Variational Inference with Coin Toss example

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1 Introduction

Variational inference (VI) is a machine learning method for approximation of the difficult to compute probability densities that appear in Bayesian methods. In general, the goal is to find a surrogate distribution over hidden variables and parameters of the original Bayesian model that is close to the original distribution but where the evaluation is computationally efficient. The closeness is defined in terms of a divergence measure between the approximate distribution and the original distribution.

2 Motivation

Consider classical Bayesian setup

$$p(Z|X) = \frac{p(X,Z)}{p(X)} \tag{1}$$

where $X = x_{1:n}$ denotes the observed data while $Z = z_{1:k}$ denotes all the hidden variables and parameters of the model. Numerator of the fraction is called joint distribution

$$p(X,Z) = p(X|Z) p(Z)$$
(2)

and the denominator (often called evidence) is a marginal distribution

$$p(X) = \int_{Z} p(X, Z) dZ \tag{3}$$

Computing the posterior probability is often a very hard problem (for example, due to the exponentially large number of hidden states or because required integrations do not have a closed-form analytical solution). This is why we resort to techniques such as approximation, where the objective is to find a joint distribution q(Z) that replaces original posterior p(Z|X) in a way that enables us to find computationally tractable solutions.

2.1 Variational inference setup

Variational inference posits a set of densities Q over the latent variables Z. We typically try to minimize the Kullback-Leibler (KL) divergence

$$KL(q(Z) \mid\mid p(Z|X)) = E_q \left[log \frac{q(Z)}{p(Z|X)} \right]$$
(4)

of the approximate and the original, true joint distribution

$$q^*(Z) = \underset{q(Z) \in \mathcal{Q}}{\operatorname{arg \, min}} \ KL(q(Z) \mid\mid p(Z|X)) \tag{5}$$

KL divergence tells us how much information we loose by choosing the approximate distribution instead of true posterior distribution. We can expand the right hand side of (4)

$$KL(q(Z) \mid\mid p(Z|X)) = E_q[q(Z)] - E_q[\log p(Z|X)]$$
 (6)

Using (1) we get

$$KL(q(Z) \mid\mid p(Z|X)) = p(X) - \underbrace{\left(E_q[\log p(X,Z)] - E_q[q(Z)]\right)}_{\text{ELBO(q)}}$$
(7)

We want to minimize the KL divergence by varying distribution q(Z). p(X) does not depend on q and is always positive (or equal to zero) so we need to maximize the ELBO(q). The only assumption we are making is that q(Z) factorizes in the following way

$$q(Z) = \prod_{k=1}^{K} q_k(z_k) \tag{8}$$

which means that we are breaking possible dependencies between hidden variables in our approximation process.

$$ELBO(q) = \int q(Z) \log p(X, Z) dZ - \int q(Z) \log q(Z) dZ$$
 (9)

3 Variational inference application

$$p(Z|\pi) = \prod_{n=1}^{N} \prod_{k=1}^{K} \pi_k^{z_{nk}}$$
 (10)

$$p(\pi) = Dir(\pi|\alpha_0) = C(\alpha_0) \prod_{k=1}^{K} \pi_k^{\alpha_k - 1}$$
(11)

$$p(X|Z,\Theta) = \prod_{n=1}^{N} \prod_{k=1}^{K} \prod_{j=1}^{J} [\Theta_k^{x_n^j} (1 - \Theta_k)^{1 - x_n^j}]^{z_{nk}}$$
(12)

$$p(\Theta|a,b) = \prod_{k=1}^{K} \frac{\Theta^{a-1} (1-\Theta)^{b-1}}{Beta(a,b)}$$
 (13)

Joint distribution is given by

$$p(X, Z, \Theta, \pi, a, b) = p(X|Z, \Theta)p(Z|\pi)p(\pi)p(\Theta|a, b)$$
(14)

with factors on the right side of the equation as defined above. Only variables $X = x_1, \ldots, x_N$ were observed. In the next step we consider a variational distribution with the following factorization

$$q(Z, \pi, \Theta) = q(Z)q(\pi, \Theta). \tag{15}$$

We are separating the latent variables and parameters and this is actually the only assumption we are making. In order to proceed with the factorization, we use the general result given by Bishop[2006].

$$\ln q^*(Z) = E_{\pi,\Theta}[\ln p(X, Z, \Theta, \pi, a, b)] + const$$
 (16)

For the factor of \mathbf{Z} we are only interested in those components of the decomposition 14 that depend on \mathbf{Z} . All other terms are absorbed into the additive normalization constant, giving:

$$ln q^*(Z) = E_{\pi}[ln p(Z|\pi)] + E_{\Theta}[ln p(X|Z,\Theta)] + const$$
 (17)

where

$$E_{\pi}[\ln p(Z|\pi)] = \sum_{n=1}^{N} \sum_{k=1}^{K} z_{nk} E_{\pi}[\ln \pi_{k}]$$
 (18)

and

$$E_{\Theta}[\ln p(X|Z,\Theta)] = \sum_{n=1}^{N} \sum_{k=1}^{K} z_{nk} E_{\Theta}[\sum_{j=1}^{J} \ln \Theta_k^{x_n^j} (1 - \Theta_k)^{1 - x_n^j}]$$
 (19)

Hence

$$\ln q^*(Z) = \sum_{n=1}^N \sum_{k=1}^K z_{nk} \left(E_{\pi}[\ln \pi_k] + E_{\Theta}[\ln \Theta_k^{n_H} (1 - \Theta_k)^{n_T}] \right) + const \qquad (20)$$

where n_H is a number of heads and n_T number of tails in the n-th experiment. Proceeding similarly for π and Θ we get the following expression

$$\ln q^*(\pi,\Theta) = E_Z[\ln(\pi) + \ln p(Z|\pi)] + E_Z[\ln p(X|Z,\Theta) + \ln p(\Theta)] + const (21)$$

Since there are no expressions that depend on both parameters at the same time we may proceed with the factorization of the parameters independently

$$q(\pi, \Theta) = q(\pi) \ q(\Theta) \tag{22}$$

where

$$\ln q^*(\pi) = \ln p(\pi) + E_Z[\ln p(Z|\pi)] + const$$
 (23)

$$\ln q^*(\pi) = \sum_{k=1}^K (\alpha_k - 1) \ln \pi_k + \sum_{k=1}^K r_k \ln \pi_k + const$$
 (24)

where $r_k = \sum_{n=1}^{N} E[z_{nk}]$ We have already derived the expectations over Z in EM document. Taking the exponential of equation 24 we get that the

$$q(\pi) = Dir(\pi|\alpha) \tag{25}$$

where α is vector with K components $\alpha_k = \alpha_k + r_k$

$$ln q^*(\Theta) = ln p(\Theta) + E_Z[ln p(X|Z,\Theta)] + const$$
 (26)

$$\ln q^*(\Theta) = \sum_{k=1}^K (\ln \left[\Theta_k^{a_k - 1} (1 - \Theta_k)^{b_k - 1}\right] + \sum_{n=1}^N r_{nk} \sum_{j=1}^J \ln \left[\Theta_k^{x_n^j} (1 - \Theta_k)^{1 - x_n^j}\right]_+ const$$
(27)

$$\ln q^*(\Theta) = \sum_{k=1}^K \ln \left[\Theta_k^{a_k - 1 + n_H r_k} (1 - \Theta_k)^{b_k - 1 + n_T r_k} \right] + const \tag{28}$$

where n_H equals number of the outcomes of $x_n^j = 1$ (number of heads), and n_T number of the outcomes of $x_n^j = 0$ (number tails). We see that the factor for Θ is Beta distributed variable:

$$q^*(\Theta) = \prod_{k=1}^K Beta(\Theta|A, B)$$
 (29)

where A is a vector with parameter components $a = a_k + n_H r_k$ and B with components $b = b_k + n_T r_k$.

4 Variational lower bound

Variational lower bound L is given by

$$L = E[\ln p(X, Z, \Theta, \pi, a, b)] - E[\ln q(Z, \Theta, \pi, a, b)]$$
(30)

Using results from 14, 15 and 22 this simplifies to

$$L = E[\ln p(X|Z,\Theta)] + E[\ln p(Z|\pi)] + E[\ln p(\pi)] + E[\ln p(\Theta|a,b)] - E[\ln q(Z)] - E[\ln q(\pi)] - E[\ln q(\Theta)]$$
(31)

We write down each of the terms separately:

$$E[\ln p(\pi)] = \ln C(\alpha_0) + \sum_{k=1}^{K} (\alpha_k - 1)(\psi(\alpha_k) - \psi(\sum_{k=1}^{K} \alpha_k))$$
 (32)

$$E[lnp(\Theta_k|a,b)] = \sum_{k=1}^{K} -lnBeta(a_k,b_k) + (a_k-1)\psi(a_k) - (b_k-1)\psi(b_k) + (a_k+b_k-2)\psi(a_k+b_k)$$
(33)

$$E[\ln p(Z|\pi) = \sum_{n=1}^{N} \sum_{k=1}^{K} r_{nk} (\psi(\alpha_k) - \psi(\sum_{k=1}^{K} \alpha_k))$$
 (34)

$$E[ln p(X|Z,\Theta)] = \sum_{n=1}^{N} \sum_{k=1}^{K} r_{nk} [n_H(\psi(a_k) - \psi(a_k + b_k)) + n_T(\psi(b_k) - \psi(a_k + b_k))]$$
(35)

5 Algorithm

This section should contain algorithmic description of the problem

```
Data: Data X_{1:n}, number of components K
Result: Variational densities q(\Theta_k; a_k, b_k) and q(z_{nk}, \alpha_k) initialization;
while the ELBO has not converged do
read current;
if understand then
go to next section;
current section becomes this one;
else
go back to the beginning of current section;
end
end
```

Algorithm 1: How to write algorithms

6 Results

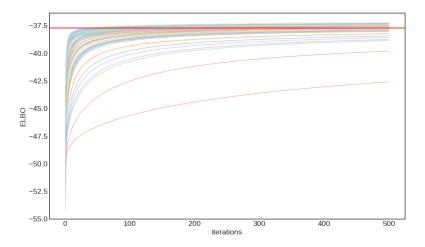


Figure 1: Different initialization converge to different local optima of the ELBO

Initialization. The ELBO is generally a non-convex objective function. Convergence to the local optimum is guaranteed, however, it can be sensitive with regard to the initialization. Figure 6 shows the ELBO convergence for 100 random initializations of the model parameters. Red line denotes the average of the convergence asymptote for all runs. Convergence. We define the treshold for the change of ELBO value between subsequent algorithm iterations. Once this difference has fallen under the treshold the procedure stops. Calculation. During the calculation of the coefficient (which may grow arbitrarily large) we have encountered the problems with the calculation of the normalization coefficient for Dirichlet distribution. Replacing the hand-crafted version with the one from scipy package resolved the problem.

7 Conclusion

We described variational inference algorithm with mean-field approximation. We have derived parameter update equations for a simple mixture model. Evidence lower bound optimization procedure was used as a criteria for algorithm convergence. We have choosen probability distribution from exponential family