Calibration results
====================
Camera-system parameters:
cam0 (/camera/camera/color/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [0.1716008 -0.2485906   0.01697883 -0.00805107] +- [0.00445252 0.01298834 0.00062889 0.0007571]
projection: [614.9683717 614.17089186 316.51564328 261.2937947] +- [0.93700399 0.98353406 1.04880691
0.98190997]
reprojection error: [0.000002, 0.000001] +- [0.563072, 0.795519]

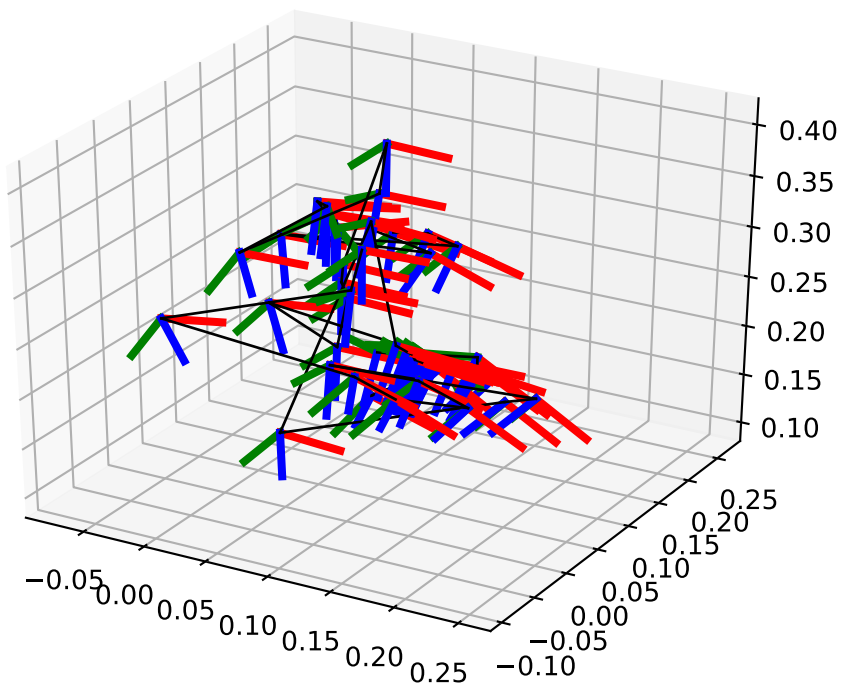Target configuration
====================
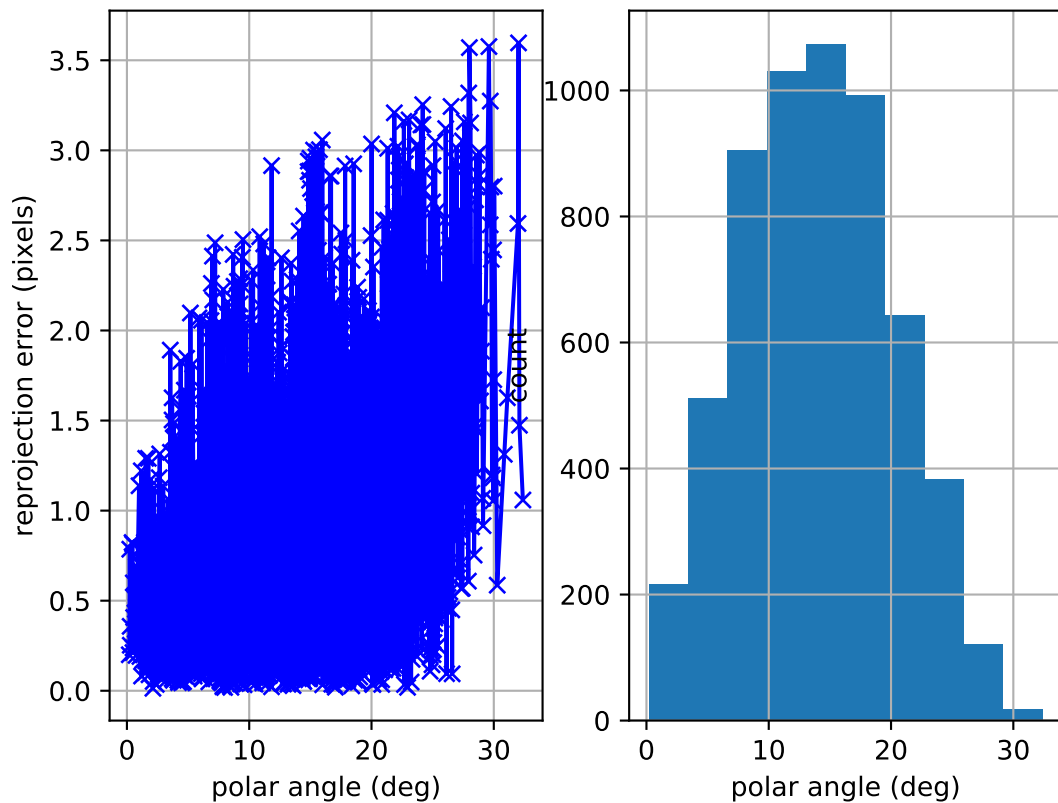
Type: aprilgrid
Tags:
Rows: 6
Cols: 6
Size: 0.0205 [m]
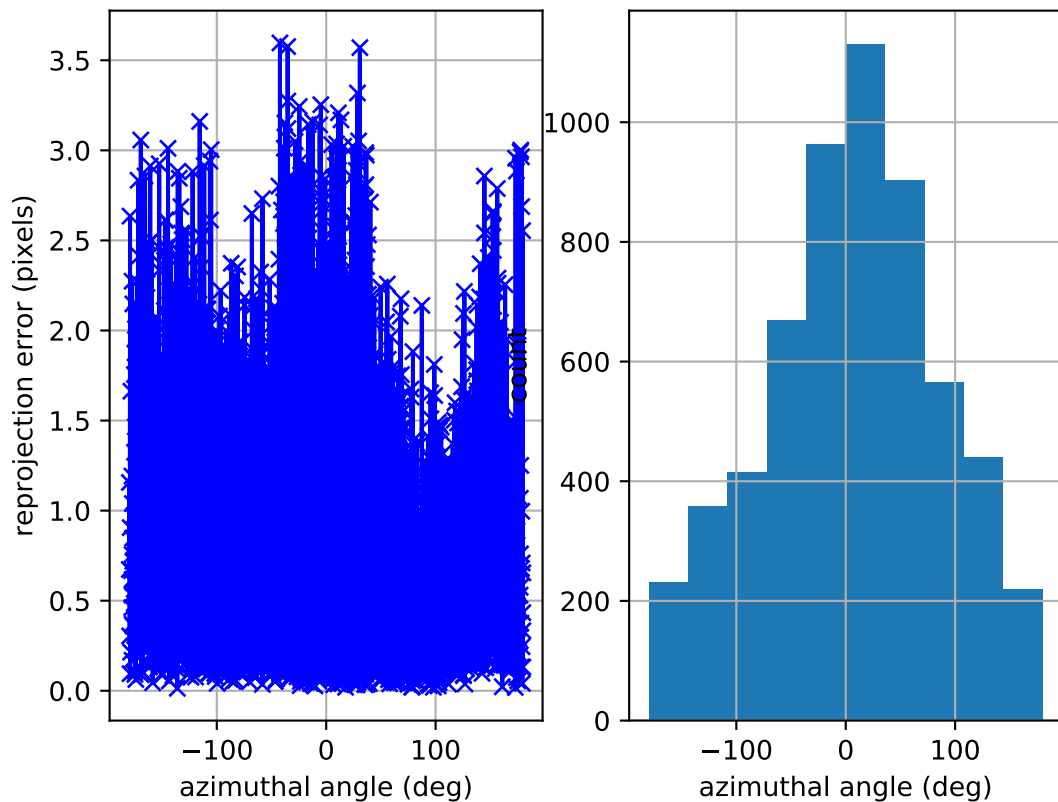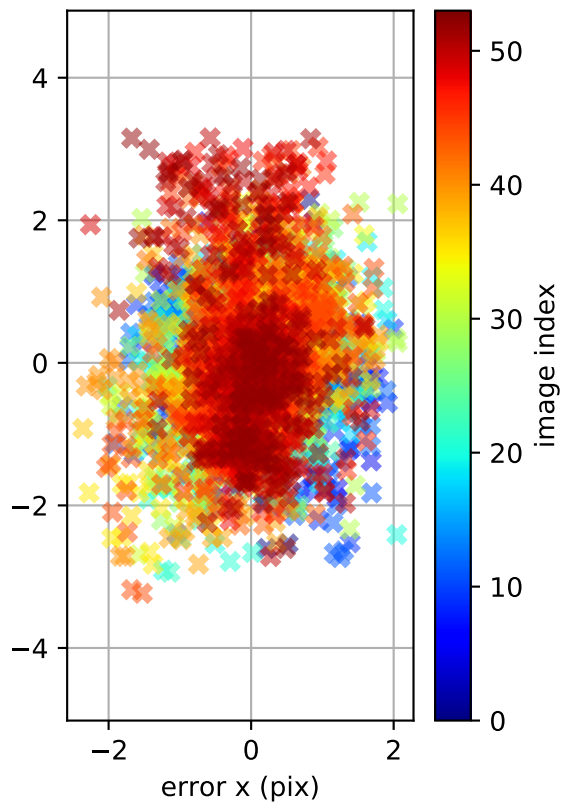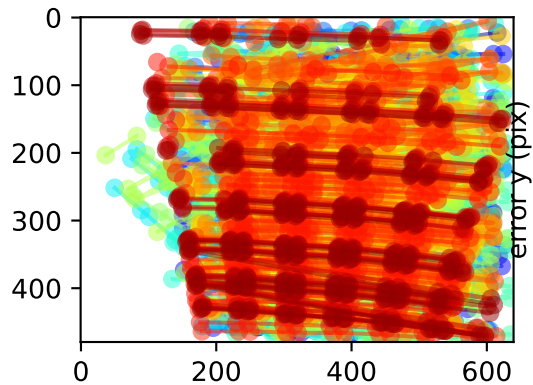Spacing 0.00630006 [m]

cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0