

BehaviorPlanner::evaluate  
FreeLaneBonus

```
graph LR; A[BehaviorPlanner::evaluate  
FreeLaneBonus] --> B[distance];
```

A diagram showing a function call. A gray rectangular box on the left contains the text "BehaviorPlanner::evaluate" and "FreeLaneBonus" on two lines. A dark blue arrow points from the right side of this box to a white rectangular box on the right, which contains the word "distance".

distance