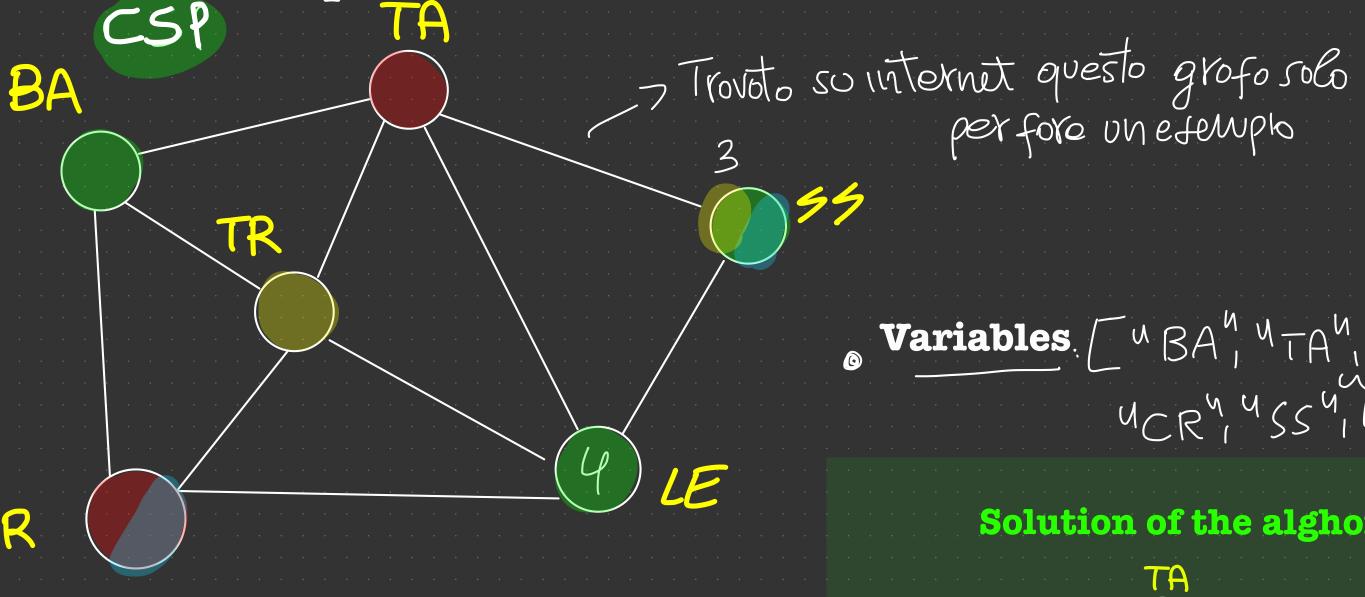
Hamiltonian path L'obbiettivo è visitare tutte le città non passando due volte dalla stessa



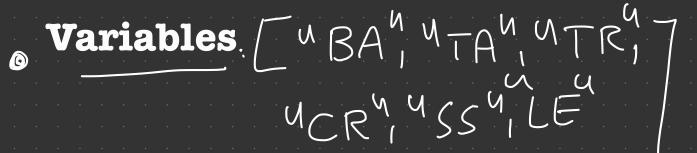
BA, TA, GG, TR, LE

Variable: for euch stop

CR

Constraints. Alldiff (Voyobles)

NeighbourConstr(BA,LE)



Solution of the alghoritm V

