

# 1 Regression Model

We will talk about the conditional mean model and the linear projection model.

**Notation:** in this note,  $y$  is a scale random variable, and  $x$  is a  $K \times 1$  random vector.

## 1.1 Conditional Expectation Model

A regression model can be written as  $y = m(x) + \epsilon$ , where  $m(x) = E[y|x]$  is called the *conditional mean function*, and  $\epsilon = y - m(x)$  is called the *regression error*.

The error term  $\epsilon$  satisfies the following properties.

- $E[\epsilon|x] = 0$ ,
- $E[\epsilon] = 0$ ,
- $E[h(x)\epsilon] = 0$ , where  $h$  is a function of  $x$ .

The last one means that  $\epsilon$  is uncorrelated with any function of  $x$ .

The conditional expectation function is of interest, because it is the best prediction of  $y$  under the *mean squared error* (MSE).<sup>1</sup>

Among all the functions  $g(X)$ , the conditional mean function  $m(x)$  minimizes the MSE.

*Proof.* We take a guess-and-verify approach.

$$E[(y - g(x))^2] = E[(y - m(x))^2] + 2E[(y - m(x))(m(x) - g(x))] + E[(m(x) - g(x))^2].$$

The first term is irrelevant to  $g(x)$ . The second term is  $2E[\epsilon(m(x) - g(x))] = 0$ , which is again irrelevant of  $g(x)$ . The third term is minimized at  $g(x) = m(x)$ .  $\square$

## 1.2 Linear Projection Model

As discussed in the previous section, we are interested in the conditional mean function  $m(x)$ . However,  $m(x)$  is a complex function depending on the joint distribution of  $(y, x)$ . A special case is  $m(x) = x'\beta$ , that is, the conditional mean function is a linear function of  $x$ .<sup>2</sup> It is true if  $(y, x)$  follows a joint normal distribution. Even if  $m(x) \neq x'\beta$ , the linear  $x'\beta$  is still useful as an approximation, as will be clear soon. Therefore, we may write the linear regression model, or the linear projection model, as

$$y = x'\beta + e \tag{1}$$

$$E[xe] = 0, \tag{2}$$

where  $e$  is called the *projection error*. Eq.(2) implies that, if a constant is included in  $x$ , we have  $E[e] = 0$  and moreover,  $\text{cov}(x, e) = E[xe] = 0$ .

<sup>1</sup>The quadratic loss function is between  $y$  and a prediction  $g(x)$  is defined as  $L(y, g(x)) = (y - g(x))^2$ , and its expectation  $R(y, g(x)) = E[(y - g(x))^2]$  is called the MSE.

<sup>2</sup>The linear function is not as restrictive as one might thought. It can be used to generate some nonlinear (in random variables) effect. For example, if  $y = x_1\beta_2 + x_2\beta_2 + x_1x_2\beta_3 + e$ , then  $\frac{\partial}{\partial x_1}m(x_1, x_2) = \beta_1 + x_2\beta_3$ , which is nonlinear in  $x_1$ , while it is still linear in the parameter  $\beta$ .

The coefficient  $\beta$  in the linear projection model has a straightforward closed-form. Multiplying  $x$  on both sides and taking expectation, we have  $E[xy] = E[xx']\beta$ . If  $E[xx']$  is invertible, we explicitly solve

$$\beta = (E[xx'])^{-1} E[xy]. \quad (3)$$

Even if  $m(x) \neq x'\beta$ , we are interested in  $\beta$  as is the *linear* minimizer of the MSE. That is,

$$\beta = \arg \min_{\beta \in \mathbb{R}^K} E[(y - x'\beta)^2]. \quad (4)$$

*Proof.* We look for such a  $\beta$  that minimizes  $E[(y - x'\beta)^2]$ . Set the first order condition to zero,  $2E[x(y - x'\beta)] = 0$ . We solve  $\beta = (E[xx'])^{-1} E[xy]$ .  $\square$

In the meantime,  $x'\beta$  is also the best *linear* approximation to  $m(x)$ .

*Proof.* If we replace  $y$  in (4) by  $m(x)$ , we solve the minimizer as

$$(E[xx'])^{-1} E[xm(x)] = (E[xx'])^{-1} E[E[xy|x]] = (E[xx'])^{-1} E[xy] = \beta.$$

Therefore  $\beta$  is also the linear minimizer of  $E[(m(x) - x'\beta)^2]$ , the best linear approximation to  $m(x)$  under MSE.  $\square$

### 1.2.1 Subvector Regression

Sometimes we are interested in a subvector of  $\beta$ , but not the entire vector  $\beta$ . For example, when we include a constant and some variables in  $x$ , we are often more interested in the slope coefficients (those associated with the random variables), as they represent the effect of these explanatory factors. In such a regression

$$y = \beta_1 + x'\beta_2 + e,$$

we take an expectation to get  $E[y] = \beta_1 + E[x']\beta_2$ . Differentiate the two equations,

$$y - E[y] = (x - E[x])'\beta_2,$$

so that

$$\beta_2 = (E[(x - E[x])(x - E[x])'])^{-1} E[(x - E[x])(y - E[y])] = (\text{var}(x))^{-1} (\text{cov}(x, y)),$$

where for two random vectors  $x$  and  $y$  (a scalar is a  $1 \times 1$  vector), the variance and covariance are

$$\begin{aligned} \text{var}(x) &= E[(x - E[x])(x - E[x])'] \\ \text{cov}(x, y) &= E[(x - E[x])(y - E[y])], \end{aligned}$$

respectively. This is a special case of the subvector regression.

**Don't read the part below. It is not ready yet.**

To discuss the general case, we need to know the formula of the partitioned inverse, a fact from linear

algebra. If  $Q = \begin{pmatrix} Q_{11} & Q_{12} \\ Q_{21} & Q_{22} \end{pmatrix}$  is a symmetric and positive definite matrix, then

$$Q^{-1} = \begin{pmatrix} (Q_{11} - Q_{12}Q_{22}Q_{21})^{-1} & -(Q_{11} - Q_{12}Q_{22}Q_{21})^{-1}Q_{12}Q_{22}^{-1} \\ -(Q_{22} - Q_{21}Q_{11}Q_{12})^{-1}Q_{21}Q_{11}^{-1} & (Q_{22} - Q_{21}Q_{11}Q_{12})^{-1} \end{pmatrix}.$$

Let  $A_{11.2} = E[x_1x_1'] - E[x_1x_2'](E[x_2x_2'])^{-1}E[x_2x_1']$ , and  $A_{1y.2} = E[x_1y] - E[x_1x_2'](E[x_2x_2'])^{-1}E[x_2y]$  then  $\beta_1 = A_{11.2}^{-1}A_{1y.2}$ . Why is this useful?

Let  $x_1$  be a scalar and  $x_2$  be a vector (with constant). We first run a regression

$$x_1 = x_2'\gamma + u$$

so that  $u = x_1 - x_2'\gamma = x_1 - x_2'(E[x_2x_2'])^{-1}E[x_2x_1']$ . We then run a regression of  $y$  on  $u$  with a constant, so that

$$\beta_u = \frac{\text{cov}(u, y)}{\text{var}(u)}.$$

The nominator  $\text{cov}(u, y) = E[x_1y] - E[x_1x_2'](E[x_2x_2'])^{-1}E[x_2y]$ . The denominator  $\text{var}(u) = E[u^2] = A_{11.2}$ .

### 1.3 Omitted Variable Bias

Long regression

$$y = x_1'\beta_1 + x_2'\beta_2 + \epsilon$$

and short regression

$$y = x_1'\gamma + u.$$

To discuss how to sign the bias, we first demean all the variables, which is equivalent as if we project out the effect of the constant.

$$\begin{aligned} \tilde{y} &= \tilde{x}_1'\beta_1 + \tilde{x}_2'\beta_2 + \epsilon \\ \tilde{y} &= \tilde{x}_1'\gamma + u \end{aligned}$$

where tilde denotes the demeaned variable. Now the cross moment equals to the covariance.