Model Evaluation

- Metrics for Performance Evaluation
 - How to evaluate the performance of a model?

- Methods for Performance Evaluation
 - How to obtain reliable estimates?

- Methods for Model Comparison
 - How to compare the relative performance of different models?

Metrics for Performance Evaluation

- Focus on the predictive capability of a model
 - Rather than how fast it takes to classify or build models, scalability, etc.
- Confusion Matrix:

	PREDICTED CLASS		
		Class=Yes	Class=No
ACTUAL	Class=Yes	a: TP	b: FN
CLASS	Class=No	c: FP	d: TN

a: TP (true positive)

b: FN (false negative)

c: FP (false positive)

d: TN (true negative)

Metrics for Performance Evaluation...

	PREDICTED CLASS		
		Class=Yes	Class=No
ACTUAL CLASS	Class=Yes	a (TP)	b (FN)
OLAGO	Class=No	c (FP)	d (TN)

Most widely–used metric:

Accuracy =
$$\frac{a+d}{a+b+c+d} = \frac{TP+TN}{TP+TN+FP+FN}$$

Limitation of Accuracy

- Consider a 2-class problem
 - Number of Class 0 examples = 9990
 - Number of Class 1 examples = 10
- If model predicts everything to be class 0, accuracy is 9990/10000 = 99.9 %
 - Accuracy is misleading because model does not detect any class 1 example

Cost Matrix

	PREDICTED CLASS		
	Class=No		
ACTUAL CLASS	Class=Yes	C(Yes Yes)	C(No Yes)
CLASS	Class=No	C(Yes No)	C(No No)

C(i|j): Cost of misclassifying class j example as class i

Computing Cost of Classification

Cost Matrix	PREDICTED CLASS		
ACTUAL CLASS	C(i j)	+	-
	+	-1	100
02/100	I	1	0

Model M ₁	PREDICTED CLASS		
		+	-
ACTUAL CLASS	+	150	40
02,100	-	60	250

Accuracy
$$= 80\%$$

Cost $= 3910$

Model M ₂	PREDICTED CLASS		
		+	-
ACTUAL CLASS	+	250	45
02,100	-	5	200

Accuracy =
$$90\%$$

Cost = 4255

Cost vs Accuracy

Count	PREDICTED CLASS		
		Class=Yes	Class=No
ACTUAL CLASS	Class=Yes	а	b
	Class=No	С	d

Cost	PREDICTED CLASS		
		Class=Yes	Class=No
ACTUAL	Class=Yes	р	q
CLASS	Class=No	q	р

Cost vs Accuracy

Count	PREDICTED CLASS		
		Class=Yes	Class=No
ACTUAL	Class=Yes	а	b
CLASS	Class=No	С	d

Accuracy is proportional to cost if

- 1. C(Yes|No)=C(No|Yes) = q
- 2. C(Yes|Yes)=C(No|No)=p

$$N = a + b + c + d$$

$$Accuracy = (a + d)/N$$

Cost = p (a + d) + q (b + c)
= p (a + d) + q (N - a - d)
= q N - (q - p)(a + d)
= N [q - (q-p)
$$\times$$
 Accuracy]

Cost-Sensitive Measures

Precision (p) =
$$\frac{a}{a+c} = \frac{TP}{TP+FP}$$

Recall (r) = $\frac{a}{a+b} = \frac{TP}{TP+FN}$
F - measure (F) = $\frac{2rp}{r+p} = \frac{2a}{2a+b+c} = \frac{2TP}{2TP+FP+FN}$

- Precision is biased towards C(Yes|Yes) & C(Yes|No)
- Recall is biased towards C(Yes|Yes) & C(No|Yes)

Weighted Accuracy =
$$\frac{w_1 a + w_4 d}{w_1 a + w_2 b + w_3 c + w_4 d}$$

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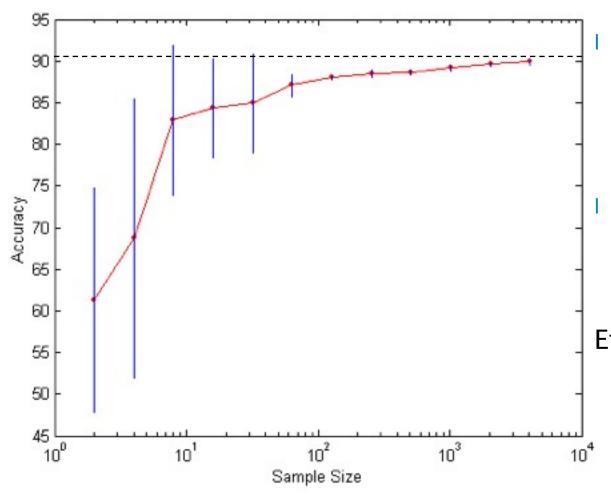
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Methods for Performance Evaluation

 How to obtain a reliable estimate of performance?

- Performance of a model may depend on other factors besides the learning algorithm:
 - Class distribution
 - Cost of misclassification
 - Size of training and test sets

Learning Curve



- Learning curve shows how accuracy changes with varying sample size
- Requires a sampling schedule for creating learning curve

Effect of small sample size:

- Bias in the estimate
- Variance of estimate

Methods of Estimation

Holdout

Reserve 2/3 for training and 1/3 for testing

Random subsampling

Repeated holdout

Cross validation

- Partition data into k disjoint subsets
- k-fold: train on k-1 partitions, test on the remaining one
- Leave-one-out: k=n

Bootstrap

Sampling with replacement

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ROC (Receiver Operating Characteristic)

- Developed in 1950s for signal detection theory to analyze noisy signals
 - Characterize the trade-off between positive hits and false alarms
- ROC curve plots TPR (on the y-axis) against FPR (on the x-axis)

$$TPR = \frac{TP}{TP + FN}$$

$$FPR = \frac{FP}{FP + TN}$$

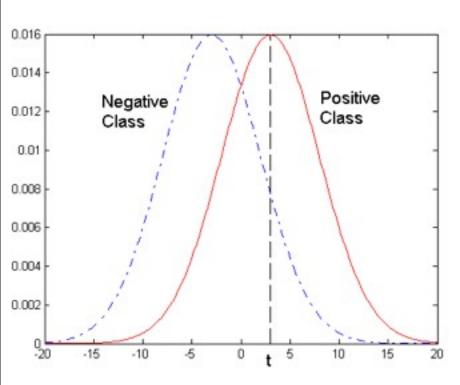
	PREDICTED CLASS		
		Yes	No
Actual	Yes	a (TP)	b (EN)
, totaar	No	c (FP)	d (TN)

ROC (Receiver Operating Characteristic)

- Performance of each classifier represented as a point on the ROC curve
 - changing the threshold of algorithm, sample distribution or cost matrix changes the location of the point

ROC Curve

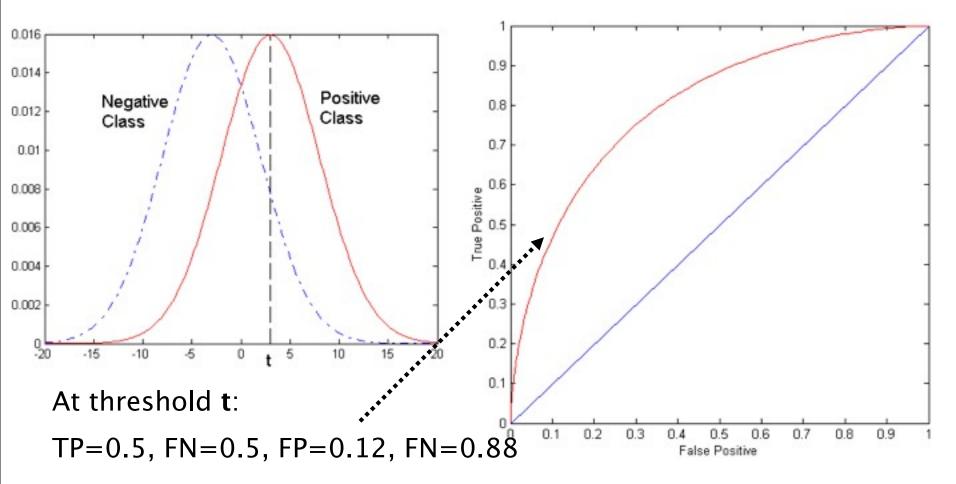
- 1-dimensional data set containing 2 classes (positive and negative)
- any points located at x > t is classified as positive



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ROC Curve

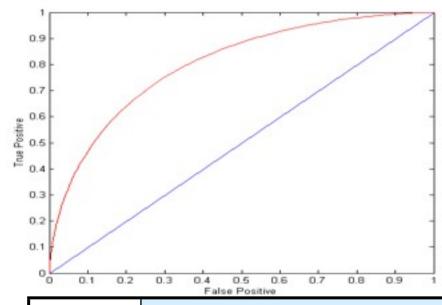
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ROC Curve

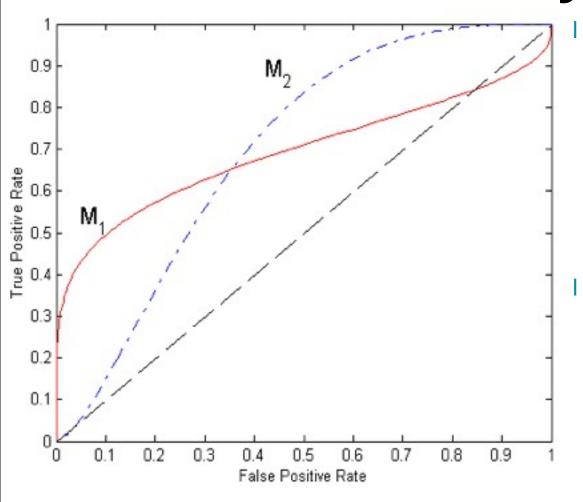
(TP,FP):

- (0,0): declare everything to be negative class
- (1,1): declare everything to be positive class
- (0,1): ideal
- Diagonal line:
 - Random guessing
 - Below diagonal line:
 - prediction is opposite of the true class



	PREDICTED CLASS		
		Yes	No
Actual	Yes	a (TP)	b (FN)
	No	c (FP)	d (TN)

Using ROC for Model



- No model consistently outperform the other
 - M₁ is better for small FPR
 - M₂ is better for large FPR
- Area Under the ROC curve
 - Ideal: Area = 1
 - Random guess:
 - Area = 0.5

How to Construct an ROC curve

Instance	P(+ A)	True Class
1	0.95	+
2	0.93	+
3	0.87	-
4	0.85	-
5	0.85	-
6	0.85	+
7	0.76	-
8	0.53	+
9	0.43	-
10	0.25	+

- Use classifier that produces posterior probability for each test instance P(+|A)
- Sort the instances according to P(+|A) in decreasing order
- Apply threshold at each unique value of P(+|A)
- Count the number of TP, FP, TN, FN at each threshold
- TP rate, TPR = TP/(TP+FN)
- FP rate, FPR = FP/(FP + TN)

How to construct an ROC

	Class	+	-	+	-	-	-	+	-	+	+	
Threshold	>=	0.25	0.43	0.53	0.76	0.85	0.85	0.85	0.87	0.93	0.95	1.00
	TP	5	4	4	3	3	3	3	2	2	1	0
	FP	5	5	4	4	3	2	1	1	0	0	0
	TN	0	0	1	1	2	3	4	4	5	5	5
	FN	0	1	1	2	2	2	2	3	3	4	5
\longrightarrow	TPR	1	0.8	0.8	0.6	0.6	0.6	0.6	0.4	0.4	0.2	0
→	FPR	1	1	0.8	0.8	0.6	0.4	0.2	0.2	0	0	0

