

Semi-Supervised QA with Generative Domain-Adaptive Nets

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Motivation

Constructing the training data by semi-supervised method.

Utilize $\langle p, a \rangle$ to generate q .

A Simple Baseline

Giving SQuAD data, regard the context of answer as the question. The simple baseline method leads to substantial improvements when labeled data is limited.

Generative Domain-Adaptive Nets

- Discriminative Model
- Generative Model

Discriminative Model

Gated-attention reader model

Domain Adaptation with Tags

During training the discriminative model, the training data is from two distributions (human-generated and model-generated). These two domains of the data should be treated differently. So it uses a **domain tag** as an additional input to the discriminative model.

d_true represent the domain of human-generated data, **d_gen** represent the domain of model-generated data.

At test time, using the **d_true** tag.

Generative Model

seq2seq model + copy mechanism.

During using label data, MLE. $P(q|p,a)$

During using unlabel data, RL. $P(a|p,q)$

Attention: During using unlabel data training generative model, in order to prevent the generated question close to the distribution of the answer, it appends the **d_true** tag to the generated questions.

By this way, the discriminative model regards them as human-generated question to treat, and make the generated questions close to the distribution of human-generated questions.

Training

Training progress

Algorithm 1 Training Generative Domain-Adaptive Nets

Input: labeled data L , unlabeled data U , #iterations T_G and T_D

Initialize G by MLE training on L

Randomly initialize D

while not stopping **do**

for $t \leftarrow 1$ to T_D **do**

 Update D to maximize $J(L, d_{\text{true}}, D) + J(U_G, d_{\text{gen}}, D)$ with SGD

end for

for $t \leftarrow 1$ to T_G **do**

 Update G to maximize $J(U_G, d_{\text{true}}, D)$ with Reinforce and SGD

end for

end while

return model D

ps. Two modules are updated alternately.

The objective function

$$\max_D J(L, d_{true}, D) + J(U_G, d_{gen}, D)$$

$$\max_G J(U_G, d_{true}, D)$$

Model architecture and training

