise unset.
- If BG is not found, the output indexOfBG is set to a free cell in BGs.
- If BG is not found and no free cell is available in BGs, indexValid is unset.

Table 235: indexOfBG_by_id Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | Version : 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Determines the index of BG in BGs</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.13.2. Interface

Table 236: Inputs of indexOfBG_by_id

| Name | Type | Comments and Information |
|--------|--|--------------------------|
| BG | TrainPosition_Types_Pc k::positionedBG_T | |
| BGs | TrainPosition_Types_Pc k::positionedBGs_T | |
| enable | bool | |

Table 237: Outputs of IndexOfBG_by_id

| Name | Type | Comments and Information |
|-----------|------|--------------------------|
| indexOfBG | int | |

| Name | Type | Comments and Information |
|------------|------|---|
| BG_found | bool | Comments: Indicates, that BG exists in BGs. |
| indexValid | bool | Comments: Indicates, that no valid index could be assigned to BG. Practically, this means that there could no place be assigned to BG in BGs. |

15.3.13.3. Operator Hierarchy

diagram : diagram_indexOfBG_by_id_1

15.3.13.4.1. View of diagram_indexOfBG_by_id_1 (indexOfBG_by_id)

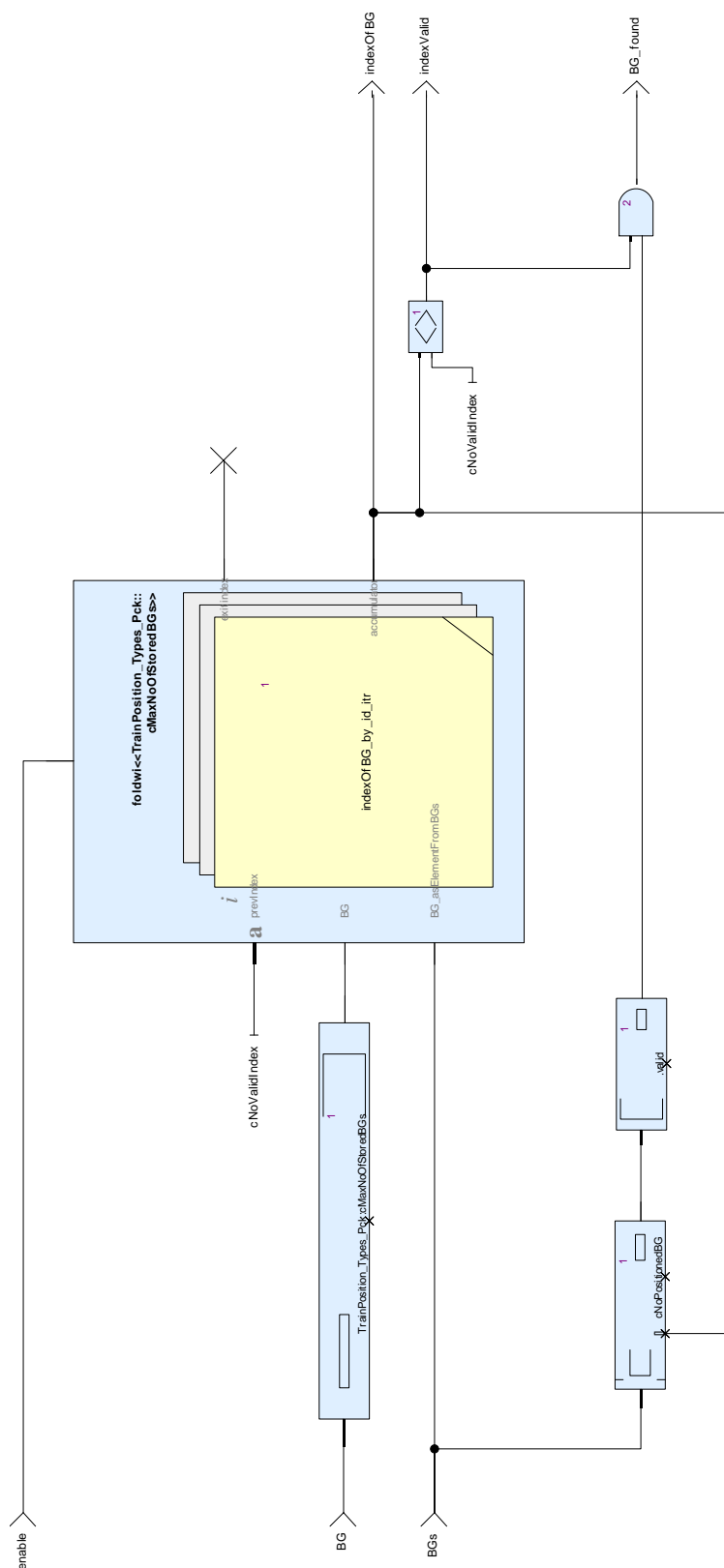


Figure 92: View of diagram_indexOfBG_by_id_1 (indexOfBG_by_id)

15.3.14. indexOfBG_by_id_itr Operator

Declared as **private function**

15.3.14.1. Comments and Information

indexOfBG_by_id_itr Comments:

- Iterated function for determining the index of BG in BGs

Table 238: indexOfBG_by_id_itr Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | Version : 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Iterated function for determining the index of BG in BGs</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.14.2. Interface

Table 239: Inputs of indexOfBG_by_id_itr

| Name | Type | Comments and Information |
|---------------------|---|--------------------------|
| iteratorIndex | int | |
| prevIndex | int | |
| BG | TrainPosition_Types_Pck::positionedBG_T | |
| BG_asElementFromBGs | TrainPosition_Types_Pck::positionedBG_T | |

Table 240: Outputs of indexOfBG_by_id_itr

| Name | Type | Comments and Information |
|-----------|------|--------------------------|
| cont | bool | |
| indexOfBG | int | |

15.3.14.3. Operator Hierarchy

diagram : diagram_indexOfBG_by_id_itr_1

15.3.14.4.1. View of diagram_indexOfBG_by_id_itr_1 (indexOfBG_by_id_itr)

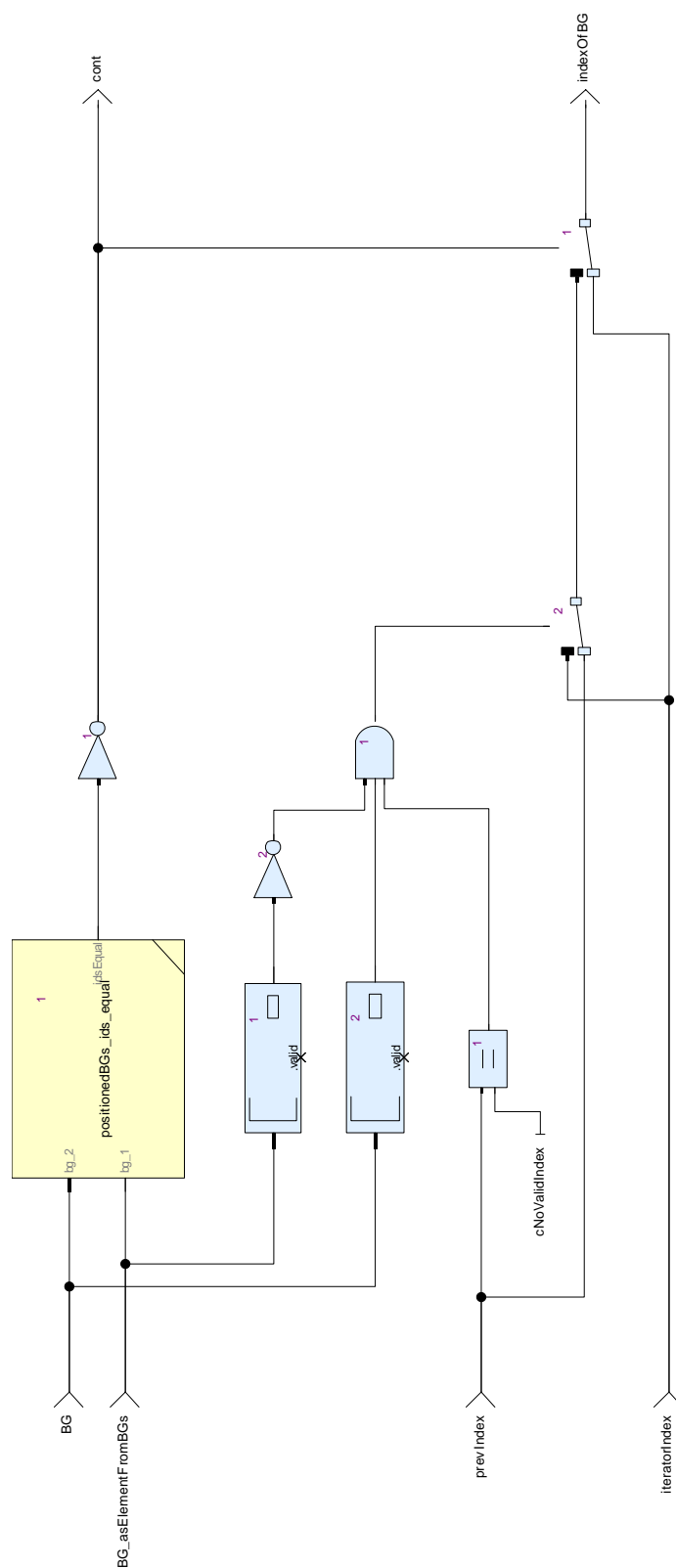


Figure 93: View of diagram_indexOfBG_by_id_itr_1 (indexOfBG_by_id_itr)

15.3.15. indexOfBG_onTrack Operator

Declared as **public function**

15.3.15.1. Comments and Information

indexOfBG_onTrack Comments:

- Determines the must index of BG in BGs.
- If BG is a passed BG, the index is determined by the order of the sequence no (seqNoOnTrack).
- If BG is an announced (linked) BG (not yet passed), the index is determined by the expected nominal location.
- If BG already exists in BGs at that index, BG_found is set, otherwise unset.
- If no index can be assigned, indexValid is unset.
- Note:
- indexOfBG may point to a cell in BGs already occupied by a different BG.
- It is not checked, if BG is already stored in BGs at a different index.

Table 241: indexOfBG_onTrack Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | Version : 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Determines the index of BG in BGs - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke</p> <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.15.2. Interface

Table 242: Inputs of indexOfBG_onTrack

| Name | Type | Comments and Information |
|------|--|--------------------------|
| BG | TrainPosition_Types_Pc k::positionedBG_T | |
| BGs | TrainPosition_Types_Pc k::positionedBGs_T | |

| Name | Type | Comments and Information |
|--------|------|--------------------------|
| enable | bool | |

Table 243: Outputs of indexOfBG_onTrack

| Name | Type | Comments and Information |
|------------|------|--|
| indexOfBG | int | |
| BG_found | bool | Comments: Indicates, that BG exists in BGs. |
| indexValid | bool | Comments: Indicates, that no valid index could be assigned to BG. Practically, this means that no cell could be assigned to BG in BGs. |

15.3.15.3. Operator Hierarchy

diagram : diagram_indexOfBG_onTrack_1

15.3.15.4. Graphical and Textual Diagrams

15.3.15.4.1. View of diagram_indexOfBG_onTrack_1 (indexOfBG_onTrack)

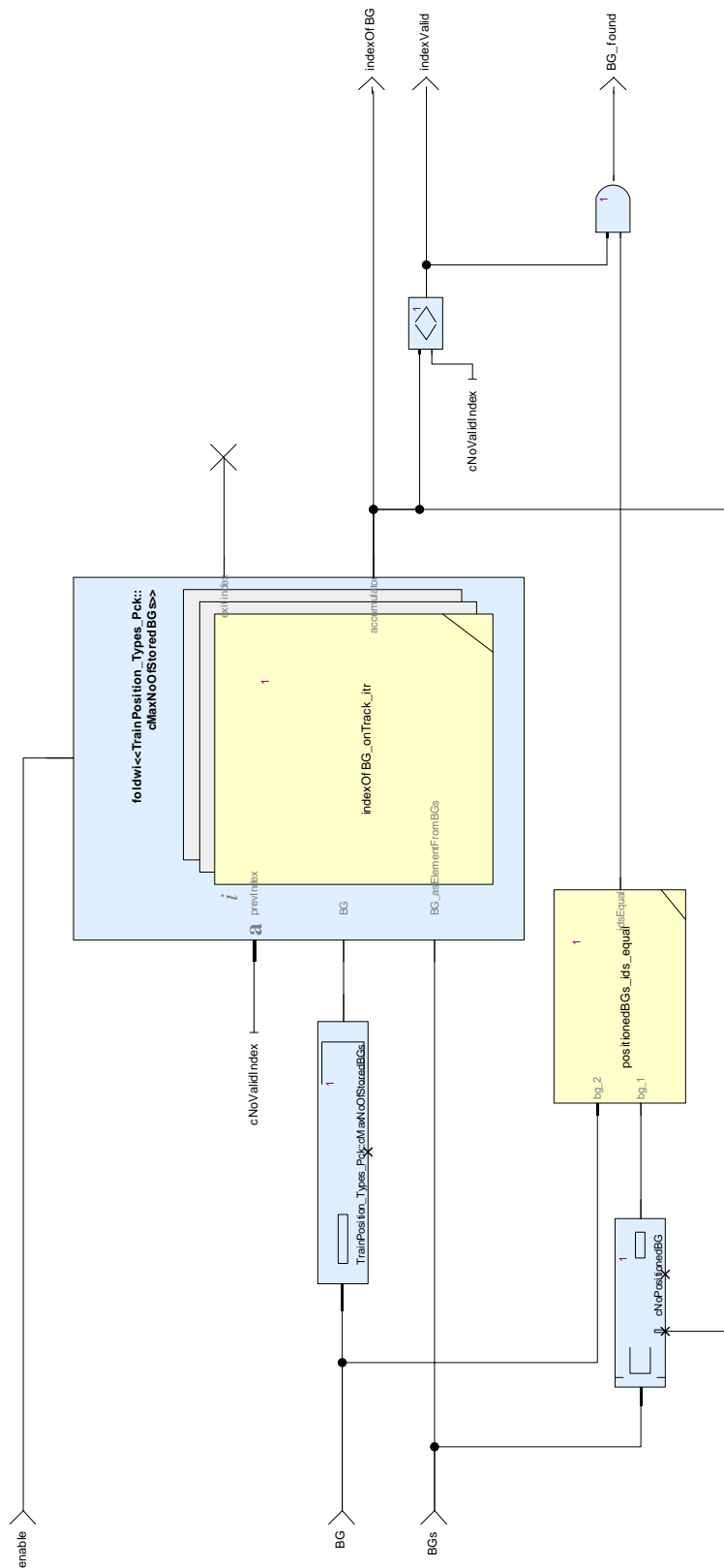


Figure 94: View of diagram_indexOfBG_onTrack_1 (indexOfBG_onTrack)

15.3.16. indexOfBG_onTrack_itr Operator

Declared as **private function**

15.3.16.1. Comments and Information

indexOfBG_onTrack_itr Comments:

- Iterated function for determining the index of BG in BGs

Table 244: indexOfBG_onTrack_itr Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | Version : 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Iterated function for determining the index of BG in BGs</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.16.2. Interface

Table 245: Inputs of indexOfBG_onTrack_itr

| Name | Type | Comments and Information |
|---------------------|---|--------------------------|
| iteratorIndex | int | |
| prevIndex | int | |
| BG | TrainPosition_Types_Pck::positionedBG_T | |
| BG_asElementFromBGs | TrainPosition_Types_Pck::positionedBG_T | |

Table 246: Outputs of indexOfBG_onTrack_itr

| Name | Type | Comments and Information |
|-----------|------|--------------------------|
| cont | bool | |
| indexOfBG | int | |

15.3.16.3. Locals

Table 247: Locals of indexOfBG_onTrack_itr

| Name | Type | Comments and Information |
|-----------------|------|--------------------------|
| invalidateIndex | bool | |
| stopIteration | bool | |

15.3.16.4. Operator Hierarchy

diagram : diagram_setIndex

diagram : diagram_stopIteration

15.3.16.5.1. View of diagram_setIndex (indexOfBG_onTrack_itr)

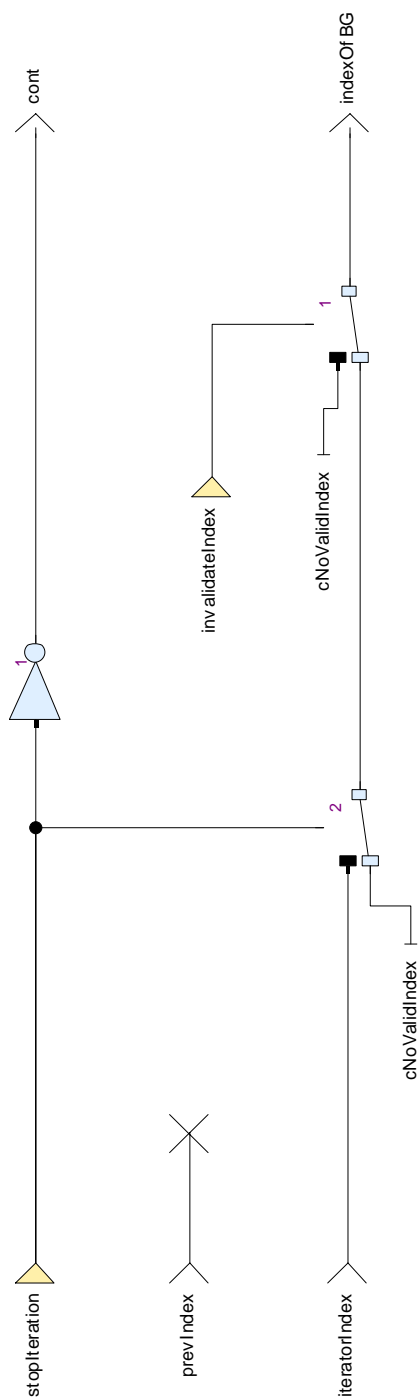


Figure 95: View of diagram_setIndex (indexOfBG_onTrack_itr)

Declared as **public function**

15.3.17.1. Comments and Information

indexOfLastPassedBG Comments:

- Determines the index of the last (most ahead) linked or unlinked passed BG in BGs.

15.3.17.2. Interface

Table 248: Inputs of indexOfLastPassedBG

| Name | Type | Comments and Information |
|--------|--|---|
| linked | bool | Comments: Condition if the seach is for a linked or unlinked BG. |
| BGs | TrainPosition_Types_Pc k::positionedBGs_T | |
| enable | bool | |

Table 249: Outputs of indexOfLastPassedBG

| Name | Type | Comments and Information |
|------------|------|---|
| indexOfBG | int | |
| BG_found | bool | Comments: Indicates, that BG exists in BGs. |
| indexValid | bool | Comments: Indicates, that a valid index was found. |

15.3.17.3. Operator Hierarchy

diagram : diagram_indexOfLastPassedBG_1

15.3.17.4.1. View of diagram_indexOfLastPassedBG_1 (indexOfLastPassedBG)

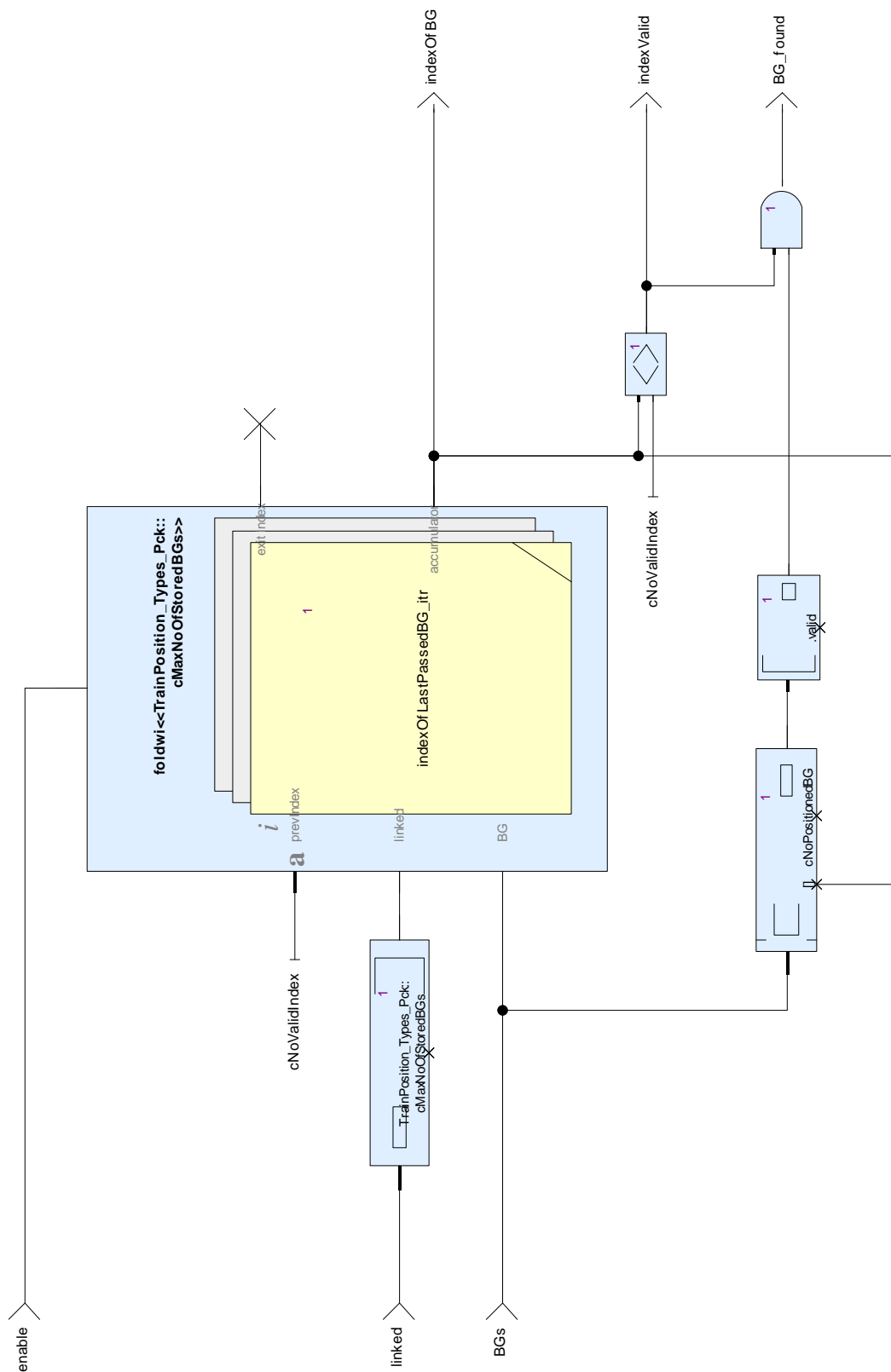


Figure 97: View of diagram_indexOfLastPassedBG_1 (indexOfLastPassedBG)

15.3.18. indexOfLastPassedBG_itr Operator

Declared as **private function**

15.3.18.1. Comments and Information

indexOfLastPassedBG_itr Comments:

- Iterated function for indexOfLastPassedBG

Table 250: indexOfLastPassedBG_itr Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | Version : 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Iterated function for determing the index of BG in BGs</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.18.2. Interface

Table 251: Inputs of indexOfLastPassedBG_itr

| Name | Type | Comments and Information |
|---------------|---|---|
| iteratorIndex | int | |
| prevIndex | int | |
| linked | bool | Comments: Condition if the seach is for a linked or unlinked BG. |
| BG | TrainPosition_Types_Pc k::positionedBG_T | |

Table 252: Outputs of indexOfLastPassedBG_itr

| Name | Type | Comments and Information |
|------|------|--------------------------|
| cont | bool | |

| Name | Type | Comments and Information |
|-----------|------|--------------------------|
| indexOfBG | int | |

15.3.18.3. Operator Hierarchy

diagram : diagram_indexOfLastPassedBG_itr_1

15.3.18.4. Graphical and Textual Diagrams

15.3.18.4.1. View of diagram_indexOfLastPassedBG_itr_1 (indexOfLastPassedBG_itr)

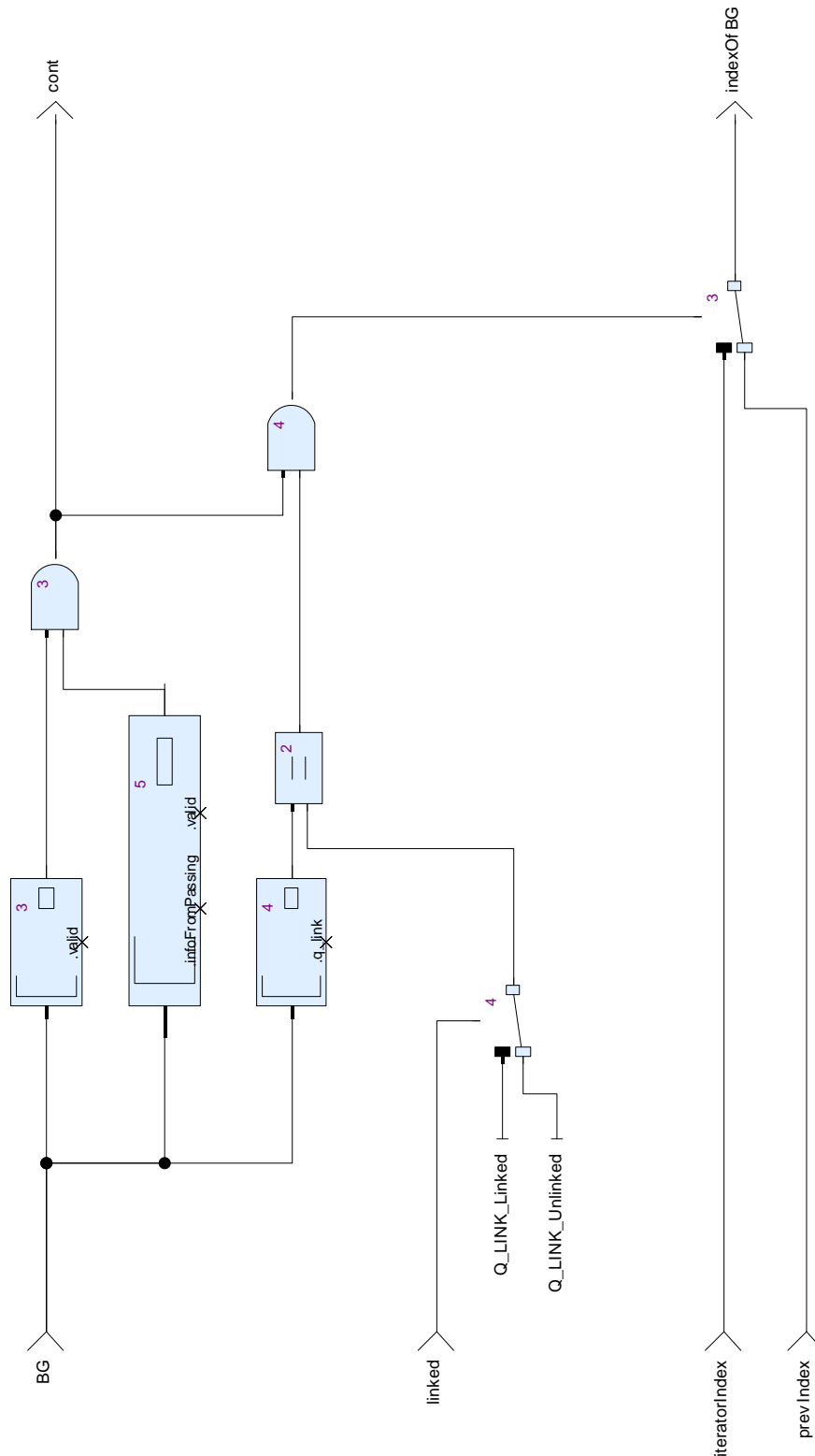


Figure 98: View of diagram_indexOfLastPassedBG_itr_1 (indexOfLastPassedBG_itr)

15.3.19. indexOfPassedBG_by_id Operator

Declared as **public function**

15.3.19.1. Comments and Information

indexOfPassedBG_by_id Comments:

- Determines the index of a passed BG in BGs by comparing NID_BG and NID_C.

Table 253: indexOfPassedBG_by_id Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Determines the index of a passed BG in BGs</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.19.2. Interface

Table 254: Inputs of indexOfPassedBG_by_id

| Name | Type | Comments and Information |
|--------|--|--------------------------|
| BG | BG_Types_Pkg::passedBG_T | |
| BGs | TrainPosition_Types_Pkg::positionedBGs_T | |
| enable | bool | |

Table 255: Outputs of indexOfPassedBG_by_id

| Name | Type | Comments and Information |
|------------|------|---|
| indexOfBG | int | |
| BG_found | bool | Comments: Indicates, that BG exists in BGs. |
| indexValid | bool | Comments: Indicates, that no valid index could be assigned to BG. Practically, this means that there could no place be assigned to BG in BGs. |

15.3.19.3. Operator Hierarchy

diagram : diagram_indexOfPassedBG_by_id_1

15.3.19.4. Graphical and Textual Diagrams

15.3.19.4.1. View of diagram_indexOfPassedBG_by_id_1 (indexOfPassedBG_by_id)

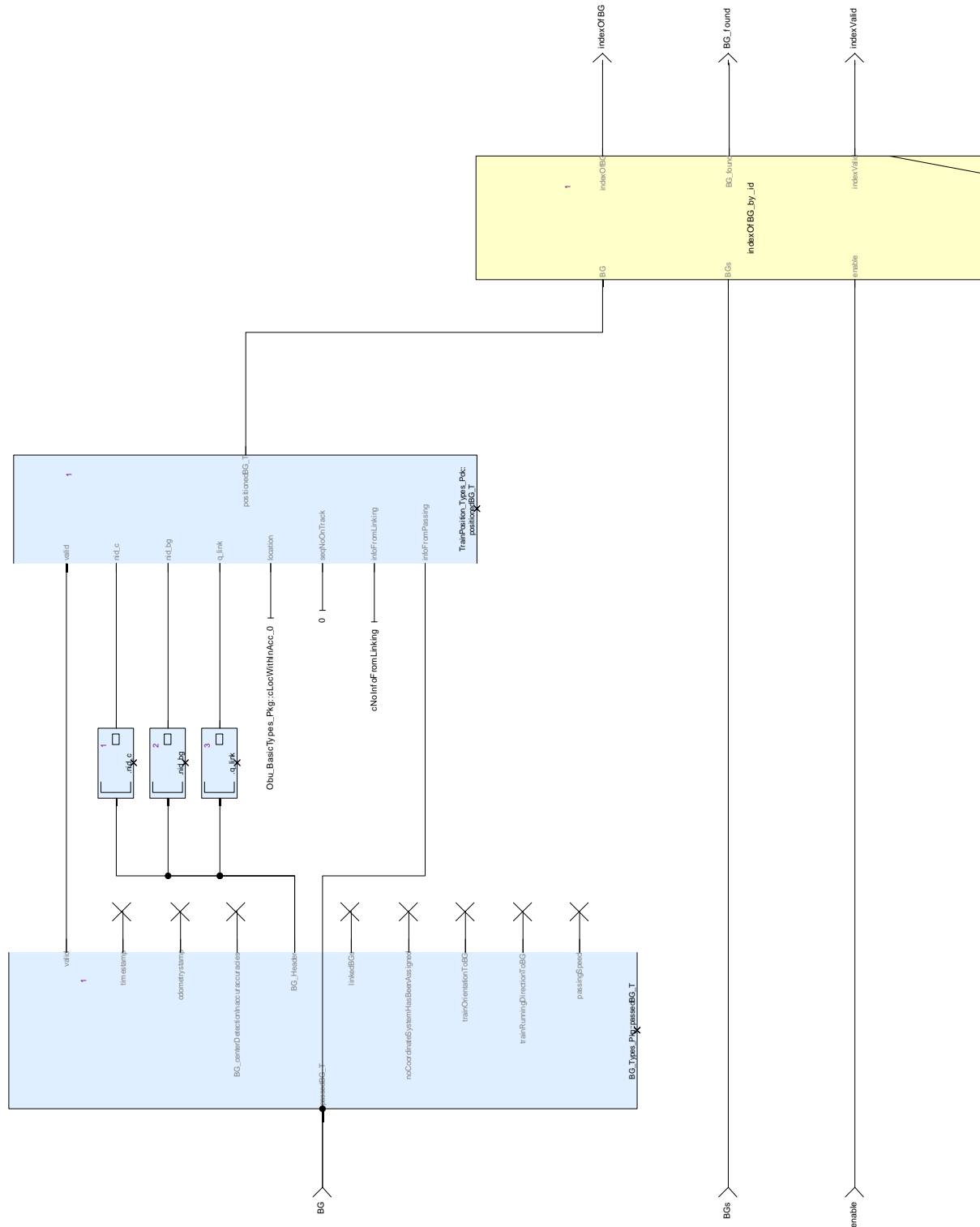


Figure 99: View of diagram_indexOfPassedBG_by_id_1 (indexOfPassedBG_by_id)

15.3.20. insertBG_atIndex Operator

Declared as **public function**

15.3.20.1. Comments and Information

insertBG_atIndex Comments:

- Inserts BG in BGs_in at the cell given by indexOfBG.
- The BGs above BG are shifted upwards by 1.
- If a BG with the same ID already exists in BGs at the same cell, BG will replace it.
- If there is no space in BGs_in for the insertion, overrun will be set and no insertion performed.

15.3.20.2. Interface

Table 256: Inputs of insertBG_atIndex

| Name | Type | Comments and Information |
|-----------|--|--|
| BG | TrainPosition_Types_Pc k::positionedBG_T | |
| BGs_in | TrainPosition_Types_Pc k::positionedBGs_T | |
| indexOfBG | int | |
| insert | bool | Comments: insert comand. Must be true to execute the insertion. |

Table 257: Outputs of insertBG_atIndex

| Name | Type | Comments and Information |
|---------|--|---|
| BGs_out | TrainPosition_Types_Pc k::positionedBGs_T | |
| overrun | bool | Comments: Indicates, that no merge took place due to no space in BGs_in. |

15.3.20.3. Operator Hierarchy

diagram : diagram_insertBG_atIndex_1

15.3.20.4. Graphical and Textual Diagrams

15.3.20.4.1. View of diagram_insertBG_atIndex_1 (insertBG_atIndex)

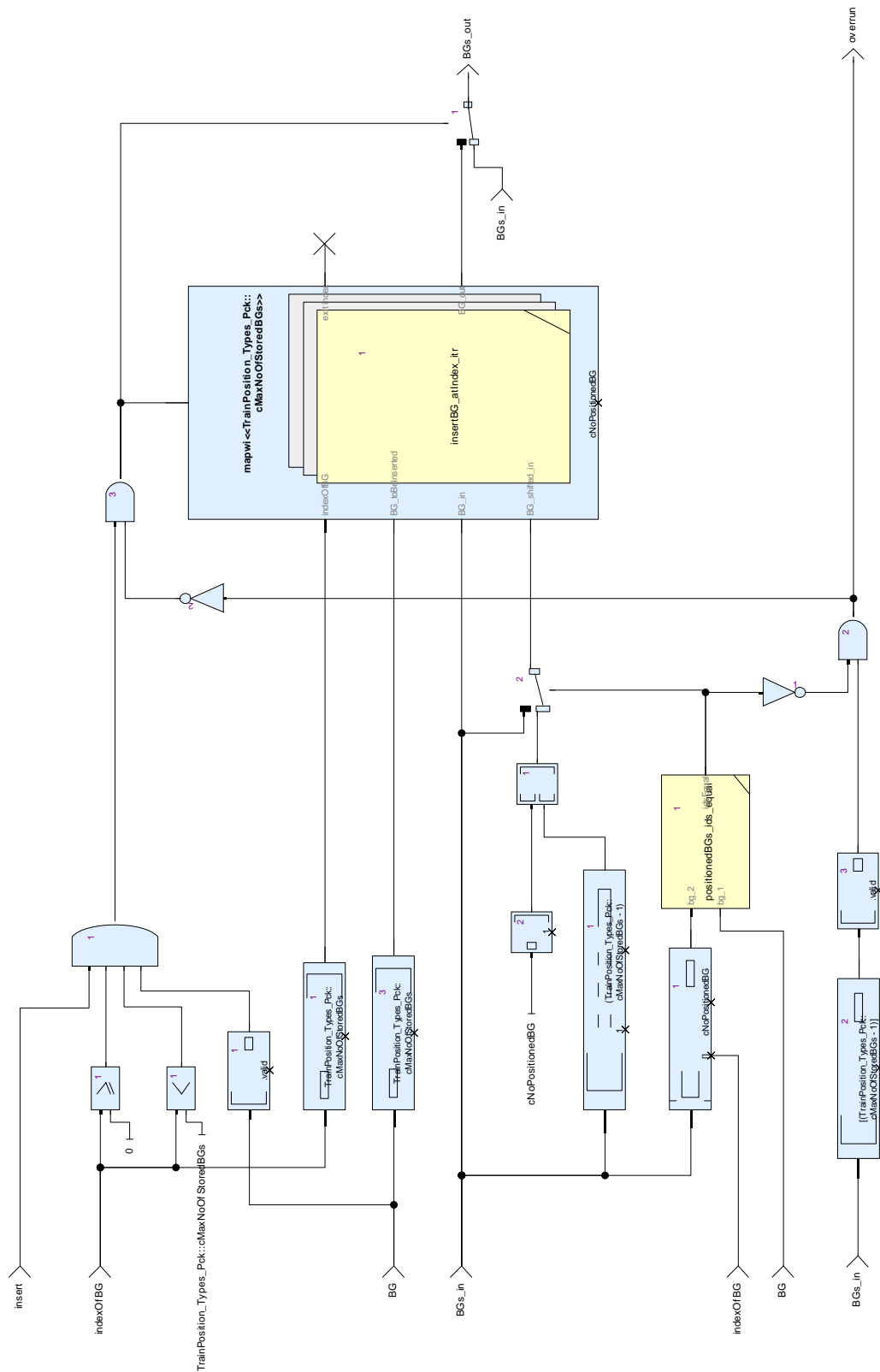


Figure 100: View of diagram_insertBG_atIndex_1 (insertBG_atIndex)

15.3.21. insertBG_atIndex_itr Operator

Declared as **private function**

15.3.21.1. Comments and Information

insertBG_atIndex_itr Comments:

- Iterated function for insertBG_atIndex.

15.3.21.2. Interface

Table 258: Inputs of insertBG_atIndex_itr

| Name | Type | Comments and Information |
|-----------------|---|--------------------------|
| iteratorIndex | int | |
| indexOfBG | int | |
| BG_toBeInserted | TrainPosition_Types_Pc k::positionedBG_T | |
| BG_in | TrainPosition_Types_Pc k::positionedBG_T | |
| BG_shifted_in | TrainPosition_Types_Pc k::positionedBG_T | |

Table 259: Outputs of insertBG_atIndex_itr

| Name | Type | Comments and Information |
|--------|---|--------------------------|
| cont | bool | |
| BG_out | TrainPosition_Types_Pc k::positionedBG_T | |

15.3.21.3. Operator Hierarchy

diagram : diagram_insertBG_atIndex_itr_1

```
activate if : IfBlock1
  branch : then
  branch : else
    branch : then
    branch : else
```

15.3.21.4. Graphical and Textual Diagrams

15.3.21.4.1. View of diagram_insertBG_atIndex_itr_1 (insertBG_atIndex_itr)

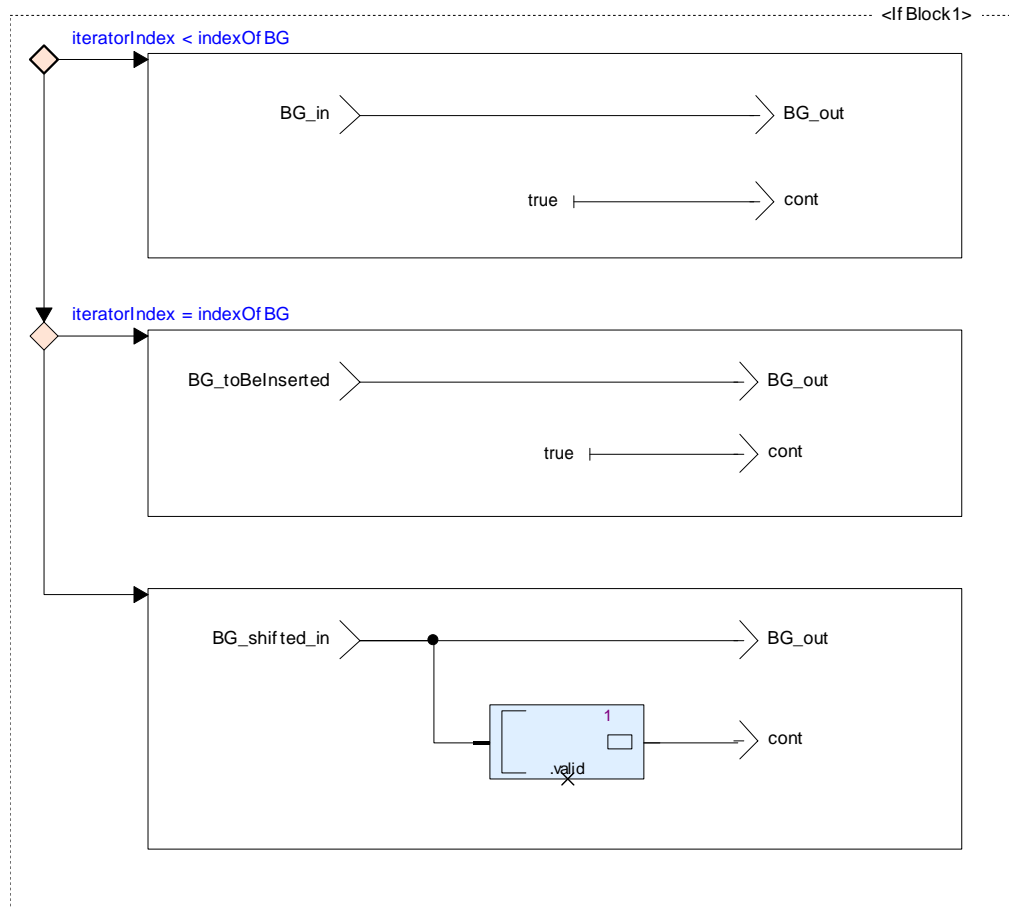


Figure 101: View of diagram_insertBG_atIndex_itr_1 (insertBG_atIndex_itr)

Table 260: Conditional Blocks of diagram_insertBG_atIndex_itr_1

| Conditional Block | Comments and Information |
|-------------------|--------------------------|
| IfBlock1 | |

Table 261: Actions of diagram_insertBG_atIndex_itr_1

| Conditional Block Action | Comments and Information |
|--------------------------|--------------------------|
| IfBlock1: then | |
| IfBlock1: else: then | |
| IfBlock1: else: else | |

15.3.22. mergeBG_by_id Operator

Declared as **private function**

15.3.22.1. Comments and Information

mergeBG_by_id Comments:

- Merges a BG into an array of BGs.
- If an element in BGs exists in BGs with the same ID as BG, the element in BGs will be replaced by BG.

Table 262: mergeBG_by_id Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Merges a BG into an array of BGs</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.22.2. Interface

Table 263: Inputs of mergeBG_by_id

| Name | Type | Comments and Information |
|--------|--|---|
| BG | TrainPosition_Types_Pck::positionedBG_T | Comments: The BG to be merged. |
| BGs_in | TrainPosition_Types_Pck::positionedBGs_T | Comments: The BGs where BG is to be merged with. |

Table 264: Outputs of mergeBG_by_id

| Name | Type | Comments and Information |
|---------|--|---|
| BGs_out | TrainPosition_Types_Pck::positionedBGs_T | Comments: The resulting array of merged BGs. |
| overrun | bool | Comments: Indicates, that no merge took place due to no space in BGs_in. |

15.3.22.3. Operator Hierarchy

diagram : diagram_mergeBG_by_id_1

15.3.22.4. Graphical and Textual Diagrams

15.3.22.4.1. View of diagram_mergeBG_by_id_1 (mergeBG_by_id)

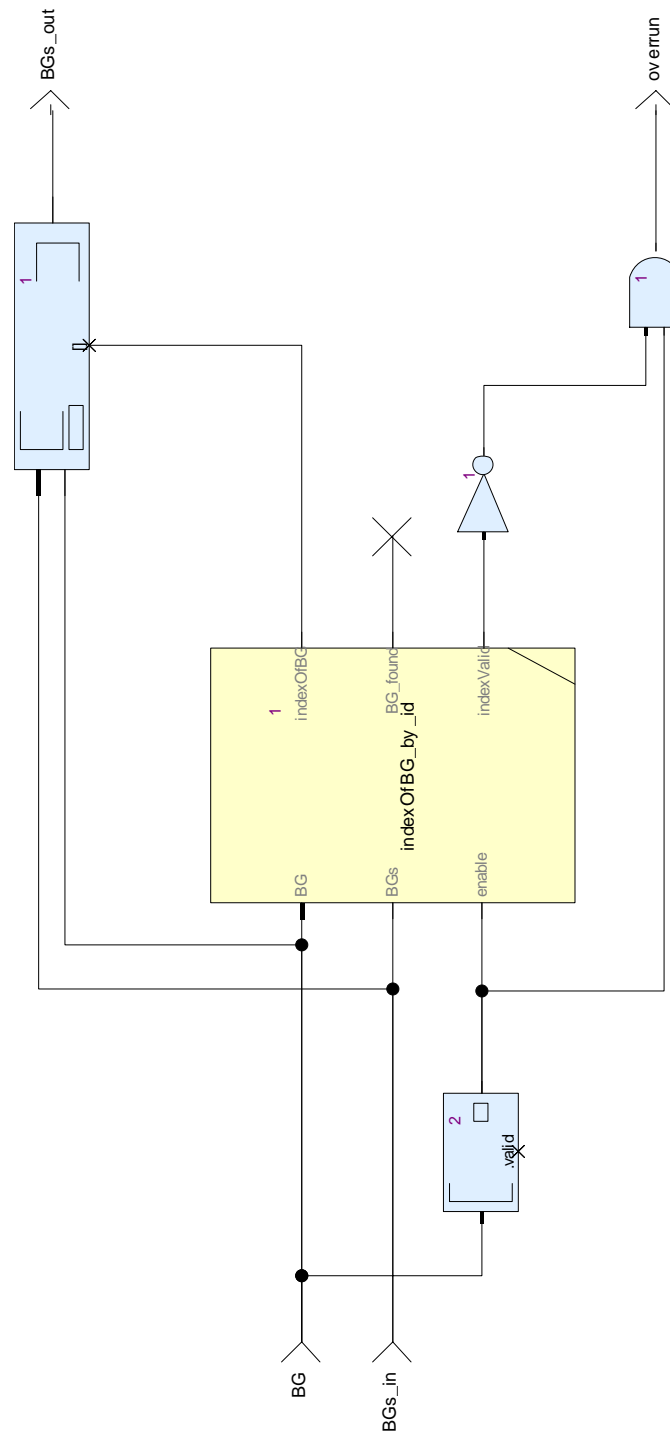


Figure 102: View of diagram_mergeBG_by_id_1 (mergeBG_by_id)

15.3.23. mergeBG_onTrack Operator

Declared as **public function**

15.3.23.1. Comments and Information

mergeBG_onTrack Comments:

- Inserts BG into the collection of BGs.
- If BG has been passed already, it will be sorted by its seqNoOnTrack within all other passed BGs.
- If the passed BG was an announced BG in BGs before, it will replace this announced BG, if necessary on a different position in BGs.
- If BG is an announced BG, it will be sorted by its nominal location within all other announced BGs.
- BGs_in and BGs_out comprise all passed BGs followed by all announced BGs.

15.3.23.2. Interface

Table 265: Inputs of mergeBG_onTrack

| Name | Type | Comments and Information |
|--------|--|---|
| BG | TrainPosition_Types_Pc k::positionedBG_T | Comments: The BG to be merged. |
| BGs_in | TrainPosition_Types_Pc k::positionedBGs_T | Comments: The BGs where BG is to be merged with. |

Table 266: Outputs of mergeBG_onTrack

| Name | Type | Comments and Information |
|---------|--|---|
| BGs_out | TrainPosition_Types_Pc k::positionedBGs_T | Comments: The resulting array of merged BGs. |
| overrun | bool | Comments: Indicates, that no merge took place due to no space in BGs_in. |

15.3.23.3. Operator Hierarchy

diagram : diagram_mergeBG_onTrack_1

15.3.23.4. Graphical and Textual Diagrams

15.3.23.4.1. View of diagram_mergeBG_onTrack_1 (mergeBG_onTrack)

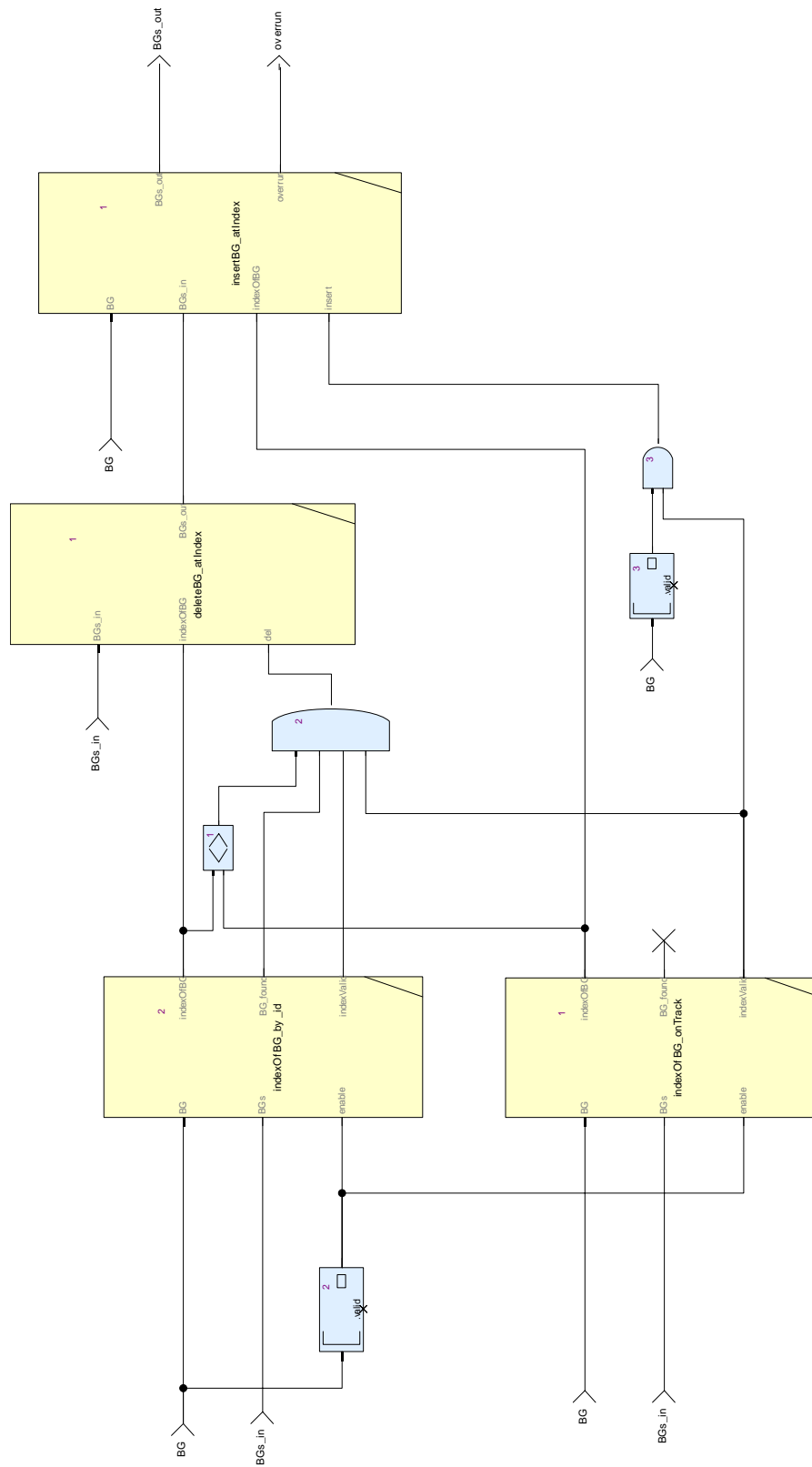


Figure 103: View of diagram_mergeBG_onTrack_1 (mergeBG_onTrack)

15.3.24. mergeBGs_by_id Operator

Declared as **public function**

15.3.24.1. Comments and Information

mergeBGs_by_id Comments:

- Merges two arrays of BGs by id.
- If a BG with the same id exists in BGs_1 and BGs_2, the BG from BGs_2 will override the element in BGs_1.
- Otherwise, the valid elements of BGs_2 will be stored in empty slices of BGs_1.
- Overrun indicates not enough space for merging.

Table 267: mergeBGs_by_id Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Merges two arrays of BGs by id.</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.24.2. Interface

Table 268: Inputs of mergeBGs_by_id

| Name | Type | Comments and Information |
|-------|--|--|
| BGs_1 | TrainPosition_Types_Pck::positionedBGs_T | Comments: The first array of BGs to be merged. |
| BGs_2 | TrainPosition_Types_Pck::positionedBGs_T | Comments: The second array of BGs to be merged. |

Table 269: Outputs of mergeBGs_by_id

| Name | Type | Comments and Information |
|---------|--|---|
| BGs_out | TrainPosition_Types_Pc k::positionedBGs_T | Comments: The resulting array of merged BGs. |
| overrun | bool | Comments: Indicates, that not all of the elements of BGs_2 could be merged into BGs_out, due to not enough space in BGs_out. |

15.3.24.3. Operator Hierarchy

diagram : diagram_mergeBGs_by_id_1

15.3.24.4. Graphical and Textual Diagrams

15.3.24.4.1. View of diagram_mergeBGs_by_id_1 (mergeBGs_by_id)

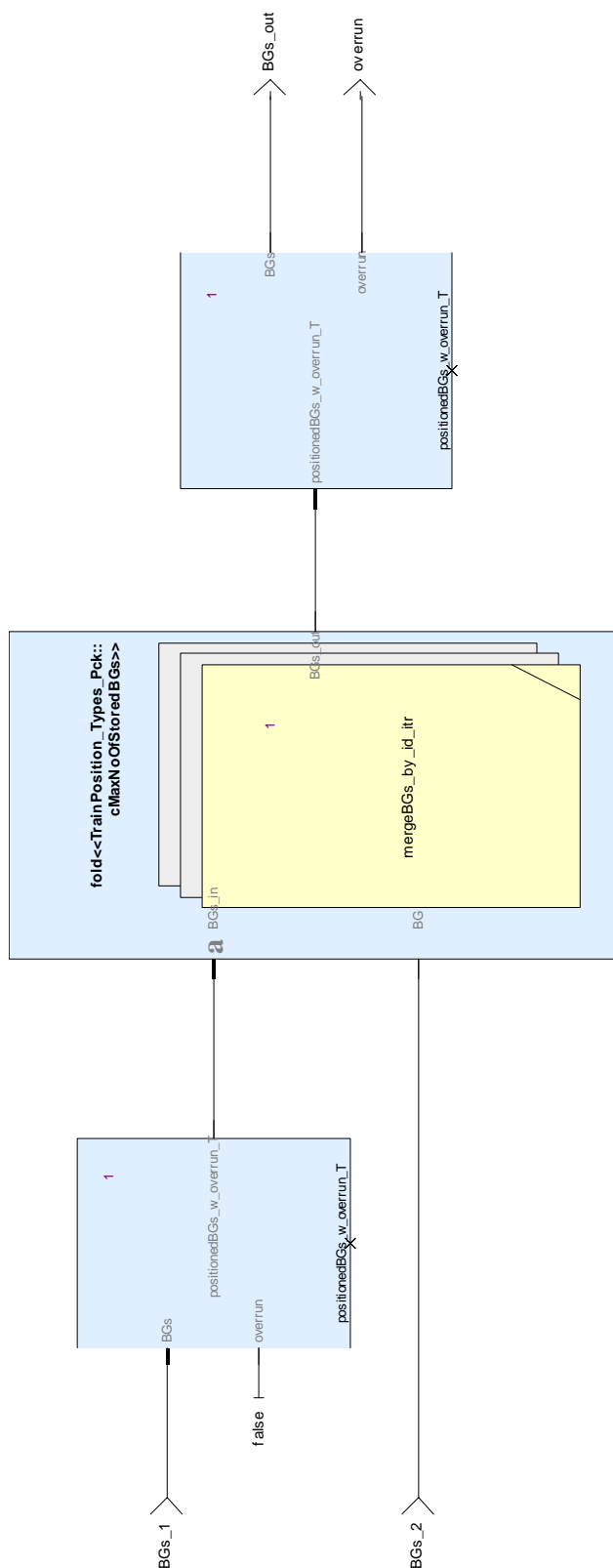


Figure 104: View of diagram_mergeBGs_by_id_1 (mergeBGs_by_id)

15.3.25. mergeBGs_by_id_itr Operator

Declared as **private function**

15.3.25.1. Comments and Information

mergeBGs_by_id_itr Comments:

- Iterated function for the merge of a BG into an array of BGs.

Table 270: mergeBGs_by_id_itr Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Iterated function for the merge of a BG into an array of BGs.</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.25.2. Interface

Table 271: Inputs of mergeBGs_by_id_itr

| Name | Type | Comments and Information |
|--------|---|---|
| BGs_in | CalculateTrainPosition_Pkg::positionedBGs_w_ _overrun_T | Comments: The BGs where BG is to be merged with. |
| BG | TrainPosition_Types_Pkg::positionedBG_T | Comments: The BG to be merged. |

Table 272: Outputs of mergeBGs_by_id_itr

| Name | Type | Comments and Information |
|---------|---|---|
| BGs_out | CalculateTrainPosition_Pkg::positionedBGs_w_ _overrun_T | Comments: The resulting array of merged BGs. |

15.3.25.3. Operator Hierarchy

diagram : diagram_mergeBGs_by_id_itr_1

15.3.25.4. Graphical and Textual Diagrams

15.3.25.4.1. View of diagram_mergeBGs_by_id_itr_1 (mergeBGs_by_id_itr)

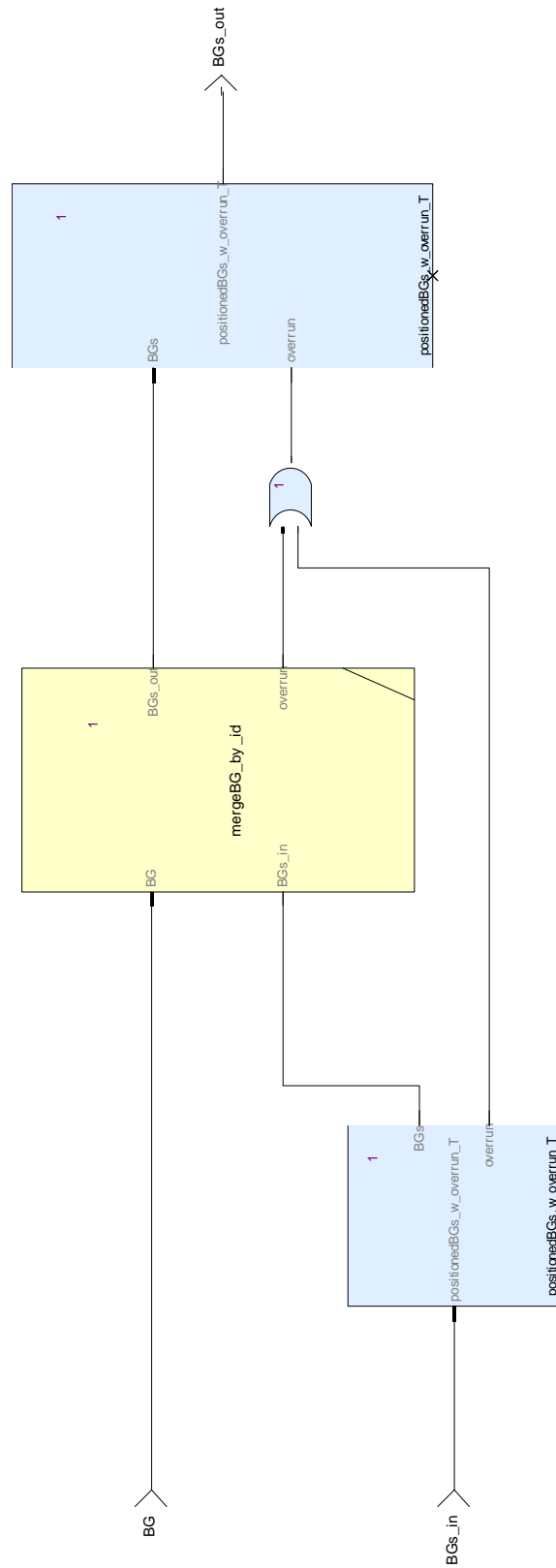


Figure 105: View of diagram_mergeBGs_by_id_itr_1 (mergeBGs_by_id_itr)

15.3.26. mergeBGs_onTrack Operator

Declared as **public function**

15.3.26.1. Comments and Information

mergeBGs_onTrack Comments:

- Merges two arrays of BGs and sorting their sequence by seqNoOnTrack (passed BGs) and nominal location announced BGs)
- If a BG with the same id exists in BGs_1 and BGs_2, the BG from BGs_2 will override the element in BGs_1.
- Otherwise, the valid elements of BGs_2 will be stored in empty slices of BGs_1.
- Overrun indicates not enough space for merging.

Table 273: mergeBGs_onTrack Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Merges two arrays of BGs by id.</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.26.2. Interface

Table 274: Inputs of mergeBGs_onTrack

| Name | Type | Comments and Information |
|-------|--|--|
| BGs_1 | TrainPosition_Types_Pc k::positionedBGs_T | Comments: The first array of BGs to be merged. |
| BGs_2 | TrainPosition_Types_Pc k::positionedBGs_T | Comments: The second array of BGs to be merged. |

Table 275: Outputs of mergeBGs_onTrack

| Name | Type | Comments and Information |
|---------|--|---|
| BGs_out | TrainPosition_Types_Pc k::positionedBGs_T | Comments: The resulting array of merged BGs. |
| overrun | bool | Comments: Indicates, that not all of the elements of BGs_2 could be merged into BGs_out, due to not enough space in BGs_out. |

15.3.26.3. Operator Hierarchy

diagram : diagram_mergeBGs_onTrack_1

15.3.26.4. Graphical and Textual Diagrams

15.3.26.4.1. View of diagram_mergeBGs_onTrack_1 (mergeBGs_onTrack)

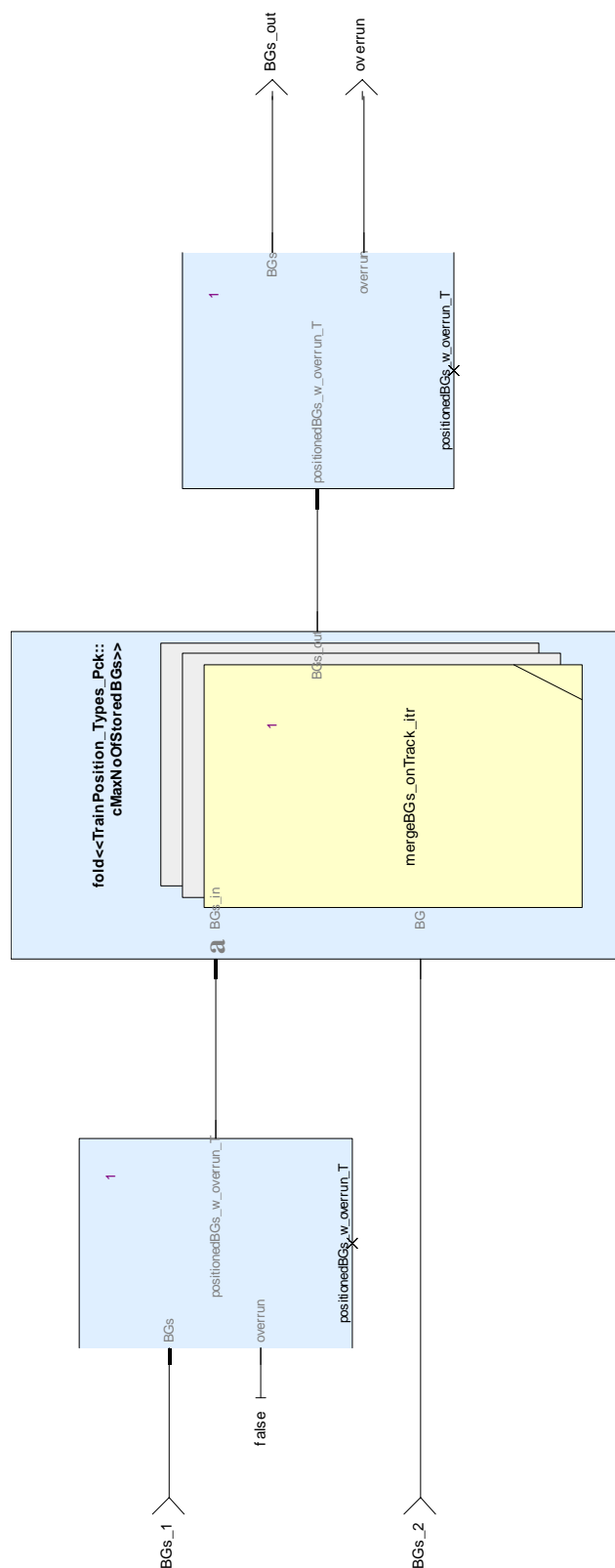


Figure 106: View of diagram_mergeBGs_onTrack_1 (mergeBGs_onTrack)

15.3.27. mergeBGs_onTrack_itr Operator

Declared as **private function**

15.3.27.1. Comments and Information

mergeBGs_onTrack_itr Comments:

- Iterated function for the merge of a BG into a sorted array of BGs.

Table 276: mergeBGs_onTrack_itr Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Iterated function for the merge of a BG into an array of BGs.</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.27.2. Interface

Table 277: Inputs of mergeBGs_onTrack_itr

| Name | Type | Comments and Information |
|--------|---|---|
| BGs_in | CalculateTrainPosition_ Pkg::positionedBGs_w _overrun_T | Comments: The BGs where BG is to be merged with. |
| BG | TrainPosition_Types_Pc k::positionedBG_T | Comments: The BG to be merged. |

Table 278: Outputs of mergeBGs_onTrack_itr

| Name | Type | Comments and Information |
|---------|---|---|
| BGs_out | CalculateTrainPosition_ Pkg::positionedBGs_w _overrun_T | Comments: The resulting array of merged BGs. |

15.3.27.3. Operator Hierarchy

diagram : diagram_mergeBGs_onTrack_itr_1

15.3.27.4. Graphical and Textual Diagrams

15.3.27.4.1. View of diagram_mergeBGs_onTrack_itr_1 (mergeBGs_onTrack_itr)

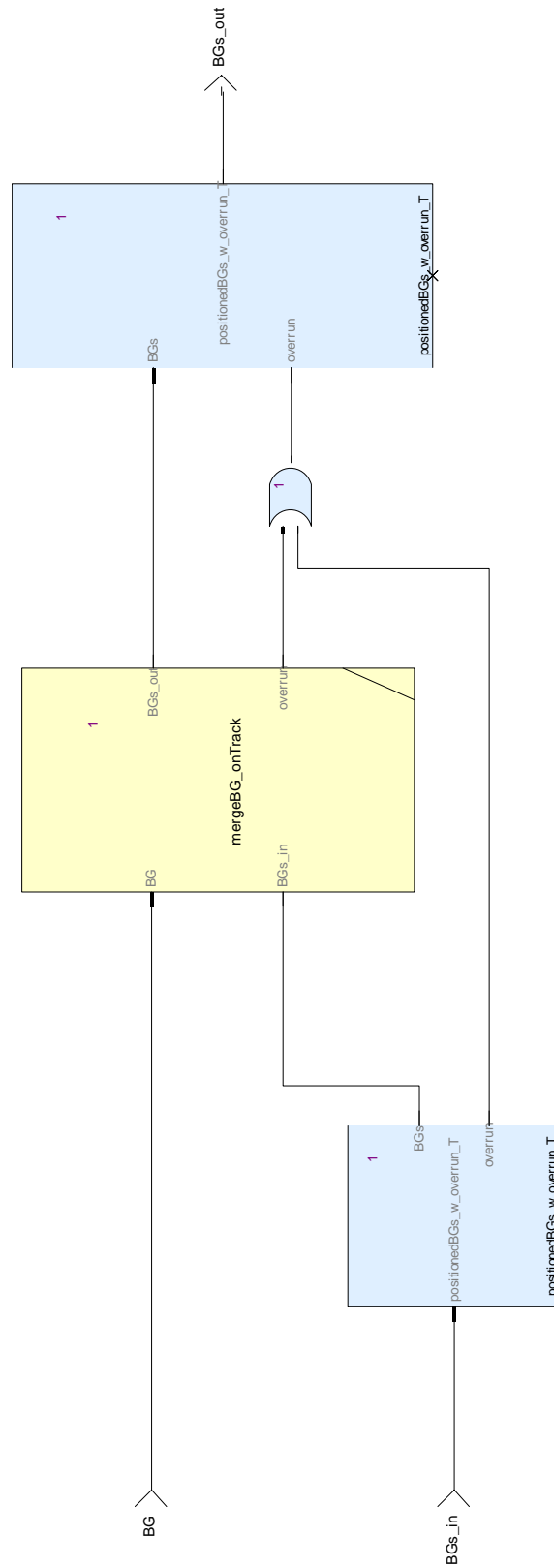


Figure 107: View of diagram_mergeBGs_onTrack_itr_1 (mergeBGs_onTrack_itr)

15.3.28. nidBG_nidc_equal Operator

Declared as **public function**

15.3.28.1. Comments and Information

nidBG_nidc_equal Comments:

- Checks if the ids of 2 BG are equal by comparing their NID_BG and NID_C values.

Table 279: nidBG_nidc_equal Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Checks if the ids of 2 BG are equal by comparing their NID_BG and NID_C values</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.28.2. Interface

Table 280: Inputs of nidBG_nidc_equal

| Name | Type | Comments and Information |
|----------|--------|--------------------------|
| nid_c_2 | NID_C | |
| nid_bg_2 | NID_BG | |
| nid_c_1 | NID_C | |
| nid_bg_1 | NID_BG | |

Table 281: Outputs of nidBG_nidc_equal

| Name | Type | Comments and Information |
|---------|------|--------------------------|
| isEqual | bool | |

15.3.28.3. Operator Hierarchy

diagram : diagram_nidBG_nidc_equal_1

15.3.28.4. Graphical and Textual Diagrams

15.3.28.4.1. View of diagram_nidBG_nidc_equal_1 (nidBG_nidc_equal)

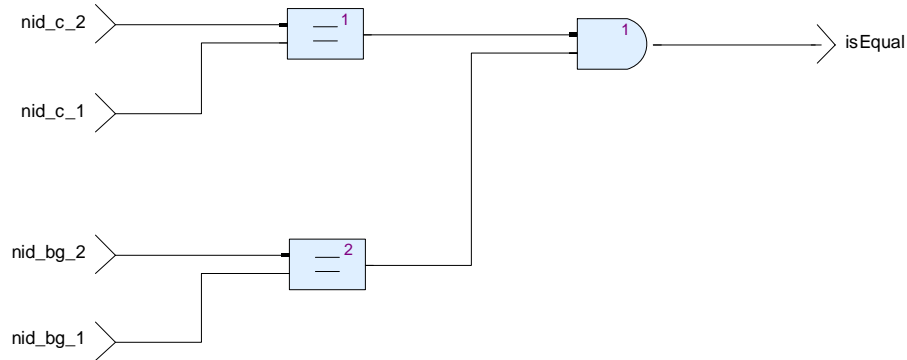


Figure 108: View of diagram_nidBG_nidc_equal_1 (nidBG_nidc_equal)

15.3.29. nidC_nidBG_2_NIDLRGB Operator

Declared as **public function**

15.3.29.1. Comments and Information

nidC_nidBG_2_NIDLRGB Comments:

- Constructs an NID_LRGB value from NID_C and NID_BG

15.3.29.2. Interface

Table 282: Inputs of nidC_nidBG_2_NIDLRGB

| Name | Type | Comments and Information |
|-------|--------|--------------------------|
| valid | bool | |
| nidC | NID_C | |
| nidBG | NID_BG | |

Table 283: Outputs of nidC_nidBG_2_NIDLRGB

| Name | Type | Comments and Information |
|---------|----------|--------------------------|
| nidLRBG | NID_LRGB | |

15.3.29.3. Operator Hierarchy

diagram : diagram_nidC_nidBG_2_NIDLRGB_1

15.3.29.4. Graphical and Textual Diagrams

15.3.29.4.1. View of diagram_nidC_nidBG_2_NIDLRBG_1 (nidC_nidBG_2_NIDLRBG)

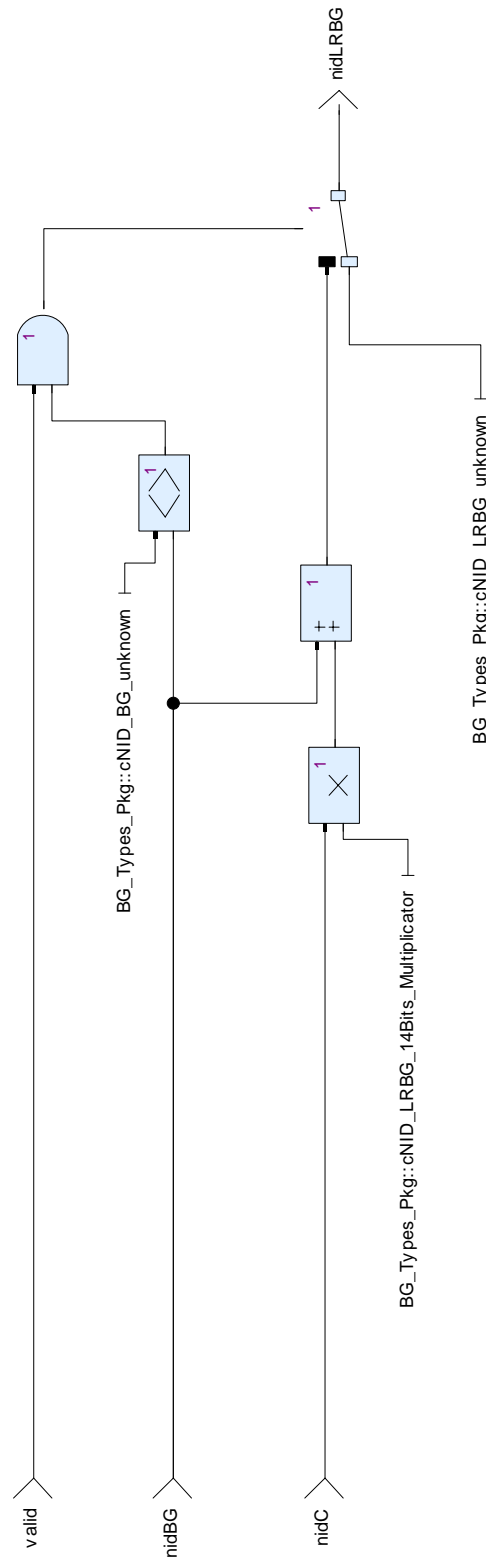


Figure 109: View of diagram_nidC_nidBG_2_NIDLRBG_1 (nidC_nidBG_2_NIDLRBG)

15.3.30. passedBGs_ids_equal Operator

Declared as **public function**

15.3.30.1. Comments and Information

passedBGs_ids_equal Comments:

- Checks if the ids of 2 BG are equal by comparing their NID_BG and NID_C values.

Table 284: passedBGs_ids_equal Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Checks if the ids of 2 BG are equal by comparing their NID_BG and NID_C values.</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.30.2. Interface

Table 285: Inputs of passedBGs_ids_equal

| Name | Type | Comments and Information |
|------|--------------------------|--------------------------|
| bg_2 | BG_Types_Pkg::passedBG_T | |
| bg_1 | BG_Types_Pkg::passedBG_T | |

Table 286: Outputs of passedBGs_ids_equal

| Name | Type | Comments and Information |
|--------------|------|--------------------------|
| idsEqual | bool | |
| idsDifferent | bool | |

15.3.30.3. Operator Hierarchy

diagram : diagram_passedBGs_ids_equal_1

15.3.30.4. Graphical and Textual Diagrams

15.3.30.4.1. View of diagram_passedBGs_ids_equal_1 (passedBGs_ids_equal)

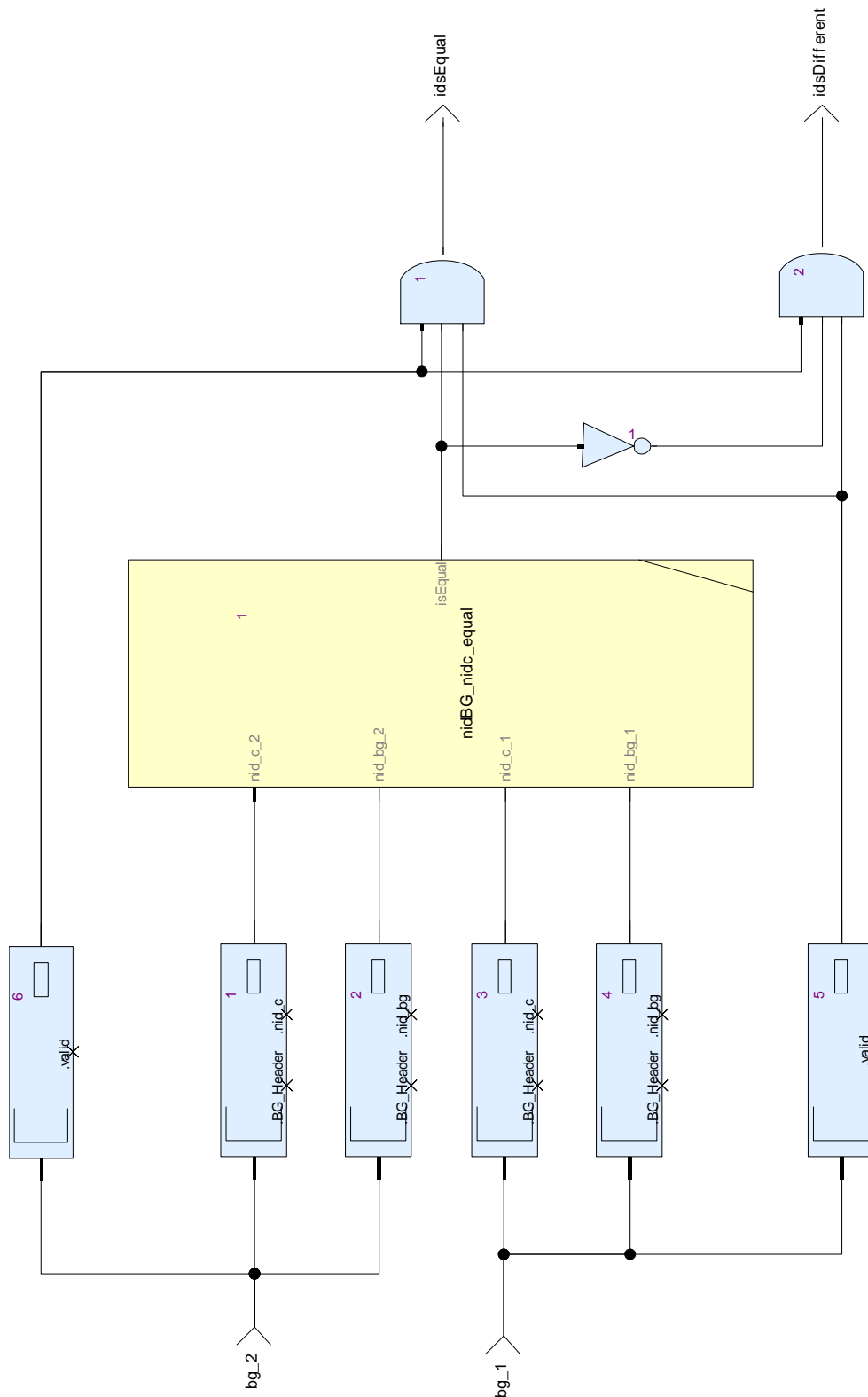


Figure 110: View of diagram_passedBGs_ids_equal_1 (passedBGs_ids_equal)

15.3.31. positionDerivedFromPassedBG Operator

Declared as **public function**

15.3.31.1. Comments and Information

positionDerivedFromPassedBG Comments:

- Calculates the train position on the base of the odometry and a passed reference BG.
- If there is no reference BG or the reference BG had not been passed, the odoPosition will simply be converted into a position.

Table 287: positionDerivedFromPassedBG Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Calculates the train position on the base of the odometry and a passed reference BG.</p> <p>- Copyright Siemens AG, 2014</p> <p>- Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl)</p> <p>- Gist URL: ---</p> <p>- Cryptography: No</p> <p>- Author(s): Uwe Steinke</p> <p>The use of this software is limited to non-vital applications.</p> <p>It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss.</p> <p>THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.31.2. Interface

Table 288: Inputs of positionDerivedFromPassedBG

| Name | Type | Comments and Information |
|-------------|---|---|
| odoPosition | Obu_BasicTypes_Pkg::OdometryLocations_T | Comments: The position measured by odometry |
| passedRefBG | TrainPosition_Types_Pkg::positionedBG_T | Comments: The passed reference BG. Important: this BG must have been passed already, since its odometry values must be known. |

Table 289: Outputs of positionDerivedFromPassedBG

| Name | Type | Comments and Information |
|----------|------------------------------------|--------------------------------------|
| position | Obu_BasicTypes_Pkg::LocWithInAcc_T | Comments: The resulting position. |

15.3.31.3. Operator Hierarchy

diagram : diagram_positionDerivedFromPassedBG_1

activate if : IfBlock1

branch : then

branch : else

15.3.31.4. Graphical and Textual Diagrams

15.3.31.4.1. View of diagram_positionDerivedFromPassedBG_1 (positionDerivedFromPassedBG)

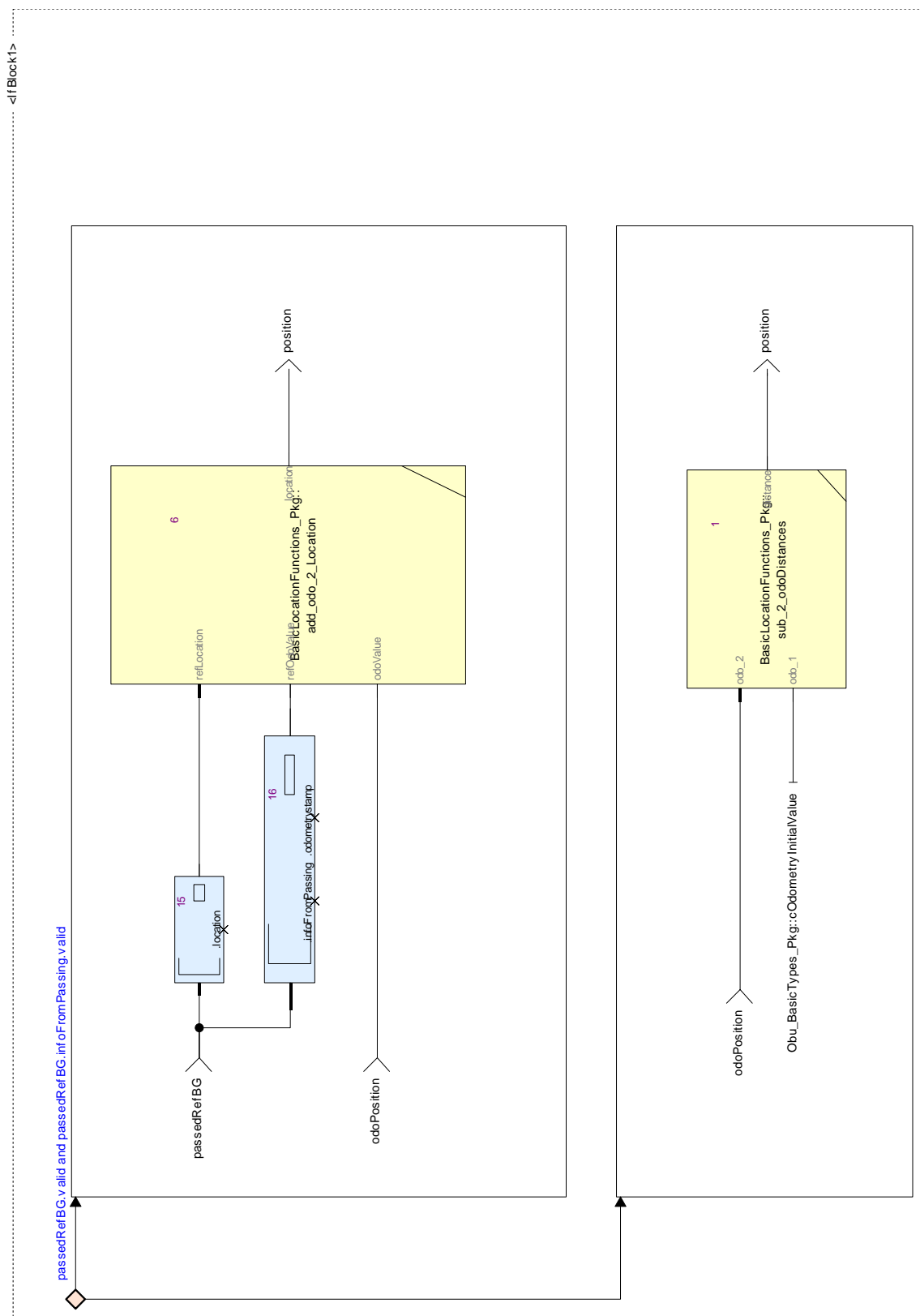


Figure 111: View of diagram_positionDerivedFromPassedBG_1 (positionDerivedFromPassedBG)

Table 290: Conditional Blocks of diagram_positionDerivedFromPassedBG_1

| Conditional Block | Comments and Information |
|-------------------|--------------------------|
| IfBlock1 | |

Table 291: Actions of diagram_positionDerivedFromPassedBG_1

| Conditional Block Action | Comments and Information |
|--------------------------|--------------------------|
| IfBlock1:then | |
| IfBlock1:else | |

15.3.32. positionedBGs_ids_equal Operator

Declared as **public function**

15.3.32.1. Comments and Information

positionedBGs_ids_equal Comments:

- Checks if the ids of 2 BG are equal by comparing their NID_BG and NID_C values.

Table 292: positionedBGs_ids_equal Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Checks if the ids of 2 BG are equal by comparing their NID_BG and NID_C values.</p> <ul style="list-style-type: none"> - Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.32.2. Interface

Table 293: Inputs of positionedBGs_ids_equal

| Name | Type | Comments and Information |
|------|---|--------------------------|
| bg_2 | TrainPosition_Types_Pc k::positionedBG_T | |
| bg_1 | TrainPosition_Types_Pc k::positionedBG_T | |

Table 294: Outputs of positionedBGs_ids_equal

| Name | Type | Comments and Information |
|----------|------|--------------------------|
| idsEqual | bool | |

15.3.32.3. Operator Hierarchy

diagram : diagram_positionedBGs_ids_equal_1

15.3.32.4. Graphical and Textual Diagrams

15.3.32.4.1. View of diagram_positionedBGs_ids_equal_1 (positionedBGs_ids_equal)

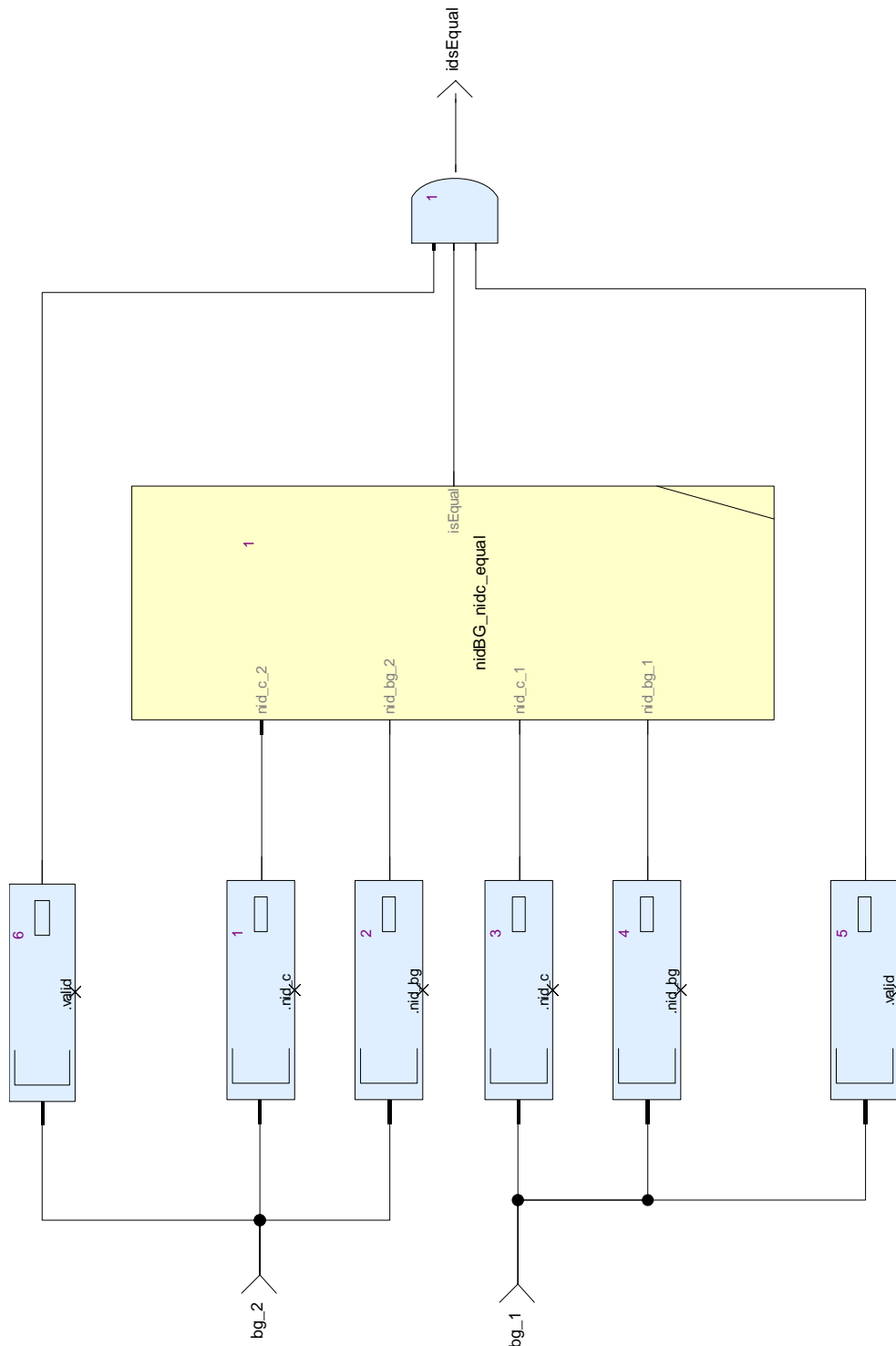


Figure 112: View of diagram_positionedBGs_ids_equal_1 (positionedBGs_ids_equal)

15.3.33. positionLinkedBGs Operator

Declared as **public function**

15.3.33.1. Comments and Information

positionLinkedBGs Comments:

- Converts the linking information - received while passing a BG - into announced (= linked positioned) BGs.

Table 295: positionLinkedBGs Annotations

| Note Name | Attribute | Value |
|-----------|-------------|---|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Converts the linking information, received while passing a BG into an announced (= linked positioned) BG.</p> <p>- Copyright Siemens AG, 2014 - Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl) - Gist URL: --- - Cryptography: No - Author(s): Uwe Steinke</p> <p>The use of this software is limited to non-vital applications. It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss. THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.33.2. Interface

Table 296: Inputs of positionLinkedBGs

| Name | Type | Comments and Information |
|--------------------|---|---|
| passedPositionedBG | TrainPosition_Types_Pck::positionedBG_T | Comments: The actually passed BG, where the linking information originates from. |
| linkedBGs | BG_Types_Pkg::LinkedBGs_T | |

Table 297: Outputs of positionLinkedBGs

| Name | Type | Comments and Information |
|---------------------|--|--------------------------|
| linkedPositionedBGs | TrainPosition_Types_Pck::linkedBGs_asPositionedBGs_T | |

15.3.33.3. Operator Hierarchy

diagram : diagram_positionLinkedBGs_1

15.3.33.4. Graphical and Textual Diagrams

15.3.33.4.1. View of diagram_positionLinkedBGs_1 (positionLinkedBGs)

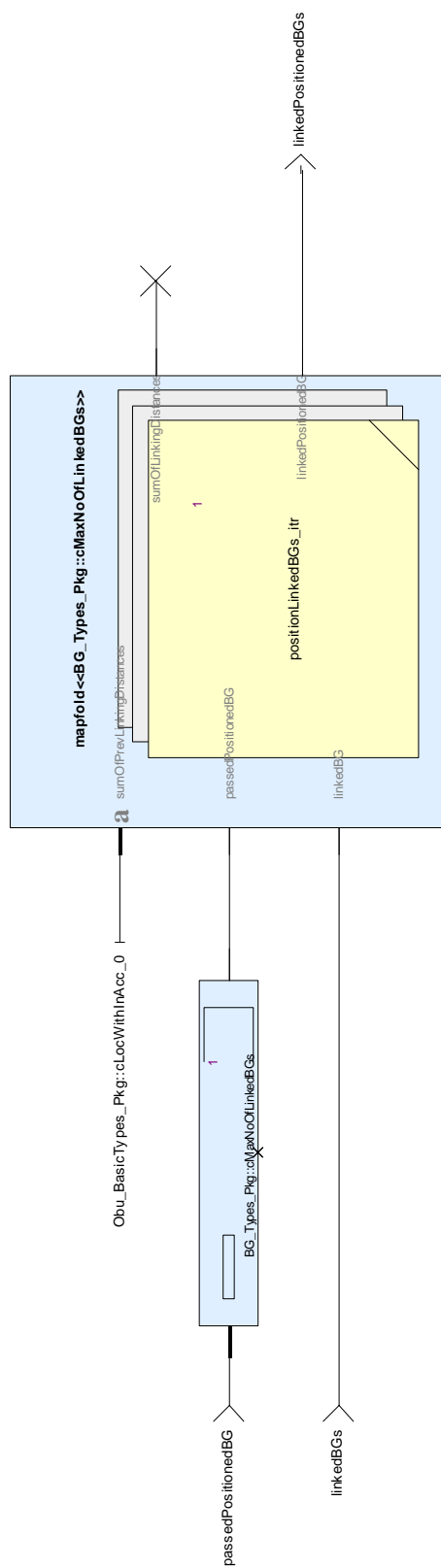


Figure 113: View of diagram_positionLinkedBGs_1 (positionLinkedBGs)

15.3.34. positionLinkedBGs_itr Operator

Declared as **private function**

15.3.34.1. Comments and Information

positionLinkedBGs_itr Comments:

- Iterated function for the conversion of the linking information - received while passing a BG - into an announced (= linked positioned) BG.

Table 298: positionLinkedBGs_itr Annotations

| Note Name | Attribute | Value |
|-----------|-------------|--|
| GdC_1 | Author | Uwe Steinke |
| | DateC | Created : 2014-05-22 |
| | DateM | Modified : 2014-05-22 |
| | Version | 00.02.00 |
| | to_c | True |
| Remark_1 | Description | <p>Iterated function for the conversion of the linking information, received while passing a BG into an announced (= linked positioned) BG.</p> <p>- Copyright Siemens AG, 2014</p> <p>- Licensed under the EUPL V.1.1 (http://joinup.ec.europa.eu/software/page/eupl/licence-eupl)</p> <p>- Gist URL: ---</p> <p>- Cryptography: No</p> <p>- Author(s): Uwe Steinke</p> <p>The use of this software is limited to non-vital applications.</p> <p>It has not been developed for vital operation purposes and must not be used for applications which may cause harm to people, physical accidents or financial loss.</p> <p>THEREFORE, NO LIABILITY WILL BE GIVEN FOR SUCH AND ANY OTHER KIND OF USE.</p> |
| | to_c | True |

15.3.34.2. Interface

Table 299: Inputs of positionLinkedBGs_itr

| Name | Type | Comments and Information |
|---------------------------|---|---|
| sumOfPrevLinkingDistances | Obu_BasicTypes_Pkg::LocWithInAcc_T | Comments: The sum of the linking distances from the chain of previous linked BGs since the passedPositionedBG. |
| passedPositionedBG | TrainPosition_Types_Pkg::positionedBG_T | Comments: The actually passed BG, where the linking information originates from. |
| linkedBG | BG_Types_Pkg::LinkedBG_T | Comments: One of the linked BG, announced by the passed BG. |

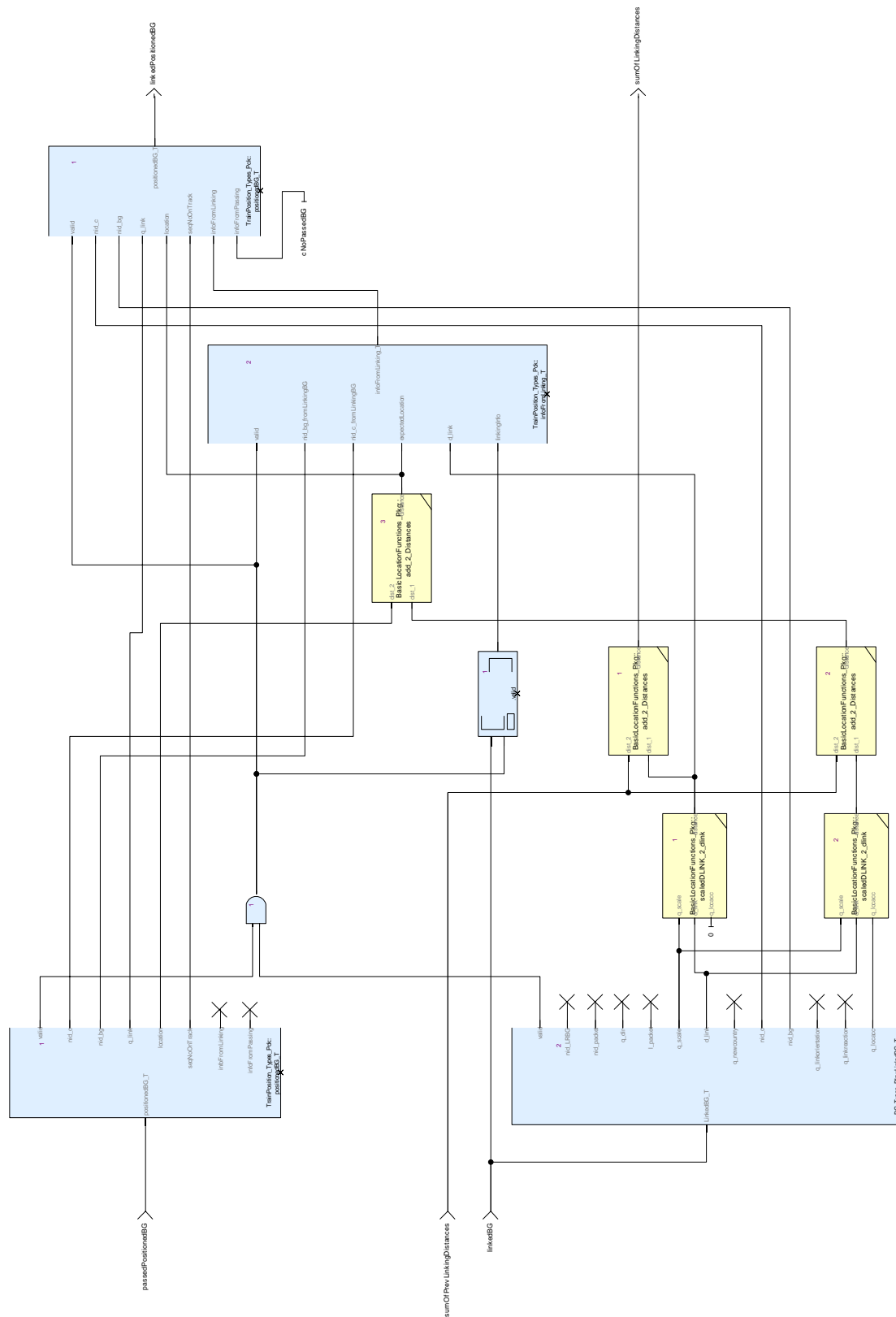
Table 300: Outputs of positionLinkedBGs_itr

| Name | Type | Comments and Information |
|-----------------------|---|--|
| sumOfLinkingDistances | Obu_BasicTypes_Pkg::LocWithInAcc_T | Comments: Sum of linking distances from the passedPositionedBG until this BG. |
| linkedPositionedBG | TrainPosition_Types_Pkg::positionedBG_T | |

15.3.34.3. Operator Hierarchy

diagram : diagram_positionLinkedBGs_itr_1

15.3.34.4.1. View of diagram_positionLinkedBGs_itr_1 (positionLinkedBGs_itr)



15.3.35. trimSeqNoOnTrack Operator

Declared as **public function**

15.3.35.1. Comments and Information

trimSeqNoOnTrack Comments:

- Adjusts the sequence number (seqNoOnTrack) of announced (not yet passed BGs).

15.3.35.2. Interface

Table 301: Inputs of trimSeqNoOnTrack

| Name | Type | Comments and Information |
|--------|--|---|
| BGs_in | TrainPosition_Types_Pck::positionedBGs_T | Comments: The BGs where BG is to be merged with. |

Table 302: Outputs of trimSeqNoOnTrack

| Name | Type | Comments and Information |
|---------|--|---|
| BGs_out | TrainPosition_Types_Pck::positionedBGs_T | Comments: The resulting array of merged BGs. |

15.3.35.3. Operator Hierarchy

diagram : diagram_trimSeqNoOnTrack_1

15.3.35.4. Graphical and Textual Diagrams

15.3.35.4.1. View of diagram_trimSeqNoOnTrack_1 (trimSeqNoOnTrack)

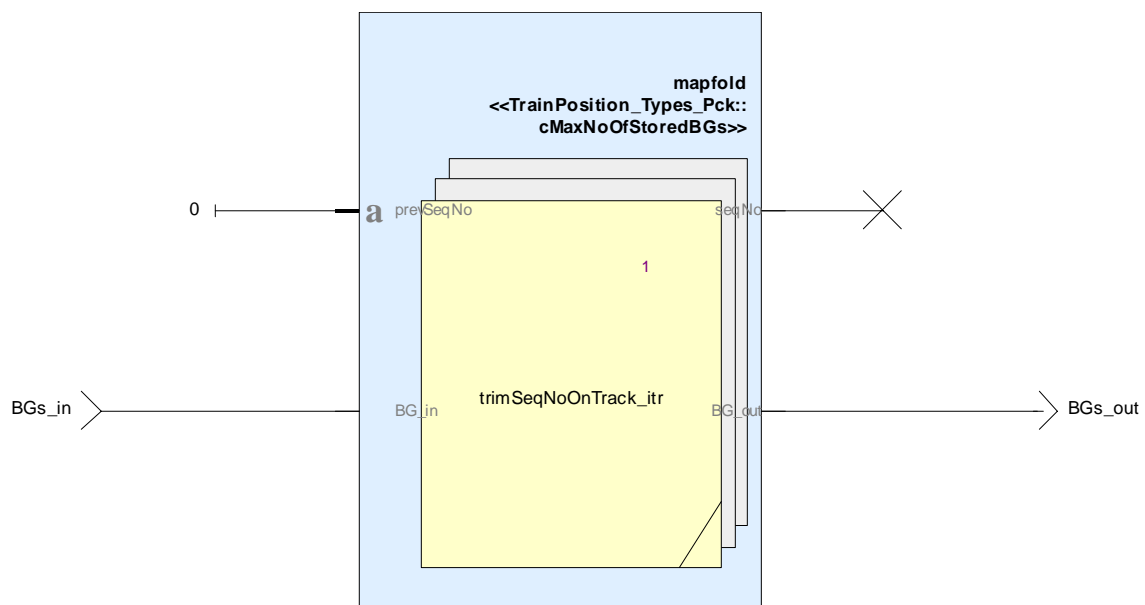


Figure 115: View of diagram_trimSeqNoOnTrack_1 (trimSeqNoOnTrack)

15.3.36. trimSeqNoOnTrack_itr Operator

Declared as **private function**

15.3.36.1. Comments and Information

trimSeqNoOnTrack_itr Comments:

- Adjusts the sequence number (seqNoOnTrack) of announced (not yet passed BGs).

15.3.36.2. Interface

Table 303: Inputs of trimSeqNoOnTrack_itr

| Name | Type | Comments and Information |
|-----------|---|-----------------------------------|
| prevSeqNo | int | |
| BG_in | TrainPosition_Types_Pc k::positionedBG_T | Comments: The BG to be merged. |

Table 304: Outputs of trimSeqNoOnTrack_itr

| Name | Type | Comments and Information |
|--------|---|-----------------------------------|
| seqNo | int | |
| BG_out | TrainPosition_Types_Pc k::positionedBG_T | Comments: The BG to be merged. |

15.3.36.3. Operator Hierarchy

diagram : diagram_trimSeqNoOnTrack_itr_1

15.3.36.4. Graphical and Textual Diagrams

15.3.36.4.1. View of diagram_trimSeqNoOnTrack_itr_1 (trimSeqNoOnTrack_itr)

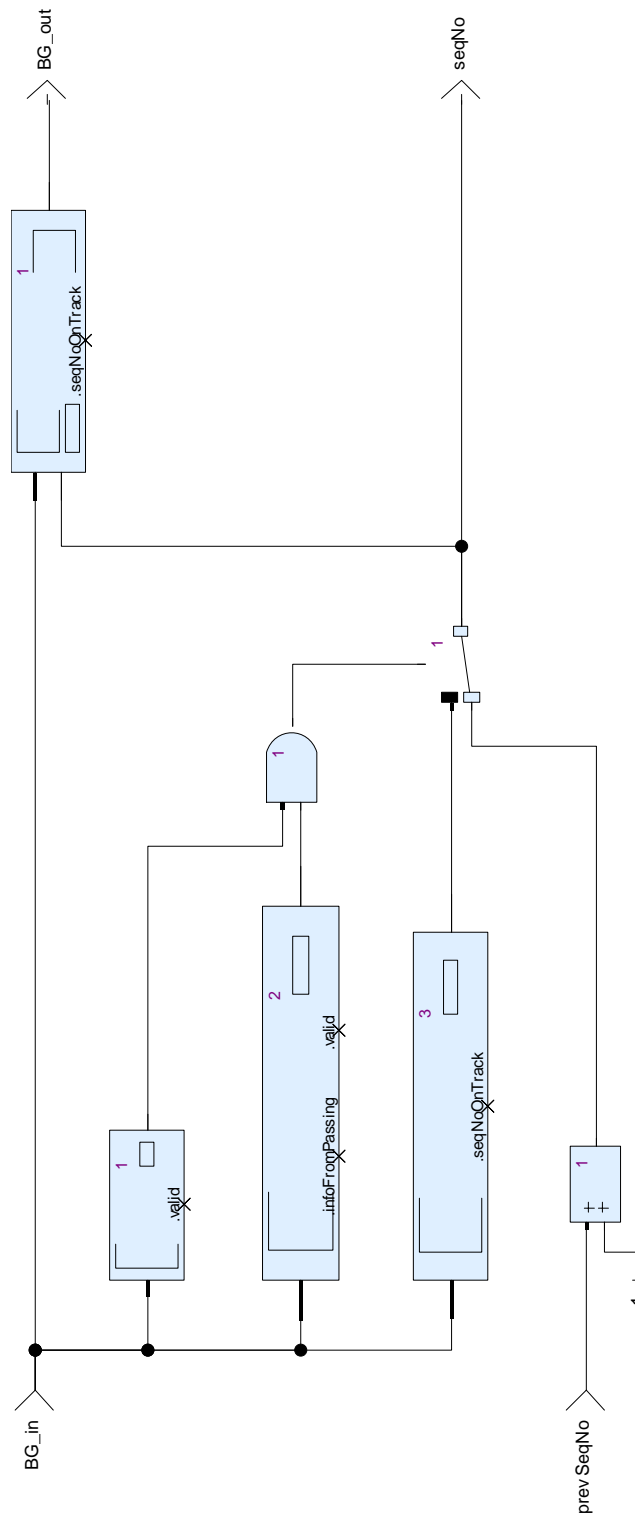


Figure 116: View of diagram_trimSeqNoOnTrack_itr_1 (trimSeqNoOnTrack_itr)

15.4. CalculateTrainPosition_Pkg::gp_functions_Pkg Package

15.4.1. Constants

Table 305: Public Constants of gp_functions_Pkg

| Name | Type | Value | Comments and Information |
|--------------|------|-------|--------------------------|
| noValidIndex | int | -1 | |

15.4.2. countUp Operator

Declared as **public node**

15.4.2.1. Comments and Information

countUp Comments:

- Counter counting upwards by one.

15.4.2.2. Interface

Table 306: Inputs of countUp

| Name | Type | Properties | Comments and Information |
|-------|------|------------|---|
| count | bool | | Comments: Enables counting. |
| reset | bool | hidden | Comments: Resets the counter value to 0. |

Table 307: Outputs of countUp

| Name | Type | Comments and Information |
|---------|------|---------------------------------|
| counter | int | Comments: The counter value. |

15.4.2.3. Operator Hierarchy

diagram : diagram_countUp_1

15.4.2.4. Graphical and Textual Diagrams

15.4.2.4.1. View of diagram_countUp_1 (countUp)

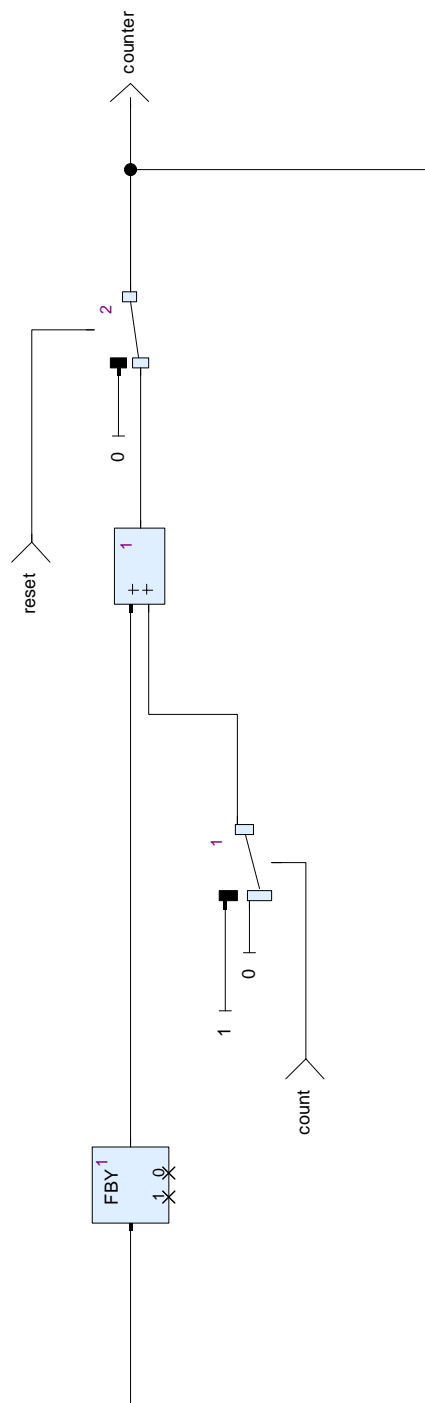


Figure 117: View of diagram_countUp_1 (countUp)

16. Project Library: ProvidePositionReport

16.1. ProvidePositionReport_Pkg Package

16.1.1. Types

Table 308: Public Types of ProvidePositionReport_Pkg

| Name | Definition | Comments and Information |
|---------------------------|--|---|
| ErrorMessage_T | {present : bool, errorType : M_ERROR} | Comments: Combining M_ERROR and the present flag. |
| IterPacket58_T | {d_loc : D_LOC, q_lgtloc : Q_LGTLOC} | |
| IterPacket58List_T | ProvidePositionReport_Pkg::IterPacket58_T ^clIterPacket58 | |
| LinkingInfoUsedOnBoard | bool | Comments: Defined in 3.4.4.2.1.1; probably added to PositionedBG_T |
| MemorizedErrorMsg_T | {valid : bool, errorType : M_ERROR} | Comments: internal data structre |
| Packet0_T | {valid : bool, packet0 : TrainToTrack::Position_Report} | Comments: Adding a valid flag to Packet 0 |
| Packet1_T | {valid : bool, packet1 : TrainToTrack::Position_Report_based_on_two_balise_groups} | Comments: Adding a valid flag to packet 1. |
| Packet4_T | {valid : bool, packet4 : TrainToTrack::Error_reporting} | Comments: Adding a valid flag to packet 4. |
| Packet58_T | {nid_packet : NID_PACKET, q_dir : Q_DIR, l_packet : L_PACKET, q_scale : Q_SCALE, t_cycloc : T_CYCLOC, d_cycloc : D_CYCLOC, m_loc : M_LOC, n_iter : N_ITER, interPacket58List : ProvidePositionReport_Pkg::IterPacket58List_T} | |
| Packet5_T | {valid : bool, packet5 : TrainToTrack::Train_running_number} | Comments: Adding a valid flag to packet 5. |
| PositionReport_T | {valid : bool, header : ProvidePositionReport_Pkg::PositionReportHeader_T, packet0 : ProvidePositionReport_Pkg::Packet0_T, packet1 : ProvidePositionReport_Pkg::Packet1_T, packet4 : ProvidePositionReport_Pkg::Packet4_T, packet5 : ProvidePositionReport_Pkg::Packet5_T} | Comments: Position report: either packet 0 or packet 1 has valid flag set to true. |
| PositionReportHeader_T | {nid_message : NID_MESSAGE, l_message : L_MESSAGE, t_train : T_TRAIN, nid_engine : NID_ENGINE} | Comments: Position report header |
| PositionReportParameter_T | {present : bool, packet58 : ProvidePositionReport_Pkg::Packet58_T} | |
| PresentxMLOC_T | {present : bool, m_loc : M_LOC} | Comments: Crossproduct of present flag and M_LOC; internal memory representation |

| Name | Definition | Comments and Information |
|---------------------|---|--|
| RBC_Communication_T | {newSessionEstablished : bool} | Comments: variables necessary for the communication with the RBC newSessionEstablished Comments: to decide 3.6.5.1.4.h |
| SystemTime_T | Obu_BasicTypes_Pkg::T_internal_Type | Comments: global system time |
| TrackInfo_T | {minSafeRearEndPassed : bool, maxSafeFrontEndPassed : bool, levelTransitionBorderPassed : bool} | Comments: Information necessary to calculate whether event triggering the sending of a position report evaluates to true. minSafeRearEndPassed Comments: to decide 3.6.5.1.4.e maxSafeFrontEndPassed Comments: to decide 3.6.5.1.4.k levelTransitionBorderPassed Comments: to decide 3.6.5.1.4.f |

16.1.2. Constants

Table 309: Public Constants of ProvidePositionReport_Pkg

| Name | Type | Value | Comments and Information |
|--------------------|---|---|------------------------------------|
| cErrorMessage | ProvidePositionReport_Pkg::ErrorMessage_T | {present : false, errorType : M_ERROR_Balise_group_linking_consistency_error} | |
| cIterPacket58 | int | 2 | Comments: value is bound to 32 |
| cL_MESSAGE | L_MESSAGE | 0 | |
| cMinSafeRearEnd | int | 0 | |
| cPresentxM_LOC | ProvidePositionReport_Pkg::PresentxMLOC_T | {present : false, m_loc : M_LOC_Now} | |
| cQ_SCALE | Q_SCALE | Q_SCALE_10_cm_scale | |
| cT_TRAIN | T_TRAIN | 0.0 | |
| cTrack2TrainStatus | BG_Types_Pkg::TrainToTrackStatus_T | {m_mode : M_MODE_Full_Supervision, m_level : M_LEVEL_Level_0, m_leveltr : M_LEVELTR_Level_0, nid_ntc : 0, q_length : Q_LENGTH_No_train_integrity_information_available} | Comments: used as initial value |

| Name | Type | Value | Comments and Information |
|----------------|--|---|------------------------------------|
| cTrainPosition | TrainPosition_Types_Pck::trainPosition_T | {valid : false, timestamp : 0, trainPositionIsUnknown : false, noCoordinateSystemHasBeenAssigned : false, trainPosition : {nominal : 0, d_min : 0, d_max : 0}, estimatedFrontEndPosition : 0, minSafeFrontEndPosition : 0, maxSafeFrontEndPosition : 0, nid_LRBG : 0, nid_PrivLRB : 0, nominalOrReverseToLRBG : Q_DLRBG_Reverse, trainOrientationToLRBG : Q_DIRLRBG_Reverse, trainRunningDirectionToLRBG : Q_DIRTRAIN_Reverse, speed : 0} | Comments: used as initial value |
| cTrigger | bool | false | |
| cUnknownLRBG | int | 16777215 | |

16.1.3. AggregateHeader Operator

Declared as **public function**

16.1.3.1. Comments and Information

AggregateHeader Comments:

- Aggregates values necessary for the position report header. Used default value for L_MESSAGE and T_TRAIN.

16.1.3.2. Interface

Table 310: Inputs of AggregateHeader

| Name | Type | Comments and Information |
|------------|--|--------------------------|
| trainProps | TrainPosition_Types_Pck::trainProperties_T | |

Table 311: Outputs of AggregateHeader

| Name | Type | Comments and Information |
|--------------|---|--------------------------|
| posRepHeader | ProvidePositionReport_Pkg::PositionReportHeader_T | |

16.1.3.3. Operator Hierarchy

diagram : diagram_AggregateHeader_1

16.1.3.4. Graphical and Textual Diagrams

16.1.3.4.1. View of diagram_AggregateHeader_1 (AggregateHeader)

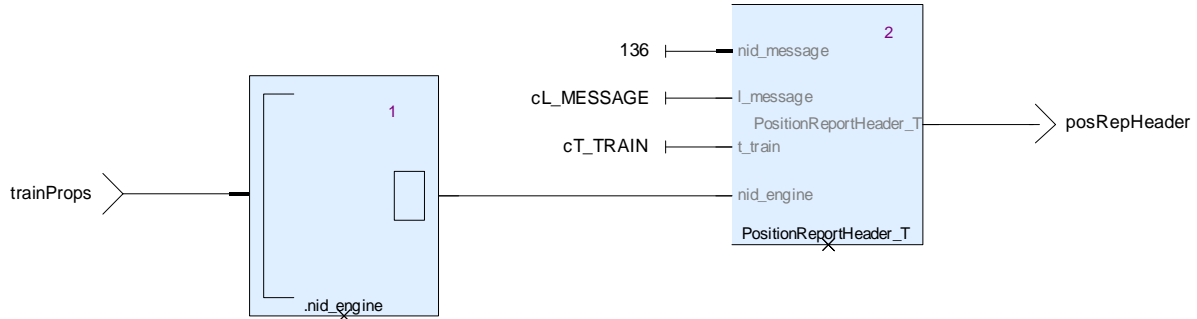


Figure 118: View of diagram_AggregateHeader_1 (AggregateHeader)

16.1.4. AggregatePacket_0 Operator

Declared as **public function**

16.1.4.1. Comments and Information

AggregatePacket_0 Comments:

- Aggregates all values necessary for report packet 0.

16.1.4.2. Interface

Table 312: Inputs of AggregatePacket_0

| Name | Type | Comments and Information |
|-------------------|--|--------------------------|
| posBGs | TrainPosition_Types_Pck::positionedBG_T | |
| trainPos | TrainPosition_Types_Pck::trainPosition_T | |
| train2trackStatus | BG_Types_Pkg::TrainToTrackStatus_T | |
| TrainRearEndPos3 | L_TRAININT | |

Table 313: Outputs of AggregatePacket_0

| Name | Type | Comments and Information |
|---------|--------------------------------------|--------------------------|
| packet0 | ProvidePositionReport_Pkg::Packet0_T | |

16.1.4.3. Operator Hierarchy

diagram : diagram_AggregatePacket_0_1

16.1.4.4. Graphical and Textual Diagrams

16.1.4.4.1. View of diagram_AggregatePacket_0_1 (AggregatePacket_0)

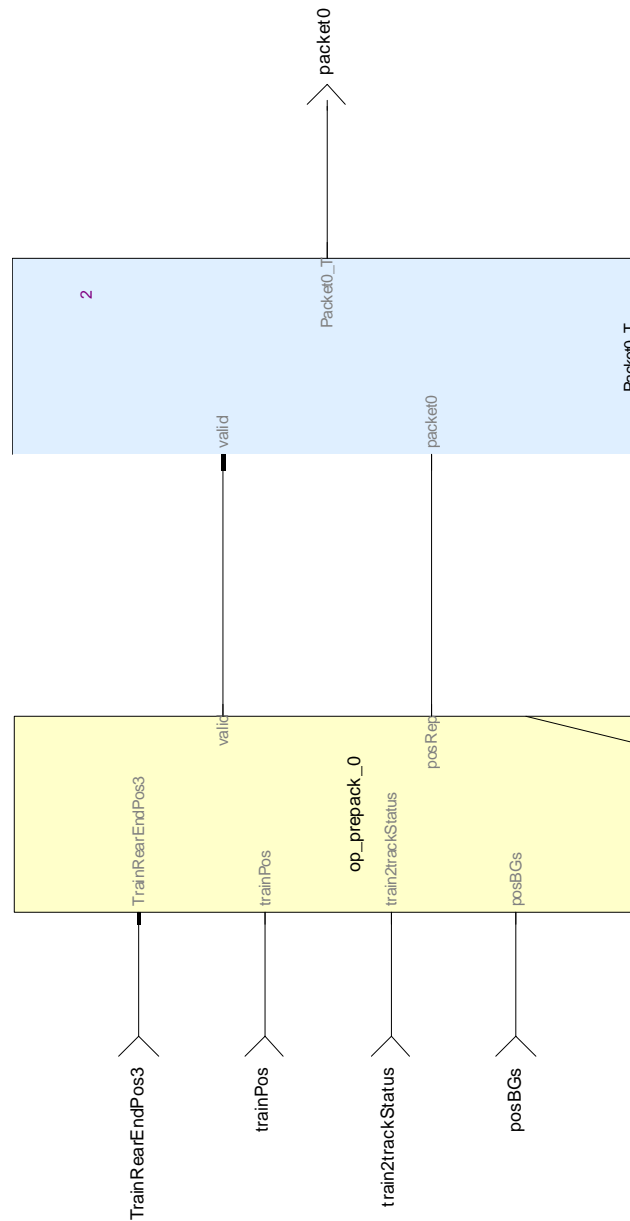


Figure 119: View of diagram_AggregatePacket_0_1 (AggregatePacket_0)

16.1.5. AggregatePacket_1 Operator

Declared as **public function**

16.1.5.1. Comments and Information

AggregatePacket_1 Comments:

- Aggregates all values necessary for report packet 1.

16.1.5.2. Interface

Table 314: Inputs of AggregatePacket_1

| Name | Type | Comments and Information |
|-------------------|--|--------------------------|
| posBGs | TrainPosition_Types_Pkg::positionedBG_T | |
| trainPos | TrainPosition_Types_Pkg::trainPosition_T | |
| train2trackStatus | BG_Types_Pkg::TrainToTrackStatus_T | |
| TrainRearEndPos4 | L_TRAININT | |

Table 315: Outputs of AggregatePacket_1

| Name | Type | Comments and Information |
|---------|--------------------------------------|--------------------------|
| packet1 | ProvidePositionReport_Pkg::Packet1_T | |

16.1.5.3. Operator Hierarchy

diagram : diagram_AggregatePacket_1_1

16.1.5.4. Graphical and Textual Diagrams

16.1.5.4.1. View of diagram_AggregatePacket_1_1 (AggregatePacket_1)

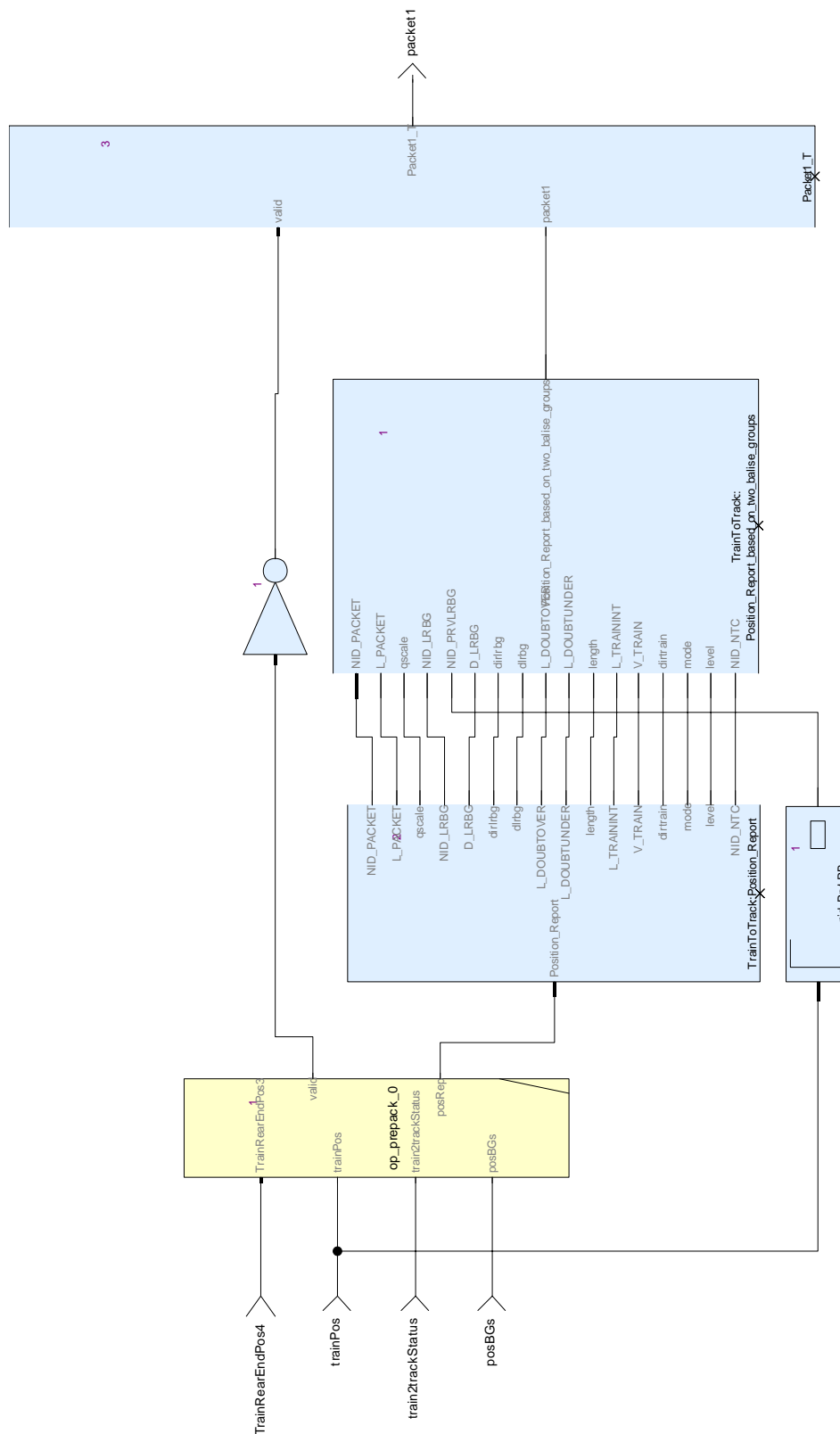


Figure 120: View of diagram_AggregatePacket_1_1 (AggregatePacket_1)

16.1.6. AggregatePacket_4 Operator

Declared as **public node**

16.1.6.1. Comments and Information

AggregatePacket_4 Comments:

- Aggregates all values necessary for report packet 4.
- The memory stores one error. If another error is reported before the position report has been sent,
- the first error is overwritten by the last error. The error is stored until a position report is sent (trigger=true)
- or it is overwritten.
- With the help of the state machine, we can ensure that a stored error is reported with the next trigger message.

16.1.6.2. Interface

Table 316: Inputs of AggregatePacket_4

| Name | Type | Properties | | Comments and Information |
|----------|---|------------|---------------|--------------------------|
| errorMsg | ProvidePositionReport_Pkg::ErrorMessage_T | last | cErrorMessage | |
| trigger | bool | last | cTrigger | |

Table 317: Outputs of AggregatePacket_4

| Name | Type | Comments and Information |
|---------|--------------------------------------|--------------------------|
| packet4 | ProvidePositionReport_Pkg::Packet4_T | |

16.1.6.3. Locals

Table 318: Locals of AggregatePacket_4

| Name | Type | Properties | | Comments and Information |
|--------------|------|------------|-------|--------------------------|
| empty | bool | default | true | |
| intermediate | bool | default | false | |
| valid | bool | | | |

16.1.6.4. Operator Hierarchy

diagram : diagram_AggregatePacket_4_1

state-machine : SM1

state : emptyStorage

state : filledStorage

state : init

state : intermediate

16.1.6.5.1. View of diagram_AggregatePacket_4_1 (AggregatePacket_4)

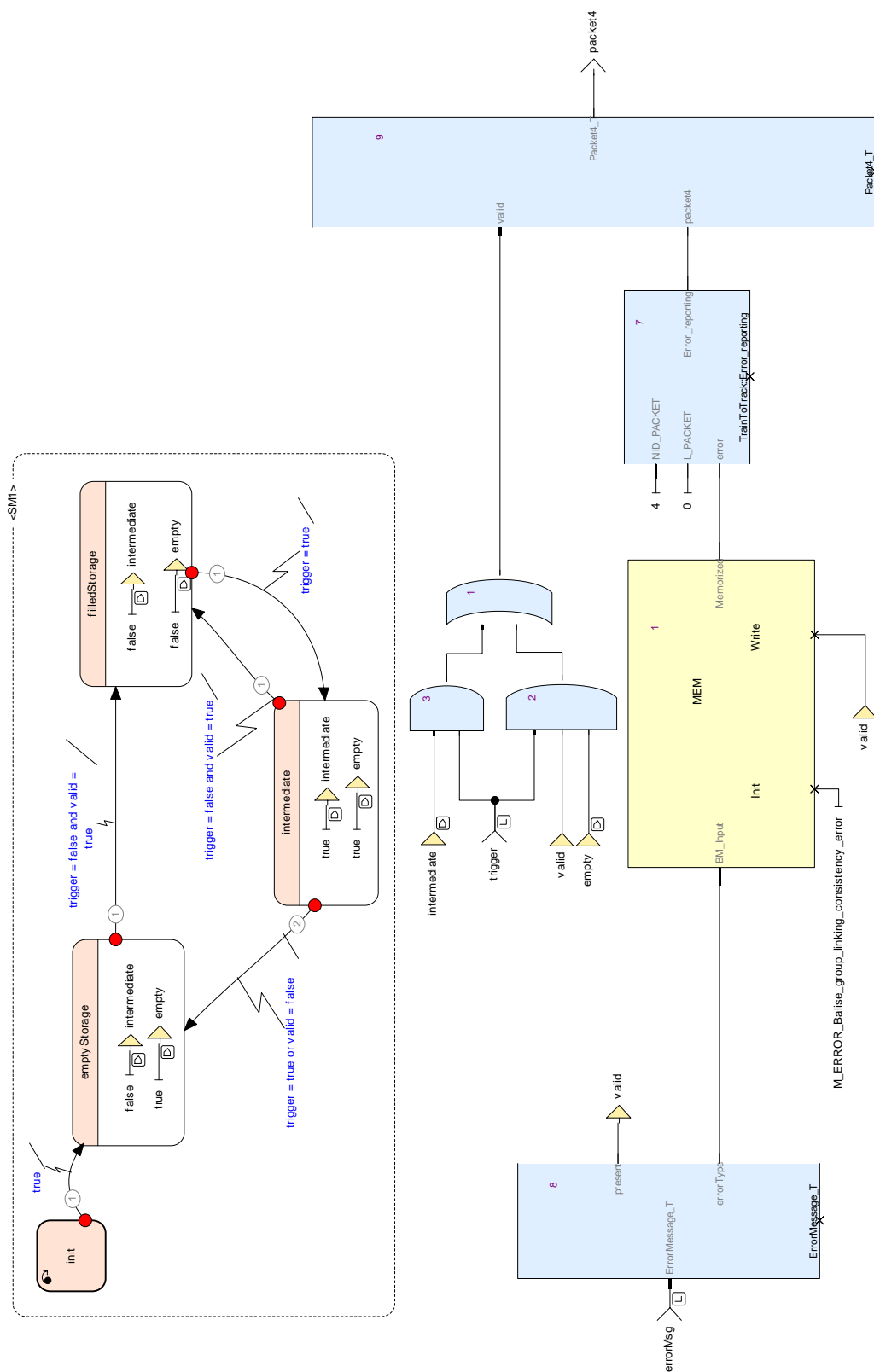


Figure 121: View of diagram_AggregatePacket_4_1 (AggregatePacket_4)

Table 319: State Machines of diagram_AggregatePacket_4_1

| State Machine | Comments and Information |
|---------------|--------------------------|
| SM1 | |

Table 320: States of diagram_AggregatePacket_4_1

| State | Comments and Information |
|-------------------|--------------------------|
| SM1:emptyStorage | |
| SM1:filledStorage | |
| SM1:init | |
| SM1:intermediate | |

Table 321: Transitions of diagram_AggregatePacket_4_1

| Source/Target | # | Conditions/Actions | Comments and Information |
|---|---|---|--------------------------|
| Source: SM1:emptyStorage Target: SM1:filledStorage | 1 | Condition: trigger = false and valid = true | |
| Source: SM1:filledStorage Target: SM1:intermediate | 1 | Condition: trigger = true | |
| Source: SM1:init Target: SM1:emptyStorage | 1 | Condition: true | |
| Source: SM1:intermediate Target: SM1:filledStorage | 1 | Condition: trigger = false and valid = true | |
| Source: SM1:intermediate Target: SM1:emptyStorage | 2 | Condition: trigger = true or valid = false | |

16.1.7. AggregatePacket_5 Operator

Declared as **public function**

16.1.7.1. Comments and Information

AggregatePacket_5 Comments:

- Aggregates all values necessary for report packet 5. As train information data is
- always available, the valid flag is always set to true.

16.1.7.2. Interface

Table 322: Inputs of AggregatePacket_5

| Name | Type | Comments and Information |
|------------|--|--------------------------|
| trainProps | TrainPosition_Types_Pc k::trainProperties_T | |

Table 323: Outputs of AggregatePacket_5

| Name | Type | Comments and Information |
|---------|--|--------------------------|
| packet5 | ProvidePositionReport_ Pkg::Packet5_T | |

16.1.7.3. Operator Hierarchy

diagram : diagram_AggregatePacket_5_1

16.1.7.4. Graphical and Textual Diagrams

16.1.7.4.1. View of diagram_AggregatePacket_5_1 (AggregatePacket_5)

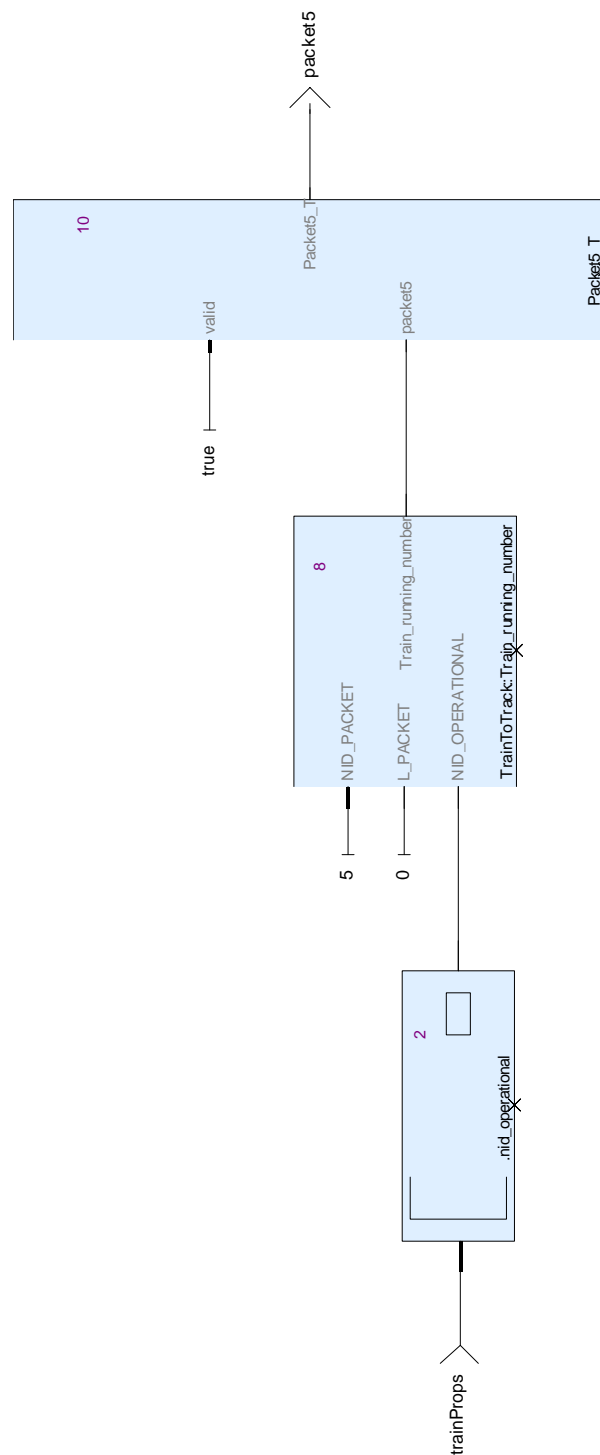


Figure 122: View of diagram_AggregatePacket_5_1 (AggregatePacket_5)

16.1.8. CalculateSafeTrainLength Operator

Declared as **public node**

16.1.8.1. Comments and Information

CalculateSafeTrainLength Comments:

- Calculates the the safeTrainLength according to 3.6.5.2.4/5.
- $\text{safeTrainLength} = \text{absolute}(\text{EstimatedFrontEndPosition} - \text{MinSafeRearEnd})$
 , where
- $\text{MinSafeRearEnd} = \text{minSafeFrontEndPosition} - L_{\text{TRAIN}}$

16.1.8.2. Interface

Table 324: Inputs of CalculateSafeTrainLength

| Name | Type | Comments and Information |
|---------------|--|--------------------------|
| trainProps | TrainPosition_Types_Pc k::trainProperties_T | |
| trainPosition | TrainPosition_Types_Pc k::trainPosition_T | |

Table 325: Outputs of CalculateSafeTrainLength

| Name | Type | Comments and Information |
|-----------------|------------|--------------------------|
| safeTrainLength | L_TRAININT | |

16.1.8.3. Operator Hierarchy

diagram : diagram_CalculateSafeTrainLength_1

16.1.8.4. Graphical and Textual Diagrams

16.1.8.4.1. View of diagram_CalculateSafeTrainLength_1 (CalculateSafeTrainLength)

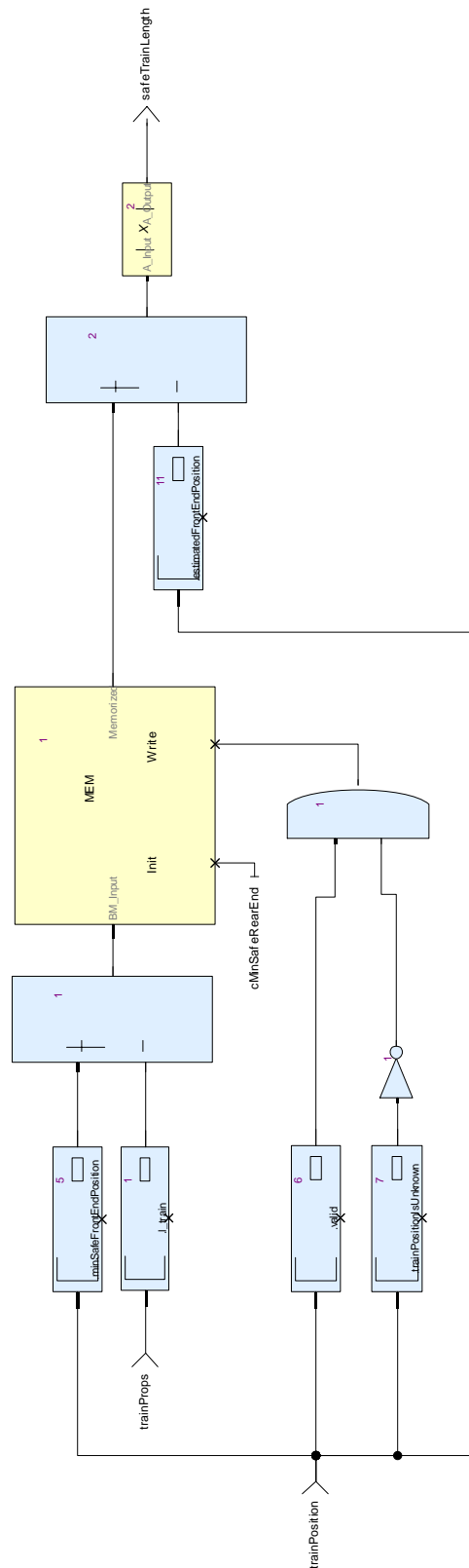


Figure 123: View of diagram_CalculateSafeTrainLength_1 (CalculateSafeTrainLength)

16.1.9. CollectData Operator

Declared as **public node**

16.1.9.1. Comments and Information

CollectData Comments:

- In this operation, data of packets 0 -5 and the header is aggregated to a position report.

16.1.9.2. Interface

Table 326: Inputs of CollectData

| Name | Type | Comments and Information |
|-------------------|--|--------------------------|
| posBGs | TrainPosition_Types_Pck::positionedBG_T | |
| trainPos | TrainPosition_Types_Pck::trainPosition_T | |
| trainProps | TrainPosition_Types_Pck::trainProperties_T | |
| TrainRearEndPos | L_TRAININT | |
| trigger | bool | |
| errorMsg | ProvidePositionReport_Pkg::ErrorMessage_T | |
| train2trackStatus | BG_Types_Pkg::TrainToTrackStatus_T | |

Table 327: Outputs of CollectData

| Name | Type | Comments and Information |
|--------|---|--------------------------|
| posRep | ProvidePositionReport_Pkg::PositionReport_T | |

16.1.9.3. Operator Hierarchy

diagram : diagram_CollectData_1

16.1.9.4. Graphical and Textual Diagrams

16.1.9.4.1. View of diagram_CollectData_1 (CollectData)

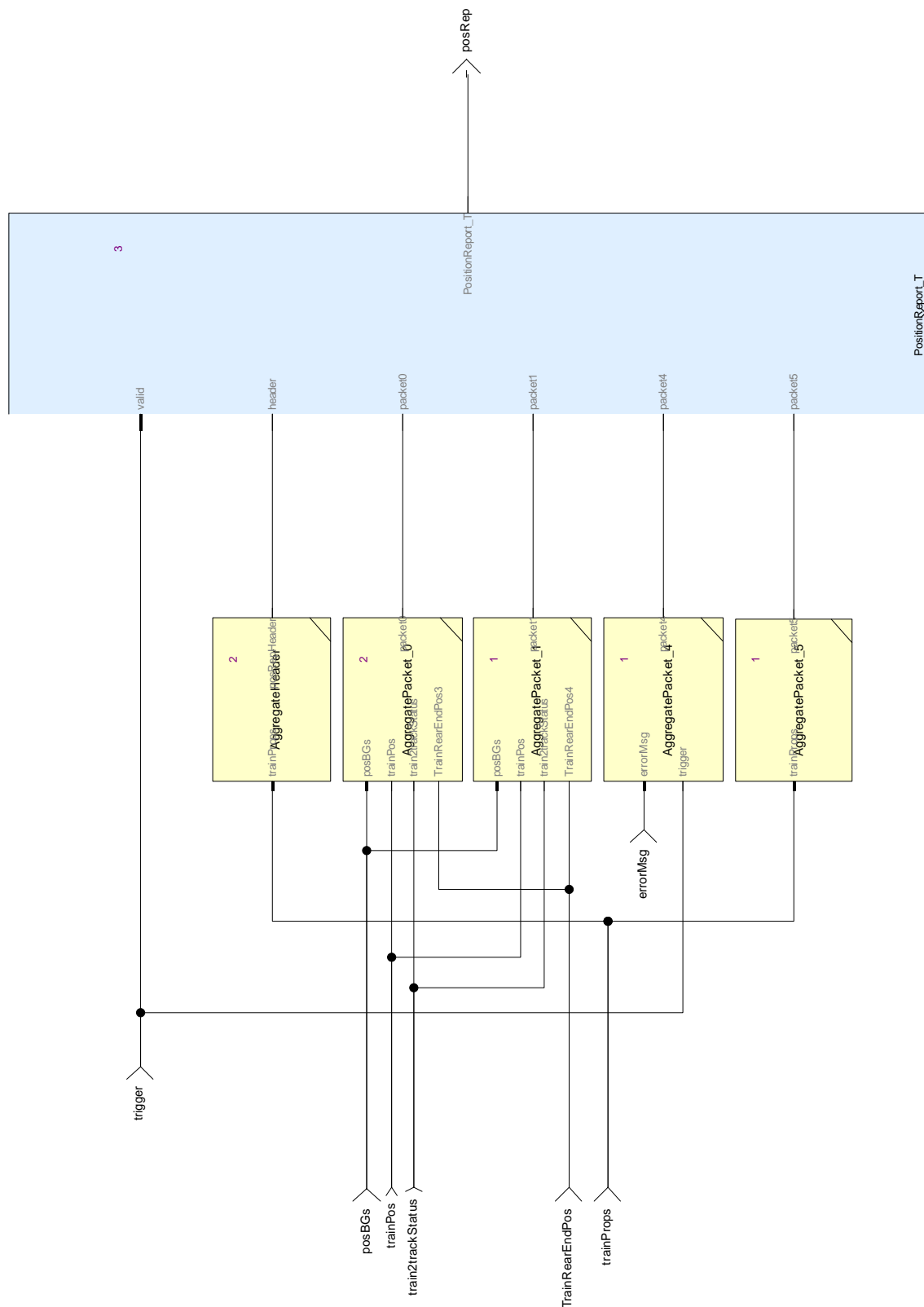


Figure 124: View of diagram_CollectData_1 (CollectData)

16.1.10. EvaluateEvents Operator

Declared as **public node**

16.1.10.1. Comments and Information

EvaluateEvents Comments:

- Evaluates whether one of the events described in 3.6.5.1.4 holds.

16.1.10.2. Interface

Table 328: Inputs of EvaluateEvents

| Name | Type | Comments and Information |
|-------------------|---|--------------------------|
| trackInfo | ProvidePositionReport_Pkg::TrackInfo_T | |
| trainPos | TrainPosition_Types_Pkg::trainPosition_T | |
| posBGs | TrainPosition_Types_Pkg::positionedBG_T | |
| rbcComm | ProvidePositionReport_Pkg::RBC_Communication_T | |
| train2trackStatus | BG_Types_Pkg::TrainToTrackStatus_T | |
| linkingInfoUsed | ProvidePositionReport_Pkg::LinkingInfoUsedOnBoard | |

Table 329: Outputs of EvaluateEvents

| Name | Type | Comments and Information |
|--------|------|--------------------------|
| result | bool | |

16.1.10.3. Operator Hierarchy

diagram : diagram_EvaluateEvents_1

16.1.10.4. Graphical and Textual Diagrams

16.1.10.4.1. View of diagram_EvaluateEvents_1 (EvaluateEvents)

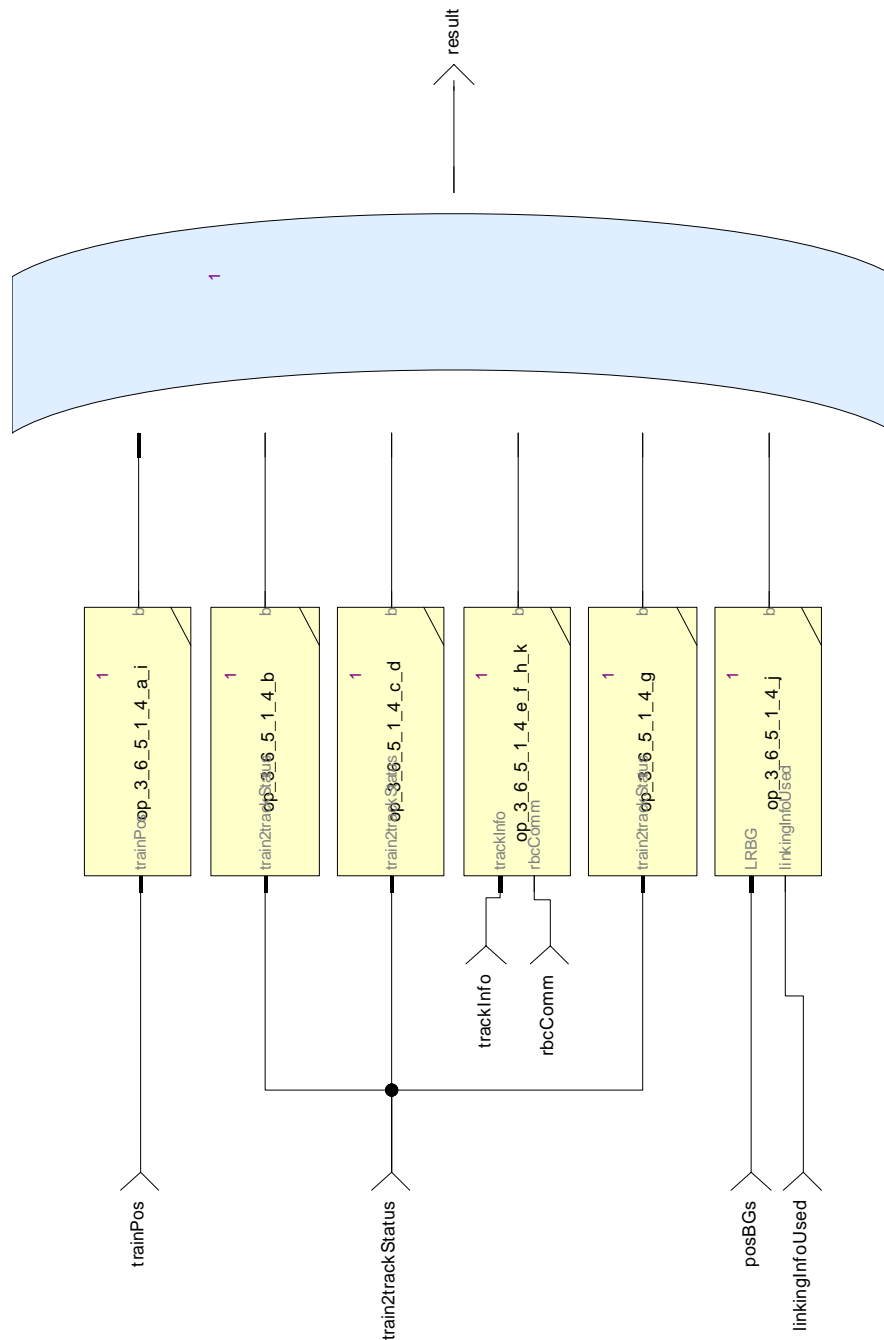


Figure 125: View of diagram_EvaluateEvents_1 (EvaluateEvents)

16.1.11. EvaluateTrigger Operator

Declared as **public node**

16.1.11.1. Comments and Information

EvaluateTrigger Comments:

- Evaluates whether one of the triggers as specified by the trigger parameters evaluates to true.

- Trigger parameters are sent by the RBC using packet 58.

16.1.11.2. Interface

Table 330: Inputs of EvaluateTrigger

| Name | Type | Comments and Information |
|-----------------|--|--------------------------|
| linkingInfoUsed | ProvidePositionReport_ Pkg::LinkingInfoUsedO nBoard | |
| posBGs | TrainPosition_Types_Pc k::positionedBG_T | |
| trainPos | TrainPosition_Types_Pc k::trainPosition_T | |
| posRepPara | ProvidePositionReport_ Pkg::PositionReportPar ameter_T | |
| systemTime | ProvidePositionReport_ Pkg::SystemTime_T | |

Table 331: Outputs of EvaluateTrigger

| Name | Type | Comments and Information |
|--------|------|--------------------------|
| result | bool | |

16.1.11.3. Operator Hierarchy

diagram : diagram_EvaluateTrigger_1

16.1.11.4. Graphical and Textual Diagrams

16.1.11.4.1. View of diagram_EvaluateTrigger_1 (EvaluateTrigger)

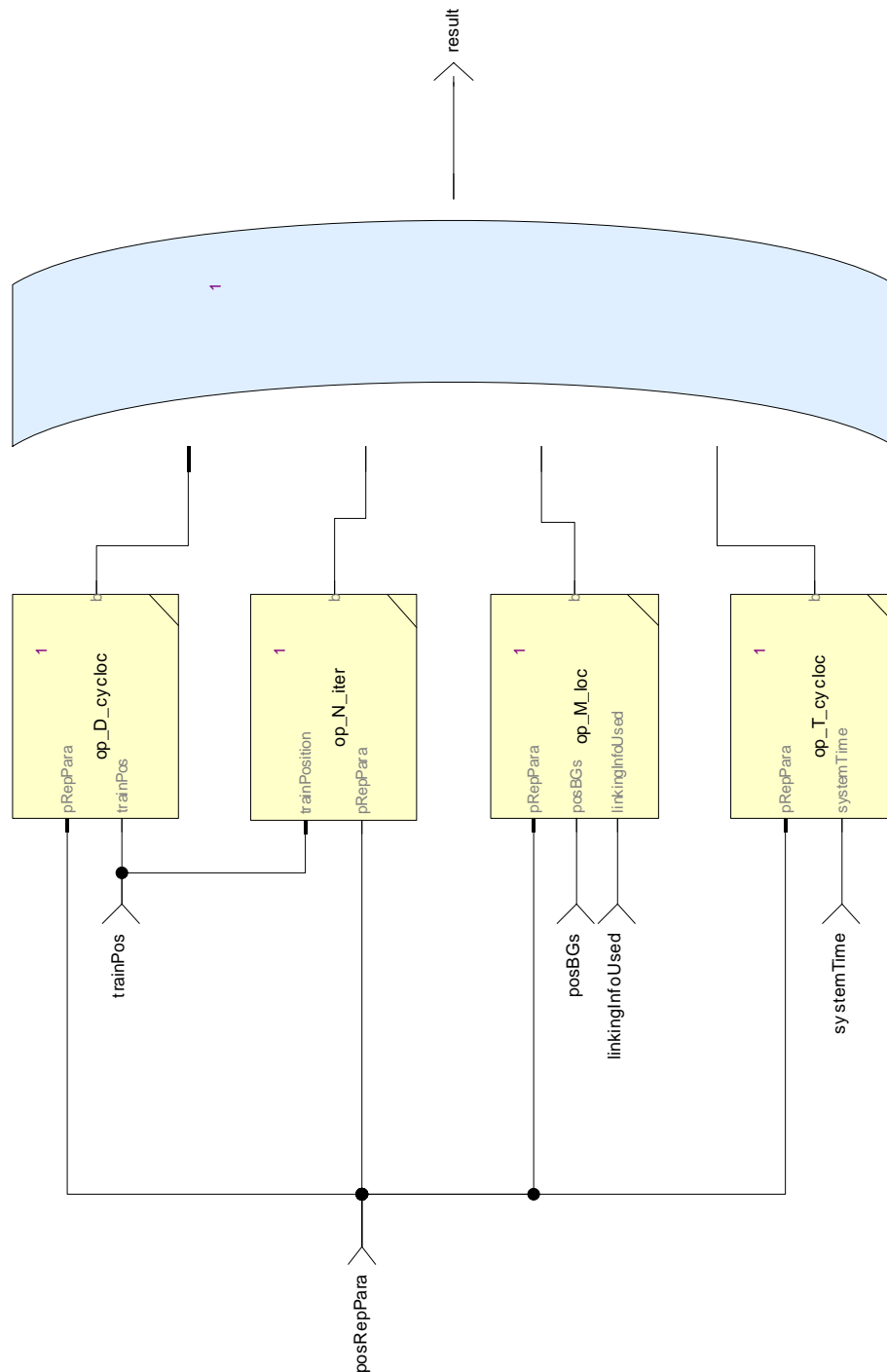


Figure 126: View of diagram_EvaluateTrigger_1 (EvaluateTrigger)

16.1.12. EvaluateTriggerAndEvents Operator

Declared as **public node**

16.1.12.1. Comments and Information

EvaluateTriggerAndEvents Comments:

- conjunction of the evaluation of triggers and events.

16.1.12.2. Interface

Table 332: Inputs of EvaluateTriggerAndEvents

| Name | Type | Comments and Information |
|-------------------|--|--------------------------|
| trackInfo | ProvidePositionReport_ Pkg::TrackInfo_T | |
| trainPos | TrainPosition_Types_Pc k::trainPosition_T | |
| posRepPara | ProvidePositionReport_ Pkg::PositionReportPar ameter_T | |
| posBGs | TrainPosition_Types_Pc k::positionedBG_T | |
| systemTime | ProvidePositionReport_ Pkg::SystemTime_T | |
| rbcComm | ProvidePositionReport_ Pkg::RBC_Communicat ion_T | |
| train2trackStatus | BG_Types_Pkg::TrainT oTrackStatus_T | |
| linkingInfoUsed | ProvidePositionReport_ Pkg::LinkingInfoUsedO nBoard | |

Table 333: Outputs of EvaluateTriggerAndEvents

| Name | Type | Comments and Information |
|---------|------|--------------------------|
| trigger | bool | |

16.1.12.3. Operator Hierarchy

diagram : diagram_EvaluateTriggerAndEvents_1

16.1.12.4. Graphical and Textual Diagrams

16.1.12.4.1. View of diagram_EvaluateTriggerAndEvents_1 (EvaluateTriggerAndEvents)

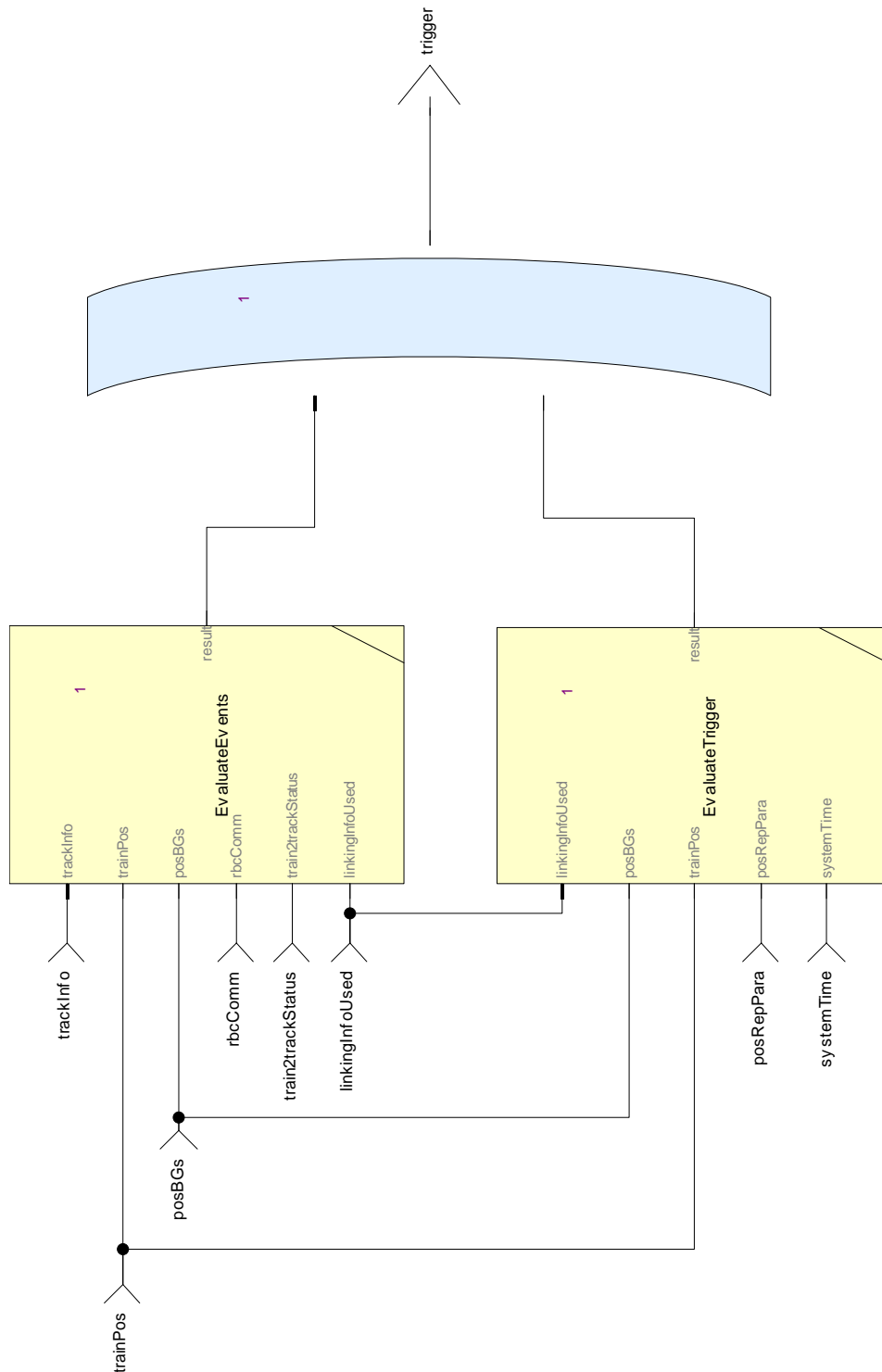


Figure 127: View of diagram_EvaluateTriggerAndEvents_1 (EvaluateTriggerAndEvents)

16.1.13. op_3_6_5_1_4_a_i Operator

Declared as **public node**

16.1.13.1. Comments and Information

op_3_6_5_1_4_a_i Comments:

- Models events as listed in 3.6.5.1.4 a) and i),

16.1.13.2. Interface

Table 334: Inputs of op_3_6_5_1_4_a_i

| Name | Type | Properties | | Comments and Information |
|----------|--|------------|----------------|--------------------------|
| trainPos | TrainPosition_Types_Pc k::trainPosition_T | last | cTrainPosition | |

Table 335: Outputs of op_3_6_5_1_4_a_i

| Name | Type | Comments and Information |
|------|------|--------------------------|
| b | bool | |

16.1.13.3. Operator Hierarchy

diagram : diagram_op_3_6_5_1_4_a_i_1

16.1.13.4. Graphical and Textual Diagrams

16.1.13.4.1. View of diagram_op_3_6_5_1_4_a_i_1 (op_3_6_5_1_4_a_i)

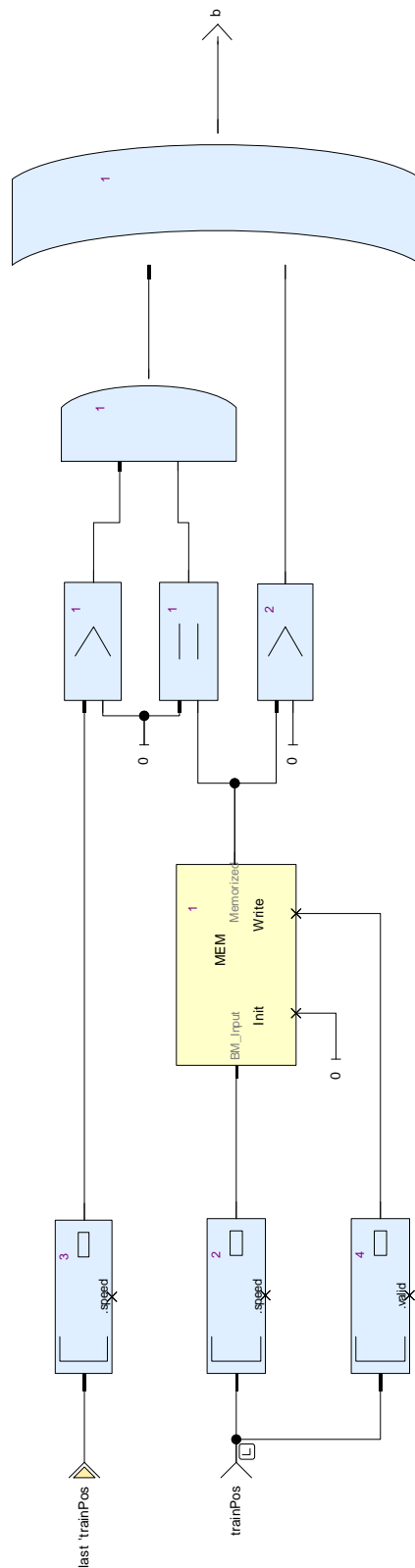


Figure 128: View of diagram_op_3_6_5_1_4_a_i_1 (op_3_6_5_1_4_a_i)

16.1.14. op_3_6_5_1_4_b Operator

Declared as **public node**

16.1.14.1. Comments and Information

op_3_6_5_1_4_b Comments:

- Models event as listed in 3.6.5.1.4 b),

16.1.14.2. Interface

Table 336: Inputs of op_3_6_5_1_4_b

| Name | Type | Properties | | Comments and Information |
|-------------------|------------------------------------|------------|--------------------|--------------------------|
| train2trackStatus | BG_Types_Pkg::TrainToTrackStatus_T | last | cTrack2TrainStatus | |

Table 337: Outputs of op_3_6_5_1_4_b

| Name | Type | Comments and Information |
|------|------|--------------------------|
| b | bool | |

16.1.14.3. Operator Hierarchy

diagram : diagram_op_3_6_5_1_4_b_1

16.1.14.4. Graphical and Textual Diagrams

16.1.14.4.1. View of diagram_op_3_6_5_1_4_b_1 (op_3_6_5_1_4_b)

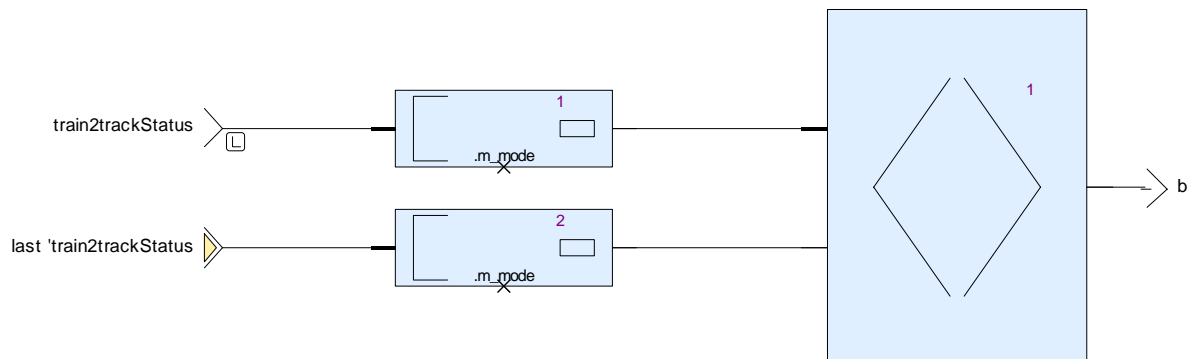


Figure 129: View of diagram_op_3_6_5_1_4_b_1 (op_3_6_5_1_4_b)

16.1.15. op_3_6_5_1_4_c_d Operator

Declared as **public function**

16.1.15.1. Comments and Information

op_3_6_5_1_4_c_d Comments:

- Models events as listed in 3.6.5.1.4 c) and d),

16.1.15.2. Interface

Table 338: Inputs of op_3_6_5_1_4_c_d

| Name | Type | Comments and Information |
|-------------------|--|--------------------------|
| train2trackStatus | BG_Types_Pkg::TrainT oTrackStatus_T | |

Table 339: Outputs of op_3_6_5_1_4_c_d

| Name | Type | Comments and Information |
|------|------|--------------------------|
| b | bool | |

16.1.15.3. Operator Hierarchy

diagram : diagram_op_3_6_5_1_4_c_d_1

16.1.15.4. Graphical and Textual Diagrams

16.1.15.4.1. View of diagram_op_3_6_5_1_4_c_d_1 (op_3_6_5_1_4_c_d)

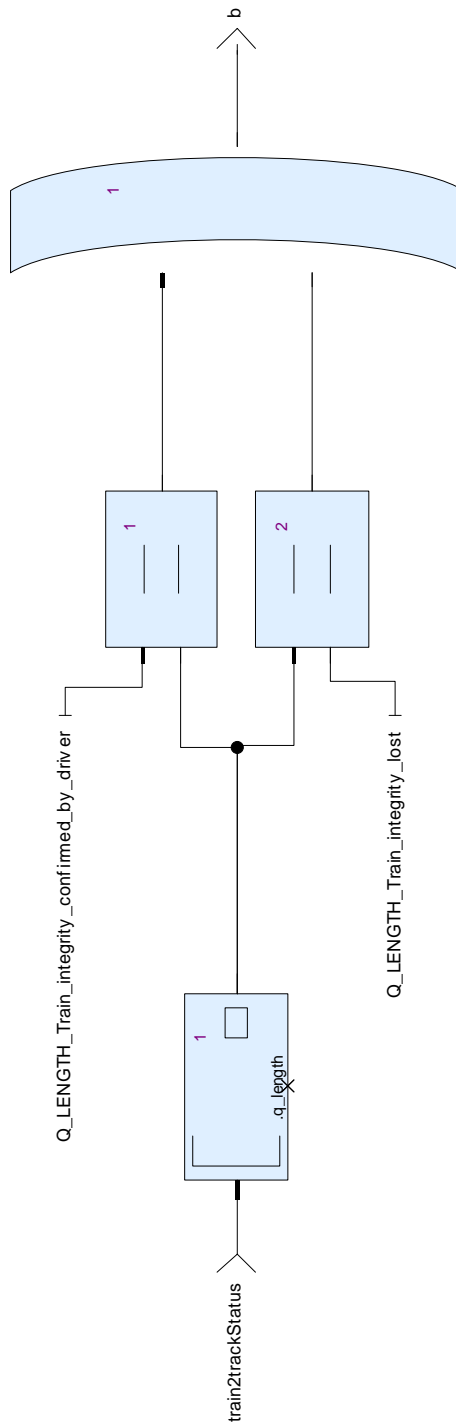


Figure 130: View of diagram_op_3_6_5_1_4_c_d_1 (op_3_6_5_1_4_c_d)

16.1.16. op_3_6_5_1_4_e_f_h_k Operator

Declared as **public function**

16.1.16.1. Comments and Information

op_3_6_5_1_4_e_f_h_k Comments:

- Models events as listed in 3.6.5.1.4 e), f), h) and k),

16.1.16.2. Interface

Table 340: Inputs of op_3_6_5_1_4_e_f_h_k

| Name | Type | Comments and Information |
|-----------|--|--------------------------|
| trackInfo | ProvidePositionReport_ Pkg::TrackInfo_T | |
| rbcComm | ProvidePositionReport_ Pkg::RBC_Communicat ion_T | |

Table 341: Outputs of op_3_6_5_1_4_e_f_h_k

| Name | Type | Comments and Information |
|------|------|--------------------------|
| b | bool | |

16.1.16.3. Operator Hierarchy

diagram : diagram_op_3_6_5_1_4_e_f_h_k_1

16.1.16.4. Graphical and Textual Diagrams

16.1.16.4.1. View of diagram_op_3_6_5_1_4_e_f_h_k_1 (op_3_6_5_1_4_e_f_h_k)

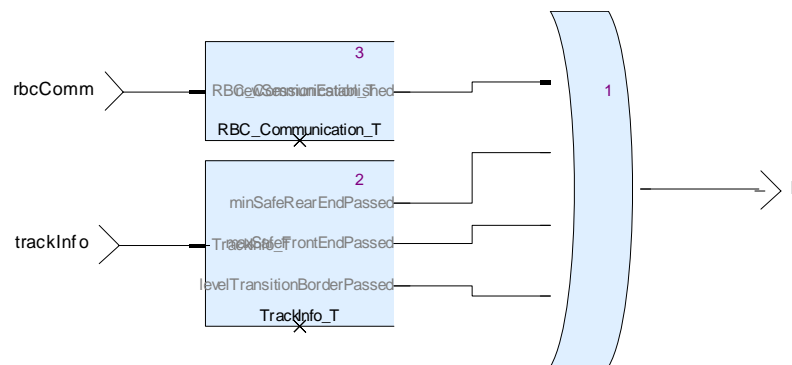


Figure 131: View of diagram_op_3_6_5_1_4_e_f_h_k_1 (op_3_6_5_1_4_e_f_h_k)

16.1.17. op_3_6_5_1_4_g Operator

Declared as **public node**

16.1.17.1. Comments and Information

op_3_6_5_1_4_g Comments:

- Models the event as listed in 3.6.5.1.4 g),

16.1.17.2. Interface

Table 342: Inputs of op_3_6_5_1_4_g

| Name | Type | Properties | | Comments and Information |
|-------------------|--|------------|------------------------|--------------------------|
| train2trackStatus | BG_Types_Pkg::TrainT oTrackStatus_T | last | cTrack2Train Status | |

Table 343: Outputs of op_3_6_5_1_4_g

| Name | Type | Comments and Information |
|------|------|--------------------------|
| b | bool | |

16.1.17.3. Operator Hierarchy

diagram : diagram_op_3_6_5_1_4_g_1

16.1.17.4. Graphical and Textual Diagrams

16.1.17.4.1. View of diagram_op_3_6_5_1_4_g_1 (op_3_6_5_1_4_g)

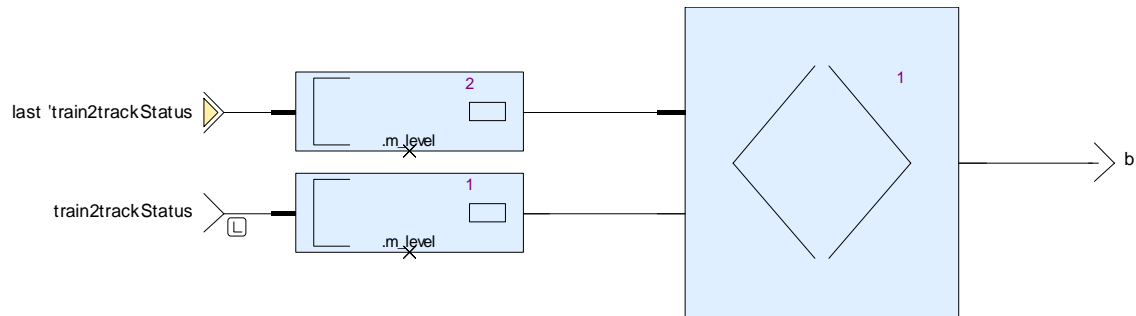


Figure 132: View of diagram_op_3_6_5_1_4_g_1 (op_3_6_5_1_4_g)

16.1.18. op_3_6_5_1_4_j Operator

Declared as **public function**

16.1.18.1. Comments and Information

op_3_6_5_1_4_j Comments:

- Models the event as listed in 3.6.5.1.4 j),
- A balise group is compliant according to the definition in 3.6.2.2.2.a

16.1.18.2. Interface

Table 344: Inputs of op_3_6_5_1_4_j

| Name | Type | Comments and Information |
|-----------------|---|--------------------------|
| LRBG | TrainPosition_Types_Pck::positionedBG_T | |
| linkingInfoUsed | ProvidePositionReport_Pkg::LinkingInfoUsedOnBoard | |

Table 345: Outputs of op_3_6_5_1_4_j

| Name | Type | Comments and Information |
|------|------|--------------------------|
| b | bool | |

16.1.18.3. Operator Hierarchy

diagram : diagram_op_3_6_5_1_4_j_1

16.1.18.4.1. View of diagram_op_3_6_5_1_4_j_1 (op_3_6_5_1_4_j)

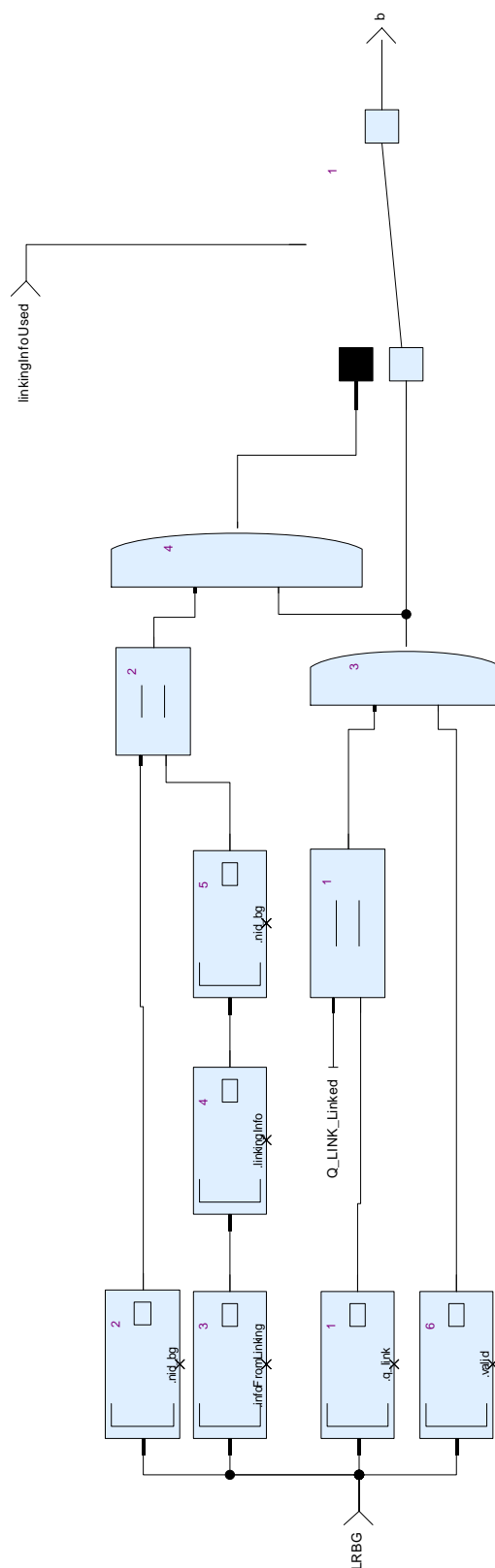


Figure 133: View of diagram_op_3_6_5_1_4_j_1 (op_3_6_5_1_4_j)

16.1.19. op_D_cycloc Operator

Declared as **public node**

16.1.19.1. Comments and Information

op_D_cycloc Comments:

- Models parameter D_CYCLOC that specifies a distance between two position reports.
- The model:
 - - Mem1 stores the value of D_CYCLOC
 - - Mem2 stores the position relative to interval given by D_CYCLOC when the last report has been sent.
 - If the clock is too slow and D_CYCLOC too small, too few reports will be sent.
 - A value is written into Mem2:
 - - if present \wedge D_CYCLOC \neq 32766 \wedge valid \wedge \neq unknownPosition
 - \wedge in_state_SimpleCase then write trainPosition into Mem2
 - (i.e., at the occurrence of a new PositionReportParameter, the current train position is written into Mem2)
 - - if \neg present \wedge D_CYCLOC \neq 32766 \wedge valid \wedge \neq unknownPosition \wedge trainPosition \geq currDistance + D_CYCLOC \wedge in_state_SimpleCase, then write currDistance + D_CYCLOC into Mem2
 - (i.e., if the train has passed the next level of the interval--currDistance + D_CYCLOC--increment currDistance by D_CYCLOC)
 - - if \neg present \wedge D_CYCLOC \neq 32766 \wedge valid \wedge \neq unknownPosition \wedge in_state_Intermediate, then write trainPosition into Mem2
 - (i.e., the first time we have a trainPosition after a PositionReportParameter has been received, we initialize Mem2 with trainPosition)
 - From these three conditions, we derive the following condition when Mem2 must be written:
 - - D_CYCLOC \neq 32766 \wedge valid \wedge \neq unknownPosition \wedge \neg in_state_SpecialCase
 - \wedge trainPosition \geq input(Mem2) (i.e., we only write currDistance + D_CYCLOC into Mem2 iff it is \leq the trainPosition))

16.1.19.2. Interface

Table 346: Inputs of op_D_cycloc

| Name | Type | Comments and Information |
|----------|--|--------------------------|
| pRepPara | ProvidePositionReport_Pkg::PositionReportParameter_T | |
| trainPos | TrainPosition_Types_Pkg::trainPosition_T | |

Table 347: Outputs of op_D_cycloc

| Name | Type | Comments and Information |
|------|------|--------------------------|
| b | bool | |

16.1.19.3. Locals

Table 348: Locals of op_D_cycloc

| Name | Type | Properties | | Comments and Information |
|---------------------|------|------------|-------|--------------------------|
| currTriggerDistance | int | last | 0 | |
| intermediate | bool | default | false | |
| mem2Locked | bool | default | false | |
| presentReport | bool | | | |
| validPositionData | bool | | | |

16.1.19.4. Operator Hierarchy

diagram : diagram_op_D_cycloc_1

state-machine : SM1

state : Init

state : Intermediate

state : SimpleCase

state : SpecialCase

16.1.19.5. Graphical and Textual Diagrams

16.1.19.5.1. View of diagram_op_D_cycloc_1 (op_D_cycloc)

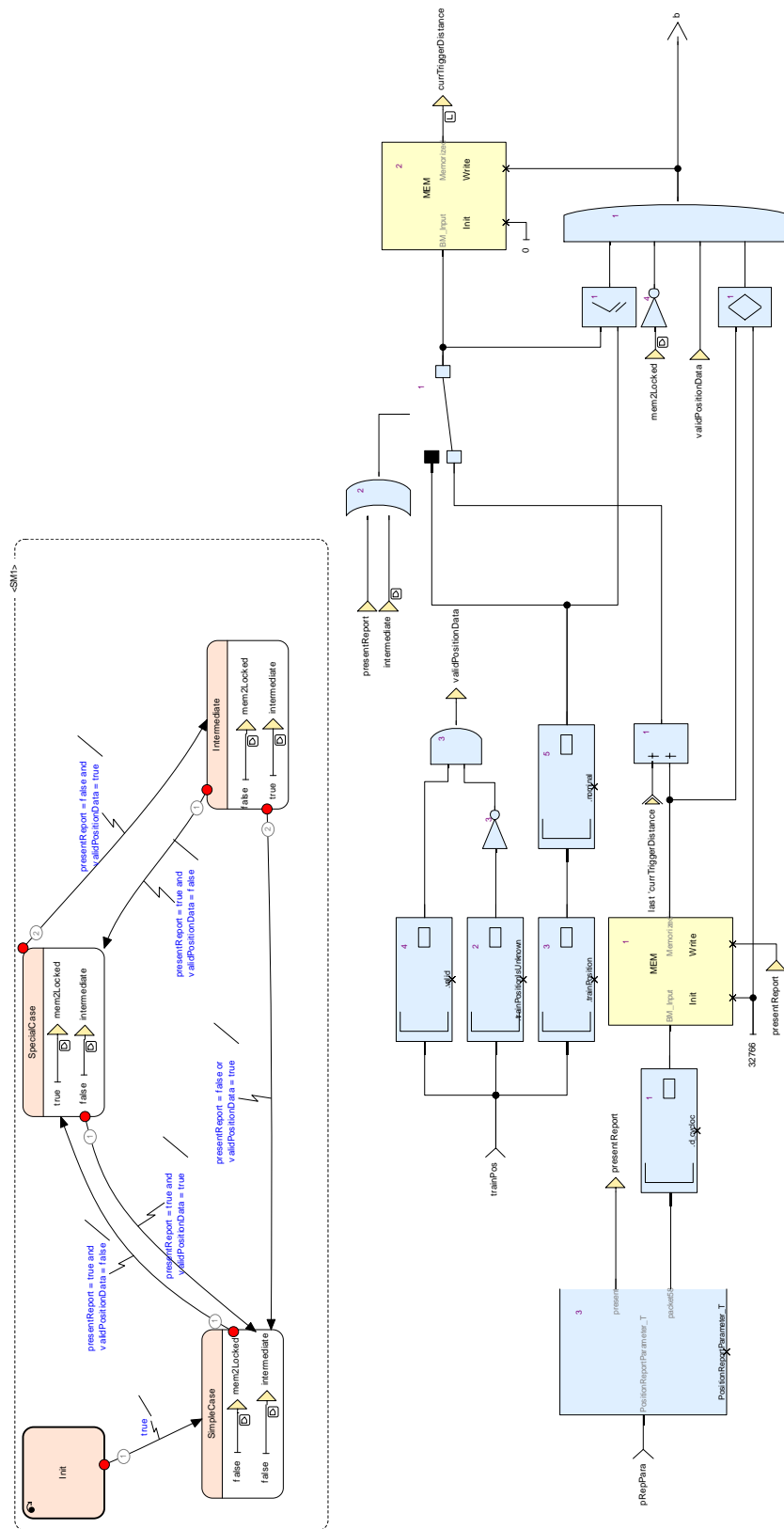


Figure 134: View of diagram_op_D_cycloc_1 (op_D_cycloc)

Table 349: State Machines of diagram_op_D_cycloc_1

| State Machine | Comments and Information |
|---------------|--------------------------|
| SM1 | |

Table 350: States of diagram_op_D_cycloc_1

| State | Comments and Information |
|-------------------|--------------------------|
| SM1: Init | |
| SM1: Intermediate | |
| SM1: SimpleCase | |
| SM1: SpecialCase | |

Table 351: Transitions of diagram_op_D_cycloc_1

| Source/Target | # | Conditions/Actions | Comments and Information |
|---|---|--|--------------------------|
| Source: SM1: Init Target: SM1: SimpleCase | 1 | Condition: true | |
| Source: SM1: Intermediate Target: SM1: SpecialCase | 1 | Condition: presentReport = true and validPositionData = false | |
| Source: SM1: Intermediate Target: SM1: SimpleCase | 2 | Condition: presentReport = false or validPositionData = true | |
| Source: SM1: SimpleCase Target: SM1: SpecialCase | 1 | Condition: presentReport = true and validPositionData = false | |
| Source: SM1: SpecialCase Target: SM1: SimpleCase | 1 | Condition: presentReport = true and validPositionData = true | |
| Source: SM1: SpecialCase Target: SM1: Intermediate | 2 | Condition: presentReport = false and validPositionData = true | |

16.1.20. op_DOUBTOVER Operator

Declared as **public function**

16.1.20.1. Comments and Information

op_DOUBTOVER Comments:

- Calculates L_DOUBTOVER = absolute(estimated front end - min safe front end)

16.1.20.2. Interface

Table 352: Inputs of op_DOUBTOVER

| Name | Type | Comments and Information |
|----------|--|--------------------------|
| trainPos | TrainPosition_Types_Pc k::trainPosition_T | |

Table 353: Outputs of op_DOUBTOVER

| Name | Type | Comments and Information |
|-------------|-------------|--------------------------|
| I_doubtover | L_DOUBTOVER | |

16.1.20.3. Operator Hierarchy

diagram : diagram_op_DOUBTOVER_1

16.1.20.4. Graphical and Textual Diagrams

16.1.20.4.1. View of diagram_op_DOUBTOVER_1 (op_DOUBTOVER)

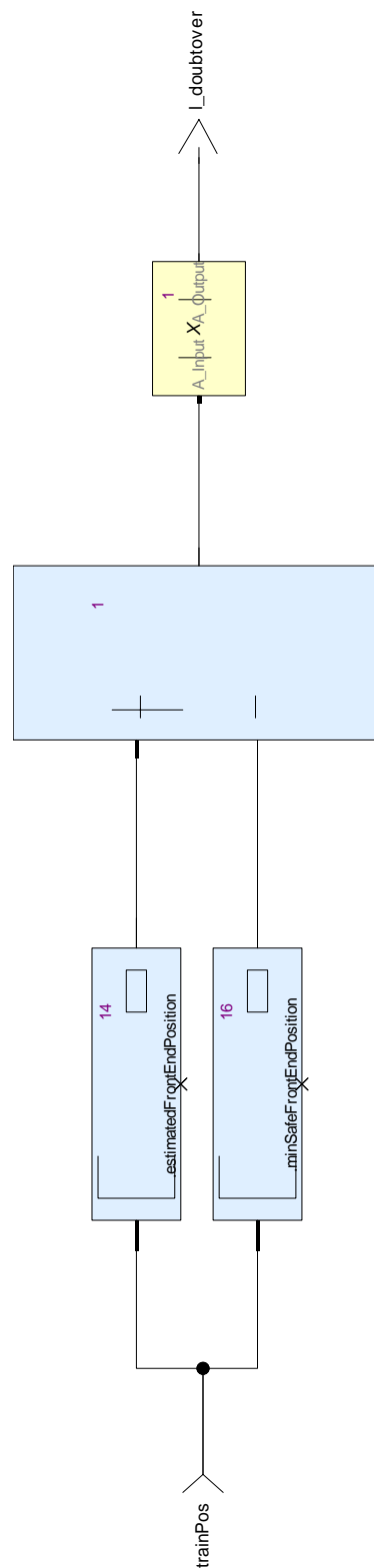


Figure 135: View of diagram_op_DOUBTOVER_1 (op_DOUBTOVER)

16.1.21. op_DOUBTUNDER Operator

Declared as **public function**

16.1.21.1. Comments and Information

op_DOUBTUNDER Comments:

- Calculates $L_DOUBTUNDER = \text{absolute}(\text{max safe front end} - \text{estimated front end})$

16.1.21.2. Interface

Table 354: Inputs of op_DOUBTUNDER

| Name | Type | Comments and Information |
|----------|--|--------------------------|
| trainPos | TrainPosition_Types_Pc k::trainPosition_T | |

Table 355: Outputs of op_DOUBTUNDER

| Name | Type | Comments and Information |
|--------------|--------------|--------------------------|
| l_doubtunder | L_DOUBTUNDER | |

16.1.21.3. Operator Hierarchy

diagram : diagram_op_DOUBTUNDER_1

16.1.21.4. Graphical and Textual Diagrams

16.1.21.4.1. View of diagram_op_DOUBTUNDER_1 (op_DOUBTUNDER)

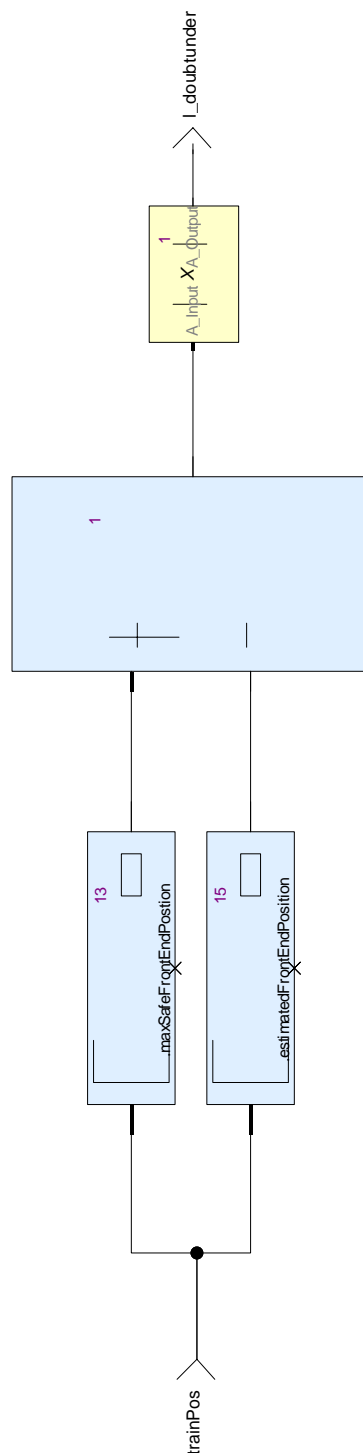


Figure 136: View of diagram_op_DOUBTUNDER_1 (op_DOUBTUNDER)

16.1.22. op_LRBG Operator

Declared as **public function**

16.1.22.1. Comments and Information

op_LRBG Comments:

- If input data are validate, then $D_LRBG = |\text{nominal}(\text{trainPosition}) - \text{nominal}(\text{BG_location})|$;
- otherwise unknown is assigned to D_LRBG

16.1.22.2. Interface

Table 356: Inputs of op_LRBG

| Name | Type | Comments and Information |
|----------|--|--------------------------|
| posBG | TrainPosition_Types_Pc k::positionedBG_T | |
| trainPos | TrainPosition_Types_Pc k::trainPosition_T | |

Table 357: Outputs of op_LRBG

| Name | Type | Comments and Information |
|--------|------|--------------------------|
| d_lrbg | int | |

16.1.22.3. Operator Hierarchy

diagram : diagram_op_LRBG_1

16.1.22.4. Graphical and Textual Diagrams

16.1.22.4.1. View of diagram_op_LRBG_1 (op_LRBG)

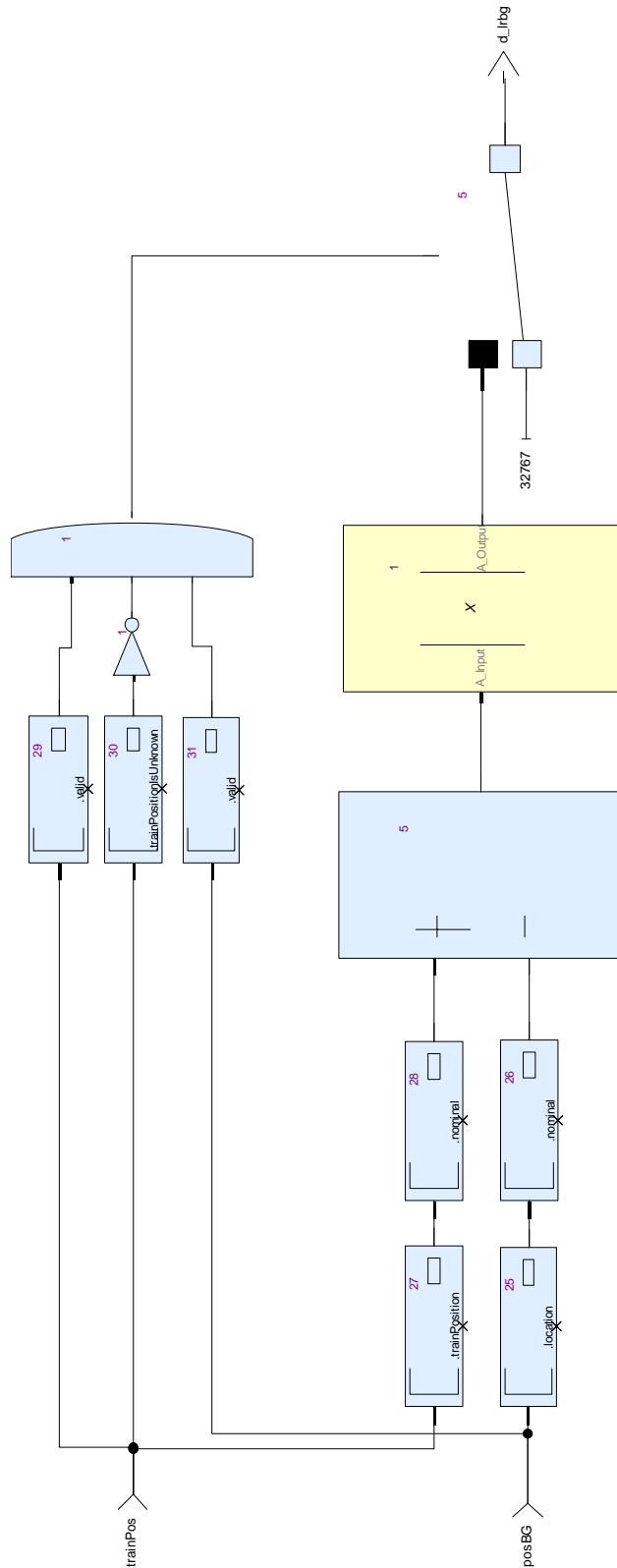


Figure 137: View of diagram_op_LRBG_1 (op_LRBG)

16.1.23. op_M_loc Operator

Declared as **public node**

16.1.23.1. Comments and Information

op_M_loc Comments:

- Models trigger based on parameter M_LOC; that is, locations and situations
- where the train has to report its position.

16.1.23.2. Interface

Table 358: Inputs of op_M_loc

| Name | Type | Comments and Information |
|-----------------|--|--------------------------|
| pRepPara | ProvidePositionReport_ Pkg::PositionReportPar ameter_T | |
| posBGs | TrainPosition_Types_Pc k::positionedBG_T | |
| linkingInfoUsed | ProvidePositionReport_ Pkg::LinkingInfoUsedO nBoard | |

Table 359: Outputs of op_M_loc

| Name | Type | Comments and Information |
|------|------|--------------------------|
| b | bool | |

16.1.23.3. Operator Hierarchy

diagram : diagram_op_M_loc_1

16.1.23.4.1. View of diagram_op_M_loc_1 (op_M_loc)

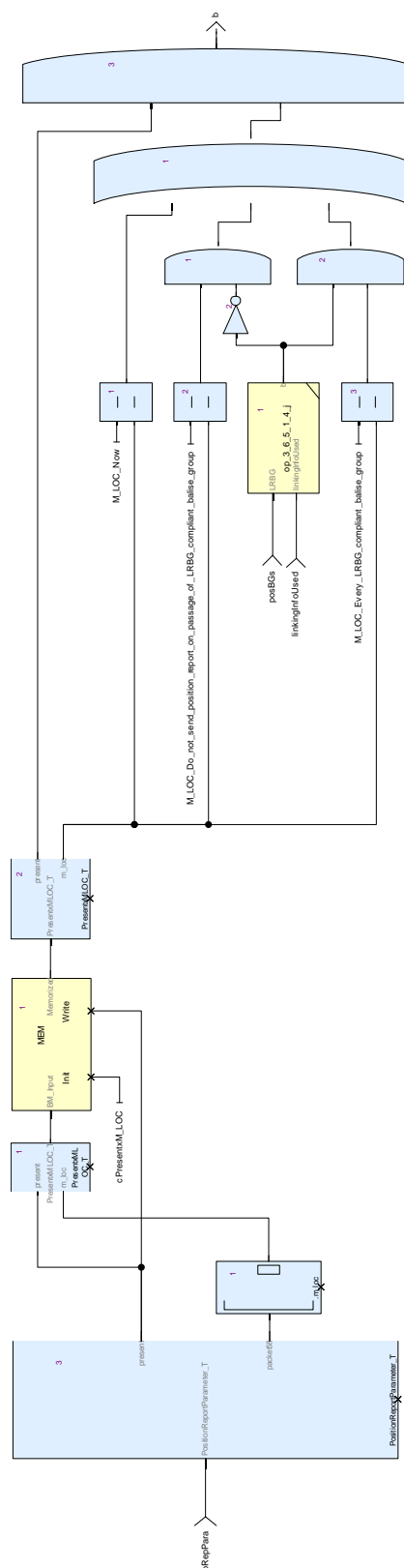


Figure 138: View of diagram_op_M_loc_1 (op_M_loc)

16.1.24. op_N_iter Operator

Declared as **public function**

16.1.24.1. Interface

Table 360: Inputs of op_N_iter

| Name | Type | Comments and Information |
|---------------|--|--------------------------|
| trainPosition | TrainPosition_Types_Pck::trainPosition_T | |
| pRepPara | ProvidePositionReport_Pkg::PositionReportParameter_T | |

Table 361: Outputs of op_N_iter

| Name | Type | Comments and Information |
|------|------|--------------------------|
| b | bool | |

16.1.24.2. Operator Hierarchy

diagram : diagram_op_N_iter_1

16.1.24.3. Graphical and Textual Diagrams

16.1.24.3.1. View of diagram_op_N_iter_1 (op_N_iter)



Figure 139: View of diagram_op_N_iter_1 (op_N_iter)

16.1.25. op_prepack_0 Operator

Declared as **public function**

16.1.25.1. Interface

Table 362: Inputs of op_prepack_0

| Name | Type | Comments and Information |
|-------------------|--|--------------------------|
| TrainRearEndPos3 | L_TRAININT | |
| trainPos | TrainPosition_Types_Pck::trainPosition_T | |
| train2trackStatus | BG_Types_Pkg::TrainToTrackStatus_T | |
| posBGs | TrainPosition_Types_Pck::positionedBG_T | |

Table 363: Outputs of op_prepack_0

| Name | Type | Comments and Information |
|--------|-------------------------------|--------------------------|
| valid | bool | |
| posRep | TrainToTrack::Position_Report | |

16.1.25.2. Operator Hierarchy

diagram : diagram_op_prepack_0_1

16.1.25.3. Graphical and Textual Diagrams

16.1.25.3.1. View of diagram_op_prepack_0_1 (op_prepack_0)

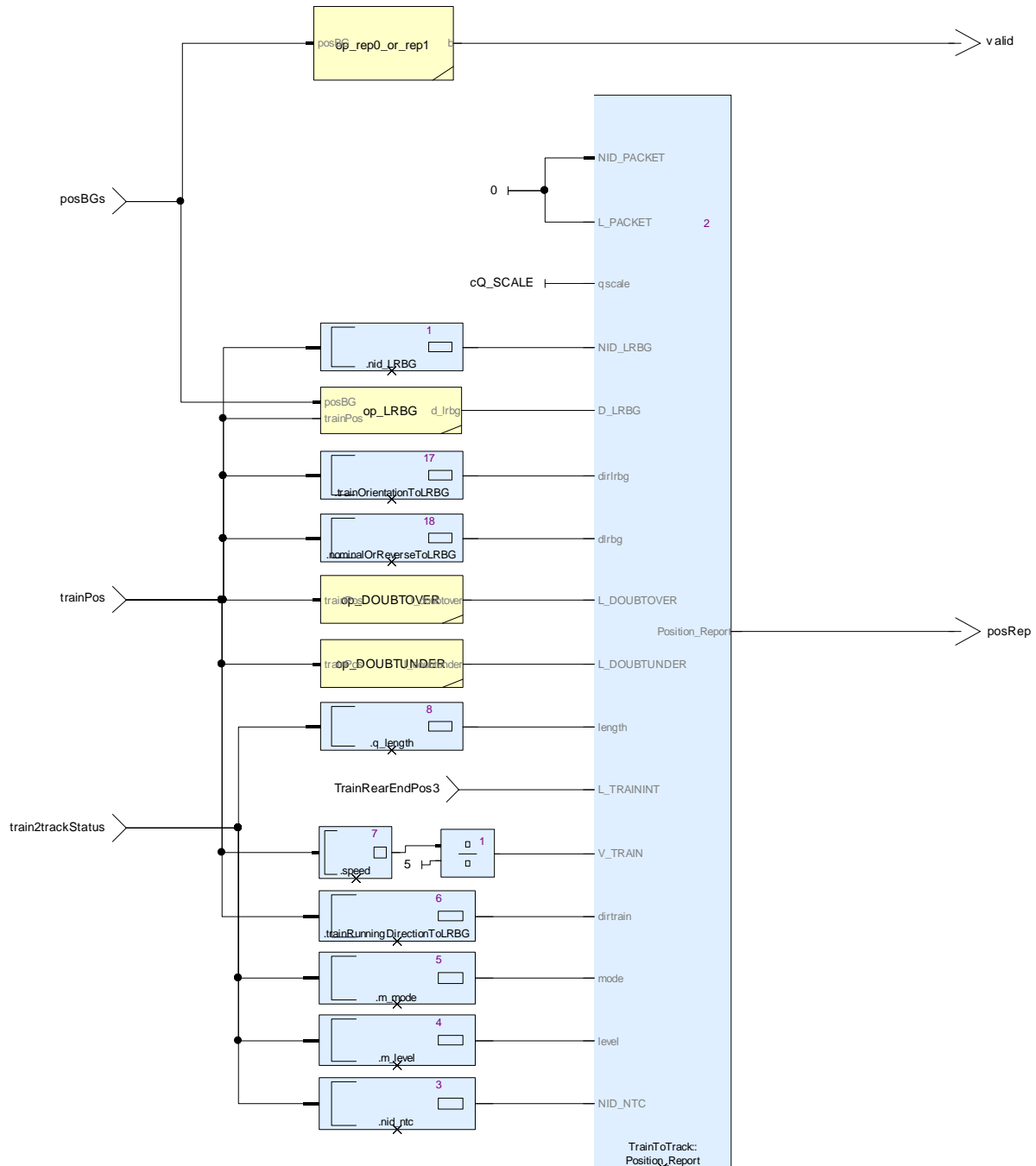


Figure 140: View of diagram_op_prepack_0_1 (op_prepack_0)

16.1.26. op_rep0_or_rep1 Operator

Declared as **public function**

16.1.26.1. Comments and Information

op_rep0_or_rep1 Comments:

- returns true if packet 0 has to be contained in the position report and false if packet 1 has to be contained.
- Decision based on 3.6.2.2.2.a; currently only 3.6.2.2.2.a.i is modeled.

16.1.26.2. Interface

Table 364: Inputs of op_rep0_or_rep1

| Name | Type | Comments and Information |
|-------|---|--------------------------|
| posBG | TrainPosition_Types_Pc k::positionedBG_T | |

Table 365: Outputs of op_rep0_or_rep1

| Name | Type | Comments and Information |
|------|------|--------------------------|
| b | bool | |

16.1.26.3. Operator Hierarchy

diagram : diagram_op_rep0_or_rep1_1

16.1.26.4. Graphical and Textual Diagrams

16.1.26.4.1. View of diagram_op_rep0_or_rep1_1 (op_rep0_or_rep1)

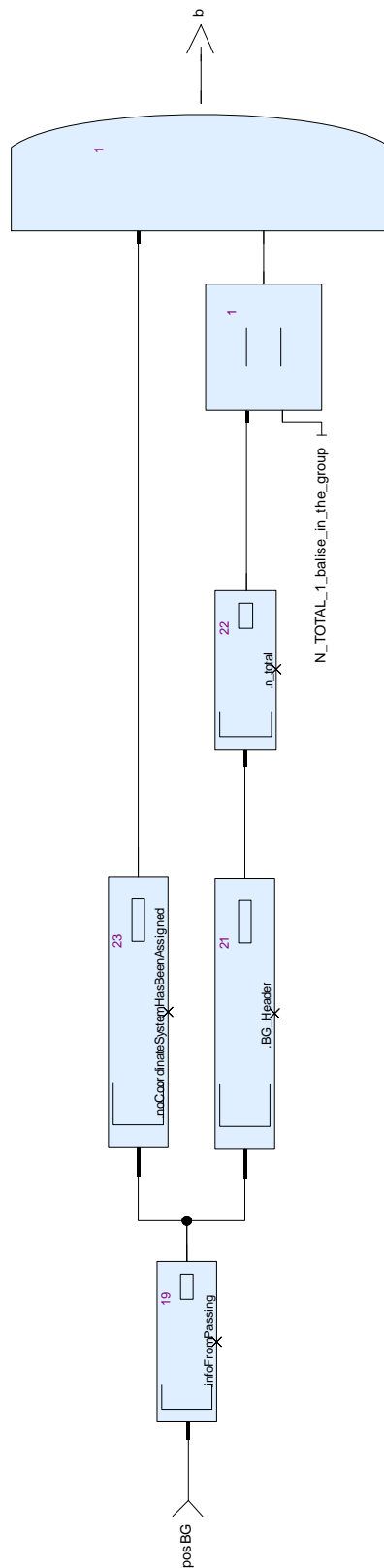


Figure 141: View of diagram_op_rep0_or_rep1_1 (op_rep0_or_rep1)

16.1.27. op_T_cycloc Operator

Declared as **public node**

16.1.27.1. Comments and Information

op_T_cycloc Comments:

- Models parameter T_CYCLOC which specifies a time interval
- between two position reports to be sent
- Output is equal to $T_CYCLOC < 255 \text{ AND } (\text{present or last local1} + T_CYCLOC)$
- This implies that the output is true when a valid posRepPara appears.
- If present = true, then we store the current time in the memory; otherwise, the stored value is incremented by
- T_CYCLOC.

16.1.27.2. Interface

Table 366: Inputs of op_T_cycloc

| Name | Type | Comments and Information |
|------------|--|--------------------------|
| pRepPara | ProvidePositionReport_ Pkg::PositionReportParameter_T | |
| systemTime | ProvidePositionReport_ Pkg::SystemTime_T | |

Table 367: Outputs of op_T_cycloc

| Name | Type | Comments and Information |
|------|------|--------------------------|
| b | bool | |

16.1.27.3. Locals

Table 368: Locals of op_T_cycloc

| Name | Type | Properties | | Comments and Information |
|--------|------|------------|---|--------------------------|
| Local1 | int | last | 0 | |

16.1.27.4. Operator Hierarchy

diagram : diagram_op_T_cycloc_1

16.1.27.5. Graphical and Textual Diagrams

16.1.27.5.1. View of diagram_op_T_cycloc_1 (op_T_cycloc)

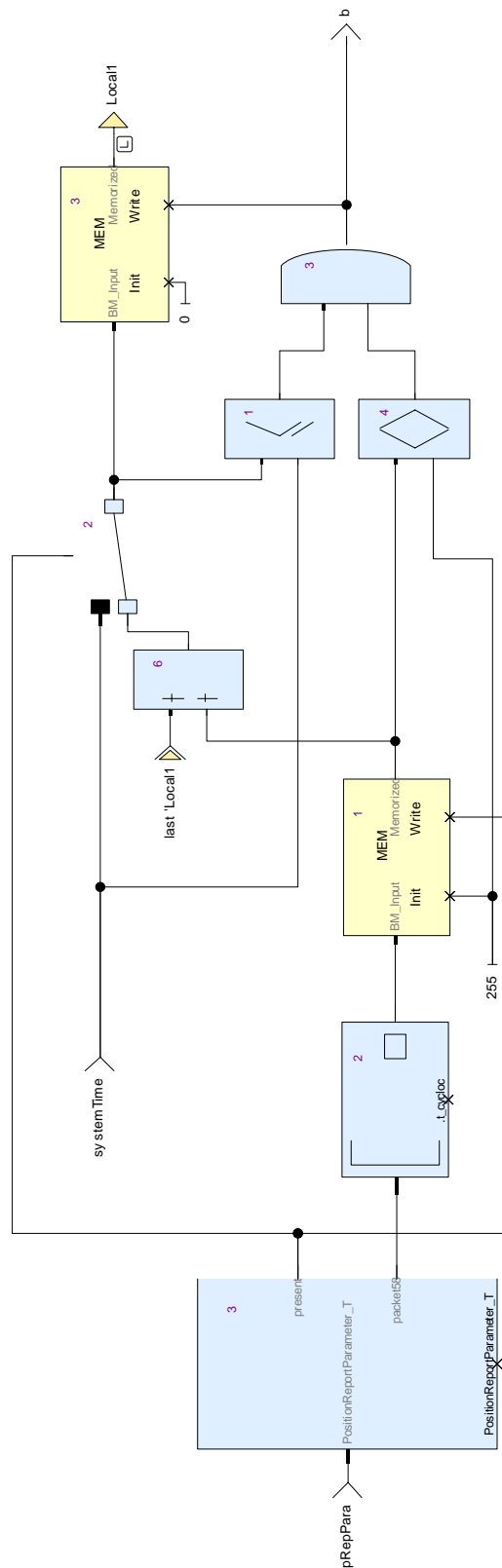


Figure 142: View of diagram_op_T_cycloc_1 (op_T_cycloc)

16.1.28. ProvidePositionReport Operator

Declared as **public node**

16.1.28.1. Comments and Information

ProvidePositionReport Comments:

- Assumption: BGs in PositionedBGs_T are ordered with the last seen BG being the first element of the array.

16.1.28.2. Interface

Table 369: Inputs of ProvidePositionReport

| Name | Type | Comments and Information |
|-------------------|--|--------------------------|
| posBGs | TrainPosition_Types_Pkg::positionedBGs_T | |
| trainPos | TrainPosition_Types_Pkg::trainPosition_T | |
| trainProps | TrainPosition_Types_Pkg::trainProperties_T | |
| errorMsg | ProvidePositionReport_Pkg::ErrorMessage_T | |
| trackInfo | ProvidePositionReport_Pkg::TrackInfo_T | |
| posRepPara | ProvidePositionReport_Pkg::PositionReportParameter_T | |
| systemTime | ProvidePositionReport_Pkg::SystemTime_T | |
| rcbComm | ProvidePositionReport_Pkg::RBC_Communication_T | |
| train2trackStatus | BG_Types_Pkg::TrainToTrackStatus_T | |
| linkingInfoUsed | ProvidePositionReport_Pkg::LinkingInfoUsedOnBoard | |

Table 370: Outputs of ProvidePositionReport

| Name | Type | Comments and Information |
|--------|---|--------------------------|
| posRep | ProvidePositionReport_Pkg::PositionReport_T | |

16.1.28.3. Operator Hierarchy

diagram : diagram_ProvidePositionReport_1

16.1.28.4. Graphical and Textual Diagrams

16.1.28.4.1. View of diagram_ProvidePositionReport_1 (ProvidePositionReport)

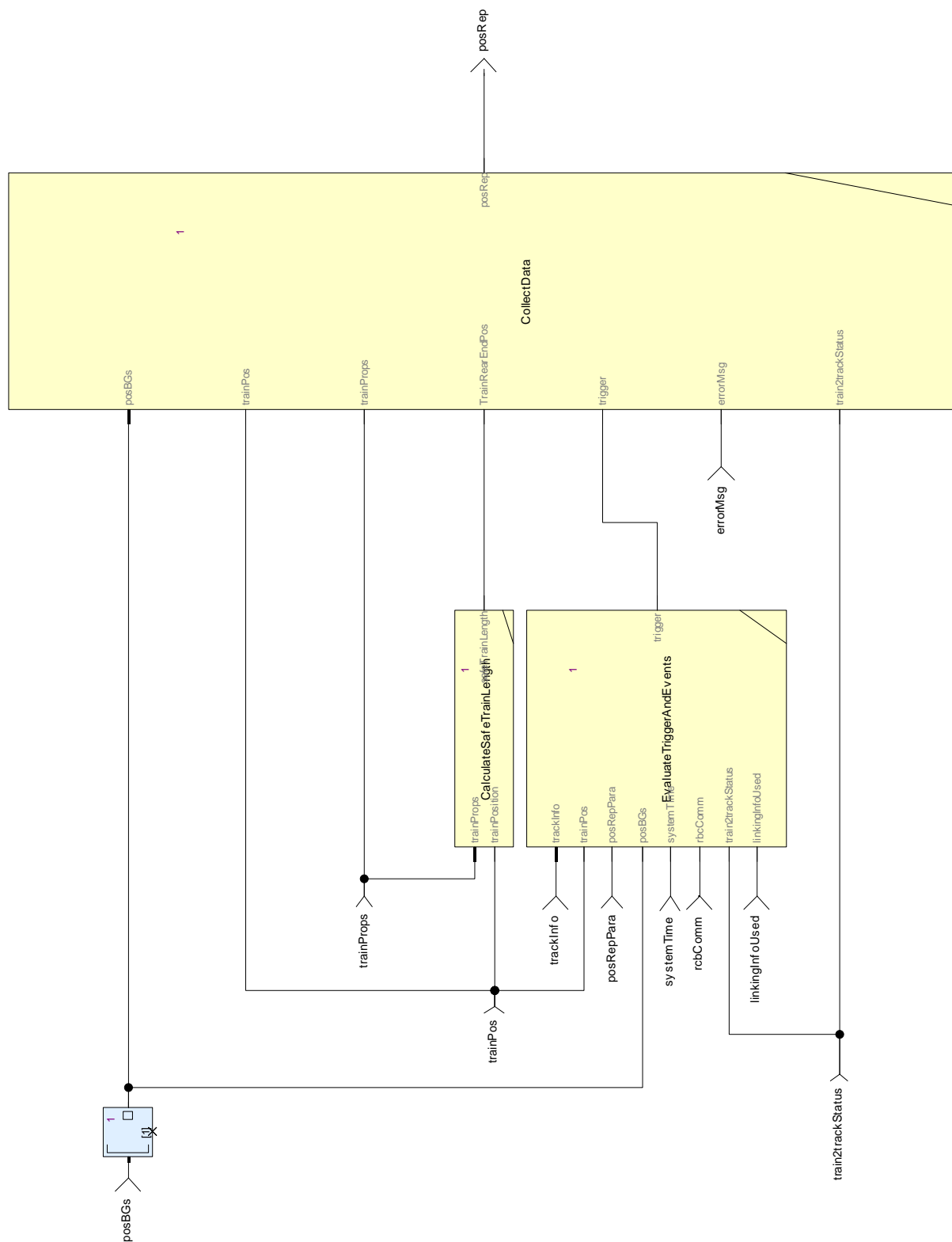


Figure 143: View of diagram_ProvidePositionReport_1 (ProvidePositionReport)

17. Project Library: ValidateDataDirection

17.1. ValidateDataDirection_Pkg Package

17.1.1. validateDataDirection Operator

Declared as **public function**

17.1.1.1. Interface

Table 371: Inputs of validateDataDirection

| Name | Type | Comments and Information |
|---------------|--|--|
| passedBG_in | BG_Types_Pkg::passedBG_T | Comments: Input event reporting a balise group during its passage, if there is one. |
| LRBG | TrainPosition_Types_Pkg::positionedBG_T | Comments: The LRBG used for RBC communication. |
| trainPosition | TrainPosition_Types_Pkg::trainPosition_T | Comments: The resulting train position with reference to the LRBG |

Table 372: Outputs of validateDataDirection

| Name | Type | Comments and Information |
|--------------|--------------------------|--|
| passedBG_out | BG_Types_Pkg::passedBG_T | Comments: Input event reporting a balise group during its passage, if there is one. |

17.1.1.2. Operator Hierarchy

diagram : diagram_validateDataDirection_1

17.1.1.3. Graphical and Textual Diagrams

17.1.1.3.1. View of diagram_validateDataDirection_1 (validateDataDirection)

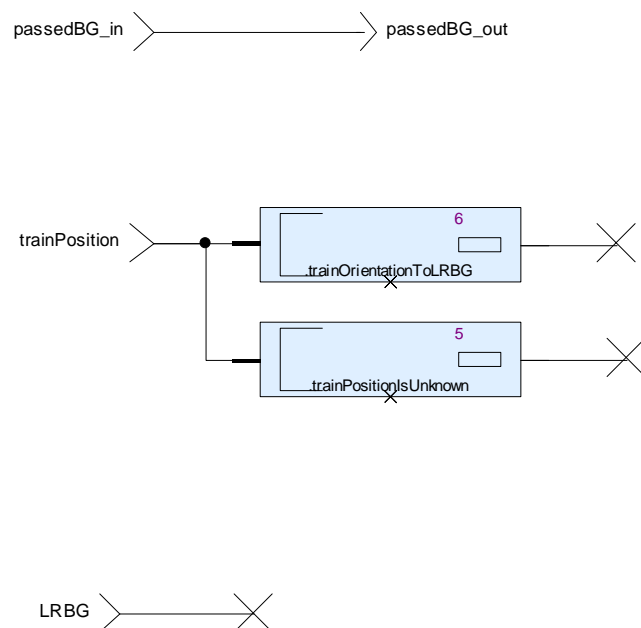


Figure 144: View of diagram_validateDataDirection_1 (validateDataDirection)

End of document.

