																												<b>7</b>
A:pend2DMotion	A:cartCoord	A:cartCoordRight	A:yAxisDir	A:startOrigin	DD:positionIX	DD:positionIY	DD:frequencyDD	DD:angFrequencyDD	DD:periodSHMDD	TM:acceleration	TM:velocity	TM:NewtonSecLawMot	TM:NewtonSecLawRotMot	GD:velocityIX	GD:velocityIY	GD:accelerationIX	GD:accelerationIY	GD:hForceOnPendulum	GD:vForceOnPendulum	GD:angFrequencyGD	GD:periodPend	IM:calOfAngularDisplacement	FR:inputValues	FR:verifyInptVals	FR:calcAngPos	FR:outputValues	NFR:correct N	NFR:portable
-		J	J	3	1	1	1 3	3 1 3	1		3			3	J					3 1 3		3 1	1	3 1	J			