Machine Problem 4 - File System

CSIE3310 - Operating Systems National Taiwan University

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1 Overview

In this MP, you will implement three common file system features in xv6: symbolic links, access control, and RAID simulation. Successfully completing this MP requires a solid understanding of xv6's file system interface. Therefore, you are strongly encouraged to carefully read *Chapter 8: File System* in the xv6 book before getting started.

2 Environment Setup

1. Download mp4.zip from NTU COOL. Unzip it, and enter.

```
#!/bin/bash
$ unzip mp4.zip
$ cd mp4
```

2. Pull the docker image from the Docker Hub.

```
$ docker pull ntuos/mp4
```

3. In the mp4 directory, use docker run to enter the container.

```
$ docker run -it -v "$(pwd)":/home/xv6 -w /home/xv6 ntuos/mp4
```

3 Problem I - Access Control & Symbolic links (40 pts)

3.1 Introduction

Access control is typically used to manage file access permissions for each user. Although xv6 does not implement user accounts, access control is still valuable for preventing unintended access to files—for example, accidental writes to executables. Additionally, while xv6 currently supports only hard links, symbolic links are often preferred because they can link to directories and span across different file systems.

In this problem, you will add two features to xv6: access control and symbolic links. Specifically, you will implement two commands: symln and chmod, along with two system calls: sys_symlink and sys_chmod. You will also modify the ls command to display file permissions correctly, and update the open system call to handle symbolic links appropriately.

3.2 Implementation Overview

Although symbolic links and access control are conceptually independent, integrating both features into xv6 requires careful consideration of their interactions. For example, the behavior of chmod with symbolic links, 1s with symbolic links, and 1s in the presence of restricted read permissions must be handled correctly. These interactions are detailed in the specification below.

In our test cases, we will call the following commands: ls, chmod, symln and the open system call to verify your implementation.

Note that we have already provided the symlink system call and the symln command for you. However, you are responsible for adding the chmod system call and the chmod command to xv6 on your own.

3.3 Specification

To help you better understand the expected behavior of your implementation, we have divided the specification of this problem into several parts.

3.3.1 Part I: Basic Usage of symln

• The format of the symln command is:

```
$ symln old new
```

Which create a symbolic link called **new** pointing to the file/directory old.

- Make sure that your symbolic link works on both files and directories.
- We have defined a new file type T_SYMLINK in kernel/stat.h which has the value 4. Your 1s command should correctly show that a symbolic link has the file type 4. Here is an example:

- You do not need to check whether the links form a cycle or not. It is guaranteed that symbolic links in test cases will not form any cycle.
- Your system call should return 0 on success and -1 when error occurs, just like link or unlink.
- It is guaranteed that old always exists in the test cases. However, if new already exists, symln must fail by giving the following error message:

```
$ symln orig new
symln orig new: failed
```

• Whether symln successes or not should not be affected by the read/write permission of target.

3.3.2 Part II: Basic Usage of chmod and Access Control

- You only have to implement read and write permission.
- The format of chmod command is:

```
$ chmod [-R] (+|-)(r|w|rw|wr) file_name|dir_name
```

Where -R flag apply chmod recursively to each file and subdirectory, +r means adding the read permission, -rw means removing both the read and write permission, .etc. Note that rw is exactly the same as wr, it is listed for clarity, and your code should handle both cases.

- We do not set the format of the chmod system call, you are free to make your choice. We will call the chmod command in the test cases and we expect your chmod user program to call your self-designed chmod system call.
- Newly created files or directories (e.g. mkdir) have the default permission of both readable and writable (i.e. rw).
- It is guaranteed that -R only appears before permission, and only one file/directory will be given in a chmod command. Therefore, the following commands will NOT appear in our test cases: chmod +w -R abc_dir, chmod -rw abc.txt def.sh
- If the command format is incorrect, print the following error message:

```
$ chmod -R +o test_dir
Usage: chmod [-R] (+|-)(r|w|rw|wr) file_name|dir_name
```

• If the target file/directory does not exist, or cannot be opened due to lack of read permission, print the following error message:

```
$ chmod +w d1/d2/f chmod: cannot chmod d1/d2/f
```

Note: chmod +w d does not need the read permission of d, while chmod +w d/f does, because you have to read d to know if there is a f inside.

• Special Consideration: Try the following commands in your terminal (on your Ubuntu or macOS system, not in xv6):

```
$ mkdir testDir
$ touch testDir/a testDir/b
$ ls -al testDir # check current permission
```

```
$ chmod -R 000 testDir
chmod: cannot read directory 'testDir': Permission denied
```

The chmod command fails because it first removes the read permission from testDir, and then attempts to descend into the directory to modify the permissions of a and b. However, since testDir is no longer readable, this operation is immediately blocked. Interestingly, the command would succeed if the execution order were reversed.

The reason most UNIX-like systems behave this way is due to the UNIX philosophy: favoring simplicity over convenience. Recursive operations like chmod -R typically follow a top-down traversal strategy. Now that you have the opportunity to implement your own version of chmod, you should handle this edge case more robustly.

Please ensure that your chmod implementation is not blocked in the following edge cases:

- 1. When the -R flag is present, the target directory has read permission, and chmod is used to recursively remove the r permission from it.
- 2. When the -R flag is present, the target directory lacks read permission, and chmod is used to recursively add r or w permission add r permission to it.

Hint: If you view the directory structure as a tree graph, in which traversal order(s) can you successfully perform chmod -R -r on a readable directory and chmod -R +r on an unreadable directory?

3.3.3 Part III: The Output of 1s

• The output format of the ls command is:

```
[file_name] [type] [inum] [size] [mode]
```

In the mode field, \mathbf{r} indicates read permission, \mathbf{w} indicates write permission, and \mathbf{r} represents the absence of a permission. The read permission (\mathbf{r}) always appears before the write permission (\mathbf{w}). Refer to the example in the Guidance section for more details.

Note that our tests will only verify the correctness of the file_name, type, and mode fields. The inum and size fields may contain any number, but they must be included in the output.

- Listing a file or directory with ls requires that the target file or directory itself has read permission. However, listing the contents of a directory does not require any specific permissions on the files or subdirectories within it. For example, if d is a directory, then ls d requires d to be readable. The entry d/f will be shown as long as d has read permission, regardless of the permissions set on d/f.
- 1s should output the following error message if the directory/file has no read permission:

```
$ ls f
ls: cannot open f
```

3.3.4 Part IV: About the Symbolic Links

- The permission of a symbolic link itself does not have any meaning and should always have rw permission.
- Applying chmod to a symbolic link always changes the permission of the target file/directory but not the link itself.
- Here we discuss how ls works on a symbolic link (Note: These behaviors might differ a little from the real UNIX kernel since we do not implement the execute permission mode):
 - 1. If x is a symbolic link to a file f, ls x should give the detail of x itself, not f.
 - 2. If x is a symbolic link to a directory d, ls x should list the content of d.
 - 3. If x is a symbolic link to a file f, and f does not have the r permission, ls x should not be affected. However, if f is inside of any directory that has no r permission, ls x should fail.
 - 4. If x is a symbolic link to a directory d, ls x should fail when d has no r permission or d is inside a directory that has no r permission.

3.3.5 Part V: open Mode Check

- We provide a new flag, O_NOACCESS, defined in kernel/fcntl.h. When the open system call is invoked with this flag:
 - 1. It should return a file descriptor (fd) for which the underlying file is neither readable nor writable.
 - 2. The file metadata must remain accessible via the fstat system call.
 - 3. If the specified path is a symbolic link, the link should not be followed. Otherwise, when O_NOACCESS is not set, symbolic links must always be followed.

The O_NOACCESS flag is useful for retrieving metadata (e.g., via stat, fstat) on files that do not grant any read or write permission, such as when listing the contents of a directory using ls.

- Make sure that your open system call denies when the provided flags does not meet the file's/directory's permission. e.g. if f does not have the r permission, open(f, O_RDONLY) should fail.
- In our test cases, we will call your open system call with some mode flags. While you are not asked to validate the mode flags in open, we will follow the policy below when calling open() in our test cases.
 - 1. Exactly one from O_RDONLY, O_WRONLY, O_RDWR, O_NOACCESS will be chosen.
 - 2. O_TRUNC will be used along with write permission.
 - 3. O_NOACCCESS will be used alone.
 - 4. A directory, or a symbolic link to a directory, will only be opened with either O_RDONLY or O_NOACCESS.

3.4 Guidance

Since we understand that this problem is quite complicated, we provide overall steps to help you complete this problem. Feel free to follow your own way if you have other ideas.

- 1. **Implement symlink**: We recommend you to first complete the basic logic of symbolic link, since it is rather simple compared to other tasks.
 - You should think about how and where to store the target file/directory in the symbolic link. Maybe the inode data block is a good idea.
- 2. Add modes: We have defined 3 mode constants in kernel/stat.h: M_READ, M_WRITE, and M_ALL. Add a new mode field in appropriate places to store mode as part of the metadata of a file.
 - Hint1: Consider adding mode in struct inode, struct stat...
 - Hint2: Can you arbitrarily modify the size of struct inode? Which field is a good trade-off to be replaced?

3. Initialize modes:

- Go to iupdate, ilock, stati and ialloc in kernel/fs.c to set the mode field correctly.
- Go to mkfs/mkfs.c to modify ialloc to initialize the mode of each file. We encourage you assign r- mode to executables and rw to other files to follow the convention, but we will not check this in our test cases.
- 4. Modify 1s: Go to user/ls.c to make sure that 1s command shows the correct permissions at the end of each line:

5. Implement chmod:

• Complete the system call sys_chmod(...) in kernel/sysfile.c. You have to add this system call on your own. Possible files to be modified to add a system call include kernel/syscall.c, kernel/syscall.h, user/usys.pl, ...

- Create a user program user/chmod.c (don't forget to modify Makefile as well) to make the chmod command available.
- 6. Check permission: Modify the open system call to ensure that open succeeds only if the provided omode is allowed by the file's permission. Also, remember to validate the omode, and fails when the given mode is illegal (You do not have to validate whether mode flag is legal or not, as mentioned in the last bullet point of Part V: open Mode Check). Test your implementation with 1s, chmod, cat .etc.

3.5 Test

This problem accounts for 40 points, where 20 points are public test cases. Each test case consists of the following steps:

- 1. Run gen command to generate some directory structures.
- 2. Run the commands: symln, chmod and ls arbitrary times in arbitrary order and collect the output.
- 3. Run mp4_1 to test your open and fstat system call.

Additionally, we guarantee that in each test case:

- 1. The length of any file/directory's name is less than or equal to 13.
- 2. We will not cd to other directory. All commands are run at the root directory.
- 3. We will not 1s the root directory. We will only 1s the directories/files/symbolic links we create.
- 4. The depth of a path will be at most 5, e.g. /d1/d2/d3/d4/f.
- 5. We will only create regular directories and plain-text files in the test cases, no executables will be created. (, and recall that all newly created files/directories should have the default permission rw.)
- 6. Your xv6's output requested by **Problem II** will not affect your grade in **Problem I**. We will ignore all output lines starting with "BW_DIAG" or "BW_ACTION".

You can test how many points you would get in public test cases by running make grade inside the docker container. We will test your submission in the same way with some private test cases.

4 Problem II - RAID 1 Simulation (60 points)

RAID 1, or disk mirroring, is a technique used to increase data reliability by writing identical data to two separate disks simultaneously. If one disk fails, the data can still be retrieved from the other disk.

This assignment involves implementing a simulation of RAID 1 at the block I/O layer (specifically within the buffer cache functions) in xv6. The goal is to ensure data redundancy during writes and to implement a basic read fallback mechanism in case the primary disk block is unavailable (simulated failure).

4.1 Provided Environment & Configuration

You will start with a modified xv6 environment where:

- Disk Size: The total virtual disk size (FSSIZE) has been set to 4096 blocks.
- RAID 1 Layout: The disk is logically divided into two parts for mirroring:
 - Disk 0 (Primary): Uses physical blocks 0 through 2047. All standard filesystem operations target logical blocks within this range (Logical Block Numbers 0 to 2047).
 - Disk 1 (Mirror): Uses physical blocks 2048 through 4095. This disk serves as a mirror copy of Disk 0.
- Constants: Relevant constants are defined (likely in kernel/param.h or included via headers):
 - LOGICAL_DISK_SIZE (=2048): The size of the logical filesystem view (and Disk 0).
 - DISK1_START_BLOCK (=2048): The starting physical block number for the mirror disk (Disk 1).
- Target File: Your primary modifications will be within kernel/bio.c.

• **Testing Mechanism:** The instructor's kernel includes a mechanism to **simulate** read failures on Disk 0 to test your fallback logic (details in Part 2).

4.2 Specification

We split the specification into three main implementation parts:

4.2.1 Part I: Mirrored Writes (Modify bwrite)

- Requirement: All write operations intended for the logical filesystem must be mirrored. When the kernel requests to write data to a logical block 1bn (where 0 <= 1bn < LOGICAL_DISK_SIZE), your code must ensure this data is physically written to both Disk 0 and Disk 1.
- Implementation Target: Modify the bwrite(struct buf *b) function in kernel/bio.c.
- Details:
 - The incoming buffer b contains the data to be written, and b->blockno initially holds the target physical block number.
 - Calculate the corresponding physical block number for Disk 0 (pbn0) and Disk 1 (pbn1 = pbn0 + DISK1_START_BLOCK).
 - Crucial: Before each call to virtio_disk_rw, you must temporarily set b->blockno to the correct physical block number (pbn0 or pbn1) that virtio_disk_rw needs. After both physical writes are complete, you must restore b->blockno back to its original block number before bwrite returns. Failure to restore b->blockno will corrupt the buffer cache.

4.2.2 Part II: Write Fallback logic (Modify bwrite)

In this part of the assignment, you will modify the bwrite function in kernel/bio.c. The goal is to make bwrite respond to "simulated disk failure" and "simulated block failure" by printing specific messages showing the intended write actions (attempting or skipping).

- Requirement: The actual disk write process in xv6 is quite complex, involving the logging system (log.c with its commit() and install_trans() functions) and the underlying virtio_disk_rw function. To allow you to focus on the decision-making logic of RAID 1 under failure conditions, this assignment simplifies certain aspects:
 - You are not required to modify virtio_disk_rw itself or prevent data from actually being written
 to the disk by the low-level driver when a failure is simulated.
 - Your core task is: when the bwrite function is called, it must correctly identify the simulated failure state (set by the force_read_error_pbn or the force_disk_fail_id) and print specific messages showing whether it would attempt a write or skip a write to PBN0 and PBN1.
- Simulated Failure Paramters (Controlled by TAs): Your bwrite function will need to be aware of and use the following global kernel variables, which will be set by the TA's test programs.
 - 1. int force_disk_fail_id:
 - -1: Normal operation, no simulated disk failure.
 - 0: Simulated Disk 0 (the primary logical disk, PBN0s) as failed.
 - 1: Simulated Disk 1 (the mirror logical disk, PBN1s) as failed.
 - 2. int force_read_error_pbn:
 - -1: Normal operation, no simulated specific block failure.
 - PBN: If this value matches the *current* PBNO that bwrite is about to operate on, it simulates a block-level write failure for that specific PBNO.
- **Details:** When bwrite is called (where b->blockno is the block number from the file system), which is PBNO for your RAID layer:
 - 1. Calculate pbn0 and pbn1.
 - 2. Read the current values of the global simulation variables force_disk_fail_id and force_read_error_pbn.

3. Print diagnostic message: Display the current PBNO, calculated PBN1, and the current state of the simulation flags (force_disk_fail_id and whether force_read_error_pbn matches the current pbn0). Use a clear format for this message:

```
printf(
    "BW_DIAG: PBN0=%d, PBN1=%d, sim_disk_fail=%d, sim_pbn0_block_fail=%d\n",
    pbn0, pbn1, fail_disk, pbn0_fail_or_not);
```

- pbn0: The physical block number to write on Disk 0.
- pbn1: The physical block number to write on Disk 1.
- fail_disk: Current simulated fail disk (must be -1, 0 or 1).
- pbn0_fail_or_not: If pbn0 is simulated as failure. (must be 0 or 1).

4. Action for PNB0 (Disk 0) Write:

If Disk 0 is simulated as failed (via force_disk_fail), bwrite should not attempt the virtio_disk_rw for PBNO. Print a specific "skip" message:

```
printf(
    "BW_ACTION: SKIP_PBNO (PBN %d) due to simulated Disk 0 failure.\n",
    pbn0);
```

- * pbn0: The physical block number to write on Disk 0.
- Else, if the current PBNO is simulated as a "bad block" for writing (via force_read_error_pbn),
 bwrite should also not attempt the virtio_disk_rw for PBNO. Print a specific "skip" message:

```
printf(
    "BW_ACTION: SKIP_PBNO (PBN %d) due to simulated PBNO block "
    "failure.\n",
    pbnO);
```

 Otherwise (PBN0 is clear for writing), bwrite should attempt the write, and print an "attempt" message:

```
printf(
    "BW_ACTION: ATTEMPT_PBNO (PBN %d).\n",
    pbn0);
```

- 5. Decision and Action for PBN1 (Disk 1) Write:
 - If Disk 1 is simulated as failed (via force_disk_fail), bwrite should not attempt the virtio_disk_rw for PBN1. Print a specific "skip" message:

```
printf(
   "BW_ACTION: SKIP_PBN1 (PBN %d) due to simulated Disk 1 failure.\n",
   pbn1);
```

Otherwise (Disk 1 is clear for writing; note that force_read_error_pbn only directly targets PBNO for simulation purposes in this assignment – if PBNO fails at a block level, the write to PBN1 should still be attempted unless Disk 1 itself is failed), bwrite should attempt the write, and print an "attempt" message:

```
printf(
    "BW_ACTION: ATTEMPT_PBN1 (PBN %d).\n",
    pbn1);
```

6. **Restore** b->blockno: At the end of all operations, you must restore b->blockno to the original incoming block number (which was PBNO) to ensure Buffer Cache consistency.

- Important Note on Real RAID 1 Behavior: Although this assignment simplifies write failure handling by focusing on your decision logic and printf messages (and not requiring you to prevent the underlying virtio_disk_rw from actually succeeding if it's called), it's crucial to understand that:
 - In a real, robust RAID 1 system, when a write to one disk or block fails, the system's goal is to preserve data integrity and availability on at least one copy.
 - This means if Disk 0 or PBN0 fails a write, a real RAID 1 system would still try its best to successfully write the data to the healthy Disk 1 or PBN1, and vice-versa. The write operation to the logical block is generally considered successful if at least one mirror copy is successfully written.
 - The simplification in this assignment is to allow you to focus on implementing the correct conditional logic for attempting or skipping writes based on the simulation flags.

4.2.3 Part III: Read Fallback Logic (Modify bread)

- Requirement: Implement a read fallback mechanism. Normally, reads should be served from Disk 0. However, if a read attempt on Disk 0 fails (this failure will be **simulated** during testing), your code must automatically attempt to read the data from the corresponding block on Disk 1.
- Implementation Target: Modify the bread(uint dev, uint blockno) function in kernel/bio.c.

• Details:

- The incoming blockno argument represents the block number that the filesystem layer wants to read (this will be a value between 0 and LOGICAL_DISK_SIZE 1, corresponding to a block on Disk 0). The bget function will provide a buffer b associated with this LBN.
- Your primary logic modification should occur within the part of bread that handles reading data from the disk (typically inside the if(!b->valid || force cache misses logic).
- Normal Path: Calculate pbn0 = blockno. Attempt to read physical block pbn0 using the underlying I/O function.
- Fallback Path Trigger (Simulation): To allow testing, the instructor's kernel contains a global variable extern int force_disk_fail_id and extern int force_read_error_pbn. Your bread implementation must check if the current failure disk is equal to disk 0, or if the physical block it is about to read from Disk 0 (pbn0) is equal to the current value of force_read_error_pbn.
- Fallback Action: If simulate_error is true, skip the read from pbn0, calculate pbn1, and attempt
 to read from pbn1 instead.
- Return Value: bread should return the buffer b containing the correct data, whether it came from pbn0 (normal path) or pbn1 (fallback path).
- Error Handling: You are not required to handle real hardware I/O errors reported by virtio_disk_rw.
 The focus is on correctly implementing the fallback logic based on the force_disk_fail_id or force_read_error_pbn simulation.

4.3 Files to Modify

- Primarily: kernel/bio.c
- You might need to include the headers you need.

4.4 Test

This problem accounts for 60 points, where 30 points are public test cases (disk failure), other 30 points for private test cases (block failure).

- 1. Correctness of mirrored writes (data identical on PBN0 and PBN1). We will check it using raw_read system call in our test instead of bread. Raw_read will directly read the data in the block.
- 2. Check the required printed message mentioned above while forcing failure on bwrite.

3. Correctness of the read fallback logic when triggered by the force_read_error_pbn or force_disk_fail_id simulation. We will use raw_read to modify the data in the failure block or failure disk, so be sure you will return the right data.

5 Bonus Report

We encouraged you to help other students. Please describe how you helped other students here. You should make the descriptions as short as possible, but you should also make them as concrete as possible (e.g., you can screenshot how you answered other students' questions on NTU COOL). Please note that you will not get any penalty if you leave it empty here. Please also note that this bonus is not for you to do optimization, so we will not release the grading criteria and the grades. Regarding the final letter grades, it is very likely that this does not help - you will get promoted to the next level only if you are near the boundary of levels and you have significant contributions.

6 Submission

Please submit your <student_id>.patch to NTU COOL, and your bonus report to Gradescope.

6.1 Bonus Report

Submit your report to the Bonus Report section on Gradescope in one pdf file.

6.2 xv6

The submission of this MP use diff to generate a patch file. Note that the following commands are available on Linux and macOS only. For Windows users, there are 2 workarounds to run diff:

- 1. If you have installed Git for Windows, you should have Git Bash on your computer. You can run the commands below in Git Bash.
- 2. Install WSL, Window Subsystem for Linux, and run the commands below in WSL. You can refer to the slides of MP0 for the WSL installation guide.

If neither way is applicable, feel free to book a TA hour. We will try to help you with your issue.

6.2.1 Submission Format

In this MP, we only accept a patch file as your submission. Please generate the patch file by the instructions below:

1. Clean your workspace, and backup your progress in case you erase all your work accidentally.

```
root@2a6008d5c4dc:/home/xv6# make clean
root@2a6008d5c4dc:/home/xv6# # ctrl D to stop and leave container
user@host ~/os/mp4 $ cd ..
user@host ~/os $ cp -r mp4 mp4-bk
```

2. Rename you current mp4 directory. Please make sure you do so, or it is very likely that your progress will be overwritten by unzip.

```
user@host ~/os $ mv mp4 mp4-new
```

3. Download mp4.zip AGAIN from NTU COOL and unzip it.

```
user@host ~/os $ unzip mp4.zip
```

- 4. Now you have mp4-new, the folder containing you work, and mp4, the original mp4.
- 5. Use diff to generate a patch file. You may add more --excludes to filter out unrelated files. And please do not mix up the order of mp4 and mp4-new.

```
user@host ~/os $ diff -ruN \
--exclude='.git' \
--exclude='.vscode' mp4 mp4-new > <student_id>.patch
```

It is normal that diff exit with code 1. diff returns 0 if two files are the same and returns 1 if they are different. Please check the return code with echo \$?

6. Upload <student_id>.patch to NTU COOL, e.g. r13922001.patch. The leading letter should be lowercase.

We will apply your patch and test your code using the following command:

```
$ cd mp4 # this is the original mp4
$ patch -p1 \
--exclude="gradelib.py" \
--exclude="grade-mp4.py" \
--exclude="user/gen.c" \
--exclude="user/mp4_1.c" \
--exclude="user/mp4_2_disk_failure_test.c" \
--exclude="user/mp4_2_forcetest.c" \
--exclude="user/mp4_2_mirror_test.c" \
--exclude="user/mp4_2_mirror_test.c" \
--exclude="user/mp4_2_write_failure_test.c" < ../<student_id>.patch
$ make grade
```

Furthermore, if your patch file creates/modifies/deletes files that are listed here, there will be a point penalty.

- Grading-related files (user/gen.c, user/mp4_1.c, user/mp4_2*.c, gradelib.py, grade-mp4.py)
- Object files, dependency files, or any file that can be removed by make clean.
- Other unrelated files, including but not limit to .git, .vscode, .idea, ...

Note: Any attempt to manipulate the grading process—such as modifying the behavior of make grade by tampering with the grade command in the Makefile—will result in severe consequences.

6.3 Grading Policy

- The total points of this MP is 100 points.
- You will get 0 points if we cannot apply your patch or compile your submission. You will also get 0 points if you submit anything other than a patch file, e.g. the whole mp4.zip.
- You will be deducted 10 points if the name of the patch is wrong. Using uppercase in the <student_id>.patch or not suffixing the file name with .patch are both considered wrong.
- If your submission is late for n days, your score will be $max(raw_score 20 \times \lceil n \rceil), 0)$. Note that you will not get any points if $\lceil n \rceil >= 5$.

7 References

- [1] xv6, a simple Unix-like teaching operating system. https://pdos.csail.mit.edu/6.828/2024/xv6.html
- [2] Docker: Empowering App Development for Developers. https://docs.docker.com/
- [3] RISC-V: The Free and Open RISC Instruction Set Architecture. https://riscv.org/
- [4] QEMU, the FAST! processor emulator. https://www.qemu.org/