# Module Interface Specification for Projectile

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# Contents

1	Syn	nbols, Abbreviations and Acronyms	1
2	Intr	roduction	1
3	Not	tation	1
4	Mo	dule Decomposition	2
5	MIS	S of Control Module	3
	5.1	Module	3
	5.2	Uses	3
	5.3	Syntax	3
		5.3.1 Exported Access Programs	3
	5.4	Semantics	3
		5.4.1 State Variables	3
		5.4.2 Access Routine Semantics	3
6	MIS	S of Input Parameters Module	4
	6.1	Module	4
	6.2	Uses	4
	6.3	Syntax	4
	6.4	Semantics	4
		6.4.1 Environment Variables	4
		6.4.2 State Variables	4
		6.4.3 Assumptions	4
		6.4.4 Access Routine Semantics	5
	6.5	Considerations	5
7	MIS	S of Input Constraints Module	6
	7.1	Module	6
	7.2	Uses	6
	7.3	Syntax	6
		7.3.1 Exported Access Programs	6
	7.4	Semantics	6
		7.4.1 Assumptions	6
		7.4.2 Access Routine Semantics	6
	7.5	Considerations	6
8	MIS	S of Calculations Module	7
	8.1	Module	7
	8.2	Uses	7
	8.3	Syntax	7

		8.3.1 Exported Access Programs	7
	8.4	Semantics	7
		8.4.1 Assumptions	7
		8.4.2 Access Routine Semantics	7
	8.5	Considerations	8
9	MIS	S of Output Module	9
	9.1	Module	9
	9.2	Uses	9
	9.3	Syntax	9
		9.3.1 Exported Access Program	9
	9.4	Semantics	9
		9.4.1 State Variables	9
		9.4.2 Environment Variables	9
		9.4.3 Access Routine Semantics	9
10	MIS	S of Specification Parameters	10
	10.1	Module	10
	10.2	Uses	10
	10.3	Syntax	10
		10.3.1 Exported Constants	10
	10.4	Semantics	10
11	Bibl	liography	11
10	A 222	pendix	11
12	ADI	DEHILIX	1 1

# 1 Symbols, Abbreviations and Acronyms

See SRS Documentation at https://jacquescarette.github.io/Drasil/examples/Projectile/srs/Projectile\_SRS.pdf

# 2 Introduction

The following document details the Module Interface Specifications for the implemented modules in a program simulating projectile motion. It is intended to ease navigation through the program for design and maintenance purposes.

Complementary documents include the System Requirement Specifications and Module Guide. The full documentation and implementation can be found at [No manual version of Projectile? Should this link be removed or should there be a link? —SC].

# 3 Notation

The structure of the MIS for modules comes from Hoffman and Strooper (1995), with the addition that template modules have been adapted from Ghezzi et al. (2003). The mathematical notation comes from Chapter 3 of Hoffman and Strooper (1995). For instance, the symbol := is used for a multiple assignment statement and conditional rules follow the form  $(c_1 \Rightarrow r_1|c_2 \Rightarrow r_2|...|c_n \Rightarrow r_n)$ .

The following table summarizes the primitive data types used by Projectile.

Data Type	Notation	Description
character	char	a single symbol or digit
real	$\mathbb{R}$	any number in $(-\infty, \infty)$

The specification of Projectile uses strings, a derived data type. Strings are lists of characters. In addition, Projectile uses functions, which are defined by the data types of their inputs and outputs. Local functions are described by giving their type signature followed by their specification.

# 4 Module Decomposition

The following table is taken directly from the Module Guide document for this project.

Level 1	Level 2
Hardware-Hiding	
	Input Parameters
	Input Constraints
Pohoviour Hiding	Calculations
Behaviour-Hiding	Output Format
	Control Module
	Specification Parameters Module
Software Decision	Sequence Data Structure

Table 1: Module Hierarchy

## 5 MIS of Control Module

#### 5.1 Module

main

#### 5.2 Uses

Param (Section 6), InputConstraints (Section 7), Calculations (Section 8), Output (Section 9)

## 5.3 Syntax

#### 5.3.1 Exported Access Programs

Name	In	Out	Exceptions
main	-	-	-

#### 5.4 Semantics

#### 5.4.1 State Variables

None

#### 5.4.2 Access Routine Semantics

main():

• transition: Modify the state of Param module and the environment variables for the Output module by following these steps

```
Get (filenameIn: string) from user.
get_input(filenameIn, Param)
input_constraints(Param)
p_land := func_p_land(Param)
d_offset := func_d_offset(Param, p_land)
s := func_s(Param, d_offset)
# Output calculated values to a file.
write_output(s, d_offset)
```

# 6 MIS of Input Parameters Module

The secrets of this module are the data structure for input parameters and how the values are input.

#### 6.1 Module

Param

#### 6.2 Uses

SpecParam (Section 10)

## 6.3 Syntax

Name	In	Out	Exceptions
$\operatorname{get\_input}$	string,	-	FileError
	Param	L	
v_launch	-	$\mathbb{R}$	
$v_{-}$ angle	-	$\mathbb{R}$	
$p_{-}target$	_	$\mathbb{R}$	

#### 6.4 Semantics

#### 6.4.1 Environment Variables

inputFile: sequence of string #f[i] is the ith string in the text file f

#### 6.4.2 State Variables

```
# To Support IM1 and IM2 v_launch: \mathbb{R} v_angle: \mathbb{R} # To Support IM3 and IM4 p_target: \mathbb{R}
```

#### 6.4.3 Assumptions

- get\_input will be called before the values of any state variables will be accessed.
- The file contains the string equivalents of the numeric values for each input parameter in order, each on a new line. Any comments in the input file should be denoted with a '#' symbol.

#### 6.4.4 Access Routine Semantics

#### Param.v\_launch:

 $\bullet$  output:  $out := v_{launch}$ 

• exception: none

#### Param.v\_angle:

• output:  $out := v_angle$ 

• exception: none

#### Param.p\_target:

• output:  $out := p_{target}$ 

• exception: none

get\_input(filename, Param):

- transition: The file name "filename" is first associated with the file f. The data from f is read sequentially to populate the state variables from FR1 (v\_launch, v\_angle, and p\_target) in Param.
- exception: exc := a file name "filename" cannot be found OR the format of inputFile is incorrect  $\Rightarrow$  FileError

See Appendix (Section 12) for the complete list of exceptions and associated error messages.

#### 6.5 Considerations

The value of each state variable can be accessed through its name (getter). An access program is available for each state variable. There are no setters for the state variables, since the values will be set by get\_input and not changed for the life of the program.

# 7 MIS of Input Constraints Module

The secret of this module is how the values are verified.

#### 7.1 Module

InputConstraints

#### 7.2 Uses

Param (Section 6)

## 7.3 Syntax

#### 7.3.1 Exported Access Programs

Name	In	Out	Exceptions
input_constraints	Param	-	badSpeed, badAngle, badTargetPosition

#### 7.4 Semantics

#### 7.4.1 Assumptions

All of the fields Param have been assigned values before any of the access routines for this module are called.

#### 7.4.2 Access Routine Semantics

input\_constraints(Param):

- out: out := none
- exception: exc := (
  - $\neg (0 < Param.v\_launch) \Rightarrow badSpeed \mid$
  - $\neg (0 < \text{Param.v\_angle} < \frac{\pi}{2}) \Rightarrow \text{badAngle} \mid$
  - $\neg (0 < Param.p\_target) \Rightarrow badTargetPosition)$

#### 7.5 Considerations

See Appendix (Section 12) for the complete list of exceptions and associated error messages.

# 8 MIS of Calculations Module

The secret of this module is how the required values are calculated.

## 8.1 Module

Calculations

#### 8.2 Uses

Param (Section 6)

## 8.3 Syntax

#### 8.3.1 Exported Access Programs

Name	In	Out	Exceptions
func_p_land	Param	$\mathbb{R}$	None
func_d_offset	Param, $\mathbb{R}$	$\mathbb{R}$	None
func_s	Param, R	String	None

#### 8.4 Semantics

#### 8.4.1 Assumptions

All of the fields Param have been assigned values before any of the access routines for this module are called.

#### 8.4.2 Access Routine Semantics

func\_p\_land(Param):

- out:  $out := \frac{2*v\_launch^2*sin(v\_angle)*cos(v\_angle)}{q}$
- exception: exc := none

func\_d\_offset(Param, p\_land):

- out:  $out := p\_land p\_target$
- exception: exc := none

func\_s(Param, d\_offset):

```
• out: out := ( |\frac{\text{d.offset}}{\text{p.target}}| < \epsilon \Rightarrow "The target was hit." | d_offset < 0 \Rightarrow "The projectile fell short."| True \Rightarrow "The projectile went long.")
```

• exception: exc := none

# 8.5 Considerations

See Appendix (Section 12) for the complete list of exceptions and associated error messages.

# 9 MIS of Output Module

# 9.1 Module

Output

#### 9.2 Uses

Param (Section 6)

# 9.3 Syntax

## 9.3.1 Exported Access Program

Name	In	Out	Exceptions
write_output	String, String, $\mathbb{R}$	-	_

#### 9.4 Semantics

#### 9.4.1 State Variables

None

#### 9.4.2 Environment Variables

file: The file named "output".

#### 9.4.3 Access Routine Semantics

write\_output(s, d\_offset):

- $\bullet$  transition: Write to environment variable named "file" the calculated values s and d\_offset.
- exception: none

# 10 MIS of Specification Parameters

The secrets of this module is the value of the specification parameters.

# 10.1 Module

 ${\bf Spec Param}$ 

# 10.2 Uses

N/A

# 10.3 Syntax

# 10.3.1 Exported Constants

```
# From Table 10 in SRS g := 9.8 \epsilon := 0.02
```

# 10.4 Semantics

N/A

# 11 Bibliography

Carlo Ghezzi, Mehdi Jazayeri, and Dino Mandrioli. Fundamentals of Software Engineering. Prentice Hall, Upper Saddle River, NJ, USA, 2nd edition, 2003.

Daniel M. Hoffman and Paul A. Strooper. Software Design, Automated Testing, and Maintenance: A Practical Approach. International Thomson Computer Press, New York, NY, USA, 1995.

# 12 Appendix

Message ID	Error Message
badSpeed	InputError: Speed must be positive.
$\mathrm{badAngle}$	InputError: Angle must be between zero and pi over two radians.
${\bf badTargetPosition}$	InputError: Target position must be positive.

Table 2: Possible Exceptions