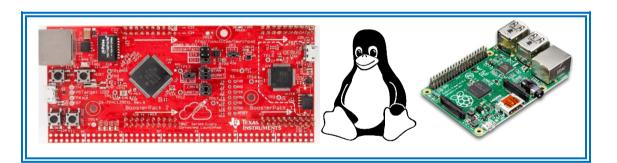




## **EMBEDDED SYSTEM DESIGN**

Project: Automatic Control via Internet

Instructor: Dr. Truong Quang Vinh



Class: DD15KSVT Group 1
Le Van Hoang Phuong 1512579
Nguyen Chinh Thuy 1513372
Tran Huy Hoang 1511149

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## II. Preface

This document summaries the overall process that we designed and implemented our class project of Embedded System Design. The topic is "Automatic Control via Internet". The officially topic we assigned is "Automatic Control via Ethernet" but with acceptance of our instructor, we have make it greater in term of distance of control. However, we do not just stop by automatic control, we developed our project to be made up of Graphic User Interface to widen our knowledge and accumulate our design skills.

This topic gives us various chance and challenges as this is the first time we have actually worked in collaboration with each other and approached a thoroughly new embedded system design methodology.

Our purpose is designing an embedded product containing our available hardware components and capable of connecting to the global network. In detail, we model the topic by designing a "smart door" automatically controlled by a server via Internet. We reckon that perhaps somewhere in the world, this model is put into practice. This model can be illustrated by diagram below:

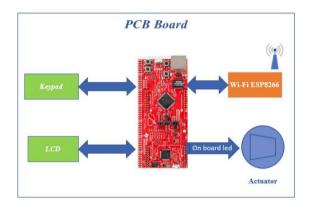






Figure I.2-1. Prototype of Desired Product

## III. Market & Version

#### III.1. Customer's need

- [1] Life is growing, people need more "smart" products, able to control automatically.
- [2] Personal and household property needs to be kept strictly confidential
- [3] Technology products should be simple, easy to use, suitable for those who are less exposed to technology.

## III.2. Customer Classification

No.	Classifications	Examples
1	Customors need simplicity	<ul> <li>Family</li> </ul>
1	Customers need simplicity	<ul><li>Farm owner</li></ul>
		Warehouse manager
2	Customers need security	<ul> <li>Laboratory</li> </ul>
		Computer room
2	C	Apartment
3	Customers need to manage data	<ul><li>Company</li></ul>

## III.3. Customer's requirement

- Simple to use
- High security
- Low power
- Low cost
- Managed on many different devices

#### III.4. Versions

	D . 17		5. 1
Versions	Detail	Advantage	Disadvantage
1	Username + Password	- Simple, easy to use - Low cost	<ul><li>Low security</li><li>Not aesthetic</li><li>Not suitable for children</li></ul>
2	Magnetic card	<ul><li>High security</li><li>Simple, easy to use</li></ul>	- Easy to lose magnetic
3	Fingerprint	- Simple, easy to use - No lose data	<ul><li>Speed authentication is slow</li><li>Easy to fake</li></ul>
4	Iris	- Simple, easy to use - No lose data	<ul> <li>High cost</li> <li>Low security (the iris sensor on the Galaxy S8 may be fooled by the print image)</li> </ul>
5	Face ID	<ul><li>Simple, easy to use</li><li>No lose data</li><li>High security</li></ul>	<ul> <li>High cost</li> <li>Only one face can be identified (Face ID of Iphone X identifies a single face)</li> </ul>

## IV. Introduction

#### IV.1. Function

Our system includes two main partitions, *User interface* and *Database server*.

First, the *User interface* is responsible for collecting data from user. In our prototype, this data is called account containing username and password (each person has an individual account). After getting verification from user, the *User interface* will transfer this data to the *Database server* through the Internet for checking whether this login data is correct. Consequently, the result will be sent back to the *User interface*. If the result reveals correctness, the *User interface* will allow the user move through the door, if not, the system will halt for an interval so that no one cannot enter the door.

Additionally, the whole of login history is saved in the *Database server*, so when the admin want to review who accessed the door, it can use a PC and connect to the *Database server* through the Internet with a unique admin account in order to view the login history. Besides, *Database server* also provides account management ability for the admin so as to modify the information of doorpermitted accessors.

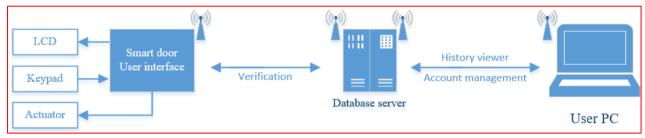


Figure IV.1-1. Overall of the system

## IV.2. Prototype



Figure IV.2-1. User interface partition



Figure IV.2-2. Server partition

## V. Project Management

## V.1. Team Contract

TEAM CONTRACT			
Team name: (Tactic -	Date: 24 Sep, 2017		
Team member	Roles	Signature	
Lê Văn Hoàng Phương	Linux OS, Leader		
Nguyễn Chính Thụy	Networking		
Trần Huy Hoàng	Embedded		
	Tasks	Responsible member	
1. Operating Platform	*	Lê Văn Hoàng Phương	
2. Functional Develop	Lê Văn Hoàng Phương		
3. Connecting Archite	Nguyễn Chính Thụy		
4. Data frame transmi	ssion	Nguyễn Chính Thụy	
5. Firmware Develop	nent	Trần Huy Hoàng	
6. User Interface Deve	elopment	Trần Huy Hoàng	
7. Integrate and test		All	
8. Report		All	
Team meeting	4 PM, Tuesda		
Team meeting	A4 hall, Bach Khoa university		
	1. Participate in all team meetings		
	2. Listen carefully to all comments at meeting		
Team rules	3. Complete all assigned tasks before deadlines		
L CWIIV I WVCD	4. Prepare idea for the subsequent work before meeting		
	5. Focus on results rather than excuses after		
	6. Complete such tasks as trello, github.		

## V.2. Project Plan

·	PROJECT PLANNING				
Team name		T.H.E (Tactic - Honor - Evolution)			
Product name		Automatic Control (In this Project: St			
Main features	2. Sy	<ol> <li>Entrance management with <i>User</i> and <i>Password</i></li> <li>Sync data to the server</li> <li>History viewer</li> </ol>			
Estimated Time	Start:	8 weeks Start: 23 Aug. 2017 End: 18 Oct. 2017			
Estimated Cost	KIT : 550,000 VNĐ Components : 300,000 VNĐ <i>Total</i> : 850,000 VND				
	Lê Văi	n Hoàng Phương	Linu	ıx OS, Leader	
Team members				Vetworking	
	Trầ	rần Huy Hoàng I		Embedded	
	Week 1	Receive the title of the project  Take an overview look about project		All	
	Week 2	Idea for system Distribution of contribution Block diagram		All	
Schedule (working weeks only)	Week 3	Connection through internet  Platform for connection on Linux  LED interface		Nguyễn Chính Thụy Lê Văn Hoàng Phương Trần Huy Hoàng	
	Week 4	Data frame Function development Interrupt		Nguyễn Chính Thụy Lê Văn Hoàng Phương Trần Huy Hoàng	
	Week 5	LCD Server service		Nguyễn Chính Thụy Lê Văn Hoàng Phương	
		Keypad		Trần Huy Hoàng	

		Firmware connection	Nguyễn Chính Thụy
	Week 6	Software connection	Lê Văn Hoàng Phương
Schedule		Product analysis	Trần Huy Hoàng
	Week 7	Testing	All
	Week 8	Report	All

## V.3. System Specification

## V.3.1. Product Specification



Figure V.3-1. Product block diagram

Product name	"Smart door"		
Functions	<ul> <li>Verification in the door opening.</li> <li>Connect to a database server to verify the right to open the door.</li> <li>Account (right to open the door) management.</li> </ul>		
I/O	<ul><li>Input: Account ID, Password (optional).</li><li>Output: Actuator (motor to open/close the door) port.</li></ul>		
User interface	<ul> <li>LCD: Display input data, verification result.</li> <li>Keypad: Input the verification data.</li> <li>PC: Add/Remove accounts in the database server.</li> </ul>		
External interface	- Wi-Fi: Connect to the database server.		
Constraints	- Real-time: Verification time is less than 2s.		
Versions	<ul> <li>Being developed (will be used in the sequential documents):         TSD102: Username + Password.</li> <li>Will be considered in the future:         TSD302: Magnetic card.         TSD312: Magnetic card + Password.         TSD502: Fingerprint.         TSD702: Iris.         TSD902: Face.</li> </ul>		

## V.3.2. Engineering Specification

8 81 3		
	- Microcontroller: TIVA-C family.	
Hardware components	- LCD 16x2, Keypad 4x4.	
	- Wi-Fi module: ESP8266.	
	- Power supply: Voltage regulator IC.	
Hardware requirements	- Implement a single-layer PCB.	
	- Size: Smaller than an A4 paper.	
	- Overcurrent protection.	
-	- Have a button to isolate MCU power from the remaining parts on	
	the PCB.	
	- Peripheral drivers.	
Firmware components	- User interface.	
	- Server interface.	
Firmware requirements	- Write in C language.	

	- Read button and display the received character from button through LCD.
	- Send login data to the server and display the received result into LCD.
C - C	- Embedded shell (serve for embedded devices).
Software components	- OS shell (serve for PC/laptop devices).
	- Write in C language.
	- Establish connection with devices.
	- Verify login data received from devices.
Software requirements	- Record the login data for history viewer.
	- Allow owner modify which accounts.
	- Allow owner backup the whole of data on the server.
	- Have some configuration modes for owner to select.

## V.3.3. Hardware Specification

- Overview:

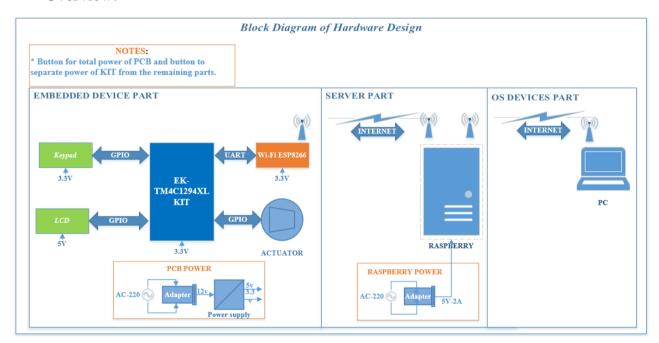


Figure V.3-2. Hardware block diagram

- Component list:

Module	Specification
Adenter	Input: 220VAC,
Adapter	Output: 12VDC – 1A
	IC LM7805: output 5VDC,
Dayyan ayanılıy	IC LM1117: output 3.3VDC,
Power supply	Power button for the whole of PCB,
	Power button for isolating MCU from the rest of PCB
MCU	Kit EK-TM4C1294XL,
WICO	Booster Packs for plugging Kit
Vaynad	Keypad 4x4,
Keypad	The front of keypad is numbered
I CD	LCD 16x2 HD44780,
LCD	Varistor for adjust the contrast of LCD,

	Using 4-bit data connection
Wi-Fi	ESP8266-v1

## V.3.4. Sotfware Specification

- Overview diagram:

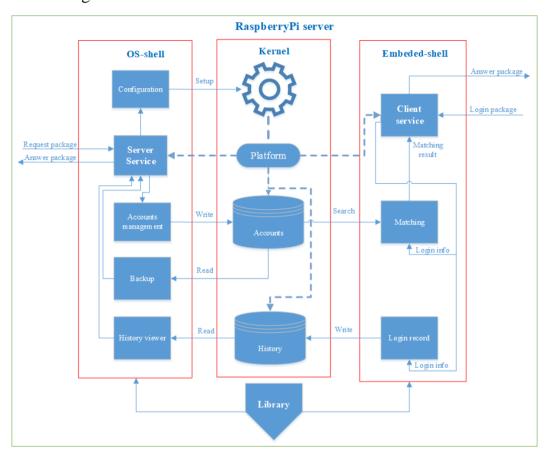


Figure V.3-3. Software block diagram

#### Detailed information:

Partition	Module	Function		
	Configuration Configuration modes of operation of server.			
	Platform	Provide threads for Embedded shell and OS shell running.		
Kernel	Accounts	Account database using for login verification.		
Kerner		The file extension: ".acc"		
	II:-4	Login record using for history viewer.		
	History	The file extension: ".log"		
Lib		Some mutual and common software libraries for programmers.		
	Client service	Receive data from embedded devices, transfer data to the		
		corresponding module, answer the result for embedded devices.		
Embedded	Matching	Verify the validity of login data by comparing the login		
shell		information with database.		
	Login record	Record time, username, password, and verification result when a		
	Logiii iecolu	login data is received from embedded shell.		
	Configuration	Allow admin to configure operation mode of the server.		
	Server service	Receive data from OS devices, transfer data to the corresponding		
OS shell		module, answer the result for OS devices.		
	Accounts	Allow admin to modify accounts on the server.		
	management			

Backup	Allow the admin backup the whole of database on the server on its OS device.
History viewer	Allow the admin view the list of login record.

#### V.3.5. Test Specification

Section	Content	
Testing equipment	Multi-meter, Oscillator	
Testing environment	Strong Wi-Fi signal	
Prototype	Self-implemented PCB (single layer)	
	Check Keypad and LCD	
	Check Wi-Fi connection of ESP8266	
	Check Verification between MCU and Server	
Testing process	Check History Viewer	
	Check Account Management	
	Check Data Backup	

## V.4. System Architecture development

	- Microcontroller: TIVA-C family.	
Hardware	- LCD 16x2, Keypad 4x4.	
	- Wi-Fi module: ESP8266.	
	- Power supply: Voltage regulator IC.	
Firmware	- Peripheral drivers.	
	- User interface.	
	- Server interface.	
Software	- Embedded shell (serve for embedded devices).	
	- OS shell (serve for PC/laptop devices).	
	- LCD driver	
Interface	- Keypad driver	
interrace	- Input/ Output control driver	
	- User Interface	

## V.5. Design Issues

#### V.5.1. Constraint issues

Low price	About 850,000đ
Long life cycle	5 years
Reliability	Data is not encrypted
Response time for control	Less than 2s
<b>Data transmission over the Internet</b>	Less than 2s

#### V.5.2. Functional issues

- Connection can be corrupted, system must automatically reconnect.
- Devices can be overheated for long time working so it needs to be detected by a sensor.
- Door controlling devices can be broken or got stuck, it needs a component to detect and go off.

- Internet access points can be crashed, it needs a device to alarm.
- Such malfunctions as wrong data comparison, wrong control could cause damages to security and economy.

#### V.5.3. Real-time issues

Components	Real-time
<b>Device for control the door</b>	Soft real-time: delay less than 1s
Server Computer	Soft real-time: delay less than 1s
Micro-controller	Soft real-time: delay less than 1s
LCD display	Soft real-time: delay less than 0.5s
Keypad	Soft real-time: delay less than 0.5s

#### V.5.4. Concurrent issues

Server computer	Multi-access	Serve clients and admins simultaneously
Microcontroller	Multi-task	Operate keypad, display LCD, connection to server, compare data, control the door simultaneously

#### V.5.5. Reactive issues

- ❖ Continuous: server computer must run 24 hours a day to serve clients and admins.
- \* Non-periodic event response:
  - People use keypad.
  - Connection is crashed.
  - Administrators accesses.

## V.6. House of Quality

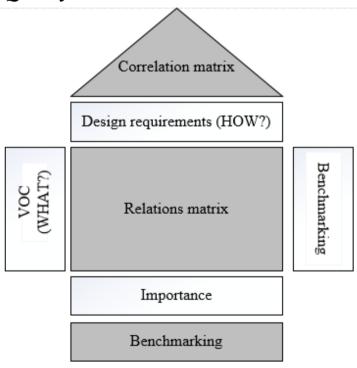


Figure V.6-1. House of quality

## V.6.1. What?

No.	Customer's requirement
1	Simple to use
2	High security
3	Low power
4	Low cost
5	Managed on many different devices

Table V.6-1. Table of What

#### V.6.2. How list

No.	Design requirement
1	Low power microcontroller
2	Read keypad and display through LCD
3	Verify login data received from devices
4	Record the login data for history viewer
5	Backup the whole of data on the sever

Table V.6-2. Table of How list

#### V.6.3. Relation matrix

Design requirement  Customer's requirement	Low power microcontroller	Read keypad and display through LCD	Verify login data received from devices	Record the login data for history viewer	Backup the whole of data on the sever
Simple to use	W	S	W	W	W
High security	W	M	S	S	M
Low power	S	S	W	W	W
Low cost	S	S	W	W	W
Managed on many different devices	W	W	M	M	S

Table V.6-3. Table of relation matrix

W = weak M = medium S = strong

## V.6.4. Benchmarking

Design	Low	Read	Verify	Record	Backup			
requirement	power	keypad	login	the	the		e,	
	micro-	and	data	login	whole	Bad	rag	Good
	controller	display	received	data for	of data	B	Average	Ď
Customer's		through	from	history	on the		A	
requirement		LCD	devices	viewer	sever			
Simple to use	W	S	W	W	W	X		
High security	W	M	S	S	M			X

Low power	S	S	W	W	W		X
Low cost	S	S	W	W	W	X	
Managed on many different devices	W	W	M	M	S	X	

Table V.6-4. Table of Benchmarking

## V.6.5. Importance level

Design requirement  Customer's Requirement		Low power micro- controller	Read keypad and display through LCD	Verify login data received from devices	Record the login data for history	Backup the whole of data on the sever	Bad	Average	Good
What	Importance				viewer				
Simple to use	2	W	S	W	w	W	х		
High security	5	W	M	S	S	M			X
Low power	1	S	S	W	W	W			X
Low cost	4	s	S	W	W	W		X	
Managed on many different devices	3	W	W	M	M	S		Х	
Impor	tance	55	81	61	61	49			

## Table V.6-5. Table of importance level

Strong = 9 Medium = 3 Weak = 1

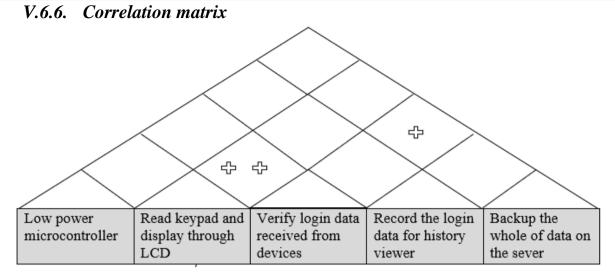


Figure V.6-2. Table of correlation matrix

- ++ strong positive
- + positive
- negative

## V.7. Analyzing the impacts on the economy, environment, society and globe of your project's topic.

## V.7.1. Identifying the social, economic, environment and global contexts related to embedded systems.

- ❖ Economy: saving time for ones to open the smart door, saving money for hiring guards.
- Society: consolidating security & stability of the society

## V.7.2. Explaining the implications of technical solutions when designing your embedded system in those contexts.

- **&** Economy:
  - Integrating more useful features and optimizing the product to reduce one's costs.
  - Power saving mode from 11 PM to 5 AM to reduce the electric bills.
- Society: technical solution is enhancing security for the system by using such ways as encrypting data.

## V.7.3. Considering selection of technical solutions (including hardware and software) and select the appropriate solution basing on those effects.

No.	Partition	Sol.1	Sol.2	Decision
1	MCU	STM8: Low power/cost	TM4C1294NCPDT: High	#2: Available
			speed, Wide memory	kit/experience,
				large resources to expand
				the application
2	Keypad	Plug-header 4x4	Solder-header 4x4 keypad	#1: Aesthetics
		keypad		
3	LCD	LCD 16x2 44780		#1: Widespread usage
4	Wi-Fi	Arduino Wi-Fi shield	ESP8266-v1	#2: Smaller cost, firmware
				programmability

	•	•	
D	2S12	nin	Q
$\boldsymbol{\sim}$			_

5	Actuator	LED	Motor	#1: To just simulate the system, using Sol.1 is cheaper.
6	Server type	PHP server: Easier, Available for installing	C server: More difficult, cost a lot of time to build	#2: We want to try programming a server in C language so that we can improve C language programming skill.
7	Server hardware	Raspberry Pi	PC	#1: Available, Save energy
8	Server OS	Windows	Linux	#2: Free license, optimized for the hardware, secured, built-in platform.

## VI. Designing

## VI.1. Principle

## VI.1.1. Block Diagram

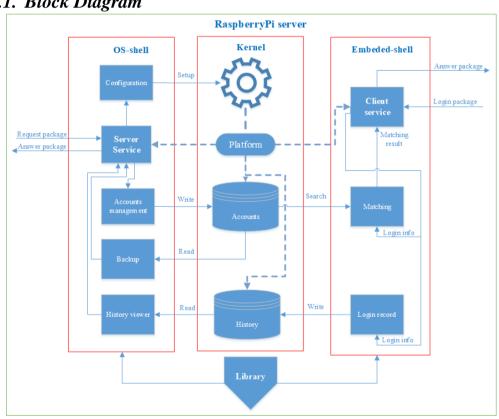


Figure VI.1-1: Block Diagram of Designing

## VI.1.2. Frame of Data Transmission

**Address** 

0x01	0x02	address	function	Number of data's byte	data	0x03	0x04
W	here:						
0x01, 0x02		Start	of frame				
	0x03,	0x04	End o	of frame			

Each admin/embedded device assigned to a

specific *number* regarded as address **Function**We define services a *number* 

#### VI.1.3. Control Scheme

Each user (embedded device or admin) is delivered some specific services defined in a list, below is the list of delivered services.

List of services delivered for specified user is formed like below:

{address 0, service 0, a callback function to service 0}, {address 0, service 1, a callback function to service 1}

#### VI.1.4. Connection Prototype

Connection process of data link layer is illustrated by diagram below:

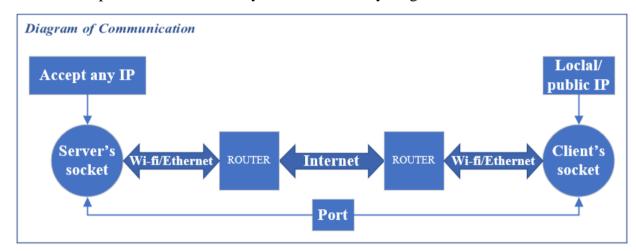


Figure VI.1-2. Socket connection

#### VI.1.5. Server & Client Model

#### VI.1.5.1. Server

Server can be a PC or an embedded computer. In this project, we concentrated on an embedded computer, say Raspberry Pi 3.

This server runs a program that stores accounts and responses to user. This program is considered as cloud database.

#### **VI.1.5.2.** Client

Clients are both embedded device and PCs. These clients require services according to its device's type.

#### VI.1.6. Operation

#### **VI.1.6.1.** Server

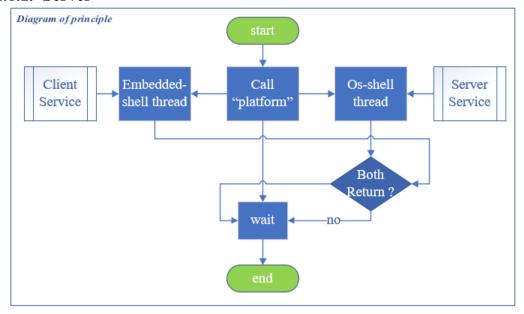


Figure VI.1-3. Diagram of server's operation

The most important server's function in our project is multi-thread. The platform block first creates 2 major threads, they are *embedded-shell* thread and *os-shell* thread. *Embedded shell* thread is used to serve embedded device, namely TivaC129 attached on PCB board. *os-shell* thread is in charge of serving devices using UNIX-like operating system (we call them "os device").

How can this server distinguish between embedded device's connection and os device's connection? Each shell is set to monitor only one "port number", so there are 2 different ports for 2 types of device and they cannot be misunderstood.

Each thread will control the service distribution center, say "server service" and "client service", and interacts with accordant devices with TCP/IP prototype. The server service manages 4 services and client service manages only "embedded login" service, see <u>System Specification</u> for more information. "embedded login" service will log clients' information to "History" each time. System Specification

Once starting, server will always wait for server both device's types unless the admin stop it by using "configuration" service.

#### VI.1.6.2. Embedded Device

Embedded devices gain connection to server by using port number defined by *embedded-shell*. Server will receive their requests and start it tasks, namely *"embedded login"*.

See Connection Prototype.\_Connection\_Prototype

#### VI.1.6.3. OS Device

OS devices set up their socket combined with the port number defined by os-shell and connect to server. Afterward, os-shell will receive their requests and call service distribution center to deal with it, namely "serverService".

## VI.2. Hardware Design

#### VI.2.1. Hardware Component

- 1. Microcontroller: 32- bit microcontroller: TM4C1294NCPDT.
- 2. Peripherals:
  - Input devices: Switch, kepad 4x4
  - Display devices: LED, text LCD.
  - Actutors: LED (for prototype).
  - Interfaces: UART, wifi.
- 3. Clock/ reset circuits: on board Tiva.
- 4. Power supply: use AC/ DC adapters 12V.
- 5. Connector:
  - Power connector
  - Header.

#### VI.2.2. Hardware Block Diagram

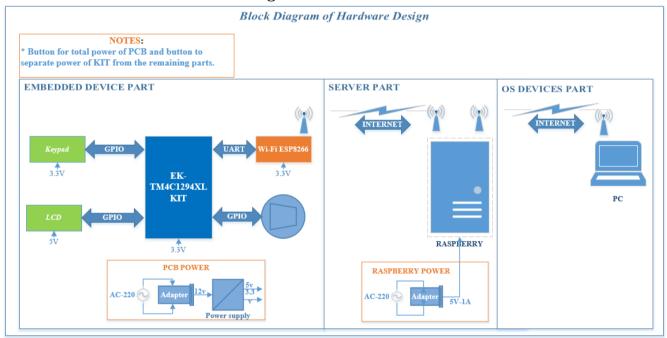


Figure VI.2-1. Hardware Block Diagram

#### VI.2.3. Schematic

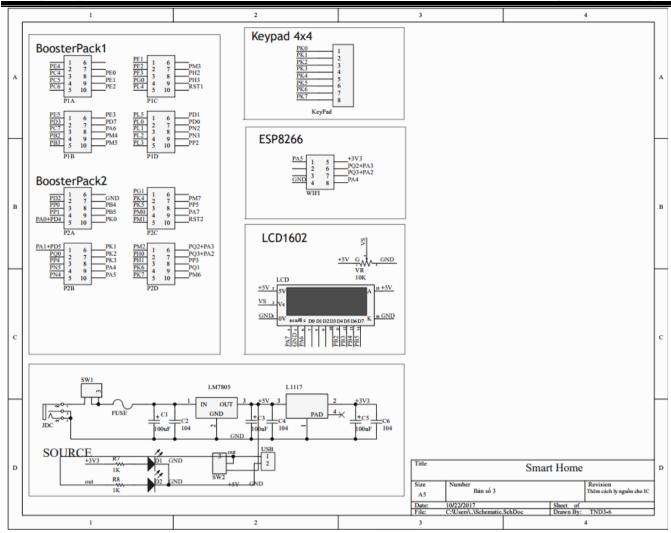


Figure VI.2-2. Schematic

## VI.3. Firmware Design

This section interprets about firmware. To design firmware methodically, we follow this process.



Figure VI.3-1. Firmware design process

As the result, subsequent sub-sections also follow this process. Because, requirements and specifications are mentioned in the section V, so in this section, we start from listing components, then figure out our peripheral library as well as modules, last but not least, all of modules will be united.

VI.3.1. Components

Modules	Component	Connection to MCU
Microcontroller	TM4C1294NCPDT	EK-TM4C1294 Kit
Interface	LCD 16x2 Keypad 4x4	GPIO
Wi-Fi	ESP8266	UART
Actuator	LED (for prototype)	GPIO

#### VI.3.2. Peripheral control

#### VI.3.2.1. LCD 16x2

LCD 16x2 has two modes of control, 4- and 8-bit data. To save resource, we decide to communicate with the LCD in 4-bit mode. For convenience, we write a library for controlling LCD 16x2, this library has functions below:

Function	Description	Input	Output	
lcdSetup	Setup GPIO for LCD,	None	None	
reasecup	Setup LCD	None	None	
lcdClearScreen	Clear screen,	None	None	
reactearscreen	Move cursor to original	None	None	
lcdChangeLine	Change the current line	(bool) line_th: false for the 1st line, true for	None	
redenangenine	Change the current line	the 2nd line.	None	
lcdDisplay	Display a string to screen	(char*)str: String to display to screen	None	
lcdAddChar	Add a character to the	(char)ch: The adding character	None	
ICUAUUCIIAI	next position	(Char)ch. The adding character	none	

#### VI.3.2.2. Keypad 4x4

To control Keypad 4x4, we use the "Sweep" method. It can be explained as the following figure.

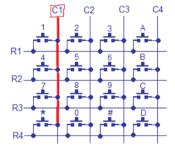


Figure VI.3-2. Keypad 4x4

Denote that C1-C4 is output signals and R1-R4 is input signals, which connect to the MCU. At a time, assume C1 is activated over the deactivated remaining ones. If user press button [1], subsequently, R1 is also activated and MCU can read this activation to know that button [1] is being pressed. Similarly, we need to activate each column in a specific interval so that MCU can read which button is pressed.

Based on this method, we built a library for controlling a keypad.

Function	Description	Input	Output
kpSetup	Setup GPIO for Keypad	None	None
kpSweep	Sweep output signals	None	None
kpCheck	Read input signals to indicate pressed button	None	None

#### VI.3.2.3. ESP8266

ESP8266 is a Wi-Fi chip with full TCP/IP stack. Besides, its communication is UART with supporting AT command set.

Function	AT Command	Response
Working	AT	OK
Restart	AT+RST	OK [System Ready, Vendor:www.ai-thinker.com]
Firmware version	AT+GMR	AT+GMR 0018000902 OK
List Access Points	AT+CWLAP	AT+CWLAP +CWLAP:(4,"RochefortSurLac",-
		38,"70:62:b8:6f:6d:58",1)
		+CWLAP:(4,"LiliPad2.4",-83,"f8:7b:8c:1e:7c:6d",1)
		OK
Join Access Point	AT+CWJAP?	Query AT+CWJAP? +CWJAP:"RochefortSurLac" OK
	AT+CWJAP="SSID","Password"	
Quit Access Point	AT+CWQAP=?	Query
	AT+CWQAP	OK
Get IP Address	AT+CIFSR	AT+CIFSR 192.168.0.105
		ОК
Set Parameters of	AT+ CWSAP?	Query
Access Point	AT+ CWSAP= <ssid>,<pwd>,<chl>, <ecn></ecn></chl></pwd></ssid>	ssid, pwd
	_	chl = channel, ecn = encryption
WiFi Mode	AT+CWMODE?	Query
	AT+CWMODE=1	STA
	AT+CWMODE=2	AP
	AT+CWMODE=3	вотн
Set up TCP or UDP	AT+CIPSTART=?	Query
connection	(CIPMUX=0) AT+CIPSTART =	id = 0-4, type = TCP/UDP, addr = IP address, port= port
	<type>,<addr>,<port></port></addr></type>	
	(CIPMUX=1) AT+CIPSTART=	
	<id><type>,<addr>, <port></port></addr></type></id>	
TCP/UDP	AT+ CIPMUX?	Query
Connections	AT+ CIPMUX=0	Single
	AT+ CIPMUX=1	Multiple
Check join devices' IP	AT+CWLIF	
TCP/IP Connection	AT+CIPSTATUS	AT+CIPSTATUS? no this fun
Status	(CIDALLIX O) AT CIDCENID . I I.	
Send TCP/IP data	(CIPMUX=0) AT+CIPSEND= <length>;</length>	
CI TOD / LIDD	(CIPMUX=1) AT+CIPSEND= <id>,<length></length></id>	<u> </u>
Close TCP / UDP	AT+CIPCLOSE= <id> or AT+CIPCLOSE</id>	
connection Set as server	ATI CIDCEDVED— compades [ compates]	made 0 to class comics made; made 1 to come, nort - nort
	AT+ CIPSERVER= <mode>[,<port>]  AT+CIPSTO?</port></mode>	mode 0 to close server mode; mode 1 to open; port = port
Set the server timeout		Query <time>0~28800 in seconds</time>
	AT+CIPSTO= <time></time>	
Baud Rate*	AT+CIOBAUD? Supported: 9600, 19200, 38400, 74880,	Query AT+ClOBAUD? +ClOBAUD:9600 OK
	115200, 230400, 460800, 921600	
Check IP address	AT+CIFSR	AT+CIFSR 192.168.0.106
CHECK IF dudiess	ATTOLISK	OK
Firmware Upgrade	AT+CIUPDATE	1. +CIPUPDATE:1 found server
(from Cloud)		2. +CIPUPDATE:2 connect server
(		3. +CIPUPDATE:3 got edition
		c. c. o. b. i. c. bot cardon
		4. +CIPUPDATE:4 start update
Received data	+IPD	4. +CIPUPDATE:4 start update (CIPMUX=0): + IPD, <len>:</len>

Figure VI.3-3. ESP8266 AT command set

Take this platform into account, we built our library for ESP8266 as the following table.

Function	Description	Input	Output
Wi-FiSetup	Setup GPIO for ESP8266, Setup ESP8266	None	None
Wi- FiCheckServerConn	Check whether the connection with server is established	None	(bool): true if connection has been established, false if not
Wi-FiConnServer	Connect to server	None	None
Wi-FiDisconnServer	Disconnect from server	None	None
Wi-FiSendData	Send data to the server	(char*)usr: Username	None
		(char*)pass: Password	

#### Designing

Wi-FiRecData	Wait for receiving data from server	None	(bool): true if the result is correct, false if not
--------------	-------------------------------------	------	---

#### VI.3.2.4. Led

Because the EK-TM4C1294 Kit has four LEDs so that we use these available LEDs for the prototype. There are some functions for controlling LED.

Function	Description	Input	Output
actSetup	Setup GPIO for LEDs	None	None
actServe	Control LED following the result received from the server	(bool)result: If true, turn on LED for 1s, else do not turn on LED	None
actIdle	Toggle LED in idle time for notifying the system is not trapped	None	None

#### VI.3.3. Interface module

Interface module includes LCD 16x2 and Keypad 4x4 that the user inputs character from the Keypad, and LCD will display it into the screen. At the beginning, we represent meaning of buttons on the Keypad.



[0]-[9], [A]-[D] : Character buttons

[\*] : Backspace [#] : Confirm

Figure VI.3-4. Keypad 4x4

Because an account contains of Username and Password, so user must input data two times. To be appropriate with this, we make two relevant pages, one for inputting username, the rest for inputting password. In the username page, character is raw, however, in the password page, character is encrypted as \*\*\*. Nonetheless, to bring the Interface to be familiar, we added two more pages, clearly, idle page and result page. In the idle page, LCD just displays the string "Welcome", whilst, result page notifies the verification result. Furthermore, the result page only exists in a short interval (e.g., 1 second for a right result and 5 second for a false result), then the screen will return to idle page.

To summarize all of the Interface, we expose the algorithm to implement it by the following diagram.

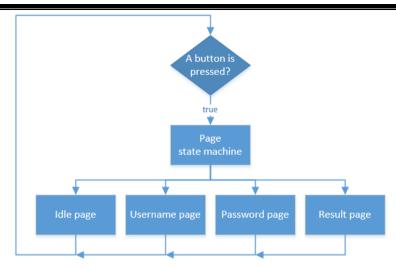


Figure VI.3-5. Interface implementation

#### VI.3.4. Wi-Fi module

To control ESP8266, programmer must obey the AT command set. Thank to this command set, we can ignore Wi-Fi handshake protocols and use UART protocol as the alternative. However, a barrier rising up is that the MCU must automatically analyze the received string from ESP8266 to be aware of the current state. For instance, when MCU sends a command to ESP8266, ESP8266 will implement its work and the return a result string, to know this result, MCU must find a key character in the received string. To overcome this obstacle, we introduce an algorithm (see Figure VI.3-6. Automatic analysis algorit) to analyze the returned string from the ESP8266.

Besides, the main function of ESP8266 is transferring data through Wi-Fi, so we continue introducing an algorithm (see Figure VI.3-7. Send data to server) to transfer data from ESP8266. To send data, MCU must check the connection with server, if the connection does not exist, it will tell ESP9266 connect to the server. After the handshake is established, MCU encodes data and sends it to the server.

Finally, we want to announce the Data package algorithm, which is used to encode/decode the data after sending/receiving. As mentioned in the section **VI.1.2**, a data frame includes four fields (e.g., address, function, length of data, data), so our Data package block has one terminal is fields, and the remaining terminal is the frame. In this context, we use a state machine to build this block (see Figure VI.3-8).

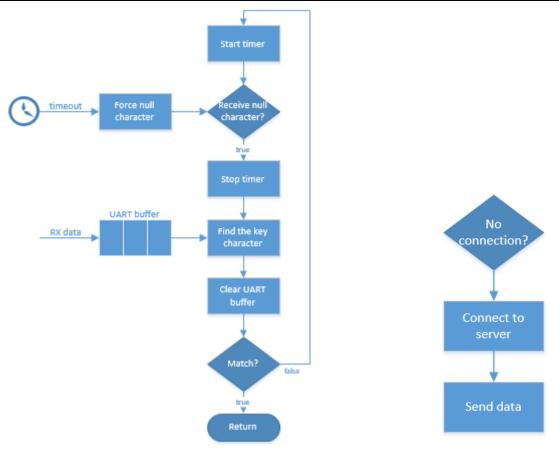


Figure VI.3-6. Automatic analysis algorithm

Figure VI.3-7. Send data to server

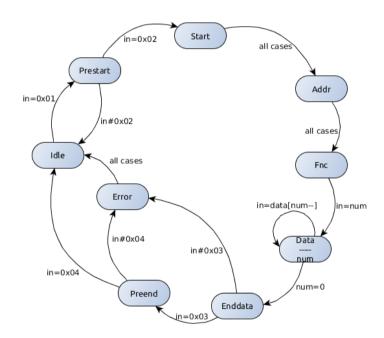


Figure VI.3-8. State machine of data frame decoding

#### VI.3.5. Actuator module

Actuator is the final module of firmware, so it uses result from previous modules to deicide its behavior. If the result is true, the notification LED is turned on for 1 second, else, this LED is not turned on. Moreover, we also provide an alive LED that continuously toggle so that people can know the system is still alive by observing this LED. Furthermore, a Wi-Fi LED is included that it will light when the data transaction is being taken place. If this LED is turned on too long, the Wi-Fi connection maybe corrupted, so user can be aware of this situation and try to fix the Wi-Fi connection.

#### VI.3.6. Unite the whole of firmware modules

After completing all of modules, we start combining them. In order to obtain a successful combination, we specify each independent input and output.

Module	Input	Output
Interface	String to be displayed	Pressed button
Wi-Fi	Encoded data frame to be sent	Received encoded data frame
Actuator	Verification result	None

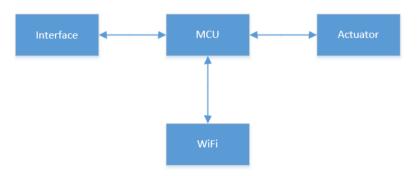


Figure VI.3-9. United firmware

### VI.4. Software Design

We used C programming language and a variety of supporting libraries to create Graphic User Interface which administrator can see the operating progress on a Linux distro' terminal.

To avoid failures and speed up programming process, we design software structurally by programming one side in parallel with the other and design algorithms in form of a couple.

## Diagram of main function algorithm Raspberry **PC-admin** Call Create socket platform\_thread' Wait Connect to server 'platform thread" return Define admin's adress Call "adminService" return

#### VI.4.1. Main function Algorithm

Figure VI.4-1. Main Function Algorithm

## VI.4.2. Platform Algorithm

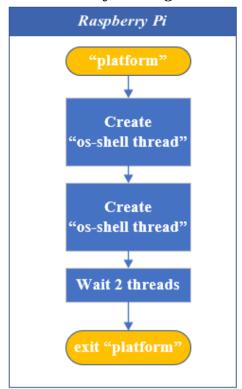


Figure VI.4-2. Platform algorithm

## VI.4.3. Os-shell Algorithm

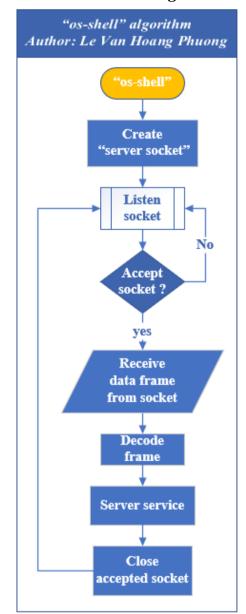


Figure VI.4-3. os-shell algorithm

## VI.4.4. Server Service Algorithm

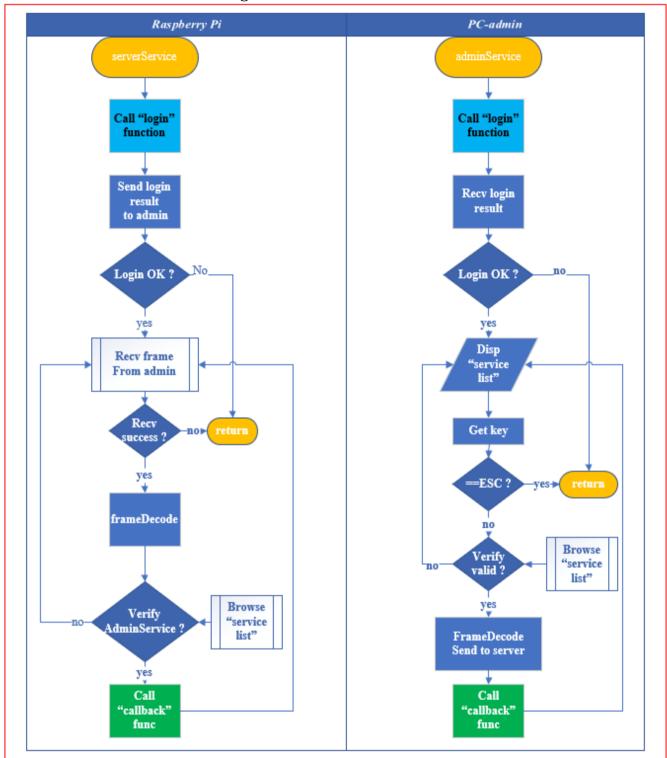


Figure VI.4-4. serverService & adminService algorithm

## VI.4.5. Backup Algorithm

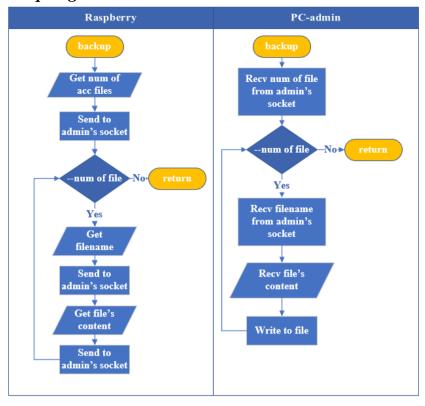


Figure VI.4-5. Backup algorithm

## VI.4.6. Account Management Algorithm

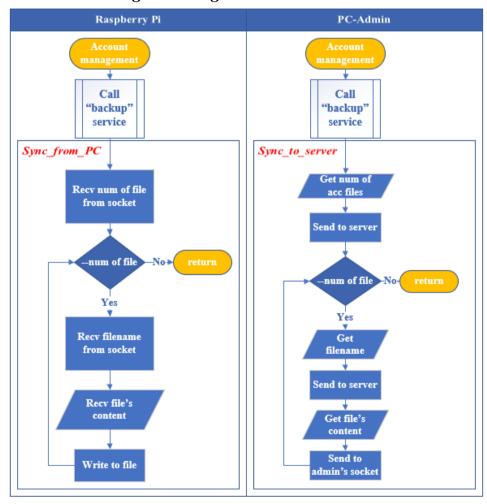


Figure VI.4-6. Account management algorithm

## VI.4.7. Configuration Algorithm

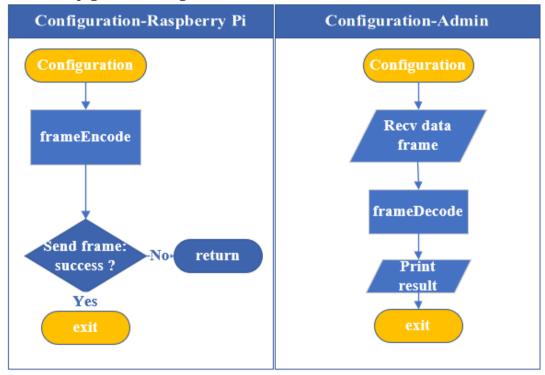


Figure VI.4-7. Configuration algorithm

## VI.4.8. History Viewer Algorithm

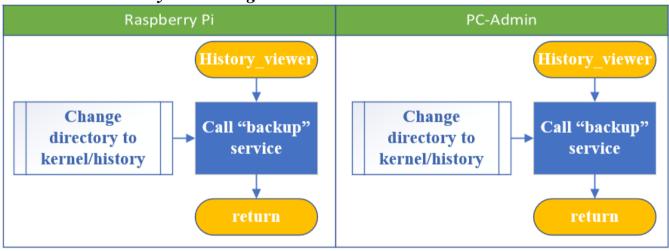


Figure VI.4-8. History\_viewer algorithm

## VII. Operating Condition

## VII.1. Ideal Condition

- [1] Strong Wi-Fi signal.
- [2] People use keypad to do the procedure actively.
- [3] No power interrupts at user's site.
- [4] No power interrupts at server's site.

## VII.2. Real Condition

- [1] Enough strong Wi-Fi signal level, Wi-Fi can be crashed.
- [2] Power can be interrupted at user's site.
- [3] No power interrupts at server's site.

# VIII. Result of Testing

# VIII.1. Networking

Tool	Arduino UART terminal,
	Linux terminal
Condition	Strong Wi-Fi,
	Local network
Target	ESP8266 connects to the server (handle) and sends an arbitrary data in one
	direction
Process	Build a simple server by Linux terminal.
	Use Arduino terminal, type AT command to connect ESP8266 to the server.
	Use Arduino terminal, type AT command to send an arbitrary data to the server.
Result	ESP8266 can connect to the server.
	The data is received correctly by the server (see Figure VIII.1-1).

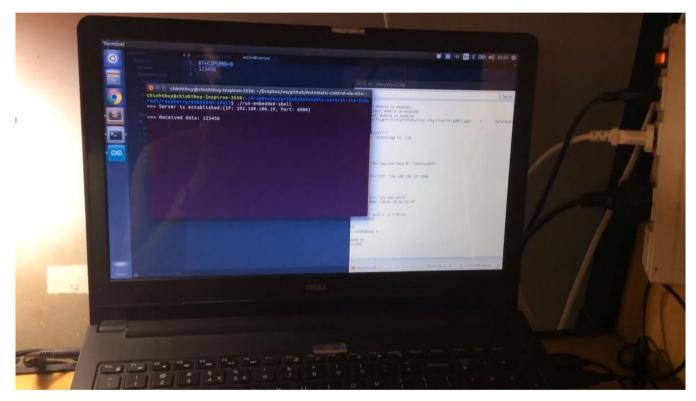


Figure VIII.1-1. [TCP connection exam] The sent string "123456"

is received correctly by the server

### VIII.2. OS Shell

## VIII.2.1. Os-shell & Platform

Tool	2 Linux terminals, one for PC-admin, the other for Raspberry-server	
Network	LAN	
Target	PC in role of admin send its username and password to server, the server verifies	
	that information and responses login's result to admin	
	[1] Run program	
Process	[2] See server's terminal and check if os-shell & embedded-shell are set up	
	(platform) and whose 2 sockets are also established.	
	Os-shell and embedded-shell are set up.	
Result	2 sockets are set up on the same IP and 2 ports: 8000 & 9000.	

```
hoangphuong@hpdell:/media/hoangphuong/HP HONOR/Google Drive BKU/Honor Program/Term 171/Embedded Stylength of the Stylength of
```

Figure VIII.2-1. Platform and 2 sockets

#### VIII.2.2. Login

Tool	2 Linux terminals, one for PC-admin, the other for Raspberry-server	
Network	LAN	
Target	PC in role of admin send its username and password to server, the server verifies	
	that information and responses login's result to admin	
Process	[3] Make full use of built platform (os-shell).	
	[4] Create some samples of account files on server's kernel.	
	[5] Use admin's terminal, connect to server, input login information, repeat this	
	task for other cases of wrong information.	
	[6] Display information of processing on server's terminal.	
	[7] See response on admin's terminal.	
Result	Admin gain connection successfully	
	Admin receive right login's results.	

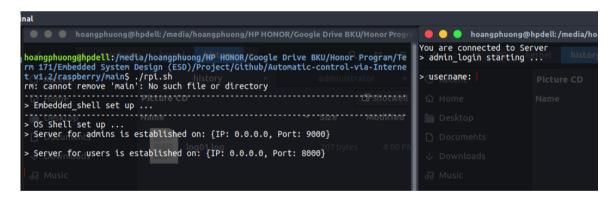


Figure VIII.2-2. Connection succeeded

Figure VIII.2-3. Right information {123-123}. The first login failed for wrong information.

#### VIII.2.3. Backup

Tool	2 Linux terminals on the same PC, one for PC-admin, the other for Raspberry-	
	server	
Network	LAN	
Target	Embedded device's accounts will be copied to PC-admin	
Process	[1] Make full use of built platform (os-shell).	
	[2] Create some samples of account files on server's kernel.	
	[3] Run backup service on PC-admin and on Raspberry-server.	
	[4] Display information of processing on both terminals.	
	[5] Check if the copied database on PC exists.	
Result	Admin gain connection successfully	
	Admin receive the database completely.	

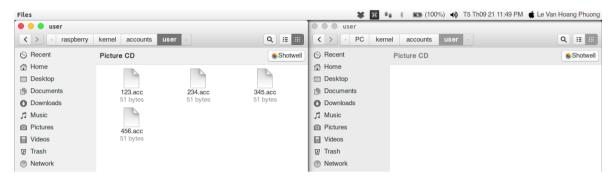


Figure VIII.2-4. Initial state

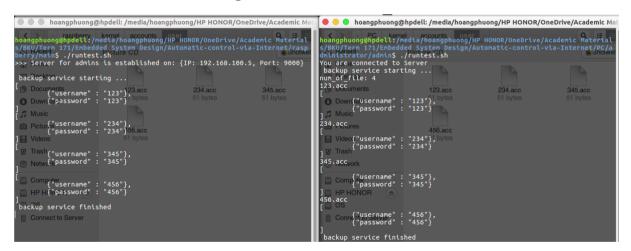


Figure VIII.2-5. Backup process

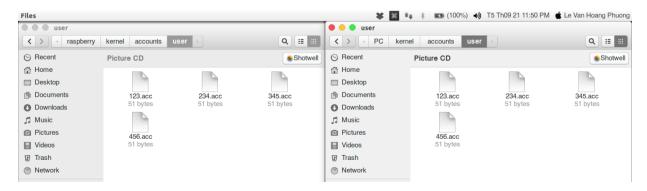


Figure VIII.2-6. After backup succeeded

#### VIII.2.4. Account Management

Tool	2 Linux terminals on the same PC, one for PC-admin, the other for Raspberry-		
	server.		
Network	LAN.		
Target	Admin can modify the database on server.		
D	[1] Make full use of built platform (os-shell).		
	[2] Create some samples of account files on server's kernel.		
	[3] Run account management service on PC-admin and on Raspberry-server.		
Process	[4] Display information of processing on both terminals.		
	[5] Admin modifies database on PC's kernel.		
	[6] Check if the database on server is up to date.		
Result	Admin gain connection successfully.		
	Admin receive the database completely.		
	Server's database is updated.		

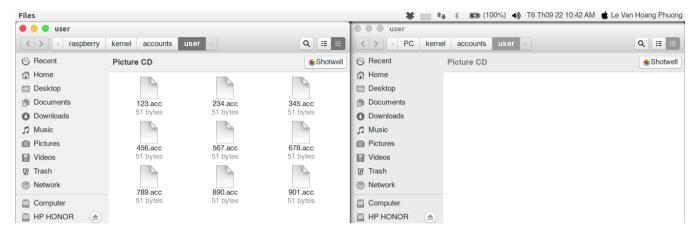


Figure VIII.2-7. Initial state of database of raspberry and PC



Figure VIII.2-8. Run service- phase 1: copied database of server to PC (backup)

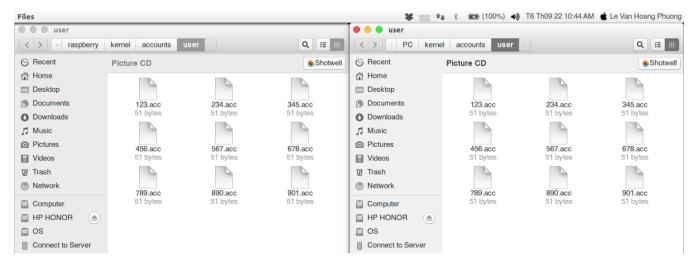


Figure VIII.2-9. Phase 1: copying database to PC done

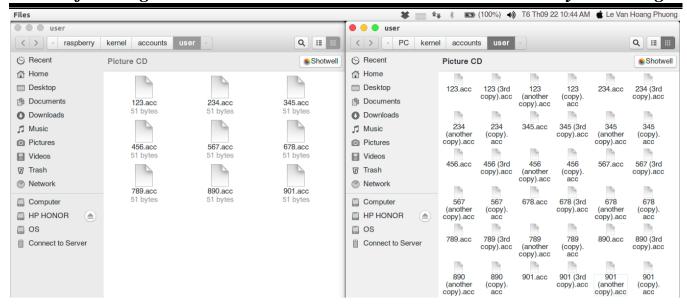


Figure VIII.2-10. Phase 2: modifying database on PC

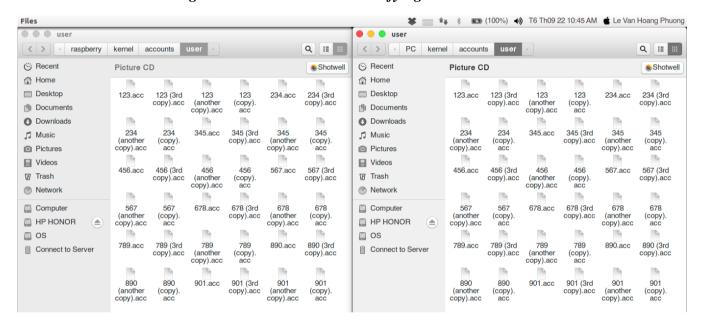


Figure VIII.2-11. Phase 2: syncing to server

#### VIII.2.5. Configuration

Tool	2 Linux terminals on the same PC, one for PC-admin, the other for Raspberry-	
	server.	
Network	LAN.	
Target	Admin can turn off server remotely.	
	[1] Make full use of built platform (os-shell).	
	[2] Run configuration service on PC-admin. Simulating the server is running any	
Process	tasks.	
	[3] Display information of processing on both terminals.	
	[4] Check server's terminal if the program is exited.	
Result	Admin gain connection successfully.	
	Server is stopped by admin.	

```
hoangphuong@hpdell:/media/hoangphuong/HP HONOR/Google Drive BKU/Hon

> OS Shell set up ...

> Embedded_shell set up ...

> Server for admins is established on: {IP: 0.0.0.0, Port: 9000}

> Server for users is established on: {IP: 0.0.0.0, Port: 8000}

> admin_login starting ...

username: 123
password: 123
pa
```

Figure VIII.2-12. Server is executed tasks, admin logged in

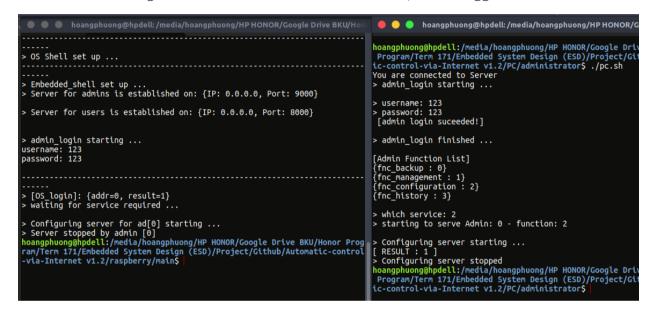


Figure VIII.2-13. Admin called configuration service & result

#### VIII.2.6. History Viewer

Tool	2 Linux terminals on the same PC, one for PC-admin, the other for Raspberry-	
	server.	
Network	LAN.	
Target	Admin can see the history of login tasks of embedded devices.	
	[1] Make full use of built platform (os-shell).	
	[2] Create 2 samples of log file on server's kernel.	
Process	[3] Admin run history viewer service.	
	[4] Check if those log files are existed in kernel and match server's ones in term	
	of content.	
Result	Admin gain connection successfully.	
	Receive log files successfully and their contents are reserved.	

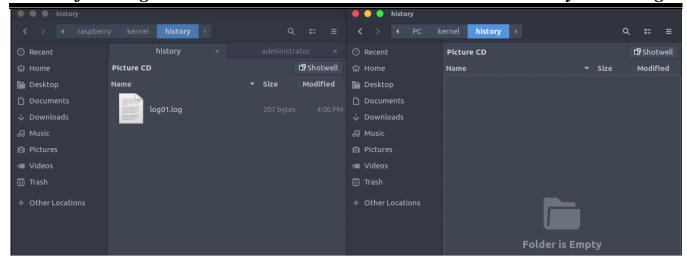


Figure VIII.2-14. Initial state of the server and admin's kernel

Figure VIII.2-15. Querying history from server

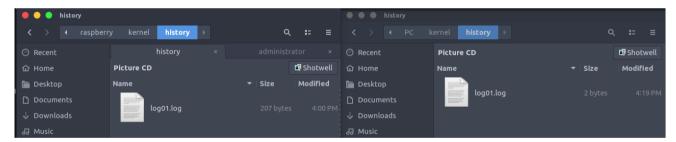


Figure VIII.2-16. Querying history done

Figure VIII.2-17. Both files' content match

### VIII.3. Embedded Shell

Tool	Arduino UART terminal,	
	Linux terminal	
Condition	Strong Wi-Fi,	
	Local network	
Target	ESP8266 connects to the server (auto), send login data, receive verification result	
Process	Run the Embedded shell by Linux terminal.	
	Run firmware on the prototype.	
	Use Arduino terminal to replace LCD – Keypad.	
	Type login to the Arduino terminal.	
Result	Connection is established.	
	Data transaction is done correctly (see Figure VIII.3-1).	

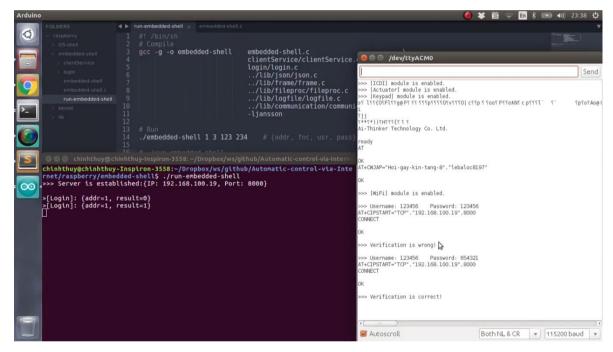
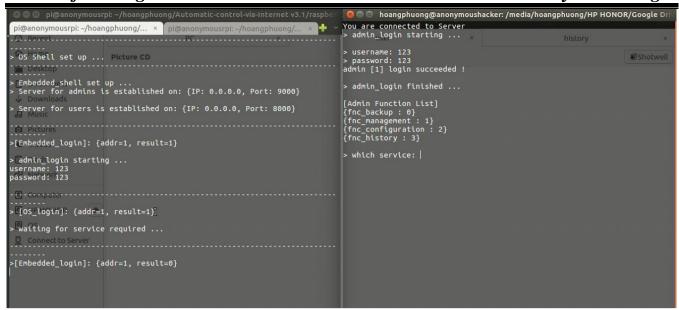


Figure VIII.3-1. [Data transaction exam] The right account is "123456" – "654321". At the first time, the login "123456" – "123456" is wrong. Afterward, the true login is recognized

## VIII.4. The Whole of System

Tool	2 Linux terminals, one for PC-admin, the other for Raspberry-server, "ssh" tool for remote control server and display on a terminal.	
Network	Internet	
Target	PC and Embedded device (Tiva) connect to server simultaneously, server should serve both at the same time	
Process	<ul> <li>[1] Run server's program</li> <li>[2] See server's terminal and check if os-shell &amp; embedded-shell are set up (platform) and whose 2 sockets are also established.</li> <li>[3] See operating processes on server's terminal</li> </ul>	
Result	Os-shell and embedded-shell are set up. 2 sockets are set up on the same IP and 2 ports: 8000 & 9000. 2 kinds of device connected at the same time and operating properly.	



## IX. Conclusion

#### IX.1. Achievement

In this project, we have built successfully a system that supports people in building-access management. With a prototype of self-implemented single-layer PCB and a Raspberry board, we respond almost planning requirements, e.g., input login data, online verification, notification, history viewer, account management. Besides, we also survey a market analysis to study how a security system that people need. Furthermore, at the beginning, we design a clear plan, and, during conducting the project, we monitor ourselves tightly by using Trello software. As the result, our working has completed on time.

Nevertheless, there are a few shortcomings that we are stuck. First, we carry out the system in a LAN network, whilst, our target is Internet scale. Second, the actuator in our prototype is not as considered. In our desire, it would be a mechanical motor structure, which can control the door open/close. However, because of time lack, and cost, we cannot bring this hope to this current prototype. Besides, when the admin connects to the server, it requires that the admin must know how to use Linux terminal, which is fairly inconvenient. Finally, the whole of the server data is not encrypted so that hacker can access and steal data.

#### IX.2. Future Work

Basing on drawbacks of this current prototype, we plan a coming work that fixes those weaknesses. In the future, we will use a VPN client to expand the scope from LAN to WAN. Subsequently, a new sub-team will be created to develop the mechanicals field to realize the actuator. Additionally, a GUI will be also formed to help the admin easily in interacting with the server. Especially, we are in the progress of designing an encryption method with intervalchanging key to protect our data. Last but not least, thank to general definitions in specifications, we can develop a number of versions in order to adapt to a large range of using purpose types.

## X. Reference

- Embedded system design
  - [1] Lecture: Embedded System Design, Dr. Truong Quang Vinh, HCMC University of Technology.
  - [2] Embedded Systems Architecture, A Comprehensive Guide for Engineers and Programmers, By Tammy Noergaard.
- Programming language
  - [1] Kernighan, Brian W.; Ritchie, Dennis M. (February 1978). The C Programming Language (1st ed.). Englewood Cliffs, NJ: Prentice Hall. ISBN 0-13-110163-3.
  - [2] Beginning Linux® Programming, 4th Edition. Published by. Wiley Publishing, Inc. 10475 Crosspoint Boulevard. Indianapolis, IN 46256.
- **❖** IDE and editor
  - [1] Code Composer Studio: <a href="http://processors.wiki.ti.com/index.php/Download\_CCS">http://processors.wiki.ti.com/index.php/Download\_CCS</a>
  - [2] Tivaware: <a href="http://www.ti.com/tool/SW-TM4C">http://www.ti.com/tool/SW-TM4C</a>
  - [3] Sublime Text: https://www.sublimetext.com
  - [4] GCC integrated on Linux's distros.

# XI. Appendix A

## XI.1. Hardware Design

The Software used to design PCB circuit is Alitum 16.0. This software has a user-friendly interface for designing, managing and editing, easy compilation, file management, version management for design documents. With a widely shared library source, it is easy to choose the components for the printed circuit.

### XI.2. Firmware & Software Design

To develop Firmware, we use software <u>Code Composer Studio</u> of Texas Instrument to program the microcontroller. Code Composer Studio is a software built based on Eclipse, a familiar IDE, so it inherits a powerful debugger from Eclipse, which helps us extremely to overcome uncomfortable bugs. This software can be download in the official website of Texas Instrument. Besides, to program the TM4C-129 family microcontroller easily, we use the supporting library <u>TivaWare. Reference</u> <u>Reference</u>

Whilst, we just use a trial version of <u>Sublime Text</u> editor for developing Software. This editor is combined with available Linux terminal to run our code. <u>Reference</u>

# XII. Appendix B

## XII.1. Code Organization

We structured our source code in form of hierarchy of system's partitions. It is a bit of complicated from *root* to *leaf folder*.

Root folder	Automatic-control-via-Internet v1.2
(home folder)	
3 main function's	PC
folders	raspberry
	tiva



Figure XII.1-1. Code organization

### XII.2. Repository

For further details, see:



#### Below are 3 main functions in our project:

#### [1] Raspberry-main.c

```
/*********
* Date created:
                   6-8-2017
* Date finished:
* Editor: Sublime Text 3
* Compiler: gcc
* Author: Le Van Hoang Phuong
* Description: raspberry main program
************
#include <stdio.h>
#include <string.h>
#include <stdlib.h>
                      //boolean
#include <stdbool.h>
#include <dirent.h>
                       //folder proc
#include <pthread.h>
                       //multi-threads
/*common private lib*/
#include "../lib/fileproc/fileproc.h"
#include "../lib/communication/communication.h"
#include "../lib/frame/frame.h"
#include "../lib/json/json.h"
#include "../lib/platform/thread.h"
#include "../lib/bufferproc/bufferproc.h"
/*include platform for shells*/
#include "platform.h"
/*include shell*/
#include "../os-shell/os shell.h"
#include "../embedded-shell/embedded shell.h"
int main(int argc, char const *argv[])
    /*platform thread: control os shell thread &
embedded shell thread*/
             thread exit; //message when thread cancelled
    void *
    pthread t platform thread;
                                //declare thread name
    /*run platform in parallel with main*/
    /*this platform will run os shell & embedded shell*/
```

```
if(!createThread(&platform_thread, platform, thread_exit))
exit(1);
    /*force main to hang to wait for platform exited first*/
    pthread_join(platform_thread, &thread_exit);

    /*print the result as platform exited*/
    fprintf(stderr, "%s\n", (char *)thread_exit);

    /*remove main.o*/
    unlink("main");
    /*return*/
    return 1;
}
```

#### [2] **PC-** main.c

```
/*********
* Date created:
                  6-8-2017
* Date finished:
* Editor: Sublime Text 3
* Compiler: gcc
* Author: Le Van Hoang Phuong
* Description: PC main program
***********
#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#include <stdbool.h>
#include <dirent.h>
#include <pthread.h>
/*user library*/
#include "../../lib/fileproc/fileproc.h"
#include "../../lib/communication/communication.h"
#include "./adminService/backup/backup.h"
#include "./adminService/adminService.h"
#include "adminService/management/management.h"
#include "./serveAdmin/serveAdmin.h"
/*main function*/
int main(int argc, char const *argv[])
    int connfd;
    /*create socket for admin*/
    connfd = createClientSocket(argv[1], atoi(argv[2]));
    /*run admin Service control*/
    /*define admin addr here: ad 0*/
    adminService(&connfd, ad 0);
    /*remove main.o*/
    unlink("main");
    /*return*/
    return 0;
```

#### [3] Tiva- main.c

```
: Thuy Nguyen-Chinh.
   Author
            : Sep 04, 2017
   Date
   Description: This is the main file of the project.
              : 1.0.1.
   Version
/*********************
   Include
************************
/* Project */
#include "modules/pin def.h"
#include "system/system.h"
#include "modules/ui/ui.h"
/***********************
****************************
void main()
  /* Setup */
  systemSetup();
   /* Serve */
  while (1)
      /* Idle: Toggle LED */
      actIdle();
      clkDelayMs(10);
      /* Sweep keypad */
      kpSweep();
      flgBtnInt = kpCheck();
      /* User interface */
      uiServing();
   }
```