FR:calcAngPos
FR:outputValues
A:pend2DMotion
A:cartCoord
A:cartCoordRight
A:cyAxisDir
A:startOrigin
DD:positionIX
DD:positionIY
DD:frequencyDD
DD:angFrequencyDD
DD:periodSHMDD
TM:acceleration
TM:velocity
TM:NewtonSecLawMot
TM:NewtonSecLawRotMot
GD:velocityIX
GD:velocityIY
GD:accelerationIX
GD:accelerationIY
GD:hForceOnPendulum
GD:vForceOnPendulum
GD:angFrequencyGD
GD:periodPend
FR:inputValues
FR:verifyInptVals
NFR:correct
NFR:portable
GS:motionMass
IM:calOfAngularDisplacement