

Experimental methods

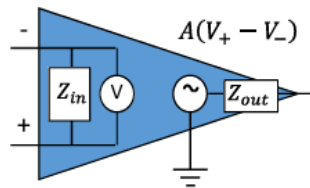
1. Uncertainty principle in signal processing (purely mathematical) $\Delta f \Delta t = 2\pi$, Δt is time-window/total sample time.
2. $E^2 = p^2 c^2 + m_0^2 c^4$ because $p = \gamma m_0 v$, $E = \gamma m_0 c^2$
3. Johnson-Nyquist noise: current/voltage fluctuation in resistor due to thermal fluctuations

$$V_{\text{RMS}} = \sqrt{4k_B T R \Delta f}$$

where R is resistance,
 Δf is measurement bandwidth.

4. Golden rule

- Gain G is infinite



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- Input impedance $Z_{in} = \frac{\partial V_{in}}{\partial I_{in}}$ is ∞
- Output impedance $Z_{out} = \frac{\partial V_{out}}{\partial I_{out}}$ is 0
- The input I_- is 0 (because Z_{in} is infinite)
- $V_- = V_+$ (only if not saturated, **negative feedback** established)
 (A question on positive feedback & saturated op-amp, results in oscillating output)

5. Non-ideal op-amp

- $V_{out} = G(V_+ - V_-)$
- Gain G not infinite, $10^4 \sim 10^6$
- Z_{in} not infinite, Z_{out} not 0
- Gain G is complex and function of frequency
- Finite slew rate $\frac{\partial V_{out}}{\partial t}$
- An input bias current independent of V_{in}
- An output bias voltage independent of $(V_+ - V_-)$

6. Sd of a set of numbers: $\sqrt{\frac{1}{N} \sum_i (x_i - \bar{x})^2}$

- Estimated Sd of a population, if \bar{x} is also estimated here $\sqrt{\frac{1}{N-1} \sum_i (x_i - \bar{x})^2}$ (Bessel's correction)

- Uncertainty/Sd in mean = $\frac{\sum \text{uncertainty of each measurement}}{\sqrt{N}}$

- Gaussian error propagation $\sigma_f^2 = \left(\frac{\partial f}{\partial x}\right)^2 \sigma_x^2 + \left(\frac{\partial f}{\partial y}\right)^2 \sigma_y^2$

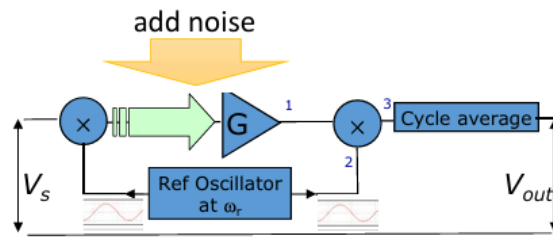
7. Noise

- White noise (Johnson-Nyquist, shot noise, thermal fluctuations)
- $1/f$ -noise/pink noise, worst at low frequency/DC
- $1/f^2$ -noise/Brownian noise, random walk

8. Eliminating noise

- Filter out $1/f$ noise, high pass filter (Switch on and off, if DC)
- $1/f$ noise, phase sensitive detection with high ω
- Differential experiment, measure change $\Delta f = f_1 - f_2$
- Shielding (Electromagnetism, heat)
- Eliminate source
 - Remote - away from electricity interference/vibration
 - High - above atmosphere
 - Antarctic - Dry/High/Cold
 - Space - All above and gravity free

9. Phase-sensitive detection - eliminate $1/f$ noise

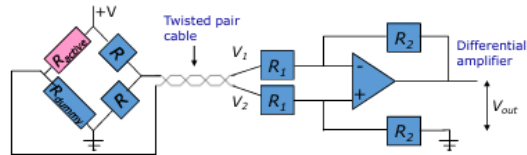


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- Modulator at frequency ω_r , left $\cos(\omega_r t + \phi)$, right $\cos(\omega_r t)$
- Signal V_s , noise $V_n = V_n(\omega)$
- At 1, $V_1 = V_s G \sin(\omega t + \phi)$
- At 3, $V_3 = V_s G \sin(\omega t + \phi) \sin(\omega t) = \frac{V_s G}{2} [\cos(\phi) - \cos(2\omega t + \phi)]$
- $\langle V_3 \rangle = \frac{V_s G}{2} \cos(\phi)$
- At green arrow and op-amp, noise of frequency ω_n produced
- $\langle V_n \rangle$ not zero if $\omega = \omega_n$
- Set ω high, so noise is small

10. Mechanical vibration - air cushion

Thermal noise - reduce radiation/convection/evaporation - a lid, shiny shielding

This circuit uses four different “tricks”

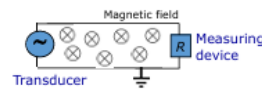


- Use of a bridge to compare the resistances.
- Use of two strain gauges, once active and the other just used to calibrate for the environment.
- Use of a twisted pair; E & B will induce \approx the same currents in each lead because they follow almost the same path through space.
- Use of a differential amplifier ignores all “common-mode” induced signals because:

$$V_{out} = R_2/R_1 (V_2 - V_1).$$

Eliminating electrical pickup

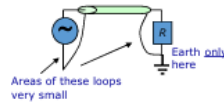
- Consider the effect of a changing magnetic field on a typical transducer or instrument set-up:



→ Unwanted induced $EMF = -\frac{d}{dt}(B \times \text{loop area})$
and hence induced noise across R.

(B typically has oscillating component at 50Hz stemming from power lines.)

- Mitigate by minimizing geometric area of loop



- Don't create ground loops aka earth loops:

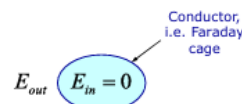
- Loop can have the size of the building
- Induced EMF in the unnecessary loop
- Finite resistance of earth connections
→ neither A nor B is at ground – so varying $V_B \Rightarrow$ noise.

• N.B: Earth connection of devices essential for electrical safety, good design can separate signal ground from case!

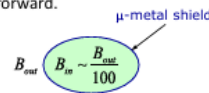


Shielding

- For Electric fields, use a Faraday cage.
- Re-arrangement of charges within conductor lead to no enclosed overall field.



- For Magnetic fields, the situation is less straightforward.
- Use shield made of high permeability metal, e.g. “ μ -metal”, a Ni/Fe alloy with $\mu_r > 10^4$.
- Provides a low reluctance path for the B field lines.



Circuits -

- Binomial $P(r, p, N) = \frac{N!}{r!(N-r)!} p^r (1-p)^{N-r}$, $\sum_{r=0}^N P(r) = 1$, $\langle r \rangle = Np$, $Var(r) = Np(1-p)$
- Poisson $\frac{\lambda^r}{r!} e^{-\lambda}$, mean=variance= λ
(shot noise, let $p \rightarrow 0$, $N \rightarrow \infty$, $\langle r \rangle = \lambda$)
- Gaussian $\frac{1}{\sigma\sqrt{2\pi}} e^{-(x-\mu)^2/2\sigma^2}$, mean μ , variance σ^2
1,2,3 sd - 68,95,99.7%
(Johnson noise, thermal fluctuations, $\sim k_B T$)
- Chi-square $\chi^2(x, n) = \begin{cases} \frac{1}{2^{n/2}\Gamma(n/2)} x^{n/2-1} e^{-x/2}, & \text{if } x > 0 \\ 0 & \text{otherwise} \end{cases}$,
degree of freedom n , mean n , variance $2n$.

12. Likelihood $\prod_i p(y_i|\mathbf{a})$ should be maximized

13. a is parameter(s)

14. Posterior $p(a|\text{data}) = p(\text{data}|a) \frac{p(a)}{p(\text{data})}$, $p(a)$ is prior. ($p(\text{data})$ is a normalizing constant)

15. Choice of prior

- uniform in log space, $p(a) = 1/a$
- uniform $p(a) = \text{constant}$, **most common** so $p(\text{param}|\text{data}) = p(\text{data}|\text{param})$
- Better, complicated assumption

16. Straight line fitting, constant prior

- $p(y_i|a) = \frac{1}{\sigma\sqrt{2\pi}} e^{-(y_i - f(x_i|a))^2 / 2\sigma_i^2}$
- $L(\mathbf{y}|a) = \prod_i^n p(y_i|a)$
- to maximize $\ln(L)$, minimize $\chi^2 = \sum_i \left(\frac{y_i - f(x_i|a)}{\sigma_i} \right)^2$
- $f(x_i|a) = mx_i + c$, $a = \mathbf{a} = m, c$
- $\frac{\partial \chi^2}{\partial c} = 0 = \frac{1}{N} \frac{\partial \chi^2}{\partial c} = \frac{1}{N} (-2) \sum_i y_i - (mx_i + c) \implies \bar{y} = m\bar{x} + c$
- $\frac{\partial \chi^2}{\partial m} = 0 = \frac{1}{N} \frac{\partial \chi^2}{\partial m} = \frac{1}{N} (-2) \sum_i x_i (y_i - mx_i - c) \implies \overline{xy} = m\overline{x^2} + c\bar{x}$
- $m = \frac{\overline{xy} - \bar{x}\bar{y}}{\overline{x^2} - \bar{x}^2} = \frac{\text{Cov}(x, y)}{\text{Var}(x)}$
- $c = \bar{y} - m\bar{x}$
- sd of y is $\frac{1}{N-2} \sum_i (y_i - (mx_i + c))^2$
- $\frac{\partial \bar{y}}{\partial y_i} = \frac{1}{N}$, $\frac{\partial \overline{xy}}{\partial y_i} = \frac{x_i}{N}$
- $\sigma_m = \sigma^2 \sum_i \left(\frac{\partial m}{\partial y_i} \right) = \frac{\sigma^2}{N(\overline{x^2} - \bar{x}^2)}$
- $\sigma_c = \sigma^2 \sum_i \left(\frac{\partial c}{\partial y_i} \right) = \frac{\sigma^2 \bar{x}}{N(\overline{x^2} - \bar{x}^2)}$
- Weighting by $1/\sigma_i^2$ instead of 1, $\bar{y} = \frac{\sum_i y_i / \sigma_i^2}{\sum_i 1 / \sigma_i^2}$, reduces to $\bar{y} = \frac{\sum_i y_i}{\sum_i 1}$ above
- Assuming:
 - Uniform prior
 - Only errors in y_i
 - y_i Gaussian distribution
- Remember: Gaussian, $\min \chi^2$, $y = mx + c$, $\frac{1}{N-2}$, $1/\sigma_i^2$ weighting

17. χ^2 test, for binned data (defined differently as above), $\chi^2 = \sum_i \frac{(O_i - E_i)^2}{E_i}$ = degree of freedom = No.data - No.parameter

18. Other tests

- Non-parametric statistics - look at your data
- Runs test: non-random pattern despite χ^2 fits well?
- Sign test: x and y have same distribution?
- Mann-Whitney test: 2 samples from same distribution?
- Kolmogorov-Smirnov test: 2 distributions different?

19.

Oscillations

1. $\ddot{x} + \gamma\dot{x} + \omega_0^2 x = \frac{F}{m}, \omega_0 = \sqrt{\frac{k}{m}}, \gamma = \frac{b}{m}, Q = \frac{\text{sqr}tmk}{b}$
2. $L\ddot{q} + R\dot{q} + \frac{1}{C}q = V(t), \omega_0 = \frac{1}{\sqrt{LC}}, \gamma = R/L, Q = \frac{1}{R}\sqrt{\frac{L}{C}}$
3. $Q = \frac{\omega_0}{\gamma}$
4. Response function
 - $x = \mathcal{R}(x_0 e^{i\omega t}), x_0 = Ae^{i\phi_x}, F = \mathcal{R}(F_0 e^{i\omega t}), F_0 = Be^{i\phi_F}$
 - $R(\omega) = \frac{x_0}{F_0} = \frac{1}{m[(\omega_0^2 - \omega^2) + i\gamma\omega]}$
 - $|R| = \frac{1}{m\sqrt{(\omega_0^2 - \omega^2)^2 + \gamma^2\omega^2}}$
 - $\arg(R) = \arctan\left[\frac{-\gamma\omega}{(\omega_0^2 - \omega^2)}\right]$
 - Resonance $\omega_a = \omega_0\sqrt{1 - \frac{\gamma^2}{2\omega_0^2}} = \omega_0\sqrt{1 - \frac{1}{2Q^2}}$
 - $v_0 = i\omega x, \left|\frac{v_0}{F_0}\right| = \frac{1}{m\sqrt{\frac{(\omega_0^2 - \omega^2)^2}{\omega^2} + \gamma^2}}$
 - $\arg\left(\frac{v_0}{F_0}\right) = \arctan\left[\frac{\omega_0^2 - \omega^2}{\gamma\omega}\right], \omega_v = \omega$
 - $a_0 = \frac{-F_0}{m[(\omega_0^2 - \omega^2)/\omega^2 + \frac{i\gamma}{\omega}]}$
 - $\omega_{\text{acc}} - \omega_0 \left(1 - \frac{1}{2Q^2}\right)^{-1/2}, \omega_a \omega_{\text{acc}} = \omega_0^2$
 - $\langle P \rangle = \frac{1}{2}\Re(F_0 v_0^*) = \frac{1}{2}\Re v_0 v_0^* m[(\omega_0^2 - \omega^2)/i\omega + \gamma] = \frac{1}{2}m\gamma|v_0|^2 = \frac{1}{2}b|v_0|^2 = \langle P_{\text{dissipated}} \rangle$
 - Mechanical Impedance $Z = \frac{F_0}{v_0} = m\left[\frac{\omega_0^2 - \omega^2}{i\omega} + \gamma\right], \langle P \rangle = \frac{1}{2}|v_0|^2\Re(Z)$
5. $\boxed{\Re(A)\Re(B) = \frac{1}{2}(A + A^*)\frac{1}{2}(B + B^*) = \frac{1}{2}\Re(AB + AB^*)}$
6. $P = Fv = \Re(F_0 e^{i\omega t})\Re(v_0 e^{i\omega t}) = \frac{1}{2}\Re(F_0 v_0 e^{2i\omega t} + F_0 v_0^*), \langle P \rangle = \frac{1}{2}\Re(|F_0||v_0|e^{i(\phi_F - \phi_v)}) = \frac{1}{2}|F_0||v_0|\cos(\phi_F - \phi_v)$
7. $\langle P \rangle = \frac{1}{2}\Re(V_0 I_0^*) = \frac{1}{2}|I_0|^2 R$
8. $\omega_P = \omega_v = \omega_0$
9. At $\omega = \omega_{\pm}, |v_{\text{max}}|/|v_0| = 1/\sqrt{2}, \Delta\omega = \omega_+ - \omega_- = \gamma, Q = \frac{\omega_0}{\Delta\omega}$
10. Two coherent cosine driving forces, $x = A_1 \cos(\omega t + \alpha_1 + \phi) + A_2 \cos(\omega t + \alpha_2 + \phi), A^2 = A_1^2 + A_2^2 + 2A_1 A_2 \cos(\alpha_2 - \alpha_1)$
11. $\frac{\partial^2 \Psi}{\partial t^2} = v^2 \frac{\partial^2 \Psi}{\partial x^2}, \text{ phase speed } v = \sqrt{T/\rho}$
12. $\Psi(x, t) = \Re(Ae^{i(\omega t - kx)}), k \text{ is the wavenumber}$
13. $\boxed{\frac{\partial^2 \Psi}{\partial t^2} = v^2 \nabla^2 \Psi}$
14. $\Psi(\mathbf{r}, t) = \Re(Ae^{i\omega - i\mathbf{k} \cdot \mathbf{r}}), \mathbf{k} \text{ is the wavevector}$

15. Spherical waves $v^2 \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \Psi}{\partial r} \right) = \frac{\partial^2 \Psi}{\partial r^2}$, $\Psi(r, t) = \frac{f(r \pm vt)}{r} = \Re \left(\frac{Ae^{i\omega t - ikr}}{r} \right)$

16. Cylindrical waves $v^2 \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \Psi}{\partial r} \right) = \frac{\partial^2 \Psi}{\partial r^2}$, for $r \gg \lambda$, $\Psi(r, t) \approx \Re \left(\frac{f(r \pm vt)}{\sqrt{r}} \right)$

17. Wave impedance (can be **negative**)

- $Z = \frac{\text{transverse driving force}}{\text{transverse velocity}} = \frac{-T \frac{\partial \Psi}{\partial x}}{\frac{\partial \Psi}{\partial t}} = \frac{T}{v} = \sqrt{T\rho} = \rho v$
- Power = transverse force \times transverse velocity, $\langle P \rangle = \frac{1}{2} \Re(Fu^*) = \frac{1}{2} \Re(Z)|u|^2$
- $u = i\omega A_0 e^{i(\omega t - kx)} \implies \langle P \rangle = \frac{1}{2} \Re(Z) \omega^2 A_0^2$
- $\frac{dKE}{dt} = \frac{1}{2} \rho \left(\frac{\partial \Psi}{\partial t} \right)^2$, $\frac{dPE}{dx} = \frac{1}{2} T \left(\frac{\partial \Psi}{\partial x} \right)^2$, $v^2 = \frac{\omega^2}{k^2} = \frac{T}{\rho} \implies KE = PE$
- $\langle P \rangle = \frac{d\langle E \rangle}{dx} v = \frac{d\langle KE \rangle + \langle PE \rangle}{dx} = \frac{1}{2} \rho v \omega^2 A_0^2 = \frac{1}{2} Z \omega^2 A_0^2$ (Note $\Re(e^{ix})^2 = \Re(e^{2ix} + 1) \neq \Re(e^{2ix})$)

18. Transverse rope wave at a boundary, same frequency, different wavelength

- $A_1 e^{i(\omega t - k_1 x)}$, $B_1 e^{i(\omega t + k_1 x)}$, $A_2 e^{i(\omega t - k_2 x)}$, incident, reflected, transmitted
- Continuous displacement Ψ , $A_1 + B_1 = A_2$
- Continuous transverse force $-T \frac{\partial \Psi}{\partial x} \propto Z\Psi$, $Z_1(A_1 - B_1) = Z_2 A_2$
- $r = \frac{B_1}{A_1} = \frac{Z_1 - Z_2}{Z_1 + Z_2}$, $\tau = \frac{A_2}{A_1} = \frac{2Z_1}{Z_1 + Z_2}$
- $R = \frac{\langle P_{B_1} \rangle}{\langle P_{A_1} \rangle} = \left(\frac{Z_1 - Z_2}{Z_1 + Z_2} \right)^2$, $T = \frac{\langle P_{A_2} \rangle}{\langle P_{A_1} \rangle} = \frac{4Z_1 Z_2}{(Z_1 + Z_2)^2}$, $R + T = 1$
- Antiphase $Z_2 = \infty$, in-phase $Z_2 = 0$, matched $Z_1 = Z_2$

19. Longitudinal wave in gas, for displacement a ,

- Adiabatic process $pV^\gamma = pV^{C_p/C_v} = \text{constant}$
- $-\frac{\partial \Psi_p}{\partial x} = \rho \frac{\partial^2 a}{\partial t^2}$
- $\Psi_p = dp = -\gamma p \frac{d\Delta V}{dV} = -\gamma p \frac{\partial a}{\partial x}$
- $\frac{\partial \Psi_p}{\partial x} = -\gamma p \frac{\partial^2 a}{\partial x^2} - \gamma \frac{\partial p}{\partial x} \frac{\partial a}{\partial x} \approx -\gamma p \frac{\partial^2 a}{\partial x^2}$
- $\frac{\partial^2 a}{\partial x^2} = \frac{\rho}{\gamma p} \frac{\partial^2 a}{\partial t^2} = v^2 \frac{\partial^2 a}{\partial t^2}$, $v = \sqrt{\frac{\gamma p}{\rho}} = \sqrt{\frac{\gamma n R T V}{V m}} = \sqrt{\frac{\gamma R T}{M}}$,

where M is the molar mass.

- $\frac{1}{2} m \langle v^2 \rangle = \frac{3}{2} k_B T \implies v_{\text{rms}} = \sqrt{\langle v^2 \rangle} = \sqrt{\frac{3RT}{M}} \geq v$ (phase speed of sound wave is slightly smaller than rms speed of gas)
- $a = a_0 e^{i\omega t - ikx}$, $\Psi_p = -\gamma p \frac{\partial a}{\partial x} = i\gamma p k a$
- Acoustic impedance $\mathcal{L} = \sqrt{\gamma p \rho} = v\rho = \frac{\gamma p}{v}$, impedance $Z = \frac{\text{force}}{\text{velocity}} = \frac{\Delta S \Psi_p}{\dot{a}} = \Delta S \mathcal{L}$
- Pressure amplitude $A = i\gamma p k a_0$ is the amplitude of pressure $\Psi_p = A e^{i\omega t - ikx} = i\gamma p k a_0 e^{i\omega t - ikx}$
- Intensity $I = \frac{1}{2} \Re(\Psi_p \dot{a}^*) = \frac{1}{2} \gamma p k \omega a_0^2 = \frac{|A|^2}{2\mathcal{L}} = \frac{A_{\text{rms}}^2}{\mathcal{L}} = \frac{1}{2} \mathcal{L} \omega^2 |a_0|^2$ (mean P per unit area)

- $\text{dBA} = 10 \log_{10} \left(\frac{I}{I_{\text{ref}}} \right) = 20 \log_{10} \left(\frac{p_{\text{rms}}}{p_{\text{ref}}} \right)$ (p_{ref} is a rms value)

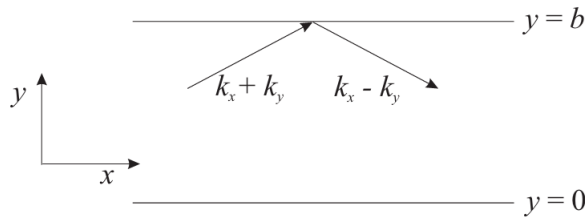
20. Longitudinal sound waves

- $\Psi_p = -K \frac{\partial a}{\partial x}$, K is elastic modulus for any medium
 - In adiabatic gas, $K = B = \gamma p$ (B is the bulk modulus), correct assumption
 - In isothermal gas, $K = B = p$, bad assumption for sound in air
 - In solid, $K = E$, Young's modulus
- $v = \sqrt{\frac{K}{\rho}}$, gas $v = \sqrt{\frac{\gamma p}{\rho}}$, solid $v = \sqrt{\frac{E}{\rho}}$, non-dispersive
- $\mathcal{L} = \frac{K}{v} = \sqrt{K\rho}$

21. Damped waves on a string, damping force on dx is $-\beta \dot{\psi} dx$

- $\boxed{\frac{\partial^2 \Psi}{\partial t^2} + \frac{\beta}{\rho} \frac{\partial \Psi}{\partial t} = v^2 \frac{\partial^2 \Psi}{\partial x^2}}, \Gamma = \frac{\beta}{\rho}$
- trial solution $\psi = \psi_0 e^{i(\omega t - kx)}$, ω is real, k is complex in general ($k = k_r - ik_i$)
- $\frac{\partial^2 \Psi}{\partial t^2} + \Gamma \frac{\partial \Psi}{\partial t} = v^2 \frac{\partial^2 \Psi}{\partial x^2}$, $\omega^2 - i\Gamma\omega = v^2 k^2$
- $k_r^2 - k_i^2 = \frac{\omega^2}{v^2}$, $2k_r k_i = \frac{\Gamma\omega}{v^2}$
- Light damping $\Gamma \ll \omega$, $k_r \approx \omega/v$, $k_i \approx \Gamma/(2v)$
- Heavy damping $k_r \approx k_i \approx \left(\frac{\Gamma\omega}{2v^2} \right)^{1/2}$
- Find both by solving quadratic and approximating square root at the last step
- The **characteristic impedance** $Z = \frac{F}{v} = \frac{-T\Psi'}{\dot{\Psi}} = \frac{Tk}{\omega} = \frac{T}{\omega}(k_r - ik_i)$
- Light damping $Z(\omega) = \frac{T}{v} \left(1 - \frac{i\Gamma}{2\omega} \right) = Z_0 \left(1 - \frac{i\Gamma}{2\omega} \right)$, where Z_0 is Z with zero damping
- Heavy damping $Z(\omega) = Z_0(1 - i)\sqrt{\frac{\Gamma}{2\omega}}$
- Reflection coefficient $r = \frac{Z_1 - Z_2}{Z_1 + Z_2}$
- From undamped (Z_0) to damped (Z)
 - $r(\omega) \approx \frac{i\Gamma}{4\omega}$
 - $r(\omega) \approx -1$
-

22. Waveguide on a membrane



-
- $\Psi_A = Ae^{i(\omega t - k_x x - k_y y)}$
- $\Psi_B = -Ae^{i(\omega t - k_x x + k_y y)}$
- $\Psi = \Psi_A + \Psi_B = -2iA \sin(k_y y) e^{i(\omega t - k_x x)}$
- Boundary condition: $\Psi = 0$ at $y = 0, b$

- $k_y = \frac{n\pi}{b}$
- $k^2 = k_x^2 + k_y^2$
- Dispersion relation: $\omega^2 = v^2 \left(k_x^2 + \frac{n^2 \pi^2}{b^2} \right)$
- Phase velocity $v_p = \frac{\omega}{k_x} = \frac{\omega}{\sqrt{\left(\frac{\omega^2}{v^2} - \frac{n^2 \pi^2}{b^2}\right)}}$
- Group velocity $v_g = \frac{d\omega}{dk} = \frac{v^2}{\omega} \sqrt{\left(\frac{\omega^2}{v^2} - \frac{n^2 \pi^2}{b^2}\right)}$
- If $k_x^2 < 0$, k_x is imaginary, the wave is **evanescent**

23. Wave equation $\nabla^2 \mathbf{E} = \mu\epsilon \frac{\partial^2 \mathbf{E}}{\partial t^2} = \frac{1}{c^2} \frac{\partial^2 \mathbf{E}}{\partial t^2}$

24. $c_0 = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$, $n = \frac{c_0}{c} = \sqrt{\mu_r \epsilon_r}$

25. $Z = \frac{|\mathbf{E}|}{|\mathbf{H}|} = \frac{|\mathbf{E}|}{|\mathbf{B}/\mu|} = c\mu = \sqrt{\frac{\mu}{\epsilon}} = Z_0 \sqrt{\frac{\mu_r}{\epsilon_r}}$

26. $Z = \frac{Z_0}{n}$, $Z_0 = \sqrt{\frac{\mu_0}{\epsilon_0}} \approx 376.730\Omega$ (Z_0 is impedance of free space)

27. Reflection of EM wave $r = \frac{n_1 - n_2}{n_1 + n_2}$

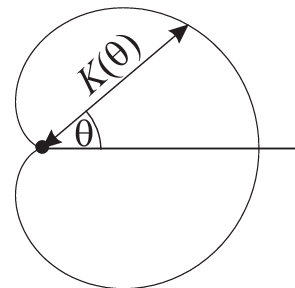
28. Optics

- Quantum Electrodynamics: full theory of EM interaction with matter, complicated, only used for simple systems
- Maxwell's Equations: Large number of photons, hard to compute except for special boundary conditions
- Physical Optics: aka scalar wave theory, ignore polarization, simplify b.c. Use Huygens' construction of secondary waves. (What we use in this course)
- Ray Optics: Ignore wave properties, "corpuscular theory".

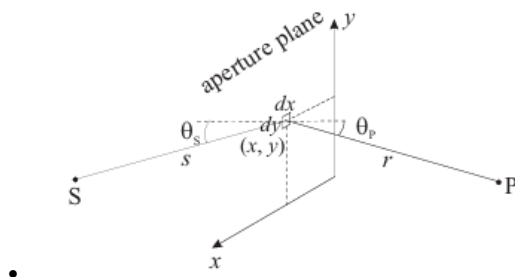
29. Huygens' Principle: each point on a wavefront acts as a source of secondary wavelets which propagate, overlap, interfere, and thus carry the wavefront forward

30. Huygens-Fresnel Principle

- Obliquity/inclination factor $K(\theta) = \frac{1 + \cos \theta}{2}$
David Miller: dipole; Forrest Anderson: dirac delta functions
- The secondary wavelets have an amplitude $-i/\lambda$ relative to the primary wave
- **No physical foundation**, but experimentally verified

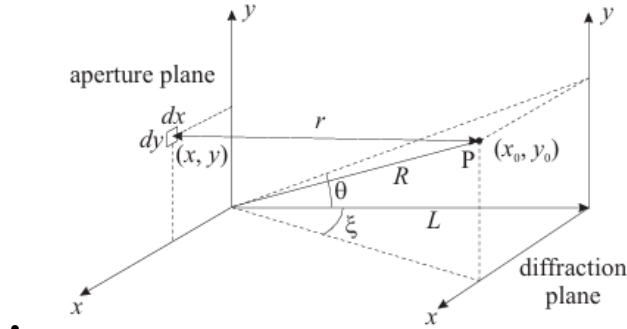


31. The diffraction integral



- $\Psi(\mathbf{r}, t) = \text{Re}(\psi(\mathbf{r}e^{-i\omega t}))$
- $\psi_{\text{incident}} = \frac{a_S e^{iks}}{s}$
- Obliquity factor $\boxed{K(\theta) = \frac{\cos \theta_S + \cos \theta_P}{2}}$ (Proof)
- Fresnel-Kirchhoff diffraction Integral $\psi_P = \iint_{\Sigma} -\frac{i}{\lambda} h(x, y) K(\theta) \frac{a_S e^{ik(s+r)}}{sr} dx dy$
- Key take-away: plane wave on aperture produces $\boxed{\psi_P \propto \frac{e^{ikr}}{r}}$

32. Fraunhofer diffraction



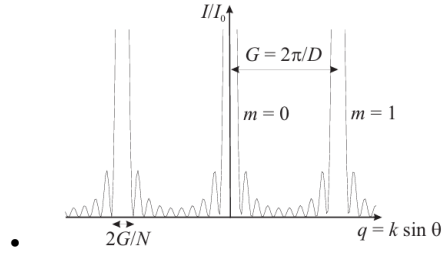
- $r^2 = L^2 + (x_0 - x)^2 + (y_0 - y)^2 = R^2 \left(1 - 2 \frac{x_0 x + y_0 y}{R^2} + \frac{x^2 + y^2}{R^2} \right)$
- $R^2 = L^2 + x_0^2 + y_0^2$
- $r \approx R - \frac{x_0 x + y_0 y}{R} + \frac{x^2 + y^2}{2R}$
- Condition for Fraunhofer $\boxed{\frac{k(x^2 + y^2)}{2R} \ll \pi}$ (or $R \gg \frac{\rho^2}{\lambda}$)
- Ignore obliquity factor, $\psi_P \propto \iint_{\Sigma} h(x, y) \exp \left[-ik \left(\frac{x_0}{R} x + \frac{y_0}{R} y \right) \right] dx dy$
- 1D aperture, $\psi_P \propto \int \boxed{h(y) e^{-iqy} dy}$, $q = ky_0/R = k \sin \theta$

33. Fraunhofer, angular resolution of circular aperture $\theta = \frac{1.22\lambda}{d}$.

34. Diffraction grating of N slits' resolution at n -th maxima $\frac{\delta\lambda}{\lambda} = \frac{1}{nN}$

- slit separation D , aperture screen distance R , $p = k \sin \theta = \frac{2\pi}{\lambda} \frac{x_0}{R}$
- Width of n -th peak is first peak at $x_0 = 0$ to position of first zero
- $h(y) = \sum_{m=0}^{N-1} \delta(x - mD)$
- $\psi_P \propto \int h(y) e^{-ipx} dx = \sum_{m=0}^{N-1} e^{-ipmD} = \frac{1 - e^{-ipND}}{1 - e^{-ipD}} = \frac{\sin\left(\frac{pND}{2}\right)}{\sin\left(\frac{pD}{2}\right)} e^{-ip(N-1)D/2}$
- $I = |\psi_P|^2 \propto \left(\frac{\sin\left(\frac{pND}{2}\right)}{\sin\left(\frac{pD}{2}\right)} \right)^2$
- Let $I = I_0$ at $N = 1$, $I = I_0 \left(\frac{\sin\left(\frac{pND}{2}\right)}{\sin\left(\frac{pD}{2}\right)} \right)^2$

- Peaks at $\frac{pD}{2} = n\pi$, if not a peak and $\frac{pND}{2} = n\pi$, a zero, there are $N - 1$ zeros between peaks. Peak height $N^2 I_0$ by l'Hopital's rule.
- $1/2$ -Peak-width (first zero) is $pND/2 = kNDx_0/2R = \pi$, $x_0 = \frac{\lambda R}{DN}$
- In the extreme case, n -th peak of $\lambda + \delta\lambda$ falls on minimum of n -th peak of λ
- n -th maximum, $D \sin \theta = D \frac{x_0}{R} = n\lambda$, $x_0 = \frac{n\lambda}{D}$
- $\frac{n(\lambda + \delta\lambda)R}{D} - \frac{n\lambda R}{D} = \frac{\lambda R}{DN}$, $\boxed{\frac{\delta\lambda}{\lambda} = \frac{1}{nN}}$
- Higher order peaks separates lights better (higher resolution), but might not be obtained.
- More slits N on grating increases resolution, but reduces x_0 so more difficult to measure. (Rayleigh Criterion)



	$f(t)$	$\tilde{f}(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(t) e^{-i\omega t} dt$
	$\delta(t - t_0)$	$\frac{e^{-i\omega t_0}}{\sqrt{2\pi}}$
35.	$f(t) = \text{int}(t \leq 1/2)$ (top-hat)	$\frac{\text{sinc}(\omega/2)}{\sqrt{2\pi}}$
	$e^{-t^2/2}$ (Gaussian)	$e^{-\omega^2/2}$
	$\sum_{n=-\infty}^{\infty} \delta(t - nT)$ (comb)	$\frac{\sqrt{2\pi}}{T} \sum_{n=-\infty}^{\infty} \delta(\omega - \frac{2\pi}{T}n)$

36. Babinet's principle: The diffracted intensities of an aperture and its complement are the same except at the origin

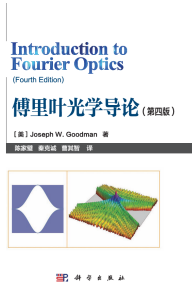
$$\psi_a \propto \iint_A e^{-i(px+qy)} dx dy$$

$$\psi_b \propto \iint_{\text{all space}} e^{-i(px+qy)} dx dy - \psi_a \propto \boxed{\delta(p, q) - \psi_a}$$

37. On-axis Fresnel diffraction ($R \sim \rho^2/\lambda$, $p = q = 0$)

$$\psi_P \propto \iint_{\Sigma} h(x, y) \exp\left(ik \frac{x^2 + y^2}{2R}\right) dx dy$$

38. Rectangular aperture



2. ★

- The plane wave has amplitude ψ_s at the aperture
- Perpendicular distance from P to aperture is L , is large
- $\psi_P = \iint_{\Sigma} K(\theta_S, \theta_P) \frac{A\psi_s e^{ikr}}{r} \rho d\rho d\phi$
- $L^2 + \rho^2 = r^2$, $\rho d\rho = r dr$, r goes from L to $R(\phi)$
- $R(\phi)$ varies rapidly as ϕ changes because L is large
- $\psi_P = \int_0^{2\pi} \int_L^{R(\phi)} \frac{A\psi_s e^{ikr}}{r} r dr d\phi = \frac{A\psi_s}{ik} \int_0^{2\pi} e^{ikR(\phi)} d\phi - \frac{2\pi A}{ik} \psi_s e^{ikL}$
- $e^{ikR(\phi)}$ oscillates quickly, first integral vanishes
- $\psi_P = \psi_s$, $\frac{-2\pi A}{ik} = 1$, $\boxed{A = -i/\lambda}$