Antonio Guillen-Perez

antonioalgaida.github.io

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Passionate machine learning and AI research scientist with +4 years of experience in applied AI, and deep reinforcement learning. During my Ph.D., I have researched solving real-world problems such as cooperative autonomous driving using multi-agent deep reinforcement learning, pedestrian flow forecasting with predictive algorithms, and health biomarker analysis for throat cancer.

SKILLS

PROGRAMMING

Python, iPython Notebook Java, C++

ARTIFICIAL INTELLIGENCE

Machine Learning (Sklearn)
Deep Learning (Pytorch, Tensorflow)
Reinforcement Learning (Gym, MuJoCo)
Al Healthcare (healthcare.ai, PyHealth)
Graph Neural Networks (DGL, PyG)
Multi-Task / Multi-Modal Learning
Imbalanced Learning
Zero-Shot Learning
Meta Learning
Imitation Learning (IRL, LfO, LfD)
Time Series Forecasting
Natural Language Processing (BERT)

DATA ANALYST

Data Wrangling (Numpy, Pandas)
Data Visualization (Matplotlib, Seaborn)
Model Interpretability (Captum)
Statistics (StatsModels, Scipy)
High-efficiency software (Dask, CUDA)
Data Debugging (A/B, Logging, Unittest)
Git and Github
Amazon Web Services

COURSEWORK

Deep Reinforcement Learning

- Deep Reinforcement Learning Nanodegree. Udacity
- Practical Reinforcement Learning. Coursera Course Certicates
- Practical Deep Reinforcement Learning for Coders v.1. fast.ai

Computer Vision & Time Series

- Time Series Forecasting. Udacity
- Sequences, Time Series, and Prediction. deeplearning.ai
- Convolution Neural Networks in TensorFlow. deeplearning.ai
- Deep Learning Specialization. deeplearning.ai

LINKS

Github://AntonioAlgaida LinkedIn://antonioguillenperez Researchgate://Antonio_Guillen-Perez Google Scholar://Antonio Guillen-Perez

EXPERIENCE & EDUCATION

PH.D. | COMPUTER SCIENCE, AUTONOMOUS VEHICLES, AND WIRELESS COMM. Sep 2018 – Jun 2022 | UPCT | Cartagena, Murcia, Spain

- Multi-Agent system trained by Deep Reinforcement Learning techniques to control autonomous vehicles at intersections in a cooperative way using 5G
- I achieved a system capable of effectively controlling **autonomous vehicles** in urban environments that **eliminated accidents** and reduced the **waiting time** by more than **94%** using **collective intelligence**, **learning from demonstration**, and **MADRL**

PREDOCTORAL STAY | University of California, Davis

Jul 2021 - Jan 2022 | Davis, CA, US

- Early detection of throat cancer by biomarker analysis using **NN** specialized in **signal processing** such as LSTM, **transformers**, and **attention mechanisms**
- I obtained an accuracy of over 90% and I have opened a new research path for new platforms capable of detecting an infinite number of diseases

ASSOCIATE PROFESSOR | DISTRIBUTED SYSTEMS AND SERVICES

Sep 2018 - May 2022 | UPCT | Cartagena, Murcia, Spain

• Introducing the students to the concepts of **distributed systems**, such as communication between **remote processes**, **synchronization**, **coordination** and **agreement** techniques, and finally, learning about the characteristics and operation of various types of distributed services

DOLPHIN WAVE | ML AND DATA SCIENTIST

Feb 2018 - Sep 2018 | Murcia, Spain

- Build **ML predictive** models for mobility research of **people** in closed environments
- Develop a Deep Learning **Multivariate** Time Series Forecasting technique with **Transformers** for item demands
- Visualization of **univariate** and **multivariate** clusters of people mobility and their **prediction** for **business intelligence** tools

MS. & BS. | ELECTRICAL, ELECTRONICS AND COMMUNICATIONS ENGINEERING Sep 2016 – Sep 2018 | Murcia, Spain

• Skills in electromagnetic, signal processing, communication systems (WiFi, Bluetooth, 5G, etc.), programming, circuit design, antennas, RADAR, and embedded systems.

RELATED RESEARCH

JOURNALS ARTICLES

- G.-P.,A. & C.,M.-D., Multi-Agent Deep Reinforcement Learning to Manage Connected Autonomous Vehicles at Tomorrow's Intersections, 2022. IEEE Transactions on Vehicular Technology, doi:10.1109/TVT.2022.3169907.
- <u>G.-P.,A.</u> & C.,M.-D., AIM5LA: A Latency-Aware Deep Reinforcement Learning-Based AIM for 5G Communication Networks, 2022, Sensors, doi:10.3390/s22062217.
- <u>G.-P.,A.</u> & C.,M.-D., Learning from Oracle Demonstrations A new approach to develop AIM control algorithms based on MADRL, Under Review. IEEE Access.

CONFERENCE PROCEEDINGS

- G.-P.,A. & C.,M.-D., RAIM: Reinforced Autonomous Intersection Management, In 34th Conference (NeurIPS) 2020 Challenges of Real-World RL Workshop, Virtually.
- <u>G.-P.,A.</u> & C.,M.-D., How super-resolution can help connected autonomous vehicles, VI doctoral conferences UPCT, University of Murcia. 2020. Oral communication.