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1. General Project Description

<description>

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2. Software Architecture

2.1. Project Architecture

This section displays the package hierarchy of projects.

Project Level_And_Mode_Types Level_And_Mode_Types_Pkg **Ref. Nr.:** <reference number> **Issue Nr.:** <issue number> **Page:** 6/10

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3. Level_And_Mode_Types Project

3.1. Level_And_Mode_Types_Pkg Package

3.1.1. Types

Table 1: Public Types of Level_And_Mode_Types_Pkg

Name	Definition	Comments and Information	
T_Data_From_DMI	{Ack_LS: bool, Ack_OS: bool, Ack_RV: bool, Ack_SH: bool, Ack_SN: bool, Ack_TR: bool, Ack_UN: bool, Req_Exit_SH: bool, Req_NL: bool, Req_Start: bool, ETCS_Isolated: bool}	Comments: Input Data from DMI needed for Mode Management, they correspond to the acknoledgement from the driver or the request from the driver to change mode	
T_Data_From_F2_funct ions	{Common_Errors: Common_Types_Pkg::MSG_Errors_T, Failure_Occured: bool, Continue_Shunting_Active: bool, Stop_Shunting_Stored: bool}	Comments: Set of data provided by other EVC functions, not identify in early version of the EVC kernel Common_Errors Comments: To computeLinking_Reaction_To_Tri p (Condition 17), T_NV_contact_error (Condition 41), Error_BG_System_Version (Condition 65)	
T_Data_From_Localisat ion	{BG_In_List_Expected_BG_In_SR: bool, BG_In_List_Expected_BG_In_SH: bool, PositionErrors: TrainPosition_Types_Pck::positionErrors_T, Train_Position: TrainPosition_Types_Pck::trainPosition_T, Train_Speed: Obu_BasicTypes_Pkg::Speed_T, Train_Standstill: bool}	Comments: Input Data From Speed and Supervision functions PositionErrors Comments: To compute condition 66, provided by position_errors_T	
T_Data_From_Speed_ Supervision	{Estim_front_End_overpass_SR_Dist : bool, Estim_Front_End_Rear_SSP : bool, Override_Function_Active : bool, EOA_Antenna_Overpass : bool, EOA_Front_End : bool, Train_Speed_Under_Overide_Limit : bool}	Comments: Input Data From Speed and Supervision functions	
T_Data_From_STM	{Interface_To_National_System : bool, National_trip_Order : bool}		

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Name	Definition	Comments and Information
T_Data_From_Track_M ASSPGradient_Availabl e	{P12_received : bool, P15_received : bool, P21_received : bool, P27_received : bool}	Comments: Input Data From TrackSide needed for Mode management: information that speed curve for FS mode can be computed by Speed and Supervision function P12_received Comments: MA in Level 1 has been received and can be used by SSF P15_received Comments: MA in Level 2/3 has been received and can be used by SSF P21_received Comments: Gradient Profile has been received and can be used by SSF P27_received Comments: SSP has been received and can be used by SSF
T_Data_From_Track_M ess	{Mess_15 : bool, Mess_16 : bool, Mess_2 : bool, Mess_27 : bool, Mess_28 : bool, Mess_6 : bool}	Comments: Data received from track side as message (without packets). Type for each message shall be defined explicitely (as packet), at least with NID_LRBG, distance, ID,
T_Data_From_Track_P acket	<pre>{P_12: Packet_Types_Pkg::P12_Level1Move mentAuthorities_T, P_135: Packet_Types_Pkg::P135_StopShunti ngOnDeskOpening_T, P_137: Packet_Types_Pkg::P137_StopIfInSta ffResponsible_T, P_138: Packet_Types_Pkg::P138_ReversingA reaInformation_T, P_139: Packet_Types_Pkg::P139_ReversingS upervisionInformation_T, P_15: Packet_Types_Pkg::P15_Level23Move mentAuthorities_T, P_21: Packet_Types_Pkg::P21_GradientProfi les_T, P_27: Packet_Types_Pkg::P27_International StaticSpeedProfile_T, P_41: Packet_Types_Pkg::P41_LevelTransist ionOrders_T, P_46: Packet_Types_Pkg::P46_ConditionalL evelTransitionOrders_T, P_63: Packet_Types_Pkg::P63_ListofBalisesi nSRAuthority_T, P_80: Packet_Types_Pkg::P80_ModeProfiles _T, LRBG: NID_LRBG, referenceLocation: Obu_BasicTypes_Pkg::Location_T}</pre>	Comments: Input Data From track needed for Mode Management LRBG Comments: LRBG which is the reference for the packets referenceLocation Comments: Position of the LRBG
T_Data_From_Track_T o_Level	{level_transition_priority_table: Level_And_Mode_Types_Pkg::T_Level Transition_PriorityTable, conditionnalTransition: Level_And_Mode_Types_Pkg::T_Level Transition_PriorityTable, receivedL2L3MA_track: bool, receivedL1MA_track: bool}	Comments: Input Data from terrack to Level Management

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Name	Definition	Comments and Information
T_Data_From_Track_T o_Mode	{MA_SSP_Gradient_Available : bool, Mode_Profile_On_Board : Level_And_Mode_Types_Pkg::T_Mode _Profile_Table, Shunting_granted_By_RBC : bool, Trip_Order_Given_By_Balise : bool, List_Bg_Related_To_SR_Empty : bool, Stop_If_In_shunting : bool, Stop_If_In_SR : bool, RBC_Ack_TR_EB_Revocked : bool, RBC_Authorized_SR : bool, Reversing_Data : Level_And_Mode_Types_Pkg::T_Reversing_Data, Emergency_Stop_Message_Received : bool}	Comments: Input Data From track needed for Mode Management
T_Data_To_BG_Manag ement	{EoM_Procedure_req : bool, Clean_BG_List_SH_Area : bool, MA_Req : bool, Req_for_SH_from_Driver : bool, Connection_to_RBC_req : bool, Position_Repport_Needed : bool}	Comments: Output to BG Management or RBC
T_Data_To_DMI	{Ack_LS: bool, Ack_OS: bool, Ack_RV: bool, Ack_SH: bool, Ack_SN: bool, Ack_SR: bool, Ack_TR: bool, Ack_UN: bool, SH_Refused_By_RBC: bool}	Comments: Output to DMI interface
T_ERTMS_capabilities	{NTC : bool, L0 : bool, L1 : bool, L2 : bool, L3 : bool}	
T_LevelTansitionInfo	{level: M_LEVEL, position: M_POSITION, transitionType: Level_And_Mode_Types_Pkg::T_Tran sitionType, immediateAck: bool, AckLength: Obu_BasicTypes_Pkg::Location_T}	"5.10.1.2 A level transition announcement to the ERTMS/ETCS on-board equipment shall consist of an order to execute the level transition at a further location corresponding to the border." Ievel Comments: the level to swtich to position Comments: the position at which to switch transitionType Comments: signals type of transition
T_LevelTransition	{is_set : bool, transition : Level_And_Mode_Types_Pkg::T_Level TansitionInfo, LRBG : NID_LRBG, referenceLocation : Obu_BasicTypes_Pkg::L_internal_Typ e}	
T_LevelTransition_Prior ityTable	Level_And_Mode_Types_Pkg::T_Level Transition ^M_Max_TransitionInPriorityTable	
T_MA	enum {Profile_OS, Profile_LS, Profile_SH, No_Profile}	
T_Mode	enum {NP, SB, PS, SH, FS, LS, SR, OS, SL, NL, UN, TR, PT, SF, IS, SN, RV}	

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Name	Definition	Comments and Information
T_Mode_Level	{compatibleModeAndLevel : bool, level : M_LEVEL, newLevel : bool, Mode : M_MODE, newMode : bool}	
T_Mode_Profile	{Distance: Obu_BasicTypes_Pkg::Location_T, Mode: Level_And_Mode_Types_Pkg::T_MA, Speed: Obu_BasicTypes_Pkg::Speed_T, Length: Obu_BasicTypes_Pkg::Location_T, Length_Ack: Obu_BasicTypes_Pkg::Location_T}	
T_Mode_Profile_Table	Level_And_Mode_Types_Pkg::T_Mode _Profile ^M_Max_ModeProfile	
T_Reversing_Data	{Available : bool, Dist_Start : Obu_BasicTypes_Pkg::Location_T, Length : Obu_BasicTypes_Pkg::Location_T, Dist_Run : Obu_BasicTypes_Pkg::Location_T, Speed : Obu_BasicTypes_Pkg::Speed_T}	
T_TransitionType	<pre>enum {M_TransitionType_Conditional, M_TransitionType_DriverInit, M_TransitionType_Normal}</pre>	

3.1.2. Constants

Table 2: Public Constants of Level_And_Mode_Types_Pkg

Name	Туре	Value	Comments and Information
C_Cycle_Duration	int	300	Comments: 300 millisecond
C_Driver_Ack_Delay	int	5000	Comments: 5 second
C_Immediate_transitio n_order_position	int	32767	
C_NoTrackLevelTransiti on	Level_And_Mode_T ypes_Pkg::T_Data_ From_Track_MASSP Gradient_Available	{P12_received : false, P15_received : false, P21_received : false, P27_received : false}	
M_Default_Transition	Level_And_Mode_T ypes_Pkg::T_LevelT ransition	<pre>{is_set : false, transition : {level : M_LEVEL_Level_0, position : 0, transitionType : M_TransitionType_N ormal, immediateAck : false, AckLength : 0}, LRBG : 0, referenceLocation : 0}</pre>	
M_Max_ModeProfile	int	3	

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Name	Туре	Value	Comments and Information
M_Max_TransitionInPri orityTable	int	7	

End of document.