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Estimating the autocorrelation

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Estimating the autocorrelation

The two standard ways to estimate the ACF can be expressed as

$$\hat{r}_y^u(k) = \frac{1}{N-k} \sum_{t=k+1}^N (y_t - \hat{m}_y)(y_{t-k} - \hat{m}_y)^*$$
$$\hat{r}_y^b(k) = \frac{1}{N} \sum_{t=k+1}^N (y_t - \hat{m}_y)(y_{t-k} - \hat{m}_y)^* = \frac{1}{N} \psi_k$$

for $0 \leq k \leq N-1$. Which is the better estimate?

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It can be shown that $E\{\psi_k\} \approx (N-k)(r_y(k) - V\{\hat{m}_y\})$, which implies that

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For a *zero-mean* process

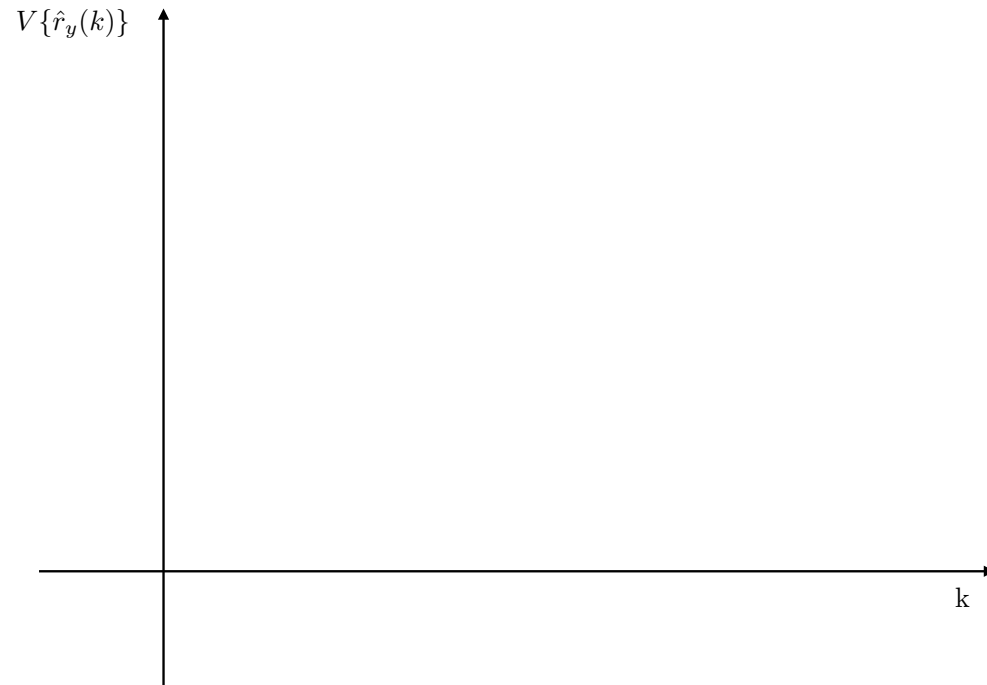
$$E\{\psi_k\} = \sum_{t=k+1}^N r_y(k) = (N-k)r_y(k)$$

In this case, this implies that

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In this case, $r_y^u(k)$ is unbiased, whereas $r_y^b(k)$ is only *asymptotically* unbiased.

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For a zero-mean white Gaussian process with variance σ_e^2 , and

$$\hat{\rho}_e(k) = \frac{\hat{r}_e(k)}{\hat{r}_e(0)}$$

where $\hat{r}_e(k)$ is the *biased* estimate of the ACF, then, for $k \neq 0$,

$$E\{\hat{\rho}_e(k)\} = 0$$

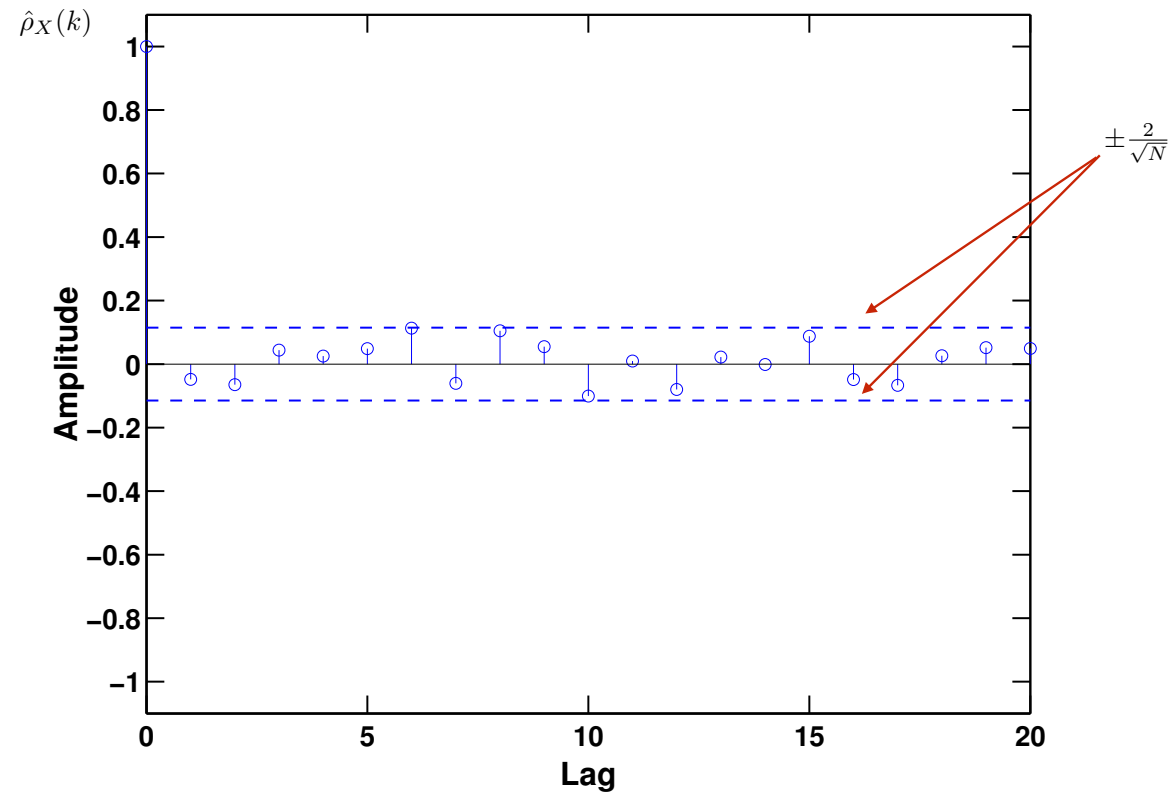
$$V\{\hat{\rho}_e(k)\} = \frac{1}{N}$$

Furthermore, $\hat{\rho}_e(k)$ is asymptotically Normal distributed for $k > 0$.

This implies that a 95% confidence interval can be formed as

$$\hat{\rho}_e(k) \approx 0 \pm \frac{2}{\sqrt{N}}$$

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As far as we can tell, this is a *white* noise. This assumes that $\hat{\rho}_e(k) \in \mathcal{N}$.

About 5% of the ACF to be (slightly) outside the confidence interval. As a rule of thumb, only estimate $r_y(k)$ for lags up to (at most) $N/4$.

Testing the model



Is the residual white?