

TrajectoryPlanner::
ClosestWaypoint



```
graph LR; A[TrajectoryPlanner::ClosestWaypoint] --> B[distance];
```

A diagram showing a return flow. On the left, a gray rectangular box with a black border contains the text "TrajectoryPlanner::ClosestWaypoint". A dark blue arrow points from the right side of this box to a white rectangular box with a black border on the right, which contains the text "distance".

distance