

TrajectoryPlanner::  
getFrenet



```
graph LR; A[TrajectoryPlanner::getFrenet] --> B[distance];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is light gray with a black border and contains the text 'TrajectoryPlanner::' on the top line and 'getFrenet' on the bottom line. A dark blue arrow points from the right side of this box to the left side of the right box. The right box is white with a black border and contains the text 'distance'.

distance