

# Swift-Hohenberg on a Torus

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# Plan

- Overview of the Closest Point Method.
- Biharmonic heat equation on a sphere and a torus.
- Swift-Hohenberg equation.

# Closest Point Method

Idea: instead of discretizing surface derivatives using parametrization, we represent them by Cartesian derivatives acting on the extension of a surface quantity to the embedding space. To achieve this, data needs to be constant in normal direction.

## Gradient Principle

For points  $x$  on a smooth surface  $S$ ,  $\nabla_S u(x) = \nabla(u(cp(x)))$  because the function  $u(cp(x))$  is constant in the normal direction and therefore only varies along the surface. In other words, at points  $x$  on the surface, intrinsic surface gradients  $\nabla_S u(x)$  are the same as gradients of  $u(cp(x))$ .

Approximation of surface operators via Cartesian grid operators acting on normally extended data...

# Closest Point Extension

To obtain the normal extension, we recall that the vector connecting a point in the embedding space to its closest point on a surface is in fact normal to it.

# Stabilized Diffusion Operator

spectra of standard and stabilized operators.

# Stabilized Diffusion Operator

spy plots on sphere.

# Stability Restrictions

stability restrictions

# Convergence on the Sphere



# Swift-Hohenberg Equation

$$u_t = -\Delta^2 u - \Delta + u(P - 1)u + su^2 - u^3$$

This equation was derived by Swift and Hohenberg in 1977 to study thermal fluctuations on a fluid near the Rayleigh-Benard convective instability. The function  $u$  is the temperature field in a plane horizontal layer of fluid heated from below. The parameter  $r$  measures how far the temperature is above the minimum temperature required for convection: for  $r < 0$ , the heating is too small to cause convection, while for  $r > 0$ , convection occurs. The Swift-Hohenberg equation is an example of a PDE that exhibits pattern formation, including stripes, spots and spirals.

# Discretization




$$u_t = \underbrace{-\Delta^2 u - \Delta + u(P-1)u}_{=:Lu} + \underbrace{su^2 - u^3}_{=:Nu}$$

Linear part is very stiff, but can be inverted (-ish) - treat implicitly.  
Nonlinear part - difficult to invert, treat explicitly.

Thank you for your attention!



# References

-  The Implicit Closest Point Method for the Numerical Solution of Partial Differential Equations on Surfaces. *SIAM J. SCI. COMPUT.* 2009 *Society for Industrial and Applied Mathematics Vol. 31, No. 6*, pp. 4330-4350
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