

# 7380 HW 1

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## 1

Presuming  $\epsilon$  is everywhere nonzero, we may rewrite (2) as  $\frac{i}{\omega\epsilon}(\nabla \times H) = E$ . Taking the curl of both sides and substituting the right side of (1) in for  $\nabla \times E$  yields

$$\nabla \times \left( \frac{i}{\omega\epsilon} (\nabla \times H) \right) = i\omega\mu H$$

Since  $H$  is always perpendicular to the  $(x_1, x_2)$  plane, it only has a component in the  $x_3$  direction, and so its curl is computed as  $\left( \frac{\partial H}{\partial x_2}, -\frac{\partial H}{\partial x_1}, 0 \right)$  using the abusive notation  $H = |H|$ . Moving the constants to the other side, the subsequent curl is

$$\left( -\frac{1}{\epsilon} \frac{\partial^2 H}{\partial x_3 \partial x_1} - \frac{1}{\epsilon^2} \frac{\partial \epsilon}{\partial x_3}, \frac{1}{\epsilon^2} \frac{\partial \epsilon}{\partial x_3} \frac{\partial H}{\partial x_2} - \frac{1}{\epsilon} \frac{\partial^2 H}{\partial x_3 \partial x_2}, \frac{1}{\epsilon^2} \left( \frac{\partial \epsilon}{\partial x_1} \frac{\partial H}{\partial x_1} + \frac{\partial \epsilon}{\partial x_2} \frac{\partial H}{\partial x_2} \right) + \frac{1}{\epsilon} \left( \frac{\partial^2 H}{\partial x_1^2} + \frac{\partial^2 H}{\partial x_2^2} \right) \right)$$

Since neither  $H$  nor  $\epsilon$  depend on  $x_3$ , all the terms containing those partials are zero. This expression then reduces to

$$\left( 0, 0, \frac{1}{\epsilon^2} \left( \frac{\partial \epsilon}{\partial x_1} \frac{\partial H}{\partial x_1} + \frac{\partial \epsilon}{\partial x_2} \frac{\partial H}{\partial x_2} \right) + \frac{1}{\epsilon} \left( \frac{\partial^2 H}{\partial x_1^2} + \frac{\partial^2 H}{\partial x_2^2} \right) \right)$$

On the right hand side, we similarly have a nonzero component only in the  $x_3$  direction since  $H$  is perpendicular to the  $(x_1, x_2)$  plane. Thus, we obtain a single scalar equation. Applying the same abusive notation to the right side, this equation is

$$\frac{1}{\epsilon^2} \left( \frac{\partial \epsilon}{\partial x_1} \frac{\partial H}{\partial x_1} + \frac{\partial \epsilon}{\partial x_2} \frac{\partial H}{\partial x_2} \right) + \frac{1}{\epsilon} \left( \frac{\partial^2 H}{\partial x_1^2} + \frac{\partial^2 H}{\partial x_2^2} \right) = \omega^2 \mu H$$

This is clearly a scalar second-order PDE for  $H$ , as desired.

## 2

For the forward implication, let  $\nabla \times F = A$ . We then write

$$\nabla \times A = J \Leftrightarrow (\nabla \times A) \cdot \Phi = J \cdot \Phi$$

There is a vector identity for the cross product

$$\nabla \cdot (A \times B) = (\nabla \times A) \cdot B - A \cdot (\nabla \times B)$$

$$\Leftrightarrow (\nabla \times A) \cdot B = \nabla \cdot (A \times B) + A \cdot (\nabla \times B)$$

which we may apply to the previous expression to obtain

$$\nabla \cdot (A \times \Phi) + A \cdot (\nabla \times \Phi) = J \cdot \Phi$$

Expanding the expression for  $A$ ,

$$\Leftrightarrow \nabla \cdot ((\nabla \times F) \times \Phi) + (\nabla \times F) \cdot (\nabla \times \Phi) = J \cdot \Phi$$

Integrating both sides over  $\mathbb{R}^3$ , set  $B = (\nabla \times F) \times \Phi$  and use the linearity of the integral to obtain

$$\int \nabla \cdot B dV + \int (\nabla \times F) \cdot (\nabla \times \Phi) dV = \int J \cdot \Phi dV$$

Since  $\Phi$  is compactly supported, there exists some bounded region  $W \subseteq \mathbb{R}^3$  whose interior encloses the support of  $\Phi$ . We may integrate over the interior of  $W$  instead, since  $\Phi$  being zero elsewhere implies the integrand and associated contributions to the integral are zero elsewhere. The first summand on the left side is by the divergence theorem equal to  $\int_{\partial W} n \cdot B dS$ , which, since we have established that the integrand is zero outside the support of  $\Phi$ , must be zero. Therefore, we obtain the desired result, that

$$\int (\nabla \times F) \cdot (\nabla \times \Phi) dV = \int J \cdot \Phi dV$$

For the reverse direction, we may apply much of the same logic in reverse: we may add 0 to the left hand side in the form of  $\int_{\partial W} n \cdot ((\nabla \times F) \times \Phi) = \int_W \nabla \cdot ((\nabla \times F) \times \Phi) dV$ ; merging the integrals using linearity yields an integrand equal to the right hand side of the cross product identity used above. Applying it yields

$$\begin{aligned} \int (\nabla \times \nabla \times F) \cdot \Phi &= \int J \cdot \Phi \Leftrightarrow \int (\nabla \times \nabla \times F) \cdot \Phi - J \cdot \Phi = 0 \\ &\Leftrightarrow \int (\nabla \times \nabla \times F - J) \cdot \Phi = 0 \end{aligned}$$

using the linearity of the dot product. The problem then reduces, setting  $C = \nabla \times \nabla \times F - J$ , to showing that if  $\forall \Phi, I = \int C \cdot \Phi = 0$ , then  $C = 0$ . We prove the contrapositive: let  $C \neq 0$ , then there exists some  $\Phi$  such that  $I \neq 0$ . Since  $F$  is smooth, all its derivatives are smooth, and so its curl and its curl's curl are both smooth. Since  $J$  is also smooth, this implies  $C$  is smooth and therefore continuous. Let  $\Phi = C$ . Then  $C \cdot \Phi = C \cdot C = |C|^2$ , which is also continuous since the Euclidean norm and squaring both are. Further, for a point  $x$  such that  $C(x) \neq 0$ ,  $|C(x)|^2 \neq 0$ . Since  $|C|^2$  is continuous and nonzero at a point, there is a region of positive measure where it is nonzero. Since the function is also non-negative everywhere, this implies its integral is nonzero.

### 3

There is a vector calculus theorem that for  $W \in \mathbb{R}^3$

$$\int_{\partial W} A \times n dS = - \int_W \nabla \times A dV$$

or, by anticommutativity of the cross product,

$$\int_{\partial W} n \times AdS = \int_W \nabla \times AdV$$

Over each of  $W_1$  and  $W_2$ , we construct a preliminary estimate of the surface integral, using  $m$  for a general normal vector to a surface (i.e. sometimes meaning different things in a single equation corresponding to the surface being integrated over), as

$$\int_{\partial W_1} m \times F_1 dS + \int_{\partial W_2} m \times F_2 dS$$

This over-counts the regions  $\partial W_1 \cap \Gamma$  and  $\partial W_2 \cap \Gamma$ , so we subtract them out to obtain

$$\int_{\partial W} m \times F dS = \int_{\partial W_1} m \times F_1 dS + \int_{\partial W_2} m \times F_2 dS - \int_{\partial W_1 \cap \Gamma} m \times F_1 dS - \int_{\partial W_2 \cap \Gamma} m \times F_2 dS$$

We may apply the theorem from above and use that  $F_1 = F_2 = F$  on  $W \setminus \Gamma$  to get

$$\int_{\partial W} m \times F dS = \int_{W_1 \cup W_2} \nabla \times F dV - \int_{\partial W_1 \cap \Gamma} m \times F_1 dS - \int_{\partial W_2 \cap \Gamma} m \times F_2 dS$$

The rightmost two terms may be rewritten in terms of  $n$ , since in the first integral  $m = n$  and in the second  $m = -n$ , to yield

$$\int_{\partial W} m \times F dS = \int_{W_1 \cup W_2} \nabla \times F dV + \int_{\partial W_2 \cap \Gamma} n \times F_2 dS - \int_{\partial W_1 \cap \Gamma} n \times F_1 dS$$

By the linearity of the integral and cross product, and by definition of  $[F]$ , this is exactly the equation desired:

$$\int_{\partial W} m \times F dS = \int_{W_1 \cup W_2} \nabla \times F dV + \int_{W \cap \Gamma} n \times [F] dS$$

**4**

**5**

Let  $\tau = t - t_0$ . Then  $\tilde{E}(x, t) = E(x, \tau)$ ,  $\tilde{H}(x, t) = H(x, \tau)$  and subsequently

$$\begin{aligned} \nabla \times \tilde{E}(x, t) &= -\frac{\partial}{\partial t}(\mu * \tilde{H}(x, t)) \Leftrightarrow \nabla \times E(x, \tau) = -\left(\frac{\partial}{\partial \tau}(\mu * H(x, \tau))\right) \frac{\partial \tau}{\partial t} \\ &\Leftrightarrow \nabla \times E(x, \tau) = -\frac{\partial}{\partial \tau}(\mu * H(x, \tau)) \end{aligned}$$

This is identical to the assumption that  $E$  and  $H$  satisfy this equation in  $t$ . An identical argument holds for the second equation of the system.