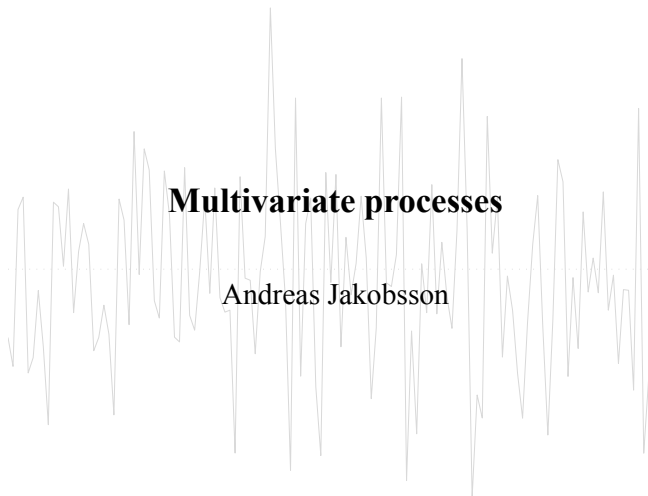


Multivariate processes

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VARMAX processes

In many applications, one may estimate many forms of data simultaneously, such that ones measurements are of the form

$$\mathbf{z}_t = \begin{bmatrix} z_{t,1} & \dots & z_{t,m} \end{bmatrix}^T$$

For such measurements, one generally wish to take the data from all m sources into account simultaneously. To do this, we introduce the notion of an m -dimensional stochastic process, \mathbf{z}_t .



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The mean of the process is given as

$$\mathbf{m}_s = E\{\mathbf{z}_t\} = \begin{bmatrix} E\{z_{t,1}\} & \dots & E\{z_{t,m}\} \end{bmatrix}^T$$

The covariance (matrix) function for the vector process is defined as

$$\begin{aligned} \mathbf{R}_s(k) &= C\{\mathbf{z}_t, \mathbf{z}_{t-k}\} \\ &= E\{[\mathbf{z}_t - \mathbf{m}_s][\mathbf{z}_{t-k} - \mathbf{m}_s]^*\} \\ &= \mathbf{R}_s^*(k) \end{aligned}$$

The notion of a white noise is formed as

$$\mathbf{R}_s(k) = \begin{cases} \Sigma_s & k = 0 \\ \mathbf{0} & k \neq 0 \end{cases}$$

If the process is also uncorrelated among data sources, $\Sigma_s = \mathbf{I}$. This is called a *doubly white* process.



VARMAX processes

The multivariate, or vector, ARMAX (VARMAX) process is defined as

$$\mathbf{A}(z)\mathbf{y}_t = \mathbf{B}(z)\mathbf{x}_{t-d} + \mathbf{C}(z)\mathbf{e}_t$$

where $\mathbf{A}(z)$ and $\mathbf{C}(z)$ are monic $(m \times m)$ matrix polynomials of order p and q , respectively, $\mathbf{B}(z)$ is a $(m \times s)$ matrix polynomial of order r , and \mathbf{x}_{t-d} is a d -step delayed s -dimensional exogenous input signal, i.e.,

$$\begin{aligned} \mathbf{A}(z) &= \mathbf{I} + \mathbf{A}_1 z^{-1} + \dots + \mathbf{A}_p z^{-p} \\ \mathbf{B}(z) &= \mathbf{B}_0 + \mathbf{B}_1 z^{-1} + \dots + \mathbf{B}_r z^{-r} \\ \mathbf{C}(z) &= \mathbf{I} + \mathbf{C}_1 z^{-1} + \dots + \mathbf{C}_q z^{-q} \end{aligned}$$

and \mathbf{e}_t is a multivariate zero-mean white noise process with variance Σ_s . To ensure stability, we require that all roots of $\det\{\mathbf{A}(z)\} = 0$, with respect to z , lie within the unit circle.

Excluding some parts yields the VMA, VAR, VARMA, etc, models.



VARMAX processes

Example:

Consider a first-order vector MA (VMA) process $\mathbf{y}_t = \mathbf{C}(z)\mathbf{e}_t$, where $\mathbf{C}(z) = \mathbf{I} + \mathbf{C}_1 z^{-1}$, with \mathbf{e}_t being a multivariate zero-mean white noise process with covariance matrix Σ_e . Then,

$$\begin{aligned}\mathbf{R}_y(k) &= C \{ \mathbf{y}_t, \mathbf{y}_{t-k} \} \\ &= E \left\{ (\mathbf{e}_t + \mathbf{C}_1 \mathbf{e}_{t-1}) (\mathbf{e}_{t-k} + \mathbf{C}_1 \mathbf{e}_{t-k-1})^* \right\} \\ &= \begin{cases} \Sigma_e + \mathbf{C}_1 \Sigma_e \mathbf{C}_1^* & k = 0 \\ \mathbf{C}_1 \Sigma_e & k = 1 \\ \Sigma_e \mathbf{C}_1^* & k = -1 \\ \mathbf{0} & |k| > 1 \end{cases}\end{aligned}$$

Note that $\mathbf{R}_y(1) = \mathbf{R}_y^* - 1$ and that $\mathbf{R}_y(k)$ is zero after lag one.



VARMAX processes

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Example:

Consider a first-order VAR process $\mathbf{A}(z)\mathbf{y}_t = \mathbf{e}_t$, where $\mathbf{A}(z) = \mathbf{I} + \mathbf{A}_1 z^{-1}$, with \mathbf{e}_t being a zero-mean white noise process with covariance matrix Σ_e . Then,

$$\begin{aligned}\mathbf{R}_y(k) &= C \{ \mathbf{y}_t, \mathbf{y}_{t-k} \} \\ &= E \left\{ (\mathbf{e}_t - \mathbf{A}_1 \mathbf{y}_{t-1}) \mathbf{y}_{t-k}^* \right\} \\ &= E \left\{ \mathbf{e}_t \mathbf{y}_{t-k}^* \right\} - \mathbf{A}_1 E \left\{ \mathbf{y}_{t-1} \mathbf{y}_{t-k}^* \right\} \\ &= \begin{cases} \Sigma_e - \mathbf{A}_1 \mathbf{R}_y(-1) & k = 0 \\ -\mathbf{A}_1 \mathbf{R}_y(k-1) & k > 0 \end{cases} \\ &= \begin{cases} \Sigma_e - \mathbf{A}_1 \mathbf{R}_y(-1) & k = 0 \\ (-\mathbf{A}_1)^k \mathbf{R}_y(0) & k > 0 \end{cases}\end{aligned}$$

Thus,

$$\Sigma_e = \mathbf{R}_y(0) + \mathbf{A}_1 \mathbf{R}_y(-1) = \mathbf{R}_y(0) - \mathbf{A}_1 \mathbf{R}_y(0) \mathbf{A}_1^*$$



VARMAX processes

The autocorrelation matrix is formed as

$$\rho_x(k) = \mathbf{P}_x^{-1/2} \mathbf{R}_x(k) \mathbf{P}_x^{-1/2}$$

where

$$\mathbf{P}_x = \text{diag} \left\{ \begin{bmatrix} \mathbf{R}_x(0) \end{bmatrix}_{1,1} \quad \dots \quad \begin{bmatrix} \mathbf{R}_x(0) \end{bmatrix}_{m,m} \right\}$$

with $\text{diag} \{ \mathbf{x} \}$ denoting the diagonal matrix formed with the vector \mathbf{x} along the diagonal.

$k = 1$	$k = 2$	$k = 3$	$k = 4$
$\rho_y(k) \begin{bmatrix} -0.67 & -0.36 \\ 0.31 & -0.57 \end{bmatrix}$	$\begin{bmatrix} 0.41 & 0.50 \\ -0.43 & -0.08 \end{bmatrix}$	$\begin{bmatrix} -0.14 & -0.37 \\ 0.33 & 0.43 \end{bmatrix}$	$\begin{bmatrix} 0.00 & 0.13 \\ -0.13 & -0.38 \end{bmatrix}$
$\begin{bmatrix} - & - \\ + & - \end{bmatrix}$	$\begin{bmatrix} + & + \\ - & + \end{bmatrix}$	$\begin{bmatrix} - & + \\ - & + \end{bmatrix}$	$\begin{bmatrix} . & + \\ - & - \end{bmatrix}$

Example with $\pm 2/\sqrt{N} \approx \pm 0.063$.

We can use the ACF and the PACF for identification! The latter is formed using the multivariate Yule-Walker equations.



A useful trick

An often useful result when working with multivariate processes is that

$$\text{vec} \{ \mathbf{ABC} \} = (\mathbf{C}^T \otimes \mathbf{A}) \text{vec} \{ \mathbf{B} \}$$

Example:

$$\text{vec} \left\{ \begin{bmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{bmatrix} \right\} = \begin{bmatrix} x_{11} \\ x_{21} \\ x_{12} \\ x_{22} \end{bmatrix}$$

Example:

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \otimes \begin{bmatrix} 0 & 5 & 1 \\ 6 & 7 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 5 & 1 & 0 & 10 & 2 \\ 6 & 7 & 0 & 12 & 14 & 0 \\ 0 & 15 & 3 & 0 & 20 & 4 \\ 18 & 21 & 0 & 24 & 28 & 0 \end{bmatrix}$$

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Thus, we may express

$$\Sigma_e = \mathbf{R}_y(0) - \mathbf{A}_1 \mathbf{R}_y(0) \mathbf{A}_1^*$$

as

$$\begin{aligned} \text{vec}\{\Sigma_e\} &= \text{vec}\{\mathbf{R}_y(0)\} - \text{vec}\{\mathbf{A}_1 \mathbf{R}_y(0) \mathbf{A}_1^*\} \\ &= \text{vec}\{\mathbf{R}_y(0)\} - (\bar{\mathbf{A}}_1 \otimes \mathbf{A}_1) \text{vec}\{\mathbf{R}_y(0)\} \\ &= [\mathbf{I} - \bar{\mathbf{A}}_1 \otimes \mathbf{A}_1] \text{vec}\{\mathbf{R}_y(0)\} \end{aligned}$$

where $\bar{\mathbf{A}}$ denotes the conjugate of \mathbf{A} .

A useful trick

Example:

Consider a first-order VAR process with $\Sigma_e = \mathbf{I}$ and

$$\mathbf{A}_1 = \begin{bmatrix} 0.5 & 0.4 \\ 0.1 & 0.8 \end{bmatrix}$$

As

$$\det(\mathbf{I} + \mathbf{A}_1 z^{-1}) = 1 + 1.3z^{-1} + 0.36z^{-2} = 0$$

has the roots $z_1 = -0.9$ and $z_2 = -0.4$, which both lie within the unit circle, the process is stable.

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$$\mathbf{R}_y(0) = \begin{bmatrix} r_{11} & r_{12} \\ r_{21} & r_{22} \end{bmatrix}$$

it holds that

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} r_{11} & r_{12} \\ r_{21} & r_{22} \end{bmatrix} - \begin{bmatrix} 0.5 & 0.4 \\ 0.1 & 0.8 \end{bmatrix} \begin{bmatrix} r_{11} & r_{12} \\ r_{21} & r_{22} \end{bmatrix} \begin{bmatrix} 0.5 & 0.1 \\ 0.4 & 0.8 \end{bmatrix}$$

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or, using $\text{vec}(\Sigma_e) = [\mathbf{I} - \bar{\mathbf{A}}_1 \otimes \mathbf{A}_1] \text{vec}\{\mathbf{R}_y(0)\}$

$$\begin{bmatrix} 0.75 & -0.20 & -0.20 & -0.16 \\ -0.05 & 0.60 & -0.04 & -0.32 \\ -0.05 & -0.04 & 0.60 & -0.32 \\ -0.01 & -0.08 & -0.08 & 0.36 \end{bmatrix} \begin{bmatrix} r_{11} \\ r_{21} \\ r_{12} \\ r_{22} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

yielding

$$\mathbf{R}_y(0) = \begin{bmatrix} 3.6028 & 2.6355 \\ 2.6355 & 4.0492 \end{bmatrix}$$

$$\mathbf{R}_y(k) = (-1)^k \begin{bmatrix} 0.5 & 0.4 \\ 0.1 & 0.8 \end{bmatrix}^k \begin{bmatrix} 3.6028 & 2.6355 \\ 2.6355 & 4.0492 \end{bmatrix}$$

It is worth noting that, as expected, $r_{12} = r_{21}$.