

Pour faire un callin : taper 3

when 2 key pressed

motor(s) bust_y goto position 20 in 2 seconds

motor(s) r_shoulder_x goto position -20 in 2 seconds

motor(s) l_shoulder_x goto position 20 in 2 seconds

motor(s) list r_shoulder_y l_shoulder_y goto position -70 in 2 seconds

wait 0.5 secs

motor(s) l_arm_z goto position -35 in 2 seconds

motor(s) r_arm_z goto position 30 in 2 seconds

motor(s) list l_elbow_y r_elbow_y goto position -100 in 2 seconds

motor(s) head_z goto position 20 in 2 seconds

motor(s) head_y goto position 20 in 2 seconds

wait 3 secs

motor(s) Init goto position 0 in 2 seconds

motor(s) l_elbow_y goto position -90 in 2 seconds

motor(s) r_elbow_y goto position -90 in 2 seconds

Pour faire cou-cou : taper sur 1

when 1 key pressed

motor(s) L_arm_z goto position 90 in 2 seconds

motor(s) L_shoulder_x goto position 90 in 2 seconds

wait 2 secs

repeat 10

motor(s) L_elbow_y goto position -110 in 0.3 seconds

wait 0.5 secs

motor(s) L_elbow_y goto position -70 in 0.3 seconds

wait 0.5 secs

wait 1 secs

motor(s) Init goto position 0 in 2 seconds

motor(s) L_elbow_y goto position -90 in 2 seconds

motor(s) r_elbow_y goto position -90 in 2 seconds

when 0 key pressed

motor(s) r_shoulder_x goto position 40 In 2 seconds

motor(s) l_shoulder_x goto position -40 In 2 seconds

wait 2 secs

motor(s) r_shoulder_y goto position -60 In 2 seconds

motor(s) l_shoulder_y goto position -60 In 2 seconds

wait 2 secs

motor(s) abs_z goto position -90 In 2 seconds

motor(s) r_shoulder_y goto position -40 In 2 seconds

motor(s) l_shoulder_y goto position -40 In 2 seconds

wait 2 secs

motor(s) r_shoulder_y goto position 0 In 2 seconds

motor(s) l_shoulder_y goto position 0 In 2 seconds

motor(s) r_shoulder_x goto position -20 In 2 seconds

motor(s) l_shoulder_x goto position 20 In 2 seconds