

# 7550 HW 5

Duncan Wilkie

21 April 2023

**Problem 1.** On an open set  $U \subseteq \mathbb{R}^n$ , show that the exterior derivative is the only operator  $d : \Omega^p(U) \rightarrow \Omega^{p+1}(U)$  satisfying:

1.  $d(\omega + \eta) = d\omega + d\eta$ ;
2.  $\omega \in \Omega^p(U), \eta \in \Omega^q(U) \Rightarrow d(\omega \wedge \eta) = d\omega \wedge \eta + (-1)^p \omega \wedge d\eta$ ;
3.  $f \in \Omega^0(U) \Rightarrow df(X) = X(f)$ ; and
4.  $f \in \Omega^0(U) \Rightarrow d(df) = 0$ .

Deduce that  $d$  is independent of the coordinate system used to define it.

*Proof.* This smells a lot like it'd follow from uniqueness of categorical limits, but I don't want to mess around with sheaf ideas. Accordingly, I'll have to do it the normal way.

Suppose that  $d'$  satisfies each of the properties above. We merely must show that  $d'$  satisfies the defining characteristic of  $d$ , namely, that if  $X$  is a smooth vector field on  $U$ , that  $d'f(X) = X(f)$ , and, letting  $\omega = f dx_1 \wedge \cdots \wedge dx_p$ , that  $d'\omega = d'f dx_1 \wedge \cdots \wedge dx_p$  (which can be extended linearly to all forms).

Let  $X$  be a smooth vector field on  $U$ . In local coordinates,  $X = \sum_{i=1}^n a_i \frac{\partial}{\partial x_i}$ , where  $a_i$  are smooth functions on  $U$ . Property 3 yields  $d'f(X) = X(f)$ , as zero-forms are exactly smooth functions.

If  $\omega = f dx_1 \wedge \cdots \wedge dx_p = f \wedge dx_1 \wedge \cdots \wedge dx_p$ , then by property 2 applied with  $p = 0$  we can induct on  $p$  (the index in the wedges). For  $p = 0$ , it's immediate that the pure zero-form  $\omega = f$  has  $d'\omega = d'f$ . Suppose that the property holds for all pure wedges with  $p - 1$  terms. Then

$$\begin{aligned} d'\omega &= d'f \wedge dx_1 \wedge \cdots \wedge dx_p + (-1)^0 f \wedge d'(dx_1 \wedge \cdots \wedge dx_p) \\ &= d'f \wedge dx_1 \wedge \cdots \wedge dx_p + (-1)^0 f \wedge \left( \sum_i dx_1 \wedge \cdots d' dx_i \wedge \cdots \wedge dx_p \right) \end{aligned}$$

By property 2, which is  $d'f = \sum_i \frac{\partial f}{\partial x_i} dx_i$  in local coordinates, we can take  $f = x_i$  (the coordinate function) to get

$$d'x_i = \sum_j \frac{\partial x_i}{\partial x_j} dx_j = dx_i.$$

Accordingly,  $dx_i = d'(x_i)$ , so we can apply property 4 to get  $d'dx_i = 0$ —all the terms on the right vanish, and we get what we want:

$$d'\omega = d'f \wedge dx_1 \wedge \cdots \wedge dx_p.$$

By assumption in property 1,  $d'$  is additive, but is it linear? Well, let  $c \in \Omega^0(U)$  be a constant and  $\eta$  be a pure form of the form of  $\omega$  above. By property 2 and the definition of the wedge product and scalar product in the exterior algebra,

$$d'(c\eta) = d'(c \wedge \eta) = d'c \wedge \eta + (-1)^0 c \wedge d'\eta$$

Trivially by the property proven above,  $d'c = 0$ —so  $d'(c\eta) = cd'\eta$ . This means that  $d'$  is indeed linear on forms that look like  $\omega$ , and so can be honest-to-goodness linearly extended to all forms.

In any particular coordinate system, the text proves that the  $d$  defined by that coordinate system has all four properties. Accordingly, since none of these properties (including the forms themselves) are coordinate-dependent, any two coordinate systems must define the same  $d$  operator.  $\square$

Let  $G$  be a Lie group, and  $g \in G$ . Recall that left-translation by  $g$ ,  $L_g : G \rightarrow G$ , is given by  $L_g(h) = gh$ , and recall also the definition and importance of left-invariant vector fields. A differential form  $\omega$  on  $G$  is left-invariant if  $L_g^*\omega = \omega$  for each  $g \in G$ . Let  $E^p(G)$  denote the vector space of left-invariant  $p$ -forms on  $G$ , and  $E^*(G) = \bigoplus_{p=0}^{\dim G} E^p(G)$ . Here are some of their properties to establish. Several of them are analogs of properties of left-invariant vector fields we've seen.

**Problem 2.** *Left-invariant forms are smooth.*

*Proof.* We must show that any left-invariant form, when expressed in local coordinates near  $g$  as

$$\omega_g = \sum f_{i_1, \dots, i_p} dx_{i_1} \wedge \dots \wedge dx_{i_p},$$

has  $f_{i_1, \dots, i_p}$  smooth.

A general  $p$ -form  $\omega$  presented as above acts on  $p$  tangent vectors  $X_1, \dots, X_p$  at  $q$ —these in turn act on smooth functions  $f$  on  $G$ . Left-invariance expresses

$$\omega_g(X_1(f), \dots, X_p(f)) = L_g^*(\omega_e(X_1(f), \dots, X_p(f))) = \omega_e(X_1(f \circ L_g), \dots, X_p(f \circ L_g))$$

If  $g$  is close to the identity (i.e. such that  $gq$  is in the neighborhood where the local coordinates  $x_i$  apply), then we can express the above equality as

$$\sum f_{i_1, \dots, i_p} dx_{i_1} \wedge \dots \wedge dx_{i_p} = \sum g_{i_1, \dots, i_p} dx_{i_1} \wedge \dots \wedge dx_{i_p}.$$

Since  $dx_{i_j}$  is a basis for the exterior algebra(s near  $q$ ),

However,  $gq$  is a point in  $G$ —give it local coordinates  $y_1, \dots, y_n$ . With respect to these,

$$\omega_q = \omega_{gq} = \sum g_{i_1, \dots, i_p} dy_{i_1} \wedge \dots \wedge dy_{i_p};$$

$\square$

**Problem 3.**  $E^*(G)$  is a subalgebra of the algebra  $\Omega^*(G)$  of all smooth differential forms on  $G$ . If  $e$  denotes the identity element of  $G$ , the map  $\omega \mapsto \omega_e$  is an algebra isomorphism of  $E^*(G)$  and the exterior algebra  $\Lambda((T_e G)^*)$ . Note that this map gives an isomorphism of  $E^1(G)$  with  $(T_e G)^*$ , that is, with the dual space of the Lie algebra  $\mathfrak{g}$  of  $G$ .

*Proof.* First, the subalgebra condition. If  $\omega, \nu$  are left-invariant, then  $L_g * (\omega + \nu)$

$\square$

**Problem 4.** If  $\omega$  is a left-invariant form and  $X$  is a left-invariant vector field, then  $\omega(X)$  is a constant function on  $G$ .

**Problem 5.** Let  $\{X_1, \dots, X_n\}$  and  $\{\omega_1, \dots, \omega_n\}$  be dual bases for  $\mathfrak{g}$  and  $E^1(G)$ . Then there are constants  $c_{ijk}$  so that  $[X_i, X_j] = \sum_{k=1}^n c_{ijk} X_k$ . These structure constants of  $G$  with respect to the specified basis of  $\mathfrak{g}$  satisfy  $c_{ijk} + c_{jik} = 0$  and  $\sum_r (c_{ijr} c_{rks} + c_{jkr} c_{ris} + c_{kir} c_{rjs}) = 0$ . Use the invariant formula for the exterior derivative to show that the exterior derivatives of the form  $\omega_i$  are given by the Maurer-Cartan equations

$$d\omega_i = \sum_{j < k} c_{jki} \omega_k \wedge \omega_j.$$

**Problem 6.** Show that a Lie group  $G$  is orientable. Hint: can you use (a basis for)  $E^1(G)$  to produce a nowhere-vanishing  $n$ -form, where  $n = \dim G$ ?