



# Mini-Project (ML for Time Series) - MVA

## 2023/2024

Machine Learning for Time Series

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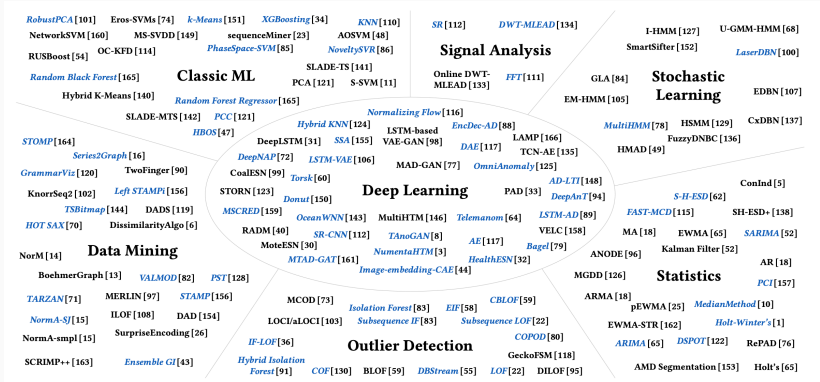
# Introduction

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We studied **Anomaly Detection in Time Series: A Comprehensive Evaluation** by Schmidl, Wenig et al. [12].

**An anomaly** in a time series refers to an instant or a sequence of instants that deviate from the regular patterns of the series.

# Introduction



**Figure 1:** All 158 collected anomaly detection methods by [12] for time series data structured by their method family. Methods directly evaluated in [12] are highlighted in blue italics.

# Introduction

- Chose a handful of the presented methods.
- Tested them on datasets of our choice to verify the paper's conclusions.
- Adjusted model's parameters and observed their influence on its performance.
- Tried to tweak the methods and find improvements.

## Method

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# Method: preliminaries

## Notations

We denote by  $x = \{x[1], \dots, x[N]\} \in \mathbb{R}^N$  a time series with  $x[t]$ ,  $t \in \{1, \dots, N\}$  a value at a specific timestamp

## Performances evaluation

$$\text{Precision} = \frac{TP}{TP+FP} \quad \text{Recall} = \frac{TP}{TP+FN} \quad \text{Expectancy} = \frac{FP}{TN+FP}$$

**AUC-ROC:** area under the ROC curve where the x-axis is the Precision and the y-axis is the Expectancy

**AUC-PR:** area under the precision-recall curve where the x-axis is the Precision and the y-axis is the Recall



## Method: Median method (1)

### Median method [2]

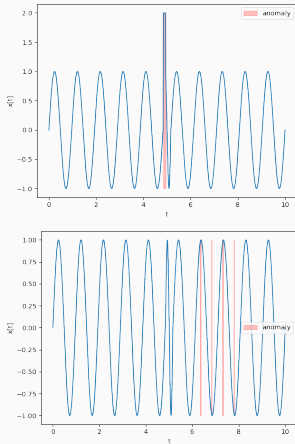
We let  $\gamma[t] = \{x[t - \kappa], \dots, x[t - 1], x[t + 1], \dots, x[t + \kappa]\}$  for  $t \in \{\kappa + 1, N - \kappa\}$  a neighborhood of points of size  $2\kappa$

$$|x[t] - \text{med}(\gamma[t])| > \tau \sigma(\gamma[t])$$

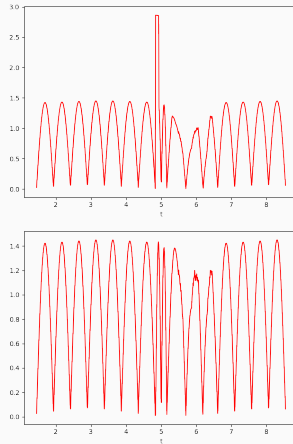
where  $\text{med}(\cdot)$  is the median,  $\sigma(\cdot)$  the standard deviation and  $\tau$  a threshold.

# Method: Median method (2)

## Example: Median method



Anomalies detected



Anomaly scores

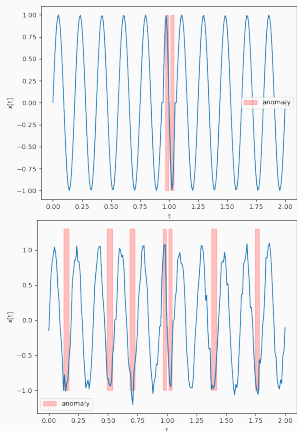
Figure 2: Anomaly detection using the Median method

### Fourier Transform Based Spatial Outlier Mining (FFTBSOM) [9]

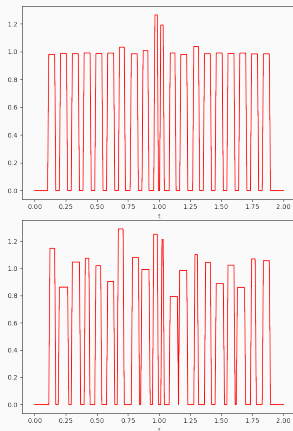
1. Apply a low-pass filter on the signal, giving  $\hat{x}$
2. Compute  $s[t] = |\hat{x}[t] - x[t]|$  for each data point
3. If  $s[t] > \tau_1$ , with  $\tau_1$  a threshold, store  $s[t]$  as a potential local outlier
4. If  $(s[t] - \mu(s))/\sigma(s) > \tau_2$  with  $\tau_2$  another threshold, store  $s[t]$  as a local outlier
5. If  $\text{sign}(s[t]) \neq \text{sign}(s[t + 1])$  return  $s[t]$  and  $s[t + 1]$  as outliers

# Method: FFTBSOM (2)

## Example: FFTBSOM



Anomalies detected



Anomaly scores

Figure 3: Anomaly detection using FFTBSOM

# Method: Spectral Residual (1)

## Spectral Residual [10]

Fourier Transform :  $A(f) = \text{Amplitude}(\mathfrak{F}(x))$  ,  $P(f) = \text{Phase}(\mathfrak{F}(x))$

Spectral Residual :  $R(f) = \log A(f) - \overline{\log A(f)}$

Saliency Map :  $S(x) = \|\mathfrak{F}^{-1}(\exp(R(f) + iP(f)))\|$

Scoring is computed through the local relative amplitude :

$$O(x_i) = \frac{S(x_i) - \overline{S(x_i)}}{\overline{S(x_i)}}$$

## Method: Spectral Residual (2)

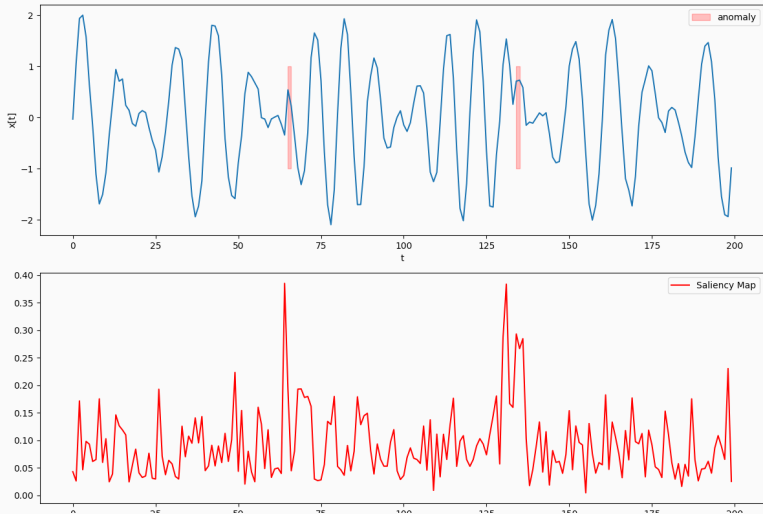


Figure 4: The Saliency Map against a signal and its anomalies

# Method: Phase Space SVM

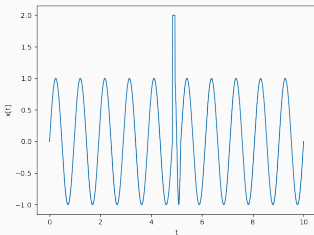
## Phase Space SVM (1) [8]

Let

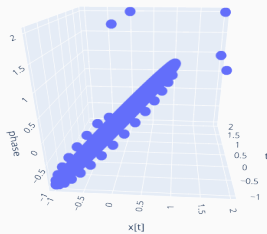
$$K : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}^+ \quad (1)$$

$$(x, y) \mapsto \langle \phi(x), \phi(y) \rangle \quad (2)$$

a kernel and  $\phi : \mathbb{R} \rightarrow \mathcal{X}$  a feature map. We first unfold the time series using a time-delay embedding process <sup>1</sup>



An arbitrary time series



The time series and its vector set in the phase space

<sup>1</sup>Packard, N. H., Crutchfield, J. P., Farmer, J. D., Shaw, R. S. (1980). Geometry from a time series. Physical review letters, 45(9), 712.

## Method: Phase Space SVM (2)

We then want to solve the one-class SVM problem

$$\begin{aligned} \arg \min_{\mathbf{w}, \rho, \xi} \quad & \|\mathbf{w}\|_2^2 + \frac{1}{\nu(N-d)} \sum_{i=1}^{N-d} \xi_i - \rho \\ \text{s.t.} \quad & \langle \mathbf{w}, \phi(S_d[i]) \rangle \geq \rho - \xi_i \\ & \xi_i \geq 0, \quad i = 1, \dots, N-d \end{aligned}$$

where  $S_d[i]$  is the shifted time series,  $\nu$  is a hyperparameter for the training error and fraction of support vectors,  $\xi_i$  are slack variables and  $\rho$  is the threshold. The dual can be shown to be <sup>2</sup>

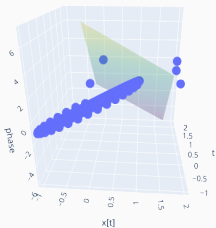
$$\begin{aligned} \arg \min_{\alpha} \quad & \frac{1}{2} \alpha^T K \alpha \\ \text{s.t.} \quad & \|\alpha\|_1 = 1 \\ & 0 \leq \alpha_i \leq \frac{1}{\nu(N-d)}, \quad i = 1, \dots, N-d \end{aligned}$$

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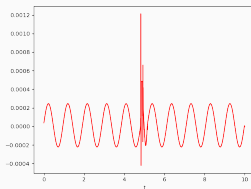
<sup>2</sup>Schölkopf, B., Williamson, R. C., Smola, A., Shawe-Taylor, J., Platt, J. (1999). Support vector method for novelty detection. Advances in neural information processing systems, 12.



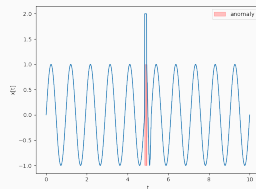
## Method: Phase Space SVM (3)



Hyperplane of the  
one-class SVM (linear  
kernel)



Anomaly scores



Anomalies detected

*Note: in practice we use a Gaussian kernel.*

## Scalable Time series Anytime Matrix Profile Incremental [14]

Solve the all-pair-similarity-search problem :

$$\theta_{1nn} : \mathbf{A} \times \mathbf{B} \longrightarrow \{0, 1\}$$

$$(A[i], B[j]) \longmapsto \begin{cases} 1 & \text{if } B[j] \text{ is the closest neighbor to } A[i] \text{ in } B \\ 0 & \text{otherwise} \end{cases}$$

The Matrix Profile  $\mathbf{P}_{AB}$  is then defined as the vector of Euclidean distances between each pair of sub-sequences in  $\mathbf{A} \bowtie_{\theta_{1nn}} \mathbf{B}$ .

Thus, consider the scoring  $\mathbf{P}_{AA}$  for

$$\mathbf{A} \bowtie_{\theta_{1nn}} \mathbf{A} \text{ with } \mathbf{A} = \{x[i : i + m] \mid 0 \leq i \leq |x| - m\}$$

## Method : STAMPi (2)

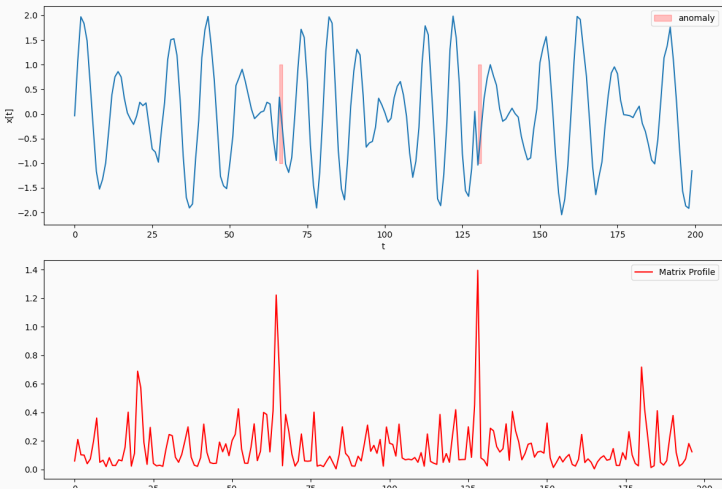


Figure 7: The Matrix Profile against a signal and its anomalies

# Method: Sub-LOF (1)

## Subsequence Local Outlier Factor [4]

Let  $d : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}^+$  a distance and  $z$  an arbitrary point

- $N_k(z) = \{p \in \mathbb{R} \mid d(z, p) \leq k - \text{distance}(z)\}$
- $RD_k(z, p) = \max(k - \text{distance}(p), \text{distance}(z, p))$  where  $p \in \mathbb{R}$  is an arbitrary point
- $LRD_k(z) = 1 / \left( \frac{\sum_{p \in N_k(z)} RD_k(z, p)}{|N_k(z)|} \right)$
- $LOF_k(z) = \frac{\sum_{p \in N_k(z)} \frac{LRD(p)}{LRD(z)}}{|N_k(z)|}$
- $z$  is an outlier if  $LOF_k(z) > 1$

To apply Sub-LOF to time series, we split them into sequences.

# Method: DWT\_MLEAD (1)

## Discrete Wavelet Transform MLE Anomaly Detection [13]

- Compute DWT for levels  $l \in \{l_0, \dots, L\}$ ,  $L = \log_2(m)$ ,  $m = 2^{\lceil \log_2(|x|) \rceil}$
- Sliding a window of size  $\omega$  to get  $\mathbf{D}^{(l)} = \begin{pmatrix} d_{1,l} & \dots & d_{\omega,l} \\ \vdots & \vdots & \vdots \\ d_{2^l-\omega+1,l} & \dots & d_{2^l,l} \end{pmatrix}$
- For each  $\mathbf{D}^{(l)}$  and  $\mathbf{C}^{(l)}$  compute MLE estimators of  $(\mu, \Sigma)$  for a Gaussian distribution. Associate the likelihood to each row of the matrices.

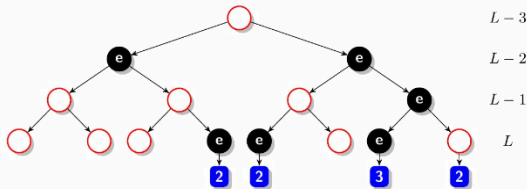


Figure 8: Leaf counters for anomalies [13]

## Method: DWT\_MLEAD (2)

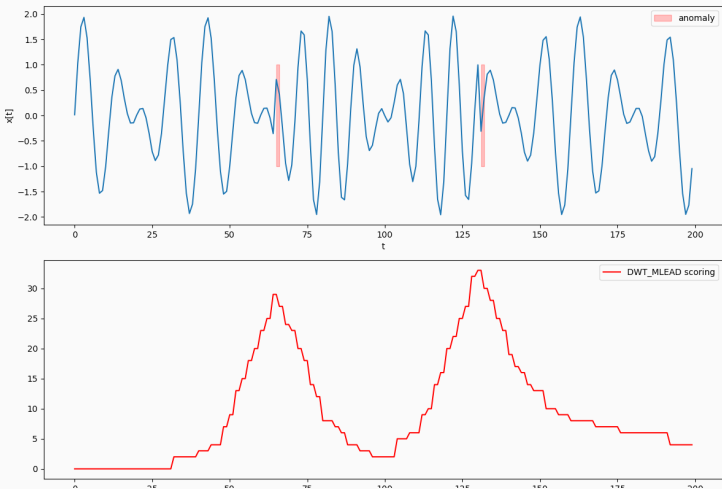


Figure 9: Example of anomaly detection with **DWT\_MLEAD**

# Data

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As the article is a survey, we use the dataset provided by the authors for accurate comparison:

- Dodges [7]: real data
- NAB [1]: real and synthetic data
- NASA-MSL, NASA-SMAP [6]: real and synthetic data
- NormA [3]: real and synthetic data



## Results

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## Results: Median method (1)

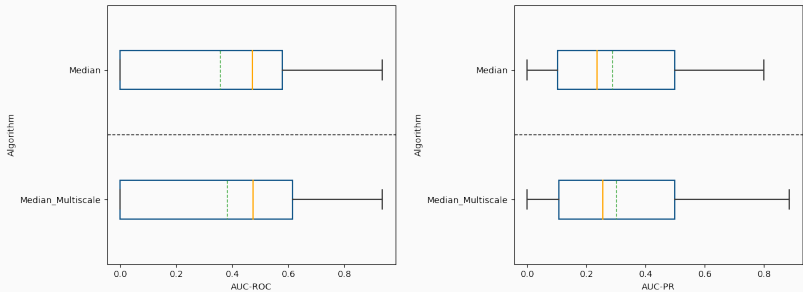
Instead of using only one window

$\gamma_\kappa[t] = \{x[t - \kappa], \dots, x[t - 1], x[t + 1], \dots, x[t + \kappa]\}$ , we try using three such that

$$\gamma[t] = \frac{\gamma_\kappa[t] + \gamma_{2\kappa}[t] + \gamma_{3\kappa}[t]}{3}$$

to have a multiscale view of the signal.

## Results: Median method (2)



AUC-ROC obtained on the datasets

AUC-PR obtained on the datasets

**Figure 10:** Results obtained with the Median method by using a multiscale version

## Results: FFTBSOM (1)

The algorithm is sensitive to noise. We can denoise the signal by using

- Moving average:

$$x[t] = \frac{x[t - k/2] + \dots + x[t] + \dots + x[t + k/2 - 1]}{k}$$

- Dictionary learning [5, 11]:

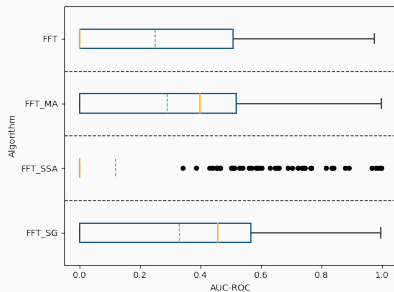
$$\arg \min_z \frac{1}{2} \|x - Dz\|_2^2 + \lambda \|z\|_1$$

- Savitzky-Golay <sup>3</sup>: polynomial regression within a frame on the signal

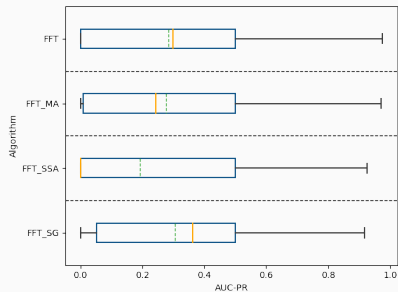
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<sup>3</sup>Savitzky, A., Golay, M. J. (1964). Smoothing and differentiation of data by simplified least squares procedures. Analytical chemistry, 36(8), 1627-1639.

## Results: FFTBSOM (2)



AUC-ROC obtained on the datasets



AUC-PR obtained on the datasets

**Figure 11:** Results obtained with FFTBSOM by smoothing the data

## Results: Spectral Residual

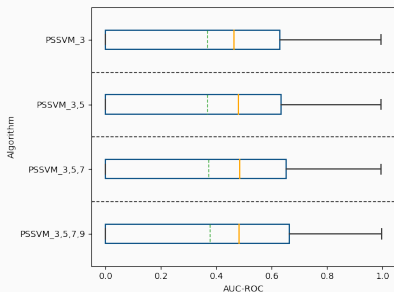
All three parameters  $\omega$ ,  $m$  and  $z$  are window size parameters.  
Only  $z$  proved to have a significant global influence on our dataset.

Value of $z$	ROC AUC	PR AUC
3	0.47	0.13
23	0.50	0.17
43	0.50	0.19
63	<b>0.51</b>	<b>0.20</b>

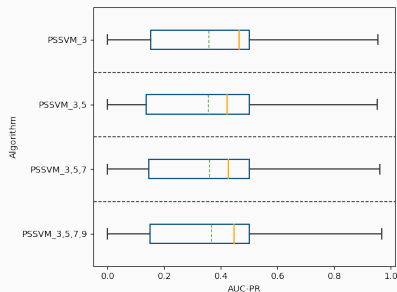
**Table 1:** Means obtained for different values of the score window size,  $z$ , in the Spectral Residual algorithm.

# Results: Phase Space SVM

We average the scores over the phase space



AUC-ROC obtained on the datasets

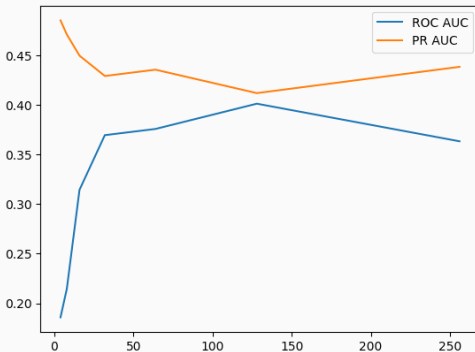


AUC-PR obtained on the datasets

**Figure 12:** Results obtained with PS-SVM by using different time-delay embeddings

## Results: STAMPi

The model exhibits a single parameter  $m$ , the length of the subsequences to compare.



**Figure 13:** Means of the performance scores obtained for different values of the subsequence length,  $m$ , in the STAMPi algorithm.



The method offers to fit a Gaussian distribution: What about other distributions?

Heavy tail vs Light tail :

Method / Score	ROC AUC	PR AUC
DWT	<b>0.78</b>	<b>0.50</b>
DWT-Laplace	0.76	<b>0.50</b>
DWT-T <sub>19</sub>	0.77	<b>0.50</b>

**Table 2:** Medians obtained for the different distributions used

## Results: Sub-LOF (1)

Due to the complexity ( $\mathcal{O}(n^2)$ ) of the algorithm, the algorithm is not scalable with custom metrics on Python.

We try three different metrics:

- DTW: measures the similarity between time series by finding an optimal matching by dynamic programming
- Soft-DTW: a differentiable version of the DTW
- Wasserstein-Fourier <sup>4</sup>

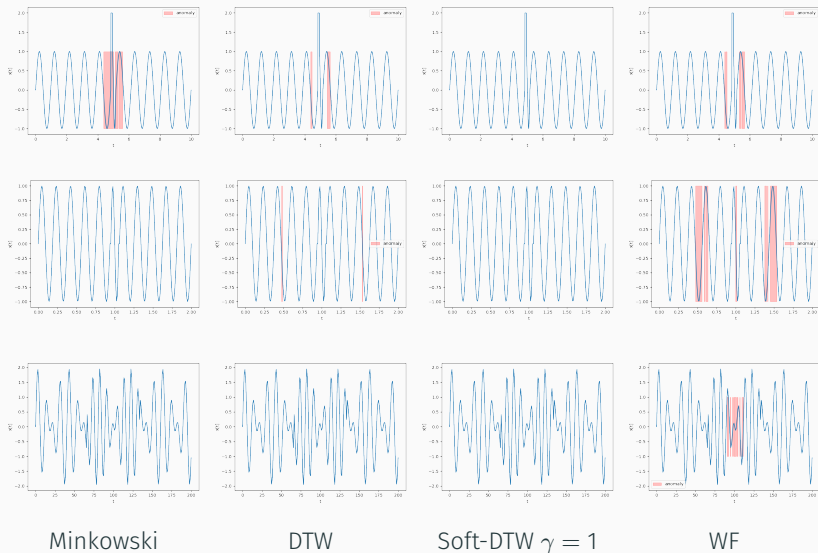
$$\mathbf{WF}_2^2(s_x, s_y) = \left( \min_{\sigma \in \mathfrak{S}_N} \sum_{i=1}^N (s_x[i] - s_y[\sigma(i)])^2 \right)$$

where  $s_x$  and  $s_y$  are the normalized power spectral density given by  $s_z(\xi) = \frac{S_z(\xi)}{\sum S_z(\xi)}$  where  $z$  is an arbitrary signal

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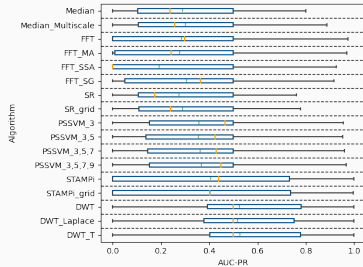
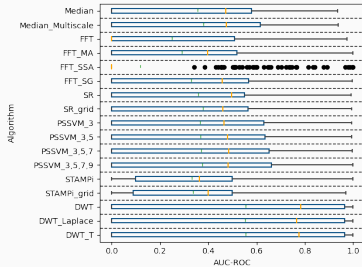
<sup>4</sup> Cazelles, E., Robert, A., Tobar, F. (2020). The Wasserstein-Fourier distance for stationary time series. IEEE Transactions on Signal Processing, 69, 709-721.

# Results: Sub-LOF



**Figure 14:** Anomaly detection on toy signals with Sub-LOF and different metrics

# Results



**Figure 15:** Boxplots performances of the algorithms and modified algorithms we used for the AUC-ROC and AUC-PR metrics. The mean value is in green and the median in orange.

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[?]

Questions?