

南开大学

计算机学院 网络安全技术作业报告

端口扫描器的设计与实现

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一、 实验介绍

端口扫描器是一种重要的网络安全检测工具。通过端口扫描,不仅可以发现目标主机的开放端口和操作系统的类型,还可以查找系统的安全漏洞,获得弱口令等相关信息。因此,端口扫描技术是网络安全的基本技术之一,对于维护系统的安全性有着十分重要的意义。

(一) 实验目的

- 掌握端口扫描器的基本设计方法。
- 理解 ping 程序, TCP connect 扫描, TCP SYN 扫描, TCP FIN 扫描以及 UDP 扫描的工作原理。
- 熟练掌握 Linux 环境下的套接字编程技术。
- 掌握 Linux 环境下多线程编程的基本方法

(二) 实验流程

- 编写端口扫描程序, 提供 TCP connect 扫描
- 编写端口扫描程序, 提供 TCP SYN 扫描
- 编写端口扫描程序, 提供 TCP FIN 扫描
- 编写端口扫描程序, 提供 UDP 扫描
- 设计并实现 ping 程序,探测目标主机是否可达。

二、实验步骤

(一) 实验环境

Ubuntu Server 20.04 LTS 64bit (腾讯云服务器), C++11, Cmake

(二) 核心代码实现

1. 代码框架

header.h 中包含了端口扫描器的基本结构体和函数声明。TCPConnectScan.cpp 、TCPFIN-Scan.cpp、TCPSYNScan.cpp、UDPScan.cpp 和 main.cpp 中分别实现了 TCP connect 扫描、TCP FIN 扫描、TCP SYN 扫描、UDP 扫描以及 ping 程序的实现。

2. IP 头、TCP 头和 TCP 伪头以及一些工具函数

TCP 头, 用于发送 TCP 报文

```
struct TCPHeader {
        uint16_t srcPort;
        uint16_t dstPort;
        uint32_t seq;
        uint32_t ack;
        uint8_t null1 : 4;
        uint8_t length : 4;
        uint8_t FIN : 1;
        uint8_t SYN : 1;
        uint8_t RST : 1;
10
        uint8_t PSH : 1;
11
        uint8_t ACK : 1;
12
        uint8_t URG : 1;
13
        uint8_t null2 : 2;
14
        uint16_t windowSize;
15
16
        uint16_t checkSum;
        uint16_t ptr;
17
    };
18
```

TCP 伪头,用于计算 TCP 头的校验和

```
struct pseudohdr

unsigned int saddr;
unsigned int daddr;
char useless;
unsigned char protocol;
unsigned short length;

};
```

IP 头,用于发送 IP 报文

```
struct IPHeader {
      unsigned char headerLen: 4;
      unsigned char version: 4;
      unsigned char tos;
      unsigned short length;
      unsigned short ident;
      unsigned short fragFlags;
      unsigned char ttl;
      unsigned char protocol;
      unsigned short checksum;
10
      unsigned int srcIP;
11
      unsigned int dstIP;
12
      IPHeader(unsigned int src, unsigned int dst, int protocol) {
13
         version = 4;
14
         headerLen = 5;
15
         srcIP = src;
16
         dstIP = dst;
         ttl = (char)128;
18
         this -> protocol = protocol;
19
         if (protocol == IPPROTO_TCP) {
            length = htons(20 + 20);
21
```

校验和计算函数

```
static inline unsigned short in_cksum(unsigned short *ptr, int nbytes)
2
      register long sum;
3
      u_short oddbyte;
      register u_short answer;
      sum = 0;
      while(nbytes > 1)
          sum += *ptr++;
10
         nbytes -= 2;
      }
12
13
      if(nbytes == 1)
14
      {
15
16
         oddbyte = 0;
          *((u_char *) &oddbyte) = *(u_char *)ptr;
17
          sum += oddbyte;
18
      }
19
20
      sum = (sum >> 16) + (sum & 0xffff);
21
      sum += (sum >> 16);
22
      answer = \simsum;
23
      return(answer);
25
   }
26
```

获取本地 IP 地址

```
static inline unsigned int GetLocalHostIP(void)
1
2
      FILE *fd;
3
      char buf[20] = \{0x00\};
4
      fd = popen("/sbin/ifconfig | grep inet | grep -v 127 | awk '{print $2}' | cut -d
          \":\" -f 2", "r");
      if(fd == NULL)
8
         fprintf(stderr, "cannot get source ip -> use the -f option\n");
         exit(-1);
10
11
      fscanf(fd, "%20s", buf);
12
      return(inet_addr(buf));
13
   }
```

3. ICMP 探测指定主机

该程序用于测量本地主机与目标主机之间的网络通信情况,用 ping 函数实现。具体实现为首先我们需要建立一个套接字用来通信,并设置我们需要发送的 IP 包

```
bool Ping(std::string HostIP, unsigned LocalHostIP) {
      struct iphdr *ip;
      struct icmphdr *icmp;
3
      unsigned short LocalPort = 8888;
      int PingSock = socket(AF_INET, SOCK_RAW, IPPROTO_ICMP);
      if(PingSock < 0) {</pre>
          std::cout << "socket error" << std::endl;</pre>
          return false:
10
      }
11
12
      int on = 1;
13
      int ret = setsockopt(PingSock, 0, IP_HDRINCL, &on, sizeof(on));
15
      if(ret < 0) {
16
          std::cout << "setsockopt error" << std::endl;</pre>
17
          return false;
18
      }
19
```

然后我们创建 ICMP 请求数据包,并对 ip 头和 icmp 头进行填充,为了保证对面成功接受并进行应答

```
int SendBufSize = sizeof(struct iphdr) + sizeof(struct icmphdr) + sizeof(struct
          timeval);
      char *SendBuf = (char*)malloc(SendBufSize);
      memset(SendBuf, 0, sizeof(SendBuf));
      ip = (struct iphdr*)SendBuf;
      ip \rightarrow ihl = 5;
      ip -> version = 4;
      ip \rightarrow tos = 0;
      ip -> tot_len = htons(SendBufSize);
      ip \rightarrow id = rand();
10
      ip -> ttl = 64;
11
      ip \rightarrow frag\_off = 0x40;
12
      ip -> protocol = IPPROTO_ICMP;
13
      ip \rightarrow check = 0;
14
      ip -> saddr = LocalHostIP;
15
      ip -> daddr = inet_addr(&HostIP[0]);
16
17
      //填充icmp头
      icmp = (struct icmphdr*)(ip + 1);
19
      icmp->type = ICMP_ECHO;
20
      icmp->code = 0;
21
      icmp->un.echo.id = htons(LocalPort);
22
      icmp->un.echo.sequence = 0;
23
      struct timeval *tp = (struct timeval*) &SendBuf[28];
25
      gettimeofday(tp, NULL);
26
      icmp -> checksum = in_cksum((u_short *)icmp, sizeof(struct icmphdr) + sizeof(struct
27
            timeval));
```

二、 实验步骤 网络安全技术实验报告

然后我们设置套接字的发送地址,即我们需要扫描的目标地址,并向目标地址发送我们的 icmp 的数据包。

```
//设置套接字的发送地址
      struct sockaddr_in PingHostAddr;
      PingHostAddr.sin_family = AF_INET;
      PingHostAddr.sin_addr.s_addr = inet_addr(&HostIP[0]);
      int Addrlen = sizeof(struct sockaddr_in);
      //发送ICMP请求
      ret = sendto(PingSock, SendBuf, SendBufSize, 0, (struct sockaddr*) &PingHostAddr,
          sizeof(PingHostAddr));
      if(ret < 0) {
         std::cout << "sendto error" << std::endl;</pre>
10
11
         return false;
      }
12
13
      if(fcntl(PingSock, F_SETFL, O_NONBLOCK) == -1) {
         perror("fcntl error");
15
         return false;
16
      }
```

然后循环接受 icmp 响应,具体为首先获得循环起始时间,然后创建一个 ICMP 接受数据包,进入循环,如果接收到一个数据包则对其进行解析,获得响应数据包的 IP 头的原地址、目的地址,然后判断该数据包的源地址是否等于被测主机的 IP 地址和目的地址是否相等 ICMP 头的 type 字段是否为 ICMP_ECHOREPLY,如果等待时间超过三秒则是失败。

```
struct timeval TpStart, TpEnd;
     bool flags;
     //循环等待接收ICMP响应
     gettimeofday(&TpStart, NULL); //获得循环起始时刻
     flags = false;
     char RecvBuf[1024];
     struct sockaddr_in FromAddr;
     struct icmp* Recvicmp;
     struct ip* Recvip;
10
     std::string SrcIP, DstIP, LocalIP;
11
     struct in_addr in_LocalhostIP;
12
     do {
14
        //接收ICMP响应
15
        ret = recvfrom(PingSock, RecvBuf, 1024, 0, (struct sockaddr*) &FromAddr,
16
        (socklen_t*) &Addrlen);
17
        if (ret > 0) //如果接收到一个数据包,对其进行解析
19
           Recvip = (struct ip*) RecvBuf;
20
           Recvicmp = (struct icmp*) (RecvBuf + (Recvip -> ip_hl * 4));
           SrcIP = inet_ntoa(Recvip -> ip_src); //获得响应数据包IP头的源地址
           DstIP = inet_ntoa(Recvip -> ip_dst); //获得响应数据包IP头的目的地址
           in_LocalhostIP.s_addr = LocalHostIP;
24
           LocalIP = inet_ntoa(in_LocalhostIP); //获得本机IP地址
25
           //判断该数据包的源地址是否等于被测主机的IP地址,目的地址是否等于
           //本机IP地址, ICMP头的type字段是否为ICMP_ECHOREPLY
27
```

```
if (SrcIP == HostIP && DstIP == LocalIP &&
28
             Recvicmp->icmp_type == ICMP_ECHOREPLY) {
29
                /*ping成功,退出循环*/
30
                std::cout << "Ping Host " << HostIP << " Successfully !" << std::endl;</pre>
31
                flags =true;
32
                break;
33
            }
         }
35
         //获得当前时刻,判断等待相应时间是否超过3秒,若是,则退出等待。
36
         gettimeofday(&TpEnd, NULL);
         float TimeUse = (1000000 * (TpEnd.tv_sec - TpStart.tv_sec) + (TpEnd.tv_usec -
38
              TpStart.tv_usec)) / 1000000.0;
         if(TimeUse < 3) {</pre>
39
             continue;
40
         }
         else {
42
             flags = false;
43
             break;
         }
45
      } while(true);
46
      return flags;
47
48
```

4. TCP connect 扫描

这一部分我们使用的数据结构如下:

```
struct TCPConHostThrParam
{
    std::string HostIP;
    unsigned HostPort;
};

struct TCPConThrParam
{
    std::string HostIP;
    unsigned BeginPort;
    unsigned EndPort;
};
```

我们这一部分的主要功能是利用 TCP 扫描确定目的主机的某一 TCP 端口是否开启,具体来收就是尝试连接被测主机的指定端口,若连接成功,则表示端口开启;否则,表示端口关闭。为了提高效率,我们使用多线程进行扫描,每个进程扫描一个端口。首先我们先创建两个线程锁,为了让我们扫描端口并行化扫描。使用变量 TCPConThrdNum 来记录已经创建的子线程数。

```
int TCPConThrdNum;
pthread_mutex_t TCPConPrintlocker = PTHREAD_MUTEX_INITIALIZER;
pthread_mutex_t TCPConScanlocker = PTHREAD_MUTEX_INITIALIZER;
```

然后我们编写 void* Thread_TCPconnectHost(void* param) 函数,该该函数的主要功能是连接目标主机指定端口的工作。首先,我们获得目标主机的 IP 地址和扫描端口号,然后创建流套接字,进入连接区,加锁防止多个线程同时打印字符出现乱码。

```
1 void* Thread_TCPconnectHost(void* param) {
2 /*变量定义*/
```

```
//获得目标主机的IP地址和扫描端口号
struct TCPConHostThrParam *p = (struct TCPConHostThrParam*) param;
std::string HostIP = p -> HostIP;
unsigned HostPort = p -> HostPort;
//创建流套接字
int ConSock = socket(AF_INET,SOCK_STREAM,0);
if(ConSock < 0) {
   pthread_mutex_lock(&TCPConPrintlocker);
}
```

然后设置连接主机,利用 connect 函数连接目标主机,加锁防止多个线程同时打印出现输出乱码,若连接成功,则表示端口开启;否则,表示端口关闭。

```
//设置连接主机地址
      struct sockaddr_in HostAddr;
      memset(&HostAddr, 0, sizeof(HostAddr));
      HostAddr.sin_family = AF_INET;
      HostAddr.sin_addr.s_addr = inet_addr(&HostIP[0]);
      HostAddr.sin_port = htons(HostPort);
      //connect目标主机
      int ret = connect(ConSock, (struct sockaddr*) &HostAddr, sizeof(HostAddr));
      if(ret < 0) {
         pthread_mutex_lock(&TCPConPrintlocker);
10
         std::cout << "TCP connect scan: " << HostIP << ":" << HostPort << " is closed"
11
             << std::endl:
         pthread_mutex_unlock(&TCPConPrintlocker);
12
      } else {
13
         pthread_mutex_lock(&TCPConPrintlocker);
14
         std::cout << "TCP connect scan: " << HostIP << ":" << HostPort << " is open" <<
15
             std::endl;
         pthread_mutex_unlock(&TCPConPrintlocker);
17
```

然后我们关闭套接字,释放线程锁,线程数量减一。

```
delete p;
close(ConSock); //美闭套接字

//子线程数减1
pthread_mutex_lock(&TCPConScanlocker);
TCPConThrdNum--;
pthread_mutex_unlock(&TCPConScanlocker);

// TCP connect 扫描
```

然后,我们编写 void* Thread_TCPconnectHost(void* param) 函数,该函数用于遍历目标主机的端口,是该功能的主线程函数。首先我们获得扫描的目标主机 IP、启始端口、终止端口,然后我们将线程数设置为 0。

```
void* Thread_TCPconnectScan(void* param)
{

/*变量定义*/
//获得扫描的目标主机IP, 启始端口, 终止端口
struct TCPConThrParam *p = (struct TCPConThrParam*) param;
std::string HostIP = p -> HostIP;
unsigned BeginPort = p -> BeginPort;
unsigned EndPort = p->EndPort;
```

```
      9
      TCPConThrdNum = 0; //将线程数设为0

      10
      //开始从起始端口到终止端口循环扫描目标主机的端口
```

接下来,我们开始从起始端口到终止端口循环扫描目标主机的端口。首先我们在循环中设置子线程参数,然后将子线程设为分离状态,创建 connect 目标主机指定的端口和一个独立的子线程进行绑定,并将子线程数加 1。每一寸循环都会判断子线程的数量,如果如果子线程数大于 100,则暂时休眠。

```
pthread_t subThreadID;
      pthread_attr_t attr;
      for (unsigned TempPort = BeginPort; TempPort <= EndPort; TempPort++)</pre>
         //设置子线程参数
         TCPConHostThrParam *pConHostParam = new TCPConHostThrParam;
         pConHostParam->HostIP = HostIP;
         pConHostParam->HostPort = TempPort;
         //将子线程设为分离状态
10
         pthread_attr_init(&attr);
         pthread_attr_setdetachstate(&attr,PTHREAD_CREATE_DETACHED);
11
         //创建connect目标主机指定的端口子线程
12
         int ret = pthread_create(&subThreadID, &attr, Thread_TCPconnectHost,
             pConHostParam);
         if(ret == -1) {
14
            std::cout << "Create TCP connect scan thread error!" << std::endl;</pre>
15
         }
16
         //线程数加1
         pthread_mutex_lock(&TCPConScanlocker);
18
         TCPConThrdNum++;
19
         pthread_mutex_unlock(&TCPConScanlocker);
20
         //如果子线程数大于100, 暂时休眠
21
         while (TCPConThrdNum>100) {
22
            sleep(3);
23
         }
24
25
      }
```

最后, 我们等待子线程数为 0, 返回。

```
while (TCPConThrdNum != 0) {
    sleep(1);
}
pthread_exit(NULL);
}
```

5. TCP SYN 扫描

这一部分我们使用的数据结构如下:

```
struct TCPSYNHostThrParam
{
    std::string HostIP;
    unsigned HostPort;
    unsigned LocalPort;
    unsigned LocalHostIP;
};
```

```
9  struct TCPSYNThrParam
10  {
11    std::string HostIP;
12    unsigned BeginPort;
13    unsigned EndPort;
14    unsigned LocalHostIP;
15  };
```

我们这一部分的主要功能是利用 TCP SYN 扫描确定目的主机的某一 TCP 端口是否开启该,具体来收就是尝试向被测主机的指定端口发送 SYN 报文,如果接收到 ACK 报文,则说明开启,否则则说明关闭。为了提高效率,我们使用多线程进行扫描,每个进程扫描一个端口。首先我们先创建两个线程锁,为了让我们扫描端口并行化扫描。使用变量 TCPSynThrdNum 来记录已经创建的子线程数。

```
pthread_mutex_t TCPSynPrintlocker = PTHREAD_MUTEX_INITIALIZER;
pthread_mutex_t TCPSynScanlocker = PTHREAD_MUTEX_INITIALIZER;

int TCPSynThrdNum;
```

然后我们编写 void* Thread_TCPSYNHost(void* param) 函数,该函数的主要功能是完成对目标主机指定端口的 TCP SYN 扫描。首先,我们获得目标主机的 IP 地址和扫描端口号

```
void* Thread_TCPSYNHost(void* param) {
     /*变量定义*/
      //获得目标主机的IP地址和扫描端口号
      struct TCPSYNHostThrParam *p = (struct TCPSYNHostThrParam*) param;
      std::string HostIP = p -> HostIP;
      unsigned HostPort = p -> HostPort;
      unsigned LocalPort = p -> LocalPort;
      unsigned LocalHostIP = p -> LocalHostIP;
      struct sockaddr_in SYNScanHostAddr;
10
      memset(&SYNScanHostAddr, 0, sizeof(SYNScanHostAddr));
11
      SYNScanHostAddr.sin_family = AF_INET;
12
      SYNScanHostAddr.sin_addr.s_addr = inet_addr(HostIP.c_str());
13
      SYNScanHostAddr.sin_port = htons(HostPort);
```

然后我们创建套接字

```
int SynSock = socket(AF_INET, SOCK_RAW, IPPROTO_TCP);
if(SynSock < 0) {
    pthread_mutex_lock(&TCPSynPrintlocker);
    std::cout << "Can't creat raw socket !" << std::endl;
    pthread_mutex_unlock(&TCPSynPrintlocker);
}
int flag = 1;
if (setsockopt(SynSock, IPPROTO_IP, IP_HDRINCL, (void*)&flag, sizeof(int)) ==
    -1) {
    std::cout << "set IP_HDRINCL error.\n";
}</pre>
```

填充 TCP SYN 数据包

```
char sendbuf[8192];
char recvbuf[8192];
struct pseudohdr *ptcph = (struct pseudohdr*) sendbuf;
struct tcphdr *tcph = (struct tcphdr*)(sendbuf + sizeof(struct pseudohdr));
```

填充 TCP 伪头部,用于计算校验和

```
ptcph -> saddr = LocalHostIP;
ptcph -> daddr = inet_addr(HostIP.c_str());
in_addr src, dst;
ptcph -> useless = 0;
ptcph -> protocol = IPPROTO_TCP;
ptcph -> length = htons(sizeof(struct tcphdr));

src.s_addr = ptcph -> saddr;
dst.s_addr = ptcph -> daddr;
```

填充 TCP 头

```
memset(tcph, 0, sizeof(struct tcphdr));
// std::cout<<LocalPort<<" "<<HostPort<<std::endl;
tcph->th_sport = htons(LocalPort);
tcph->th_dport = htons(HostPort);
tcph->th_seq = htonl(123456);
tcph->th_ack = 0;
tcph->th_ack = 0;
tcph->th_off = 5;
tcph->th_off = 5;
tcph->th_flags = TH_SYN;
tcph->th_win = htons(65535);
tcph->th_sum = 0;
tcph->th_sum = 0;
tcph->th_sum = 0;
tcph->th_sum = in_cksum((unsigned short*)ptcph, 20 + 12);
```

封装 IP 头

```
IPHeader IPheader(ptcph -> saddr, ptcph -> daddr, IPPROTO_TCP);
char temp[sizeof(IPHeader) + sizeof(struct tcphdr)];

memcpy((void*)temp, (void*)&IPheader, sizeof(IPheader));
memcpy((void*)(temp+sizeof(IPheader)), (void*)tcph, sizeof(struct tcphdr));
```

发送 TCP SYN 数据包

开始利用一个循环循环接受包到 buffer 中。

```
int count = 0;
std::string SrcIP;
struct ip *iph;
flag = 1;
sockaddr_in recvAddr;
int addrLen = sizeof(recvAddr);
do{
len = recvfrom(SynSock, recvbuf, 8192, 0, (sockaddr*)&recvAddr,
```

```
(socklen_t*)&addrLen);

if(len < 0) {

    /*接收错误*/

    pthread_mutex_lock(&TCPSynPrintlocker);

    std::cout << "Read TCP SYN Packet error !" << std::endl;

    pthread_mutex_unlock(&TCPSynPrintlocker);

}
```

解析 IP 头和 TCP 头,然后从 TCP 头和 IP 头中解析源地址、目的地址、源 IP、目的 IP

```
else {
    struct ip *iph = (struct ip *)recvbuf;
    int i = iph -> ip_hl * 4;
    tcph = (struct tcphdr *)(recvbuf + i);

std::string SrcIP = inet_ntoa(iph -> ip_src);
    std::string DstIP = inet_ntoa(iph -> ip_dst);
    struct in_addr in_LocalhostIP;
    in_LocalhostIP.s_addr = LocalHostIP;
    std::string LocalIP = inet_ntoa(in_LocalhostIP);

unsigned SrcPort = ntohs(tcph -> th_sport);
    unsigned DstPort = ntohs(tcph -> th_dport);
```

判断响应数据包的源地址是否等于目标主机地址,目的地址是否等于本机; IP 地址,源端口是否等于被扫描端口,目的端口是否等于本机端口号

```
// std::cout << "_____" << std::endl;

// std::cout << HostIP << ' ' << SrcIP << std::endl;

// std::cout << LocalIP << ' ' << DstIP << std::endl;

// std::cout << SrcPort << ' ' << HostPort<< std::endl;

// std::cout << DstPort << ' ' << HostPort<< std::endl;

// std::cout << DstPort << ' ' << LocalPort<< std::endl;

if(HostIP == SrcIP && LocalIP == DstIP && SrcPort == HostPort && DstPort == LocalPort)

{</pre>
```

判断数据包类型,给出动作响应。只让这个过程循环 20 次,如果没收到默认关闭。

```
// std::cout<<(int)(tcph->th_flags)<<std::endl;</pre>
              if(tcph->th_flags == 0x12) //判断是否为SYNIACK数据包
              {
                 /*端口开启*/
                 flag = 0;
                 pthread_mutex_lock(&TCPSynPrintlocker);
                 std::cout << "Host: " << SrcIP << " Port: " << ntohs(tcph -> th_sport)
                     << " open !" << std::endl;
                 pthread_mutex_unlock(&TCPSynPrintlocker);
9
              if(tcph->th_flags == 0x14) //判断是否为RST数据包
11
                 /*端口关闭*/
13
                 flaq = 0;
14
                 pthread_mutex_lock(&TCPSynPrintlocker);
15
                 std::cout << " Port: " << ntohs(tcph -> th_sport) << " closed !" << std
16
                      ::endl;
```

```
pthread_mutex_unlock(&TCPSynPrintlocker);

pthread_mutex_unlock(&TCPSynPrintlocker);

pthread_mutex_unlock(&TCPSynPrintlocker);

while(synPrintlocker);

while(synPrintlocker);

while(synPrintlocker);

pthread_mutex_unlock(&TCPSynPrintlocker);

while(synPrintlocker);

pthread_mutex_unlock(&TCPSynPrintlocker);

pthread_mu
```

最后,我们等待子线程数为0,返回。

```
1  //退出子线程
2  if(flag){
3    pthread_mutex_lock(&TCPSynPrintlocker);
4    std::cout << "Host: " << SrcIP << " Port: " << HostPort << " closed !" << std:: endl;
5    pthread_mutex_unlock(&TCPSynPrintlocker);
6  }
7  delete p;
8  close(SynSock);
9  pthread_mutex_lock(&TCPSynScanlocker);
10  TCPSynThrdNum--;
11  pthread_mutex_unlock(&TCPSynScanlocker);
12 }</pre>
```

然后我们进行编写 void* Thread_TCPSynScan(void* param) 函数,该函数的主要功能是调用Thread_TCPSYNHost 函数创建多个扫描子线程负责遍历目标主机的被测端口。首先我们获得目标主机的 IP 地址和扫描的起始端口号,终止端口号,以及本机的 IP 地址

```
void* Thread_TCPSynScan(void* param) {
/*变量定义*/
//获得目标主机的IP地址和扫描的起始端口号,终止端口号,以及本机的IP地址
struct TCPSYNThrParam *p = (struct TCPSYNThrParam*)param;
std::string HostIP = p -> HostIP;
unsigned BeginPort = p-> BeginPort;
unsigned EndPort = p-> EndPort;
unsigned LocalHostIP = p -> LocalHostIP;
```

接下来,我们开始从起始端口到终止端口循环扫描目标主机的端口。首先我们在循环中设置子线程参数,然后将子线程设为分离状态,创建 SYN 目标主机指定的端口和一个独立的子线程进行绑定,并将子线程数加 1。每一寸循环都会判断子线程的数量,如果如果子线程数大于 100,则暂时休眠。

```
TCPSynThrdNum = 0;
      unsigned LocalPort = 1024;
      pthread_attr_t attr,lattr;
      pthread_t listenThreadID, subThreadID;
      for (unsigned TempPort = BeginPort; TempPort <= EndPort; TempPort++)</pre>
         //设置子线程参数
         struct TCPSYNHostThrParam *pTCPSYNHostParam =
8
         new TCPSYNHostThrParam;
         pTCPSYNHostParam->HostIP = HostIP;
10
         pTCPSYNHostParam->HostPort = TempPort;
         pTCPSYNHostParam->LocalPort = TempPort + LocalPort;
12
         pTCPSYNHostParam->LocalHostIP = LocalHostIP;
13
         //将子线程设置为分离状态
14
         pthread_attr_init(&attr);
15
         pthread_attr_setdetachstate(&attr,PTHREAD_CREATE_DETACHED);
16
```

```
//创建子线程
17
         int ret = pthread_create(&subThreadID, &attr, Thread_TCPSYNHost,
              pTCPSYNHostParam);
         if (ret==-1)
19
20
             std::cout << "Can't create the TCP SYN Scan Host thread !" << std::endl;</pre>
21
22
         }
         pthread_attr_destroy(&attr);
23
         //子线程数加1
24
         pthread_mutex_lock(&TCPSynScanlocker);
         TCPSynThrdNum++;
26
         pthread_mutex_unlock(&TCPSynScanlocker);
27
         //子线程数大于100, 休眠
28
         while(TCPSynThrdNum > 100) {
29
             sleep(3);
         }
31
      }
32
```

最后, 我们等待子线程数为 0, 返回。

```
while(TCPSynThrdNum != 0) {
    sleep(1);
}

//返回主流程
pthread_exit(NULL);
}
```

6. TCP FIN 扫描

这一部分我们需要使用的数据结构如下:

```
struct TCPFINHostThrParam
2
      std::string HostIP;
      unsigned HostPort;
      unsigned LocalPort;
      unsigned LocalHostIP;
   };
   struct TCPFINThrParam
9
   {
10
      std::string HostIP;
11
      unsigned BeginPort;
12
      unsigned EndPort;
13
      unsigned LocalHostIP;
   };
```

我们这一部分的主要功能是利用 TCP FIN 扫描确定目的主机的某一 TCP 端口是否开启,具体来说就尝试向被测主机发送 FIN 报文,如果接收到 ACK 报文,则说明开启,否则则说明关闭。未来提高效率,我们使用多线程进行扫描,每个进程扫描一个端口。首先我们先创建两个线程锁,为了让我们扫描端口并行化进行。使用变量 TCPFinThrdNum 来记录已经创建的子进程数

```
int TCPFinThrdNum;
pthread_mutex_t TCPFinPrintlocker = PTHREAD_MUTEX_INITIALIZER;
pthread_mutex_t TCPFinScanlocker = PTHREAD_MUTEX_INITIALIZER;
```

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然后我们编写 void* Thread_TCPFINHost(void* param) 函数,该函数的主要目的是完成对目标主机制定端口的 TCP FIN 扫描。首先,我们获得目标主机的 IP 地址和扫描端口号

```
void* Thread_TCPFINHost(void* param) {
     //填充 TCP FIN 数据包
     struct TCPFINHostThrParam *p = (struct TCPFINHostThrParam*)param;
     std::string HostIP = p -> HostIP;
     unsigned HostPort = p->HostPort;
     unsigned LocalPort = p->LocalPort;
     unsigned LocalHostIP = p->LocalHostIP;
     struct sockaddr_in FINScanHostAddr;
10
     memset(&FINScanHostAddr, 0, sizeof(FINScanHostAddr));
11
12
     FINScanHostAddr.sin_family = AF_INET;
     FINScanHostAddr.sin_addr.s_addr = inet_addr(&HostIP[0]);
13
     FINScanHostAddr.sin_port = htons(HostPort);
```

然后我们创建两个套接字,一个用于发送 FIN 报文,一个用于接收回复

```
int FinSock=socket(PF_INET, SOCK_RAW, IPPROTO_TCP);
1
      if (FinSock < 0) {</pre>
         pthread_mutex_lock(&TCPFinPrintlocker);
          std::cout << "Can't creat raw socket !" << std::endl;</pre>
          pthread_mutex_unlock(&TCPFinPrintlocker);
      }
6
      int FinRevSock = socket(PF_INET, SOCK_RAW, IPPROTO_TCP);
      if (FinRevSock < 0)</pre>
      {
         pthread_mutex_lock(&TCPFinPrintlocker);
11
          std::cout << "Can't creat raw socket !" << std::endl;</pre>
         pthread_mutex_unlock(&TCPFinPrintlocker);
13
14
      int flag = 1;
      if (setsockopt(FinSock, IPPROTO_IP, IP_HDRINCL, (void*)&flag, sizeof(int)) ==
16
          -1) {
17
          std::cout << "set IP_HDRINCL error.\n";</pre>
19
      if (setsockopt(FinRevSock, IPPROTO_IP, IP_HDRINCL, (void*)&flag, sizeof(int)) ==
20
21
          std::cout << "set IP_HDRINCL error.\n";</pre>
22
```

填充 TCP 头

```
char sendbuf[8192];
struct pseudohdr *ptcph = (struct pseudohdr*)sendbuf;
struct tcphdr *tcph = (struct tcphdr*)(sendbuf + sizeof(struct pseudohdr));

ptcph->saddr = LocalHostIP;
ptcph->daddr = inet_addr(&HostIP[0]);
ptcph->useless = 0;
ptcph->protocol = IPPROTO_TCP;
ptcph->length = htons(sizeof(struct tcphdr));
```

二、 实验步骤

```
12
13
      tcph->th_sport = htons(LocalPort);
14
      tcph->th_dport = htons(HostPort);
15
      tcph->th_seq = htonl(123456);
16
      tcph->th_ack = 0;
17
      tcph->th_x2 = 0;
      tcph->th_off = 5;
19
      tcph->th_flags = TH_FIN;
      tcph->th\_win = htons(65535);
      tcph->th_sum = 0;
22
      tcph->th\_urp = 0;
23
      tcph->th_sum = in_cksum((unsigned short*)ptcph, 20 + 12);
```

封装 IP 头

```
IPHeader IPheader(ptcph -> saddr, ptcph -> daddr, IPPROTO_TCP);
char temp[sizeof(IPHeader) + sizeof(struct tcphdr)];

memcpy((void*)temp, (void*)&IPheader, sizeof(IPheader));
memcpy((void*)(temp+sizeof(IPheader)), (void*)tcph, sizeof(struct tcphdr));
```

发送 TCP FIN 数据包,并将另一个套接字设置为非阻塞模式进行接收

```
int len = sendto(FinSock, temp, sizeof(IPHeader) + sizeof(struct tcphdr), 0, (
           struct sockaddr *)&FINScanHostAddr, sizeof(FINScanHostAddr));
      if(len < 0)
         pthread_mutex_lock(&TCPFinPrintlocker);
         std::cout << "Send TCP FIN Packet error !" << std::endl;</pre>
         pthread_mutex_unlock(&TCPFinPrintlocker);
6
      if(fcntl(FinRevSock, F_SETFL, O_NONBLOCK) == -1)
         pthread_mutex_lock(&TCPFinPrintlocker);
10
         std::cout << "Set socket in non-blocked model fail !" << std::endl;</pre>
11
         pthread_mutex_unlock(&TCPFinPrintlocker);
12
13
14
      int FromAddrLen = sizeof(struct sockaddr_in);
```

然后开始利用一个循环将收到的数据包存入 buffer 中

```
struct timeval TpStart,TpEnd;
char recvbuf[8192];
struct sockaddr_in FromAddr;
std::string SrcIP, DstIP, LocalIP;
gettimeofday(&TpStart, NULL); //获得开始接收时刻
struct in_addr in_LocalhostIP;
do {
    //调用 recvfrom 函数接收数据包
    len = recvfrom(FinRevSock, recvbuf, sizeof(recvbuf), 0, (struct sockaddr*) &
    FromAddr, (socklen_t*) &FromAddrLen);
```

然后我们需要判断响应包的原地址是不是等于目的主机地址,并解析 IP 头和 TCP 头,然后从TCP 头和 IP 头中解析源地址、目的地址、源 IP、目的 IP

```
if(len > 0)
         std::string SrcIP = inet_ntoa(FromAddr.sin_addr);
3
         if(1)
         {
            //响应数据包的源地址等于目标主机地址
            struct ip *iph = (struct ip *)recvbuf;
            int i = iph -> ip_hl * 4;
8
            struct tcphdr *tcph = (struct tcphdr *)&recvbuf[i];
            SrcIP = inet_ntoa(iph->ip_src);
11
            DstIP = inet_ntoa(iph->ip_dst);
12
13
14
            in_LocalhostIP.s_addr = LocalHostIP;
15
            LocalIP = inet_ntoa(in_LocalhostIP);
16
17
            unsigned SrcPort = ntohs(tcph->th_sport);
18
            unsigned DstPort = ntohs(tcph->th_dport);
```

判断响应数据包的源地址是否等于目标主机,目的地址是否等于本地主机;IP 地址,源端口是否等于被扫描端口,目的端口是否等于本机号

```
// std::cout << "______" << std::endl;

// std::cout << HostIP << ' ' << SrcIP << std::endl;

// std::cout << LocalIP << ' ' << DstIP << std::endl;

// std::cout << SrcPort << ' ' << HostPort<< std::endl;

// std::cout << DstPort << ' ' << LocalPort<< std::endl;

//判断响应数据包的源地址是否等于目标主机地址,目的地址是否等于本机 IP 地址,源端口是否等于被扫描端口,目的端口是否等于本机端口号

if(HostIP == SrcIP && LocalIP == DstIP && SrcPort == HostPort && DstPort == LocalPort)

{
```

然后我们判断数据包类型,给出动作响应,

```
if (tcph->th_flags == 0x14)
{
    pthread_mutex_lock(&TCPFinPrintlocker);
    std::cout << "Host: " << SrcIP << " Port: " << ntohs(tcph -> th_sport) << "
        closed !" << std::endl;
    pthread_mutex_unlock(&TCPFinPrintlocker);
}
break;</pre>
```

只让这个过程重复5秒,如果5秒内没有响应则判定为没有响应,继续进行扫描

二、实验步骤

```
else
{
//超时,扫描端口开启
pthread_mutex_lock(&TCPFinPrintlocker);
std::cout << "Host: " << HostIP << " Port: " << HostPort << " open !" << std:: endl;
pthread_mutex_unlock(&TCPFinPrintlocker);
break;
}
while(true);
```

最后我们退出子进程, 并返回

```
delete p;
close(FinSock);
close(FinRevSock);

pthread_mutex_lock(&TCPFinScanlocker);
TCPFinThrdNum--;
pthread_mutex_unlock(&TCPFinScanlocker);
}
```

然后我们编写 void* Thread_TCPFinScan(void* param) 函数,该函数的主要功能是调用 Thread_TCPFINHost 函数创建多个扫描子线程负责遍历目标主机的被测端口。首先我们获取目标主机的 IP 地址和扫描的起始端口号,终止端口号,以及本机的 IP 地址

```
void* Thread_TCPFinScan(void* param) {
    struct TCPFINThrParam *p = (struct TCPFINThrParam*)param;
    std::string HostIP = p->HostIP;
    unsigned BeginPort = p->BeginPort;
    unsigned EndPort = p->EndPort;
    unsigned LocalHostIP = p->LocalHostIP;

TCPFinThrdNum = 0;
    unsigned LocalPort = 1024;
```

接下来,我们开始从起始端口到终止端口循环扫描目标主机的端口。首先我们在循环中设置子线程参数,然后将子线程设为分离状态。创建 FIN 目标主机指定的端口和一个独立的子线程进行绑定,并将子线程数加 1。每一次循环都会判断子线程的数量,如果如果子线程数大于 100,则 暂时休眠。

```
TCPFinThrdNum = 0;
unsigned LocalPort = 1024;

pthread_attr_t attr, lattr;
pthread_t listenThreadID, subThreadID;
for (unsigned TempPort = BeginPort; TempPort <= EndPort;TempPort++)

{
    struct TCPFINHostThrParam *pTCPFINHostParam = new TCPFINHostThrParam;
    pTCPFINHostParam->HostIP = HostIP;
    pTCPFINHostParam->LocalPort = TempPort;
    pTCPFINHostParam->LocalPort = TempPort + LocalPort;
    pTCPFINHostParam->LocalHostIP = LocalHostIP;
```

```
pthread_attr_init(&attr);
15
          pthread_attr_setdetachstate(&attr,PTHREAD_CREATE_DETACHED);
16
17
18
          int ret = pthread_create(&subThreadID,&attr,Thread_TCPFINHost,pTCPFINHostParam);
19
          if (ret == -1)
20
21
             std::cout << "Can't create the TCP FIN Scan Host thread !" << std::endl;</pre>
22
          }
23
          pthread_attr_destroy(&attr);
25
          pthread_mutex_lock(&TCPFinScanlocker);
26
          TCPFinThrdNum++;
27
          pthread_mutex_unlock(&TCPFinScanlocker);
28
          while (TCPFinThrdNum>100)
30
31
             sleep(3);
          }
33
      }
```

最后,我们等待子线程数为0,返回

```
while (TCPFinThrdNum != 0)
{
    sleep(1);
}

std::cout << "TCP FIN scan thread exit !" << std::endl;
pthread_exit(NULL);
}</pre>
```

7. UDP 扫描

这一部分我们使用的数据结构如下:

```
struct UDPThrParam
   {
2
      std::string HostIP;
      unsigned BeginPort;
      unsigned EndPort;
      unsigned LocalHostIP;
   };
8
   struct UDPScanHostThrParam
9
10
      std::string HostIP;
11
      unsigned HostPort;
      unsigned LocalPort;
13
      unsigned LocalHostIP;
14
   };
```

我们这一部分的主要功能是利用 UDP 扫描确定目的主机的 UDP 扫描确定目的主机的某一 UDP 端口是否开启,具体来说就是向被测主机的指定端口发送 UDP 报文,如果收到回复则说明连接成果,则表示端口开启;否则,表示端口关闭。但是这个扫描和之前的有所不同,因为目标主机

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返回的 ICMP 不可达数据包没有包含目标主机的源端口号,扫描器无法判断 ICMP 响应是从哪个端口发出的,如果让让多个子线程同时扫描端口,会造成无法区分 ICMP 响应数据包与其对应端口的情况,无法进行判断。所以我们舍弃了多线程并行的操作,可能效率有所降低,但是准确率有所保障。我们首先编写 void* UDPScanHost(void* param) 函数,该函数的主要功能是完成主机对指定端口的扫描。在该函数最开始,首先获得目标主机的 IP 地址和扫描端口号,然后创建流套接字,发送信息

```
void* UDPScanHost(void* param) {
      struct UDPScanHostThrParam *p = (struct UDPScanHostThrParam*) param;
      std::string HostIP = p -> HostIP;
      unsigned HostPort = p -> HostPort;
      unsigned LocalPort = p -> LocalPort;
      unsigned LocalHostIP = p -> LocalHostIP;
      int UDPSock = socket(AF_INET, SOCK_RAW, IPPROTO_ICMP);
      if(UDPSock < 0)</pre>
10
         pthread_mutex_lock(&UDPPrintlocker);
11
         std::cout << "Can't creat raw icmp socket !" << std::endl;</pre>
12
         pthread_mutex_unlock(&UDPPrintlocker);
      }
14
      int on = 1;
15
      int ret = setsockopt(UDPSock, IPPROTO_IP, IP_HDRINCL, &on, sizeof(on));
17
      if (ret < 0)
18
19
         pthread_mutex_lock(&UDPPrintlocker);
20
         std::cout << "Can't set raw socket !" << std::endl;</pre>
         pthread_mutex_unlock(&UDPPrintlocker);
22
      }
23
```

然后设置 UDP 套接字地址,填充 UDP 数据包,填充 UDP 头和伪首部,用于计算校验和

```
struct sockaddr_in UDPScanHostAddr;
      memset(&UDPScanHostAddr, 0, sizeof(UDPScanHostAddr));
      UDPScanHostAddr.sin_family = AF_INET;
      UDPScanHostAddr.sin_addr.s_addr = inet_addr(&HostIP[0]);
      UDPScanHostAddr.sin_port = htons(HostPort);
      char packet[sizeof(struct iphdr) + sizeof(struct udphdr)];
      memset(packet, 0x00, sizeof(packet));
      struct iphdr *ip = (struct iphdr *)packet;
10
      struct udphdr *udp = (struct udphdr *)(packet + sizeof(struct iphdr));
11
      struct pseudohdr *pseudo = (struct pseudohdr *)(packet + sizeof(struct iphdr) -
12
          sizeof(struct pseudohdr));
13
      udp -> source = htons(LocalPort);
14
      udp -> dest = htons(HostPort);
15
      udp -> len = htons(sizeof(struct udphdr));
16
      udp \rightarrow check = 0;
17
      pseudo -> saddr = LocalHostIP;
19
      pseudo -> daddr = inet_addr(&HostIP[0]);
20
      pseudo -> useless = 0;
21
      pseudo -> protocol = IPPROTO_UDP;
```

```
pseudo -> length = udp->len;

udp->check = in_cksum((u_short *)pseudo,sizeof(struct udphdr)+sizeof(struct pseudohdr));
```

填充 IP 头

```
ip -> ihl = 5;
ip -> version = 4;
ip -> tos = 0x10;
ip -> tot_len = sizeof(packet);
ip -> frag_off = 0;
ip -> ttl = 69;
ip -> protocol = IPPROTO_UDP;
ip -> check = 0;
ip -> saddr = inet_addr("192.168.1.168");
ip -> daddr = inet_addr(&HostIP[0]);
```

然后发送 UDP 数据包,并将 UDPSock 套接字设置为为非阻塞模式

开始利用一个循环循环接受包到 buffer 中,如果接收到了则说明端口打开,如果没接收到则说明没有打开

```
struct timeval TpStart, TpEnd;
      struct ipicmphdr hdr;
      gettimeofday(&TpStart,NULL); //get start time
      do
         //receive response message
         n = read(UDPSock, (struct ipicmphdr *)&hdr, sizeof(hdr));
         if(n > 0)
         {
10
            if((hdr.ip.saddr == inet_addr(&HostIP[0])) && (hdr.icmp.code == 3) && (hdr.
                 icmp.type == 3))
12
                pthread_mutex_lock(&UDPPrintlocker);
                std::cout << "Host: " << HostIP << " Port: " << HostPort << " closed !" <<
14
                     std::endl;
                pthread_mutex_unlock(&UDPPrintlocker);
15
               break;
16
```

```
17 }
18 }
```

判断接收时间,如果接收时间超过了三秒没有响应则自动认为没有链接,这时候便退出

```
gettimeofday(&TpEnd,NULL);
         float TimeUse = (1000000 * (TpEnd.tv_sec - TpStart.tv_sec) + (TpEnd.tv_usec -
              TpStart.tv_usec)) / 1000000.0;
         if(TimeUse < 3)</pre>
         {
             continue;
         }
         else
             pthread_mutex_lock(&UDPPrintlocker);
             std::cout << "Host: " << HostIP << " Port: " << HostPort << " open !" << std
10
                 ::endl;
             pthread_mutex_unlock(&UDPPrintlocker);
11
            break;
12
         }
      }
14
      while(true);
```

最后断开链接,线程结束

```
//close socket
close(UDPSock);
delete p;
}
```

然后我们编写 void* Thread_UDPScan(void* param) 函数,该函数的作用是调用 UDPScanHost 函数创建线程负责遍历目标主机被测端口,首先我们获取目标主机的 IP 地址和扫描的起始端口号,终止端口号,以及本机的 IP 地址

```
void* Thread_UDPScan(void* param)

// pthread_t subThreadID;

// pthread_attr_t attr;

// int ret;

struct UDPThrParam *p = (struct UDPThrParam*) param;

std::string HostIP = p -> HostIP;

unsigned BeginPort = p -> BeginPort;

unsigned EndPort = p -> EndPort;

unsigned LocalHostIP = p -> LocalHostIP;
```

接下来,我们从起始端口到终止端口循环遍历目标主机的端口,进行对端口的扫描。

```
for (unsigned TempPort = BeginPort; TempPort <= EndPort; TempPort++)
{
    UDPScanHostThrParam *pUDPScanHostParam = new UDPScanHostThrParam;
    pUDPScanHostParam->HostIP = HostIP;
    pUDPScanHostParam->HostPort = TempPort;
    pUDPScanHostParam->LocalPort = TempPort + LocalPort;
    pUDPScanHostParam->LocalHostIP = LocalHostIP;
    UDPScanHost(pUDPScanHostParam);
```

```
9
10     }
11     //-----exit thread-----
12     std::cout << "UDP Scan thread exit !" << std::endl;
13     pthread_exit(NULL);
14 }</pre>
```

8. 端口扫描器程序 Scaner

首先程序判断是否需要输出帮助信息,若是,则输出端口扫描器程序的帮助信息,然后退出; 否则,执行下面的步骤。

```
int main(int argc,char *argv[]) {
     std::unordered_map<std::string, void(*)(int, char*[])> mapOp = {{"-h", print_h}, {"-
          c", print_c}, {"-s", print_s}, {"-u", print_u}, {"-f", print_f}};
     if (argc != 2) {
        std::cout << "参数错误, argc = " << argc << std::endl;
        return -1;
     std::string op = argv[1];
     if (mapOp.find(op) != mapOp.end()) {
10
        mapOp[op](argc, argv);
11
        return 0;
12
    }
13
    return 0;
15
```

打印帮助信息函数如下:

```
void print_h(int argc, char *argv[]) {
    std::cout << "Scaner: usage:\n" << "\t" << "[-h] --help information " << std::endl;
    std::cout << "\t" << "[-c] --TCP connect scan" << std::endl;
    std::cout << "\t" << "[-s] --TCP syn scan" << std::endl;
    std::cout << "\t" << "[-f] --TCP fin scan" << std::endl;
    std::cout << "\t" << "[-u] --UDP scan" << std::endl;
}</pre>
```

输入目的 IP 地址和端口信息,并判断是否合法。

```
if(op != "-h") {
          std::cout << "Please input IP address of a Host:";</pre>
          std::cin >> HostIP;
          if(inet_addr(&(HostIP[0])) == INADDR_NONE)
             std::cout << "IP address wrong!" << std::endl;</pre>
             return -1;
10
          std::cout << "Please input the range of port..." << std::endl;</pre>
11
          std::cout << "Begin Port:";</pre>
12
          std::cin >> BeginPort;
13
14
          std::cout << "End Port:";</pre>
          std::cin >> EndPort;
```

二、实验步骤

```
16
          if(BeginPort > EndPort) {
17
              std::cout << "The range of port is wrong !" << std::endl;</pre>
18
              return -1;
19
          }
20
          else
21
22
          {
              if(BeginPort < 1 || BeginPort > 65535 || EndPort < 1 || EndPort > 65535) {
23
                 std::cout << "The range of port is wrong !" << std::endl;</pre>
                 return -1;
             }
26
             else {
27
                 std::cout << "Scan Host " << HostIP << " port " << BeginPort << "~" <<
28
                      EndPort << " ..." << std::endl;</pre>
29
             }
          }
30
31
          if(!Ping(HostIP, GetLocalHostIP())) {
              std::cout << "Ping Host " << HostIP << " Failed !" << std::endl;</pre>
33
              return -1;
          }
35
36
37
       }
38
```

TCP connect 扫描函数

```
void print_c(int argc, char *argv[]) {
      std::cout << "Begin TCP connect scan..." << std::endl;</pre>
      // struct TCPConThrParam TCPConParam;
3
      TCPConParam.HostIP = HostIP;
      TCPConParam.BeginPort = BeginPort;
      TCPConParam.EndPort = EndPort;
      int ret = pthread_create(&ThreadID, NULL,Thread_TCPconnectScan, &TCPConParam);
      if (ret==-1) {
          std::cout << "Can't create the TCP connect scan thread !" << std::endl;</pre>
9
          return;
10
11
      ret = pthread_join(ThreadID, NULL);
12
      if(ret != 0) {
13
          std::cout << "call pthread_join function failed !" << std::endl;</pre>
14
          return;
15
      }
16
17
      else {
          std::cout << "TCP Connect Scan finished !" << std::endl;</pre>
18
19
20
   }
21
```

TCP SYN 函数

```
void print_s(int arg, char *argv[]) {
   std::cout << "Begin TCP SYN scan..." << std::endl;

//create thread for TCP SYN scan

// struct TCPSYNThrParam TCPSynParam;

TCPSynParam.HostIP = HostIP;

TCPSynParam.BeginPort = BeginPort;</pre>
```

二、实验步骤

```
TCPSynParam.EndPort = EndPort;
      TCPSynParam.LocalHostIP = GetLocalHostIP();
      int ret = pthread_create(&ThreadID, NULL, Thread_TCPSynScan, &TCPSynParam);
      if (ret == -1)
10
11
          std::cout << "Can't create the TCP SYN scan thread !" << std::endl;</pre>
12
          return;
13
      }
14
15
      ret = pthread_join(ThreadID, NULL);
      if(ret != 0)
17
18
      {
          std::cout << "call pthread_join function failed !" << std::endl;</pre>
19
          return;
20
      }
21
      else
22
       {
23
          std::cout << "TCP SYN Scan finished !" << std::endl;</pre>
          return;
25
26
27
```

TCP FIN 函数

```
void print_f(int argc, char *argv[]) {
      std::cout << "Begin TCP FIN scan..." << std::endl;</pre>
      //create thread for TCP FIN scan
3
      TCPFinParam.HostIP = HostIP;
      TCPFinParam.BeginPort = BeginPort;
      TCPFinParam.EndPort = EndPort;
      TCPFinParam.LocalHostIP = GetLocalHostIP();
      ret = pthread_create(&ThreadID, NULL, Thread_TCPFinScan, &TCPFinParam);
      if (ret==-1)
10
          std::cout << "Can't create the TCP FIN scan thread !" << std::endl;</pre>
11
          return;
12
13
14
      ret = pthread_join(ThreadID,NULL);
15
      if(ret != 0)
16
       {
17
          std::cout << "call pthread_join function failed !" << std::endl;</pre>
18
          return;
19
      }
20
      else
21
22
          std::cout <<"TCP FIN Scan finished !" << std::endl;</pre>
          return;
24
25
      }
   }
26
```

UDP 函数

```
void print_u(int arg, char *argv[]) {
  std::cout << "Begin UDP scan..." << std::endl;

//create thread for UDP scan
UDPParam.HostIP = HostIP;</pre>
```

```
UDPParam.BeginPort = BeginPort;
      UDPParam.EndPort = EndPort;
      UDPParam.LocalHostIP = LocalHostIP;
      ret = pthread_create(&ThreadID, NULL, Thread_UDPScan, &UDPParam);
      if (ret == -1)
      {
10
          std::cout << "Can't create the UDP scan thread !" << std::endl;</pre>
11
12
      }
13
      ret = pthread_join(ThreadID,NULL);
15
      if(ret != 0)
16
      {
17
          std::cout << "call pthread_join function failed !" << std::endl;</pre>
18
19
      }
20
      else
21
          std::cout << "UDP Scan finished !" << std::endl;</pre>
23
          return;
24
25
   }
26
```

(三) 实验结果

• 打印帮助函数

• TCP Connect 扫描

```
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```

• UDP 扫描

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```

• TCP FIN 扫描

• TCP SYN 扫描

```
| Section | Sect
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