

CARLETON UNIVERSITY

SCHOOL OF COMPUTER SCIENCE

COMP4905 – HONOURS PROJECT

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# Formation Flight of UAVs Swarms in an Obstacle-Filled Three-Dimensional Environment

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## **Abstract**

Abstract goes here!

## **Acknowledgements**

This project uses Webots (<http://www.cyberbotics.com>), an open-source mobile robot simulation software developed by Cyberbotics Ltd.

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# 1 Introduction

Test