

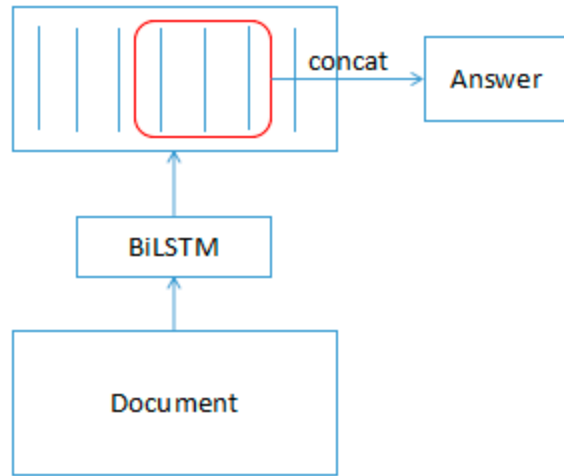
# Machine Comprehension by Text-to-Text Neural Question Generation

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# Motivation

1. Posing appropriate questions is an important aspect of information acquisition in intelligent systems.
2. Learning to ask questions may improve the ability to answer them.

# Encoder



$Embedding(Doc) \rightarrow LSTM \rightarrow (h_1, h_2, \dots, h_m)$

$A : [Hidden; Embedding]$

$Hidden : (h_i, h_{i+1}, \dots, h_j) \quad Embedding : (a_i, a_{i+1}, \dots, a_j)$

$A \rightarrow LSTM2 \rightarrow h_a$

$h_a$ :concat(the final hidden state of two directions)

Computing the initial state  $s_0$  for the decoder:

$$\mathbf{r} = \mathbf{L}\mathbf{h}^a + \frac{1}{n} \sum_i^{[D]} \mathbf{h}_i^d, \quad s_0 = \tanh(\mathbf{W}_0 \mathbf{r} + \mathbf{b}_0);$$

# Decoder(vocab softmax and pointer softmax)

$$s_t = LSTM(s_{t-1}, y_{t-1}, v_t)$$

$$e_{tj} = f(h_j^d, h^a, y_{t-1}, s_{t-1})$$
$$\alpha_{tj} = \frac{\exp(e_{tj})}{\sum_{i=1}^T \exp(e_{ij})}$$

$$c_t = \sum_{i=1}^{|D|} \alpha_{ti} h_i^d$$
$$v_t = [c_t; h^a]$$

# Decoder

$$e_t = g(s_t, v_t, y_{t-1})$$

$$o_t = \text{softmax}(W_o e_t + b_o)$$

Finally,  $p_\theta(y_t | y < t, D, A)$  is approximated by the full pointer-softmax  $p_t \in \mathbb{R}^{|V|+|D|}$  by concatenating  $o_t$  and  $\alpha_t$  after both are weighted by  $z_t$ :

$$p_t = [z_t o_t; (1 - z_t) \alpha_t]$$

$z_t$  is a MLP gate.

# Training

Cross-Entropy

$$\mathcal{L} = - \sum_t \log p_{\theta}(y_t | y_{<t}, D, A),$$

Penalty Term1 (Encourage the model not to generate answer words in the question)

$$\mathcal{L}_s = \lambda_s \sum_t \sum_{\bar{a} \in \bar{\mathcal{A}}} p_{\theta}(y_t = \bar{a} | y_{<t}, D, A).$$

Penalty Term2 (Increase output variety)

$$\mathcal{L}_e = \lambda_e \sum_t \mathbf{p}_t^T \log \mathbf{p}_t.$$

# Policy Gradient Optimization

There is a limitation in teacher-forcing that it does not teach the model how to distribute probability mass among examples other than the ground-truth.

## Rewards

QA reward:  $R_{QA}(\hat{Y}) = F1(\hat{A}, A)$

Fluency(Language Model matrix):

$$R_{PPL}(\hat{Y}) = -2^{-\frac{1}{T} \sum_{t=1}^T \log_2 P_{LM}(\hat{y}_t) | \hat{y}_{<t}}$$

## Combination

$$R_{PPL + QA}(\hat{Y}) = \lambda_{QA} R_{QA}(\hat{Y}) + \lambda_{PPL} R_{PPL}(\hat{Y}),$$

# Reinforce

$$\mathcal{L}_{\text{RL}} = -\mathbb{E}_{\hat{Y} \sim \pi(\hat{Y}|D,A)}[R(\hat{Y})],$$

$$\nabla \mathcal{L}_{\text{RL}} \approx \sum_{t=1} \nabla \log \pi(\hat{y}_t | \hat{y}_{<t}, D, A) \frac{R(\hat{Y}) - \mu_R}{\sigma_R},$$

Using beam search instead of sampling when computing the expectation.

The  $L_{RL}$  is based on beam search, and the  $L_{CE}$  is based on ground-truth.



# Experiments

	NLL	BLEU	F1	QA	PPL
Seq2Seq	45.8	4.9	31.2	45.6	153.2
Our System	<b>35.3</b>	10.2	39.5	65.3	175.7
+ PG ( $R_{\text{PPL}}$ )	35.7	9.2	38.2	61.1	<b>155.6</b>
+ PG ( $R_{\text{QA}}$ )	39.8	<b>10.5</b>	<b>40.1</b>	<b>74.2</b>	300.9
+ PG ( $R_{\text{PPL}+\text{QA}}$ )	39.0	9.2	37.8	70.2	183.1
Question LM	-	-	-	-	87.7
MPCM	-	-	-	70.5	-