Antonio Guillen-Perez

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Passionate **machine learning** and **research scientist** with **+4** years of experience in **applied AI**, and **reinforcement learning**. During my **Ph.D.**, I have researched solving **real-world problems** such as **cooperative** autonomous driving using **multi-agent deep reinforcement learning**, pedestrian flow **forecasting** with predictive algorithms, and **health** biomarker **signal** analysis for throat cancer detection.

SKILLS

PROGRAMMING

Python, iPython Notebook
Java, C++

ARTIFICIAL INTELLIGENCE

Machine Learning (Sklearn)
Deep Learning (Pytorch, Tensorflow)
Reinforcement Learning (Gym, MuJoCo)
AI Healthcare (healthcare.ai, PyHealth)
Graph Neural Networks (DGL, PyG)
Multi-Task / Multi-Modal Learning
Imbalanced Learning
Zero-Shot Learning
Meta Learning
Imitation Learning (IRL, LfO, LfD)
Time Series Forecasting
Natural Language Processing (BERT)

DATA ANALYST

Data Wrangling (Numpy, Pandas)
Data Visualization (Matplotlib, Seaborn)
Model Interpretability (Captum)
Statistics (StatsModels, Scipy)
High-efficiency software (Dask, CUDA)
Data Debugging (A/B, Logging, Unittest)
Git and Github
Amazon Web Services

COURSEWORK

Deep Reinforcement Learning
- Deep Reinforcement Learning - Nanodegree. Udacity
- Practical Reinforcement Learning. Coursera Course Certicates
- Practical Deep Reinforcement Learning for Coders v.1. fast.ai

Computer Vision & Time Series
- Time Series Forecasting. Udacity
- Sequences, Time Series, and Prediction. deeplearning.ai
- Convolution Neural Networks in TensorFlow. deeplearning.ai
- Deep Learning Specialization. deeplearning.ai

LINKS

Github:// **AntonioAlgaida**
LinkedIn:// **antonioguillenperez**
Researchgate:// **Antonio_Guillen-Perez**

EXPERIENCE & EDUCATION

PH.D. | Computer Science, Autonomous Veh., and Wireless Comm.

Sep 2018 – Expected Feb 2022 | UPCT | Cartagena, Murcia, Spain

- **Multi-Agent** system trained by **Deep Reinforcement Learning** techniques to control **autonomous vehicles** at intersections in a **cooperative** way using 5G
- Using **collective intelligence**, learning from demonstration, and the enormous capacity of the **MADR** systems, it can efficiently **control** autonomous vehicles, **eliminate accidents** and improve the **quality of life** of urban users

PREDOCTORAL STAY | University of California, Davis

Jul 2021 – Jan 2022 | Davis, CA, US

- Early detection of throat cancer by biomarker analysis using **DNN** specialized in **signal processing** such as LSTM, **transformers**, and **attention mechanisms**
- We achieved an accuracy of over **90%** and have opened a new **research path** for new platforms capable of **detecting** an infinite **number of diseases**

ASSOCIATED PROFESSOR | Distributed Systems and Services

Sep 2018 – Sep 2021 | UPCT | Cartagena, Murcia, Spain

- Familiarize students with the characteristic concepts of **distributed systems**, such as communication between **remote processes**, **synchronization**, **coordination** and **agreement** techniques and, finally, to learn about the characteristics and operation of various types of distributed services

DOLPHIN WAVE | ML and Data Scientist

Feb 2018 – Sep 2018 | Murcia, Spain

- Build **ML predictive** models for mobility research of **people** in closed environments
- Develop a Deep Learning **Multivariate** Time Series Forecasting technique with **Transformers** for item demands
- Visualization of **univariate** and **multivariate** clusters of people mobility and their **prediction** for **business intelligence** tools

MS. | Electrical and Communication Engineering

Oct 2016 – Sep 2018 | Murcia, Spain

- Skills in electromagnetic, communication systems (WiFi, Bluetooth, 5G, etc), antennas, RADAR and networking

RELATED RESEARCH

JOURNALS ARTICLES

- Learning from Oracle Demonstrations – a new approach to develop MADRL Autonomous traffic Intersection Management. Under Review. IEEE Tras. on Cyb.
- When Autonomous Intersection Traffic Management meets Multi-Agent Deep Reinforcement Learning. Under Review. IEEE TNNLS.
- Pedestrian characterization in urban environments combining WiFi and AI. International Journal of Sensor Networks, 18.

CONFERENCE PROCEEDINGS

- RAIM: Reinforced Autonomous Intersection Management - AIM based on Multi-Agent Deep Reinforcement Learning, In 34th Conference (NeurIPS) 2020 - Challenges of Real-World RL Workshop, Virtually.