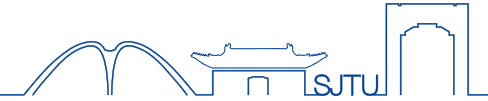


# Linear Methods for Regression



**Dept. Computer Science & Engineering,  
Shanghai Jiao Tong University**

# Key Points in Previous Talk

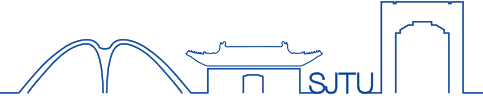


- The objective of statistical learning is to identify the model with **best generalization performance** or **with minimum training error**?
- In what conditions, linear regression is the best as a classifier?
- KNN is one of implementations of the optimal decision function, but why we do not use it as a classifier in high dimensional space?
- **Generalization error = Model Bias<sup>2</sup> + Variance**

Model  
Complexity

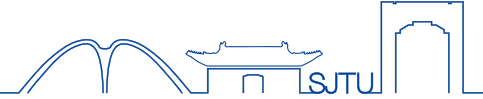
Data Noise

# Outline



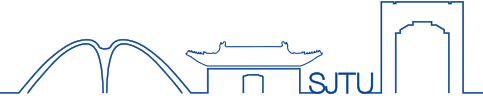
- **The simple linear regression model**
- **Multiple linear regression**
- **Regularization**
  - Subset selection
  - Shrinkage
- **Principal component Regression**
- **Partial least squares Regression**

# Objectives



- **How to use LR methods appropriately**
- **How to evaluate the performance of LR methods**
  - Confidence Interval
  - MSE / Generalization
- **How to improve the generalization performance**

# Preliminaries



- Data  $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$ 
  - $x_i$  is the predictor (regressor, covariate, independent variable)
  - $y_i$  is the response (dependent variable, outcome)

- We denote **the regression function** by

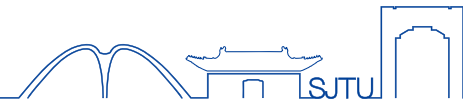
$$\eta(x) = E(Y \mid x)$$

- This is the conditional expectation of  $Y$  given  $x$ .
- The linear regression model assumes a specific linear form for

$$\eta(x) = \alpha + \beta x$$

which is usually thought of as an approximation to the truth.

# Fitting by least squares



- Minimize:  $\hat{\beta}_0, \hat{\beta} = \arg \min_{\beta_0, \beta} \sum_{i=1}^N (y_i - \beta_0 - \beta x_i)^2$

- Solutions are

$$\hat{\beta} = \frac{\sum_{j=1}^N (x_i - \bar{x}) y_i}{\sum_{j=1}^N (x_i - \bar{x})^2}$$

$$\hat{\beta}_0 = \bar{y} - \hat{\beta} \bar{x}$$

- $\hat{y}_i = \hat{\beta}_0 + \hat{\beta} x_i$ : the fitted or predicted values

- $r_i = y_i - \hat{\beta}_0 - \hat{\beta} x_i$  are called the residuals

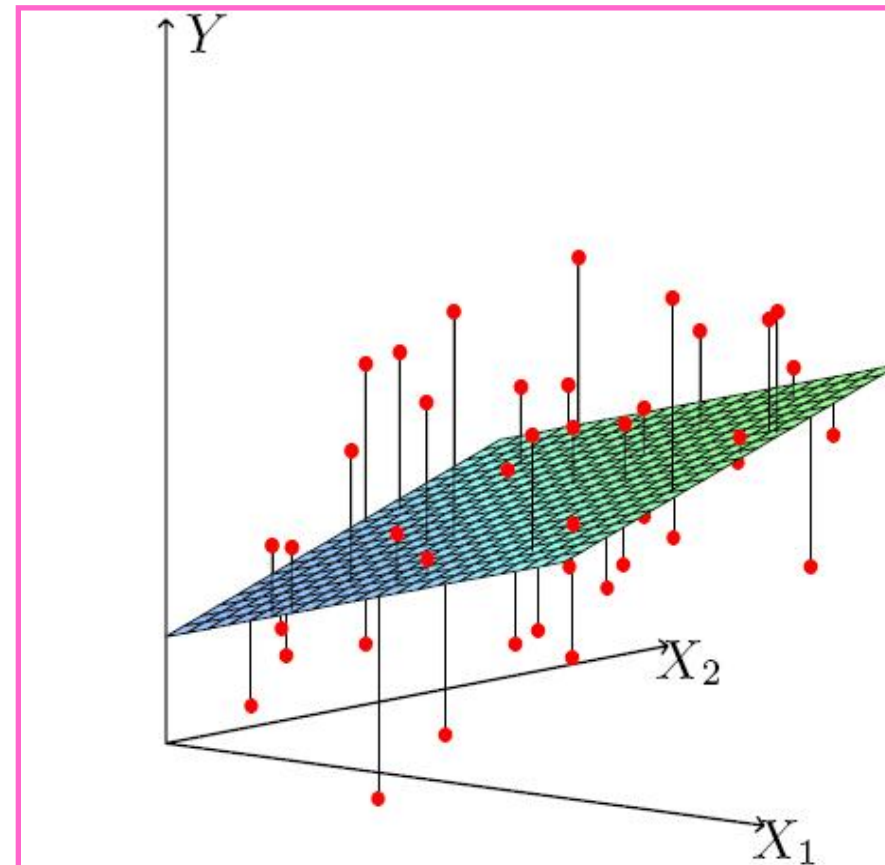
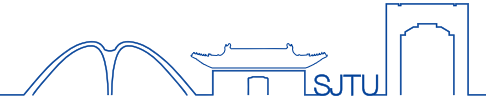


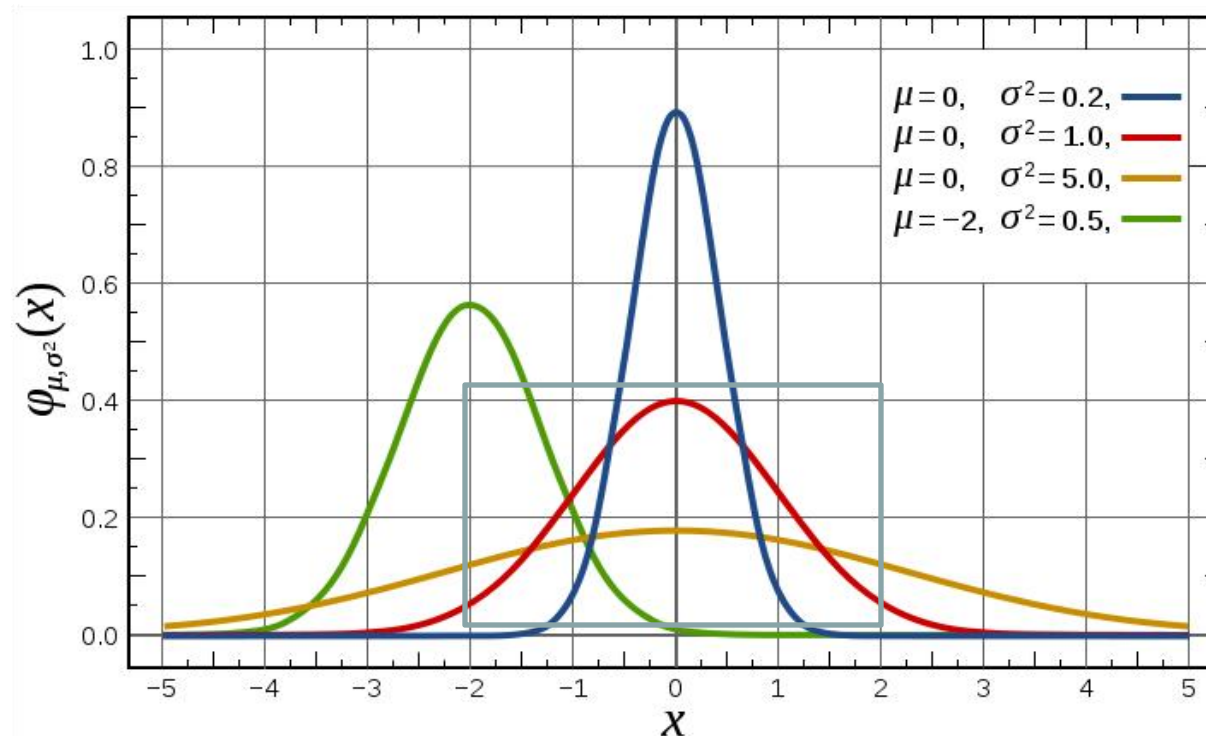
Figure 3.1 - view of linear regression in 3D

# Gaussian Distribution

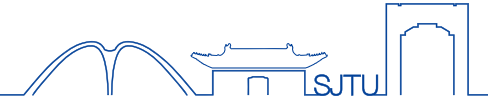


- The normal distribution with mean  $\mu$ , and variance  $\sigma^2$ .

$$f(x) = \frac{1}{\sqrt{2\pi} \sigma} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right) = \frac{1}{\sigma} \phi\left(\frac{x-\mu}{\sigma}\right)$$



# Standard errors & confidence intervals



- Assume further that

$$y_i = \beta_0 + \beta x_i + \varepsilon_i$$

where  $E(\varepsilon_i) = 0$  and  $Var(\varepsilon_i) = \sigma^2$ . Then

$$se(\hat{\beta}) = \left[ \frac{\sigma^2}{\sum (x_i - \bar{x})^2} \right]^{1/2}$$

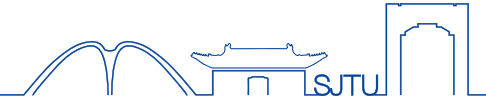
Estimate  $\sigma^2$  by  $\hat{\sigma}^2 = \sum (y_i - \hat{y}_i)^2 / (N - 2)$ .

- Under additional assumption of normality for  $\varepsilon_i$ s, a 95% confidence interval for  $\beta$  is:

$$\hat{\beta} \pm 1.96 \hat{se}(\hat{\beta}), \quad \hat{se}(\hat{\beta}) = \left[ \frac{\hat{\sigma}^2}{\sum (x_i - \bar{x})^2} \right]^{1/2}$$



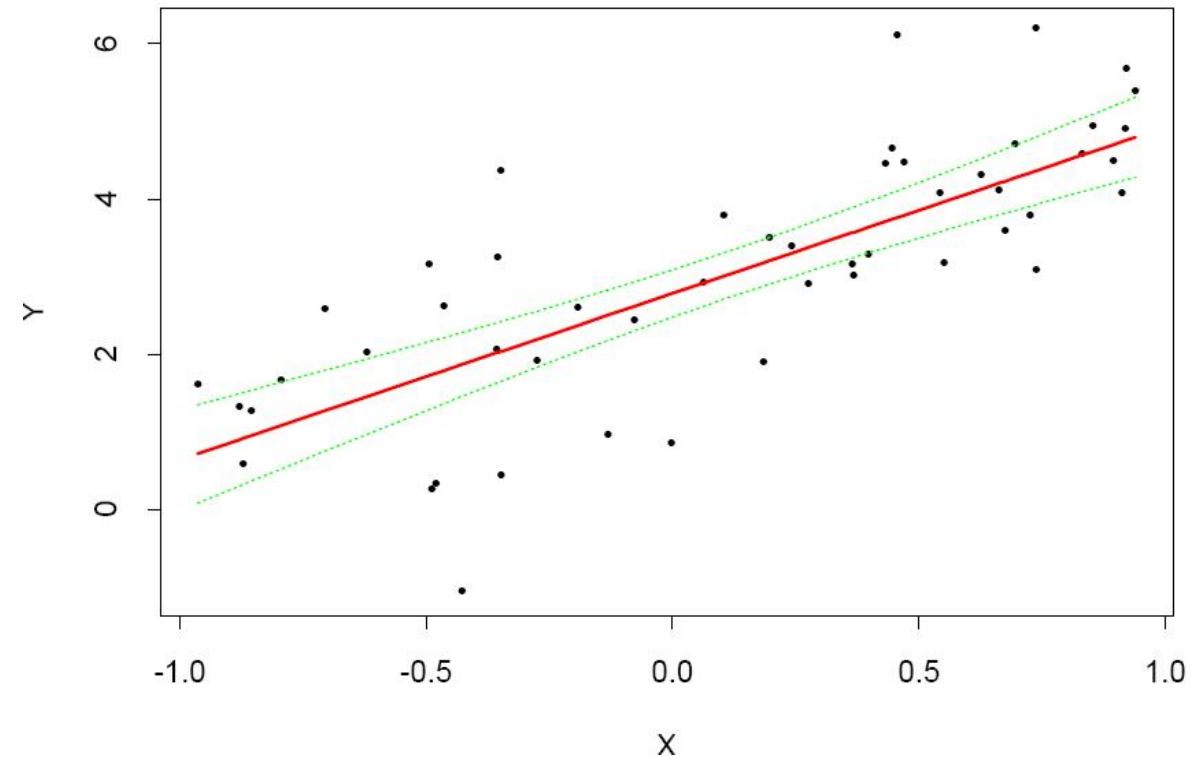
# Fitted Line and Standard Errors



- Fitted regression line with pointwise standard errors:

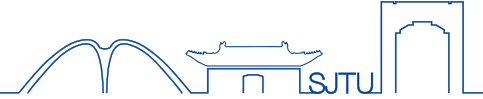
$$\begin{aligned}\hat{\eta}(x) &= \hat{\beta}_0 + \hat{\beta}x \\ &= \bar{y} + \hat{\beta}(x - \bar{x})\end{aligned}$$

$$\begin{aligned}se[\hat{\eta}(x)] &= \left[ \text{var}(\bar{y}) + \text{var}(\hat{\beta})(x - \bar{x})^2 \right]^{1/2} \\ &= \left[ \frac{\sigma^2}{n} + \frac{\sigma^2(x - \bar{x})^2}{\sum (x_i - \bar{x})^2} \right]^{1/2}\end{aligned}$$



$$\hat{\eta}(x) \pm 2 \text{se}|\hat{\eta}(x)|$$

# Multiple linear regression



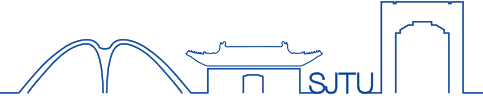
- Statistical Model  $y = \beta_0 + \mathbf{x}^T \boldsymbol{\beta} + \varepsilon$
- Model is  $y_i = \beta_0 + \mathbf{x}_i^T \boldsymbol{\beta} + \varepsilon_i, \quad i = 1, \dots, N$

Equivalently in matrix notation:

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$$

- $\mathbf{y}$  is  $N$ -vector of predicted values
- $\mathbf{X}$  is  $N \times p$  matrix of regressors, with ones in the first column
- $\boldsymbol{\beta}$  is a  $p$ -vector of parameters

# Estimation by least squares



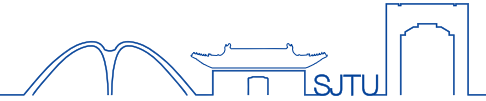
$$\begin{aligned}\hat{\beta} &= \arg \min \sum_i (y_i - \beta_0 - \sum_{j=1}^{p-1} x_{ij} \beta_j)^2 \\ &= \arg \min (\mathbf{y} - \mathbf{X}\beta)^T (\mathbf{y} - \mathbf{X}\beta)\end{aligned}$$

Solution is  $\hat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$

$$\hat{y} = \mathbf{X}\hat{\beta}$$

Also  $Var(\hat{\beta}) = (\mathbf{X}^T \mathbf{X})^{-1} \sigma^2$

# The Bias-variance tradeoff



- A good measure of the prediction performance for an estimator  $\hat{f}(x)$  is the **mean squared error**. Let  $f_0(x)$  be the true function.

$$\text{MSE}[\hat{f}(x)] = \text{E}[\hat{f}(x) - f_0(x)]^2$$

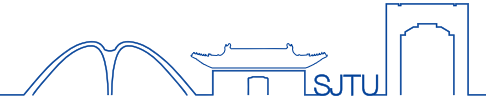
- This can be written as

$$\text{MSE}[\hat{f}(x)] = \text{Var}[\hat{f}(x)] + [\text{E}\hat{f}(x) - f_0(x)]^2$$

*variance + bias^2.*

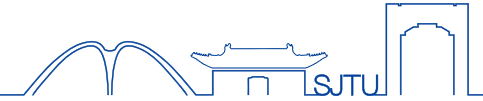
- When bias is low, variance is high and vice-versa.
  - Choose estimators ---- a tradeoff between bias and variance.

# The Bias-variance tradeoff

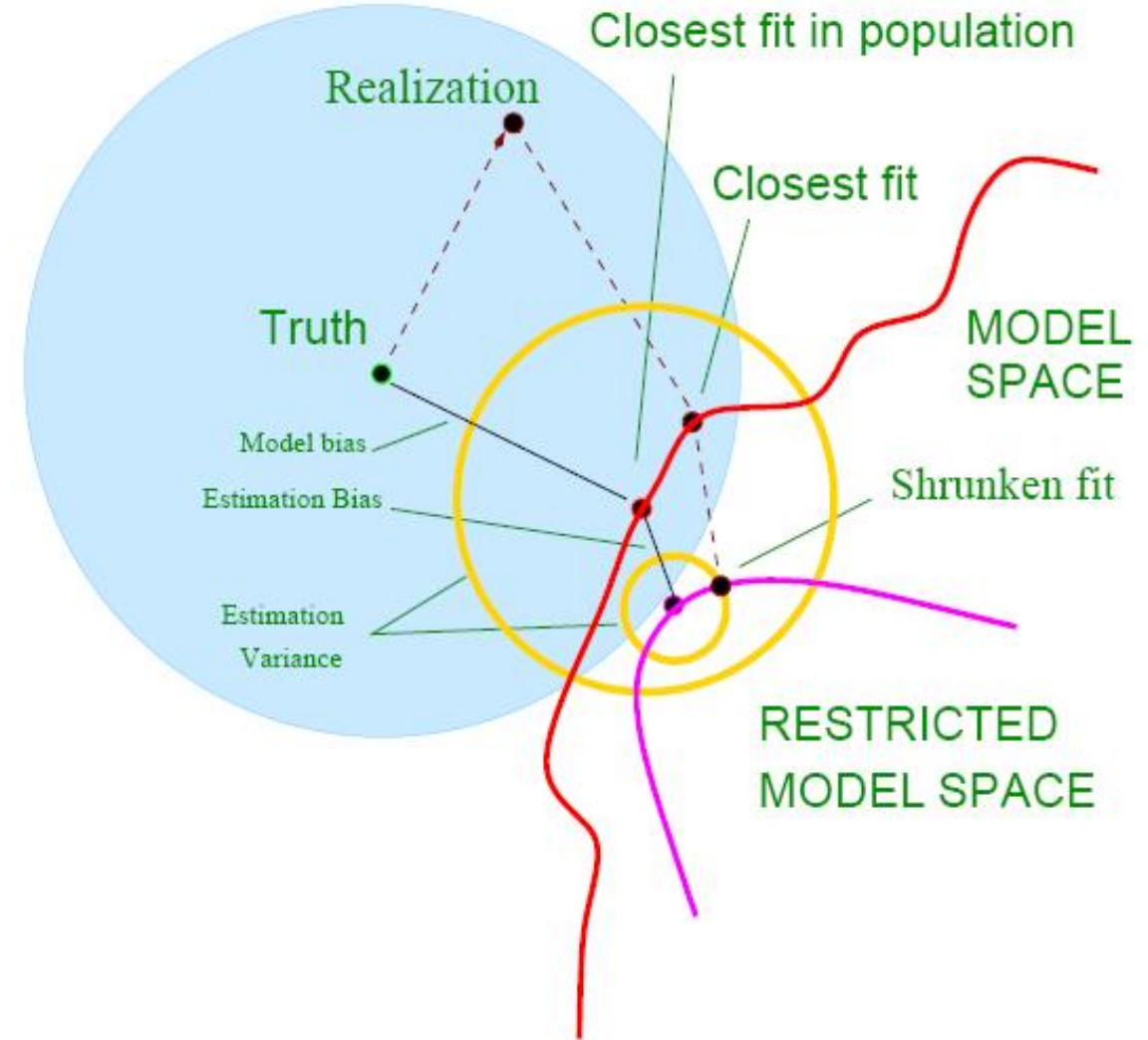


- If the linear model is correct for a given problem, then the least squares prediction  $f$  is unbiased, and has **the lowest variance** among all unbiased estimators that are linear functions of  $y$ .
- Generally, by **regularization** (shrinking, dampening, controlling)
  - the estimator in some way, its variance will be reduced
  - if the corresponding increase in bias is small, this will be worthwhile.

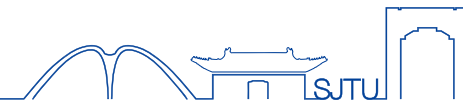
# Model Selection



- **Examples of regularization:** subset selection (forward, backward, all subsets); ridge regression, the lasso.
- In reality models are almost never correct, so there is an additional *model bias* between the closest member of the linear model class and the truth.



# Question?



Assume that the true function

$$y = f(x), \quad x \in R^{10}.$$

If we use higher dimensional

variables  $x \in R^p, (p > 10)$

to approximate the function, can

we achieve **better generalization**  
performance?

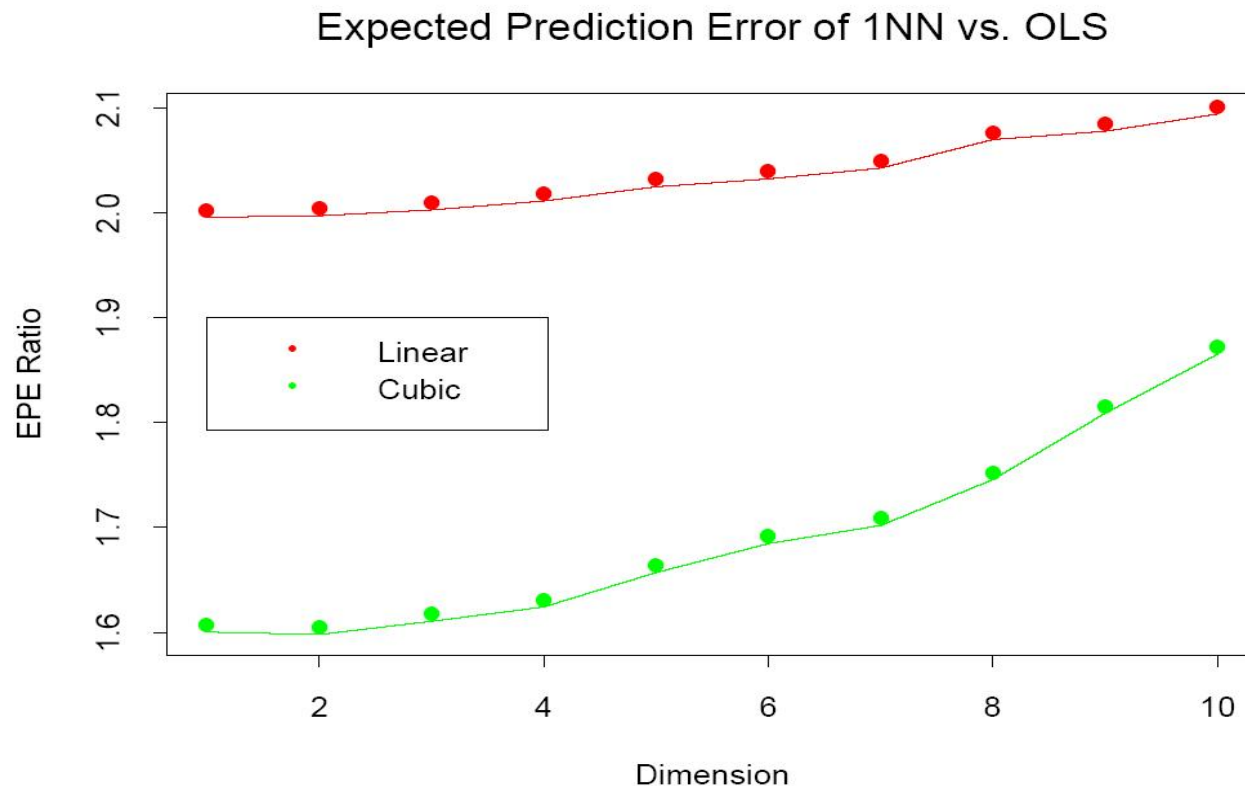
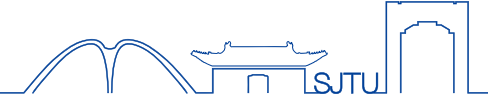


Figure 2.9: The curves show the expected prediction error (at  $x_0 = 0$ ) for 1-nearest neighbor relative to least squares for the model  $Y = f(X) + \varepsilon$ . For the red curve,  $f(x) = x_1$ , while for the green curve  $f(x) = \frac{1}{2}(x_1 + 1)^3$ .

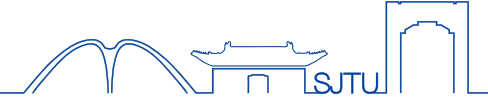
# Variable subset selection



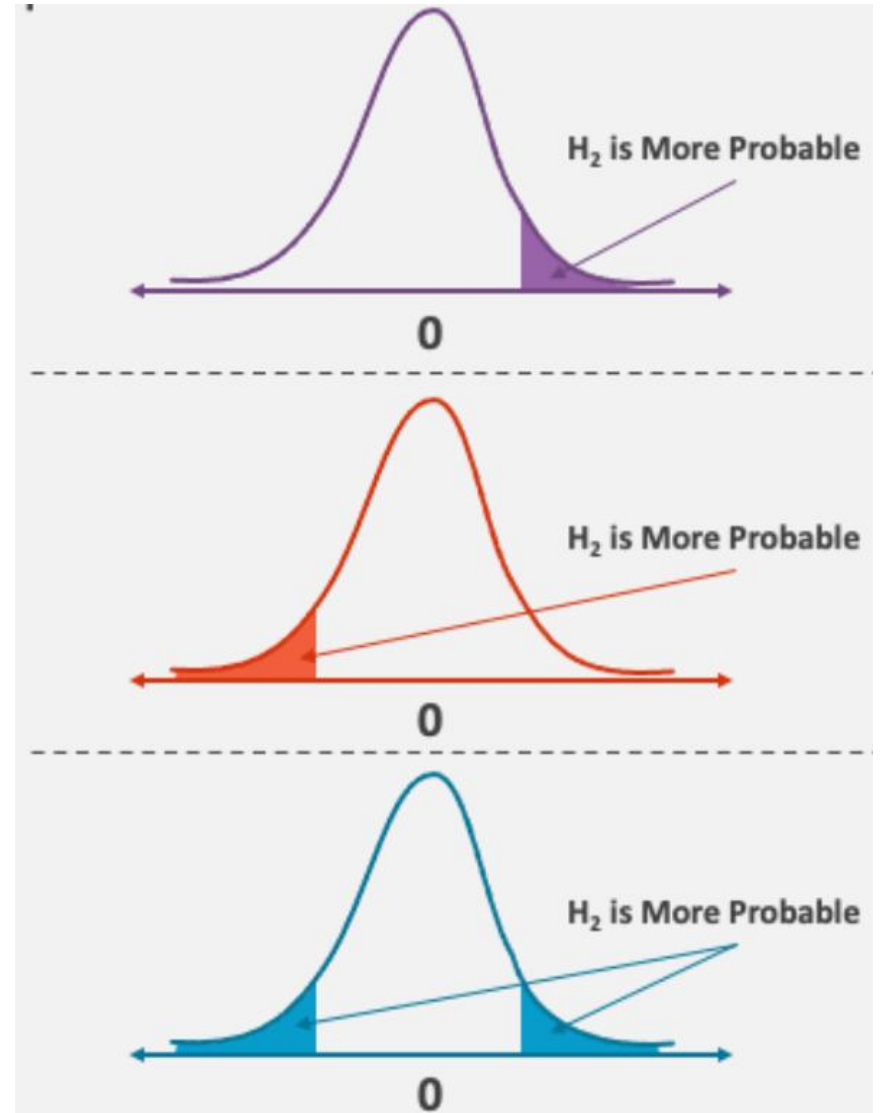
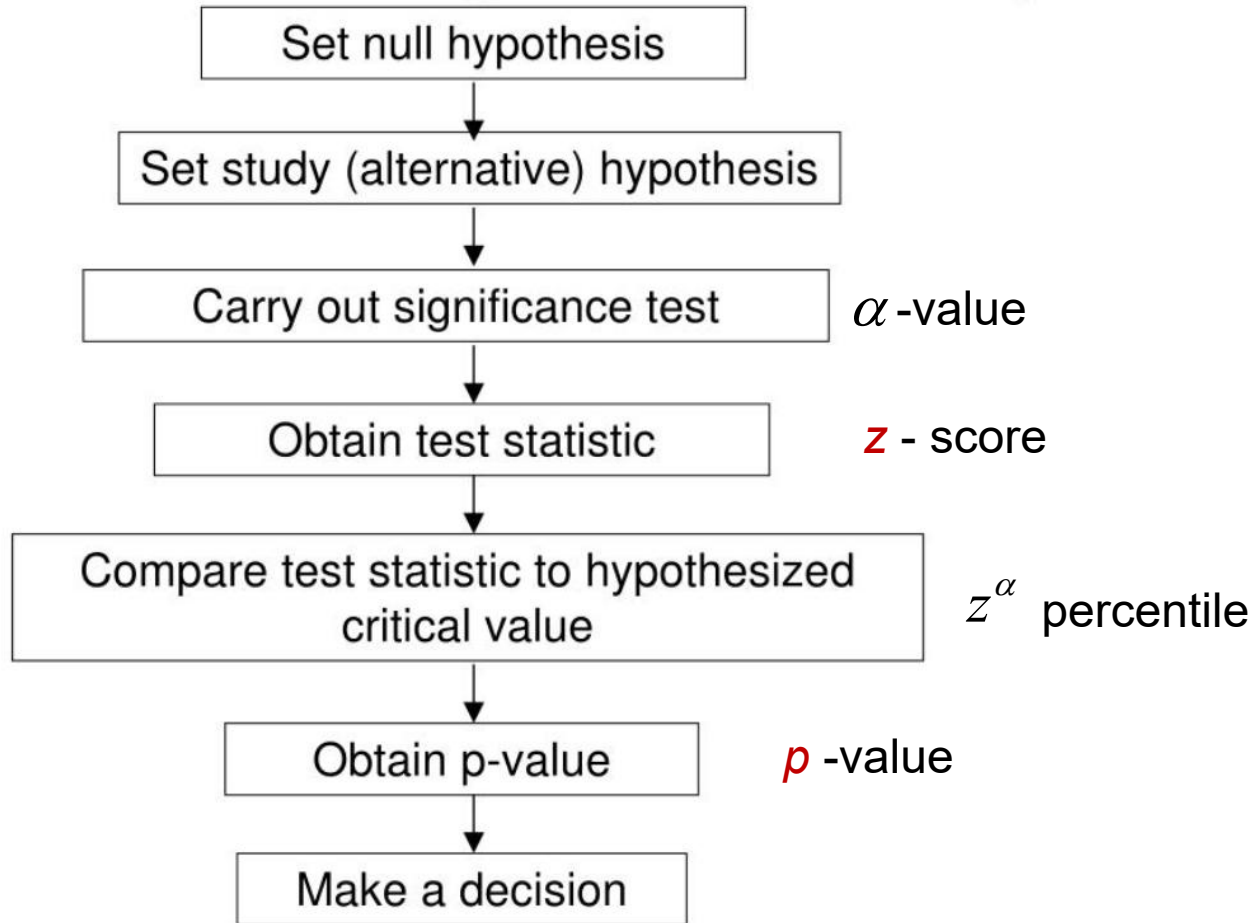
- **The first is prediction accuracy**
  - often have **low bias**, but **large variance**.
- **The second reason is interpretation.**
  - to determine a smaller subset that exhibit the strongest effects.
- **There are different strategies:**
  - **All subsets regression** is to find the subset of size  $s$  that gives smallest residual sum of squares.
  - The question of how to choose  $s$  involves the tradeoff between bias and variance: can use cross-validation



# Hypothesis Test

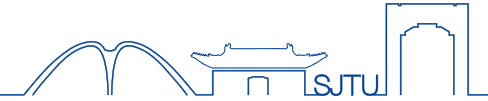


## Hypothesis testing: the main steps



$$z^{0.05} = 1.96$$

# Hypothesis Test



- **The linear regression model**

$$Y = \beta_0 + \sum_{j=1}^p X_j \beta_j + \varepsilon, \quad \varepsilon \sim N(0, \sigma^2)$$

- The regression solutions

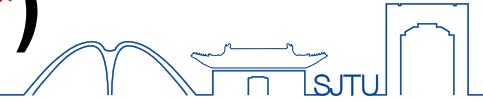
$$\hat{\beta} \sim N(\beta, (\mathbf{X}^T \mathbf{X})^{-1} \sigma^2), \quad \hat{\sigma}^2 \sim \sigma^2 \chi_{N-p-1}^2 / (N - p - 1)$$

- **To test the hypothesis** that a particular coefficient  $\beta_j = 0$ , we take the standardized coefficient or *Z-score*

$$z_j = \hat{\beta}_j / (\hat{\sigma} \sqrt{v_j})$$

where  $v_j$  is the  $j$ -th diagonal element of  $(\mathbf{X}^T \mathbf{X})^{-1}$ .

# Hypothesis Test (example: Prostate Cancer)



- **Lcavol**: log cancer volume,
- **lweight**: log prostate weight,
- **age**,
- **Lbph**: log of the amount of benign prostatic hyperplasia(良性前列腺增生量)

- **Svi**: seminal vesicle invasion,
- **Lcp**: log of capsular penetration,
- **Gleason**: Gleason score,
- **pgg45**: percent of Gleason scores 4 or 5

to fit **lpsa**: the log of prostate-specific antigen(前列腺特异抗原)

- Training samples: 67
- Test samples: 30

**TABLE 3.1.** *Correlations of predictors in the prostate cancer data.*

	lcavol	lweight	age	lbph	svi	lcp	gleason
lweight	0.300						
age	0.286	0.317					
lbph	0.063	0.437	0.287				
svi	0.593	0.181	0.129	−0.139			
lcp	0.692	0.157	0.173	−0.089	0.671		
gleason	0.426	0.024	0.366	0.033	0.307	0.476	
pgg45	0.483	0.074	0.276	−0.030	0.481	0.663	0.757

# Hypothesis Test (example: Prostate Cancer)



- Roughly a *Z-score* larger than **2** in absolute value is significantly nonzero at the  $p = 0.05$  level.

- **Significant**

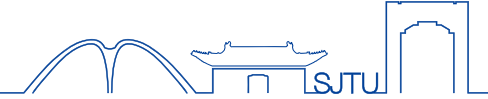
- Lcavol; lweight
- Lbph; svi

- **Non-significant**

- Age; lcp
- Gleason; pgg45

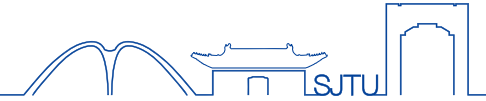
Term	Coefficient	Std. Error	Z Score
Intercept	2.46	0.09	27.60
lcavol	0.68	0.13	5.37
lweight	0.26	0.10	2.75
age	-0.14	0.10	-1.40
lbph	0.21	0.10	2.06
svi	0.31	0.12	2.47
lcp	-0.29	0.15	-1.87
gleason	-0.02	0.15	-0.15
pgg45	0.27	0.15	1.74

# Variable subset selection



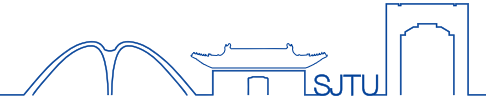
- **Backward stepwise selection** starts with the full OLS model, and sequentially deletes variables.
- There are also hybrid **stepwise selection** strategies which add in the best variable and delete the least important variable, in a sequential manner.
- Each procedure has one or more *tuning parameters*:
  - subset size
  - *P-values* for adding or dropping terms

# Model Assessment



- **Objectives:**
  1. Choose a value of a tuning parameter for a model family
  2. Estimate the prediction performance of a given model
- For both of these purposes, the best approach is to run the procedure on an independent test set, if one is available
- If possible one should use different test data for (1) and (2) above: a *validation set* for (1) and a *test set* for (2)
- Often there is insufficient data to create a separate validation or test set. In this instance *Cross-Validation* is useful.

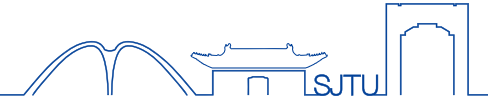
# K-Fold Cross-Validation



- Primary method for estimating a tuning parameter (such as subset size)
- Divide the data into  $K$  roughly equal parts (typically  $K=5$  or  $10$ )

1	2	3	4	5
Train	Train	Test	Train	Train

# K-Fold Cross-Validation



- For each  $k = 1, 2, \dots, K$ , fit the model with parameter to the other  $K - 1$  parts, giving  $\hat{\beta}^{-k}(\lambda)$  and compute its error in predicting the  $k$ -th part:

$$E_k(\lambda) = \sum_{i \in kth \text{ part}} (y_i - \mathbf{x}_i^T \hat{\beta}^{-k}(\lambda))^2$$

- This gives the cross-validation error

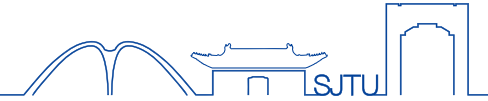
$$CV(\lambda) = \frac{1}{K} \sum_{k=1}^K E_k(\lambda)$$

- Model selection by

$$\min CV(\lambda)$$



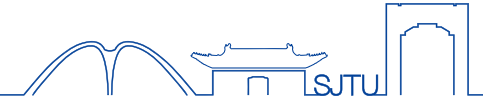
# K-Fold Cross-Validation



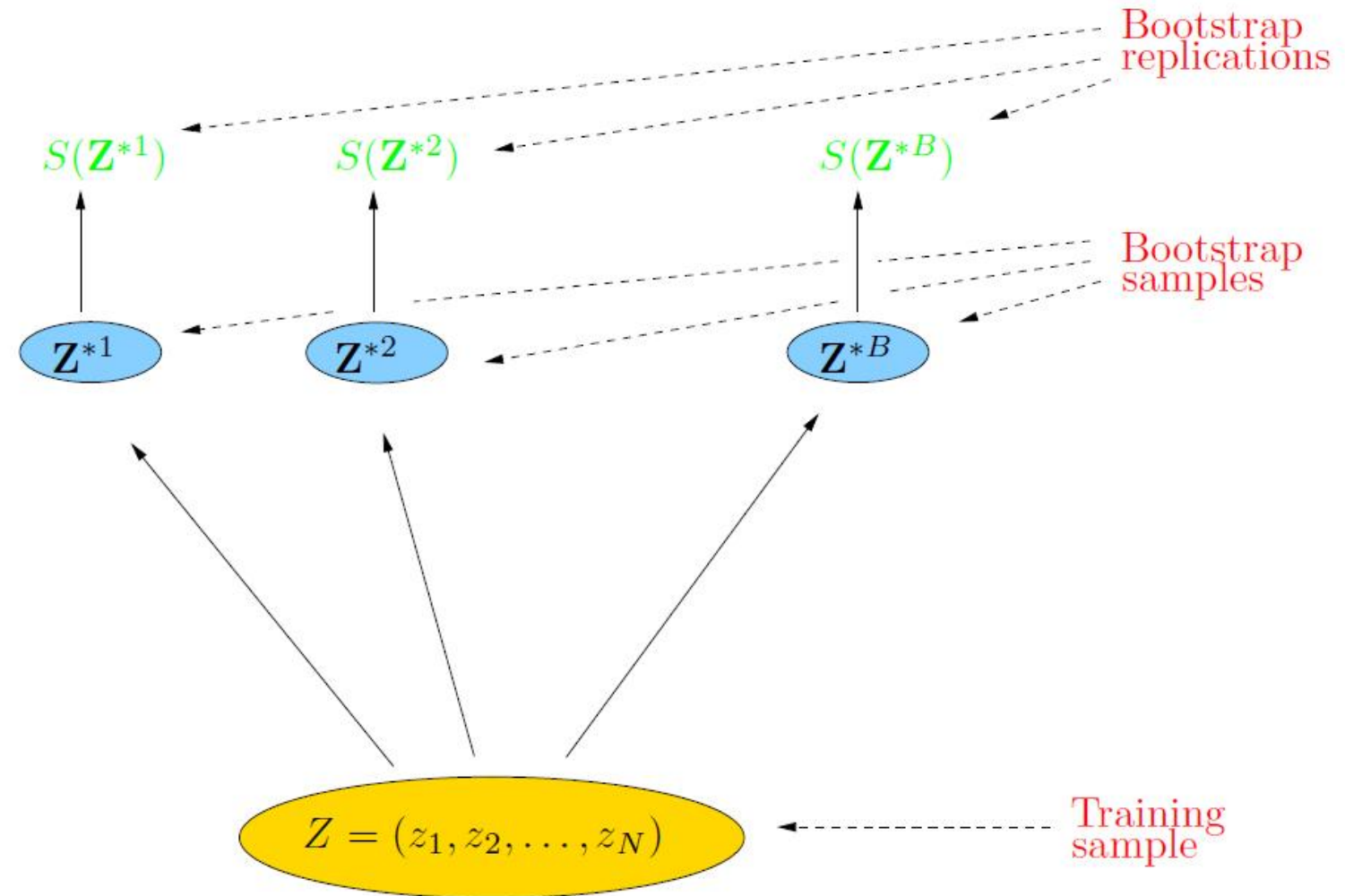
- In our **variable subsets** example,  $\lambda$  is **the subset size**
- $\hat{\beta}^{-k}(\lambda)$  are the coefficients for the best subset of size  $\lambda$ , found from the training set that leaves out the  $k$ -th part of the data
- $E_k(\lambda)$  is the estimated test error for this best subset.

- Minimizing: 
$$CV(\lambda) = \frac{1}{K} \sum_{k=1}^K E_k(\lambda)$$

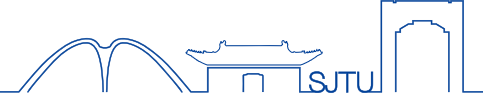
# The Bootstrap approach



- Bootstrap works by sampling  $B$  times with replacement from training set to form a “bootstrap” data set.
- This process is repeated many times and the results are averaged. Bootstrap most useful for estimating **standard errors of predictions**.

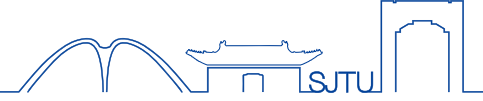


# Shrinkage Methods



- **Ridge regression**
- **Lasso regression**
- **PCA regression**
- **Partial least squares**

# Shrinkage methods



## Ridge regression

- Preprocessing: Data centering

$$x_{ij} \leftarrow x_{ij} - \bar{x}_j, \beta_0 = \bar{y} = \frac{1}{N} \sum_i y_i$$

- The ridge estimator is defined by

$$\hat{\beta}^{ridge} = \arg \min (\mathbf{Y} - \mathbf{X}\beta)^T (\mathbf{Y} - \mathbf{X}\beta) + \lambda \beta^T \beta$$

## Ridge regression

- The ridge estimator is defined by

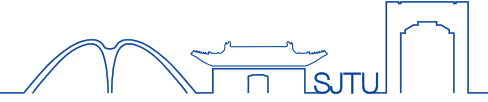
$$\hat{\beta}^{ridge} = \arg \min (\mathbf{Y} - \mathbf{X}\beta)^T (\mathbf{Y} - \mathbf{X}\beta) + \lambda \beta^T \beta$$

- Equivalently,

$$\hat{\beta}^{ridge} = \arg \min (\mathbf{Y} - \mathbf{X}\beta)^T (\mathbf{Y} - \mathbf{X}\beta)$$

$$\text{subject to } \sum \beta_j^2 \leq s$$

# Shrinkage methods



- The parameter  $\lambda > 0$  penalizes  $\beta_j$  proportional to its size  $\beta_j^2$ .

Solution:

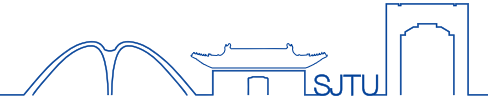
$$\hat{\beta}_\lambda = (\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{X}^T \mathbf{Y}$$

where  $\mathbf{I}$  is the identity matrix,  $\lambda > 0$

- Note  $\lambda = 0$  gives the least squares estimator; if  $\lambda \rightarrow \infty$ , then

$$\hat{\beta} \rightarrow 0$$

# Ridge regression



- Ridge solution:

$$\hat{\beta}_{\lambda} = (\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{X}^T \mathbf{Y}$$

- Singular value Decomposition:

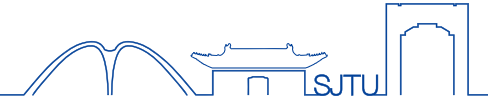
$\mathbf{X} = \mathbf{U} \mathbf{D} \mathbf{V}^T$ ;  $\mathbf{D}$  is a diagonal matrix with

$$d_1 \geq d_2 \geq d_3 \geq \dots \geq d_p \geq 0$$

- For ordinary Regression

$$\mathbf{X} \hat{\beta}^{\text{ls}} = \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y} = \mathbf{U} \mathbf{U}^T \mathbf{Y}$$

# Ridge regression



- Ridge solution:

$$\hat{\beta}_{\lambda} = (\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{X}^T \mathbf{Y}$$

- Singular value Decomposition:

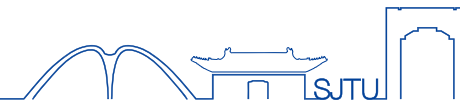
$$\mathbf{X} = \mathbf{U} \mathbf{D} \mathbf{V}^T; \quad \mathbf{D} = \text{diagonal}(d_1, d_2, \dots, d_p)$$

- For Ridge Regression

$$\begin{aligned} \mathbf{X} \hat{\beta}^{\text{ridge}} &= \mathbf{X} (\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{X}^T \mathbf{Y} \\ &= \mathbf{U} \mathbf{D} (\mathbf{D} \mathbf{D} + \lambda \mathbf{I})^{-1} \mathbf{D} \mathbf{U}^T \mathbf{Y} = \sum_{j=1}^p \mathbf{u}_j \frac{d_j^2}{d_j^2 + \lambda} \mathbf{u}_j^T \mathbf{Y} \end{aligned}$$



# The Lasso



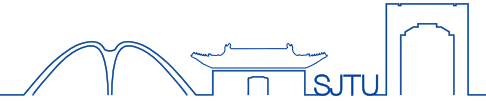
- The lasso (least absolute shrinkage and selection operator) is a shrinkage method like ridge, but acts in **a nonlinear manner** on the outcome  $y$ .
- The lasso is defined by

$$\hat{\beta}^{lasso} = \arg \min (\mathbf{Y} - \mathbf{X}\beta)^T (\mathbf{Y} - \mathbf{X}\beta)$$

$$\text{subject to } \sum_{j=1}^p |\beta_j| \leq t$$

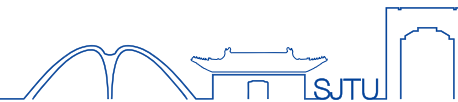
- **No constraint on  $\beta_0$**

# The Lasso

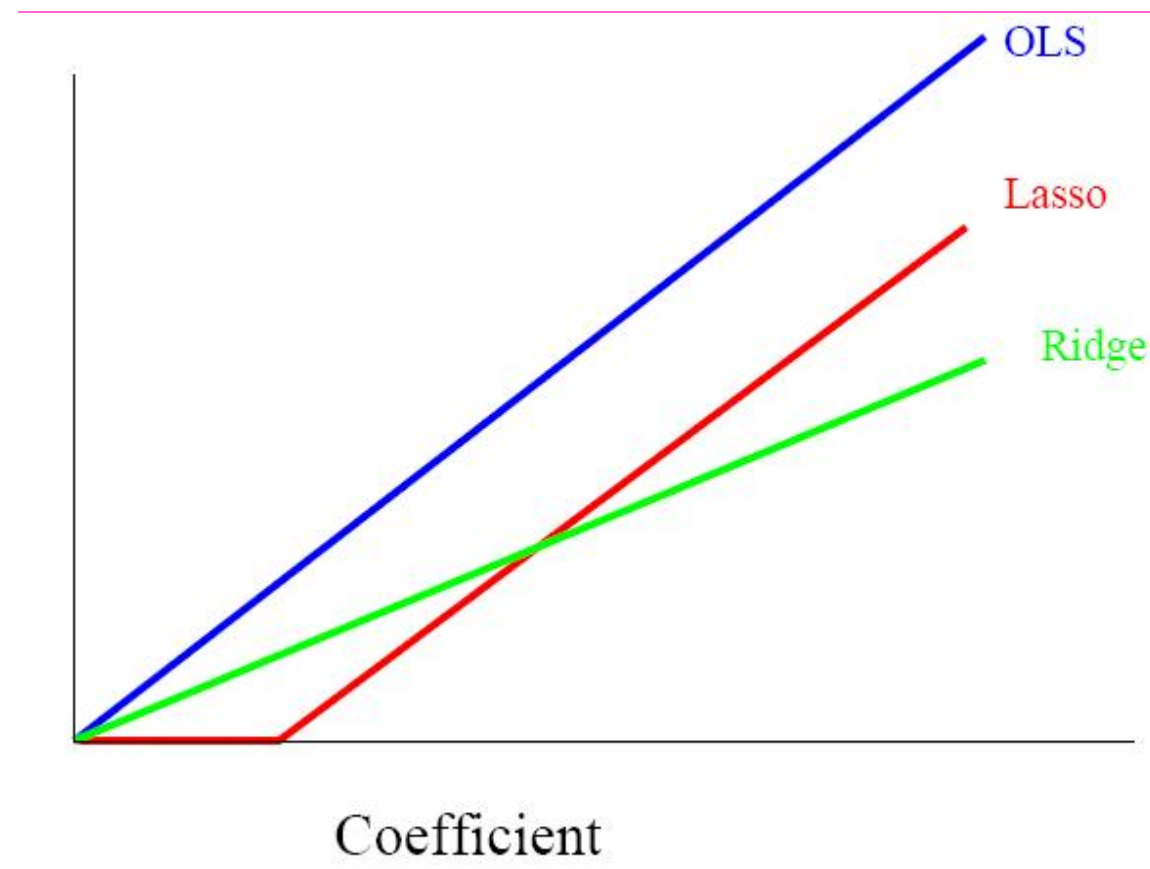


- Notice that ridge penalty  $\sum \beta_j^2$  is replaced by  $\sum |\beta_j|$
- This makes the solutions nonlinear in  $y$ , and a quadratic programming algorithm is used to compute them.
- Because of the nature of the constraint, if  $t$  is chosen small enough then the lasso will set some coefficients exactly to zero. Thus the lasso does a kind of continuous model selection.

# The Lasso



- The parameter  $t$  should be adaptively chosen to minimize an estimate of expected, using say cross-validation
- **Ridge vs Lasso:** if inputs are orthogonal,
  - ridge *multiplies* least squares coefficients by a constant  $< 1$ ,
  - lasso *translates* them towards zero by a constant, truncating at zero.



# A family of shrinkage estimators

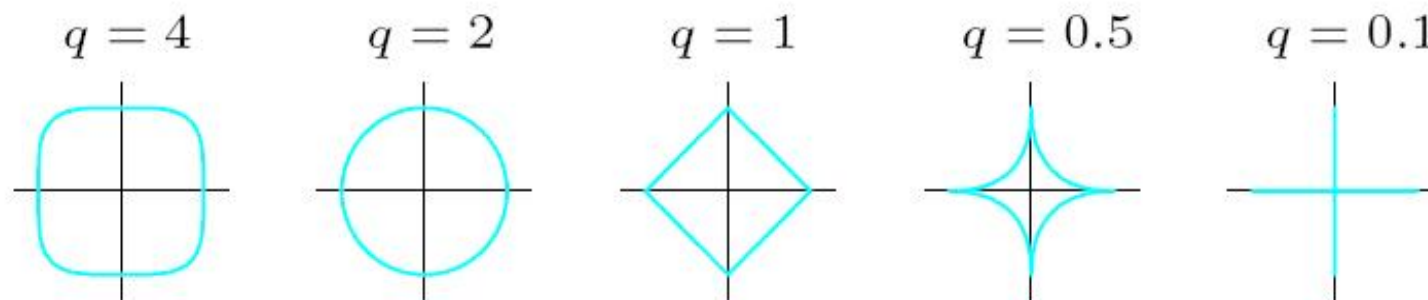


- Consider the criterion

$$\beta = \arg \min_{\beta} (Y - \mathbf{X}\beta)^T (Y - \mathbf{X}\beta)$$

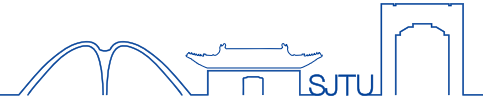
$$\text{subject to } \sum |\beta_j|^q \leq s$$

- for  $q \geq 0$ . The contours of constant value of  $\sum_j |\beta_j|^q$  are shown for the case of two inputs.



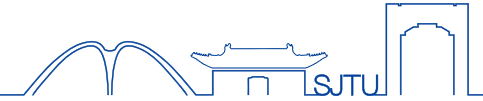
*Contours of constant value of  $\sum_j |\beta_j|^q$  for given values of  $q$ .*

# Contents



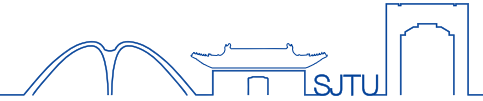
- The simple linear regression model
- Multiple linear regression
- Model selection and shrinkage —the state of the art
- **Principal component Regression**
- **Partial least squares Regression**

# Use of derived input directions

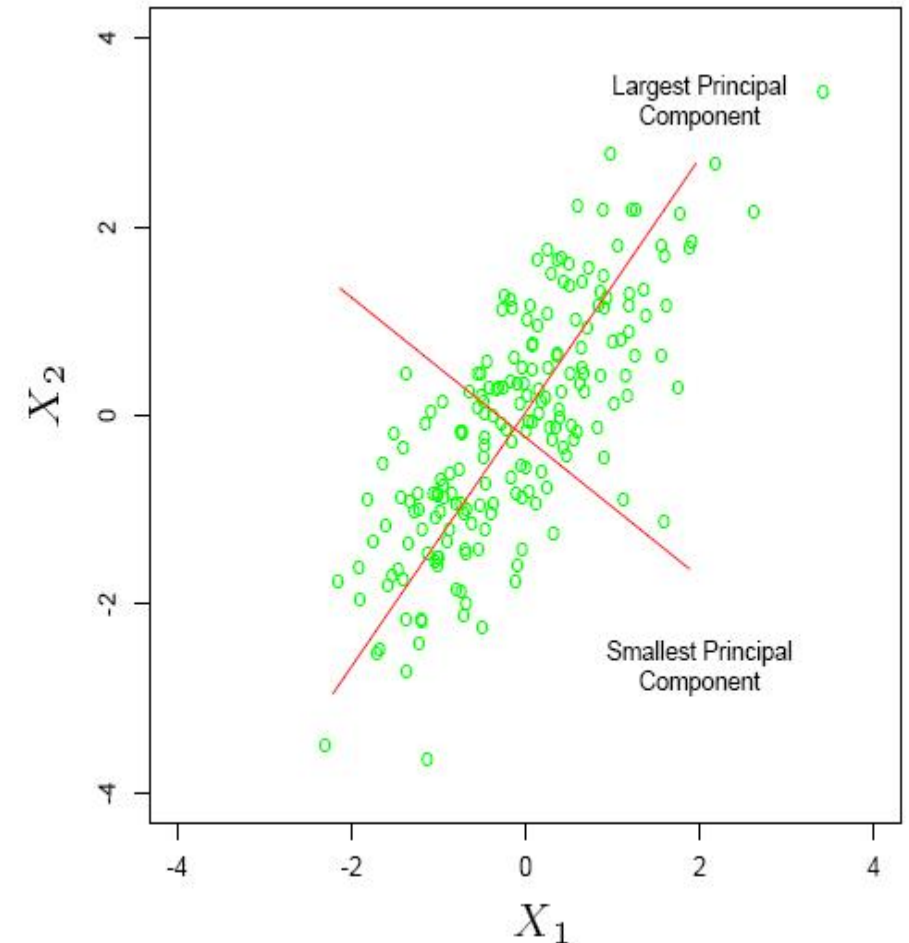


- **Principal components regression**
- Choose **a set of linear combinations** of the  $x_j$  s, and then regress the outcome on these linear combinations.
- **Principal components of the inputs**
  - Uncorrelated and ordered by decreasing variance.
- **If  $S$  is the sample covariance matrix of  $x_1, x_2, \dots, x_p$ , then the eigenvector equations  $Sq_l = d_l^2 q_l$  define the principal components of  $S$ .**

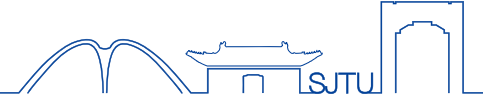
# Geometric Interpretation



- **Principal components of some input data points.** The largest principal component is the direction that maximizes the variance of the projected data, and the smallest principal component minimizes that variance.
- **Ridge regression projects  $y$  onto these components,** and then shrinks the coefficients of the low variance components more than the high-variance components.



# PCA regression



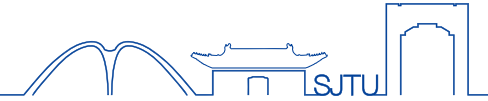
- Write  $q(j)$  for the ordered principal components, ordered from largest to smallest value of  $d_j^2$ .
- Then principal components regression computes the derived input columns

$$z_j = Xq(j)$$

and then regresses  $y$  on  $z_1, z_2, \dots, z_J$  for some  $J \leq p$ .



# PCA regression

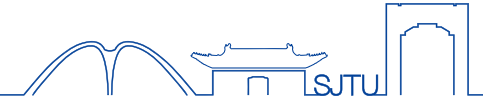


- Since the  $z_j$  s are orthogonal, this regression is just a sum of univariate regressions:

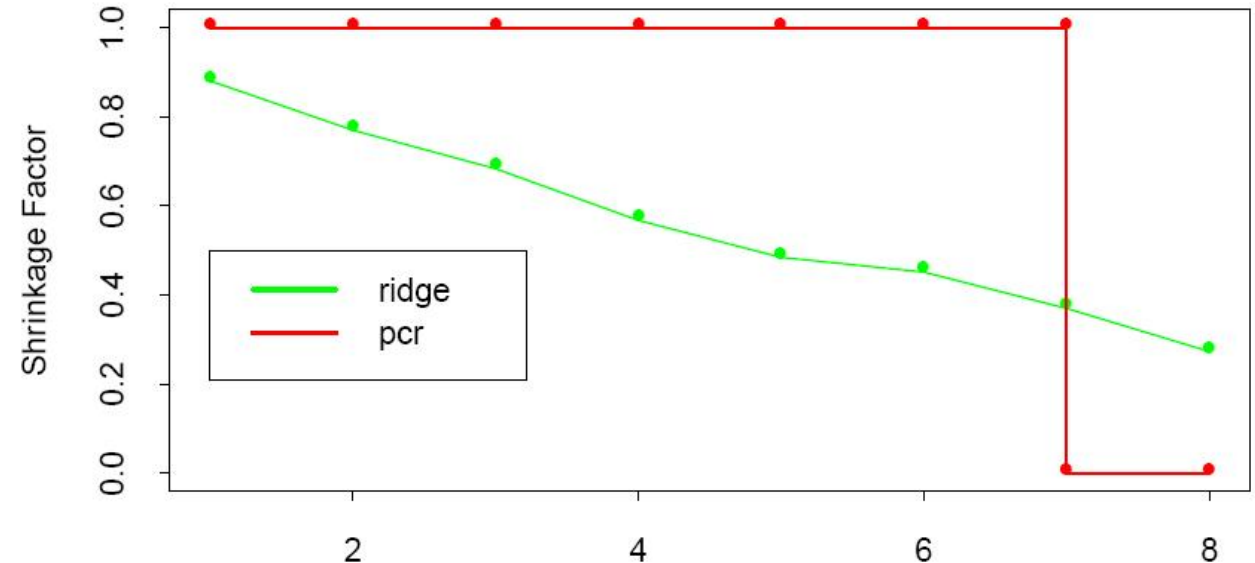
$$\hat{y}^{pcr} = \bar{y} + \sum_{j=1}^J \hat{\gamma}_j z_j$$

- where  $\hat{\gamma}_j$  is the univariate regression coefficient of  $y$  on  $z_j$ .
- **Principal components regression is very similar to ridge regression:** both operate on the principal components of the input matrix.

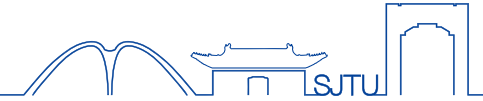
# PCA regression



- **Ridge regression shrinks the coefficients of the principal components**, with relatively more shrinkage applied to the smaller components than the larger
- **Principal components regression discards** the  $p-J+1$  smallest eigenvalue components.



# Partial least squares



- To construct a set of linear combinations of the  $x_j$  s for regression, but unlike principal components regression, it uses  $y$  (in addition to  $X$ ) for this construction.
  - We assume that  $x$  is centered and begin by computing the univariate regression coefficient

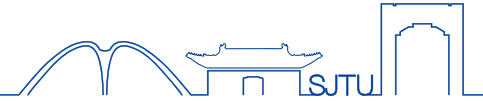
$$\hat{\gamma}_j = \langle x_j, y \rangle$$

- **From this we construct the derived input**

$$z_1 = \sum \hat{\gamma}_j x_j$$

- The first partial least squares direction.

# Partial least squares



- From this we construct the derived input

$$z_1 = \sum \hat{\gamma}_j x_j$$

– The first partial least squares direction.

- The outcome  $y$  is regressed on  $z_1$ , giving coefficient

$$z_1 : r_1 = y - \hat{\beta}_1 z_1$$

- Orthogonalize  $y, x_1, x_2, \dots, x_p$  with respect to  $z_1$

$$x_l^* = x_l - \hat{\theta}_l z_1$$

- Repeat the procedure

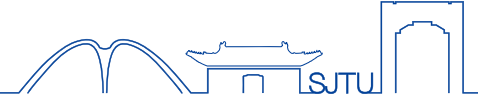
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**Algorithm 3.3** *Partial Least Squares.*

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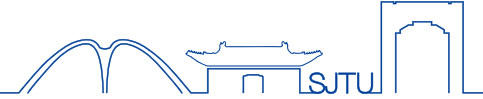
1. Standardize each  $\mathbf{x}_j$  to have mean zero and variance one. Set  $\hat{\mathbf{y}}^{(0)} = \bar{y}\mathbf{1}$ , and  $\mathbf{x}_j^{(0)} = \mathbf{x}_j$ ,  $j = 1, \dots, p$ .
2. For  $m = 1, 2, \dots, p$ 
  - (a)  $\mathbf{z}_m = \sum_{j=1}^p \hat{\varphi}_{mj} \mathbf{x}_j^{(m-1)}$ , where  $\hat{\varphi}_{mj} = \langle \mathbf{x}_j^{(m-1)}, \mathbf{y} \rangle$ .
  - (b)  $\hat{\theta}_m = \langle \mathbf{z}_m, \mathbf{y} \rangle / \langle \mathbf{z}_m, \mathbf{z}_m \rangle$ .
  - (c)  $\hat{\mathbf{y}}^{(m)} = \hat{\mathbf{y}}^{(m-1)} + \hat{\theta}_m \mathbf{z}_m$ .
  - (d) Orthogonalize each  $\mathbf{x}_j^{(m-1)}$  with respect to  $\mathbf{z}_m$ :  $\mathbf{x}_j^{(m)} = \mathbf{x}_j^{(m-1)} - [\langle \mathbf{z}_m, \mathbf{x}_j^{(m-1)} \rangle / \langle \mathbf{z}_m, \mathbf{z}_m \rangle] \mathbf{z}_m$ ,  $j = 1, 2, \dots, p$ .
3. Output the sequence of fitted vectors  $\{\hat{\mathbf{y}}^{(m)}\}_1^p$ . Since the  $\{\mathbf{z}_\ell\}_1^m$  are linear in the original  $\mathbf{x}_j$ , so is  $\hat{\mathbf{y}}^{(m)} = \mathbf{X} \hat{\beta}^{\text{pls}}(m)$ . These linear coefficients can be recovered from the sequence of PLS transformations.

# Ridge vs PCR vs PLS vs Lasso



- Recent study has shown that **ridge and PCR** outperform **PLS** in prediction, and they are simpler to understand.
- **Lasso outperforms ridge** when there are a moderate number of sizable effects, rather than many small effects. It also produces more interpretable models.
- These are still topics for ongoing research.

# Summary



- How to use LR methods appropriately.
- How to evaluate the performance of LR methods
  - Confidence Interval
  - MSE / Generalization
- How to improve the generalization performance
  - Data: Feature selection (based on  $p$ -value); Cross-validation
  - Shrinkage: Ridge; Lasso; PC regression; Partial least squares
- What is the purpose for imposing constraints on models?

# The End of Talk

