# Synchronization Graphs

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#### 1 Introduction

In this we examine parsing streams of tagged vertices into a canonical synchronization graph.

## 2 Background

**Definition 1** (Dependency Relation). A dependency relation  $D \subseteq \Sigma \times \Sigma$  is a *symmetric* and *reflexive* relation on  $\Sigma$ .

Likewise an independence relation of D can be defined as the relative complement  $I = (\Sigma \times \Sigma) \setminus D$ .

Dependency relations are a general way of talking about equivalence relations between two streams of data  $S_1, S_2 \in \Sigma^*$ , where we say  $S_1 \equiv_D S_2$  if  $S_2$  can be reached from  $S_1$  (and vice versa) by appling permutations based on the independence relation I.

**Definition 2** (Tree Dependence Relation). A tree dependence relation  $T \subseteq \Sigma \times \Sigma$  is a dependence relation such that  $(\Sigma, T)$  induces a graph with vertices  $\Sigma$  and edges T that forms a tree with a distinguished root  $\sigma_{\top}$ . Define the predecessor function with respect to this rooting, with  $\mathbf{pred}(\sigma_{\top}) = \sigma_{\top}$ ; recursively define the depth function  $\mathbf{depth}(\sigma_{\top}) = 0$  and  $\mathbf{depth}(\sigma) = 1 + \mathbf{depth}(\mathbf{pred}(\sigma))$ .

We define a *synchronization graph*, which is intended to model data streams that (1) are equipped with a dependence relationship and (2) have "synchronizing" (also: visibly pushdown / parallel / end-marker'd) behavior.

**Definition 3** (Synchronization Graph). A synchronization graph G is a directed acyclic graph with a unique source (top) vertex  $\vee G$  and a unique sink (bot) vertex  $\wedge G$ . Recursively define G as follows:

- i. (Base Case): A single vertex is a syncrhonization graph.
- ii. (Sequential Concatenation): If  $G_1$  and  $G_2$  are synchronization graphs, then  $G = G_1 \cdot u \cdot G_2$  is also a synchronization graph for a new vertex u, where

$$(\land G_1, u), (u, \lor G_2) \in G, \qquad \lor G = \lor G_1, \qquad \land G = \land G_2$$

iii. (Parallel Union): If  $G_1$  and  $G_2$  are synchronization graphs, then  $G = u[G_1||G_2]v$  is also a synchronization graph for new vertices u, v where

$$(u, \vee G_1), (u, \vee G_2), (\wedge G_1, v), (\wedge G_2, v) \in G, \qquad \vee G = u, \qquad \wedge G = v$$

Note that synchronization graphs induce a natural partial order:  $u \leq v$  if either (1) u = v or (2) v is reachable from u.

## 3 A Parsing Problem

In this problem setting, we are given:

- i. A tree dependency relation T and its alphabet  $\Sigma$
- ii. A sequence of vertices  $v_1, v_2, \ldots$  each labeled with an element of  $\Sigma$ : that is,  $\tau(v_i) \in \Sigma$  for all i. This sequence is a linearization of a stream satisfying T.

The task is to generate a *canonical* synchronization graph.

#### 4 A Basic Algorithm

A basic algorithm we have is to iteratively grow G. Let  $\mathbf{next}()$  return the next vertex in the stream; iteratively keeping track of a *frontier* of leaf vertices L, every new vertex v has one of three possibilities:

- 1. It depends on exactly one  $l \in L$ .
- 2. It depends on more than one  $M \subseteq L$ . Furthermore,  $\operatorname{depth}(\tau(m)) < \operatorname{depth}(\tau(v))$  for all  $m \in M$ . In this case v acts as a common "synchronization point" for M.
- 3. v is independent with all of L, in which case the most recent dependency of v, written  $u^* = \bigvee \{u \in G : \tau(u)T\tau(v)\}$  is found and v appends to this.

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Parsing Linearized Stream 1: Algorithm
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**Lemma 3.** At the each iteration, (V, E) respects T.

*Proof.* TODO: Also something about induction

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Precondition: data stream S begins and ends with a vertex labeled \sigma_{\top}
Initialize L \to \emptyset
Initialize (V, E) \leftarrow (\emptyset, \emptyset).
Pop the first v \leftarrow \mathbf{next}() and set V \leftarrow \{v\}.
while v \leftarrow \mathbf{next}() succeeds do
    Let M = \{l \in L : \tau(l)T\tau(v)\}\ V \leftarrow V \cup \{v\}
    if M = \{l\} then
         E \leftarrow E \cup \{(l, v)\}
         L \leftarrow (L \setminus \{l\}) \cup \{v\}
    else if |M| > 1 then
         E \leftarrow E \cup \{(m, v) : m \in M\}
         L \leftarrow (L \setminus M) \cup \{v\}
    else
         u^* = \bigvee \{ u \in V : \tau(u) T \tau(v) \}
         E \leftarrow E \cup \{(u^\star, v)\}
        L \leftarrow L \cup \{v\}
return G = (V, E)
Lemma 1. Two streams that are T-equivalent have the same decomposition under Algorithm 1.
Proof. TODO
                                                                                                                              Lemma 2. At each iteration of the algorithm, there is at most one l \in L such that \operatorname{depth}(\tau(l)) =
\operatorname{depth}(\tau(v)) and \tau(l)T\tau(v).
                                                                                                                              Proof. TODO: something about induction
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