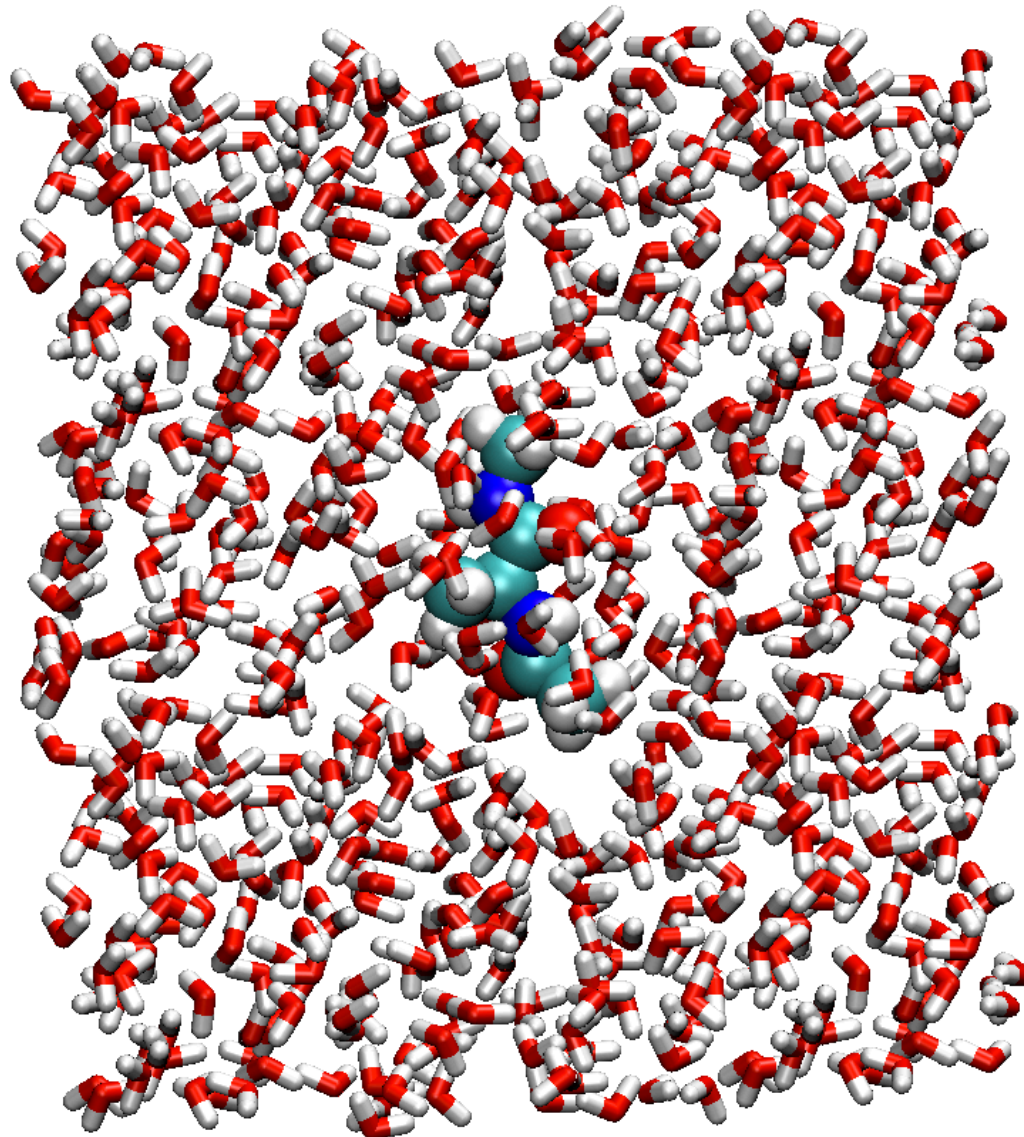


Exercise 1:

Let's ease into using OpenMM for MD simulations
The task: Simulate an alanine dipeptide in water



Remember: We can interface with OpenMM through python scripts

```
from simtk.openmm.app import *
from simtk.openmm import *
from simtk.unit import *
from sys import stdout

# Reading structure and force field files
pdb = PDBFile('input_exercise1.pdb')
forcefield = ForceField('amber99sb.xml', 'tip3p.xml')

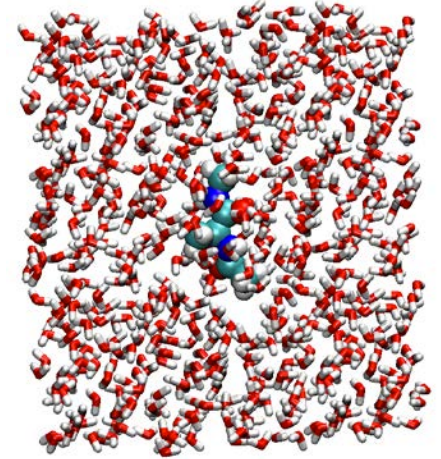
# Creating System
system = forcefield.createSystem(pdb.topology, nonbondedMethod=PME,
                                nonbondedCutoff=1.0*nanometer, constraints=HBonds)
integrator = LangevinIntegrator(300*kelvin, 1/picosecond, 0.002*picoseconds)

# Creating simulation context
simulation = Simulation(pdb.topology, system, integrator)
simulation.context.setPositions(pdb.positions)

# Minimizing System
simulation.minimizeEnergy(maxIterations=25)

# Adding Reporters
simulation.reporters.append(PDBReporter('output_exercise1.pdb', 5))
simulation.reporters.append(StateDataReporter(stdout, 100, step=True,
potentialEnergy=True, temperature=True))

# Running simulation
simulation.step(1000)
```



Let's give it a go ...

1. In your terminal window, go to the exercise directory.
2. Try running the exercise by typing: `python exercise1.py`

If you get “Import error” or “Library not found”, try this:

Mac OS X:

```
export DYLD_LIBRARY_PATH=/usr/local/openmm/lib:/usr/local/cuda/lib
```

Linux:

```
export LD_LIBRARY_PATH=/usr/local/openmm/lib:/usr/local/cuda/lib
```

Windows:

Refer to page 16 of the OpenMM Application Guide.

Your output will look something like this:

Creating System

Using Platform: OpenCL

Minimizing Energy

Adding Reporters to report Potential Energy and Temperature every 100 steps

Running Simulation for 1000 steps

Running step: 0

```
#"Step","Potential Energy (kJ/mole)","Temperature (K)"
```

```
100,-26643.6088239,175.727733927
```

Running step: 100

```
200,-26218.1442337,194.691558193
```

.

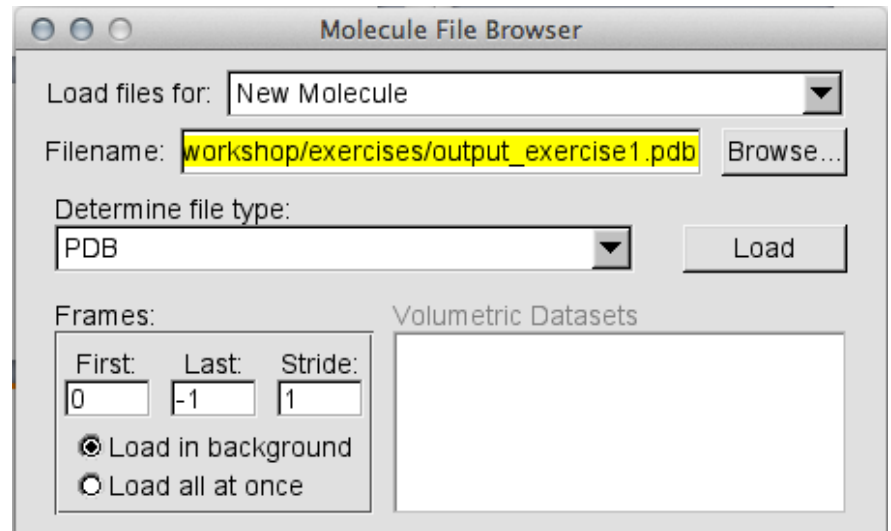
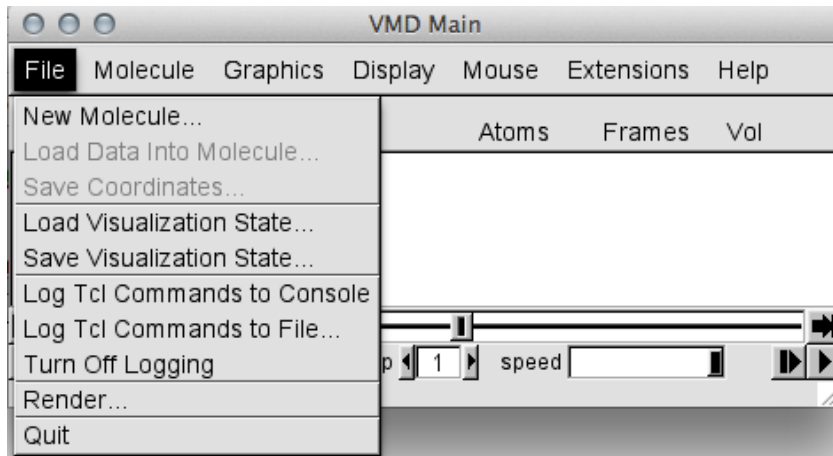
.

```
1000,-24957.7316677,283.859340959
```

Finished Simulation.

Let's now look at the simulation output

1. If your simulation ran on the Amazon cloud, download the output (psftp on Win, scp on Mac/Linux)
2. Open VMD



2. In 'VMD Main': Select **File** and **New Molecule...**
3. The 'Molecule File Browser' appears.
4. Click 'Browse' and select output_exercise1.pdb.
5. Click 'Load'.

Force fields available in OpenMM

Set with: `forcefield = ForceField('amber99sb.xml', 'tip3p.xml')`

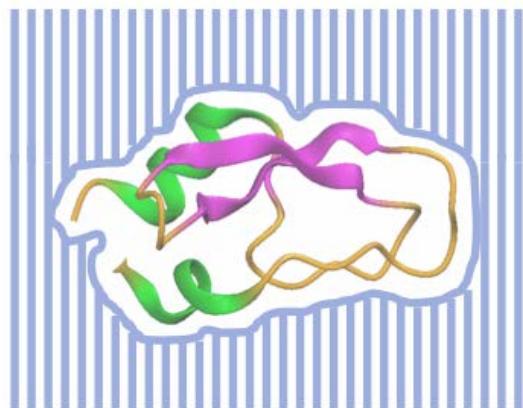
| File | Force Field |
|-------------------|---|
| amber96.xml | AMBER96 ¹ |
| amber99sb.xml | AMBER99 ² with modified backbone torsions ³ |
| amber99sbildn.xml | AMBER99SB plus improved side chain torsions ⁴ |
| amber99sbnmr.xml | AMBER99SB with modifications to fit NMR data ⁵ |
| amber03.xml | AMBER03 ⁶ |
| amber10.xml | AMBER10 |
| amoeba2009.xml | AMOEBA ⁷ (AMOEBA includes its own water model) |

New/currently unavailable and custom force fields can be added.

Check out talk by Lee-Ping tomorrow, March 27, 9:30 am!

Solvent models

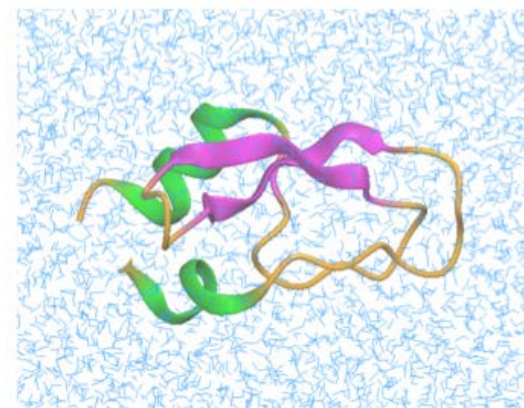
Set with: `forcefield = ForceField('amber99sb.xml', 'tip3p.xml')`



$$H = H_{\text{prot}} + \Delta G_{\text{solv}}$$

Implicit water model

- Fast (fewer atoms to track and less friction)
- Gets bulk properties 'right'



$$H = H_{\text{prot}} + H_{\text{prot-wat}} + H_{\text{wat}}$$

Explicit water model

- Slower (solvent atoms make up most of the system)
- Gets atomistic properties 'right'

Explicit solvent models ...

... parameterized to compensate for their simplified description of reality.

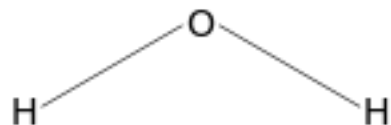
Most models have incomplete physics:

- Fixed point charges (no electronic polarization)
- Classical mechanics (no isotope effects)
- Fixed bond topology (no chemistry)

However, much can be recovered through parameterization:

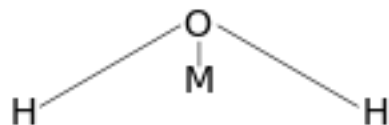
- Increase the partial charges, tune vdW parameters, etc.
- In many cases, force fields exceed the accuracy of quantum methods!

TIP3P



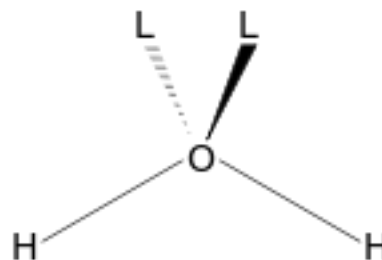
3-site

TIP4P EW

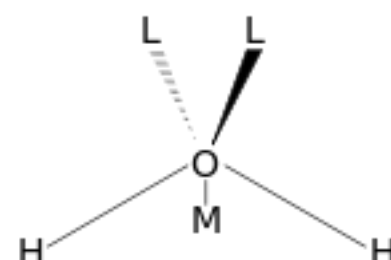


4-site

TIP5P



5-site



6-site

Implicit solvent models

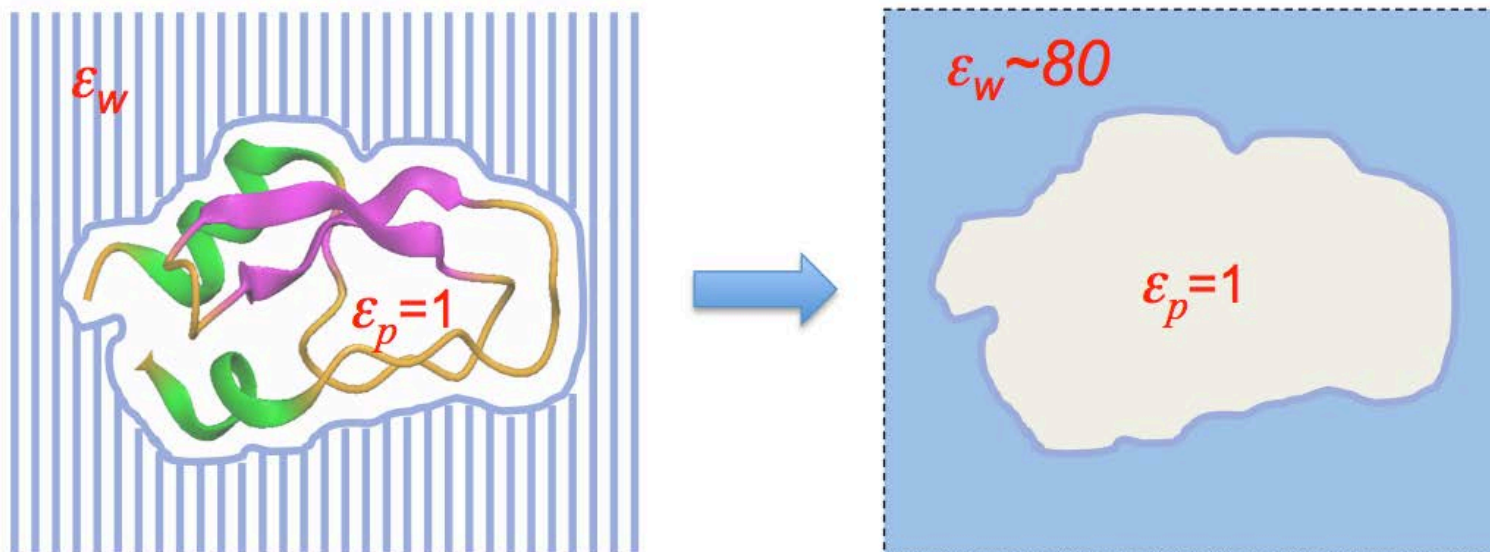
Water dynamics is typically much faster than that of protein conformational diffusion. Thus, water can be described as a **continuum** medium.

$$\Delta G_{\text{solv}} = \Delta G_{\text{elec}} + \Delta G_{\text{np}} \quad \Delta G_{\text{np}} = \gamma \cdot S$$

The electrostatic component is commonly computed using the generalized Born (GB) approximation:

$$\Delta G_{\text{elec}} \approx \frac{1}{2} \left(\frac{1}{\epsilon_w} - \frac{1}{\epsilon_p} \right) \sum_{ij} \frac{q_i q_j}{\sqrt{r_{ij}^2 + R_i^{\text{GB}} R_j^{\text{GB}} \exp(-r_{ij}^2 / 4 R_i^{\text{GB}} R_j^{\text{GB}})}}$$

This is then often augmented with a hydrophobic solvent accessible surface area (SA) term, giving the GBSA model.



Solvent models available in OpenMM

| File | Water Model |
|-------------|-----------------------------------|
| tip3p.xml | TIP3P water model ⁸ |
| tip4pew.xml | TIP4P-Ew water model ⁹ |
| tip5p.xml | TIP5P water model ¹⁰ |
| spce.xml | SPC/E water model ¹¹ |

| File | Implicit Solvation Model |
|-------------------|--|
| amber96_obc.xml | GBSA-OBC solvation model ¹² for use with AMBER96 force field |
| amber99_obc.xml | GBSA-OBC solvation model for use with AMBER99 force fields |
| amber03_obc.xml | GBSA-OBC solvation model for use with AMBER03 force field |
| amber10_obc.xml | GBSA-OBC solvation model for use with AMBER10 force field |
| amoeba2009_gk.xml | Generalized Kirkwood solvation model ¹³ for use with AMOEBA force field |

Integrators in OpenMM

```
integrator = LangevinIntegrator(300*kelvin, 1/picosecond, 0.002*picoseconds)
```

↓ ↓ ↓

Simulation Temperature Friction coefficient Timestep

Other Integrators:

Constant energy simulations:

```
VerletIntegrator(0.002*picoseconds)
```

Brownian Dynamics:

```
BrownianIntegrator(300*kelvin, 1/picosecond, 0.002*picoseconds)
```

Variable time step:

```
VariableLangevinIntegrator(300*kelvin, 1/picosecond, 0.001)  
VariableVerletIntegrator(0.001)
```

Temperature coupling:

```
system.addForce(AndersenThermostat(300*kelvin, 1/picosecond))
```

Pressure Coupling:

```
system.addForce(MonteCarloBarostat(1*bar, 300*kelvin))
```

But why don't we find out for ourselves?

Learning about the Integrator Class from OpenMM

Documentation page: https://simtk.org/api_docs/openmm/api5_0/python

OpenMM

Main Page

Classes

Class List

Class Hierarchy

Class Members

openmm

▶ app

openmm

▶ State

▶ Force

▶ AmoebaAngleForce

▶ AmoebaBondForce

▶ AmoebaGeneralizedKirkwood

▶ AmoebaInPlaneAngleForce

▶ AmoebaMultipoleForce

↔

Integrator Class Reference

An **Integrator** defines a method for simulating a **System** by integrating the equations of motion. [More...](#)

▼ Inheritance diagram for Integrator:

```
graph BT; BrownianIntegrator --> Integrator; CustomIntegrator --> Integrator; LangevinIntegrator --> Integrator; RPMDIntegrator --> Integrator; VariableLangevinIntegrator --> Integrator; VariableVerletIntegrator --> Integrator;
```

Constructor & Destructor Documentation

```
def __init__( self,  
             args  
            )
```

`init(OpenMM::LangevinIntegrator self, double temperature, double frictionCoeff, double stepSize) -> LangevinIntegrator` `init(OpenMM::LangevinIntegrator self, LangevinIntegrator other) -> LangevinIntegrator`

Create a **LangevinIntegrator**.

Parameters

temperature the temperature of the heat bath (in Kelvin)

frictionCoeff the friction coefficient which couples the system to the heat bath (in inverse picoseconds)

stepSize the step size with which to integrate the system (in picoseconds)

Reading values from an Integrator Object

OpenMM

Main Page

Classes

Class List

Class Hierarchy

Class Members

openmm

▶ app

openmm

▶ State

▶ Force

▶ AmoebaAngleForce

▶ AmoebaBondForce

▶ AmoebaGeneralizedKirkwood

▶ AmoebaInPlaneAngleForce

▶ AmoebaMultipleForce

↔

Integrator Class Reference

An **Integrator** defines a method for simulating a **System** by integrating the equations of motion. [More...](#)

▼ Inheritance diagram for Integrator:

```
graph BT; BrownianIntegrator --> Integrator; CustomIntegrator --> Integrator; LangevinIntegrator --> Integrator; RPMDIntegrator --> Integrator; VariableLangevinIntegrator --> Integrator; VariableVerletIntegrator --> Integrator;
```

Public Member Functions

```
def getTemperature  
    getTemperature(LangevinIntegrator self) -> double  
  
def setTemperature  
    setTemperature(LangevinIntegrator self, double temp)  
  
def getFriction  
    getFriction(LangevinIntegrator self) -> double  
  
def setFriction  
    setFriction(LangevinIntegrator self, double coeff)  
  
def getRandomNumberSeed  
    getRandomNumberSeed(LangevinIntegrator self) -> int  
  
def setRandomNumberSeed  
    setRandomNumberSeed(LangevinIntegrator self, int seed)  
  
def step  
    step(LangevinIntegrator self, int steps)  
  
def __init__  
    init(OpenMM::LangevinIntegrator self, double temperature, double frictionCoeff, double stepSize) -> LangevinIntegrator init(OpenMM::LangevinIntegrator self, LangevinIntegrator other) -> LangevinIntegrator  
  
def __del__  
    del(OpenMM::LangevinIntegrator self)
```

Setting non-bonded interactions in OpenMM

```
system = prmtop.createSystem(nonbondedMethod=NoCutoff, constraints=HBonds)
```

| Value | Meaning |
|-------------------|---|
| NoCutoff | No cutoff is applied. |
| CutoffNonPeriodic | The reaction field method is used to eliminate all interactions beyond a cutoff distance. Not valid for AMOEBA. |
| CutoffPeriodic | The reaction field method is used to eliminate all interactions beyond a cutoff distance. Periodic boundary conditions are applied, so each atom interacts only with the nearest periodic copy of every other atom. Not valid for AMOEBA. |
| Ewald | Periodic boundary conditions are applied. Ewald summation is used to compute long range interactions. (This option is rarely used, since PME is much faster for all but the smallest systems.) Not valid for AMOEBA. |
| PME | Periodic boundary conditions are applied. The Particle Mesh Ewald method is used to compute long range interactions. |

Constraining certain bonds and angles in OpenMM

```
system = prmtop.createSystem(nonbondedMethod=NoCutoff, constraints=HBonds)
```

| Value | Meaning | Time step |
|----------|--|-------------|
| None | No constraints are applied. This is the default value. | ≤ 1 fs |
| HBonds | The lengths of all bonds that involve a hydrogen atom are constrained. | 2 fs |
| AllBonds | The lengths of all bonds are constrained. | |
| HAngles | The lengths of all bonds are constrained. In addition, all angles of the form H-X-H or H-O-X (where X is an arbitrary atom) are constrained. | Up to 4 fs |

Constraints? \Rightarrow Larger integration time steps \Rightarrow Greater speedup.
(Note: Be aware of the added level of approximation and apply constraints with care.)

Hint: It's good practice to choose 'None' while heating a system. Once equilibrated, one can safely choose 'Hbonds' for production runs.

By default, bonds and angles of water molecules are constrained (accessible through `rigidWater` parameter):

```
system = prmtop.createSystem(nonbondedMethod=NoCutoff,  
constraints=None, rigidWater=False)
```

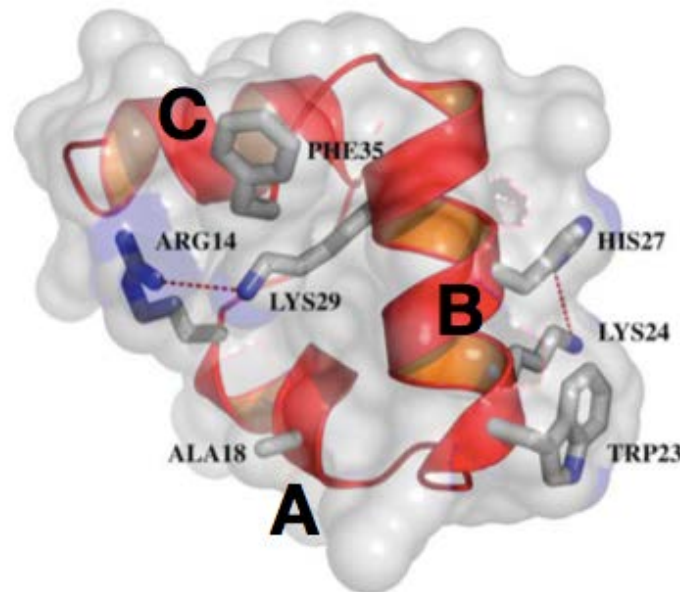

Reporters for printing values of State parameters during simulation:

```
simulation.reporters.append(StateDataReporter('data.txt', 1000, time=True,  
temperature=True, kineticEnergy=True, potentialEnergy=True, totalEnergy=True,  
volume=True, density=True, separator=' '))
```

Check out talk by Lee-Ping tomorrow, March 27, 2:15 pm!

Exercise 2: Simulating the villin headpiece in implicit solvent

Task: Set up the protein in the provided .pdb file and perform an implicit water MD.



Copy exercise1.py to exercise2.py
Use input_exercise2.pdb as the starting structure.

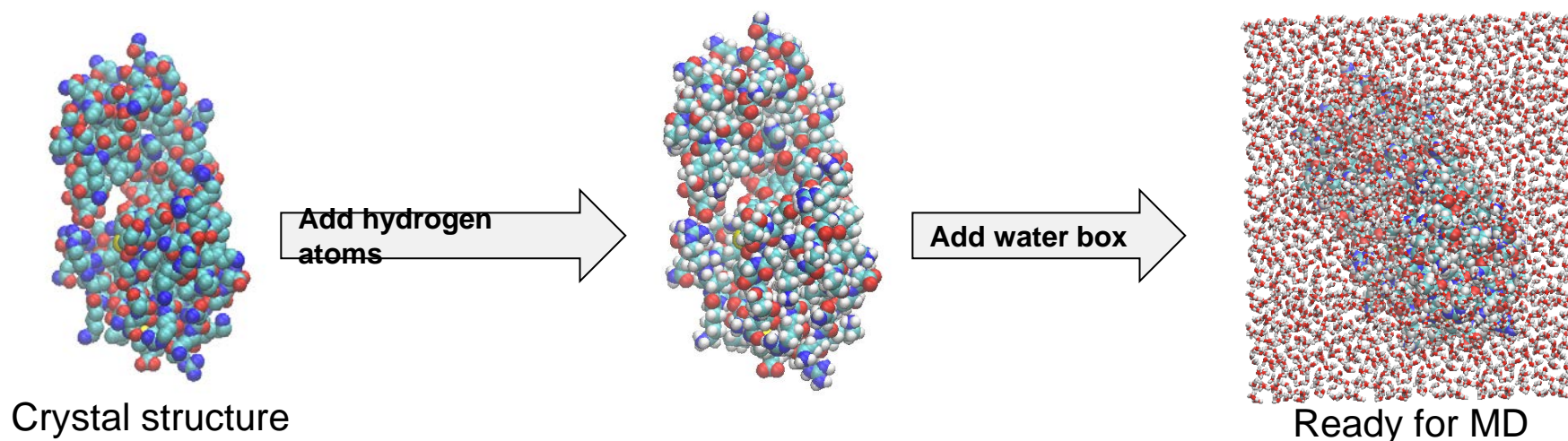
Exercise 2: Simulating the villin headpiece in implicit solvent

```
ValueError: No template found for residue 1 (LEU)
```

This message implies that there are missing atoms in the residues of this Protein. We need to use modeller class to build missing atoms.

Model Building and Editing with OpenMM

(refer OpenMM Application Guide section 5)



OpenMM modeller class can fix these issues.

```
pdb = PDBFile('input.pdb')
```

```
modeller = Modeller(pdb.topology, pdb.positions)
```

```
# ... Call some modelling functions here ...
```

```
system = forcefield.createSystem(modeller.topology, nonbondedMethod=PME)
```

Available modeller functions:

Adding Hydrogen: `modeller.addHydrogens(forcefield, pH=5.0)`

Adding Solvent: `modeller.addSolvent(forcefield, padding=1.0*nanometers, model='tip5p')`
`modeller.addSolvent(forcefield, boxSize=Vec3(5.0, 3.5, 3.5)*nanometers)`

Adding Ions: `modeller.addSolvent(forcefield, ionicStrength=0.1*molar, positiveIon='K+')`

Exercise 2: Simulating the villin headpiece in implicit solvent

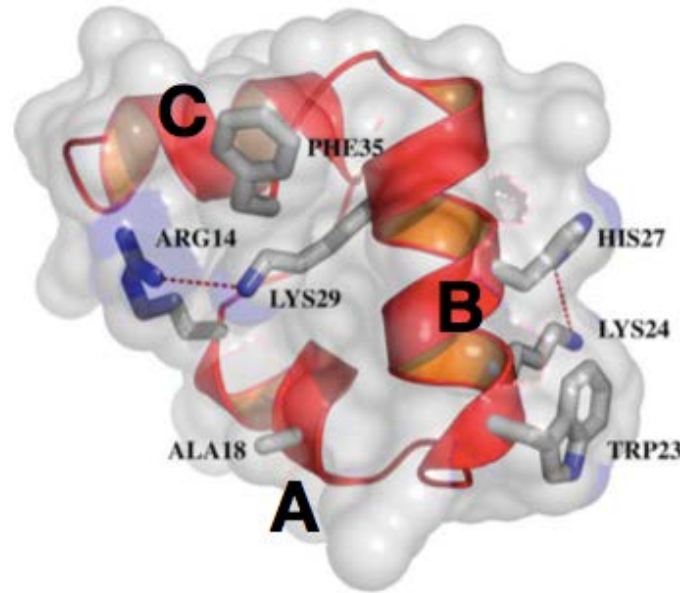
Task: Set up the protein in the provided .pdb file and perform an implicit water MD.

Instruction: Add modeller and replace the previous pdb.topology and pdb.positions with modeller.topology and modeller.positions.

```
pdb = PDBFile('input_exercise2.pdb')
forcefield = ForceField('amber99sb.xml', 'tip3p.xml')
print "Building Model.."
modeller = Modeller(pdb.topology, pdb.positions)
print('Adding hydrogens...')
modeller.addHydrogens(forcefield)
print "Creating System"
system = forcefield.createSystem(modeller.topology, constraints=HBonds)
integrator = LangevinIntegrator(300*kelvin, 1/picosecond, 0.002*picoseconds)
simulation = Simulation(modeller.topology, system, integrator)
print "Using Platform:", simulation.context.getPlatform().getName()
simulation.context.setPositions(modeller.positions)
```

Exercise 2: Simulating the villin headpiece in implicit solvent

Task: Set up the protein in the provided .pdb file and perform an implicit water MD.



Now that we fixed the error:

- Use **amber99_obc** as the implicit solvent model.
- Change friction parameter to **91/ps** for the implicit solvent model.
- Remove nonbonded parameters (method and cutoff) from the System object, which are necessary only for explicit solvent simulations.

Exercise 2: Simulating the villin headpiece in implicit solvent

Task: Set up the protein in the provided .pdb file and perform an implicit water MD.

Your input file should now look like this:

```
pdb = PDBFile('input_exercise2.pdb')
forcefield = ForceField('amber99sb.xml', 'amber99_obc.xml')
print "Building Model.."
modeller = Modeller(pdb.topology, pdb.positions)
print('Adding hydrogens...')
modeller.addHydrogens(forcefield)
print "Creating System"
system = forcefield.createSystem(modeller.topology, constraints=HBonds)
integrator = LangevinIntegrator(300*kelvin, 91/picosecond, 0.002*picoseconds)
simulation = Simulation(modeller.topology, system, integrator)
print "Using Platform:", simulation.context.getPlatform().getName()
simulation.context.setPositions(modeller.positions)
```

Exercise 3: Simulating the villin headpiece in explicit solvent

Task: Build a water box with the modeller class and perform an explicit water MD.

Instructions:

- Copy exercise1.py to exercise3.py
- Use input_exercise2.pdb as the starting structure.
- Continue using amber99sb and tip3p as the explicit solvent model.
- Add a box of explicit water molecules using the modeller class with a 1nm padding.

Exercise 3: Simulating the villin headpiece in explicit solvent

Task: Build a water box with the modeller class and perform an explicit water MD.

So, ...

... we copied exercise1.py to exercise3.py,
... used input_exercise2.pdb as the starting structure,
... used amber99sb and tip3p as the explicit solvent model,
... and added explicit water molecules using the modeller class.

```
pdb = PDBFile('input_exercise2.pdb')
forcefield = ForceField('amber99sb.xml', 'tip3p.xml')
print "Building Model..."
modeller = Modeller(pdb.topology, pdb.positions)
print('Adding hydrogens...')
modeller.addHydrogens(forcefield)
print "Adding Water.."
modeller.addSolvent(forcefield, model='tip3p', padding=1.0*nanometers)
print "Creating System..."
system = forcefield.createSystem(modeller.topology, nonbondedMethod=PME,
nonbondedCutoff=1.0*nanometer, constraints=HBonds)
integrator = LangevinIntegrator(300*kelvin, 1/picosecond, 0.002*picoseconds)
```