Faire salut avec Poppy
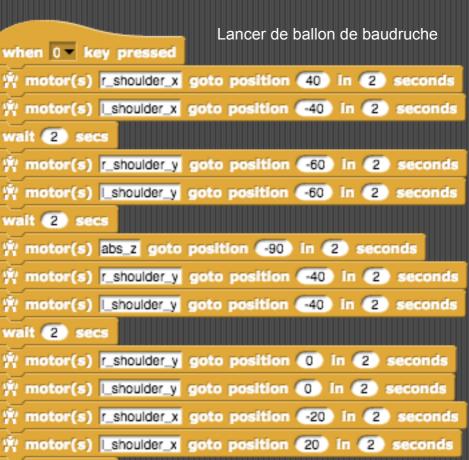
Pour faire cou-cou : taper sur 1

```
when 1 ▾ key pressed
motor(s) l_arm_z goto position 90 in 2 seconds
motor(s) l_shoulder_x goto position 90 in 2 seconds
wait 2 secs
repeat 10
    motor(s) l_elbow_y goto position -110 in 0.3 seconds
    wait 0.5 secs
    motor(s) l_elbow_y goto position -70 in 0.3 seconds
    wait 0.5 secs
wait 1 secs
```

Faire un câlin avec Poppy

motor(s) bust_y goto position 20 in 2 seconds

motor(s) r_shoulder_x goto position -20 in 2 seconds

motor(s) l_shoulder_x goto position 20 in 2 seconds

motor(s) liste r_shoulder_y l_shoulder_y ◀▶ goto position -70 in 2 seconds

attendre 0.5 sec.

motor(s) l_arm_z goto position -35 in 2 seconds

motor(s) r_arm_z goto position 30 in 2 seconds

motor(s) liste r_elbow_y r_elbow_y ◀▶ goto position -100 in 2

motor(s) head_z goto position 20 in 2 seconds

motor(s) head_y goto position 20 in 2 seconds

attendre 4 sec.

motor(s) all motors goto position 0 in 2 seconds

Lancer de ballon de baudruche

```
when [0 ▼] key pressed
motor(s) r_shoulder_x goto position 40 in 2 seconds
motor(s) l_shoulder_x goto position -40 in 2 seconds
wait 2 secs
motor(s) r_shoulder_y goto position -60 in 2 seconds
motor(s) l_shoulder_y goto position -60 in 2 seconds
wait 2 secs
motor(s) abs_2 goto position -90 in 2 seconds
motor(s) r_shoulder_y goto position -40 in 2 seconds
motor(s) l_shoulder_y goto position -40 in 2 seconds
wait 2 secs
motor(s) r_shoulder_y goto position 0 in 2 seconds
motor(s) l_shoulder_y goto position 0 in 2 seconds
motor(s) r_shoulder_x goto position -20 in 2 seconds
motor(s) l_shoulder_x goto position 20 in 2 seconds
```