

## Calibration results

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### Camera-system parameters:

cam0 (/camera/camera/color/image\_raw):

type: <class 'aslam\_cv.libaslam\_cv\_python.DistortedPinholeCameraGeometry'>

distortion: [ 0.12723914 -0.17189525 0.036598 -0.00054753] +- [0.00406381 0.00995349 0.00073688 0.00063083]

projection: [610.13355594 613.58619376 322.7614325 283.97258711] +- [1.03766484 1.13086279 1.05508756 1.22248535]

reprojection error: [-0.000000, 0.000001] +- [0.573445, 0.845310]

## Target configuration

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Type: aprilgrid

Tags:

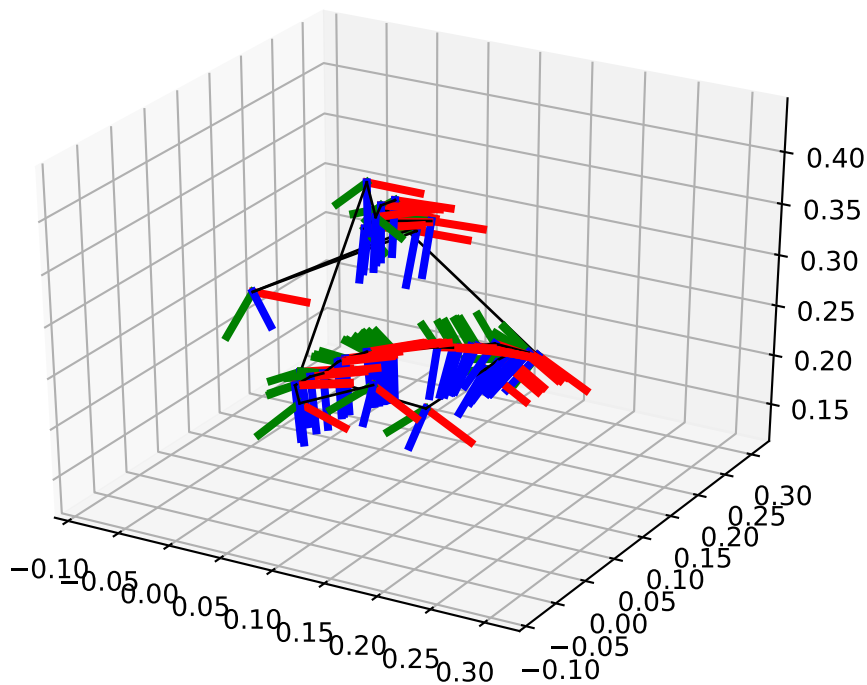
Rows: 6

Cols: 6

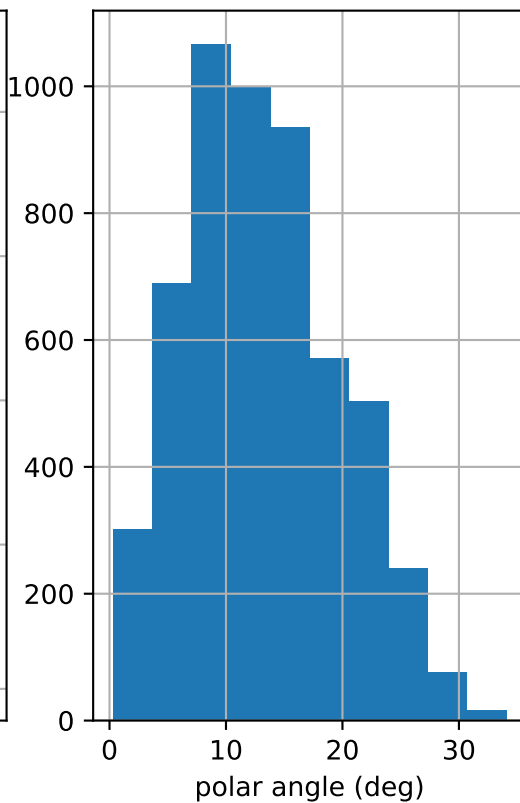
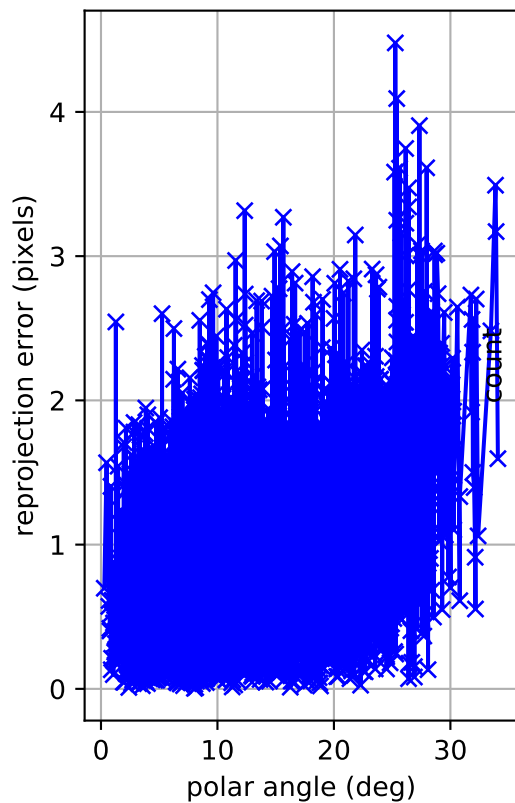
Size: 0.0205 [m]

Spacing 0.00630006 [m]

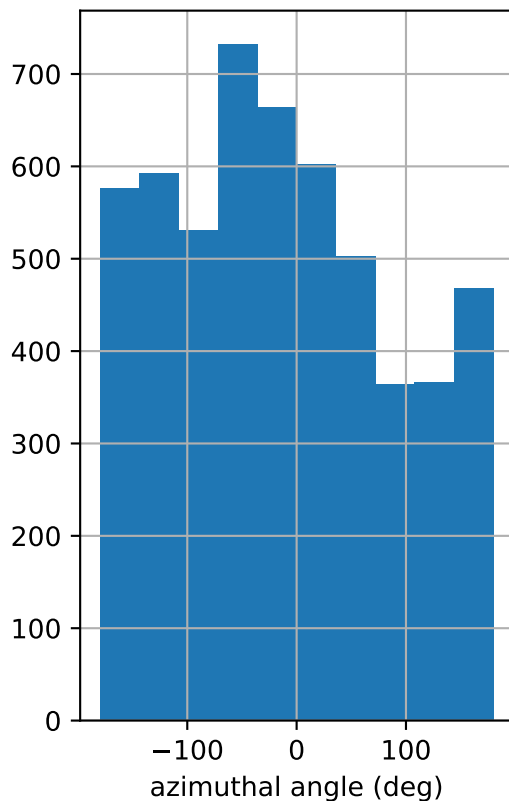
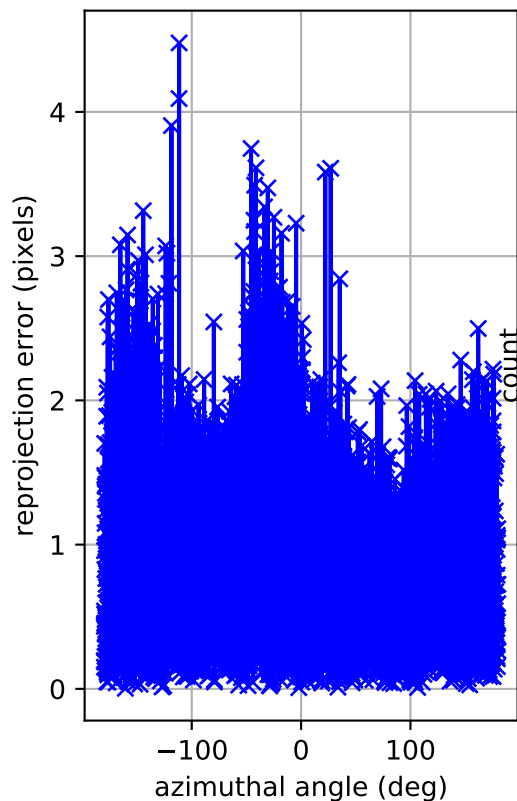
cam0: estimated poses



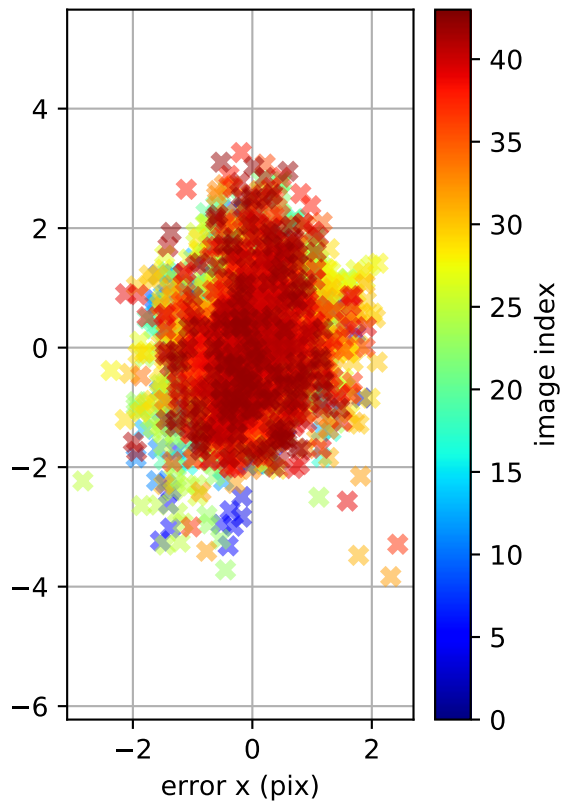
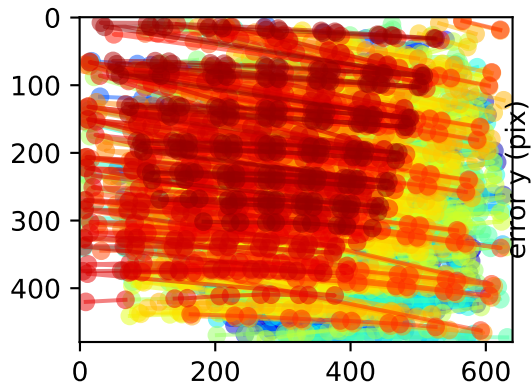
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

