

1 Regression Model

We will talk about the conditional mean model and the linear projection model.

Notation: in this note, y is a scale random variable, and x is a $K \times 1$ random vector.

1.1 Conditional Expectation Model

A regression model can be written as $y = m(x) + \epsilon$, where $m(x) = E[y|x]$ is called the *conditional mean function*, and $\epsilon = y - m(x)$ is called the *regression error*.

The error term ϵ satisfies the following properties.

- $E[\epsilon|x] = 0$,
- $E[\epsilon] = 0$,
- $E[h(x)\epsilon] = 0$, where h is a function of x .

The last one means that ϵ is uncorrelated with any function of x .

The conditional expectation function is of interest, because it is the best prediction of y under the *mean squared error* (MSE).¹

Among all the functions $g(X)$, the conditional mean function $m(x)$ minimizes the MSE.

¹The quadratic loss function is between y and a prediction $g(x)$ is defined as $L(y, g(x)) = (y - g(x))^2$, and its expectation $R(y, g(x)) = E[(y - g(x))^2]$ is called the MSE.

Proof. We take a guess-and-verify approach.

$$E \left[(y - g(x))^2 \right] = E \left[(y - m(x))^2 \right] + 2E \left[(y - m(x))(m(x) - g(x)) \right] + E \left[(m(x) - g(x))^2 \right].$$

The first term is irrelevant to $g(x)$. The second term is $2E \left[\epsilon(m(x) - g(x)) \right] = 0$, which is again irrelevant of $g(x)$. The third term is minimized at $g(x) = m(x)$. \square

1.2 Linear Projection Model

As discussed in the previous section, we are interested in the conditional mean function $m(x)$. However, $m(x)$ is a complex function depending on the joint distribution of (y, x) . A special case is $m(x) = x'\beta$, that is, the conditional mean function is a linear function of x .² It is true if (y, x) follows a joint normal distribution. Even if $m(x) \neq x'\beta$, the linear $x'\beta$ is still useful as an approximation, as will be clear soon. Therefore, we may write the linear regression model, or the linear projection model, as

$$y = x'\beta + e \tag{1}$$

$$E[xe] = 0, \tag{2}$$

where e is called the *projection error*. Eq.(2) implies that, if a constant is included in x , we have $E[e] = 0$ and moreover, $\text{cov}(x, e) = E[xe] = 0$.

The coefficient β in the linear projection model has a straightforward

²The linear function is not as restrictive as one might thought. It can be used to generate some nonlinear (in random variables) effect. For example, if $y = x_1\beta_2 + x_2\beta_2 + x_1x_2\beta_3 + e$, then $\frac{\partial}{\partial x_1}m(x_1, x_2) = \beta_1 + x_2\beta_3$, which is nonlinear in x_1 , while it is still linear in the parameter β .

closed-form. Multiplying x on both sides and taking expectation, we have $E[xy] = E[xx']\beta$. If $E[xx']$ is invertible, we explicitly solve

$$\beta = (E[xx'])^{-1} E[xy]. \quad (3)$$

Even if $m(x) \neq x'\beta$, we are interested in β as is the *linear* minimizer of the MSE. That is,

$$\beta = \arg \min_{\beta \in \mathbb{R}^K} E[(y - x'\beta)^2]. \quad (4)$$

Proof. We look for such a β that minimizes $E[(y - x'\beta)^2]$. Set the first order condition to zero, $2E[x(y - x'\beta)] = 0$. We solve $\beta = (E[xx'])^{-1} E[xy]$.

□

In the meantime, $x'\beta$ is also the best *linear* approximation to $m(x)$.

Proof. If we replace y in (4) by $m(x)$, we solve the minimizer as

$$(E[xx'])^{-1} E[xm(x)] = (E[xx'])^{-1} E[E[xy|x]] = (E[xx'])^{-1} E[xy] = \beta.$$

Therefore β is also the linear minimizer of $E[(m(x) - x'\beta)^2]$, the best linear approximation to $m(x)$ under MSE. □

1.2.1 Subvector Regression

Sometimes we are interested in a subvector of β . For example, when we include a constant and some variables in x , we are often more interested in the slope coefficients (those associated with the random variables), as they

represent the effect of these explanatory factors. In the regression

$$y = \beta_1 + x' \beta_2 + e,$$

we take an expectation to get $E[y] = \beta_1 + E[x]' \beta_2$. Differentiate the two equations to get

$$y - E[y] = (x - E[x])' \beta_2,$$

so that

$$\beta_2 = (E[(x - E[x])(x - E[x])'])^{-1} E[(x - E[x])(y - E[y])] = (\text{var}(x))^{-1} \text{cov}(x, y),$$

This is a special case of the subvector regression.

To discuss the general case, we need to know the formula of the inverse of the partitioned matrix, a fact from linear algebra. If $Q = \begin{pmatrix} Q_{11} & Q_{12} \\ Q_{21} & Q_{22} \end{pmatrix}$ is a symmetric and positive definite matrix, then

$$Q^{-1} = \begin{pmatrix} (Q_{11} - Q_{12}Q_{22}Q_{21})^{-1} & -(Q_{11} - Q_{12}Q_{22}Q_{21})^{-1}Q_{12}Q_{22}^{-1} \\ -(Q_{22} - Q_{21}Q_{11}Q_{12})^{-1}Q_{21}Q_{11}^{-1} & (Q_{22} - Q_{21}Q_{11}Q_{12})^{-1} \end{pmatrix}.$$

Let $A_{11.2} = E[x_1x_1'] - E[x_1x_2'](E[x_2x_2'])^{-1}E[x_2x_1']$, and $A_{1y.2} = E[x_1y] - E[x_1x_2'](E[x_2x_2'])^{-1}E[x_2y]$ then $\beta_1 = A_{11.2}^{-1}A_{1y.2}$. It is useful in interpreting

the partial effect of a single regressors. We first run a regression³

$$\begin{aligned}x_1 &= x_2' \gamma + u \\ E[x_2 u] &= 0\end{aligned}$$

so that

$$u = x_1 - x_2' \gamma = x_1 - x_2' (E[x_2 x_2'])^{-1} E[x_2 x_1'] = x_1 - E[x_1 x_2'] (E[x_2 x_2'])^{-1} x_2$$

We then run a simple regression of y on u , and the coefficient is

$$\theta = (E[uu'])^{-1} E[u'y].$$

The nominator $E[u'y] = E[x_1 y] - E[x_1 x_2'] (E[x_2 x_2'])^{-1} E[x_2 y]$. The denominator

$$E[uu'] = E\left[\left(x_1 - E[x_1 x_2'] (E[x_2 x_2'])^{-1} x_2\right) \left(x_1 - E[x_1 x_2'] (E[x_2 x_2'])^{-1} x_2\right)'\right] = A_{11 \cdot 2}.$$

We have verified that $\beta_1 = \theta$.

1.3 Omitted Variable Bias

Long regression is $y = x_1' \beta_1 + x_2' \beta_2 + e$, and short regression is $y = x_1' \gamma + u$.

To discuss how to sign the bias, we first demean all the variables, which is equivalent as if we project out the effect of the constant. The long regression

³We allow x_1 to be a vector. However, one may find it is easier to consider the special case that x_1 is a scalar random variable.

becomes

$$\tilde{y} = \tilde{x}'_1\beta_1 + \tilde{x}'_2\beta_2 + e,$$

and the short regression becomes

$$\tilde{y} = \tilde{x}'_1\gamma + u,$$

where *tilde* denotes the demeaned variable.

After demeaning, the cross moment equals to the covariance. The short regression coefficient

$$\begin{aligned}\gamma &= (E[\tilde{x}_1\tilde{x}'_1])^{-1} E[\tilde{x}_1\tilde{y}] \\ &= (E[\tilde{x}_1\tilde{x}'_1])^{-1} E[\tilde{x}_1(\tilde{x}'_1\beta_1 + \tilde{x}'_2\beta_2 + e)] \\ &= \beta_1 + (E[\tilde{x}_1\tilde{x}'_1])^{-1} E[\tilde{x}_1\tilde{x}'_2] \beta_2.\end{aligned}$$

Therefore, $\gamma = \beta_1$ if and only if $E[\tilde{x}_1\tilde{x}'_2]\beta_2 = 0$, which means either $E[\tilde{x}_1\tilde{x}'_2] = 0$ or $\beta_2 = 0$.