

# 1 Review of Probability

## 1.1 Probability

- *Sample space*  $\Omega$  is the collection of all possible outcomes.
- An *event* is a subset of  $\Omega$ .
- $\sigma$ -field  $\mathcal{F}$  is a collection of events such that: (i)  $\emptyset \in \mathcal{F}$ ; (ii) if an event  $A \in \mathcal{F}$ , then  $A^c \in \mathcal{F}$ ; (iii) if  $\{A_i \in \mathcal{F} : i \in \mathbb{N}\}$ , then  $\bigcup_{i \in \mathbb{N}} A_i \in \mathcal{F}$ .
- Measure space  $(\Omega, \mathcal{F})$ .
- Probability  $P : \mathcal{F} \mapsto [0, 1]$  is a function such that: (i)  $P(A) \geq 0$  for all  $A \in \mathcal{F}$ ; (ii)  $P(\Omega) = 1$ ; (iii) if  $A_i \in \mathcal{F}$ ,  $i \in \mathbb{N}$ , are mutually disjoint, then  $P(\bigcup_{i \in \mathbb{N}} A_i) = \sum_{i \in \mathbb{N}} P(A_i)$ .
- Probability space  $(\Omega, \mathcal{F}, P)$ .
- Measurable function: a function  $X$  is called  $(\Omega, \mathcal{F}) / (\mathbb{R}, \mathcal{B}_{\mathbb{R}})$  measurable if  $X^{-1}(B) = \{\omega \in \Omega : X(\omega) \in B\} \in \mathcal{F}$  for any  $B \in \mathcal{B}_{\mathbb{R}}$ .
- Random variable:  $X : \Omega \mapsto \mathbb{R}$  is a measurable function from  $(\Omega, \mathcal{F})$  and  $(\mathbb{R}, \mathcal{B}_{\mathbb{R}})$ .
- Cumulative distribution function (CDF)
- Probability density function (PDF)
  - Univariate random variable
  - Bivariate random variable
  - Multivariate random variable
- Conditional distribution

## 1.2 Expectation

- *Expectation* is an average of a random variable. Expectation is nothing but an integration, where the integrand is the random variable, and the measure is the probability measure. We write  $E[X]$ , instead of  $\int X dP_X$ , just for a concise notation when the underlying probability measure is clear.
- Conditional expectation
- Law of iterated expectation:  $E[E[Y|X]] = E[Y]$ .
- Properties of conditional expectations
  1.  $E[E[Y|X_1, X_2] | X_1] = E[Y|X_1]$
  2.  $E[E[Y|X_1] | X_1, X_2] = E[Y|X_1]$
  3.  $E[h(X)Y|X] = h(X)E[Y|X]$